

FAIR Control System Discussions on CR

Ralph C. Bär FAIR-BINP workshop, 24.05.2019



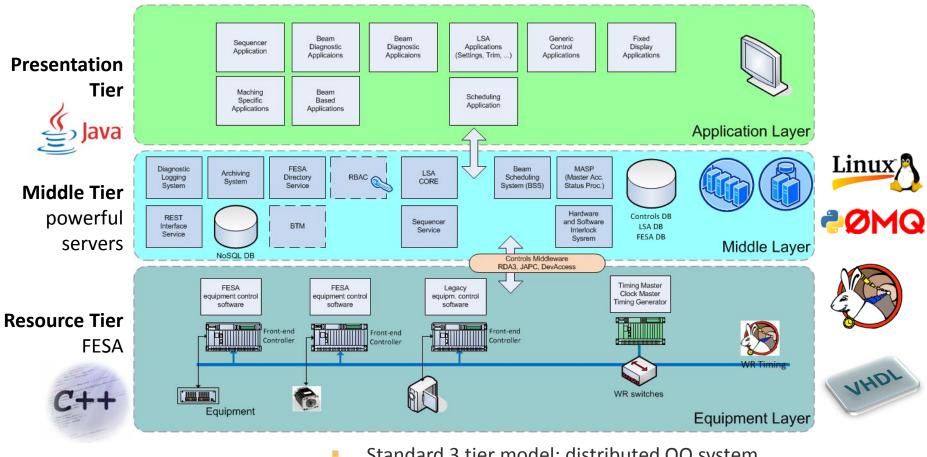
Outline

- Control System Overview System Architecture
- Implementation Status of Major System Building Blocks
- Tools for Hardware and Beam Commissioning
- Outlook & Summary





Recap: Control System Architecture Stack



- Standard 3 tier model; distributed OO system
- Modular design with well defined interfaces

Control System Implementation Strategy



Control System early use at CRYRING

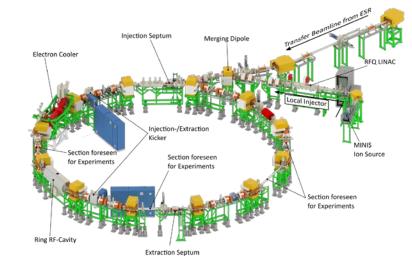
CRYRING @ GSI

- ➔ used as a continuous testbed for FAIR
- ➔ good model for CR as well

Implement basic functions of the FAIR ACS for validation of concepts, test, debugging, optimizations

"Early-adopter machine" for new control system releases and functions without interfering with production beam-times

- Gaining experience under real-life conditions
- Check and verify new features and concepts
- Identify possible design limitations, debugging early in the project
- Considered a potent QA measure for the control system
- Allows validating commissioning procedures



Equipment Control Front-End Electronic and Software

Hardware status: SCU hardware eco-system

- 250 SCU controllers produced, ~100 installed in operational environment (CRYRING, SIS18/ESR/FRS/HEBT
- Continuous in-house production of 200 units ongoing
- Preliminary analysis of SCU hardware failure rate: 13 units within 3 years (well within the expected and calculated range)
- SCU slave board of multiple types developed and in use (DIO, AIO, I/F, DDS, ...)

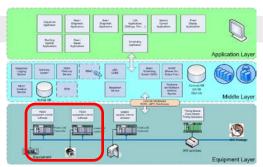
Devices controlled by FAIR SCU controllers

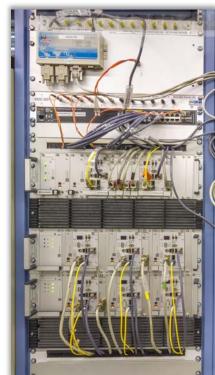
- All CRYRING power converters (multiplexed and ramped, using AIO and DIO boards, no FAIR ACU digital controllers)
- All SIS-18 and ESR ramped power converters (using MIL-1553 field-bus interface)
- All GSI HEBT multiplexed magnet power converters (MIL-1553)
- All ring RF systems using direct SCU backplane communication to DDS, AIO, DIO boards; full FAIR-style)

Equipment control software

- FESA framework (real-time equipment control software)
- Several FESA classes developed: CRYRING devices (ion source, multiplexed & ramped power converters, linac and ramped RF cavities, many BI DAQ systems, etc.)







