


Central Pattern Recognition

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A central tracker pattern recognition

This Pattern Recognition code was written for the Central part of the  detector and uses the MicroVertex Detector, the Straw Tube Tracker and the SciTil detector.

Basic assumptions used :

- 1) a t_0 is available somehow and consequently the drift time of the each Straw Detector hit is known;
- 2) tracks come from the interaction vertex at $(0,0,0)$

ALSO : tracks with less than 2 Straw axial hits and 1 MVD hit are NOT reconstructed.

PANDA
MicroVertex Detector

MicroVertex Detector (MVD)

Pixels : 10.3 M Channels
Strips : 200 K Channels

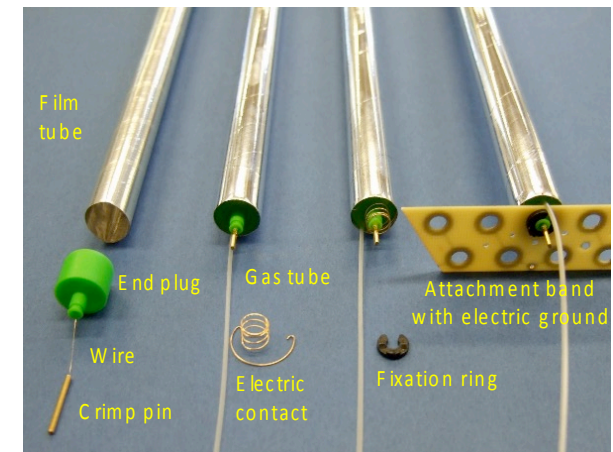
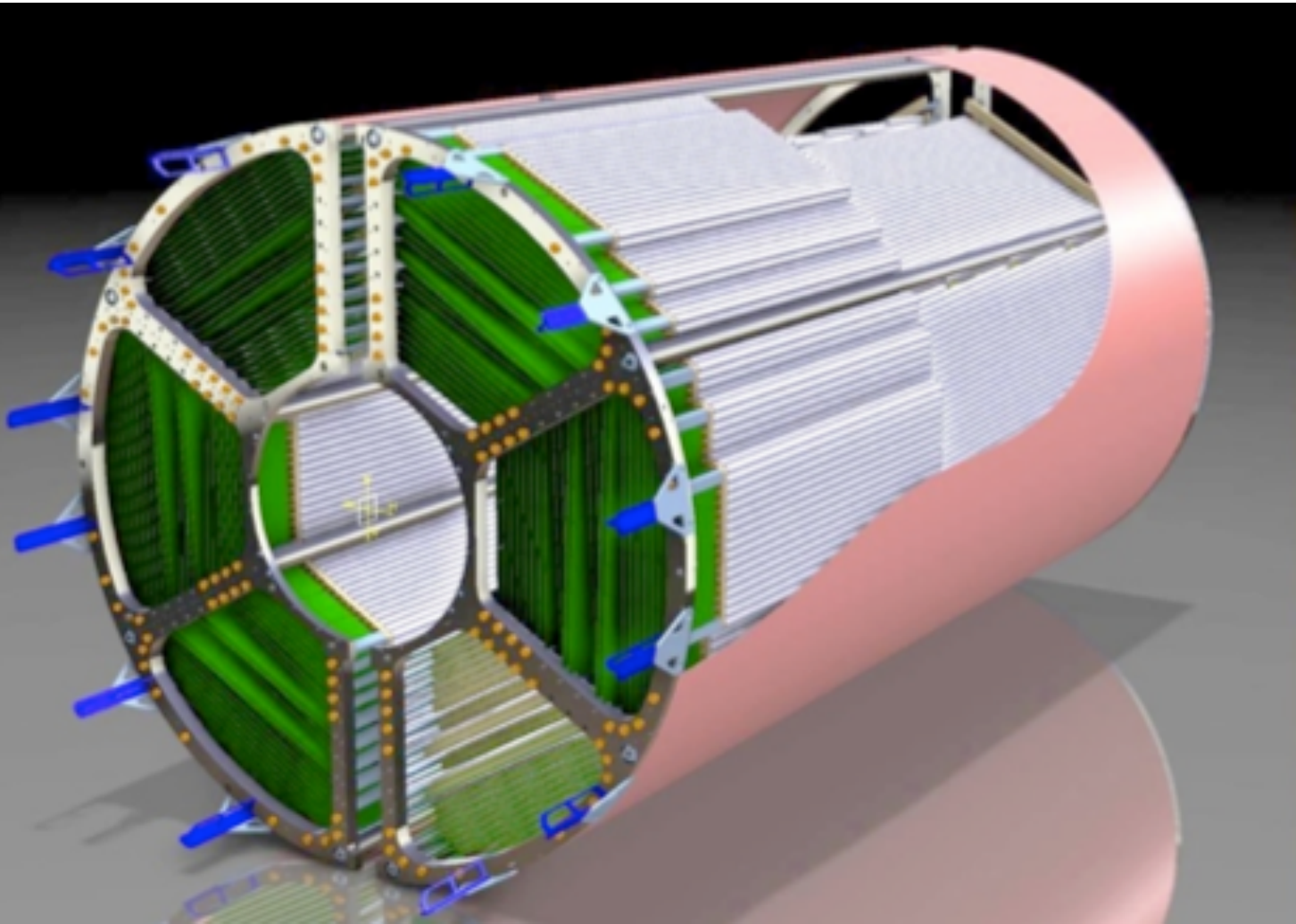
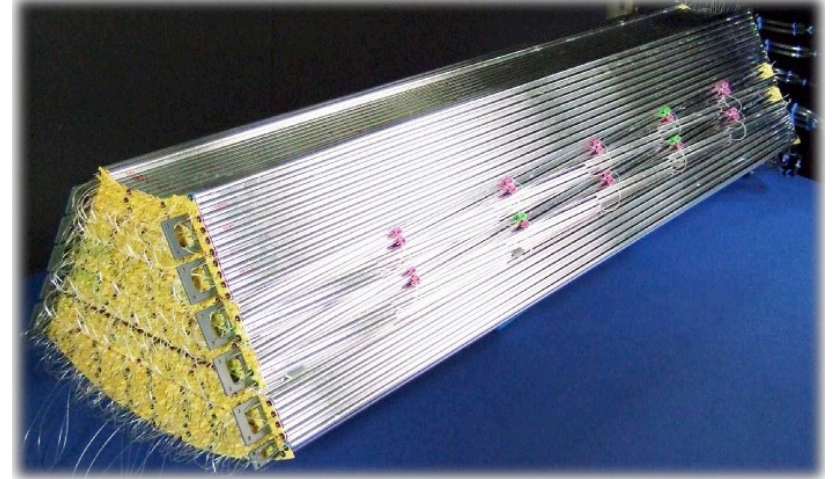
BEAM

A 3D cutaway diagram of the MicroVertex Detector (MVD) installed in a particle accelerator. A red arrow labeled "BEAM" points from the left towards the detector. The detector is a long, cylindrical structure with a complex internal structure of green and blue layers. A central vertical pipe is visible. The detector is mounted on a large, curved structure, likely part of the accelerator's tunnel. The diagram shows the detector's position relative to the beam path and the surrounding accelerator components.

