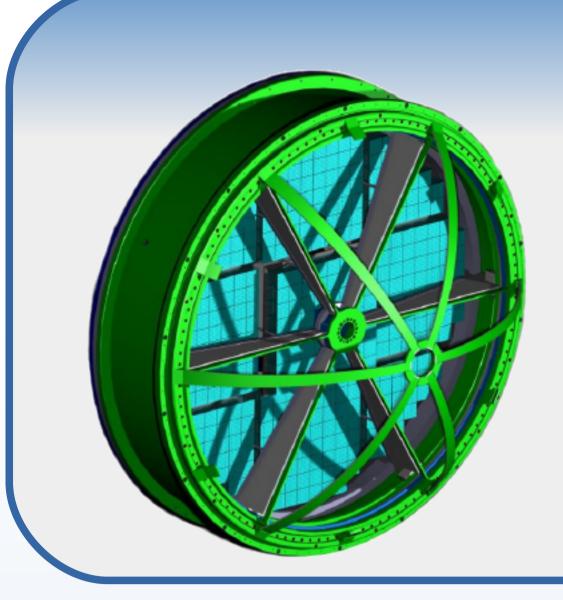
A slow control and TDC calibration system for the HADES RICH upgrade Adrian Amatus Weber¹, Peter Zumbruch², Jan Michel³ and Claudia Höhne¹ for the HADES-Collaboration -¹Justus-Liebig-Universität Gießen -²GSI Darmstadt -³Goethe-Universität Frankfurt



Motivation

The HADES RICH is upgraded for the upcoming beamtime with new Hamamatsu H12700 multianode photomultipliers (MAPMTs) and new front end electronis (FEE). The FEE is realisied with special designed DiRICH Boards which contain a FPGA based time to digital converter (TDC). Therefore a new slow control system and a FPGA based online calibration for the TDC is developed.

MAPMTs:

- High voltage power supply
- Requires magnetic field monitoring ~10mT

Front end electronics:

- Low voltage power supply
- Temperature control
- Temperature based TDC calibration



slow control system and LV power supply

EPICS based slow control

- low and high voltage control
- TRB3 board-temperature control
- X-, Y-, Z-axis magnetic field measurement
- temperature, pressure, humidity and light measurement
- Control System Studio (CSS) used as GUI

• Low Voltage Power Supply:

- TDK Lambda Genesis 60-40
- IOC running on own computer
- LAN connection between TDK Lambda and computer

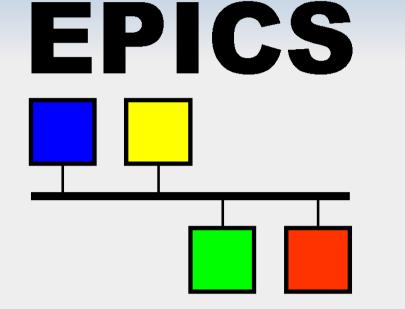


high voltage power supply

CBM_RICH HV Control

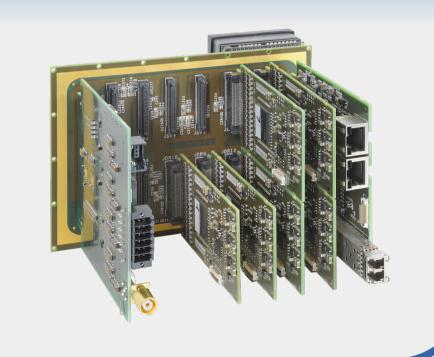
ISEG ECH 44A crate with 6 EHS F620n-F_SHV modules à 16 channels

- single channel floating ground
- CC24 master:
- IOC running on CC24 • connects EPICS via LAN • IOC allows to control ...



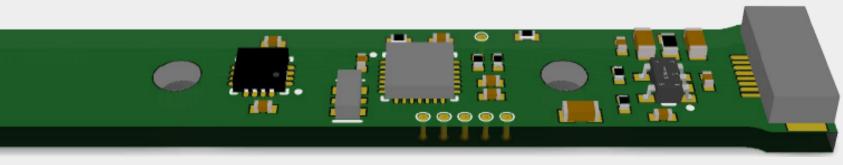
TRB temperature readout

- TRB temperature readout via EPICS slow control :
 - IOC based on TrbCmd instructions
 - communication via TrbNet
 - temperature readout of many TRB3 boards at one
 - small load for TrbNet



(environment-) sensor board

- magnetic field measurement board: 210 x 10 mm
 - ATmega168PA microcontroller
 - equipped with four 3-axis magnetic field sensors MLX90393
 - UART communication
 - possibility to shorten board to 40 x 10 mm
 - \rightarrow only 1 magnetic field sensor on board



