

The Kalman filter based track fit in TPC detector

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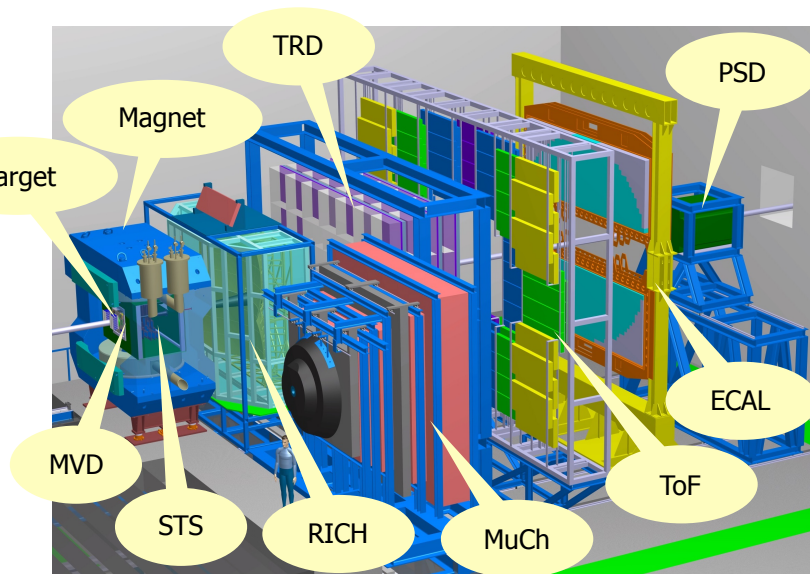
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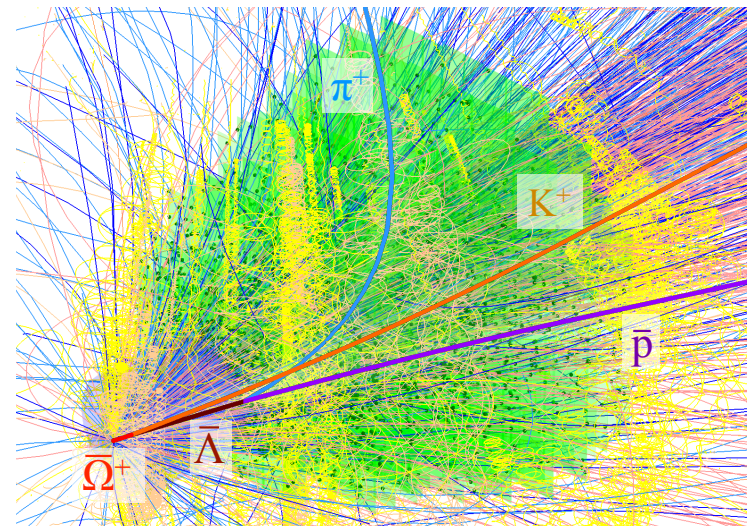
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Challenges in CBM

