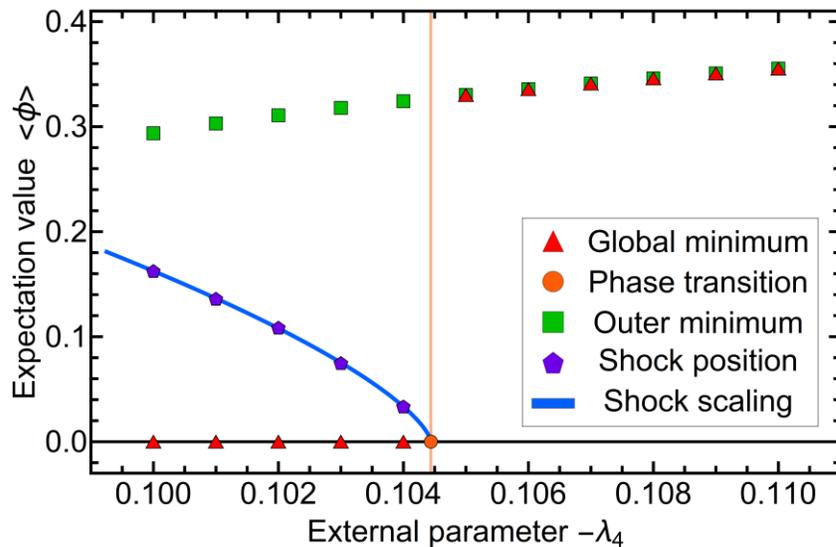


Resolving phase transitions with Discontinuous Galerkin methods

Functional Methods in Strongly Correlated Systems



Nicolas Wink

Work in collaboration with:

Eduardo Grossi

Jan M. Pawłowski

Grossi, NW, arxiv:1903.09503

Grossi, Pawłowski NW, in prep.

Partial differential equations

Partial differential equations of interest:

For simplicity: $u(t, x)$
scalar with one spatial dimension

$$\partial_t u + \partial_x f^{(c)}(u, t, x) + \partial_x f^{(D)}(u, \partial_x u, t, x) = s(u, t, x)$$

↑
Conservation term
(Goldstone modes)

↑
Diffusion term
(Radial mode)

↑
Source term
(Fermions)

A lot of physical systems are described (partially) by this class of equations:

➔ Maxwell equations

➔ General relativity + Magneto Hydro

➔ Navier–Stokes equations

➔ Functional renormalization Group equations

Discontinuous Galerkin methods are designed precisely designed for this set of equations

Conservation laws

Consider only the scalar conservation law

$$\partial_t u + \partial_x f(u) = 0$$

Given numerical approximations

$$u_h(t, x_k) \quad \text{and} \quad f_h(u_h(t, x_k))$$

Several options how the residual should vanish

$$\mathcal{R}_h = \partial_t u_h + \partial_x f_h = 0$$

On each node of the mesh:

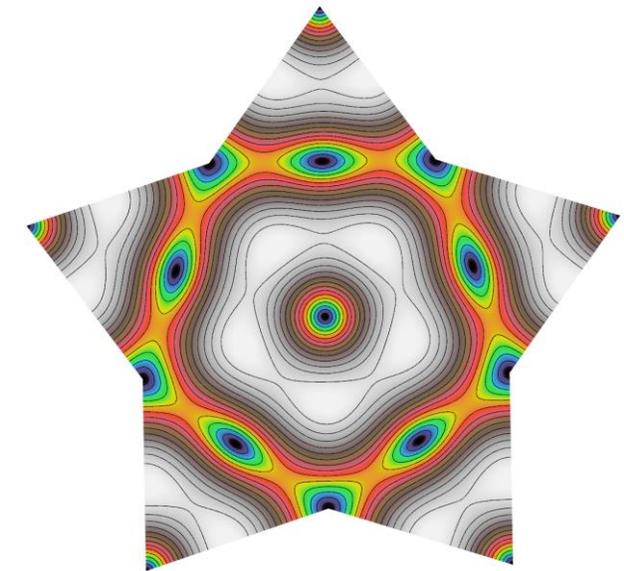
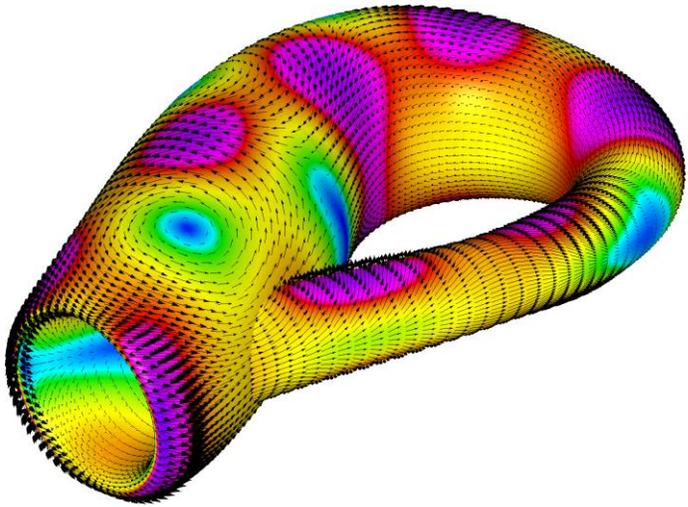
$$\Rightarrow \mathcal{R}_h(t, x_k) = 0$$

- Finite difference methods
- Finite volume methods
- ...

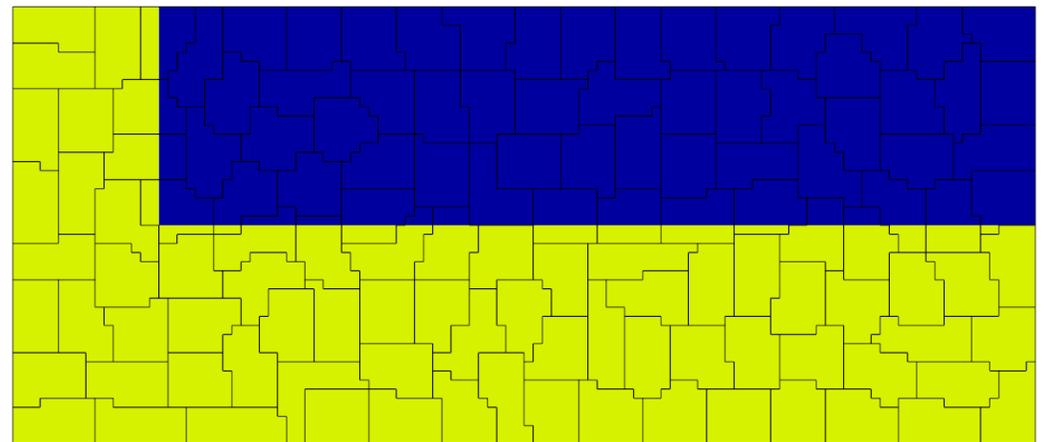
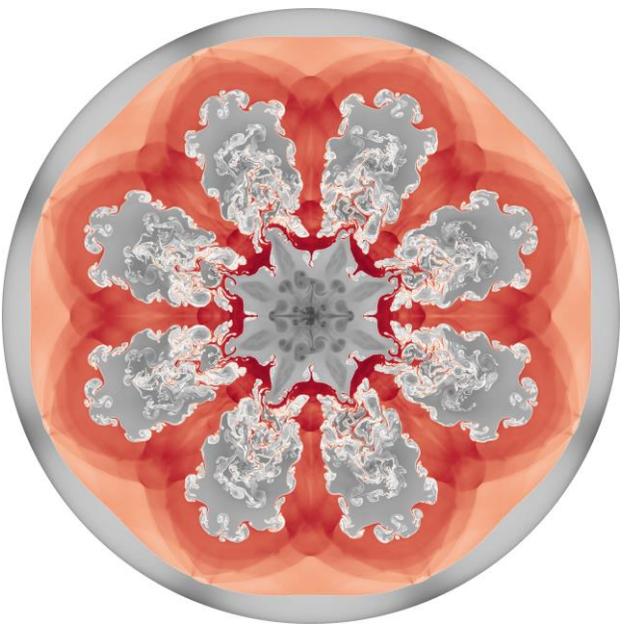
Residual orthogonal to all test functions in some space:

$$\Rightarrow \int_{\Omega} \mathcal{R}_h(t, x) \phi_h(x) = 0$$

- Finite element methods
- Spectral methods
- ...



Discontinuous Galerkin methods



The basic idea

The method combines two basic ideas:

$$\mathcal{R}_h(t, x_k) = 0$$

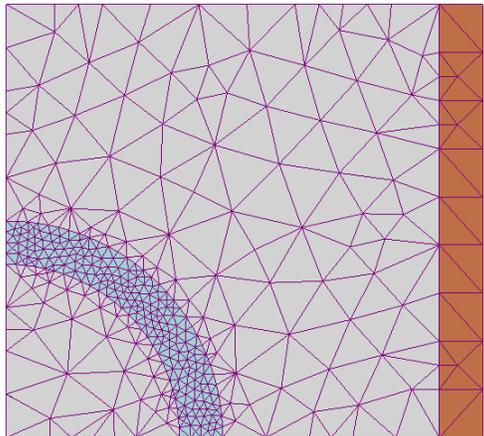
Finite volume methods

- Residue vanishes for cell averages
- Local & geometric flexible
- Inherently discontinuous
- Higher order accuracy problematic

$$\int_{\Omega} \mathcal{R}_h(t, x) \phi_h(x) = 0$$

Finite element methods

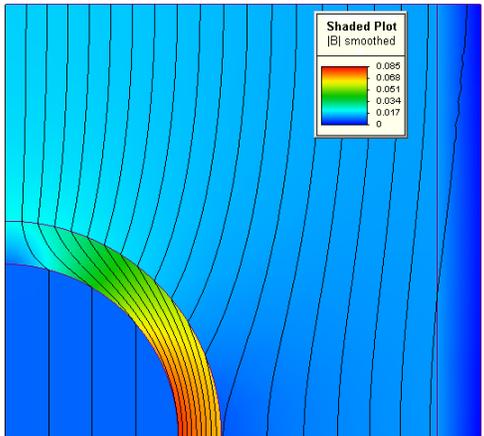
- Residue vanishes in a weak sense
- High order accuracy & geometric flexible
- Usually continuous
- Method is “global” (one giant matrix)



Copyright: https://en.wikipedia.org/wiki/Finite_element_method

Take the best from both
 → Discontinuous Galerkin methods

Slightly more technical: An extension of finite element methods that reduces to finite volume schemes at lowest order

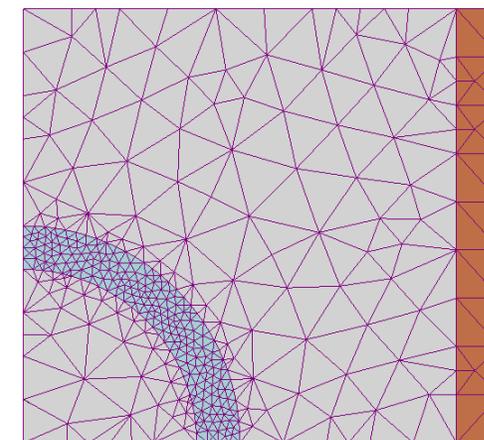


Copyright: https://en.wikipedia.org/wiki/Finite_element_method

Local approximation

Approximate solution over computational domain

$$\Omega \simeq \Omega_h = \bigcup_{k=1}^K D^k \longleftrightarrow$$

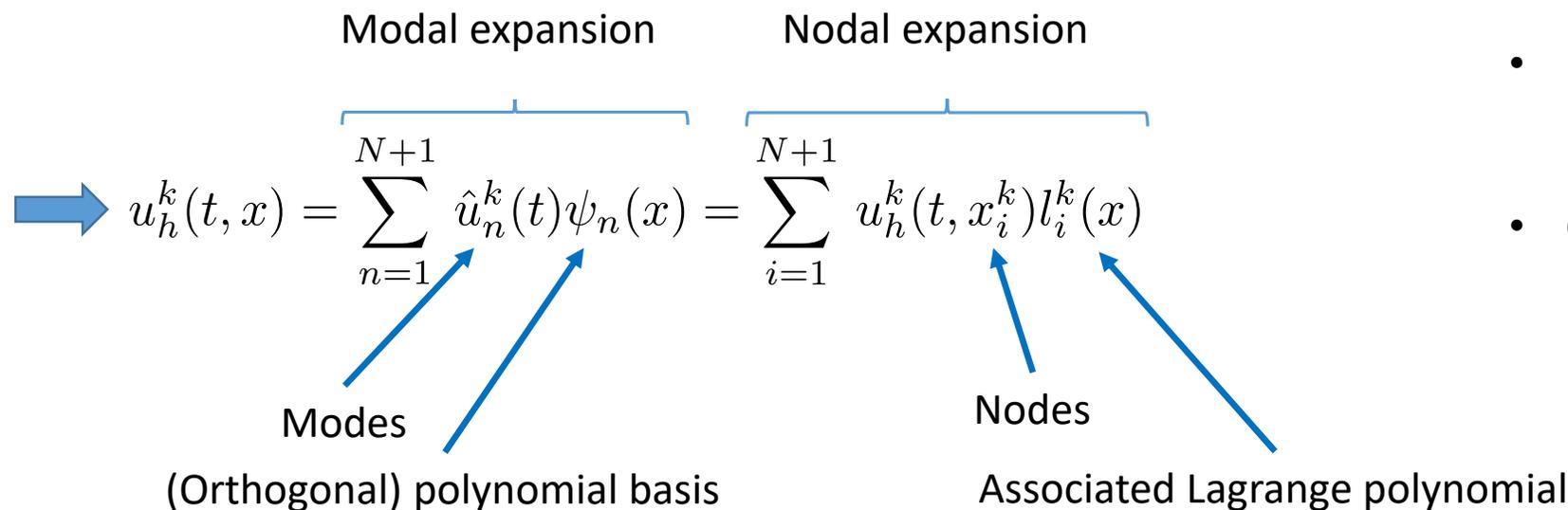


Copyright: https://en.wikipedia.org/wiki/Finite_element_method

$$\rightarrow u(t, x) \simeq u_h(t, x) = \bigoplus_{k=1}^K u_h^k(t, x)$$

Expand the solution in each element in a local polynomial basis of degree N

Good choice (obviously) important



- Legendre polynomials
 - Spectral convergence
- Gauss-Lobatto points
 - Ensures well conditioning while switching between bases

