

Hit-Reconstruction and Calibration for eToF



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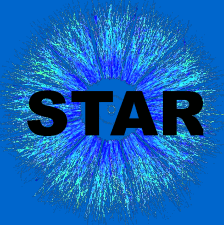
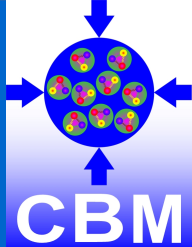
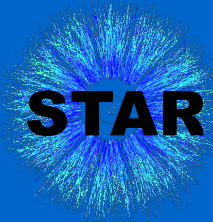


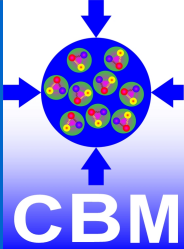
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Hit Reconstruction



Basic data format out of daq-file unpacking:

StETofDigi: time
 time over threshold
 electronic channel address

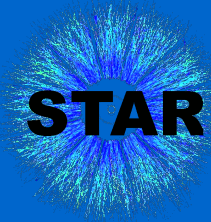
Information needed for track matching:

StETofHit: time
 position

➡ Task: reconstruct precise hit information from digis

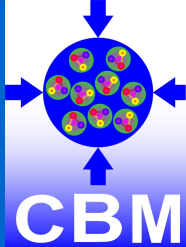
Two step strategy (adapted from CBM test-beam experiences):

1. Match digis from different sides of the same detector strip into single strip hits
2. Cluster single strip hits into multi-strip hits based on time and position correlation



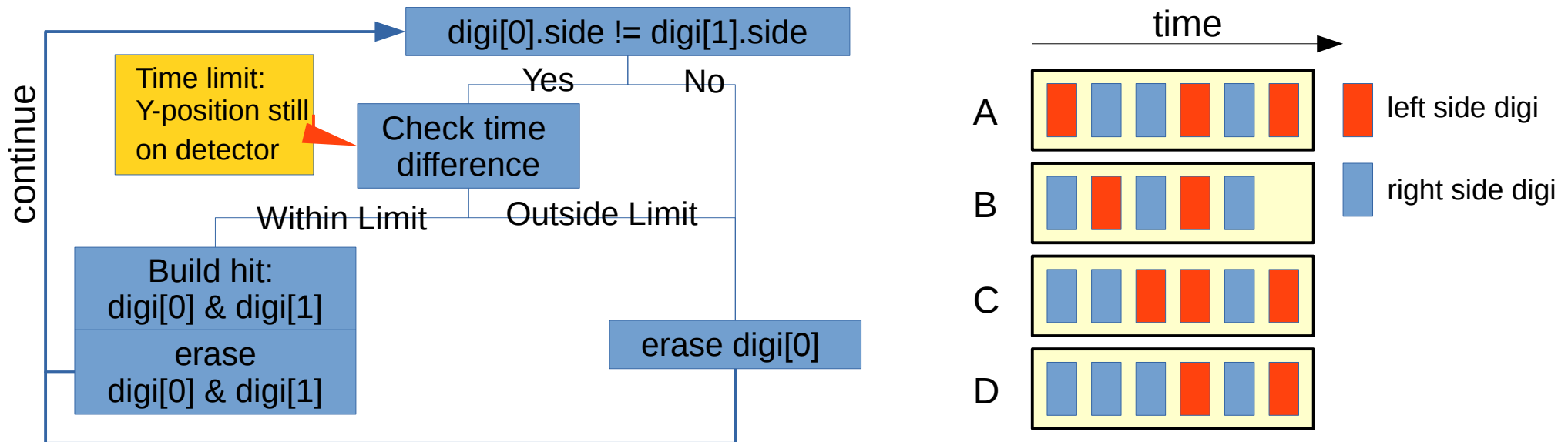
Hit Reconstruction

Digi matching



Strategy:

1. Sort Digi from both sides of a detector strip into a common vector
2. Sort digi in the vector by time
3. Start checking digis at beginning following the strategy below



Once matched, reconstruct hit time and position:

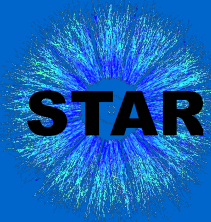
$$t = (t [0] + t [1]) / 2$$

$$x = x \text{ (strip)}$$

$$y = (t [0] - t [1]) / 2) * \text{signal velocity}$$

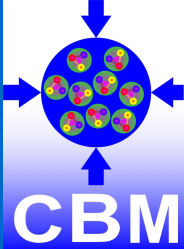
$$z = z \text{ (module)}$$





Hit Reconstruction

Cluster merging



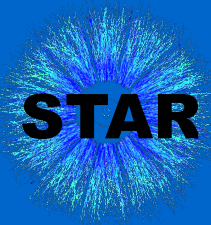
WHY:

- Physical avalanches induce signals on more than one strip => Correlated signals
- Multiple measurements of the same avalanche => improved resolution in x,y,t
- Reduction in combinations for track matching

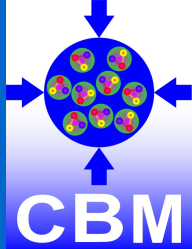
Strategy:

1. Sort single strip hits on the same MRPC into common vector
2. Sort hits in the vector by time
3. Check 4D-distance between hits
4. Merge hits on adjacent strips if $(\Delta y / v_{sig})^2 + \Delta t^2 > r_{merge}$
5. Recalculate x,y,t based on ToT-weighted average





Effects to consider for calibration:

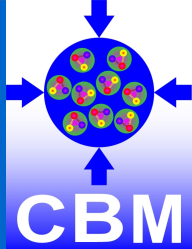


- 1. Clock reset delays between eToF and bToF (constant)
- 2. Clock range differences between eToF and bToF (constant)
3. Cable delays between eToF electronic channel
 - 3a: local y-position offsets (iterative)
 - 3b: T0 offsets (iterative)
- 4. Gain differences between eToF preamplifier channel (iterative)
- 5. Signal height dependence of signal times: Walk / Slewing (iterative)
- 6. Global position offsets (hopefully constant)
- 7. Signal velocity differences between MRPCs (constant)



Software

What happens where?



CBM - side

DigiMaker

CalibMaker

HitMaker

Matchmaker

QAMaker

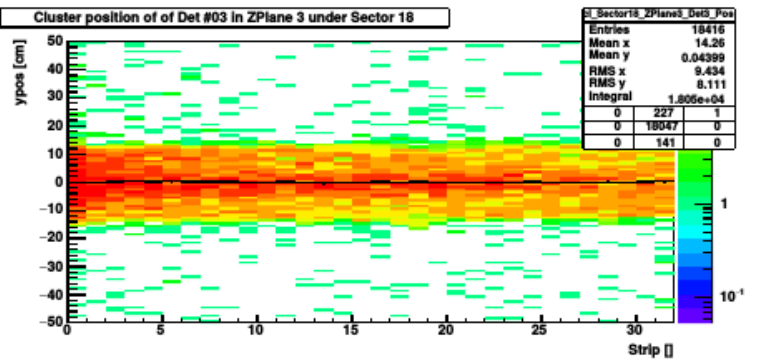
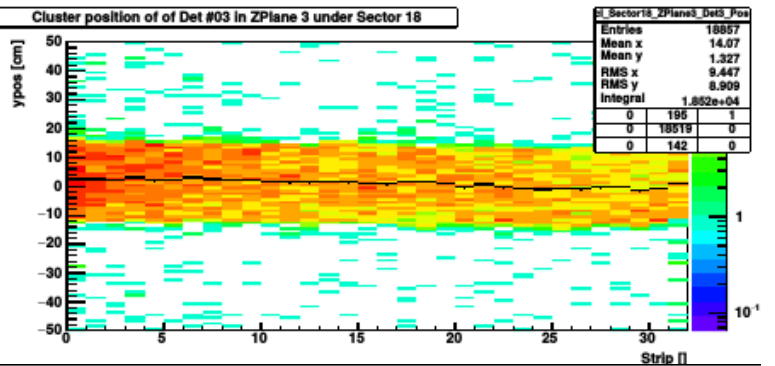
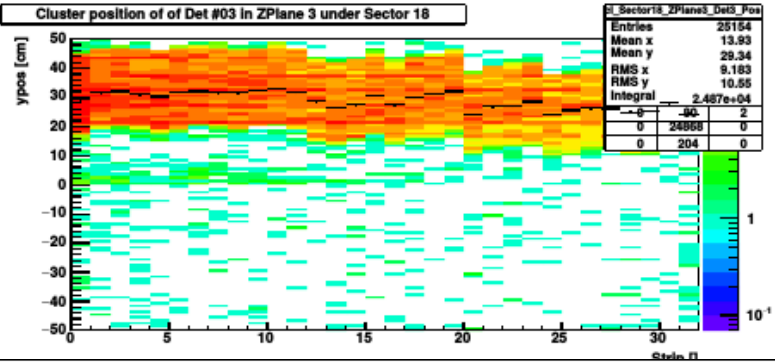
Applies all calibrations from previous steps to digis:
T0, Y-position, Walk, ToT gain, Clock offset