Retrofitted controls rack controlling power supplies

5

Ralph C. Bär, Status and Progress of the FAIR Accelerator Control System

Equipment Control Front-End Electronic and Software

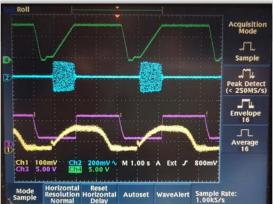
Function Generator (FG) subsystem

- control of ramped devices
- FPGA/HDL development for Function Generator
- Operational already (production beam time 2019)

Present activities & next steps

- Implementation of DAQ functionality (VHDL & FESA software)
- Roll-out of FAIR analog signal digitization systems
- Improve RT performance of the Timing System Library









Analog signals digitization system (PicoScope based)

General Machine Timing System Implementation Status

Timing System installed and productive

- CRYRING tested in 4 beam times (05/2017 to 03/2018)
- SIS-18/ESR/HEBT producively used in beamtime 2019

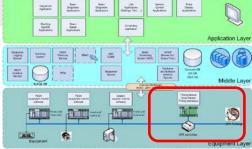
Present hardware setup

- Central Timing System installation (WR/BuTiS) done
- 2 Clock Masters installed (grandmaster clock of WR network, GPS as reference clock, phase-locked to BuTiS)
- Data Master operational (PRO, DEV, INT)
- about 80 White Rabbit Switches installed
- DM orchestrates ~300 SCU controllers (timing receivers)
- and several more in other form factors (PCIe, VME, AMC, PMC)

Hardware Situation

- 170 PCIe have been produced by GSI (\rightarrow CO Digitizers, BI)
- AMC and PMC in production (SLO in-kind)
- Procurement process for all WRS needed started: Delivery in 2019 and 2020 (full scope)





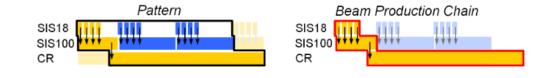


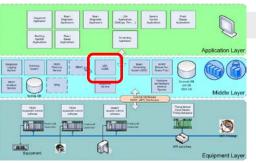


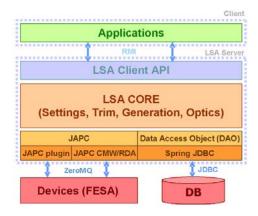
Setting Generation and Management Status

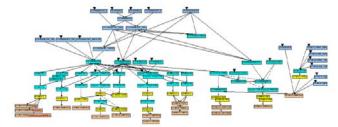
LSA status

- LSA is *the* core component of the FAIR Control System, used for settings generation and management
- Well developed framework for CERN and FAIR accelerators (maintained in collaboration)
- Provides consistent settings on all levels, contains optics, accelerator model(s) and parameters (hierarchy from physics to devices)
- To control the GSI/FAIR accelerator complex, new fundamental concepts have been defined and successfully integrated in the LSA core code base: Pattern, PBC (beam production chain).









8



LSA: Setting Generation and Management Next Steps & Outlook

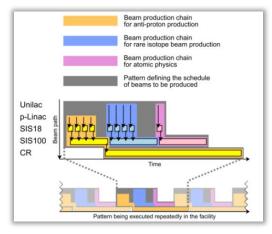
Status and operational experience

- All accelerators (CRYRING injector & ring, SIS-18, HEBT, ESR (in work)) have successfully been modelled in LSA and operated
- LSA core was extended by several components for the beam scheduling system (pattern management, beam requester, MASP status processor)
- LSA core was extended for full setting supply for the FAIR Timing System Data Master (Schedule supply fully implemented)
- Central system architecture and new concepts have proven to be adequate for facility operation, no showstoppers identified.
- LSA is a reliable system component