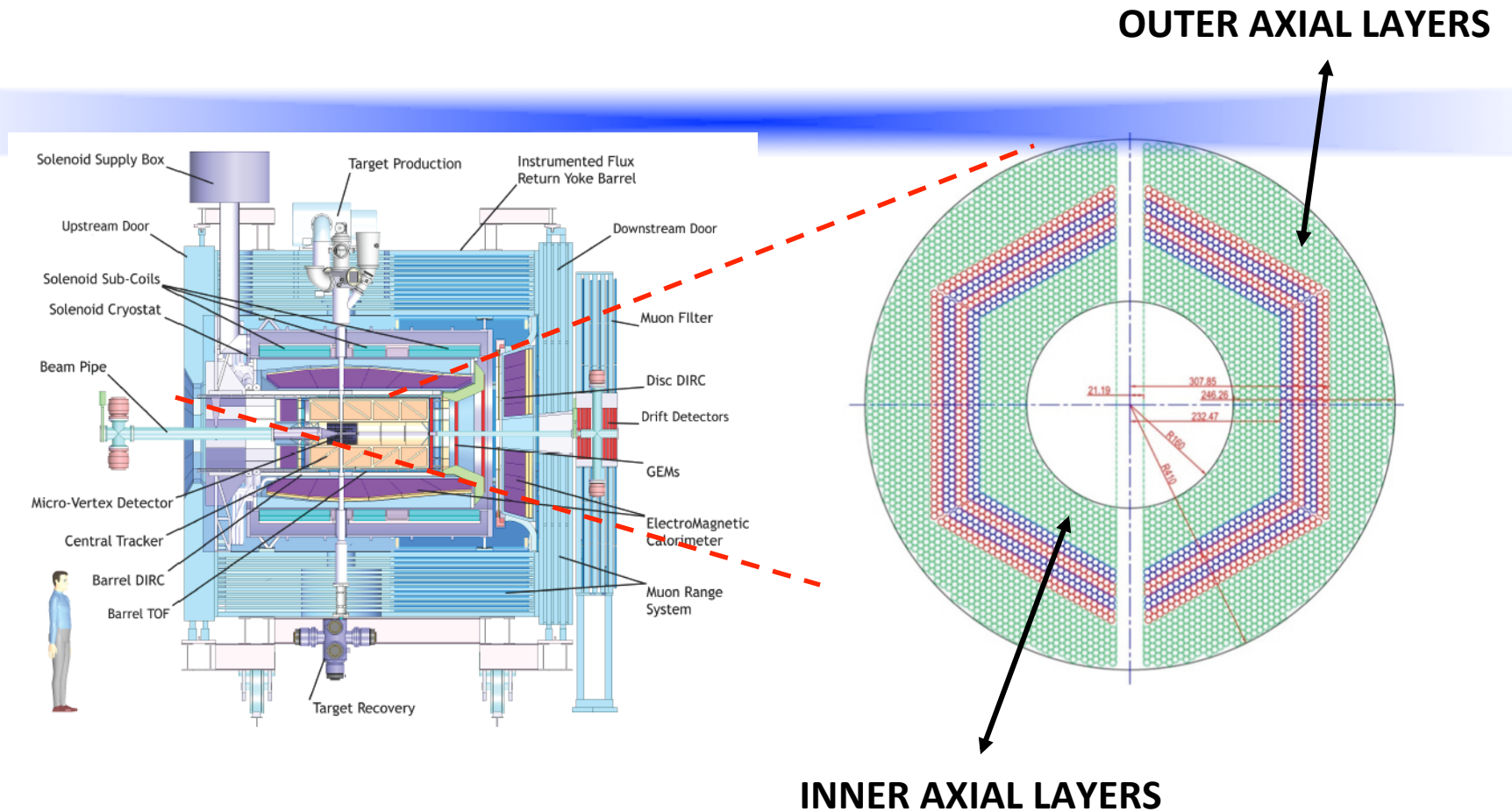
Max. Length:
~ 40 cm
Max. Radius:
15 cm

PANDA
Straw Tube Tracker

Straw Tube Tracker system (STT)



Straw Tube Tracker system (STT)



- 4636 Straw tubes
- 23-27 planar layers
- 15-19 **axial layers** (green) in beam direction
- 4 **stereo double-layers** for 3D reconstruction, with ± 2.89 skew angle (blue/red)

The trajectory parametrization
used in this PR

Helix trajectory

$$x - x_0 = R \cos(Kz + \varphi_0)$$

$$y - y_0 = R \sin(Kz + \varphi_0)$$

$$\varphi = Kz + \varphi_0$$

5 parameters :

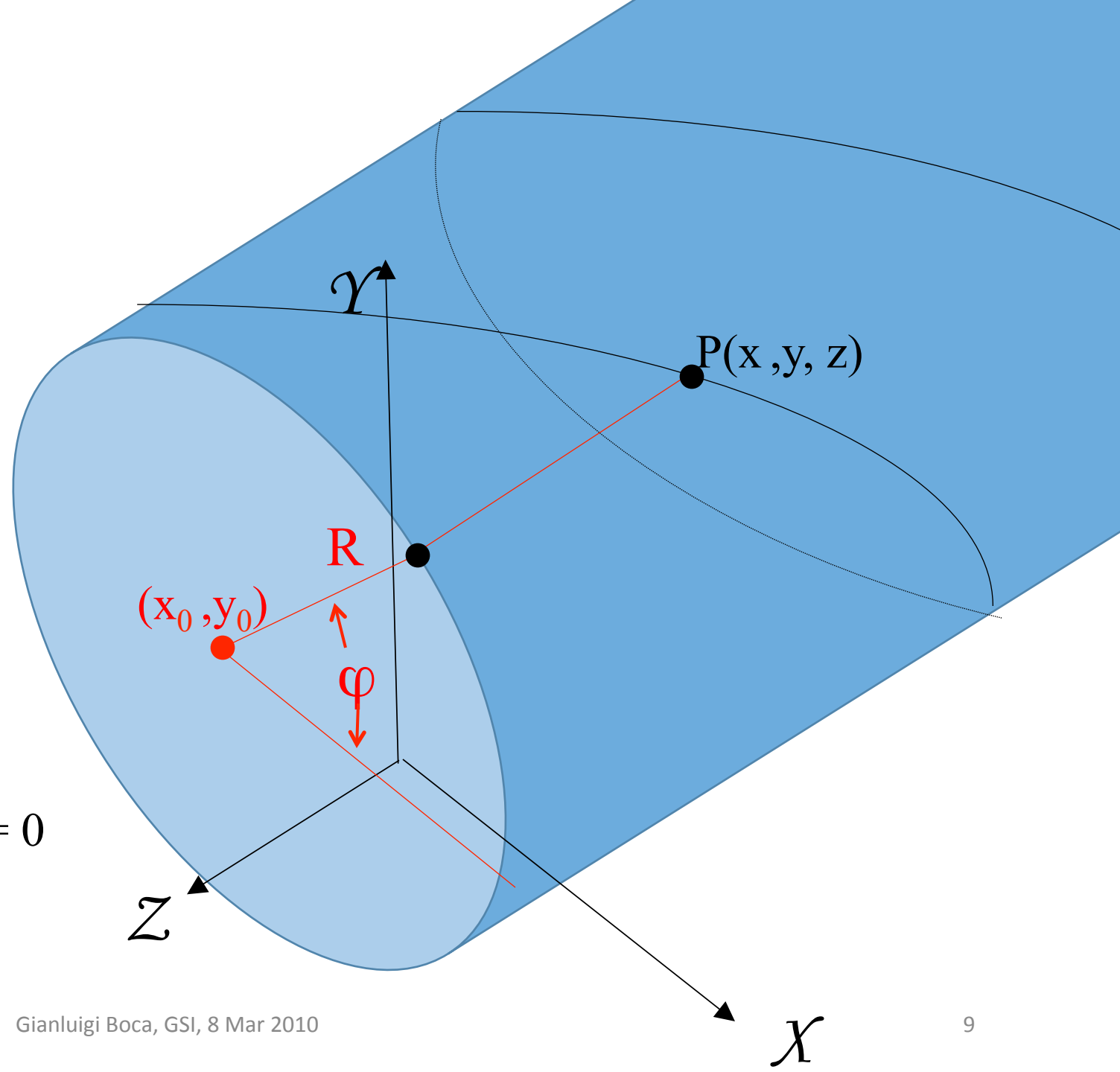
x_0 \equiv abscissa of center of cylinder

y_0 \equiv ordinate of center of cylinder

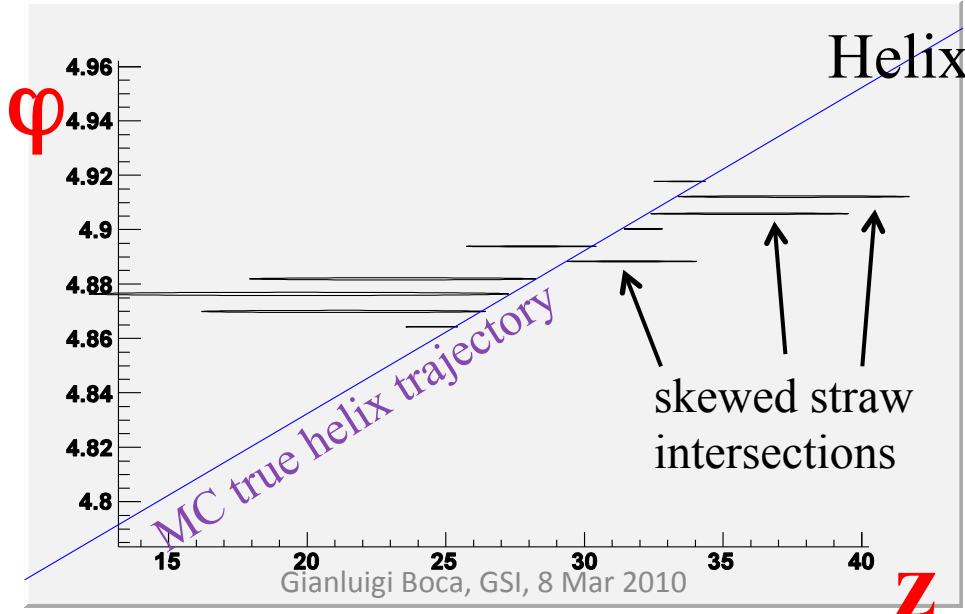
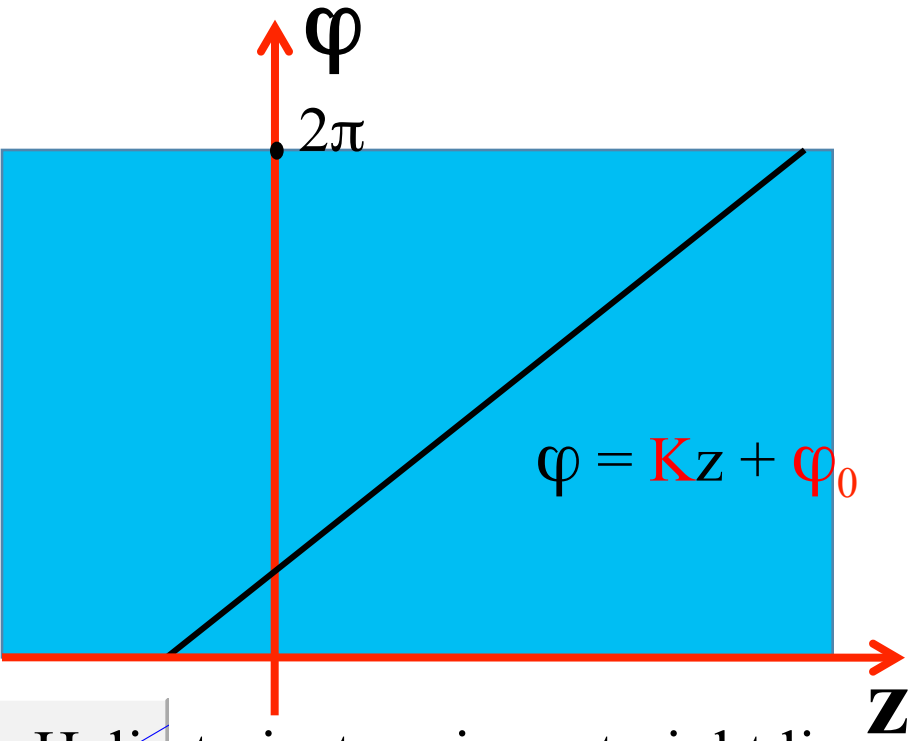
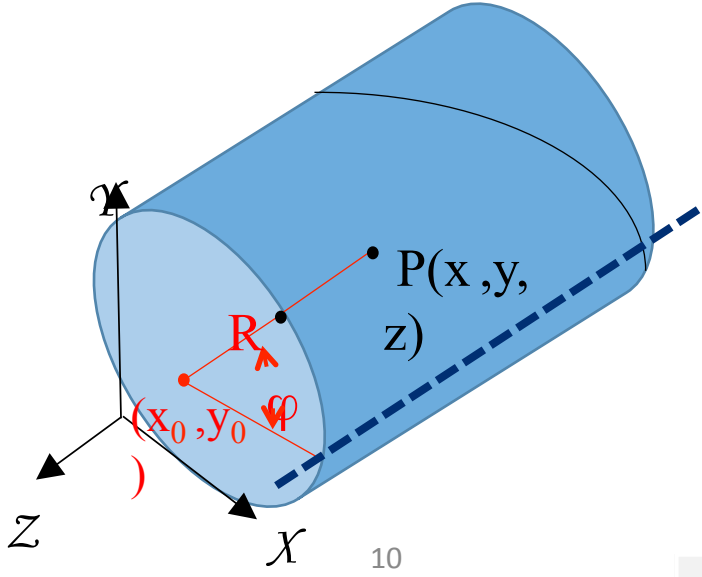
φ_0 \equiv azimuthal angle at $z = 0$

