

# Fitting of Forward Endcap EMC into the $\bar{\text{P}}\text{ANDA}$ Magnet Yoke

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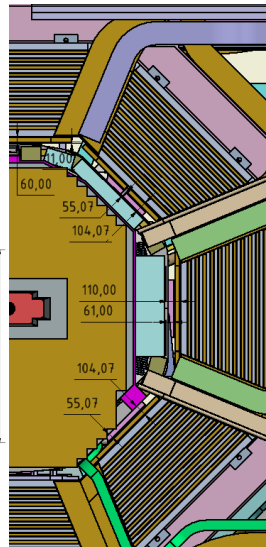
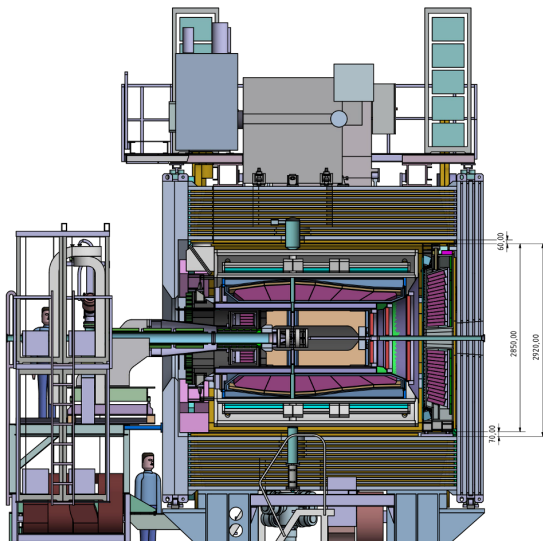
PANDA Collaboration Meeting 17/3, Novosibirsk  
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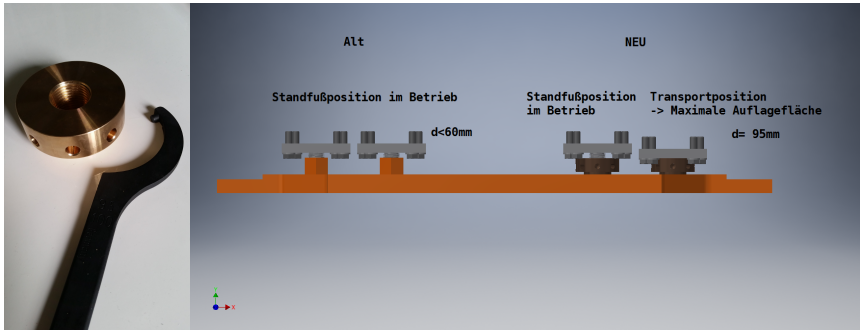


# Forward Endcap in $\bar{\text{P}}\text{ANDA}$ Magnet Yoke: Boundary Conditions



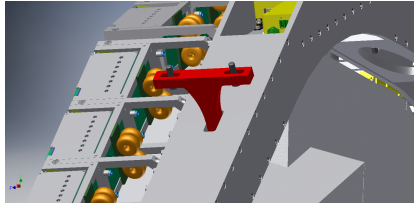
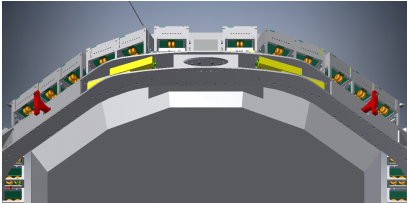
# Forward Endcap in $\bar{\text{P}}\text{ANDA}$ Magnet Yoke: Mounting

- Cast bronze feet:
  - Secure stand in 4 holes in magnet yoke (base plate)
  - Height/tilt adjustment of forward endcap by  $\approx 4$  cm
  - Increase of contact surface during transport when fully screwed in (in contrast to old hexagon design)



# Forward Endcap in $\bar{\text{P}}\text{ANDA}$ Magnet Yoke: Mounting

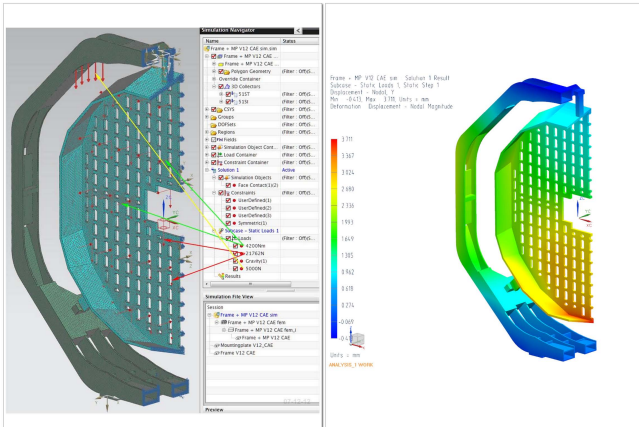
- Upper suspension (prevention from tipping) to magnet:
  - Aluminum pieces screwed to magnet, not affixed to endcap support frame
  - z-position?
  - → Deformation of frame



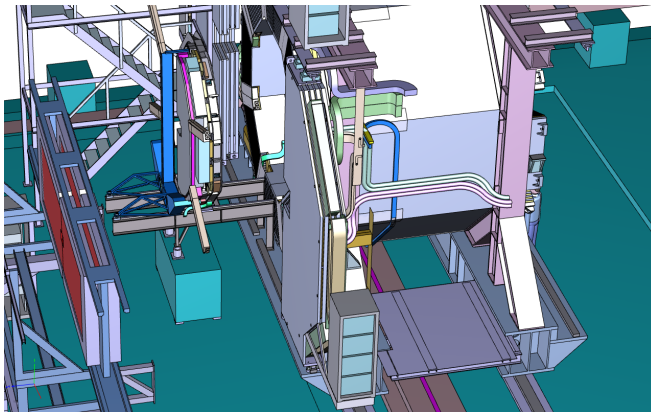
# Forward Endcap in PANDA Magnet Yoke: Boundary Conditions

- Detector inside support frame will come down by 3.7 cm
- Deformation of frame? → Query to KVI engineers

### Results simulation V12

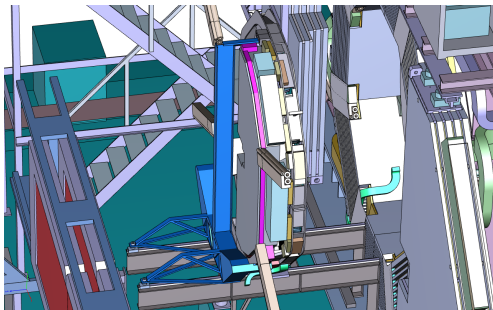


# Forward Endcap in $\bar{\text{P}}\text{ANDA}$ Magnet Yoke: Insertion



- Roll in of endcap on rails ending in front of magnet
- Clamp rolls on roll-in frame prevent fall over of endcap
- Suspension of forward endcap frame at most stable points

# Forward Endcap in $\bar{\text{P}}\text{ANDA}$ Magnet Yoke: Insertion



- Lowering of forward endcap into feed holes in magnet by very slight tilting (lowering at position of front bearings only)
- Additional securing by use of 8 securing screws on backplate (coupling also backplate to roll-in frame as during transport)
- Receiving endcap from transport frame in the same way as putting it into magnet