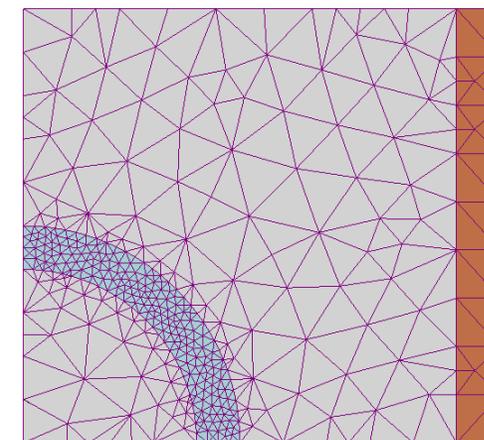
Weak formulation

$$\int_{D^k} \left(\partial_t u_h^k + \partial_x f_h^k(u_h^k) \right) \psi_n \, dx = 0 \quad \rightarrow \quad \text{Discontinuous elements: More degrees of freedom than equations!}$$

Partial integration

$$\int_{D^k} \left((\partial_t u_h^k) \psi_n - f_h^k(u_h^k) \partial_x \psi_n \right) dx = - \int_{\partial D^k} \hat{\mathbf{n}} \cdot \mathbf{f}^* \psi_n \, dx$$

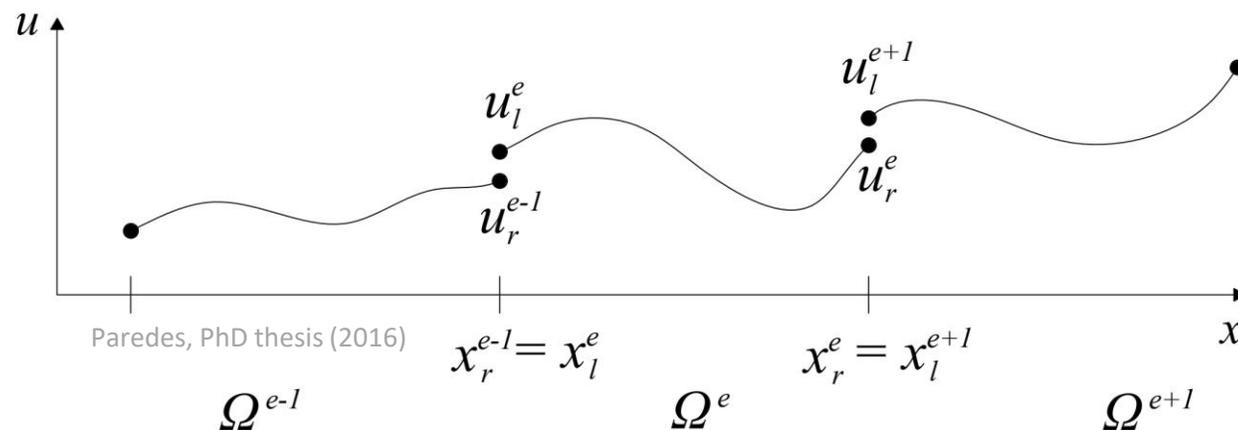
Weak form



Copyright: https://en.wikipedia.org/wiki/Finite_element_method

Numerical flux

Connects elements (closes set of equations)



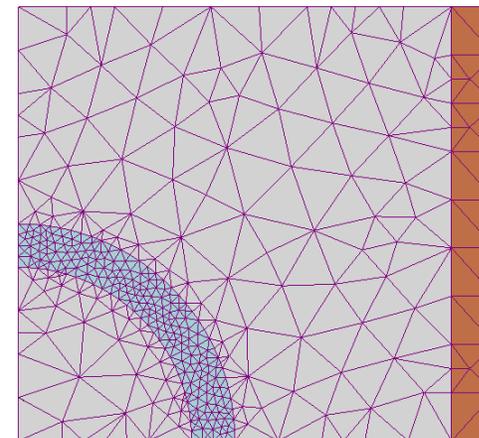
Paredes, PhD thesis (2016)

Numerical flux

$$\int_{D^k} \left(\partial_t u_h^k + \partial_x f_h^k(u_h^k) \right) \psi_n \, dx = \int_{\partial D^k} \hat{\mathbf{n}} \cdot \left(f_h^k(u_h^k) - f^* \right) \psi_n \, dx$$

Strong form

Numerical flux



Copyright: https://en.wikipedia.org/wiki/Finite_element_method

- Restricted by rather general conditions (consistency, ...)
- Defines how to treat a jump discontinuity between elements
- Acts physically like a tiny dissipation
- A variety of choices available

Lax-Friedrichs flux

$$f^*(u_h^-, u_h^+) = \{ \{ f_h(u_h) \} \} + \frac{C}{2} [[u_h]]$$

$$\{ \{ f \} \} = \frac{1}{2} (f^- + f^+) \quad \text{Average}$$

$$[[u]] = \hat{\mathbf{n}}^- u^- - \hat{\mathbf{n}}^+ u^+ \quad \text{Difference}$$

Constant related to the propagation speed of information

$$C \geq \max_{D\{i, i\pm 1\}} |\partial_u f(u)|$$

Usually an efficient, accurate and robust choice

Functional Renormalization Group

Functional Renormalization Group

Wetterich equation:

$$\partial_t \Gamma_k[\phi] = \frac{1}{2} \text{Tr} \frac{1}{\Gamma_k^{(2)}[\phi] + R_k} \partial_t R_k$$

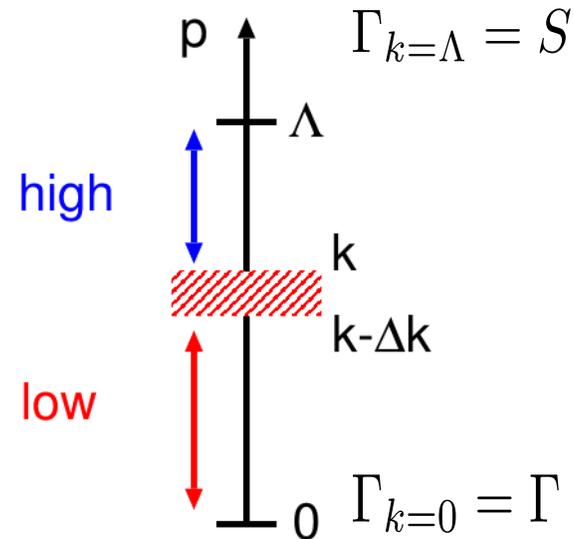
RG-time:

$$t = -\ln \frac{k}{\Lambda}$$

← Momentum scale

← Reference scale
(set to 1 here)

➔ Integrating theory from $t = 0$ to $t = \infty$ includes all quantum effects



- Non-perturbative first principle method
- Systematically integrate out momentum shells
- Access to physical mechanisms
- No sign problem
 - Chemical potential
 - Real time

$O(N)$ - Model

O(N) - Model

Relevant in many physical settings:

- (Pseudo)-scalar sector in QCD
- Higgs potential
- Condensed matter
- ...

N-component scalar theory with classical action:

$$S = \int_x \left\{ \frac{1}{2} (\partial_\mu \phi_a)^2 + \lambda_2 \phi_a \phi^a + \lambda_4 (\phi_a \phi^a)^2 + \lambda_6 (\phi_a \phi^a)^3 \right\} \quad \text{Invariant: } \rho = \frac{1}{2} \phi_a \phi^a$$

➔ Finite field expectation value signals spontaneously broken symmetry

Lowest order approximation in a derivative expansion, LPA:

$$\Gamma_k = \int_x \left\{ \frac{1}{2} (\partial_\mu \phi_a)^2 + V(\rho) \right\} \quad \begin{array}{c} \text{Flow equation} \\ \text{Rescale with (N-1)} \end{array} \quad \partial_t V(\rho) = \frac{\Omega_d}{(2\pi)^d} \frac{(\Lambda e^{-t})^{d+2}}{d} \left(\frac{1}{(\Lambda e^{-t})^2 + V'(\rho)} + \frac{1}{N-1} \frac{1}{(\Lambda e^{-t})^2 + V'(\rho) + 2\rho V''(\rho)} \right)$$

Connecting to DG

Flow equation for the effective potential:

$$\partial_t V(\rho) = \frac{\Omega_d}{d(2\pi)^d} \frac{(\Lambda e^{-t})^{d+2}}{(\Lambda e^{-t})^2 + V'(\rho)}$$

Introduce new variable for the derivative:

➔ Not ideally suited for numerical applications

$$u(\rho) = \partial_\rho V(\rho)$$

RHS now defines a flux:

$$f(t, u) = -\frac{\Omega_d}{d(2\pi)^d} \frac{(\Lambda e^{-t})^{d+2}}{(\Lambda e^{-t})^2 + u}$$



$$\partial_t u + \partial_\rho f(t, u) = 0$$

Standard conservative form

Initial & Boundary conditions:

$$u(t=0) = \lambda_2 + \lambda_4 \rho + \lambda_6 \rho^2$$

Allows for access to first &
second order phase transitions

- We require a solution on $\rho \in [0, \rho_{\max}]$
- Boundary conditions required for inflow boundary conditions

$$\hat{\mathbf{n}} \cdot (\partial_u f) < 0$$



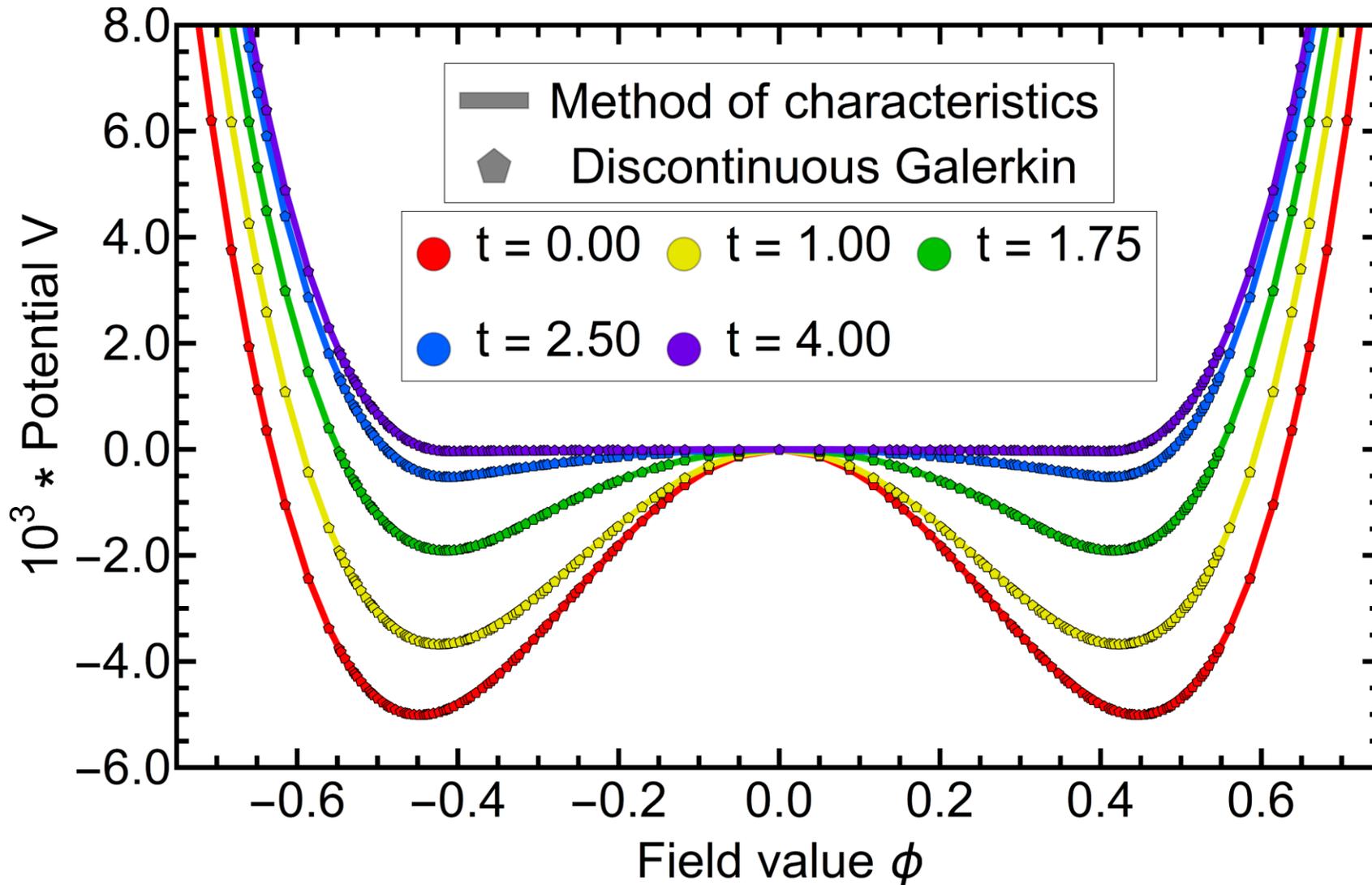
Boundary condition at large field values required,
but naturally suppressed for physical potentials