R \equiv radius of cylinder

K \equiv rate of increase of φ



The φ z projection



Helix trajectory is a straight line

The pileup problem
at 20 MHz Interaction Rate

The problem arises because the STT drift time can be as long as 200 ns. Hits from previous events or subsequent events in STT can mix to the track true hits generating fake tracks.

2 MHz interaction rate
at the beginning



essentially no overlap of different event hits

(in perspective at 20 MHz
interaction rate)



up to 8 different event hits can pileup

At the end PANDA will run at 20 MHz IR, the PR has to deal with many ghost tracks !

The brief description of the PR algorithm

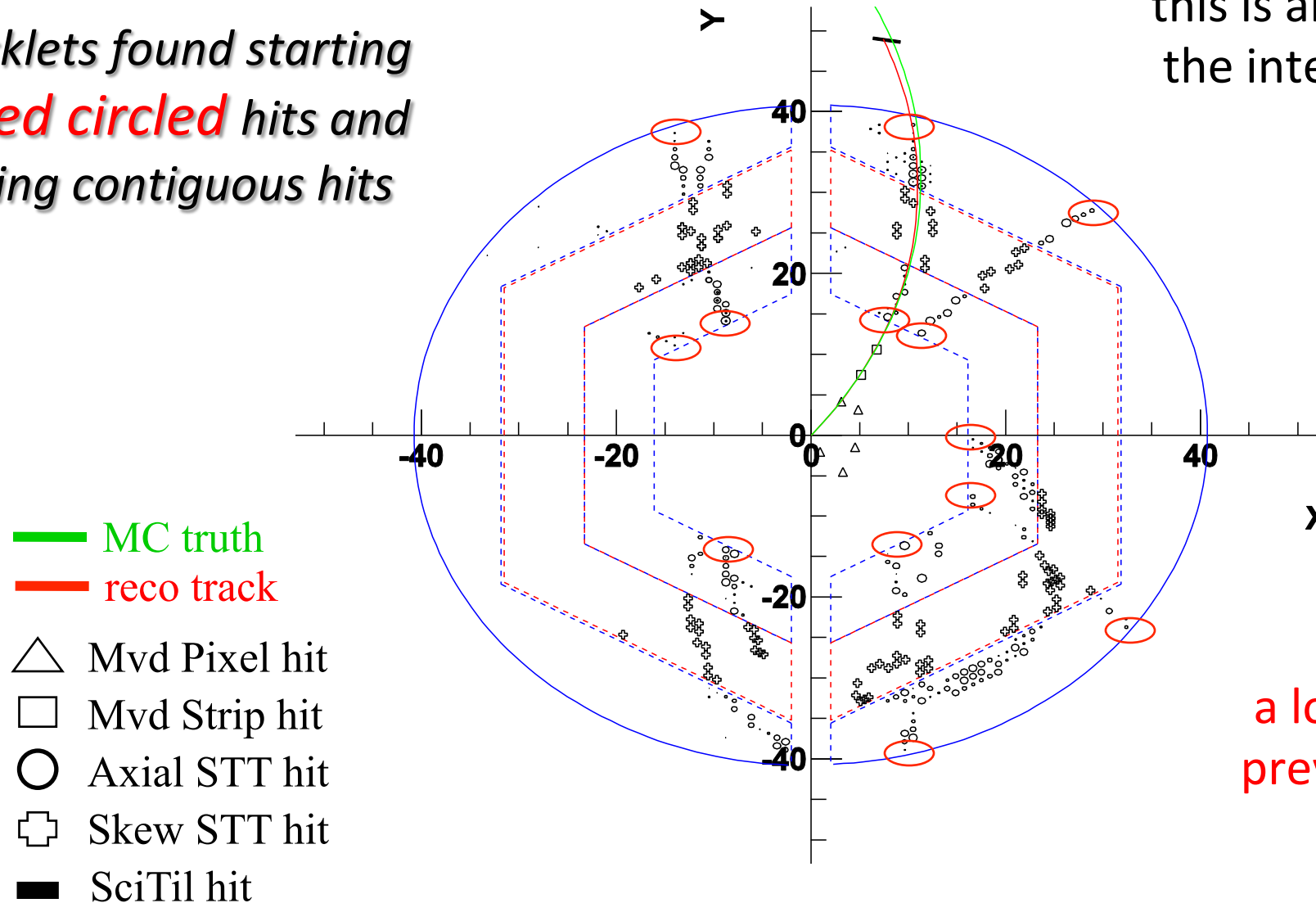
The Pattern Recognition algorithm

- *Road finding method using initial hit cluster to find tracklets first and track candidates later*
- *The parameter fit of the candidate tracks are calculated with a Hough Transform method first (it is fast) and a χ^2 minimization later (it is more precise)*
- *This Pattern Recognition uses Mvd and Stt hits in central region (an extension in the forward region including Gem as well is also available in a separate package);*
- *track candidates found first in XY view and then in φZ view;*
- *tracklets found starting from **seed hits** at the boundary of axial Stt layers*
- *many fake tracks remain in the 20 MHz interaction rate. A final Cleanup procedure that eliminates the fakes is necessary.*

Road Finding : gathering STT hits in tracklets (in XY view)

- tracklets found starting from **red circled** hits and collecting contiguous hits

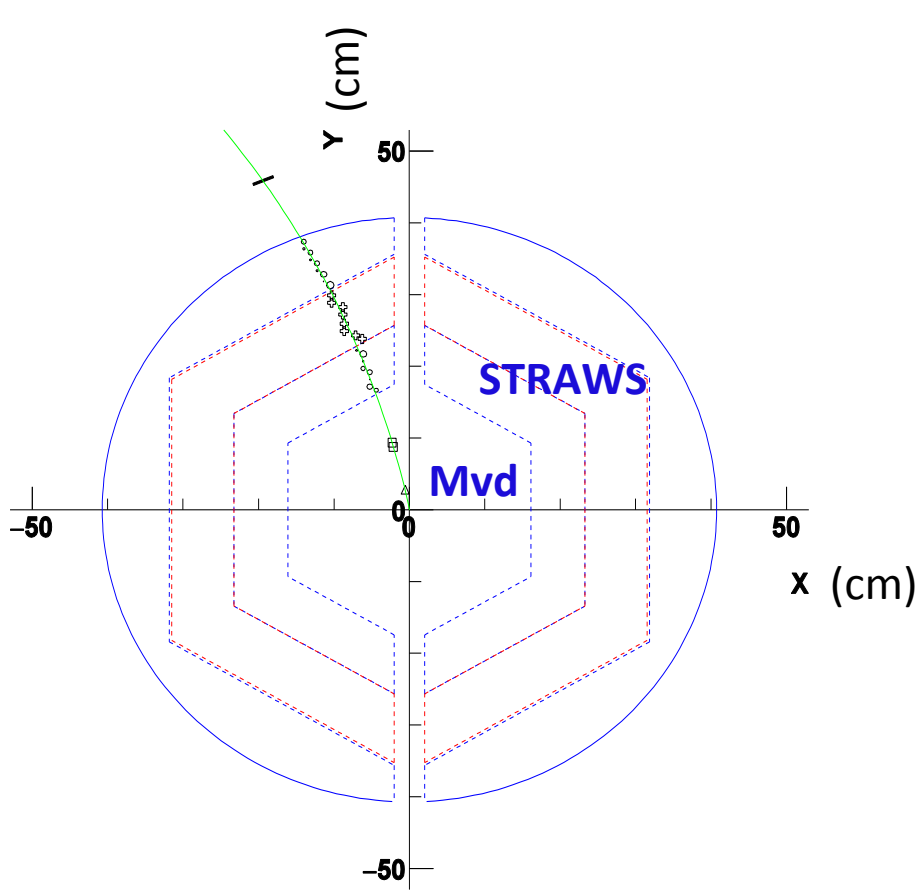
this is an event in the case when the interaction rate is 20 MHz.



a lot of pile up hits from previous and subsequent events !