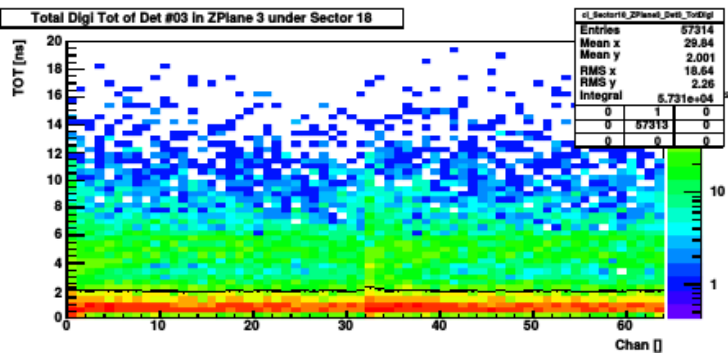
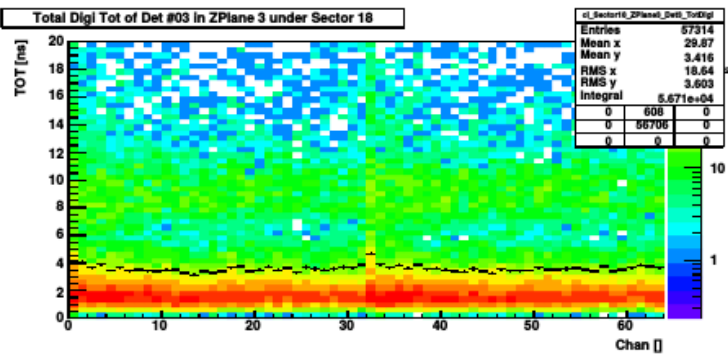
Clock range is adjusted only in hit reconstruction to avoid overflow issues

Global position adjustments are done to the geometry and T0 offsets are calculated

Calibration histograms for the next iteration are created and filled.

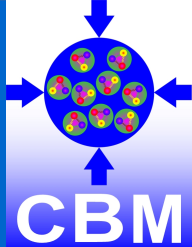
- Initial hit positions are significantly shifted in the local coordinate frame of the counter due to delays between sides.
- calculate mean position of hits on each strip
- calibrate digi times such that the mean y-position is shifted to 0. Apply half of the correction to each side to keep T0 offset constant.
- Procedure has to be iterative due to rebuilding of hits in between iterations and cross-correlation with walk correction
- Careful: Hotspots can skew the mean position on a strip. No problem in triggered data. Otherwise, fit box function instead of just taking mean.





- Amplification gain between pre-amp channels varies slightly => ToT spectra are slightly different
- Comparable ToTs are needed for averaged walk calibrations and ToT-weighting in hit reconstruction
- No cross-correlations to other calibrations. Should converge immediately.
- Iterations for some reason improve things a bit.

