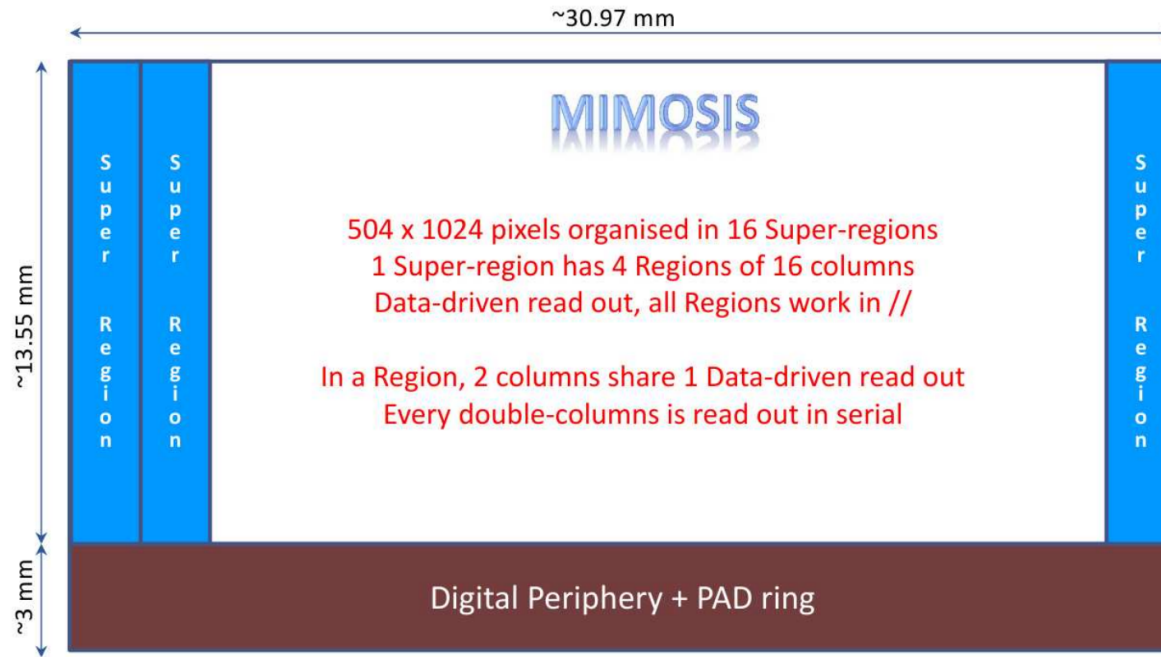
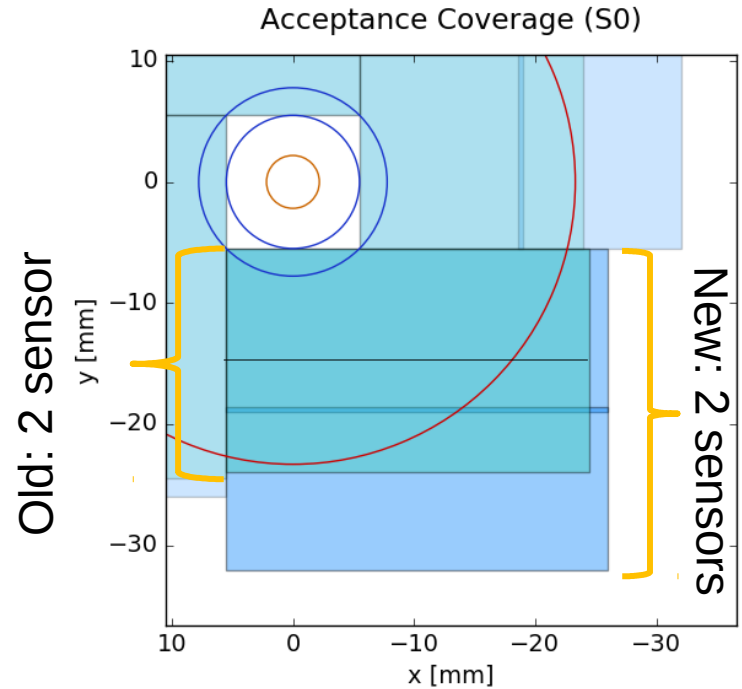
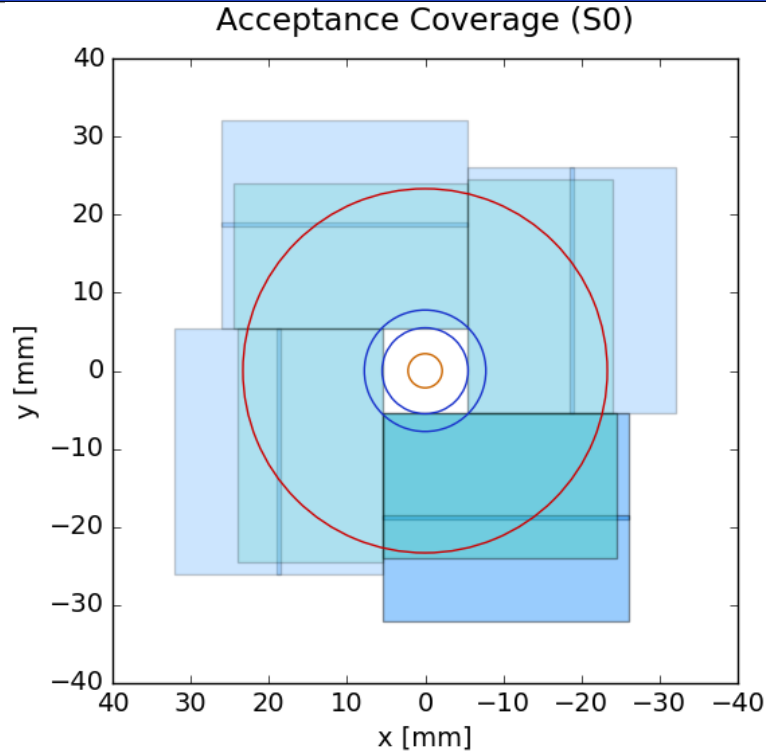