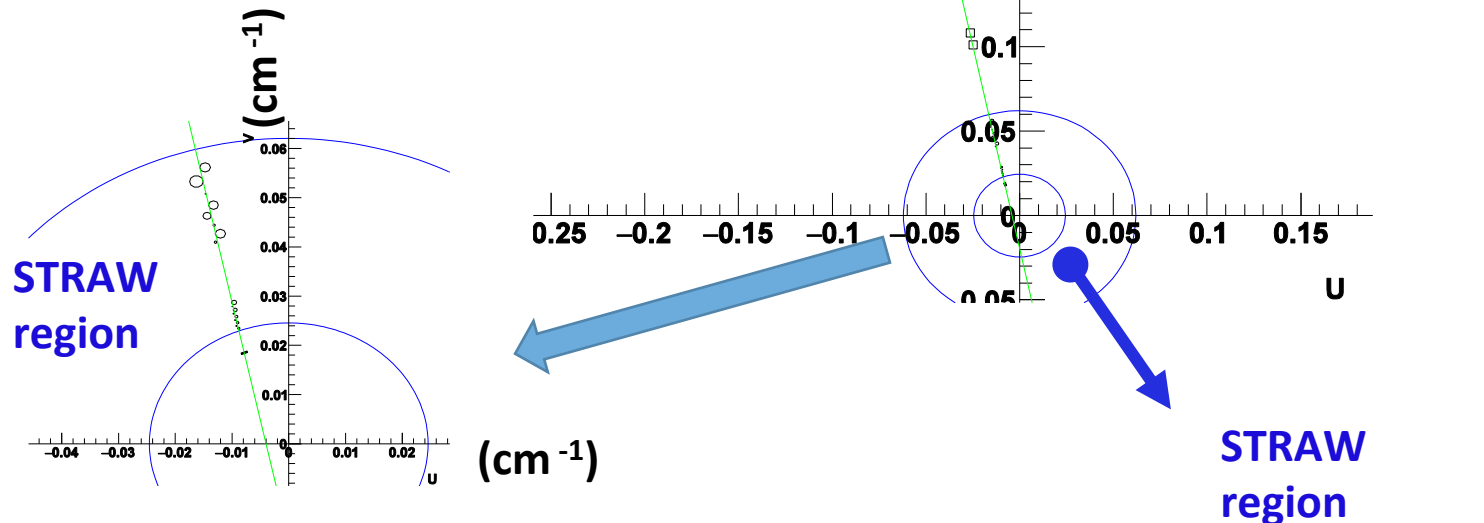
Fitting center and radius of trajectory in XY plane ($\equiv P_t$ determination)

- use Conformal transformation



$$u \equiv x/\sqrt{x^2 + y^2}$$

$$v \equiv y/\sqrt{x^2 + y^2}$$



Green line = MC truth Track

Fitting center and radius of trajectory in XY plane

..... + Hough Transform for first **fast calculation** of the Radius and center of the Helix trajectory using only the STT hits belonging to a tracklet.

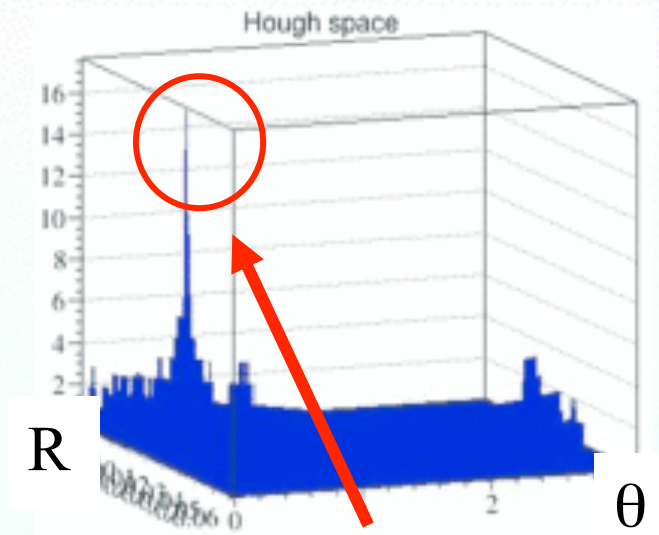
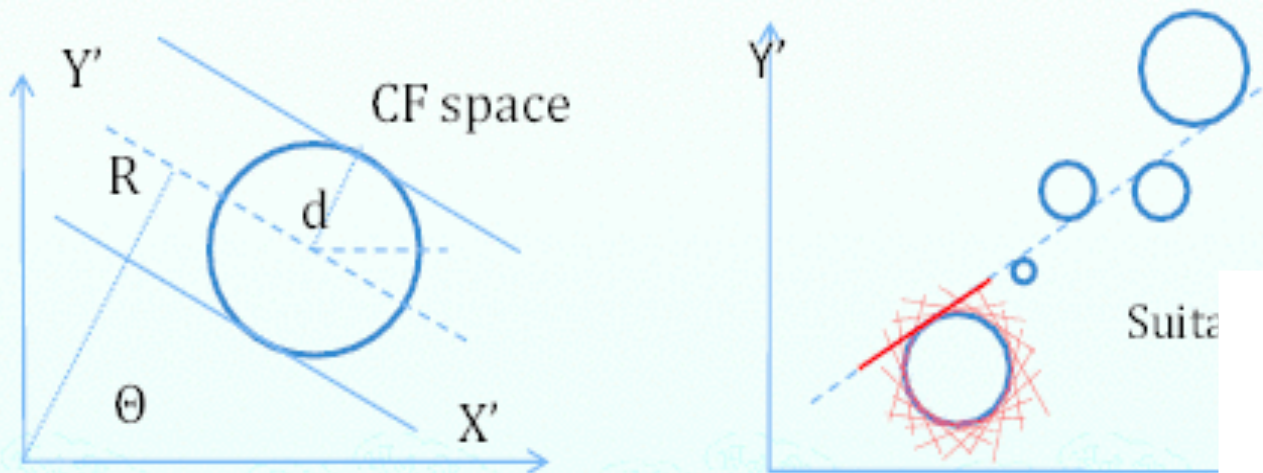
Hough transform in this case is performed only with STT hits belonging to the tracklet → Hough plot cleaner, peak stands out more clearly !

Hough transformation:

For lines: $y = mx + b$ can be described by (m, b) or (r, θ)

Hough parameter definition :

θ from 0 to π ; $R = \cos(\theta) X + \sin(\theta) Y \pm d$.



accumulation
point

Fitting better center and radius of trajectory in XY plane

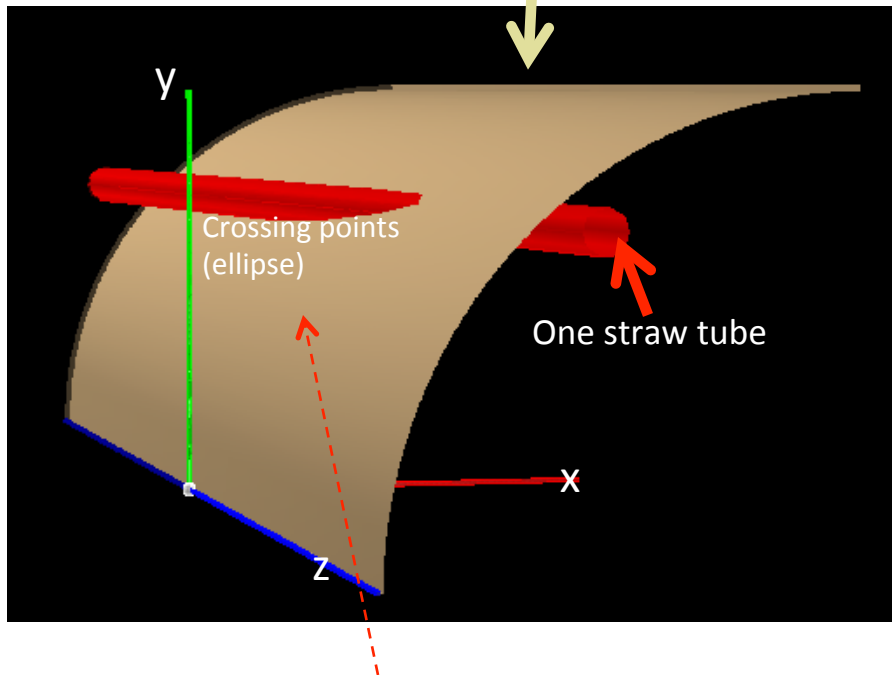
- *discard obviously unphysical tracks (radius too big or too small)*
- *work again in XY plane and using the radius and center of the trajectory collect all possible hits close to the track, including MVD hits, and eliminate those far away.*
- *in XY plane determine again R and center of Helix of track trajectory but this time using also the MVD hits and with a χ^2 minimization. This leads to a more precise determination of R and the center. The MVD hits lying too far from the found trajectory are eliminated.*
- *use newly found trajectory to eliminate possible spurious hits still remaining in the track and associate SciTil hits to the track.*
- *determine the charge of the track.*
- *use found trajectory in XY plane to associate Skew STT hits to the track.*

