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SUMMARY: SiPM nonlinearity and saturation

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Scope & outline

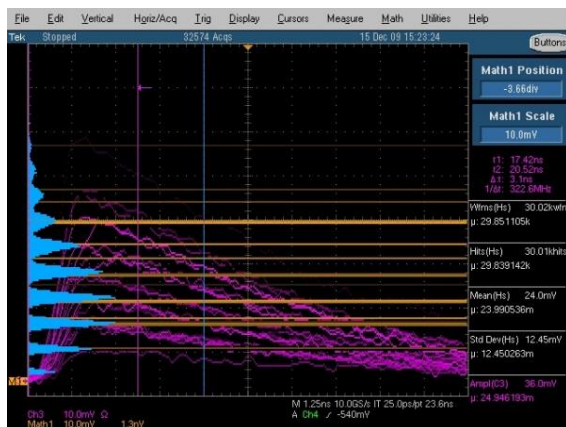
- **Our session – on SiPM nonlinearity and saturation in photon-number-resolving detection**
 - Introduction & summary – Sergey Vinogradov
 - Statistics & models – Sergey Vinogradov
 - Physics & experiments – Elena Popova
 - Methods of measurement and calibration of SiPM
 - Double Light Superposition Method by NDL – Jian Liu
 - Measurement and calibration for particle calorimetry by CALICE – Sascha Krause
- Discussion

- Applications of SiPMs, in general:
 - **Multi-photon pulse detection:**
 - **A) Measure a number of photons (typical figure of merit - photon number /energy resolution) – is in focus of our session**
 - B) Measure a time-of-flight (figure of merit - time resolution)
 - C) A + B (TOF PET, LIDAR...)
 - D) Detection of arbitrary time-varying light signals to measure intensity $I(t)$

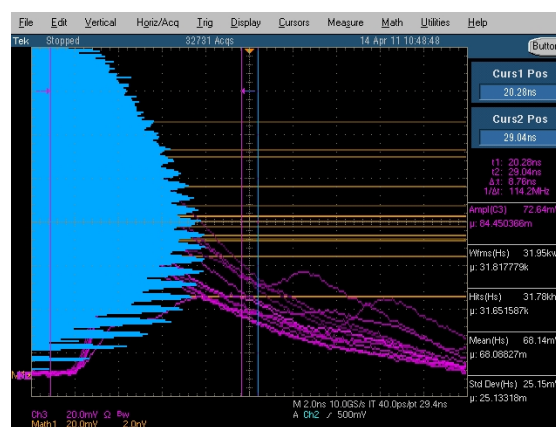
Observable quantities

- SiPM convert photons to electrons (... AQC – electrons to some units, e.g. [V]...)
 - SiPM response charge is the best observable quantity
 - - response amplitude is AQC-dependent (application & user specific)
 - - response shape is weakly dependent on incident light
- Response charge Q is a random quantity (Probability distr., Mean, StdDev)
 - as well as a number of photons N_{ph} (assumed to be Poisson random variable)
- Responsivity (calibration) function is defined for Mean quantities $\langle Q \rangle = f(\langle N_{ph} \rangle)$
- $Responsivity = \frac{\langle output\ electrons \rangle}{\langle input\ photons \rangle}$ $R = \frac{\langle Q \rangle}{\langle N_{ph} \rangle}$ if Gain is known $\rightarrow R_{pix} = \frac{\langle N_{fired} \rangle}{\langle N_{ph} \rangle}$