# Updates on the Micro Vertex Detector Geometry for the CBM - Experiment

# MIMOSIS layout and geometry



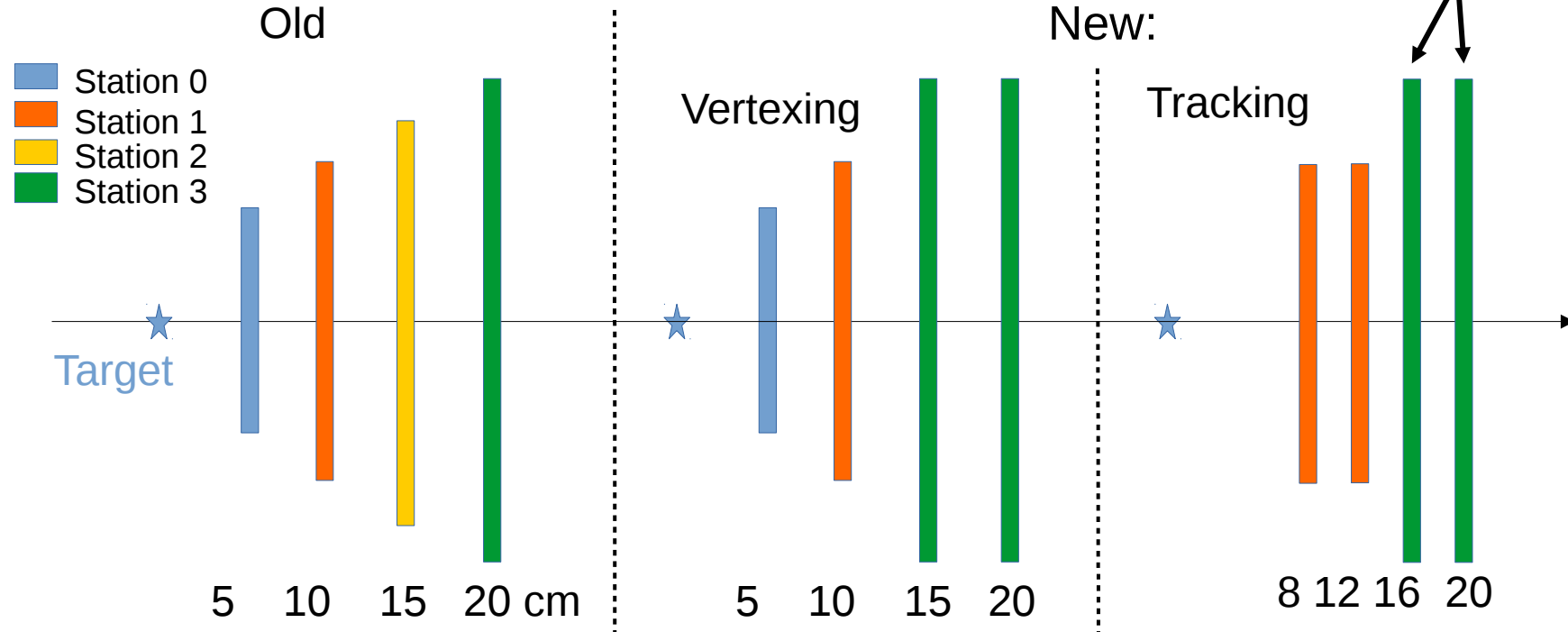
# New Sensor dimensions



- Larger sensor geometry => Less sensors needed at some places.
- All sensors moved => Rework full geometry.
- Modest improvement of material budget.

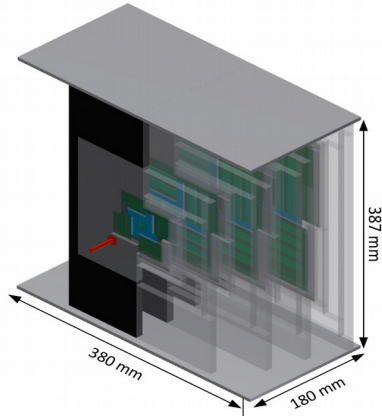
# New MVD geometry layout

Re-use building blocks to increase efficiency of the assembly process.



