

Introduction

The Silicon Tracking System (STS) facilitates the track reconstruction and momentum determination of charged particles for the Compressed Baryonic Matter (CBM) experiment. For this work, STS geometry version 15b has been taken, which consists of 8 Stations, 106 ladders, 212 half-ladder, 900 modules, 1220 sensors in five step hierarchical structure. 8 tracking layers of silicon detectors are located downstream of the target at distances 30cm and 100cm inside the magnetic dipole field. The concept of the STS tracking is based on silicon microstrip sensor mounted onto lightweight mechanical support ladders. The microstrip sensors have been designed to be double-sided with a stereo angle of 7.5° , a strip of $58\mu\text{m}$ and a thickness of $300\mu\text{m}$ of silicon.

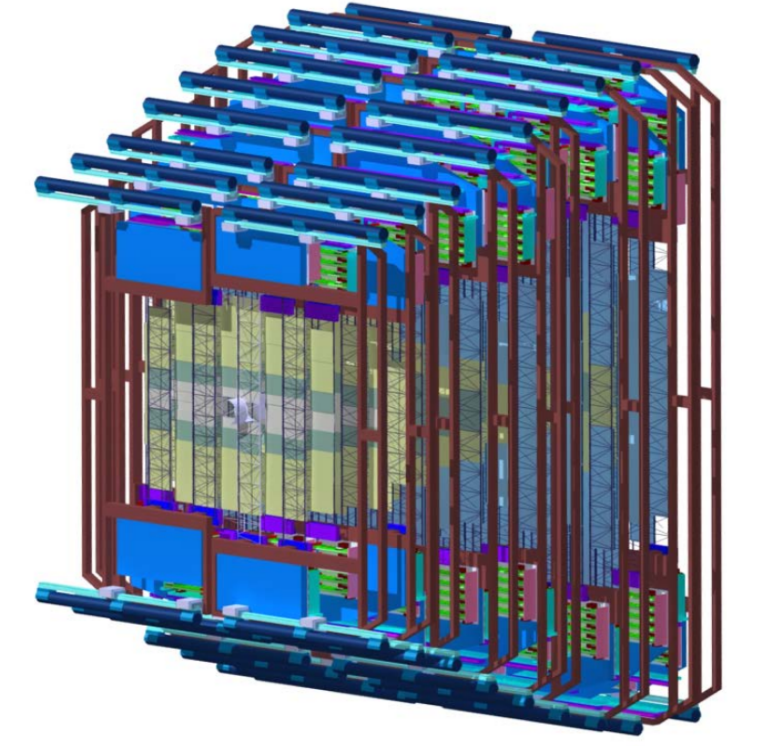


Fig. 1: Structure of STS Geometry

Motivation

- Limited mechanical mounting precision ($\sim 100\mu\text{m}$)
- Possible deformations due to temperature effect.
- Influence of magnetic field leads to misalignment of the ideal detector.
- Only mechanical mounting fails to provide unprecedented spatial resolution of the STS.
- Therefore, the track themselves are more reliable to use to determine the exact STS element positions ($\sim 10\mu\text{m}$) after alignment.