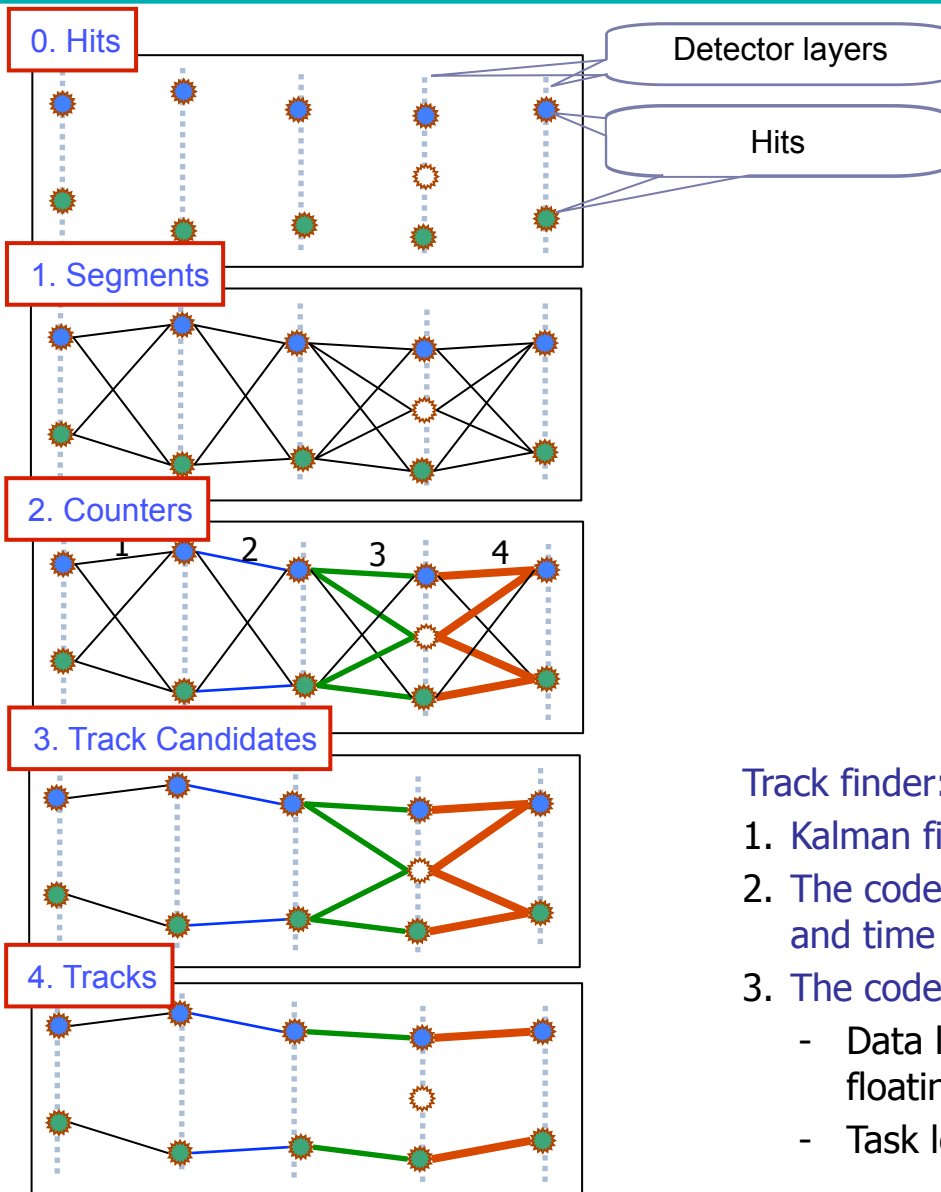


- **CBM** — future fixed-target heavy-ion experiment at **FAIR**, Darmstadt, Germany.
- 10^5 - 10^7 collisions per second.
- Up to **1000** charged particles/collision.
- Free streaming data.
- No hardware triggers.
- **On-line time-based event reconstruction and selection** is required in the first trigger level.

- **On-line** reconstruction at the on-line farm with **60000 CPU equivalent cores**.
- High **speed** and **efficiency** of the reconstruction algorithms are required.
- The algorithms have to be highly **parallelised** and **scalable**.
- CBM event reconstruction: **Kalman Filter** and **Cellular Automaton**.



Cellular Automaton Track Finder



Cellular Automaton:

1. Build short track segments.
2. Connect according to the track model, estimate a possible position on a track.
3. Tree structures appear, collect segments into track candidates.
4. Select the best track candidates.

Cellular Automaton:

- local w.r.t. data
- intrinsically parallel
- extremely simple
- very fast

Perfect for many-core CPU/GPU !