Together with $d = 3$ and $\Lambda = 1$

Grossi, NW, arxiv:1903.09503

Second order phase transition

Potential

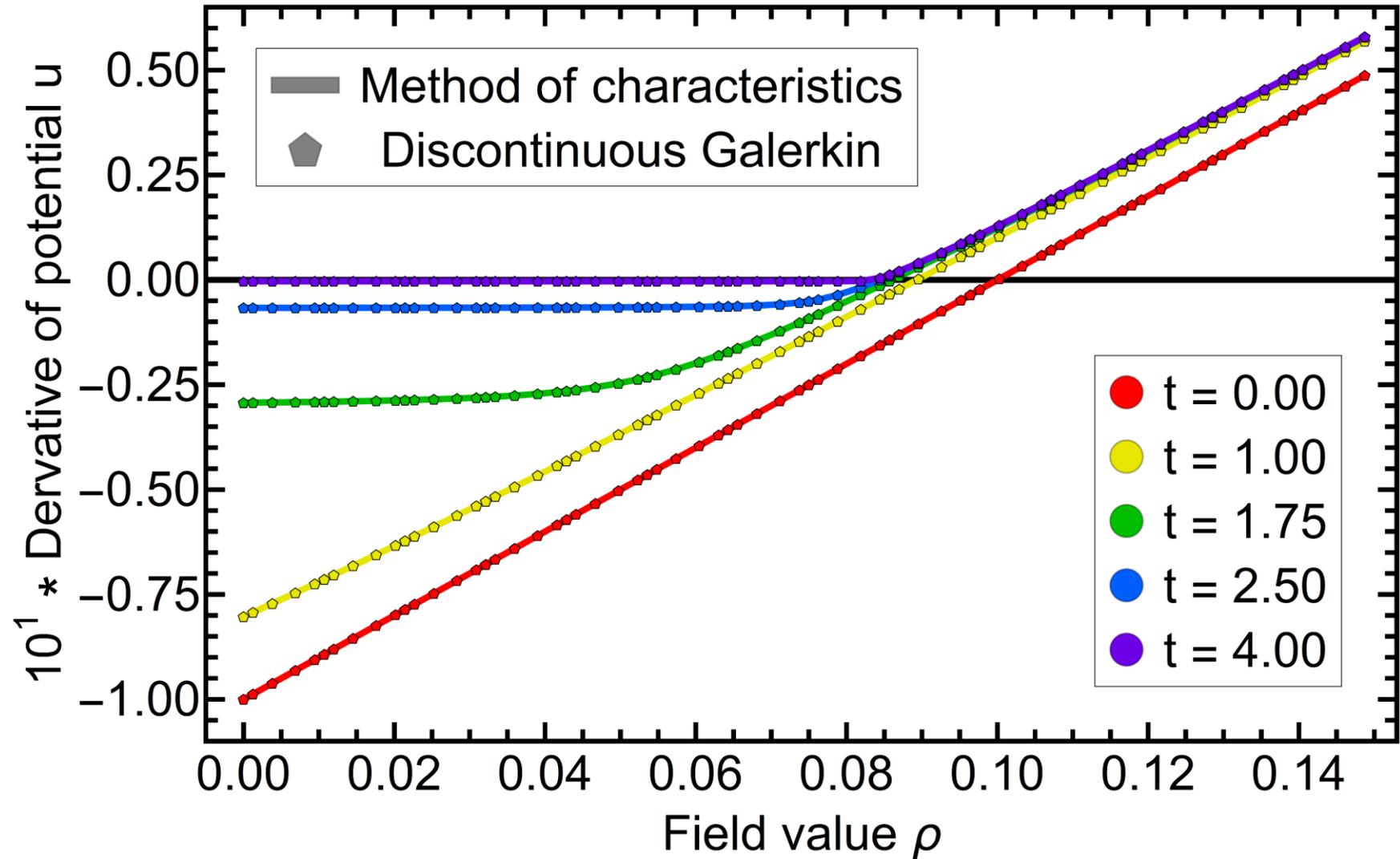
Initial condition: $u(t=0) = -\frac{1}{10} + \rho$ 

Calculated with N=5, K=30

Grossi, NW, arxiv:1903.09503

Derivative

Initial condition: $u(t = 0) = -\frac{1}{10} + \rho$



- Zero crossing signals position of minimum

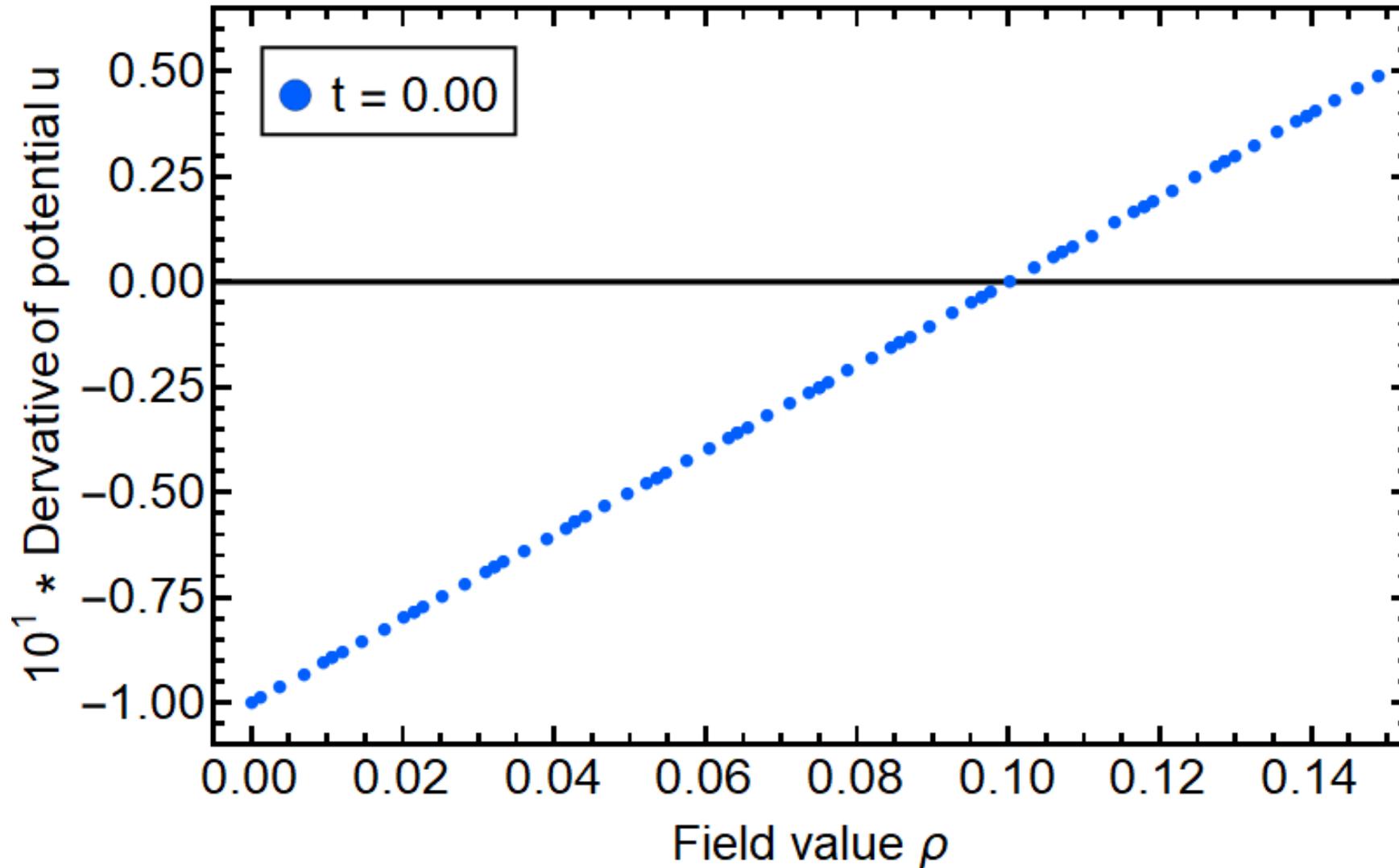

Example of symmetry broken phase
- Convexity restoration nicely visible

Calculated with N=5, K=30

Grossi, NW, arxiv:1903.09503

Derivative

Initial condition: $u(t = 0) = -\frac{1}{10} + \rho$



- Zero crossing signals position of minimum

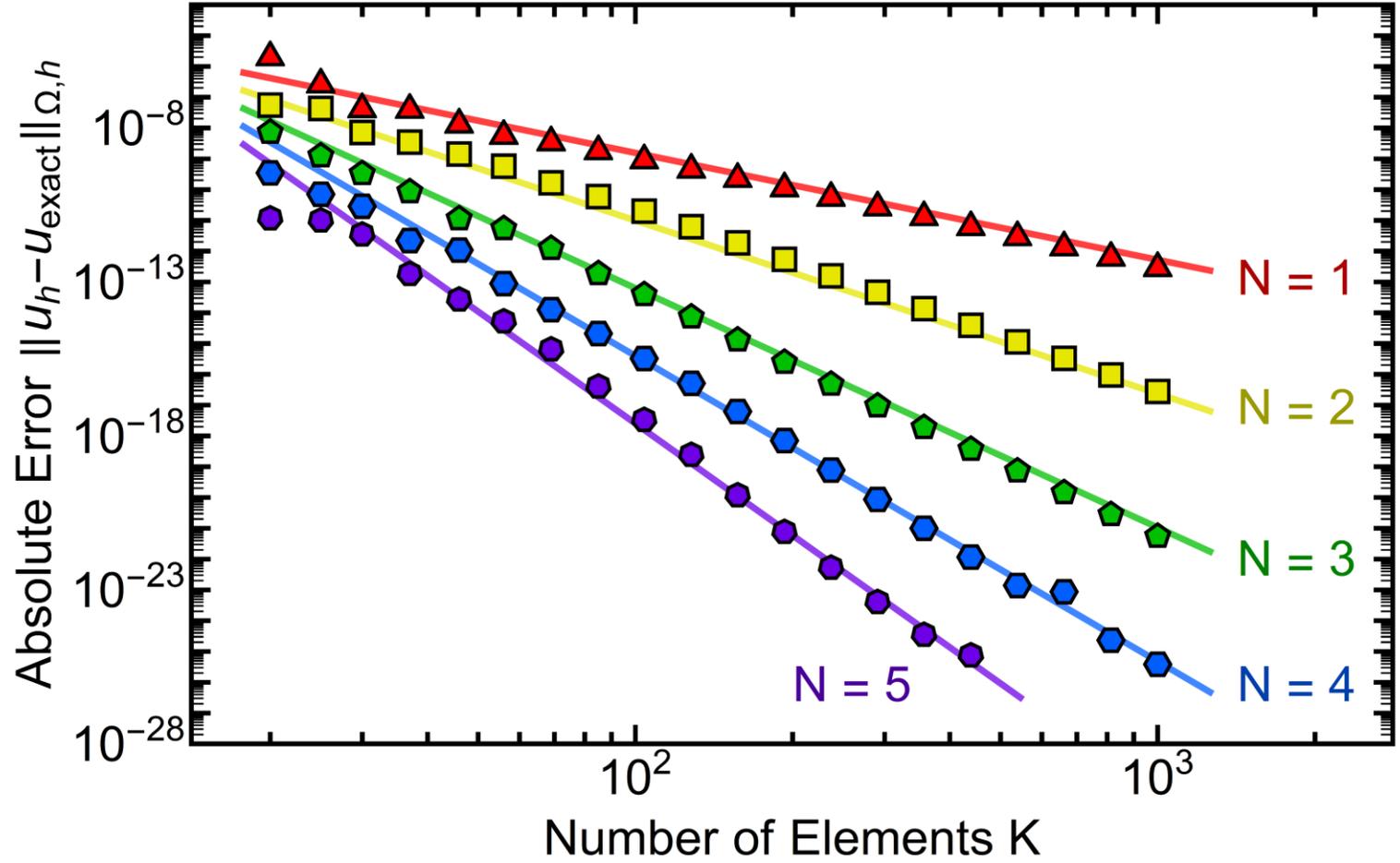
 Example of symmetry broken phase

- Convexity restoration nicely visible

Convergence

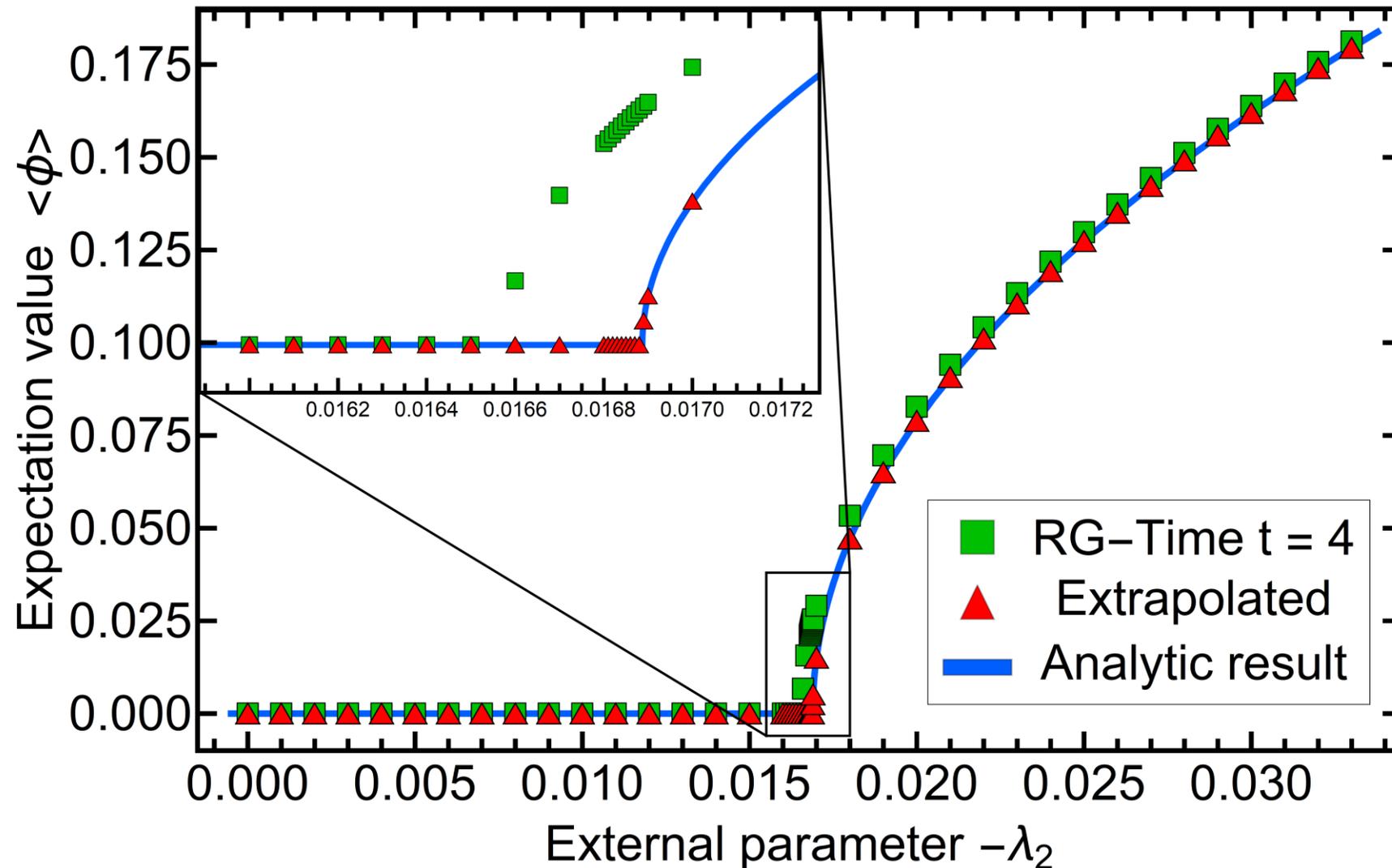
Initial condition: $u(t = 0) = -\frac{1}{10} + \rho$

25 order of magnitude!