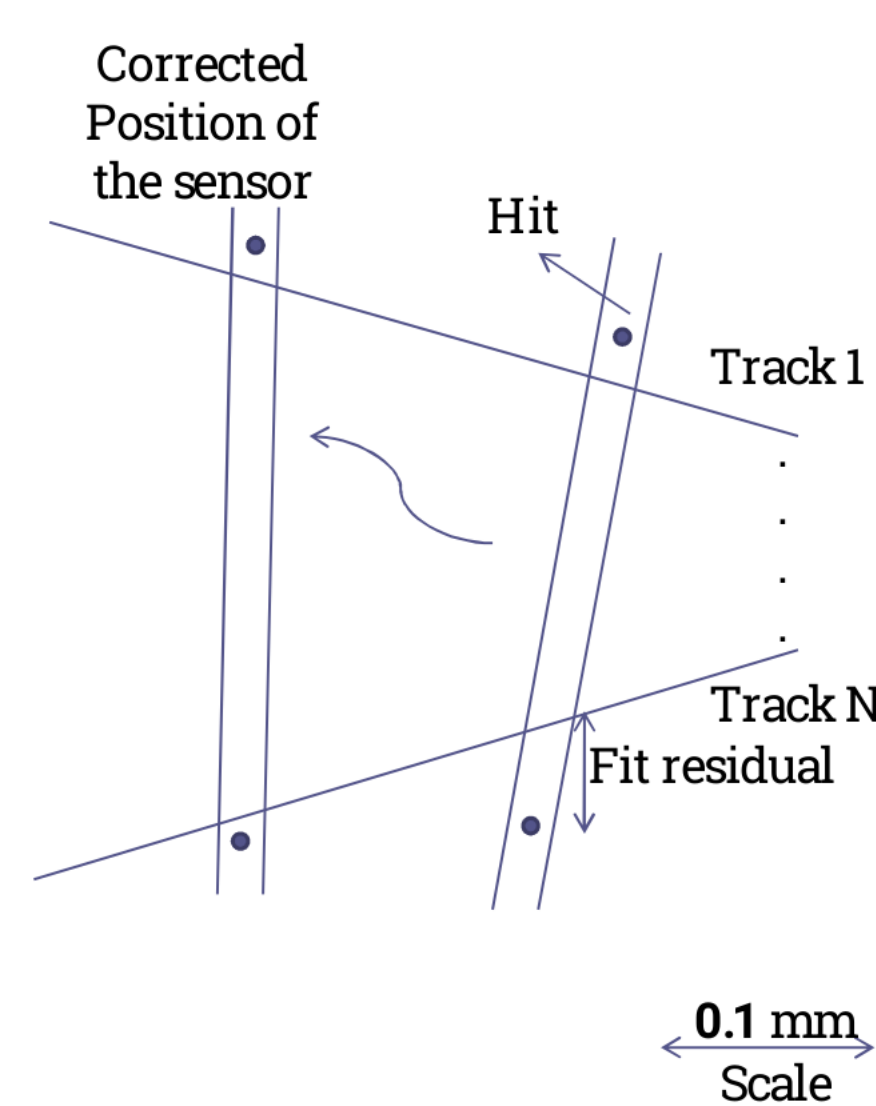


Fig. 2: Track Based Alignment

Theorem for Residual

$\varepsilon_{ij}(a, \tau_j) = m_i - f_i(a, \tau_j)$
 ε_{ij} = residual of i^{th} hit of j^{th} track
 m_i = measured hit positions w.r.t. detector module
 $f_i(a, \tau_j)$ = values obtained from track model
 a = alignment parameters
 τ_j = track parameters
 σ_i = measurement uncertainty
 $\chi^2(a, \tau) = \sum_{j \in \text{tracks}} \sum_{i \in \text{hits}} \frac{\varepsilon_{ij}^2(a, \tau_j)}{\sigma_i^2}$

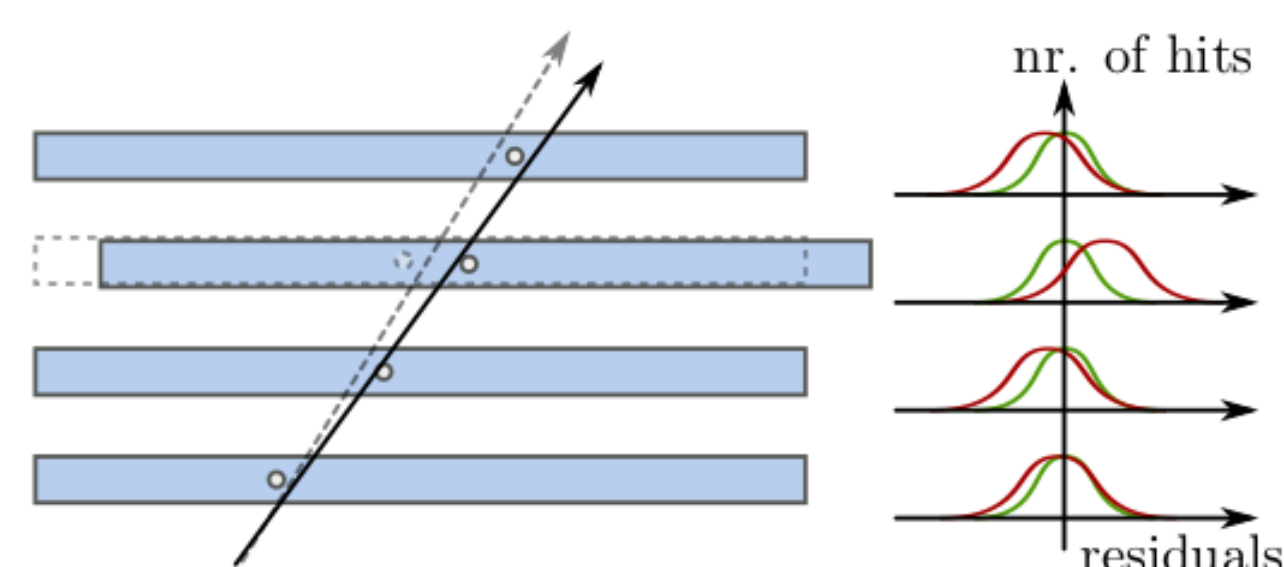


Fig. 3: Residual Distribution

- *the residual distribution to be minimized
- **MILLEPEDE package will come into play

Misalignment strategies

For this work three misalignment scenarios have been introduced in the STS geometry on hierarchical basis (i.e., to the sensors, ladders, stations). A Virtual technique has been used for misalignment, i.e., according to the misalignment scenarios, the transformations have been applied on the STS hits at the time of track reconstruction without modifying the ideal geometry (**Scenario_0**).