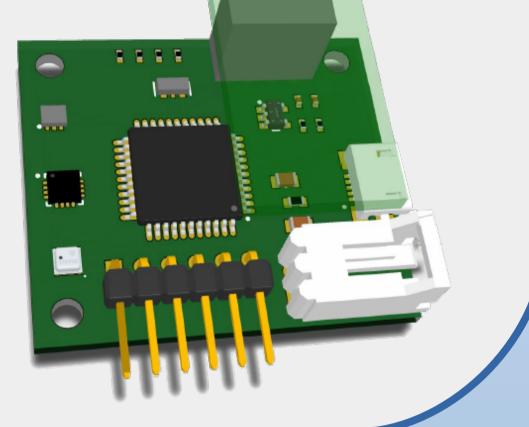
• environment sensor board: 30 x 31 mm



- ... each channel individually
- ... pre-selected groups of channe
- ... individually grouped channels
- voltage precision of 80mV
- current precision of 160nA

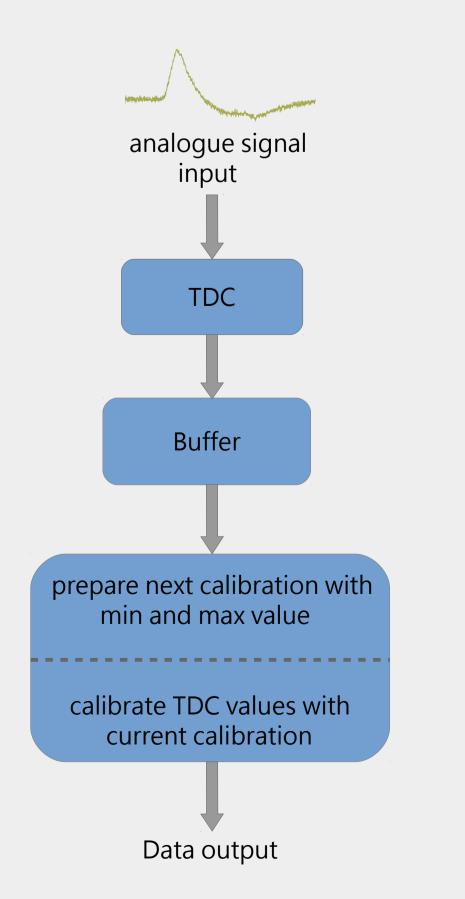
	Channel	Set Voltage [V]	Set Current [A]	Measured Voltage [V]	Measured Current [A]	Trip Time (m	5] Power	VoltageBounds	CurrentBounds	Emergency	Status	ON/C
R	CH 0	300 V	1,000E-4 A	301 V	1,431E-10 A	0 s	0	0 V	0,000 A			
V	CH 1	300 V	1,000E-4 A	301 V	1,112E-9 A	0 s	0	0 V	0,000 A			
R	CH 2	300 V	1,000E-4 A	300 V	1,253E-10 A	0 s	0	0 V	0,000 A			
	CH 3	0 V	1,000E-4 A	-0 V	1,420E-10 A	0 s	-0	0 V	0,000 A			
	CH 4	0 V	1,000E-4 A	-0 V	2,639E-10 A	0 s	-0	0 V	0,000 A			
	CH 5	0 V	1,000E-4 A	-0 V	2,871E-10 A	0 s	-0	0 V	0,000 A			
	CH 6	0 V	1,000E-4 A	-0 V	2,027E-10 A	0 s	-0	0 V	0,000 A			
	CH 7	0 V	1,000E-4 A	-0 V	1,946E-10 A	0 s	-0	0 V	0,000 A	۲		
					VoltageRampSpeed	CurrentRampSpeed					Input Error isOutageramp isEmergency isCC isCV isCV isCV isCV isCV isCV isCV	is VoltageLimit
,	Modul	Temperatur	Eve	nt Status		[%*Inom/s]	VoltageLimit	CurrentLimit	SampleRate	V_Nom	I_Nom	of Module
Ľ	Modul	28 C		nt Status	[%*Vnom/s]	[%*inom/s]	VoltageLimit	CurrentLimit	SampleRate		0,0010 A	
	Group ehaviour	Set Voltage [V]	Set Current [A	Trip Time [ms]	Voltage Bounds	Current Bounds	_		OFF			
De	enaviour	300 V	0,000E0 A	0 s	0 0	,000E0		٠ - ا				