Next steps

- Continue implementation roadmap Storage
 -> esp. Storage ring functionality (interactive manipulation mode for 2019, partially if possible for 2018)
- Code clean-up and refactoring necessary (2020/21)







Diagraphic Application

the state

Inqueste April alter

Maring Sports Approximations

Logram Agenery System Bagroune Deprese Caresi Caresi photos

Middle Lav

3

Equipment Lay

Accelerator Status Monitor

Hardware Interlocks & Beam Interlocks

Status of Accelerator equipment and devices is monitored by hardware and software interlock system

Hardware Interlock System

- in-kind delivery of Slovenian FAIR partner
- PLC based aggregation of hardware interlock signals
- Implemented for several HW signals

Software Interlock System

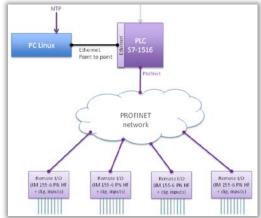
- MASP (Master Accelerator Status Processor)
- Receives and aggregates about 2000 signals from devices & components
- Prototype (mini-MASP) developed for BT 2018 operation (rapid prototype)
- Includes Gateways to monitor legacy FEC status messages
- Sends execution permit to BSS (beam scheduling system)
- Already prepared to manage Beam Modes (presently only NO_BEAM and PILOT_BEAM used)
- No real operational experience yet, just turned operational

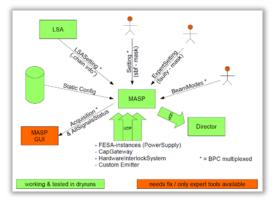
Next steps

- Overall hierarchical status concept needs to be revised and extended for BPC-specifig beam interlocks
- Refinement of functional specification of the full FAIR Status Processor system and implementation in the next years









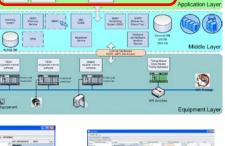
Control Room Applications

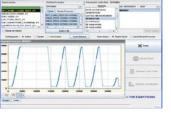
A complete new set of control room applications has been developed for CRYRING and beamtime operation in 2018.

- Implemented in Java (changed from Swing to JavaFX GUI framework)
- Present focus is on implementation of generic type applications to provide basic functionality
- Applications
 - LSA applications (Settings, Trim, ...)
 - Beam Scheduling Applications, Beam Requester
 - Equipment and Timing monitor & control, Interlock and Status monitoring
 - Set of Beam instrumentation (expert applications)

Operational experience and know issues

- Feedback from operator team required present set of applications are first rudimental versions, unhandy and inefficient to use
- Just porting popular applications from the old control system is no effective strategy, control paradigms changed
- Still very much effort to provide control room applications with operational quality
- Presently insufficient manpower to support machine-specific and beamand measurement-based applications (is addressed to PL/Management)
- New development: Oracle announced their intention to stop shipping JavaFX with JDK 11 and later
 → observe community, stay mainstream

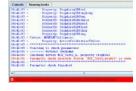


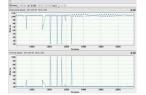


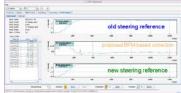
Logram Logram Symmetry

Martin Martin















Control Room Environment Prototype for the FAIR Control Centre

Control system consoles

- Prototype operator consoles for FCC have been installed in present main control room for operation with new control system
- Operator consoles consist of a 3x2 TFT screen array with 2 console computers installed in the console corpus
- Fixed displays as foreseen for FCC are already wallmounted, first overview applications are online



FAIR

Fixed display prototype (SIS-18)

GSÍ



Central control room with new FAIR console environment (June 2018)

Ralph C. Bär, Status and Progress of the FAIR Accelerator Control System

Diagnostic Logging System

Powerful System Diagnostic Tool

Diagnostic Logging: System to receive and store diagnostic logging messages in the control system

- The system focuses on system messages, not on accelerator measurement data (
 Archiving System)
- The system is implemented as a cluster of *logstash* servers

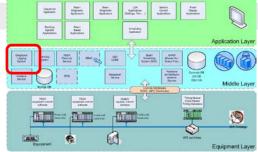
Logstash?