- $t=1.75$ (already kink like)
- Power law in number of elements
- Spectral convergence in local approximation order
- Lines from a single fit

Phase transition

Initial conditions: $u(t=0) = \lambda_2 + \rho$ 

- Second order phase
- Critical exponent agrees with mean field (within error)
- Extrapolation to infinite time easily possible

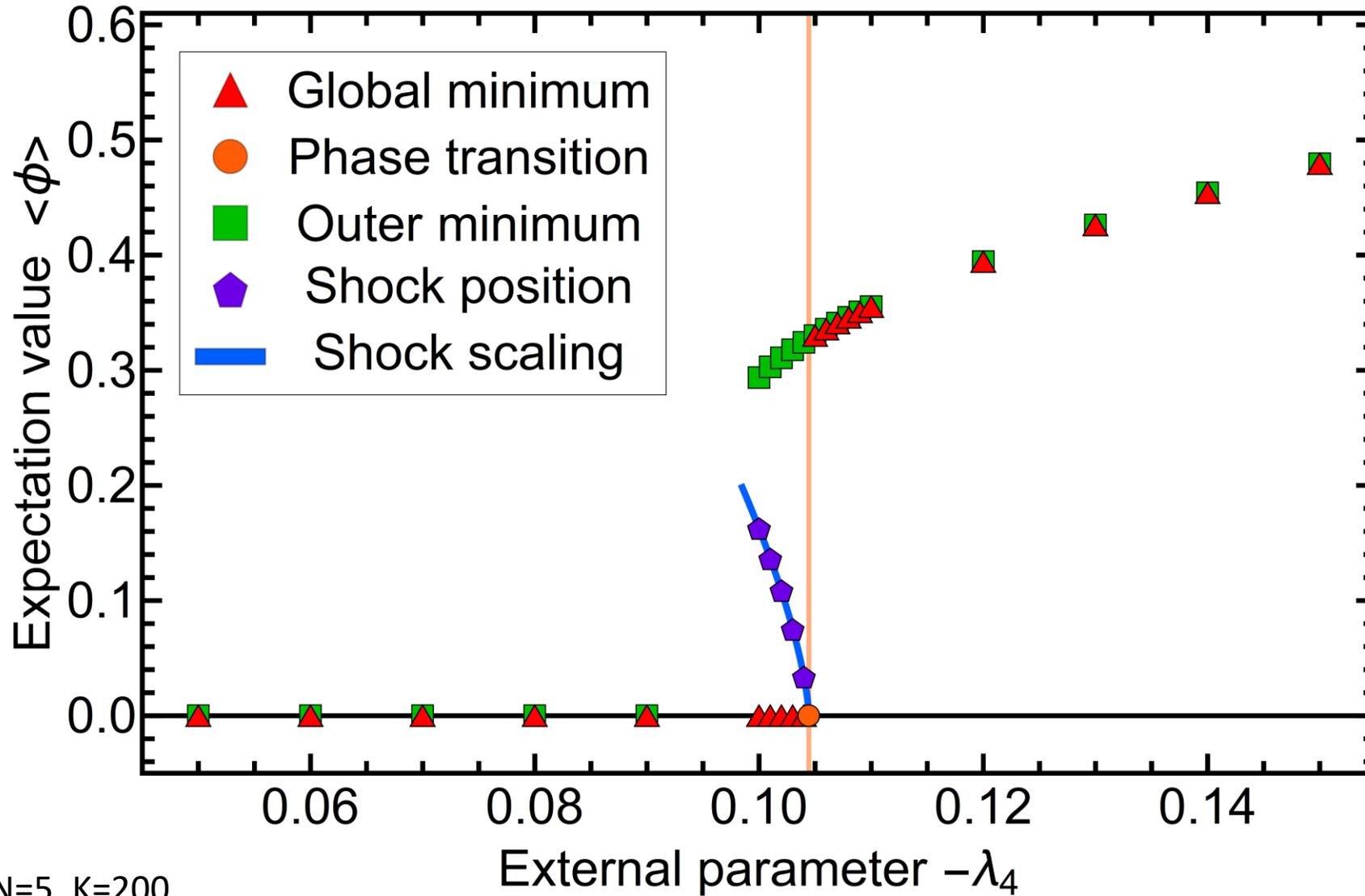
Calculated with $N=5$, $K=120$

Grossi, NW, arxiv:1903.09503

First order phase transition

1st-order phase transition

Initial condition: $u(t=0) = \lambda_2 + \lambda_4 \rho + \lambda_6 \rho^2$
with $\lambda_4 < 0$



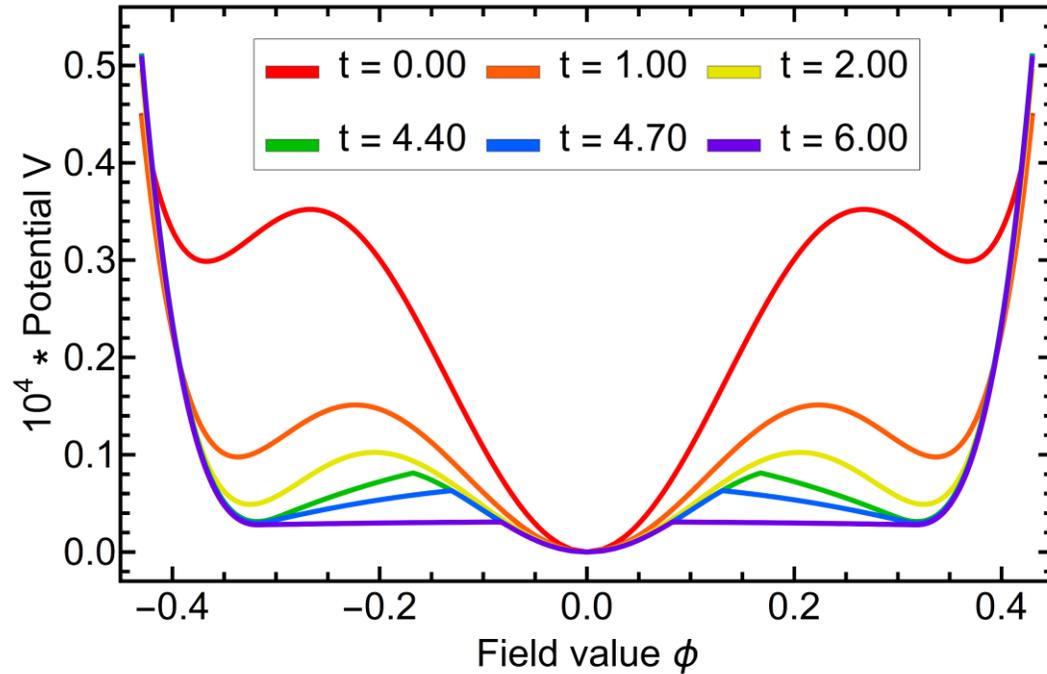
Calculated with $N=5$, $K=200$

Grossi, NW, arxiv:1903.09503

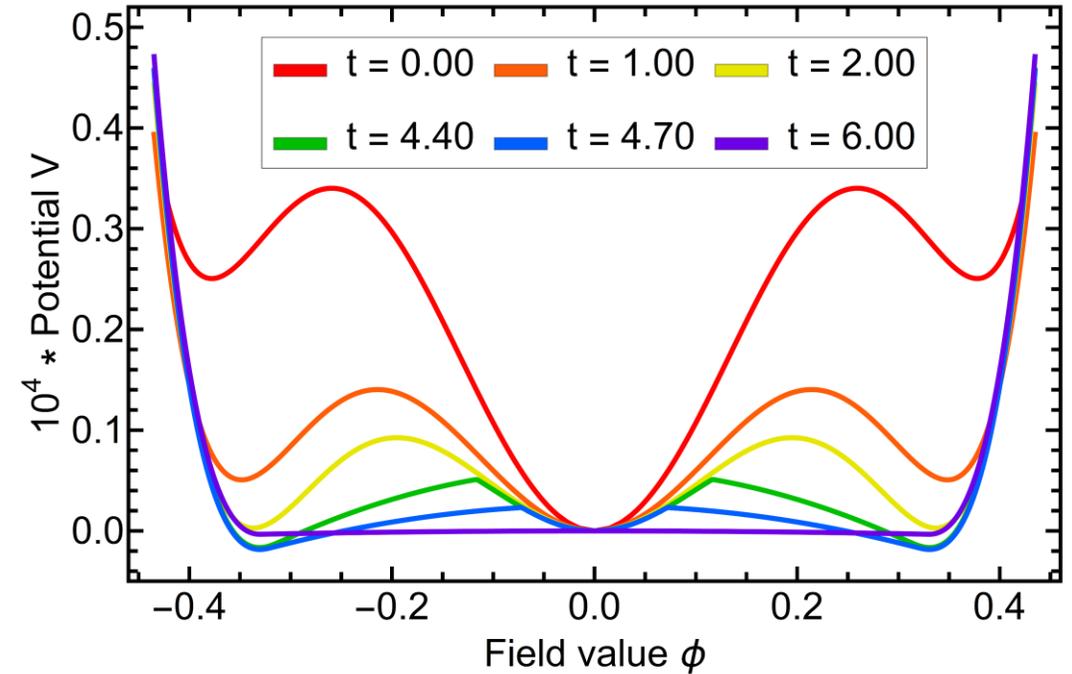
Potential

Initial condition: $u(t=0) = \lambda_2 + \lambda_4 \rho + \lambda_6 \rho^2$
with $\lambda_4 < 0$

Symmetric phase



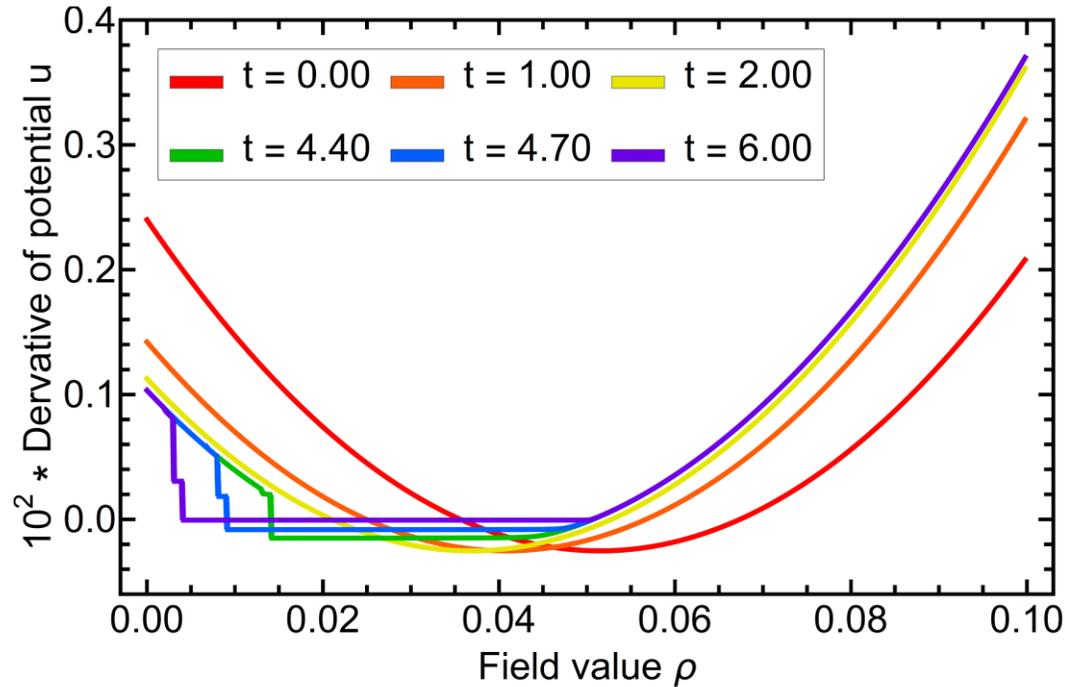
Broken phase



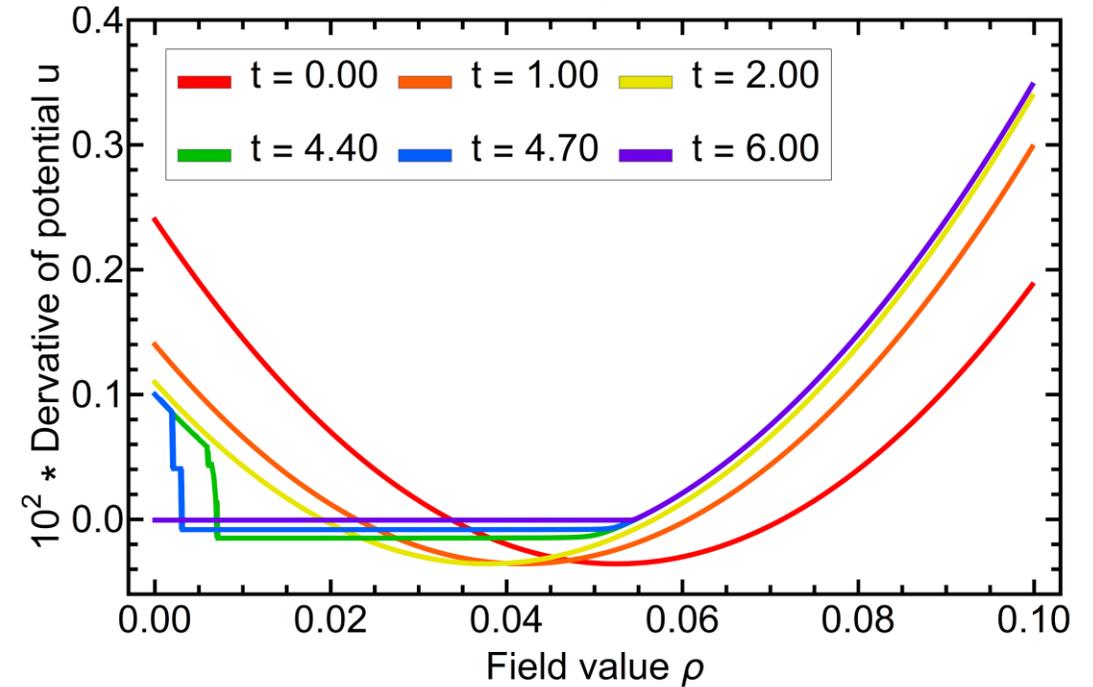
Initial condition: $u(t = 0) = \lambda_2 + \lambda_4 \rho + \lambda_6 \rho^2$
with $\lambda_4 < 0$