# Status MVD Software

# MVD Digitizer concept

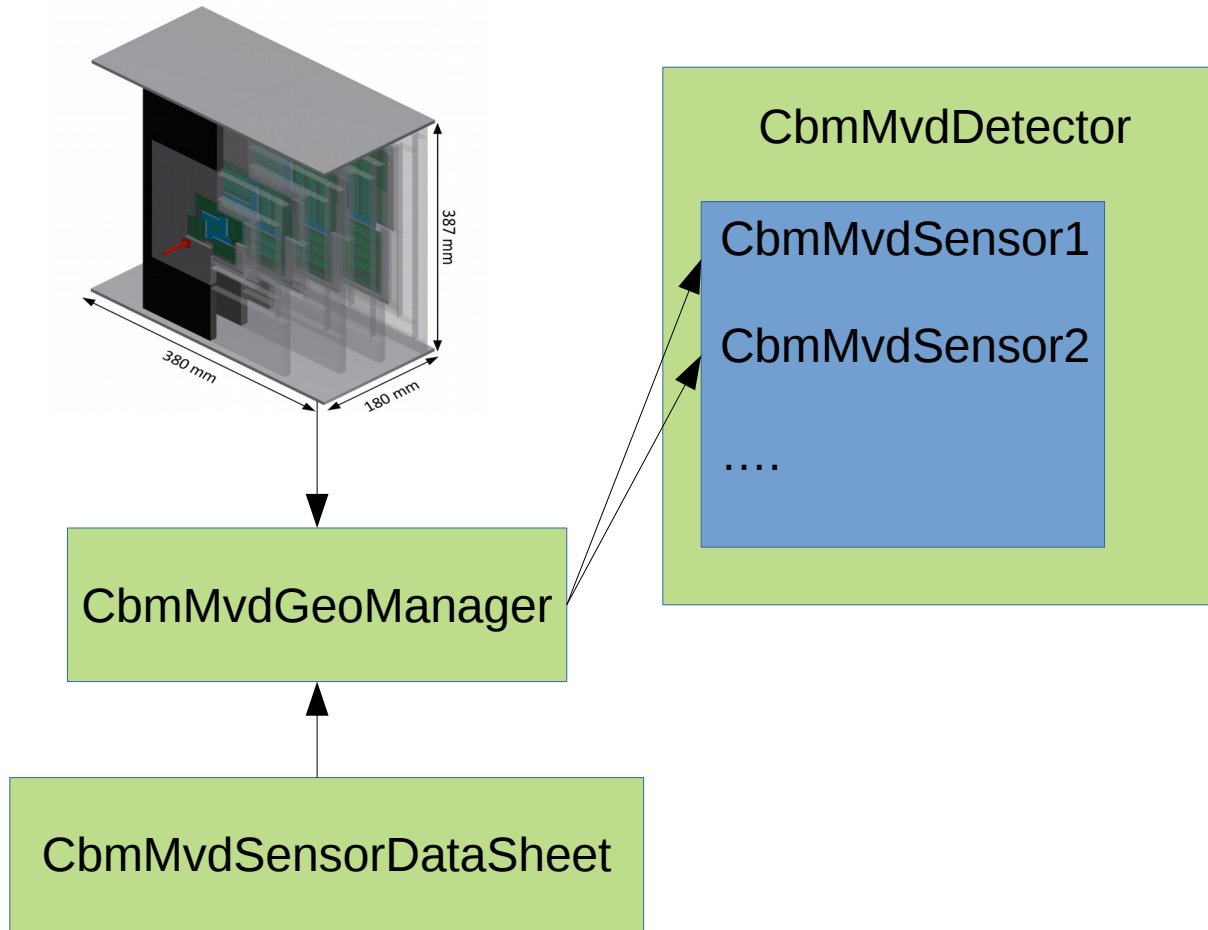


CbmMvdDetector

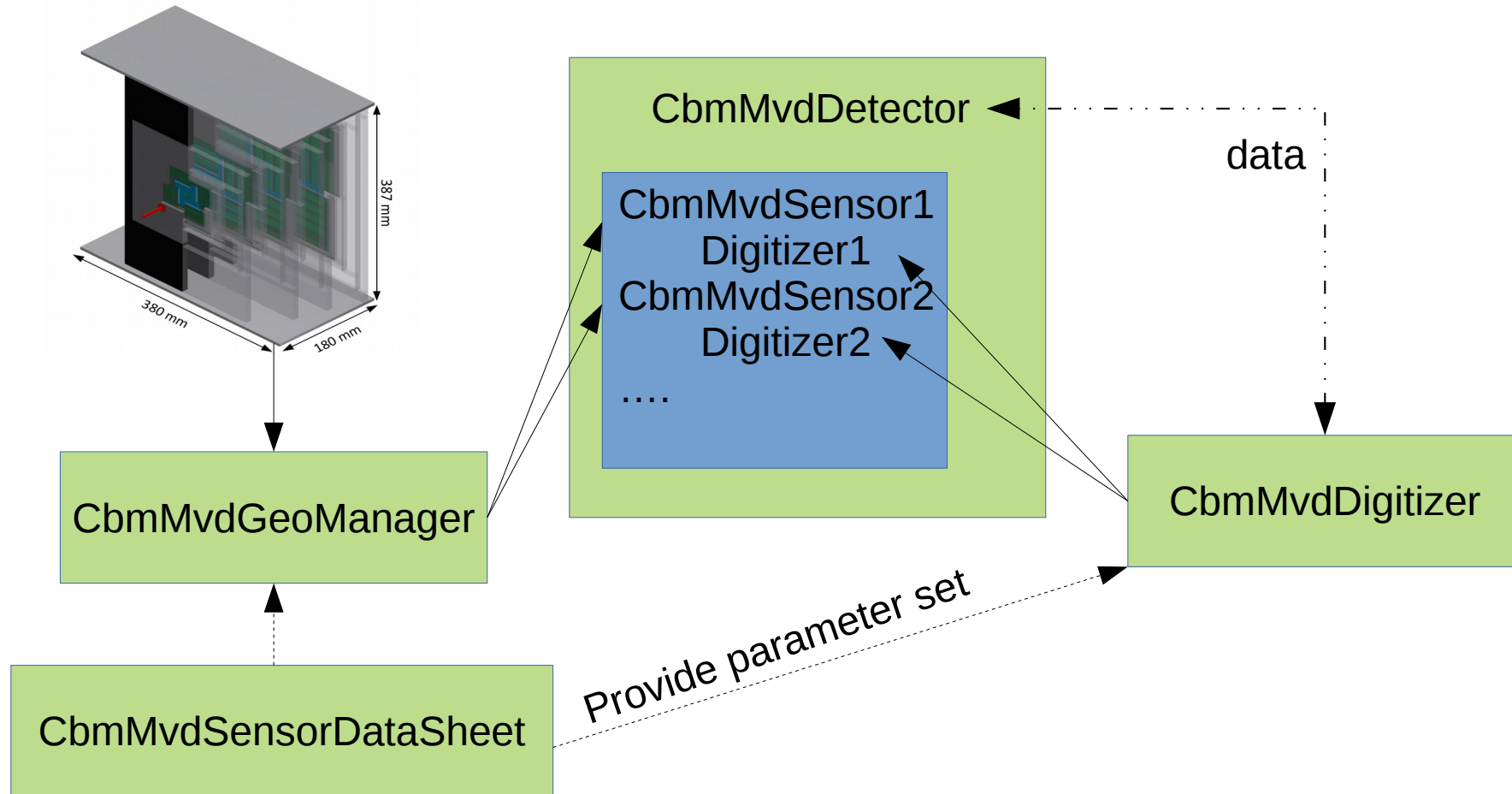
CbmMvdGeoManager

CbmMvdSensorDataSheet