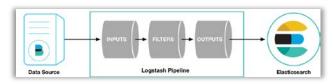
- Light-weight open-source, server-side data processing pipeline for diagnostic data
- Data pipelined and persisted in *elasticsearch* nSQL DB and popular analytics and search engine
- System emitters for syslog and log4j prepared
- Kibana Web-client (open source data visualization plugin) provides comfortable access as well as powerful filter capabilities

Status and operational experience

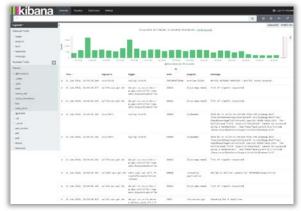
- Extremely valuable tool, a "must-have" for debugging, commissioning and operation
- All FEC and system services send diagnostic logging messages











Archiving System

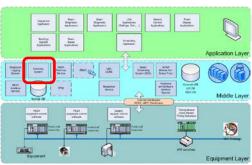
The FAIR Measurement Database

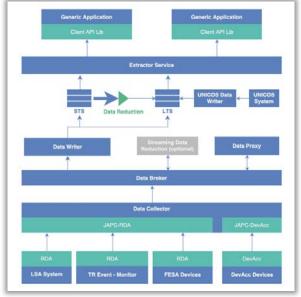
Archiving System is a central building block of the FAIR control system

- → Very important tool for HW/beam commissioning and operation
- Store historical data by FECs and controls processes permanently
- Stores data from automated sequencer tasks
- Allows storing data on configurable base (time resolution, triggered by timing events, on-change, push data)
- Functionality to query, correlate and display historic data
- Includes services that allow smart data reduction or aggregation over time
- Key parameters (FAIR final): ~100 TB storage, ~10 MB/s continuous input data stream
- Design decision: AS will receive and store future PM data (no separate system planned any more)

Some implementation details

- Consists of several components, amongst them...
- Apache Kafka (Data Broker, high performance system)
- Elastic Search (nSQL DB for Data Writer component)







Archiving System Status and Outlook

Present status

- Presently under development as SLO in-kind contribution (xlab/Tehnodrom)
- First prototype version installed on virtual server environment
- Procurement of IT hardware for test system started (20 TB disk space)
- About 100 FEC are configured to send measurement data to Archive
- Sequencer sends reports to AS
- First GUI program to retrieve, display and analyse data from AS under development
- AS is defined to receive and store PM data (no separate system planned any more)

Outlook & next steps

- Complete implementation until mid of 2019
- Performance tests with beam (2 months on real hardware)
- Gain first experience (store/retrieve) with interested users (Operation/Physics)
- Operational use for Beamtime 2020





Sequencer Framework

Semi-automated Tests for HW and Beam Commissioning

HW and beam commissioning require efficient tools for testing

- Perform initial and acceptance tests, early detection of nonconformities and faults
- Perform QA and regular re-validation tests
- Considering size and complexity of FAIR, and limited resources: efficient and reliable execution and documentation of tests

→ Development of a Java-based **Sequencer framework** started, as a core part of the FAIR control system to aid semi-automated testing

Architecture: Sequencer framework conceptually divided in three parts

- Middle-tier sequencer service (run sequences, generate automated reports)
- The sequences with a subset of tasks (testing steps)
- Graphical user interface (GUI) program

Operational experience so far:

- Was tested and used already during Dry-runs in 2017
- However, new development. Not yet adopted by FESA class and system service developers
- Establish process of writing Sequencer tasks parallel to development (in progress)