Derivative

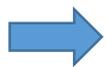
Symmetric phase



Broken phase



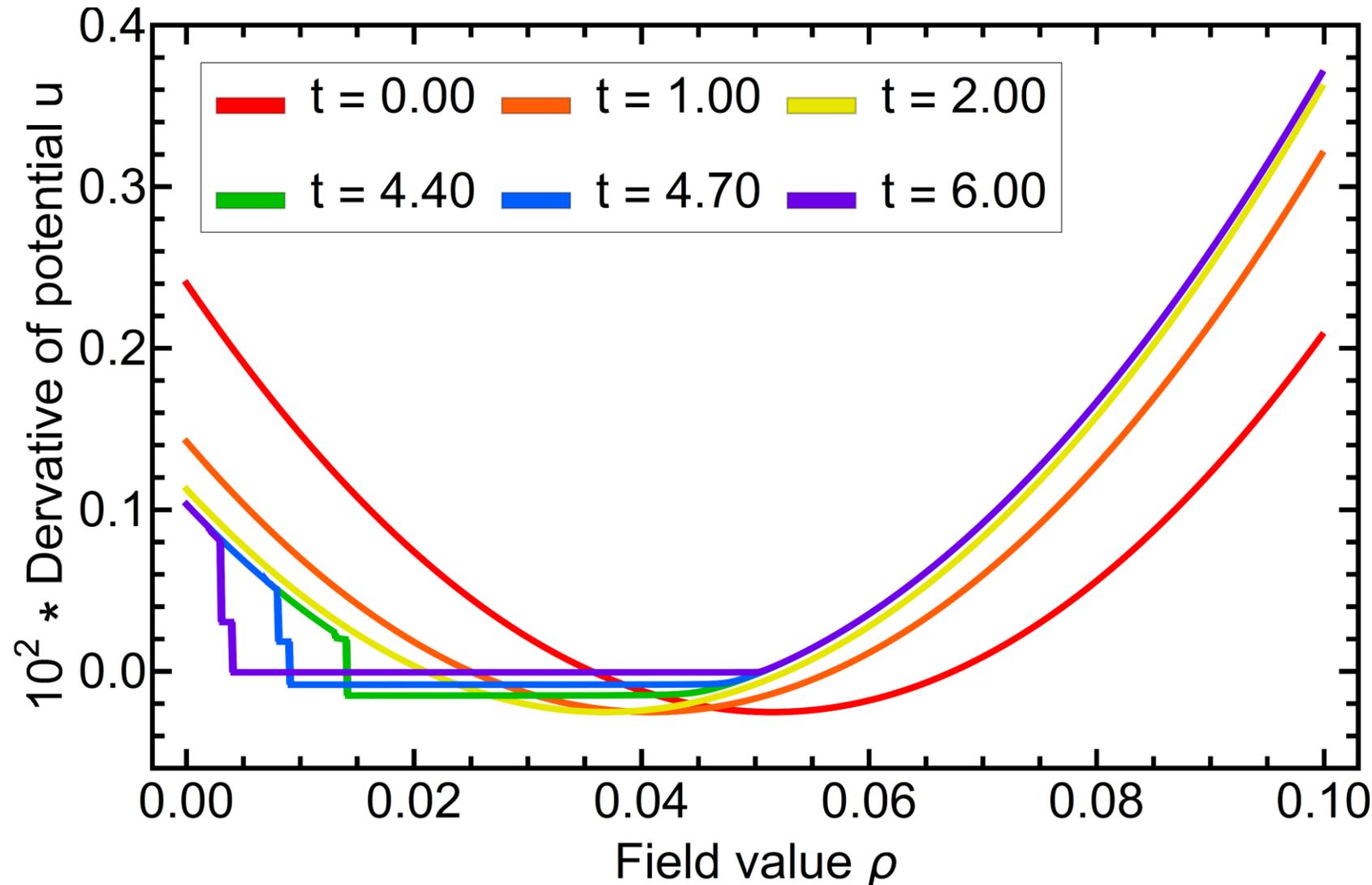
For other values of the coupling the shock doesn't freeze for positive values of the field



Mechanism for first order phase transition in terms of shocks

Initial condition: $u(t=0) = \lambda_2 + \lambda_4 \rho + \lambda_6 \rho^2$ with $\lambda_4 < 0$

Derivative



- Symmetric phase
- **Jump discontinuity forms and freezes in!**
- Non-trivial second minimum present
- First order phase transition during the flow

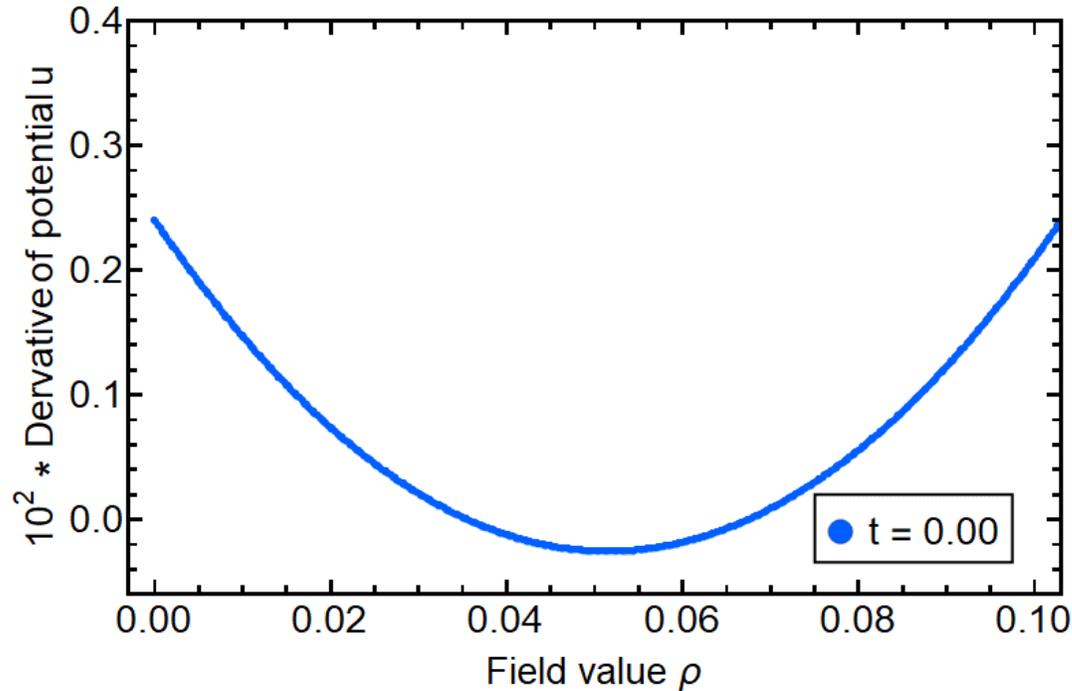
Calculated with $N=5$, $K=200$

Grossi, NW, arxiv:1903.09503

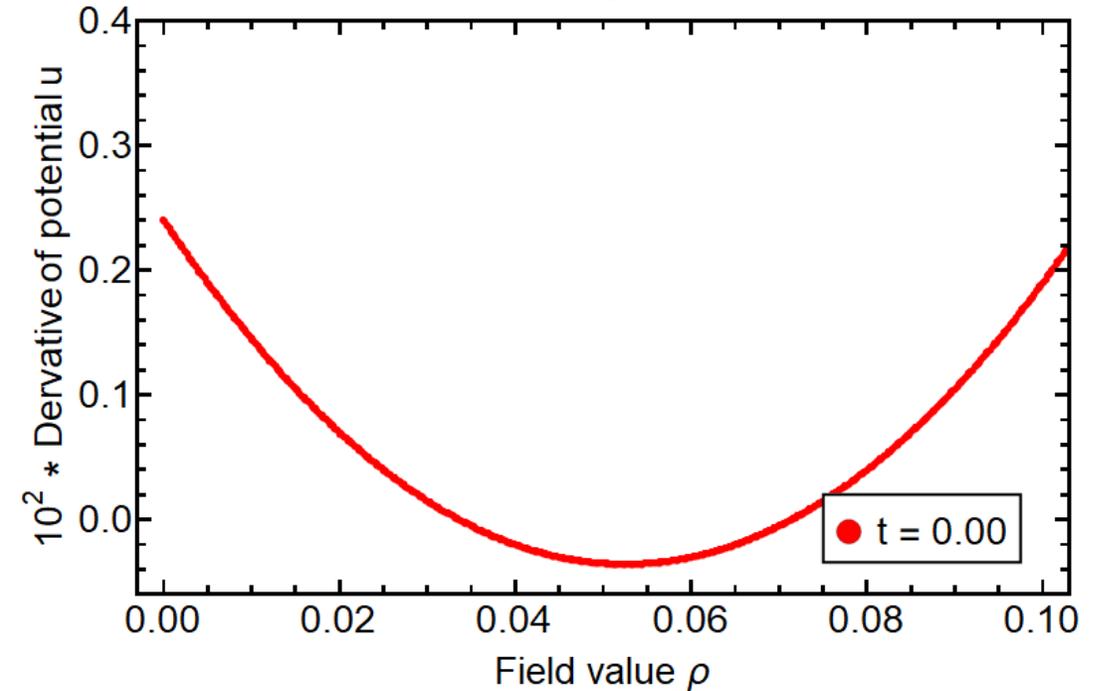
Derivative

Initial condition: $u(t = 0) = \lambda_2 + \lambda_4 \rho + \lambda_6 \rho^2$
 with $\lambda_4 < 0$

Symmetric phase



Broken phase



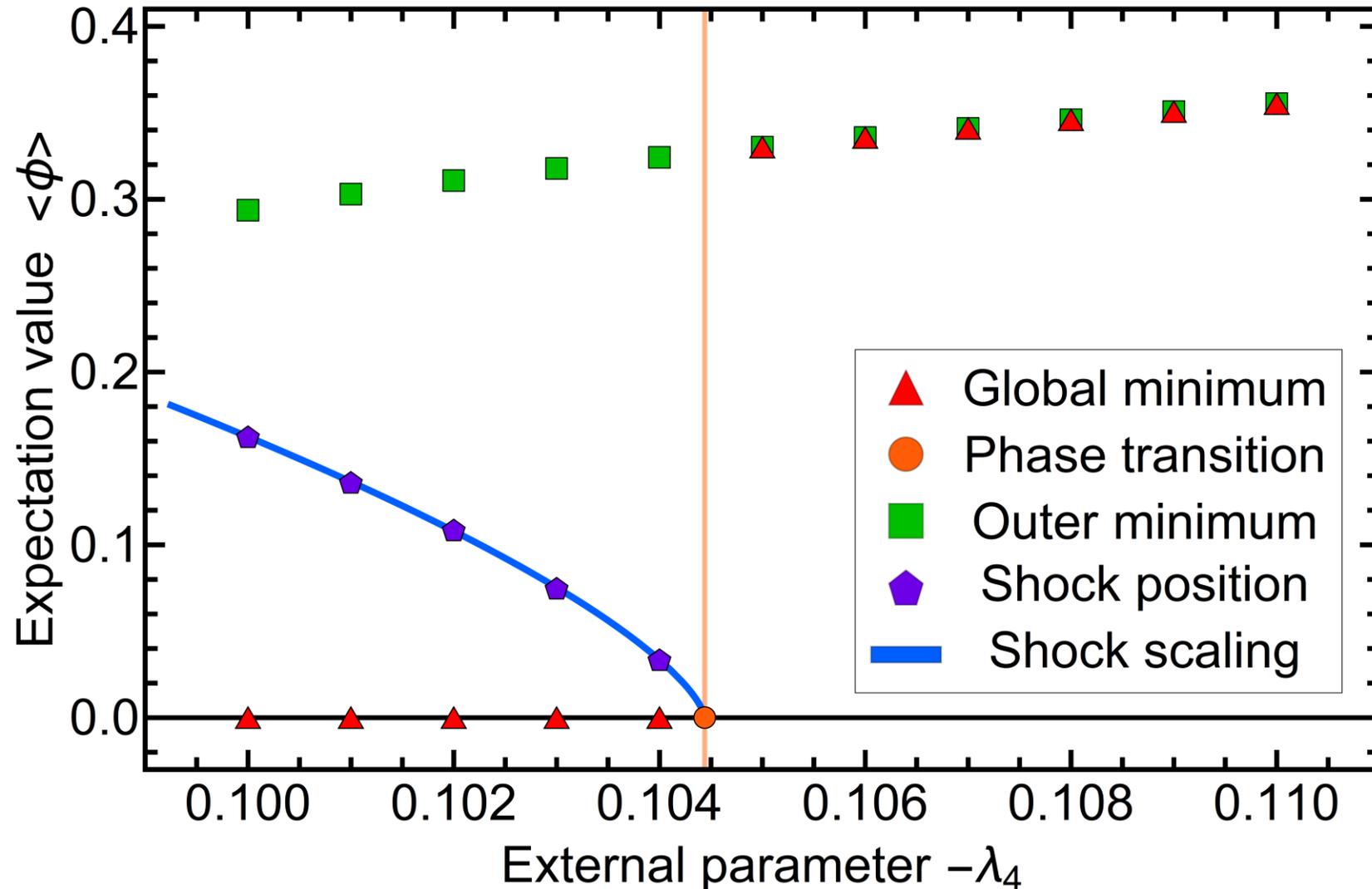
For other values of the coupling the shock doesn't freeze for positive values of the field



Mechanism for first order phase transition in terms of shocks

1st-order phase transition

Initial condition: $u(t=0) = \lambda_2 + \lambda_4 \rho + \lambda_6 \rho^2$
with $\lambda_4 < 0$



- First order phase transition
- Position of the phase transition determined by “second order transition” of the position of the shock
- Shock agrees with power law (exponent: 0.68 ± 0.01)
- Universal properties?