Finding K ($\equiv P_z$ determination) using the ϕz space

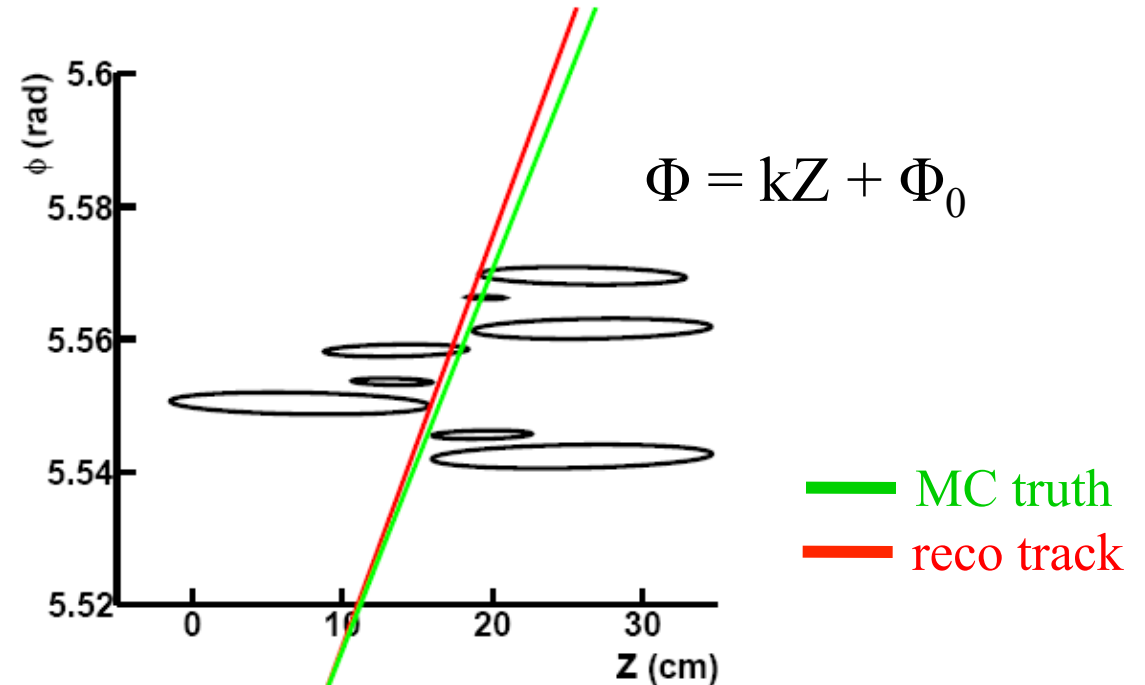
P_z determination : in the ϕZ plane the Helix trajectory is a **STRAIGHT LINE**

1: The radius, the position of the helix center in the XY plane are determined.

Cylinder on which the helix lies; determined in the previous steps in the PR



Skew straw hits as they look in the ΦZ plane



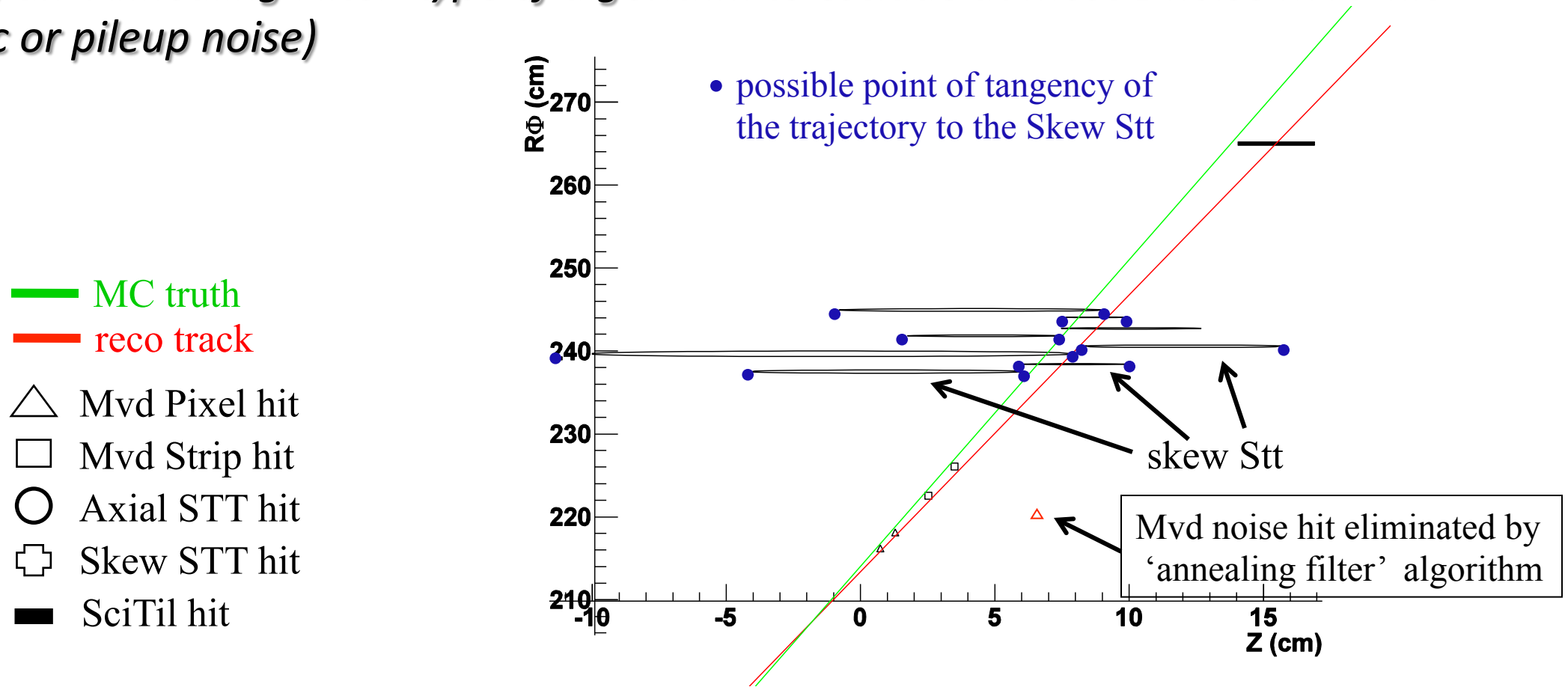
Track need to be tangent to the crossing ellipse.

Finding K ($\equiv P_z$ determination) using the ϕz space

- *for each track candidate found in the previous steps, associate all hits of those Skew STT straws that cross the trajectory cylinder .*
- *in the ϕz plane fit K the first time using only the MVD hits and the vertex constraint.*
- *Eliminate possible MVD hits too far away in the the ϕz plane from fitted trajectory.*
- *With the survived MVD hits and the Skew STT hits perform the final fit in the ϕz plane and determine K of the track.*

Finding K ($\equiv P_z$ determination) using the φz space

- perform a χ^2 fit of track in ΦZ space allowing all possible point of tangency (blue points) and using an 'Annealing Filter' type of algorithm to esclude at most 1 noise MVD hit (electronic or pileup noise)