* Loaded Sequences:		in presser in the second				
The state of the s		8 S Task		Description	Status	1
< > Martin Enter filts Enter day		DemoSequence			1165-63	
TaskName	•	unknownTaskName			V MASHED	
 Demosequence 	D	taskNamel	taskDescription 1		/ MISHED	
unknownTakkName	D	5 toskNamid2	taskDescription 2 - this te		Dimits Held	
EaskName1	D	5 taskName3		st can and is skipped by default	SKIPPED	
toskName2	D	taskNamo4		If fail but connot be recovered	INSIED F	
	D	5 taskhama5	taskDescription 5 - this te	st can be skipped	FINESHED.	
testName4(#)	D	5 taskNamoti	yet another task		P INTERNE U	
tasktierne5 (S/S)	D	X S shortTaskName	377		SKIPPED	۰.
taskName6	D	<u> </u>				
oburfgashwer (P30)	D	* Detailed Task Status				
		Task Name	Indianet	Comment:		
		Task Description: ItaskDescription 4 - this will Task Statuss Task Point Broak	RNSNED FAULTY DemoSequence YES NO NO	Warnings: Exceptions: ***reveals: deal of a sector of the sector as provide warning of the equip is a sector or most any first execution frameWarning and equip is a sector or most any first execution frameWarning and equip is a sector or most any first execution frameWarning and equip is a sector or most any first execution frameWarning and equip is a sector or most any first execution frameWarning and equip is a sector or most any first execution frameWarning and any first execution framework and the sector of the sector of the and the sector of the sector o		
 Image: Constraint of the second second	era	space for sequence/task para	nener			

Sequencer GUI impression (courtesy Ralph Steinhagen)

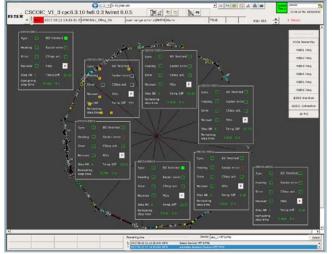
Controls Project Status Vacuum Control System (Controls WP-6)

FAIR Vacuum control system is Slovenian in-kind contribution

- Decision taken to use CRYRING for vacuum controls test bench (including bake-out)
- Implementation done by Tehnodrom and supported by CO
- System almost fully implemented, commissioned and already in use (to be completed until 08/2017)
- Technical evaluation ongoing, some problems and scaling limits identified, to be addressed.
- Detailed specification for FAIR vacuum system prepared, needs to be refined by testing results
- FAIR implementation project can only be started with equipment type and BOM vacuum list

General Status & Problems

- No technical problems
- Extended project length (up to 2025) proves to be a problem for in-kind consortium (under clarification)





6/6/2019



17

Synoptic displays from CRYRING vacuum control system



Summary

- Fundamental building blocks of the FAIR control system have already been developed and are in use (Equipment controllers, frameworks FESA, LSA, UNICOS, Timing, ...), roughly a million lines of code has been developed so far
- CRYRING has been adopted as test bench for FAIR control system vertical test, 4 runs with beam have been executed
- Control system stack was already rolled out to SIS-18, ESR and HEBT and is presently already used in production (successful beam time 2019) → FAIR version Ø control system is already in use today, years ahead of FAIR start
- Architecture, basic concepts and general system design have shown no fundamental problems, showstoppers or technical risks so far → detailed design is continuously refined
- Some technical limits/bottlenecks have been already identified → still early enough to fix in the next years
- Efficient tools for diagnostics, testing and measurement data acquisition for FAIR hardware and beam commissioning have already been developed or are under development (Diagnostic logging, Archiving, Sequencer, Digitization System)
- Control System is far from being feature-complete, presently limited to basic functions. Many important functions and features still need to be developed and iteratively rolled out in the next years until FAIR start
- Operational experience will be gained during beam times in the next years



Next Steps for CR

- CR equipment Consolidate CR "equipment type list"
 - Compilation of a list of all equipment type for control/monitoring, define rough numbers
 - If needed, discuss on equipment control interfaces (if specified solutions are not adequate)
 - Discuss and agree on equipment functionality
 - needed to work out implementation plan (hardware production, software development, test sequence developments, support for FAT/SAT, ...)
- Consider a visit to the next CRYRING beam time
 - get hands-on experience and better impression on the capacity of the system





thank you!

Ralph C. Bär, Status and Progress of the FAIR Accelerator Control System