Low N_{ph}



Moderate

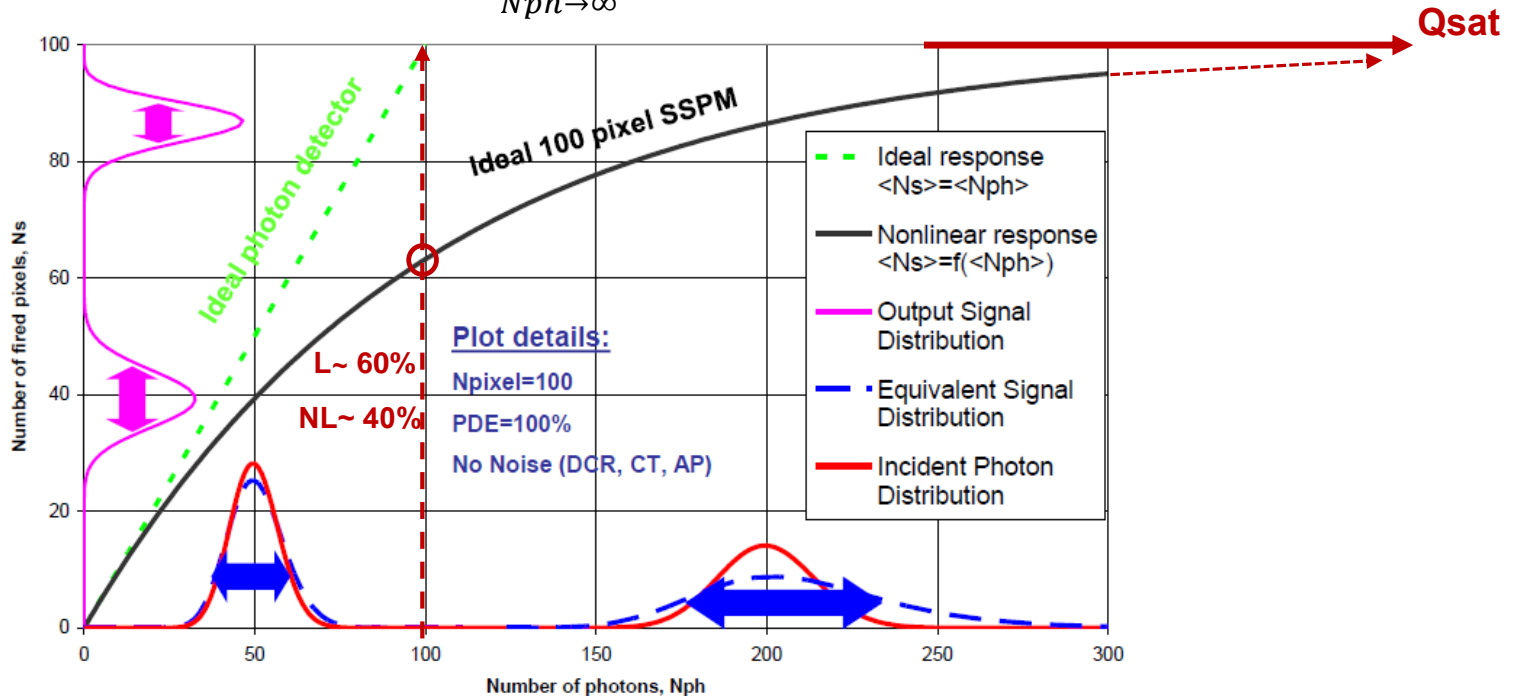


High



Definitions

- *“Ideal” linearity:* $R = \frac{\langle Q \rangle}{\langle N_{ph} \rangle} = const$ *for any $\langle N_{ph} \rangle$*
- *Linearity L:* $L = \frac{R_{min}}{R_{max}}$ *for $\langle N_{ph} \rangle = N_{min} \dots N_{max}$*
- *NonLinearity NL:* $NL = 1 - L = \frac{\Delta R}{R_{max}}$ *where $R_{max} \sim$ linear responsivity*
- *Dynamic range DR:* $DR = \frac{N_{max}}{N_{min}}$ *for given L*
- *Nmin by threshold:* $SNR(N_{min})=1$ *Nmax by some L (say, 90%; NL=10%)*
- *Saturation Qsat:* $Q_{sat} = \lim_{N_{ph} \rightarrow \infty} (Q(N_{ph}))$ *! TBD for oversaturation !*