# MVD Digitizer concept

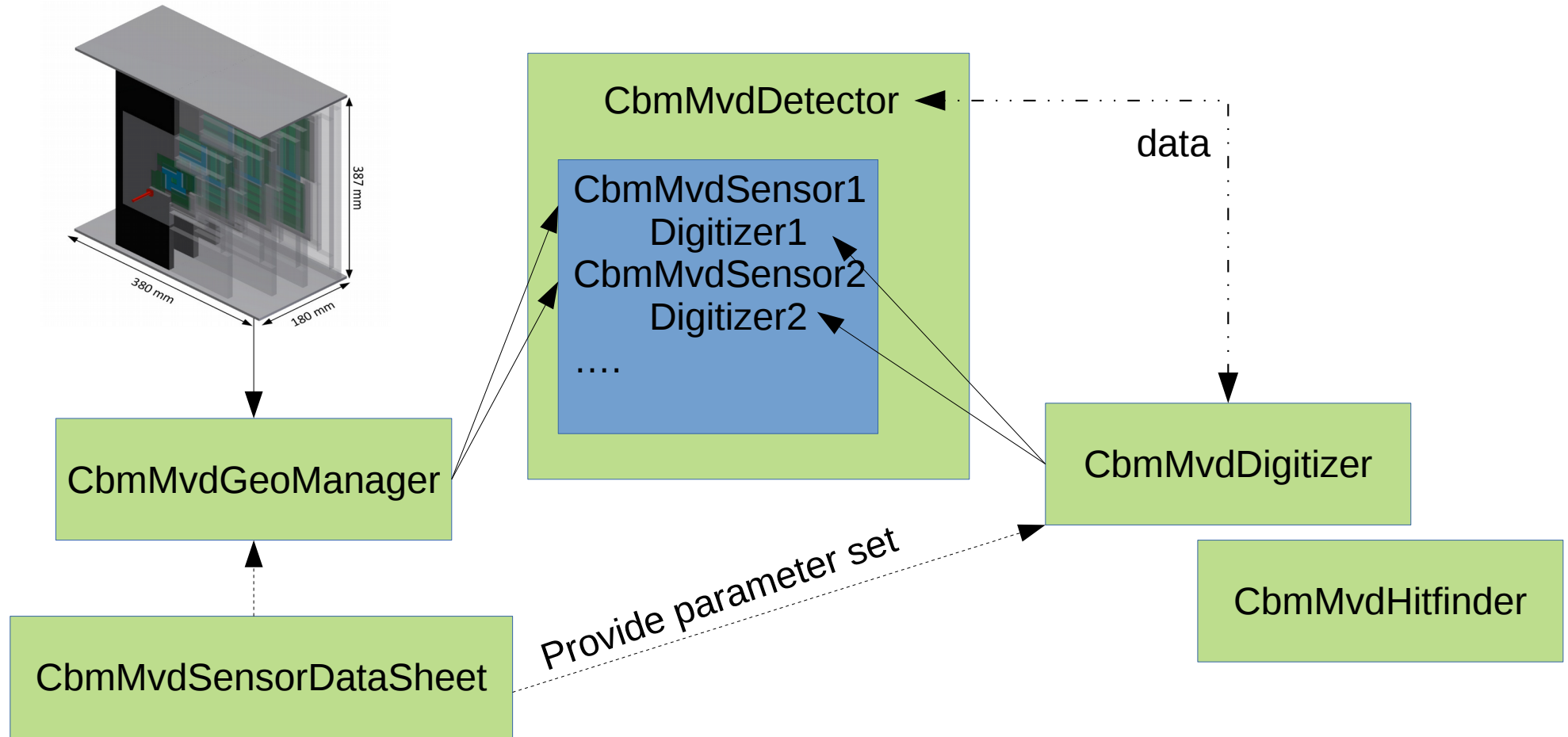


# MVD Digitizer concept





# MVD Digitizer concept



# New Geometries

```
CbmSetup* setup = CbmSetup::Instance();  