- further reject spurious using the result of fit and a proximity cut

The Cleanup procedure

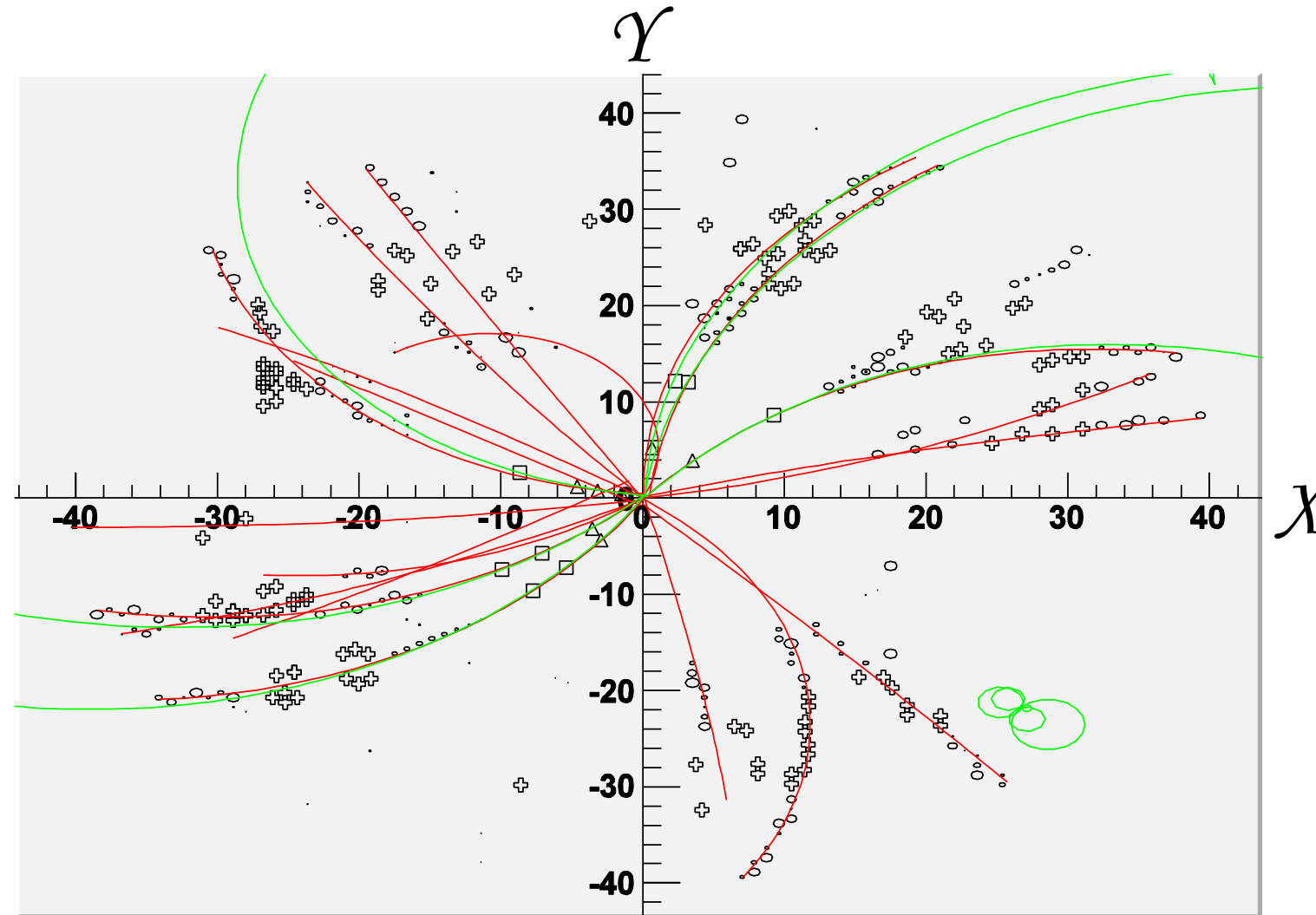
- A 'Cleanup' procedure is necessary to reject fake tracks caused by pileup of events at 20 MHz interaction rate; the rejection is based on continuity of hits requirement

Example in the case
of 20 MHz interaction rate
in the XY view

an event BEFORE
cleanup

Green line = MC truth

Red line = tracks found by PR



The Cleanup procedure

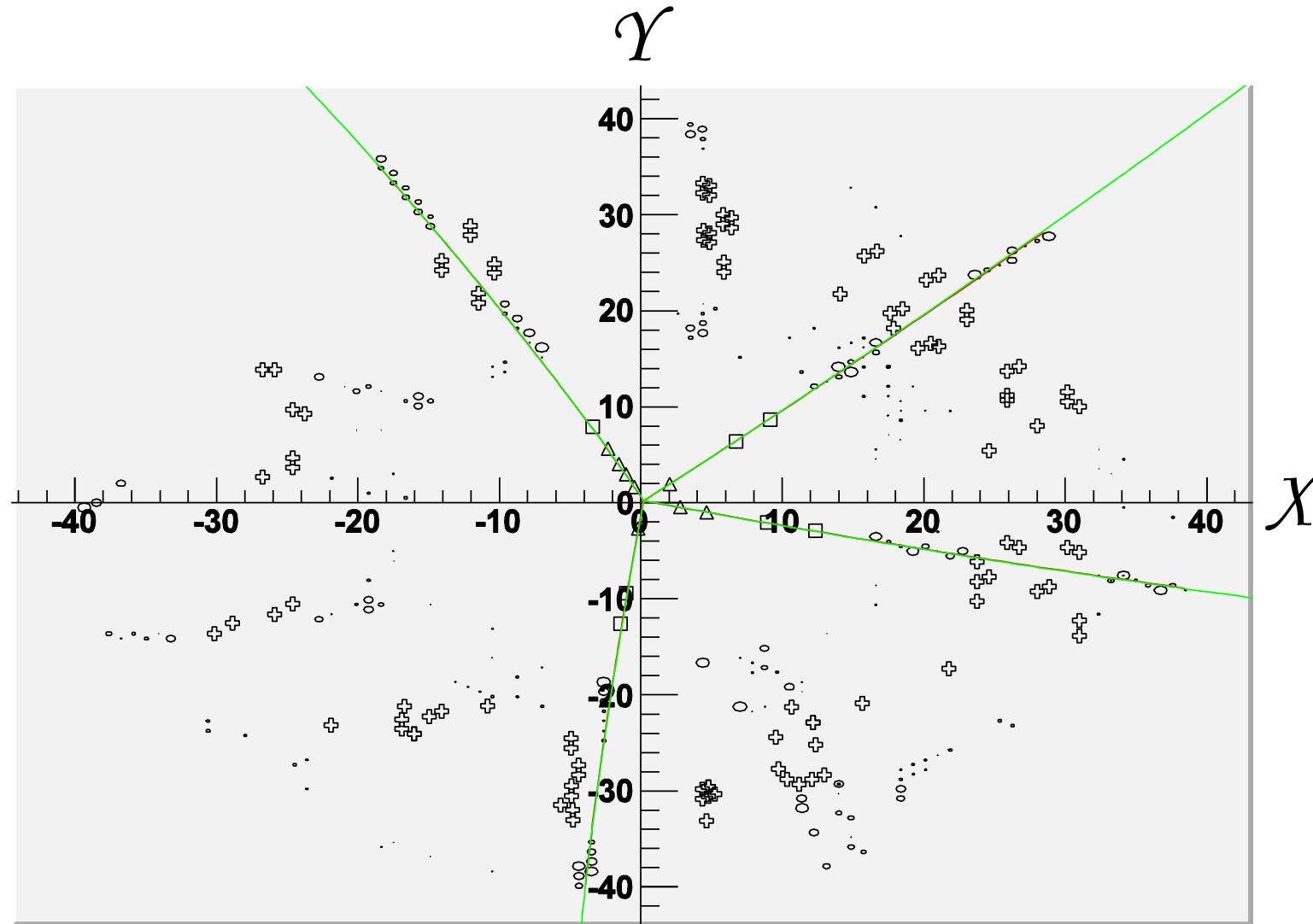
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Example in the case
of 20 MHz interaction rate
in the XY view

an event AFTER
cleanup

Green line = MC truth

Red line = tracks found by PR



The performance of the PR code

Performance of the code

- *The efficiency, purity, fake tracks rate and CPU time consumption are presented for an initial 2 MHz scenario (= essentially no pileup) and a 20 MHz interaction rate (strong pileup).*
- *Efficiency \equiv number of true (according to MC truth) tracks reconstructed over the total generated (the criterion used to declare a reconstructed track 'true' has been discussed several times in PANDA and here I don't go into details on that).*
- *Purity \equiv number of true (according to MC truth) hits in a true reconstructed track over the total number of hits in the reconstructed track.*
- *Fake track \equiv reconstructed track NOT associated to any true (according to MC) track.*

Performance of the code, case with no pileup (2 MHz IR)

MonteCarlo, Box generator, μ tracks

P (GeV/c)	Tracks/evt	Total tracks generated	% rec. tracks	# ghost tracks	# ghost/evt
0.3	1	3776	98	0	0.0
0.3	4	3797	94	0	0.0
0.3	8	3762	90	0	0.0
1.0	1	3762	98	0	0.0
1.0	4	3724	95	2	0.0
1.0	8	3723	92	6	0.0
2.0	1	3766	98	1	0.0
2.0	4	3730	95	2	0.0
2.0	8	3736	91	3	0.0
5.0	1	3750	98	0	0.0
5.0	4	3732	94	0	0.0
10.0	1	3735	98	0	0.0

generated
tracks
per evt

total generated tracks
(ie summed over all events)

