

Statistics and models of SiPM nonlinearity and saturation

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Statistics of SiPM nonlinearity and saturation **ICASiPM** 14-06-2018

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Scope & outline

- Photon detection a series of stochastic processes described by statistics
 - It could be described as a filtered marked correlated history-dependent point process
 - SiPM response a result of the stochastic process a random variable

Nonlinearity and saturation – the most sophisticated topic in SiPM statistics

Binomial nonlinearity – detection of short light pulses (Tpulse < Trecovery)</p>

- Conventional model: Poisson Npe in N pixels
- Adjustments to CT to account for
 - Crosstalk
 - Recovery
- Recovery nonlinearity detection of long light pulses (Tpulse > Trecovery)
 - Conventional model: non-paralizible counting with dead time
 - Advanced model of exponential recovery process
 - Advanced+ model of Markov reward-renewal process

Statistics of linear photon detection

Full characterization of random variable *Nout* resulted from photon detection processes Ο

- Probability distribution Pr(*Nout*) conditional on Pr(*Nin*)
 - Mean <*Nout*>
 - Variance (*Nout*) or $\sigma(N_{out})$
- Partial characterization (the most demanded in practice): 0
 - Mean and Var of *Nout* conditional on Mean and Var of *Nin*
 - Supported by Burgess variance theorem
 - ENF approach for independent process chains allows to analyse specific noise contributions
- Linear detection: responsivity $R = \langle Nout \rangle / \langle Nin \rangle = const$ Ο
 - Resolution σ/μ is degraded by specific ENFs



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Statistics of nonlinear photon detection

• Nonlinear: R = R(Nph)

- Nonlinearity = $\underline{random \ losses}$
- Losses depend on load *Nph*
- Output resolution is "improved"
- Calibrated resolution is degraded

 $\sigma_{out} < \sigma_{in} < \sigma_{calibrated}$ even for ideal nonlinear detector

• Excess noise of nonlinearity

$$ENF = \frac{Res_{calib}^2}{Res_{in}^2} = \frac{\sigma_{calib}^2}{\sigma_{in}^2} = \frac{1}{\sigma_{in}^2} \cdot \frac{\sigma_{out}^2}{\left(\frac{d\mu_{out}}{d\mu_{in}}\right)^2}$$

Nonlinear statistics:



- Linear processes + Nonlinear processes =>
- Severe complications in statistics (quantity/history/mutually-dependent processes)
 - New nonlinear distribution Pr(Nout), <Nout>, $\sigma(Nout)$
 - New nonlinear responsivity R = R(Nph)
 - -New ENF of nonlinearity

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Binomial distribution of SiPM response

Binomial distribution – detection of short light pulses (Tpulse < Trecovery)</p>



Nuisance Parameters: ENF

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Binomial distribution is presumed

SiPM dynamic range

Dynamic range is limited due to finite total number of pixels mSignal ~ $m(1-exp(-N_{ph.e}/m))$



Urn model with non-random Npe is approximated to normal distribution with binomial μ and σ

The considered problem is equivalent to a well-known problem in mathematical statistics of distributing (randomly) n balls (photoelectrons) into m urns (cells), see e.g. [4]. The number N of urns containing one or more balls is a random variable, its expected value and variance are:

$$\overline{N} = m \left[1 - (1 - m^{-1})^n \right]$$

$$\sigma_N^2 = m \left(m - 1 \right) \left(1 - 2m^{-1} \right)^n + m \left(1 - m^{-1} \right)^n - m^2 \left(1 - m^{-1} \right)^{2n}$$
(1)

The distribution of N is approximately normal when $m, n \to \infty$ and the ratio $\alpha = n/m$ is bounded [4]:

$$\overline{N} = m(1 - e^{-\alpha})
\sigma_N^2 = m e^{-\alpha} [1 - (1 + \alpha) e^{-\alpha}].$$
(2)

In practice the number of cells in a G-APD is usually greater than ~ 100 , which justifies using the asymptotic formulae (2) in the following analysis.