Beyond Large N

Including Diffusion

$$\partial_t u + \partial_x f^{(c)}(u, t, x) + \partial_x f^{(D)}(u, \partial_x u, t, x) = s(u, t, x)$$

$$\partial_t u + \partial_x f(u, q) = 0$$

$$q = \partial_x u$$

- Reformulate as first order system
- Diffusion term almost everywhere convection dominated
- Consider Finite Difference for now
(We also did DG methods)

- Convection dominated  Upwind scheme

$$\partial_t u + D_{\text{R}}^1 f(u, q) = 0$$

$$q = D_{\text{L}}^1 u$$

Quark Meson model

Chiral phase diagram

- Quark-Meson model topic in several talks

d=4 & N=4

c.f. Talks by Carl Zelle, Fabian Rennecke, Martin Steil,

- Resulting phase structure well known

Braun, Pawłowski, Rennecke, Schaefer, Wambach, and many more

$$\partial_t u + \partial_x f^{(c)}(u, t, x) + \partial_x f^{(D)}(u, \partial_x u, t, x) = s(u, t, x)$$

↑
Conservation term
(Pions)

↑
Diffusion term
(Sigma meson)

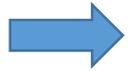
↑
Source term
(Quarks)

Chiral phase diagram

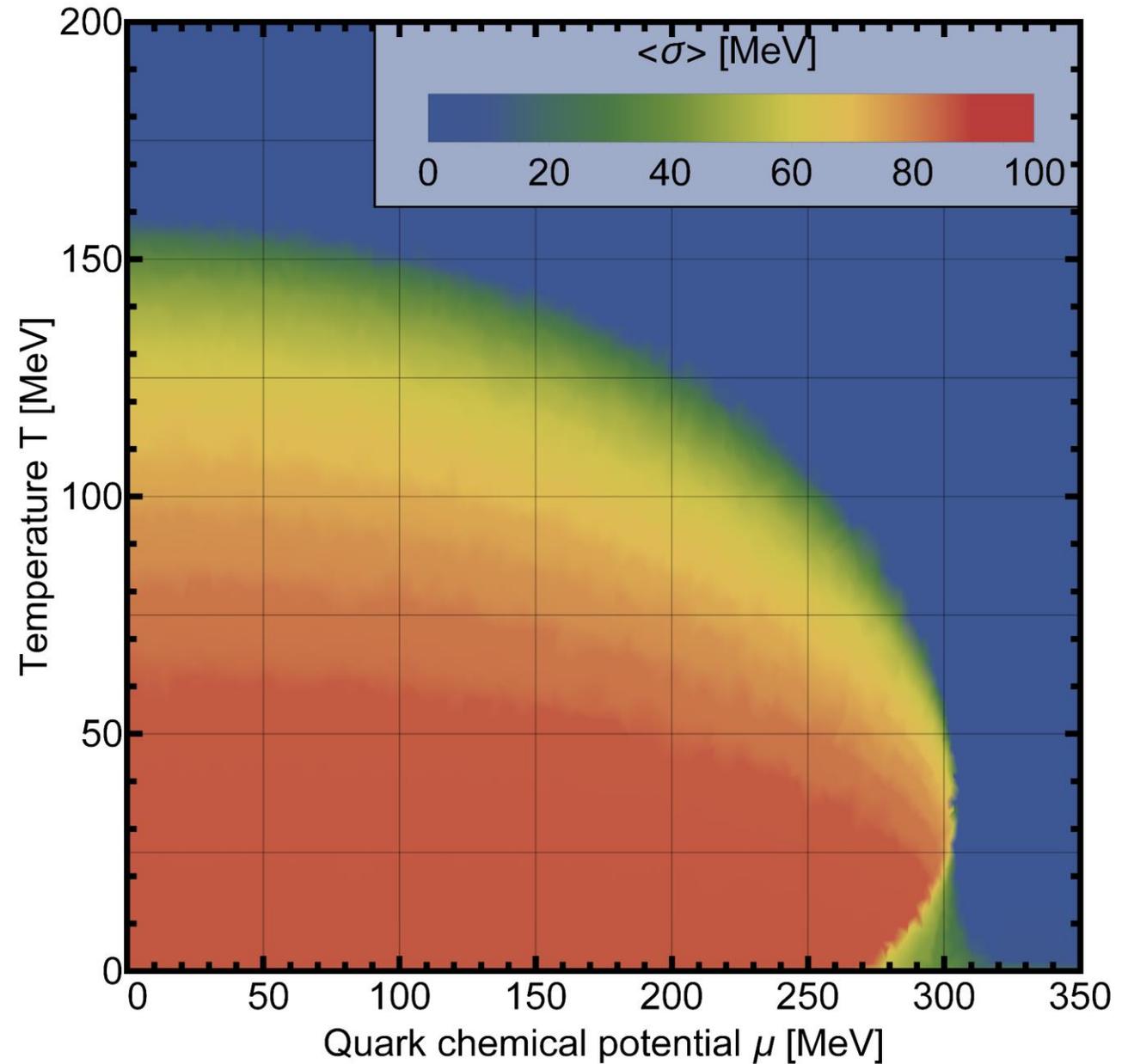
Stable scheme



No adjustment of grid points, final RG-time



Pick once and enjoy the result



Grossi, Pawłowski, NW, in prep.

DG vs FDM

$$\partial_t u + D_R^1 f(u, q) = 0$$

$$q = D_L^1 u$$

Pro & Cons of Finite Difference Methods:

- Stable
- Intuitive
- Extremely fast/easy to implement and use

- First order accurate (Godunov's theorem)
- Generalisation to higher dimensions induces headaches
- Efficient use of implicit methods becomes complicated
- Geometric flexibility (use RG properties)
- Finite accuracy quickly problematic (double precision)

- Analogy between hydro and flow equations
- Applying Discontinuous Galerkin methods to the FRG
 - Mechanism for first order phase transitions
- Robust numerical treatment in the vicinity of phase transitions

Thank you for your attention!

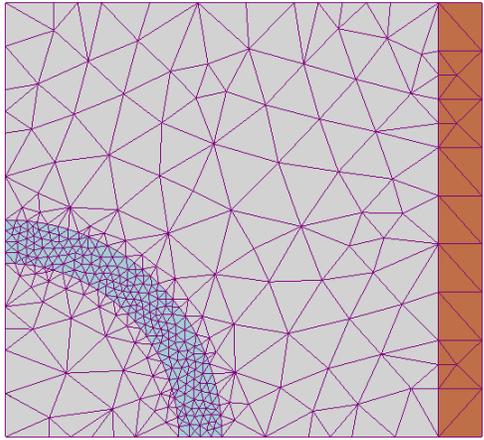
Discontinuous Galerkin methods

Different formulations

Modal expansion

Nodal expansion

$$u_h^k(t, x) = \sum_{n=1}^{N+1} \hat{u}_n^k(t) \psi_n(x) = \sum_{i=1}^{N+1} u_h^k(t, x_i^k) l_i^k(x)$$



Copyright: https://en.wikipedia.org/wiki/Finite_element_method

$$\int_{D^k} \left(\partial_t u_h^k + \partial_x f_h^k(u_h^k) \right) \psi_n \, dx = 0 \quad \rightarrow \quad \text{Discontinuous elements: More degrees of freedom than equations!}$$

Partial integration

$$\int_{D^k} \left((\partial_t u_h^k) \psi_n - f_h^k(u_h^k) \partial_x \psi_n \right) dx = - \int_{\partial D^k} \hat{\mathbf{n}} \cdot \mathbf{f}^* \psi_n \, dx \quad \text{Weak form}$$

Partial integration

$$\int_{D^k} \left(\partial_t u_h^k + \partial_x f_h^k(u_h^k) \right) \psi_n \, dx = \int_{\partial D^k} \hat{\mathbf{n}} \cdot (f_h^k(u_h^k) - \mathbf{f}^*) \psi_n \, dx \quad \text{Strong form}$$

Outward pointing normal vector Numerical flux Connects elements (closes set of equations)

Mathematically equivalent, but not numerically!

Implementation

Modal expansion

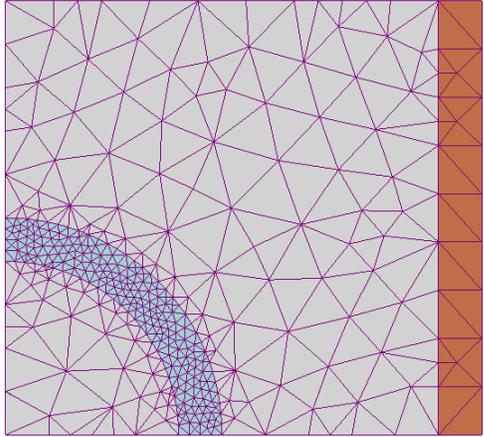
Nodal expansion

Local approx

$$u_h^k(t, x) = \sum_{n=1}^{N+1} \hat{u}_n^k(t) \psi_n(x) = \sum_{i=1}^{N+1} u_h^k(t, x_i^k) l_i^k(x)$$

Strong form

$$\int_{D^k} \left(\partial_t u_h^k + \partial_x f_h^k(u_h^k) \right) \psi_n \, dx = \int_{\partial D^k} \hat{\mathbf{n}} \cdot \left(f_h^k(u_h^k) - f^* \right) \psi_n \, dx$$



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Introduce matrices:

Mass matrix

$$\mathcal{M}_{ij}^k = \int_{D^k} l_i^k(x) l_j^k(x) \, dx$$

Stiffness matrix

$$\mathcal{S}_{ij}^k = \int_{D^k} l_i^k(x) \partial_x l_j^k(x) \, dx$$

Discretized equation

$$\mathcal{M}^k \partial_t u_h^k + \mathcal{S}^k f_h^k = \left[l^k(x) (f_h^k - f^*) \right]_{x_l^k}^{x_r^k}$$

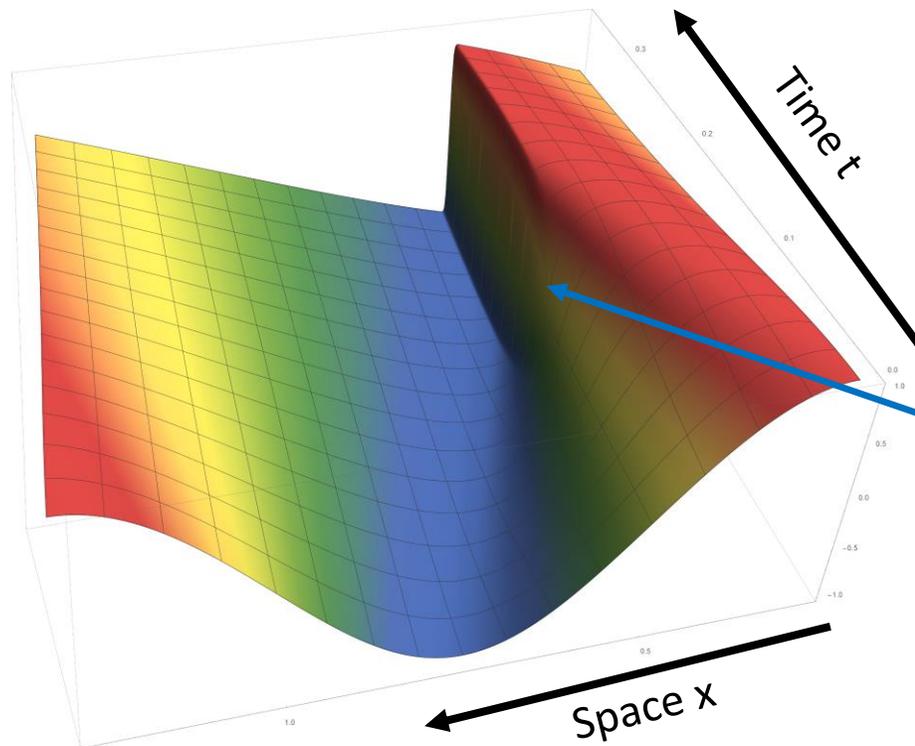
- Only requires local inversion of the mass matrix
- Introducing a reference element everything is rescaled to a matrix product (N x N)*(N x K)

Burgers equation

Burgers equation

$$\partial_t u + \partial_x f(u) = 0 \quad \text{with} \quad f(u) = \frac{1}{2}u^2$$