setup->SetFieldScale();  
setup->SetModule(kMvd, "v17a_vx");
```

```
CbmMvdDetector::SetSensorTyp(CbmMvdSensorTyp::MIMOSIS);
```

```
CbmMvdDigitizer* mvdDigitise =  
    new CbmMvdDigitizer("MVD Digitiser", 0, iVerbose);
```

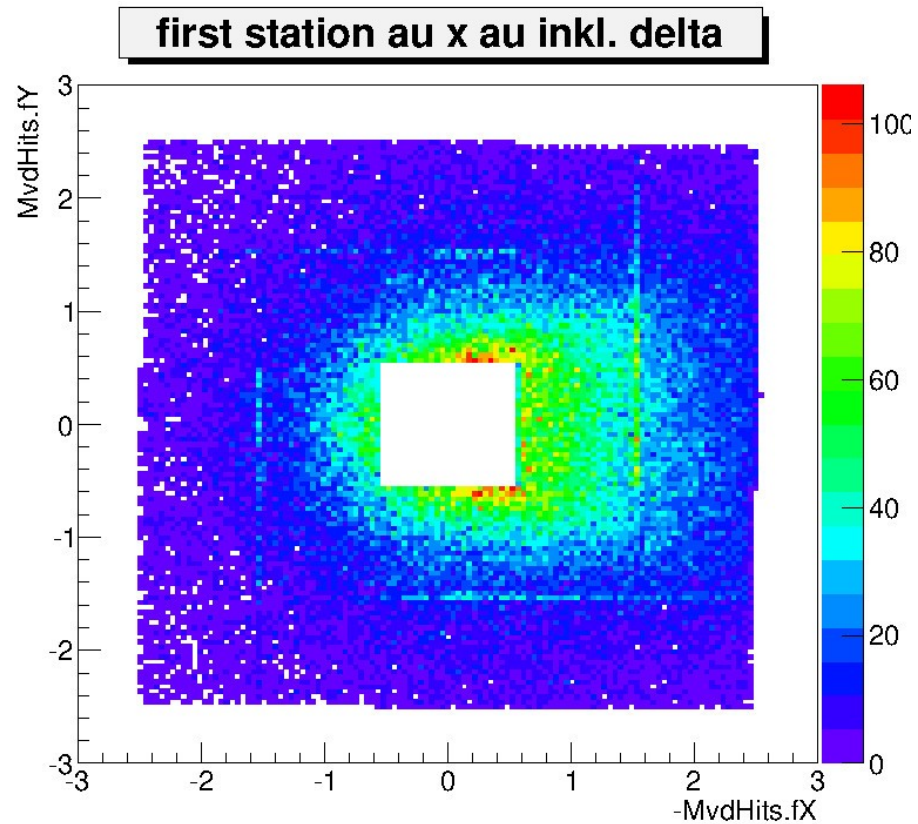
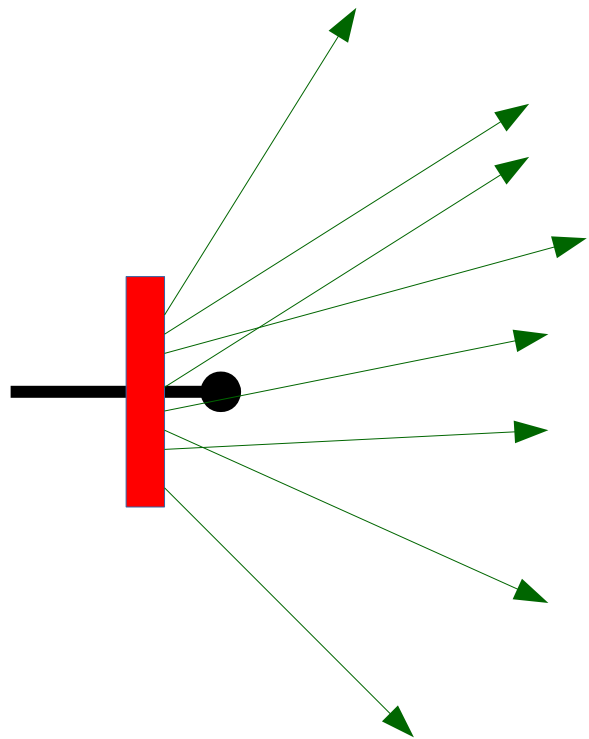
Sensor typ is set via a static Function in CbmMvdDetector.