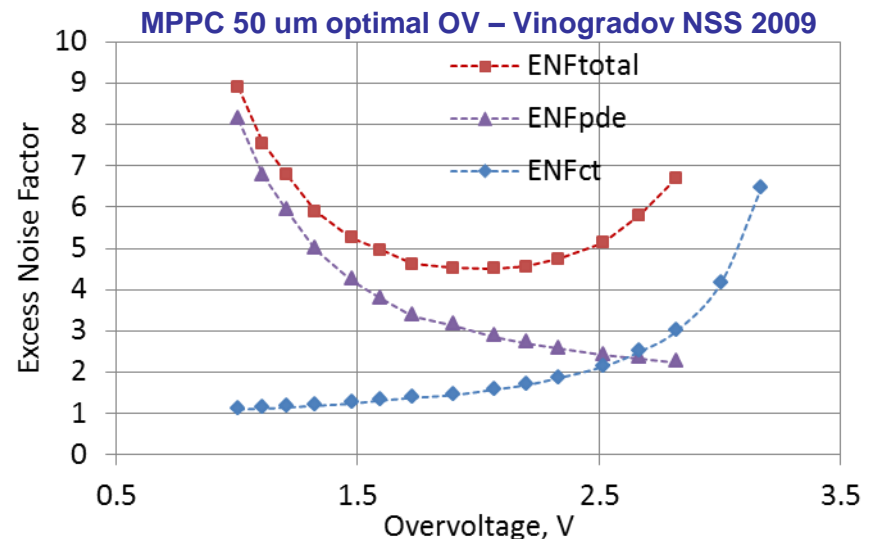


Characterization of nonlinearity

- Full: by Probability distr. $\Pr(Q \mid N_{ph}, \text{pulse shape}(t), \lambda, U_{bias}, T \dots)$
- Short: by 1st and 2nd statistical moments of Q
 - ◆ Mean_Q vs Nph – calibration curve
 - ◆ StdDev_Q vs Nph – calibration error
 - ◆ StdDev_Q/Mean_Q (in Nph scale) vs Nph – calibrated resolution
- How to define “standard” condition of measurements?
 - ◆ Light pulse: shape, duration, wavelength
 - ◆ SiPM: bias voltage, temperature
 - ◆ SiPM + Light: uniformity over active area, light on peripheral area
- If we can't define that, the calibration becomes
 - ◆ Multi-parametric function – in general
 - ◆ Application-specific – in particular
- How to resolve or balance out the trade-off?

Standardization of characterization

- Pulse shape and duration could be fixed to two distinct cases:
 - A) Short \sim sub-ns (\ll recovery time) / shape is out of spec
 - B) Long $\sim \mu\text{s}\dots\text{ms}$ (\gg recovery time) / CW light on/off
- Wavelength-related variability could be eliminated:
 - Nonlinear effects are determined by $N_{\text{pe}}/\text{cell}$; N_{pe} is an invariant input
 - Linear range: $N_{\text{pe}} = \text{PDE}(\lambda) \cdot N_{\text{ph}}$; (correlated events to be accounted)
 - Calibration in N_{pe} @ known $\text{PDE}(\lambda)$ (vendor spec; more at PDE session)
- Bias voltage should be fixed at optimal value for linear range
 - Linear range: Min $\text{ENF}_{\text{total}}$ or max DQE vs U_{bias} (see my talk on Noise and ENF, 13/06/2018)
- $T \rightarrow$ room temperature... some other?
- Something missed?



Methodical issues

- Dynamic range $> 10^6$: (e.g. MAPD of 40K cells/mm², 3x3mm²)
 - ◆ Light sources (... filters?)
 - ◆ Reference photodetectors (SPAD ... PIN diode?)
 - ◆ Acquisition electronics (... direct coupling to scope/HDR digitizer?)
- Spatial effects
 - ◆ Uniformity of illumination over active area (%?)
 - ◆ Light on peripheral area – collection of extra Npe (%?)
 - ◆ Low-gain at periphery with low E-field regions (Gain ~ 1000 @Ubias=Ubd)
- Load-dependent effects
 - ◆ Thermal – overheating of SiPM – dependent on heat dissipation/casing
 - ◆ Voltage drop – under-biasing of SiPM – dependent on quenching and external circuitry resistors
- Something missed?
- Welcome to the brave new world of high light and nonlinearity!

The end

Thank you for your attention!

Questions?

Objections?

Opinions?

...

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