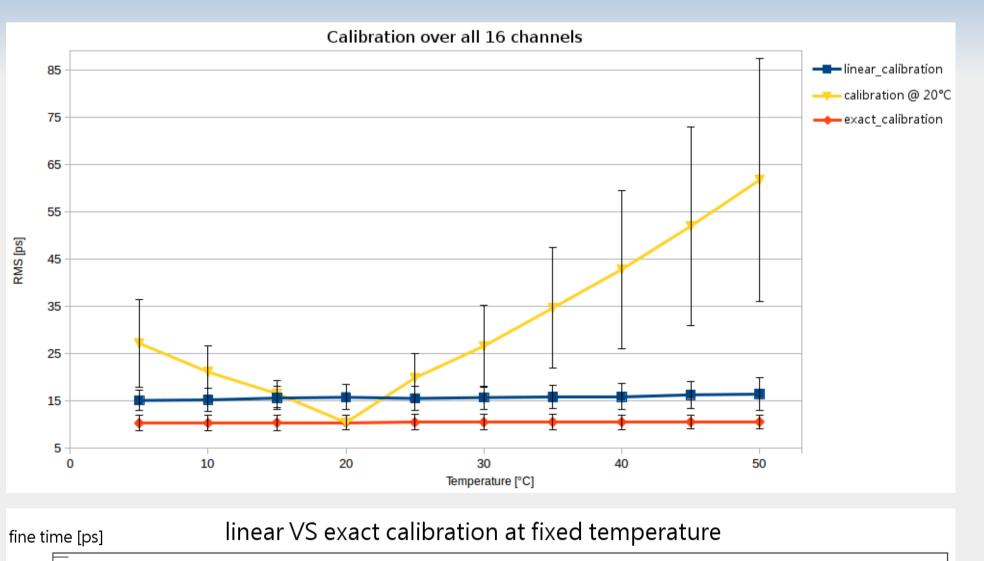
- ATmega32U4 microcontroller • 3-axis magnetic field sensors MLX90393 humidity, pressure and temperature with BME280 sensor light sensor TSL2591
- communication via USB, UART or WIFI (ESP8266)



temperature dependent calibration of FPGA based time to digital converter (TDC)

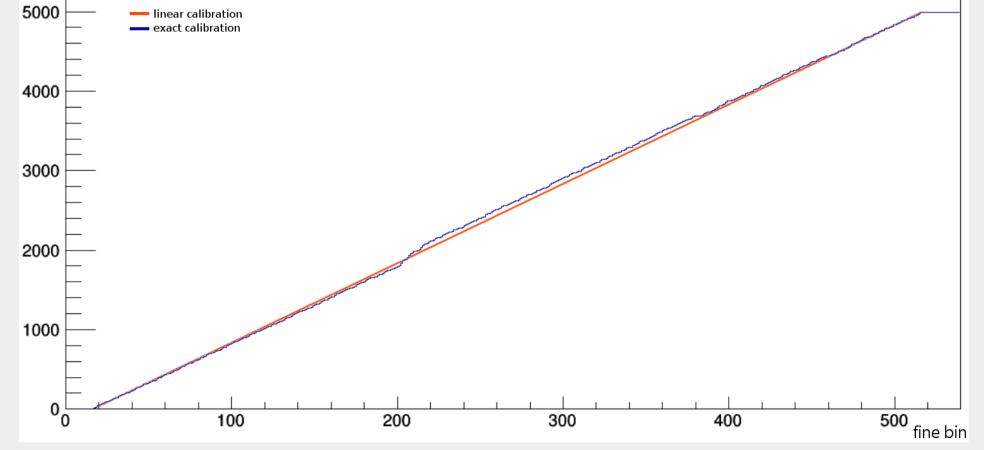
- TRB3 and DiRICH board use TDC implemented in Lattice ECP5/ECP3 FPGA
- precision of TDC is temperature dependent
- \rightarrow calibration is necessary
- until now: Software based calibration
 - linear calibration
 - exact calibration
- measurements for temperatures between 5°C and 50 °C were done
 - different calibration methods tested
 - linear calibration reaches a precision of 15 ps in mean
 - exact calibration reaches 10 ps





- \rightarrow linear calibration is a good method and reaches an adequate precision
- A linear FPGA based calibration is implemented
- FPGA uses incoming data for two purposes:
- calibrate the data with minimum and maximum values as well as slope values from lookup tables (LUT) • use new data to generate next calibration values • own calibration for each channel of each FPGA no additional temperature information necessary

Figure: Box diagram of the FPGA based calibration.



Upper figure: RMS value for different calibration methods at different temperatures. The values are mean values over all 16 channels. Methods: linear calibration; calibration with exact calibration@20°C; exact calibration. Lower figure: linear versus exact calibration for a fixed temperature.