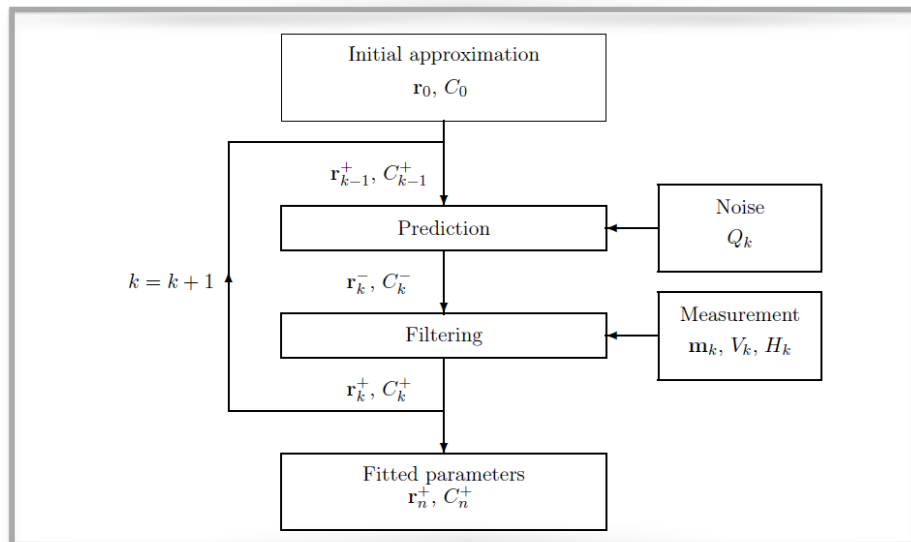
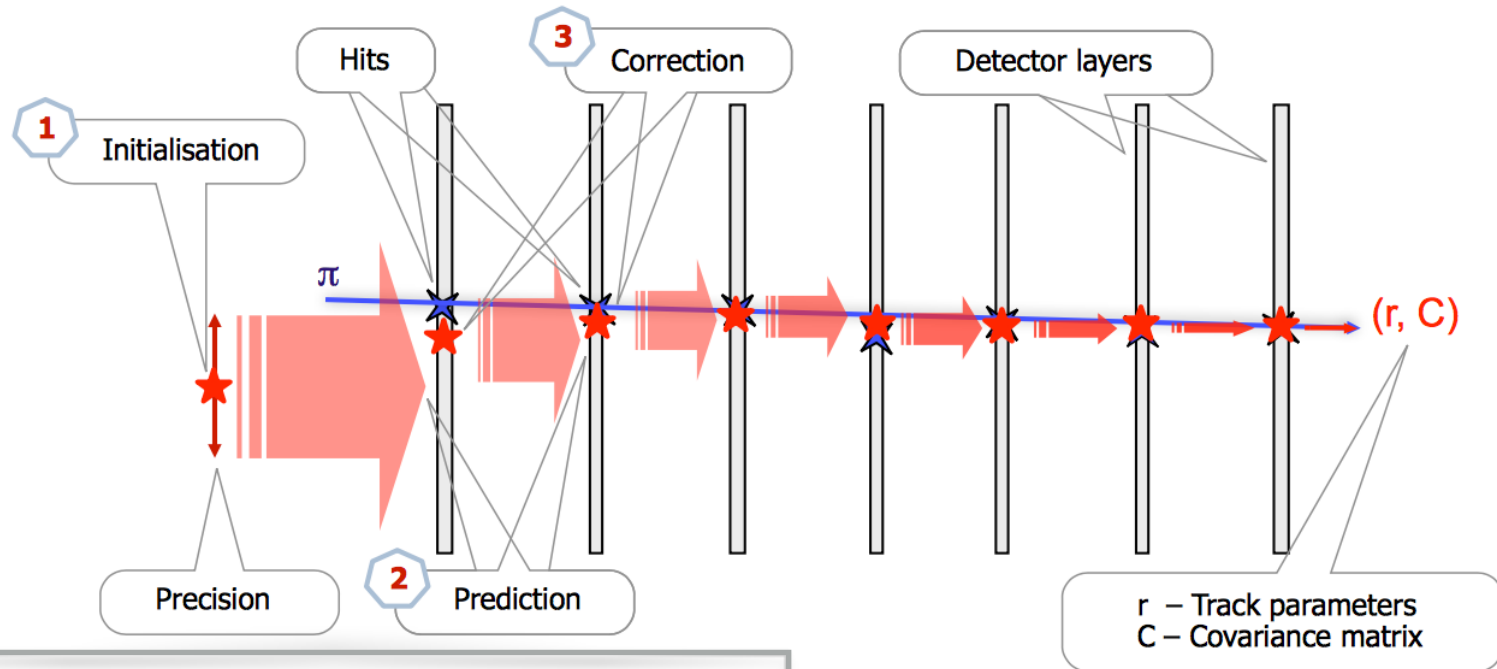
Track finder:

1. Kalman filter for track segments fit
2. The code is optimised with respect to both efficiency and time
3. The code is parallelised
 - Data level (SIMD instructions, 4 single-precision floating point calculations in parallel)
 - Task level (ITBB, parallelisation between cores)

Useful for complicated event topologies with large combinatorics and for parallel hardware

Kalman Filter for Track Fitting

Track fit: Estimation of the track parameters at one or more hits along the track — Kalman Filter (KF)



State vector

Position, direction and momentum

$$r = \{ x, y, t_x, t_y, q/p \}$$

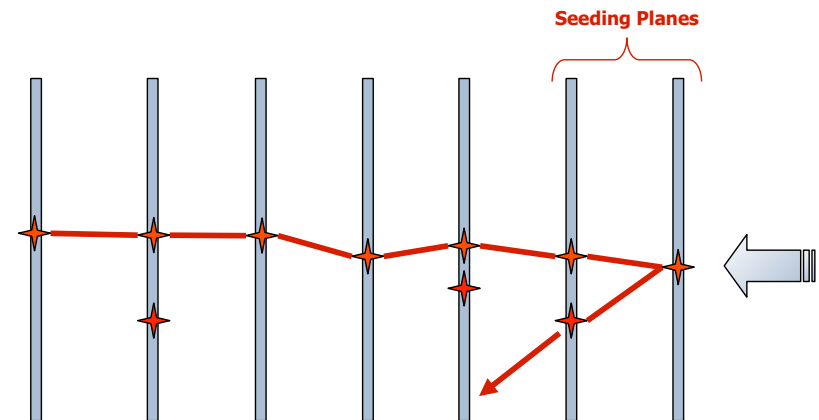
Kalman Filter:

1. Start with an arbitrary initialisation.
2. Add one hit after another.
3. Improve the state vector.
4. Get the optimal parameters after the last hit.

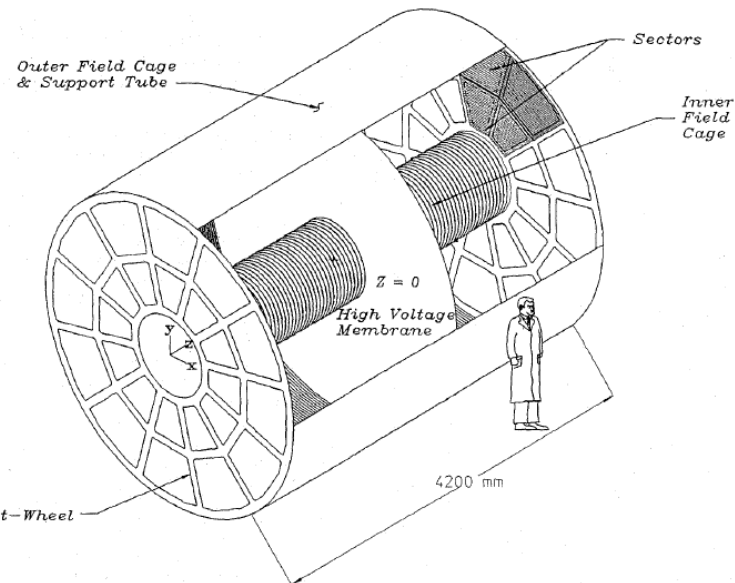
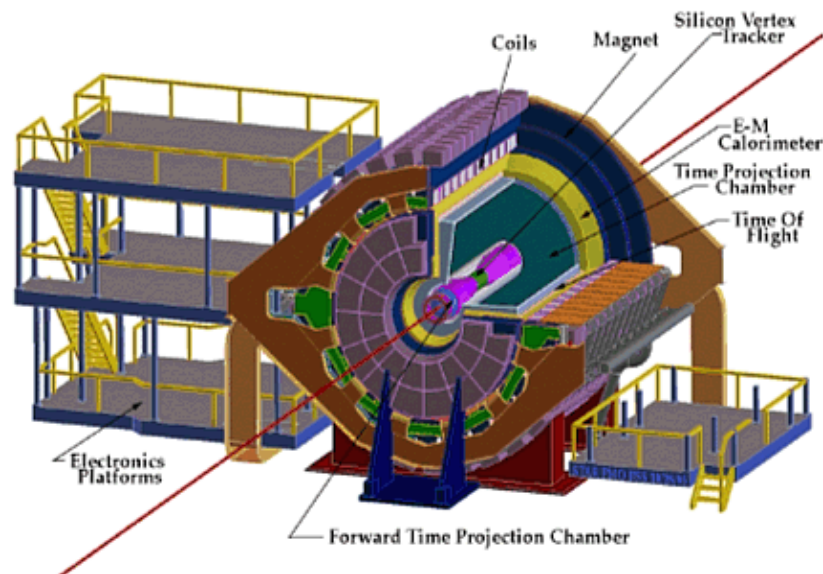
- Global track finder in CBM is based on track following.
- Disadvantages:
 - requires seeding;
 - A final track finding efficiency is limited by the seeding efficiency;
 - problems with alignment in subsystems;
 - problems with alignment of subsystems.
- Implementation of the CA based global track finder is in progress (V. Akishina, HK 46.6).