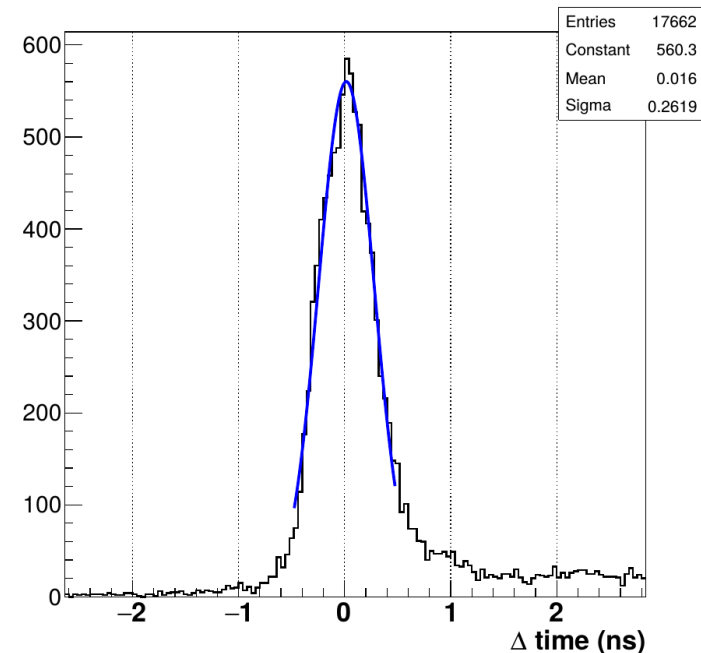
T0 determination

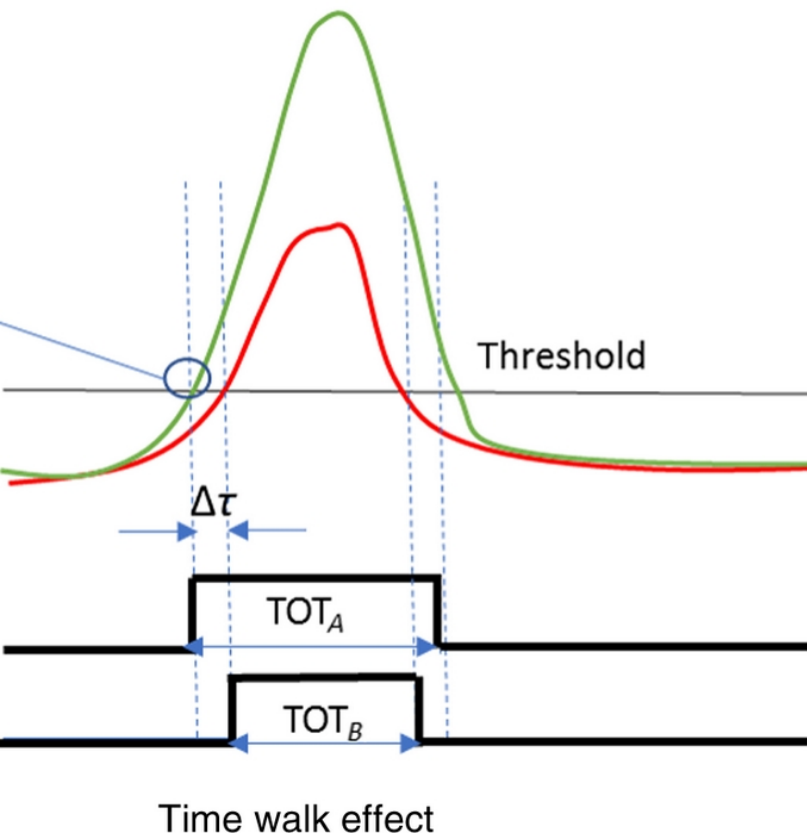


- Reset signal is routed from bToF/VPD to eToF Daq and recorded on eToF Clock
=> Can be subtracted directly from raw time.
T0 offsets should be constant afterwards!

Problem: Reset signal reached only one AFCK in 2018 runs

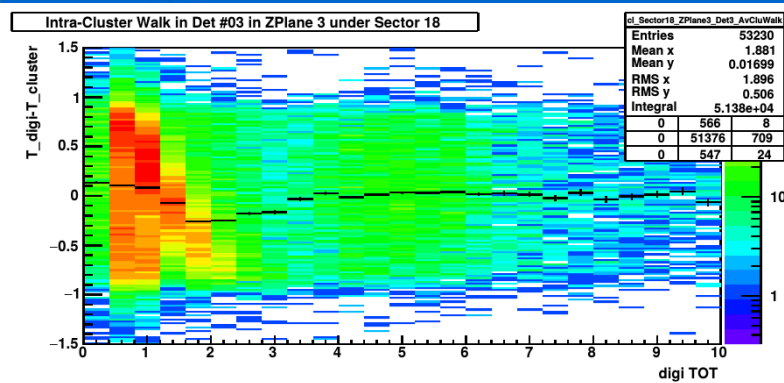
- eToF-clock is reduced to match 11bit bToF-Clock after hit-building to reduce losses due to overflow.
=> now times are comparable between eToF and bToF/VPD
- T0 offset is determined by the peak position in (measured – expected) time of flight histogram and subtracted from all digis