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SiPM binomial nonlinearity: losses of photons firing the same pixel

O Binomial distribution of fired pixels N_{det} in SiPM (*Tpulse < Trecovery*)

$$\Pr(N_{det}, N_{pix}, p)) = \frac{N_{pix}!}{(N_{pix} - N_{det})! N_{det}!} p^k (1-p)^{N_{pix} - N_{det}} \qquad p = 1 - e^{-\frac{N_{pe}}{N_{pix}}}$$

$$P(0) = \exp\left(-\frac{N_{pe}}{N_{pix}}\right) \quad E[N_{det}] = N_{pix} \cdot [1 - P(0)] \quad Var[N_{det}] = N_{pix} \cdot [1 - P(0)] \cdot P(0)$$



Excess noise factor - S. Vinogradov et al., IEEE NSS/MIC 2009

Losses of simultaneous photons in a pixel results in nonlinearity and excess noise







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Binomial vs Poisson



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Adjustments of binomial model

Crosstalk

• Typical approach: extension of mean Npe to include mean CT events μ_{CT} - Npe \rightarrow Npe(1+ μ_{CT})

• So, Mean
$$N_{det} = N_{pix} \left(1 - e^{-\frac{N_{pe}}{N_{pix}}} \right) \rightarrow N_{pix} \left(1 - e^{-\frac{N_{pe}(1 + \mu_{CT})}{N_{pix}}} \right)$$

- Reasonable from common sense, looks nice and simple but...
- In general, incorrect because Poisson with CT is not Poisson
- What about Variance N_{det} ???

—What about Resolution ???

– And finally - probability distribution ???

Adjustments of binomial model

Recovery

• Typical approach: extension of mean Npix to include mean retriggering events μ_{RT}

- Npix \rightarrow Neff = Npix(1+ μ_{RT})=Npix(1+Tpulse/Trec)

• So, Mean
$$N_{det} = N_{pix} \left(1 - e^{-\frac{N_{pe}}{N_{pix}}} \right) \rightarrow N_{pix} \left(1 + \frac{T_{pulse}}{T_{rec}} \right) \left(1 - e^{-\frac{N_{pe}}{N_{pix}(1 + \frac{T_{pulse}}{T_{rec}})}} \right)$$

- Reasonable from common sense, looks nice and simple...
- In general, <u>possible</u> because Poisson Npe over fixed Neff is still binomial — More reasons in support ???
- What about Variance N_{det} ???

—What about Resolution ???

– And finally - probability distribution ???

• Main question: what about lower Gain due to incomplete recovery?

Adjustments of binomial model

• Crosstalk + Recovery

• Typical approach: both corrections are applied as fitting parameters

• So, Mean
$$N_{det} = N_{pix} \left(1 - e^{-\frac{N_{pe}}{N_{pix}}} \right) \rightarrow N_{eff_{-1}} \left(1 - e^{-\frac{N_{pe}}{N_{eff_{-2}}}} \right)$$

• So, the same concerns and questions

Recovery nonlinearity of SiPM response

Recovery nonlinearity – detection of long light pulses (Tpulse > Trecovery)



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SiPM recovery nonlinearity

 $T_{pulse} >> T_{rec}$

Nonparalizible dead time model Probability distribution (~ Gaussian)

W. Feller, An Introduction to Probability Theory and Its Applications, Vol. 2, Ch. XI, John Willey & Sons, Inc., 1968

$$\mu_{Ns} = \frac{\lambda \cdot t}{1 + \lambda \cdot \tau_{dead}}$$
$$\sigma^{2}_{Ns} = \frac{\lambda \cdot t}{(1 + \lambda \cdot \tau_{dead})^{3}}$$

$\begin{array}{l} \mbox{Recovery nonlinearity of SiPM} \\ \rightarrow \mbox{ENF} \end{array}$

S. Vinogradov et al., IEEE NSS/MIC 2009

$$ENF_{eq(Nph)}(\lambda) = 1 + \lambda \cdot \tau_{dead}$$



SiPM recovery nonlinearity: advanced model of exponential recovery

- Non-paralizible dead time model for SiPM (ENF)
- Exponential RC recovery model (*Gain, PDE, ENF*) Losses of sequential photons due to incomplete pixel recovery





S. Vinogradov, SPIE Adv. Photon Counting 2012

Advanced model of exponential recovery: accounting for a transient PDE is a must





Pixel load, photoelectrons per recovery time

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Comparison of models



Figure 3. Photon Number Resolution for short (binomial model) and long (dead time and RC recovery models) light pulses calculated for MPPC KSX-I50015-E_S12573 Series 50 um pixel size, 3x3 sq. mm area.

Photon Number Resolution

Advanced+ model of SiPM recovery: reward-renewal Markov process:

- Renewal process: conditional probabilities of times between events (photon arrivals & avalanche triggers)
- Reward process: random gain dependent on time delay
- Exponential RC recovery model: Gain(t), PDE(t)



Reward-renewal Markov process model: qualitative correspondence for transient mean



Time, relative to pixel recovery time

SiPM nonlinearity and saturation papers

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Thank you for your attention!

Questions? Objections? Opinions?

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