Track following:

1. Create seed
2. Extrapolate to the next station
3. Find and add hit by KF method



STAR at BNL



- CA track finder is being developed in STAR within the FAIR phase 0 program
- Collider experiment at RHIC, BNL
- Up to 200 AGeV Au-Au collisions
- Main detector – TPC

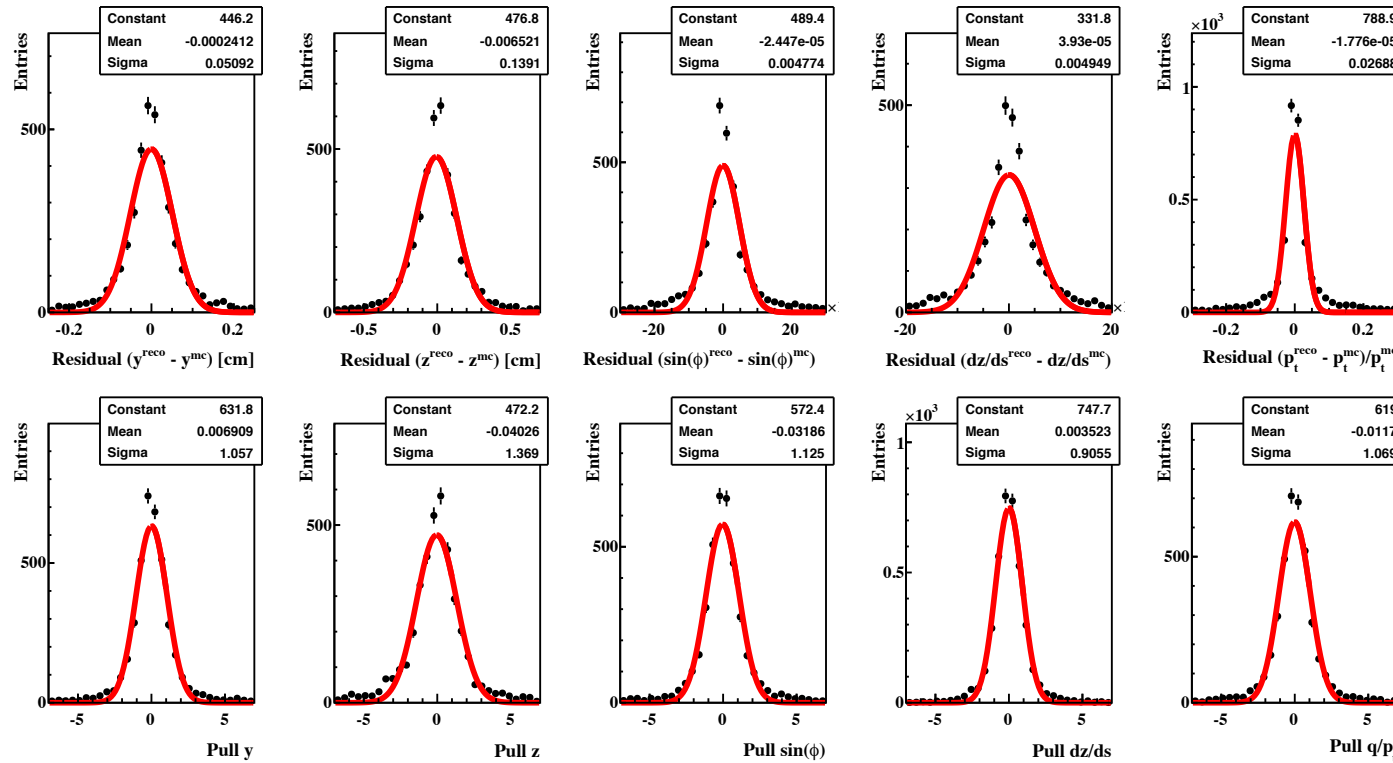
Challenges:

- Increased RHIC luminosity
- Online HLT - fast
- Global track finder has to be speed up significantly
- Upgrade the reconstruction algorithms for:
 - vectorization
 - multi-threading
 - many-core systems

- Global track finder in STAR (**Sti**) is based on track following:
 1. Create seed from TPC detector.
 2. Find track in TPC detector.
 3. Extend track to the outer ToF, BEMC and MTD detectors.
- For acceleration of the algorithm:
 - Done: integration the **CA** track finder as a seed finder for **Sti** — **StiCA** track finder.
 - Planned: extend the **CA** track finder to the outer detectors.

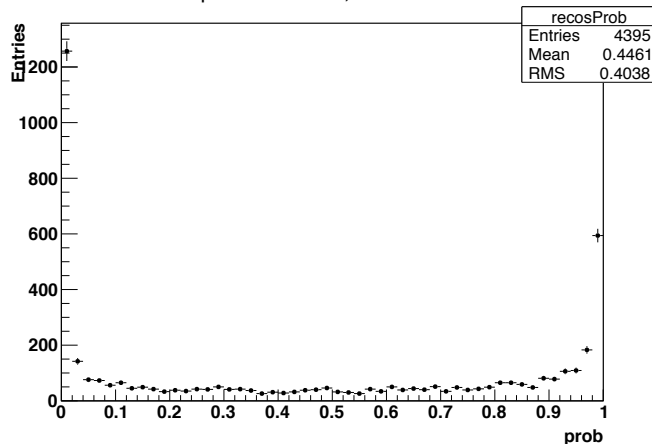
- CA track finder, being a part of StiCA, spends only **10%** of the total time of finding tracks.
- The goal is to speed up the fitting of tracks, which is performed by Sti.
- CA track finder is fully vectorised and highly optimised and includes Kalman Filter based track fitter, which assumes:
 - simplified one-component constant magnetic field;
 - simplified uniform material description. } — optimised for TPC
- For extrapolation of tracks to outer detectors, it is necessary to take into account not homogeneous magnetic field and complex material structure.

Results



- Exact position of pad rows
- Non homogeneous magnetic field
- Non homogeneous material

prob distribution, reco tracks



- Fitted track errors are in a good agreement with the simulated hit errors.
- Correct mathematics — as a result correct pulls (unbiased, width about 1), χ^2 and flat prob (p-value) distributions.

Summary

- The Kalman filter method for reconstruction of charged particle trajectories in the TPC CA track finder for the STAR experiment is extended for non homogeneous magnetic field and material.
- The developed Kalman filter based track fit is fully SIMDised and highly optimised
- The method shows correct distributions of track parameter residuals and pulls, and χ^2 .

Plans

- Extend the SIMDised KF track fit to the outer ToF, BEMC and MTD detectors.
- Apply the developed methodology to the track fit in the CBM experiment.