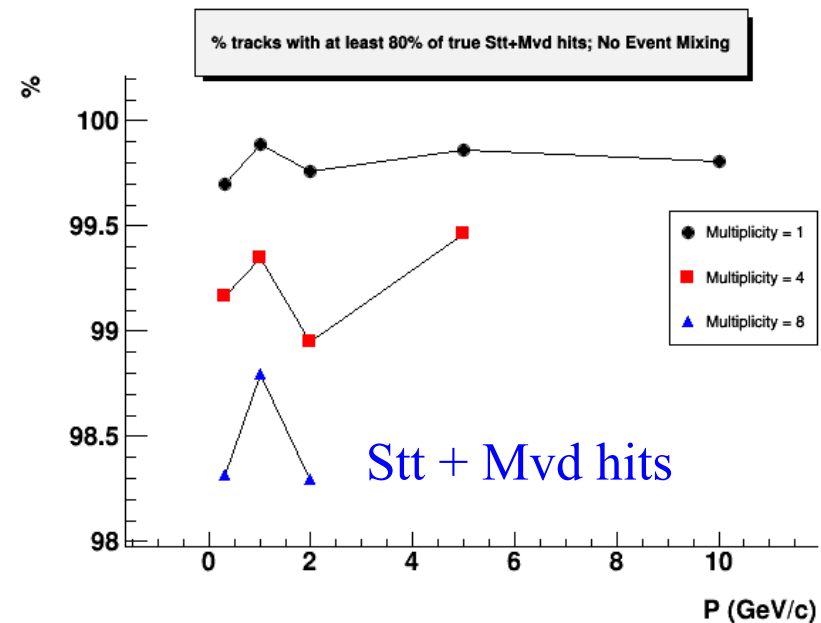
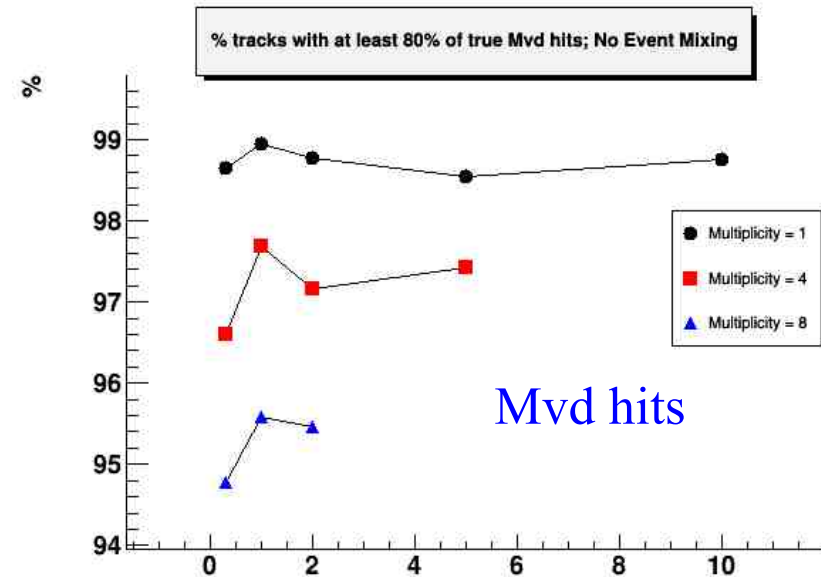
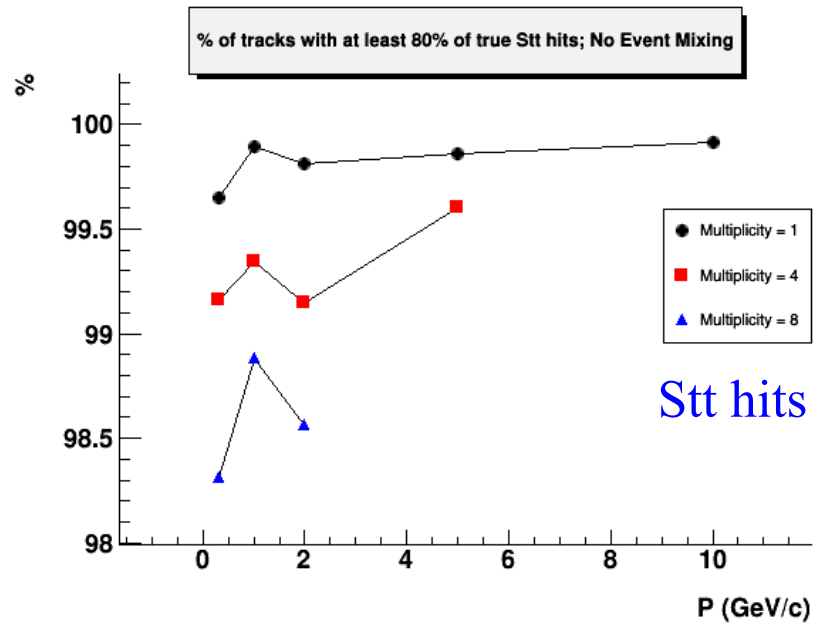
total fake tracks
(ie summed over all events)

average
fake tracks
per event

P (GeV/c)	Tracks/evt	Total tracks generated	% rec. tracks	# ghost tracks	# ghost/evt
0.3	1	3776	98	0	0.0
0.3	4	3797	94	0	0.0
0.3	8	3762	90	0	0.0
1.0	1	3762	98	0	0.0
1.0	4	3724	95	2	0.0
1.0	8	3723	92	6	0.0
2.0	1	3766	98	1	0.0
2.0	4	3730	95	2	0.0
2.0	8	3736	91	3	0.0
5.0	1	3750	98	0	0.0
5.0	4	3732	94	0	0.0
10.0	1	3735	98	0	0.0

P of
each track

Performance of the code, case with no pileup (2 MHz IR)

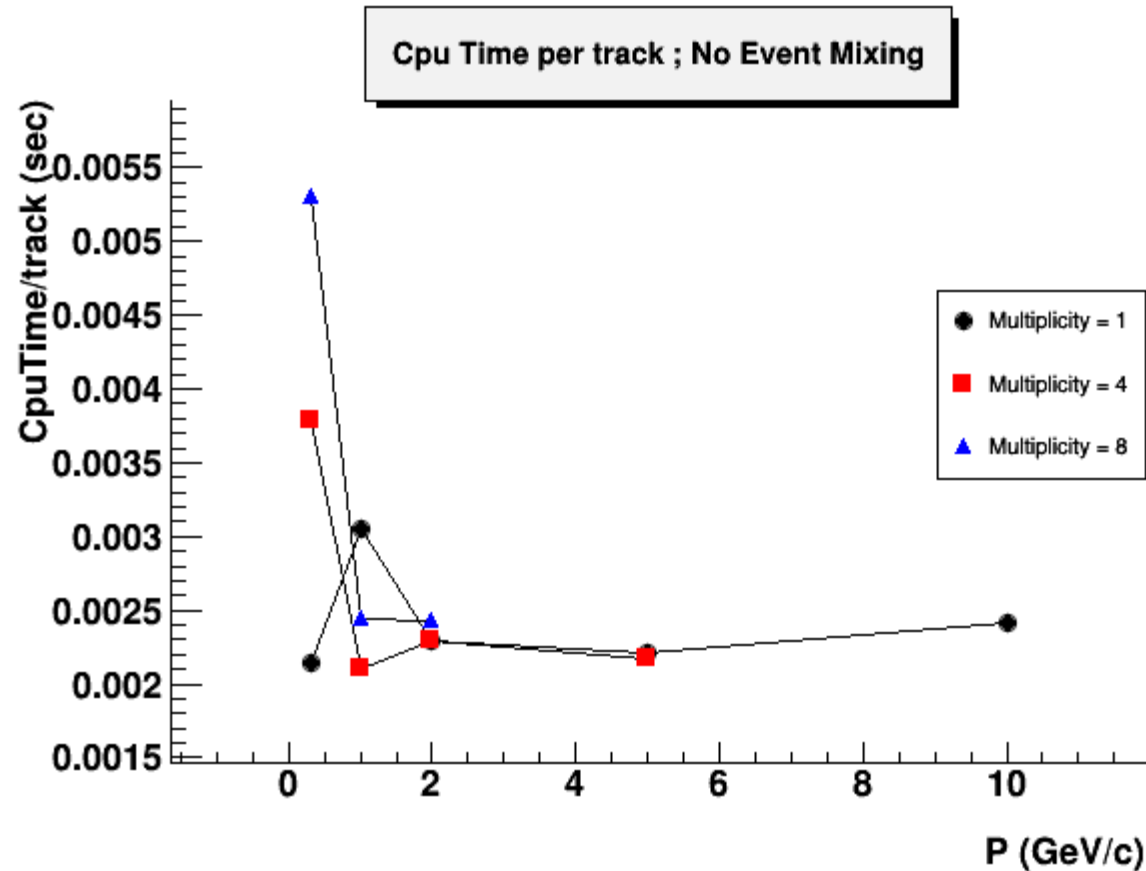


Here ‘% of tracks with at least 80% of the true ...’ means : this is the percentage of TRUE reconstructed tracks having at least 80% of the hits truly belonging to the track (according to montecarlo).