Digitizer and reconstruction automatically get parameters from data sheets

Test: New geometries

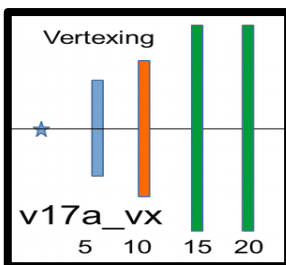
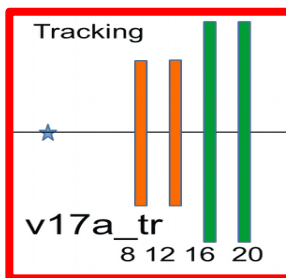
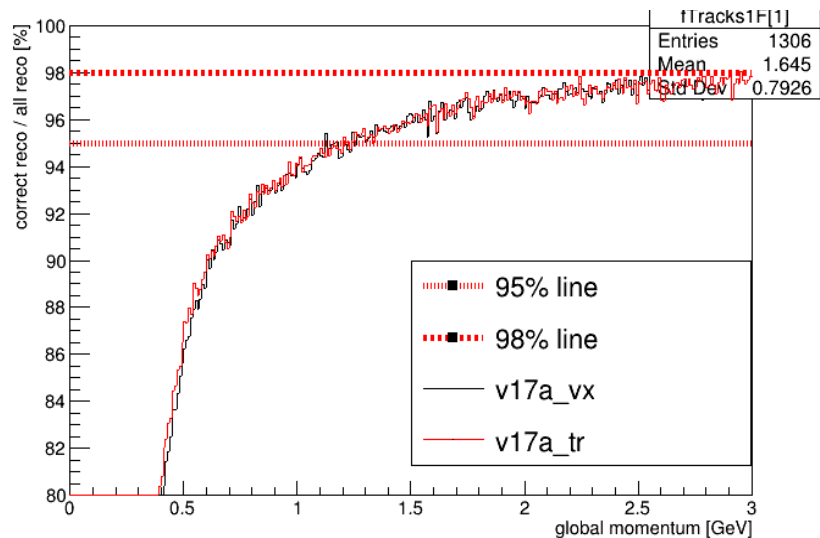
# Delta electrons on S0



