Towards a DAQT TDR

May 2018

Contents of Phase 1 TDR

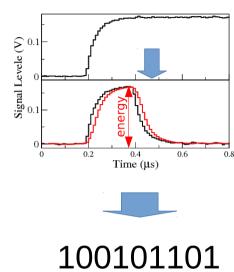
- Introduction : physics objectives, detector configuration
 - Cross sections, luminosities, detector performance (tracking, EMC, PID ...)
- Requirements (event rates, event size, pile-up situation, storage capacity, event filtering capabilities, partitioning of DAQ, running modes...)
- System architecture
 - Building blocks (time synchronisation (SODAnet), data concentrators, data transport, FPGA based Compute Nodes, CPU/GPU farm, ...)
 - Data format, interfaces and data flow
 - Event filter: partitioning and performance of algorithms (LI, L2), ...
 - Run control system, error detection and recovery, Data Quality Monitoring (DQM)
- Performance simulations and measurements with prototype systems
- Manpower, schedule and cost

Readout Approach for PANDA

The PANDA readout consist of:

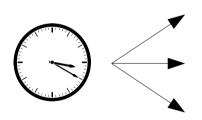
Intelligent self-triggered front-end:

 autonomous hit detection and data pre-processing (e.g. based on
 Sampling Analogue to Digital Converter)



 a very precise time distribution system (SODANET):

single clock-source for PANDA (event correlation)

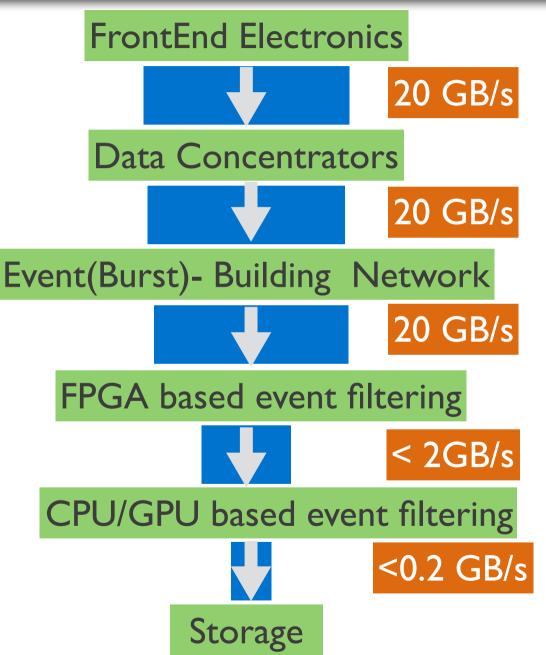


 time-sorting and processing data in real-time: processing in FPGA (Field-Programmable Gate Array)



DAQ Architecture

- Assumptions for Phase I
 - up to 10⁶ events/s 20 GB/s
 - separate runs for physics with "large" vs. "small" cross sections
 - negligible overlap between events (needs to be checked by simulations)
 - Final reduction factor for small cross section physics: 100
 - Reduction by FPGA layer: 10
 - Large cross section physics requires reduced luminosity due to storage limitations



Definition of requirements, interfaces and protocols

• Detector configuration, physics programme of Phase I needs to be defined

Work in Progress

- Cross sections, background situation
- Event rate, event size and required rejection factors, acceptable efficiency loss
- Protocols, interfaces and network topology specifications:

Burst-building network:

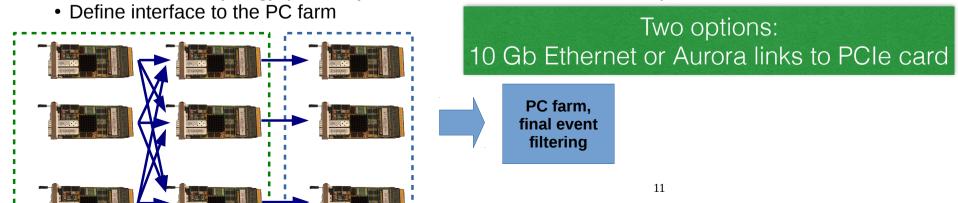
- Define protocols (data, control)
- Define interfaces for the standard data-processing IP-cores for the burst-building network:
 - Acquire requests from all sub-systems information on required data processing (e.g. pre-clustering, at least time-ordered merging of streams)

SODANET finished

To be done

Event building:

- Define protocol between the burst-building network and compute nodes (where final particle reconstruction will take place)
- Define network topology (static, dynamic with load-based distribution)



Data format for transport between FEE/Data Concentrators and CN layer

- Proposal: define universal packet format, independent of detector subsystem
 - Advantage: we can use the same set of IP cores to handle data streams independent of detector and DAQ layer
 - Data is streamed and organised in packets
 - Push architecture, but with support for back pressure

Data Origin Definitions:

- "detector": Panda Subsystem ID (EMC, STT, MVD etc.)
 - reserve one byte for unique detector definition
- "module": section ID of a detector (EMC Forward endcap, STT stereo layer, MVD pixels etc.)
 - reserve one byte for unique module definition
- "location": unique identifier for the geographical location of a hit within a module (could be STT wire number, MVD pixel ID etc.
 - reserve 4 bytes (need addressing space for MVD)

Universal Packet Format (UPF)

- Each packet contains a **packet header** with the following information (distributed in part by SODANET to FEE and/or set by slow control in FEE for local runs):
 - ID for "experiment" number (should be unique over the lifetime of Panda) (2 Bytes ?) (set by run control)
 - Run number (is reset at the start of a new experiment) 2 Bytes (set by run control)
 - Run type (physics, calibration, test/debug, local run, etc.) I Byte (set by run control)
 - Event selection identifier or has code pointing to data base(4 bytes?)
 - Superburst ID: 4 Byte (to be distributed by SODANET) (use also as last packet flag)
 - Payload size (in bytes): 3 Bytes, payload item size in bytes (1 byte) (detector specific)
 - Payload header: Number of items in payload
 - Payload items:
 - Time stamp
 - Data Origin
 - Data value(s) (detector-specific)
 - Payload trailer: repeat payload size, add checksum (CRC)
- Packet trailer
 - repeat payload size (for redundancy, debugging and recovery
 - CRC (packet checksum)

Data format for transport between FEE/Data Concentrators and CN layer

Packet Header Payload Header Payload Item 1 Payload Item N Payload Trailer Packet Trailer

Comments

- There is some redundancy in the data format
 - Important for development and integration phase
 - In a later stage, we can think about removing some redundancy for a more compact data format
- There is some freedom for detector specific aspects in the payload
 - payload item size and number of data values per item can vary
 - data origin definitions RE are flexible (could be "single EMC crystal" or EMC cluster)

Data Format: next steps:

- Agree on the details of the proposed data format
 - needs discussion with FEE developers
- Is the allocated byte size for the individual headers adequate (in particular, for MVD)?
- How large is the overhead (# bytes for headers /# data bytes)
 - Look into simulated data, right after digitisation

Open questions

- Panda configuration for DAY I physics
- Depending on the configuration, what is "first physics"
 - event filtering simulations required