Prototype for conservation law that can develop shock waves



Appears in many areas of applied mathematics:

- Fluid mechanics
- Nonlinear acoustics
- Gas dynamics
- Traffic flow
-

- Simple wave as initial condition
- Wave breaks when characteristics meet
- Discontinuous regime well understood due to analytic solution of the viscous Burgers equation

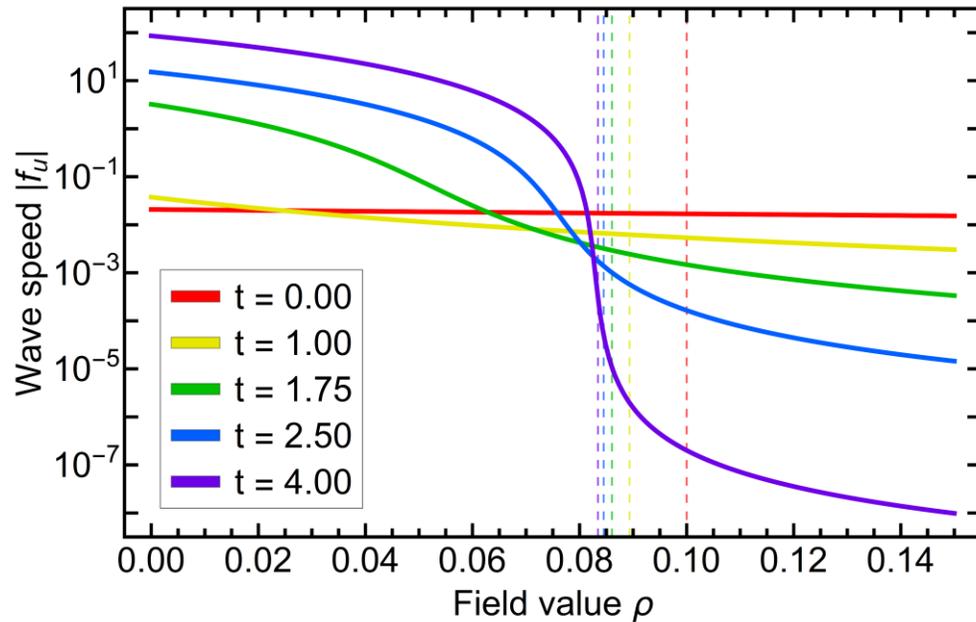
Wave breaks & shock wave forms

Second order phase transition

Other properties

Initial condition: $u(t = 0) = -\frac{1}{10} + \rho$

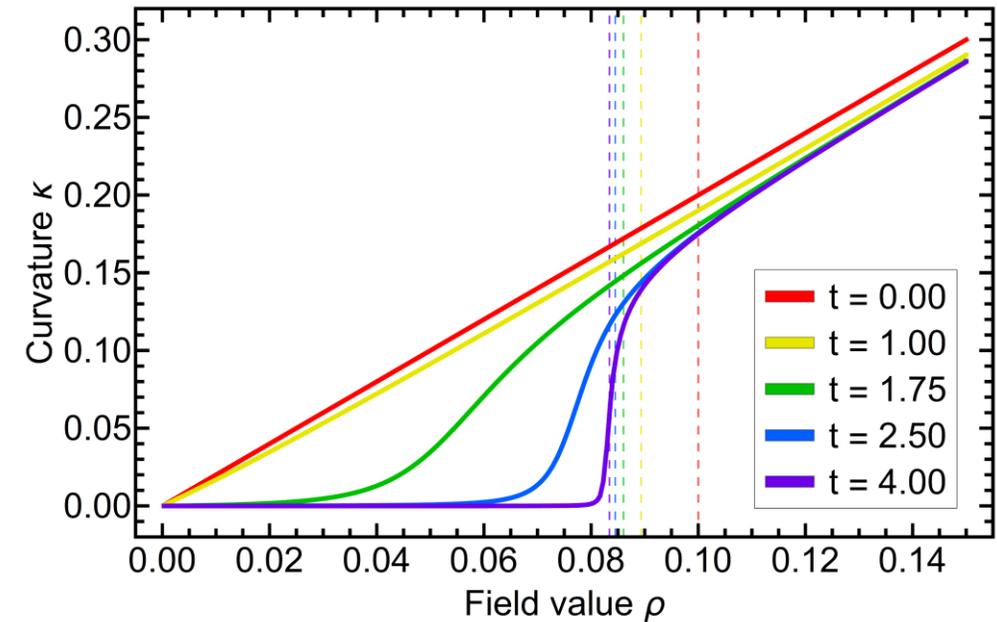
Wave speed



Wave speed strongly suppressed at large field values

➔ Justifies Taylor methods in that regime
(only local structure relevant)

Curvature



Derivatives are easily available

Riemann problem

Riemann problem

$$f(t, u) = -\frac{\Omega_d}{d(2\pi)^d} \frac{(\Lambda e^{-t})^{d+2}}{(\Lambda e^{-t})^2 + u}$$

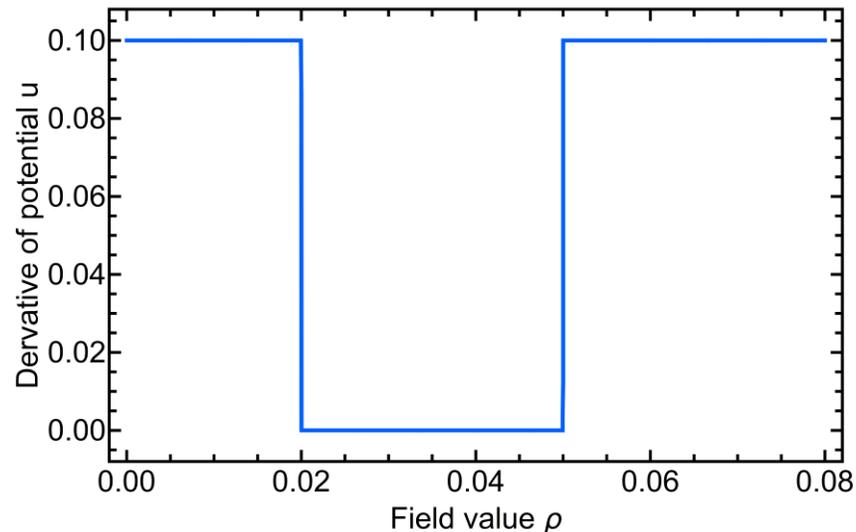
Information flows from large to small field values and is faster for smaller values of the derivative!
What does this imply for discontinuities?

➔ Jump discontinuities can form if the derivative of the initial potential has a minimum

➔ Relevant in physical cases

$$u(t=0) = \lambda_2 + \lambda_4 \rho + \lambda_6 \rho^2$$

Consider the initial conditions:



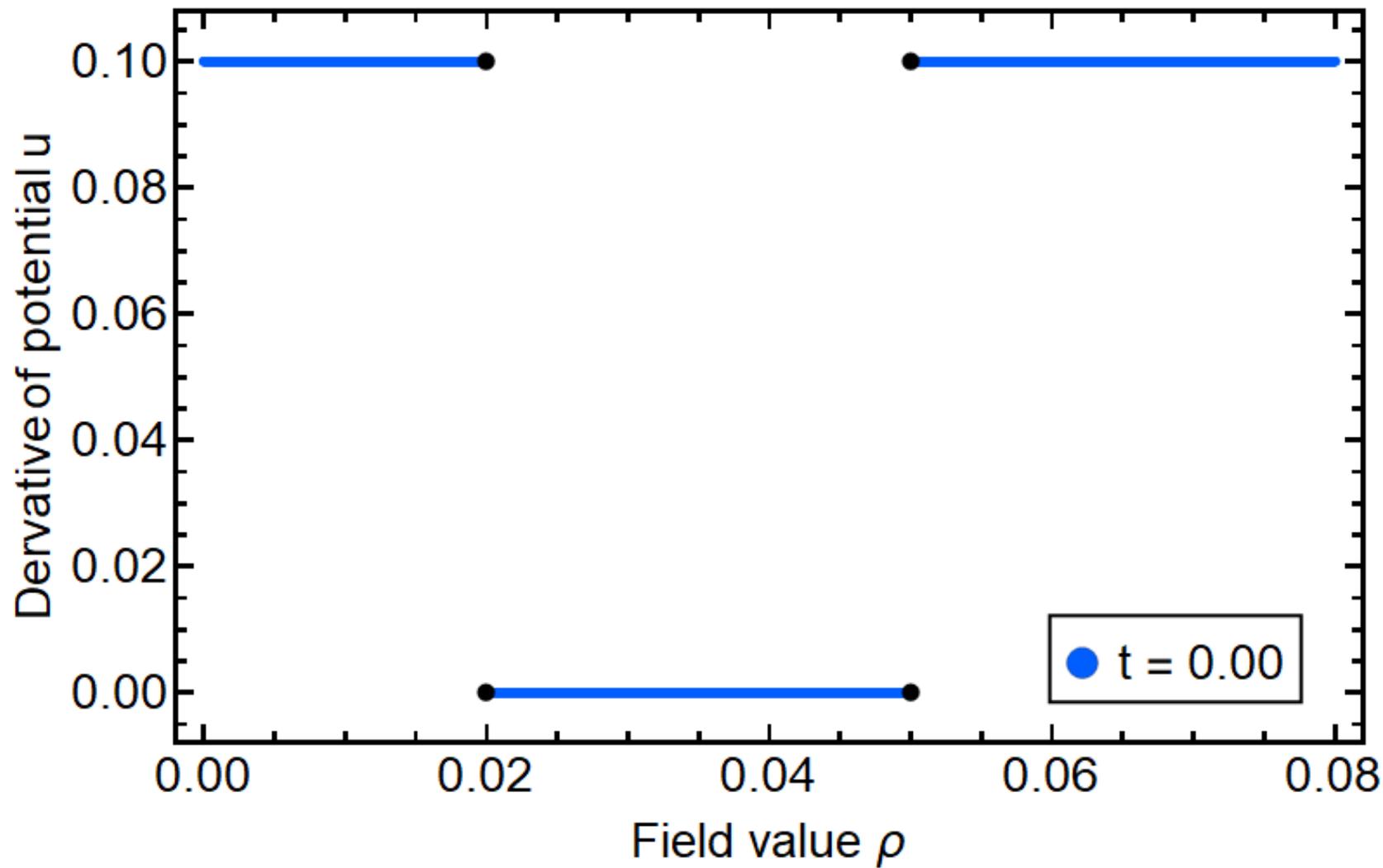
Solving for piecewise constant initial conditions known as Riemann problem

➔ Left jump will lead to shock wave
(Speed given by Rankine-Hugoniot condition)

➔ Right jump will lead to rarefaction wave

➔ Unique solution defined via entropy condition

Derivative

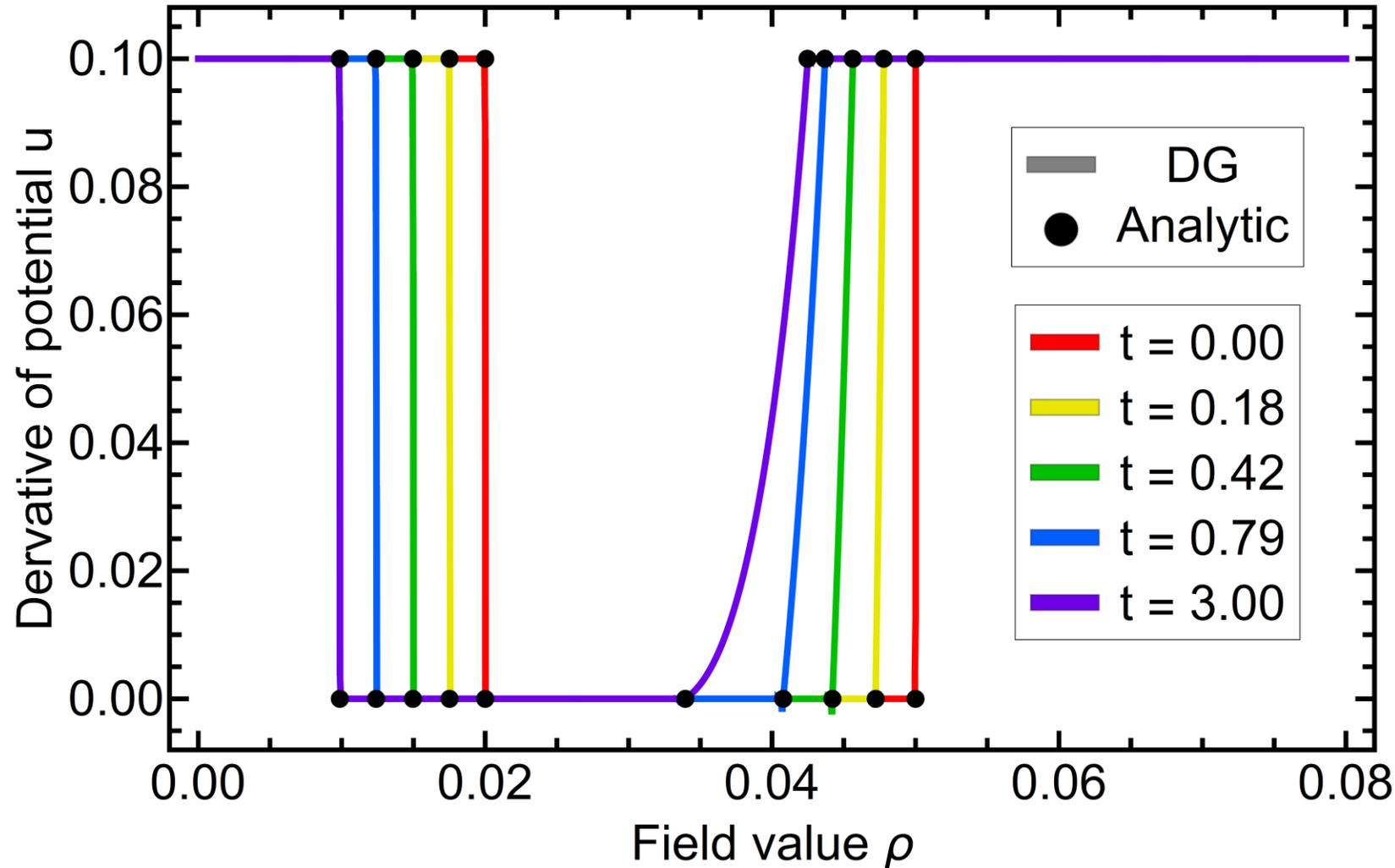


Calculated with $N=3$, $K=1500$

Derivative

Position of jump discontinuity:

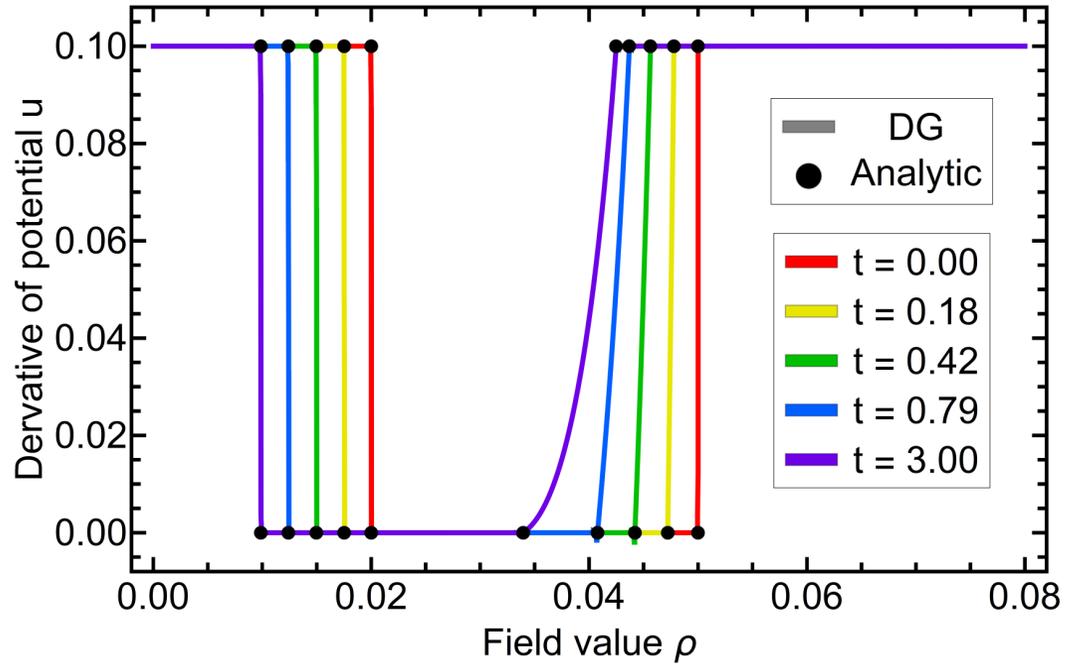
$$\xi(t) = \frac{6\pi^2\xi_0 + \sqrt{u^+} \left(\tan^{-1} \left(\frac{1}{\sqrt{u^+}} \right) - \tan^{-1} \left(\frac{e^{-t}}{\sqrt{u^+}} \right) \right) + e^{-t} - 1}{6\pi^2}$$



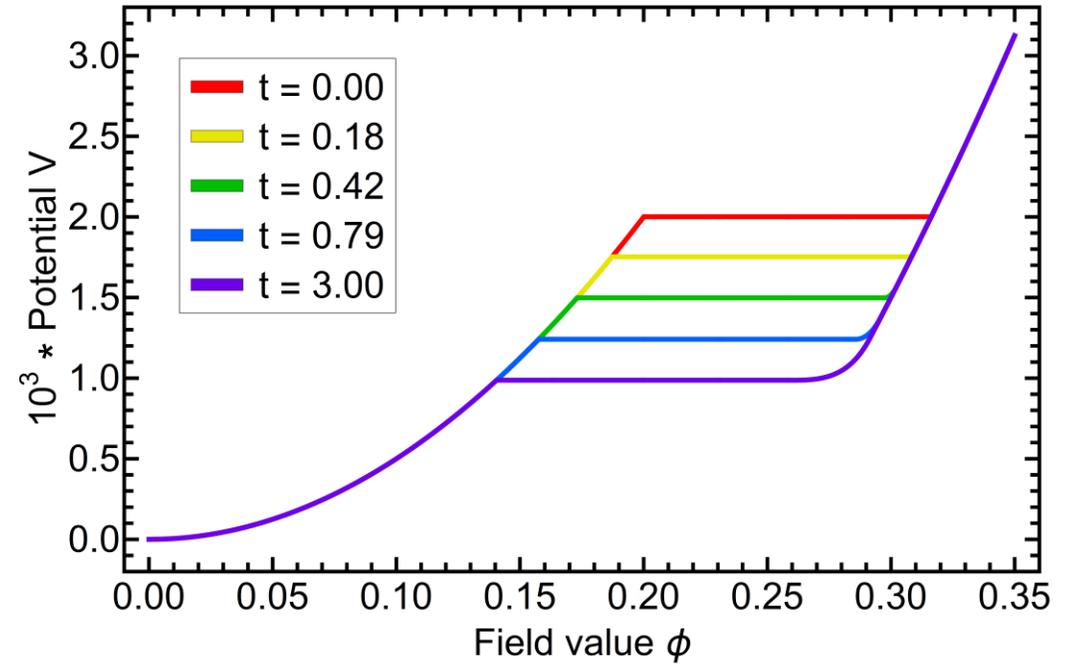
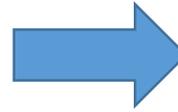
- Points of non-analyticities easily obtained analytically
- Change suppressed exponentially for large times
- Change additionally suppressed for larger jumps
- Oscillations removed in post-processing (formal accuracy can be kept!)

Calculated with $N=3$, $K=1500$

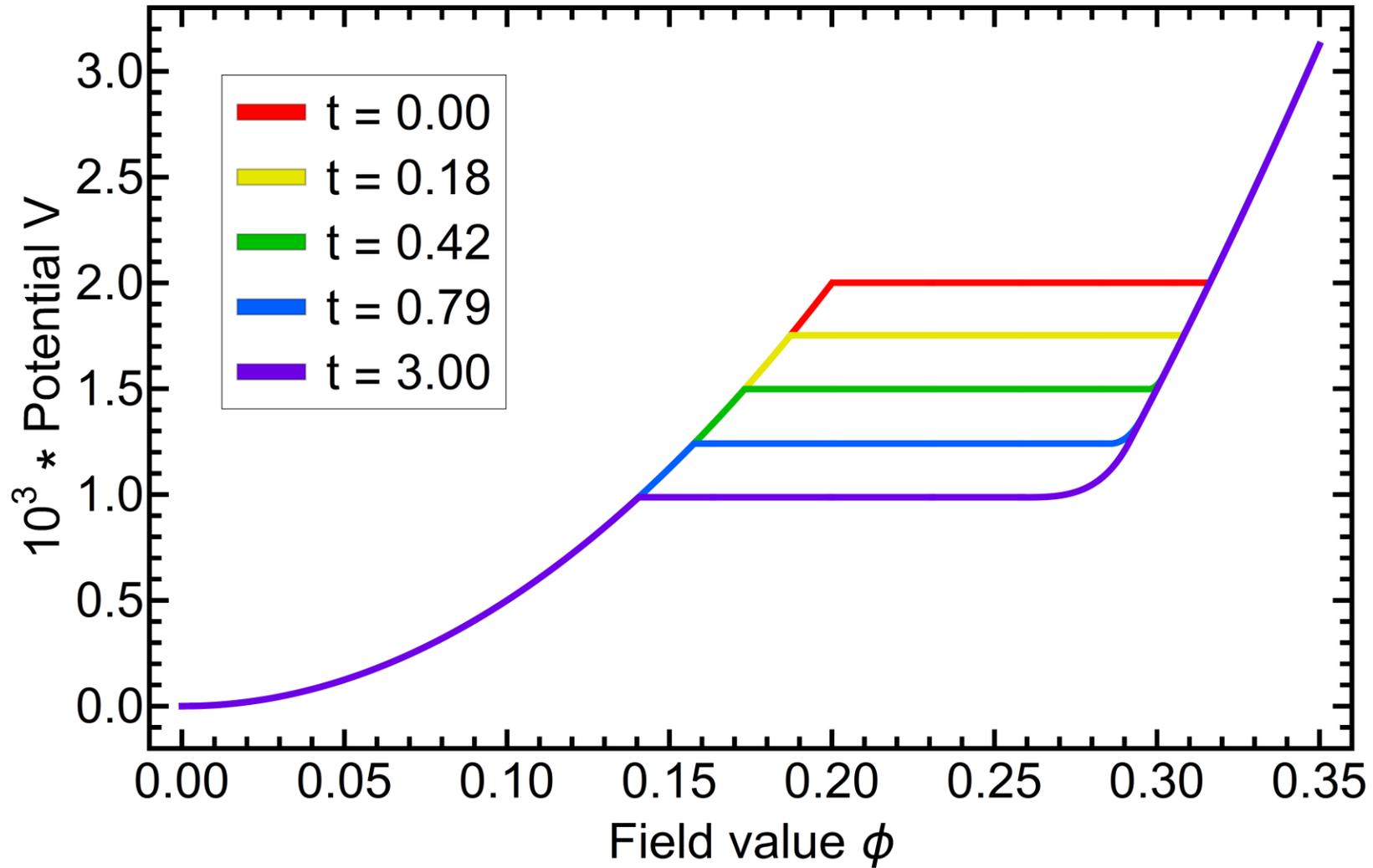
Riemann problem



Integration

Calculated with $N=3$, $K=1500$

Potential

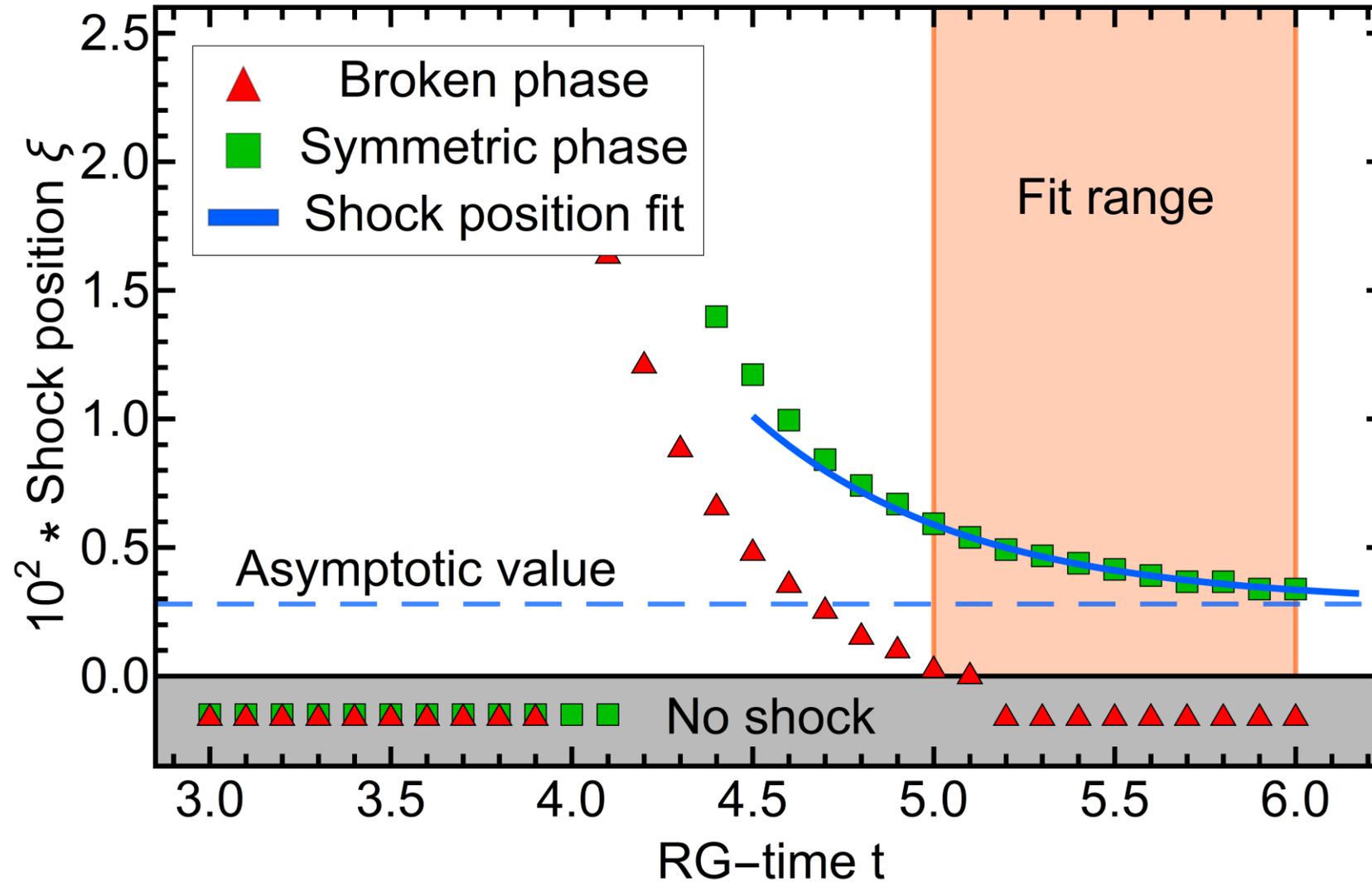


Calculated with N=3, K=1500

First order phase transition

Shock position

Initial condition: $u(t=0) = \lambda_2 + \lambda_4 \rho + \lambda_6 \rho^2$

with $\lambda_4 < 0$ 

- Position extracted via concentration kernel
- Asymptotic behavior determined by Riemann problem
 - ➔ Exponential decay
- Confirmed by numerical simulation
- Extrapolation to asymptotic limit easily possible

Calculated with $N=5$, $K=200$