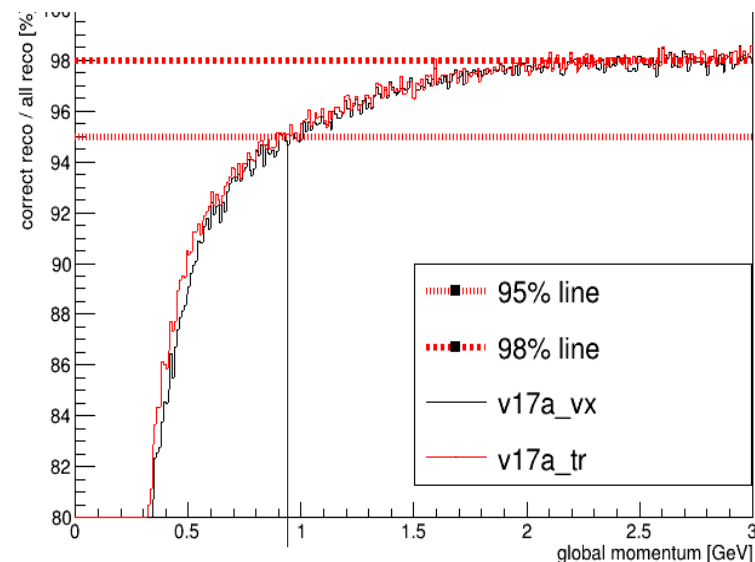
# Vertex vs. Tracking Geometry

Au+Au, 10 AGeV  
100 kHz

Field = 100%



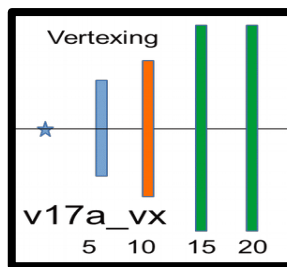
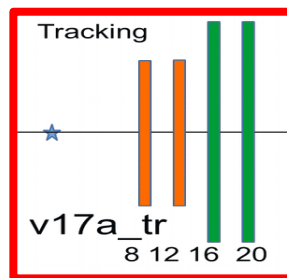
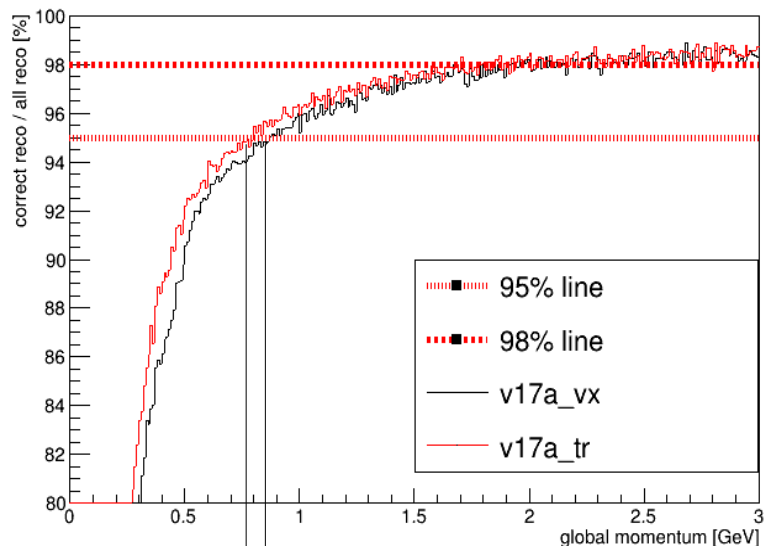
Field = 70%



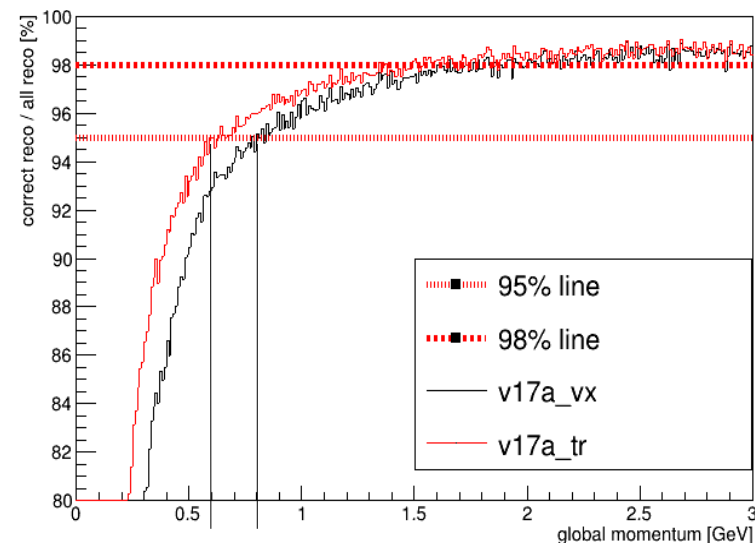
# Vertex vs. Tracking Geometry

Au+Au, 10 AGeV  
100 kHz

Field = 50%



Field = 30%



Tracking geometry helps in reconstruction low momentum tracks

# Summary and conclusion

- New Sensor design implemented.
- New updated geometries available and tested.
- New design helps in low momentum track reconstruction.

Questions?