Performance of the code, case with no pileup (2 MHz IR)

Cpu time consumption/track

Processor : Intel Core i7-2600K CPU @ 3.40 GHz

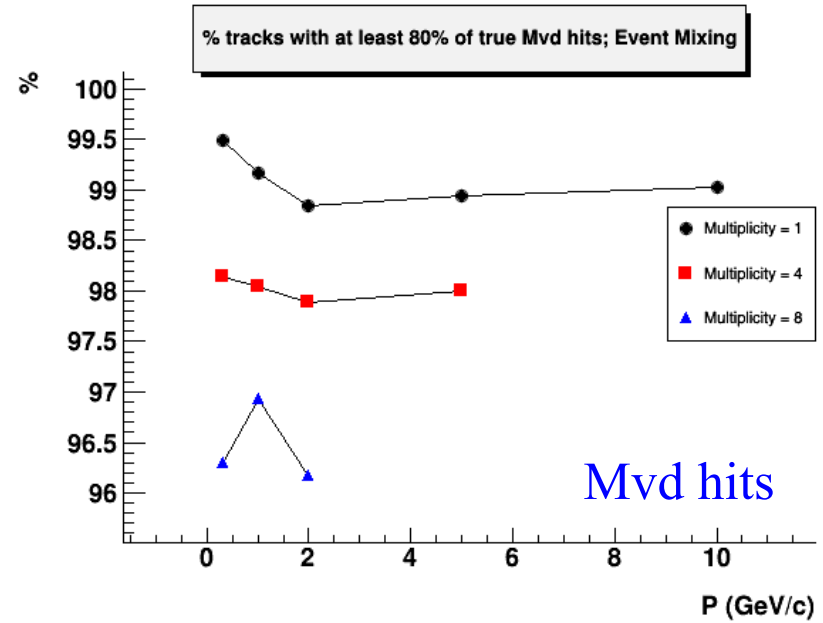
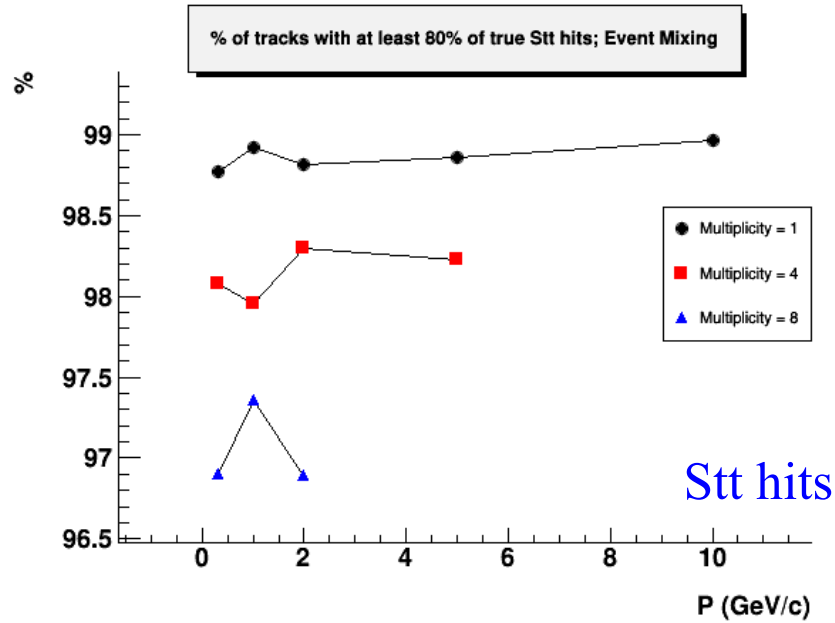


Performance of the code, case with strong pileup (20 MHz IR)

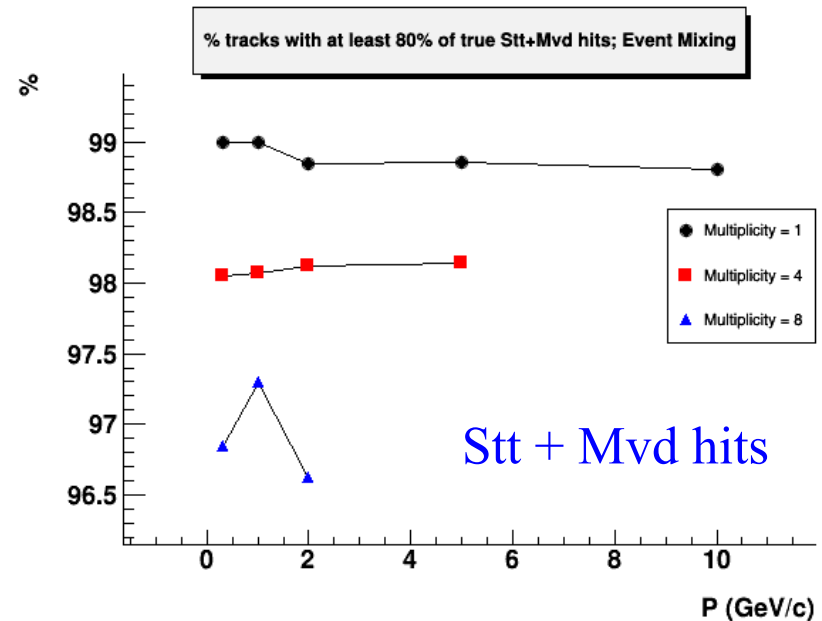
MC, Box generator, μ tracks

P (GeV/c)	Tracks/evt	Total tracks generated	% rec. tracks	# ghost tracks	# ghost/evt
0.3	1	3776	95	491	0.1
0.3	4	3797	92	361	0.3
0.3	8	3762	88	196	0.4
1.0	1	3762	96	499	0.1
1.0	4	3724	93	287	0.3
1.0	8	3723	89	208	0.4
2.0	1	3766	96	463	0.1
2.0	4	3730	93	279	0.3
2.0	8	3736	90	195	0.4
5.0	1	3750	96	497	0.1
5.0	4	3732	92	273	0.3
10.0	1	3735	96	484	0.1

Performance of the code, case with strong pileup (20 MHz IR)



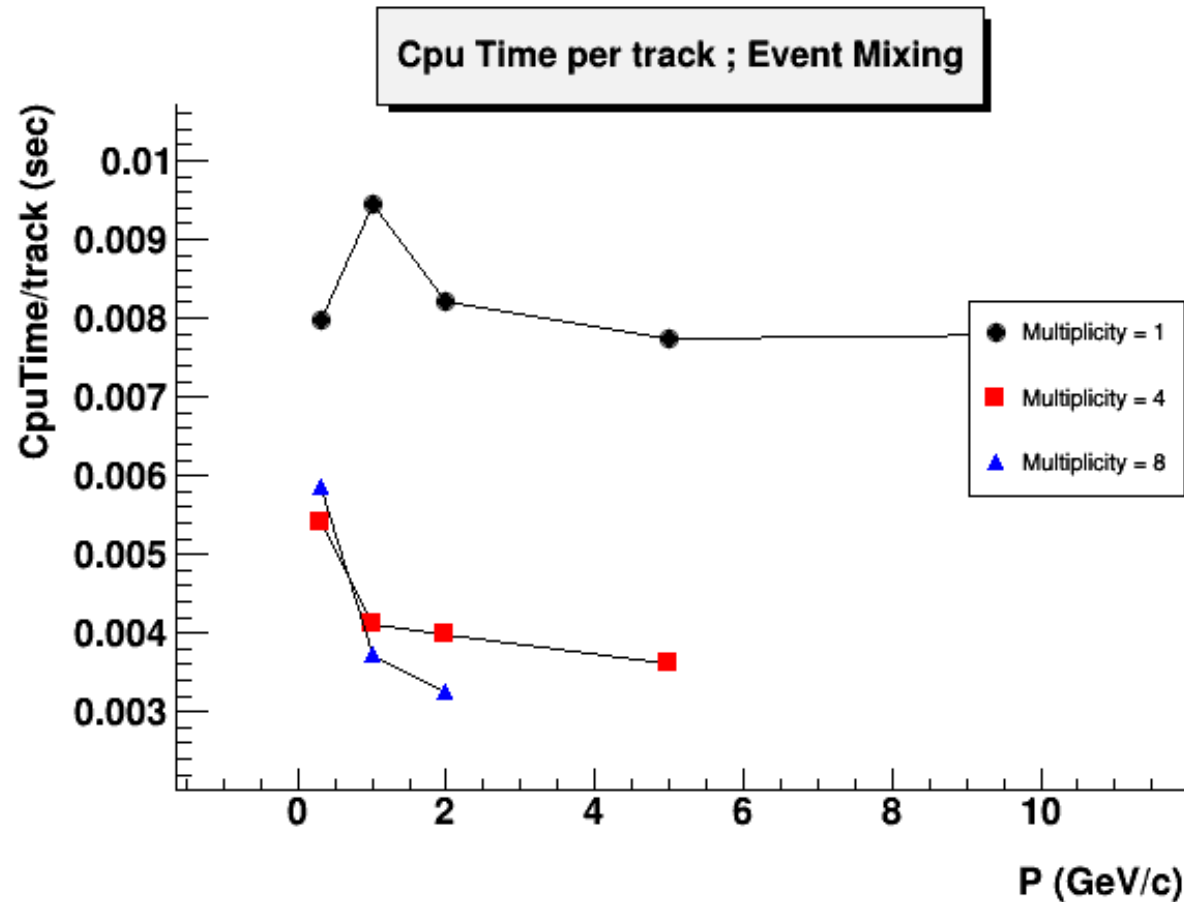
Track Quality Check



Performance of the code, case with strong pileup (20 MHz IR)

Cpu time consumption/track

Processor : Intel Core i7-2600K CPU @ 3.40 GHz



THANK YOU VERY MUCH
FOR
YOUR ATTENTION !