taken from <https://doi.org/10.1117/1.OE.56.3.031224>

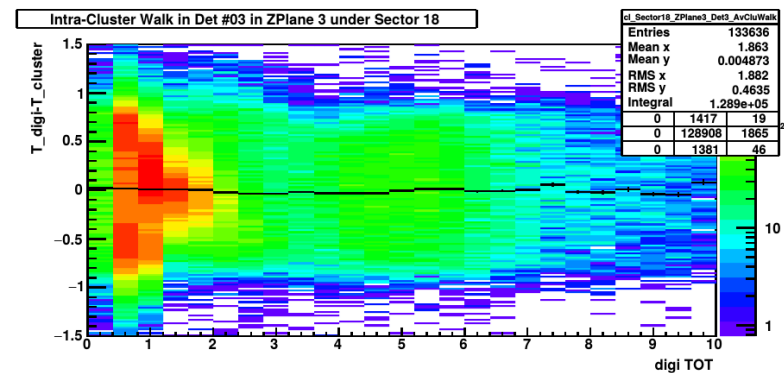
- Walk is a general correlation between signal detection time and signal amplitude. This effect is on single digi level.
- Tot can be used as a substitute for signal amplitude
- Time has to be taken with respect to some reference
Usual choice: Time of hit - expected time of flight
- Alternate choice: Time of digi – time of hit
- Idea: all signals in a hit are produced at the same time. Signals are registered at different times due to propagation time and walk. Propagation time should average out with sufficient statistics



- Walk effect ~ 300 ps can be seen before calibration. Gone afterwards.

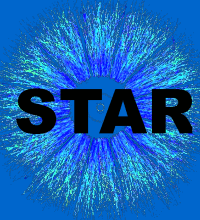
Advantages:

- Only ETof information required
- Works with any avalanche. No track match required. High statistics.

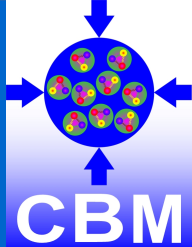


Disadvantages:

- Need to be very careful not to mess with position information => have to average over el. channels on both sides
- Self-correlation between digi time and hit time => slow convergence
- Influence on y-position is apparently not completely averaged out => Problem for track matching
- Channel averaged walk calibration limits detector resolution $O(100$ ps). Good enough to spot problems with eToF, need to get better for data analysis!



Walk correction Further steps



- Need to go to a calibration mode with respect to expected time of flight.
- Has to be done after track matching. Almost done.
- Workload of changing this mode: Change ~5 lines of code

BUT:

- High statistics in every channel and ToT bin needed.
~ 10^6 Events per iteration & $O(10)$ iterations!
- Currently: 2-3s / Event! (maybe improved now ?)
=> Need massive speed up in the runtime of the EToF change or/and parallelization!

Optimization: Memcheck: no major memory leaks
Event-by-Event print-outs disabled
=> I'm out of ideas!

Parallelization: Work in Progress!

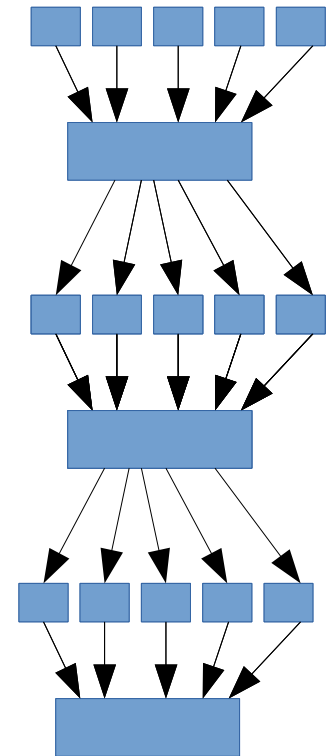
μ DST integration: Work in Progress!

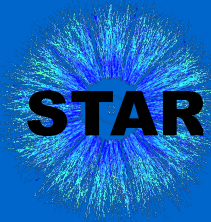
Strategy:

Run iteration in parallel jobs

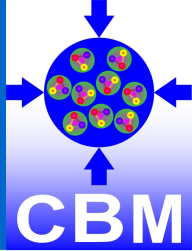
Merge into high statistics calib file for next iteration

Apply calib file in each parallel process and run next iteration





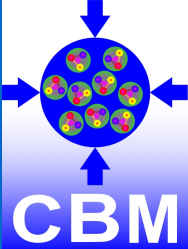
Outlook: What is still needed for next year?



1. Improved walk calibration
=> see last slide
2. StarDB integration of calibration files
=> DB content to be finalized in this meeting
3. Automatize procedure to create calibration files for next year

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Experiences with the eToF calibration will be applied in CBM!



THANK YOU FOR YOUR ATTENTION!