Misalignment Data Table

| Element | Sensor | Ladder | Station |
|----------|-------------------|--------------------|---------------------|
| X | $10\mu\text{m}$ | $50\mu\text{m}$ | $200\mu\text{m}$ |
| Y | $10\mu\text{m}$ | $50\mu\text{m}$ | $200\mu\text{m}$ |
| α | $50\mu\text{rad}$ | $250\mu\text{rad}$ | $1000\mu\text{rad}$ |
| β | $50\mu\text{rad}$ | $250\mu\text{rad}$ | $1000\mu\text{rad}$ |
| γ | $50\mu\text{rad}$ | $250\mu\text{rad}$ | $1000\mu\text{rad}$ |

Fig. 4: Transformation Data

All the data (as standard deviation) have been dived using Gaussian distribution to make the transformations random.

- On the first scenario (**Scenario_1**), transformed data have been applied at the local sensor level of ideal geometry (**Scenario_0**).
- On the second scenario (**Scenario_2**), in addition to the sensor level modifications, transformed data have been applied to the local ladder level.
- On the third scenario (**Scenario_3**), in addition to the last two scenarios, transformed data have been applied to the local station level.
- **Important assumption: Z-value** has been kept constant throughout, as the projection has always been taken to the X-Y plane.

Results

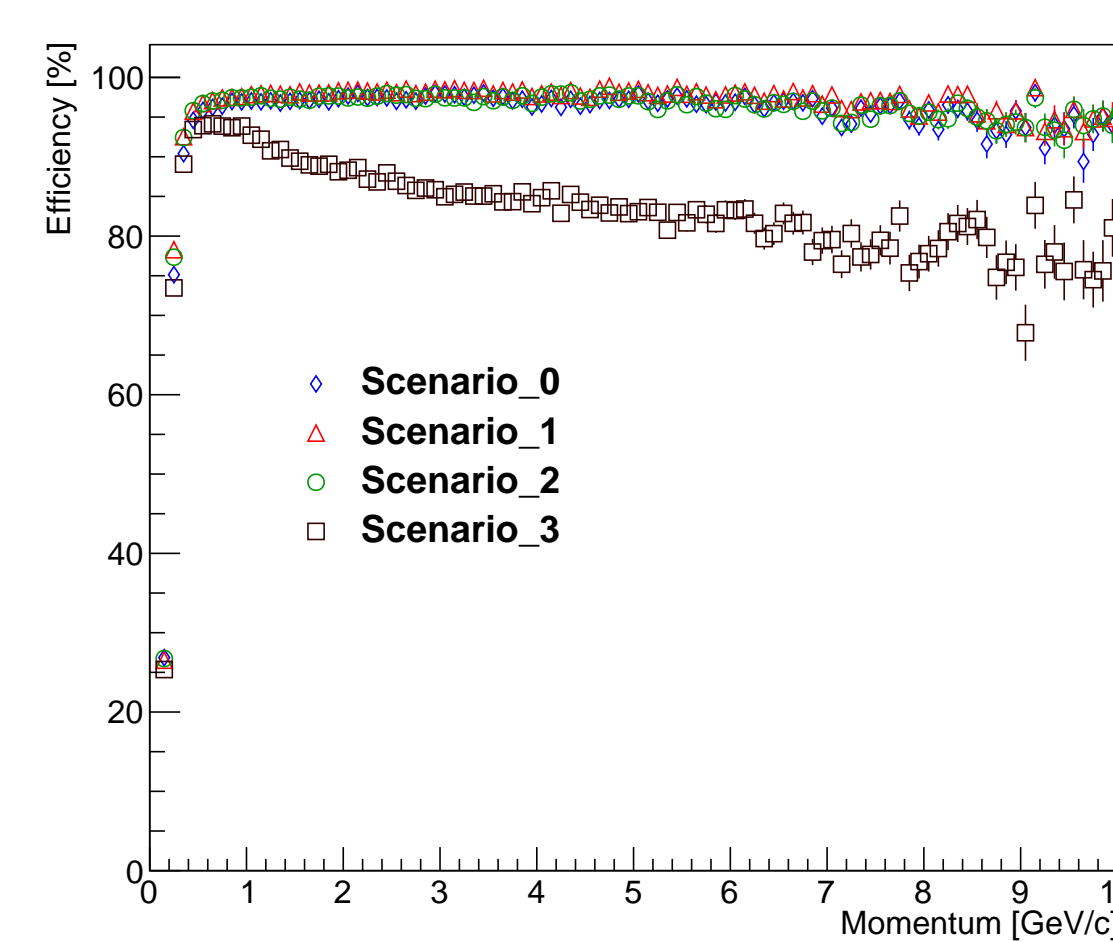


Fig. 5: Primary Track Efficiency vs. Momentum

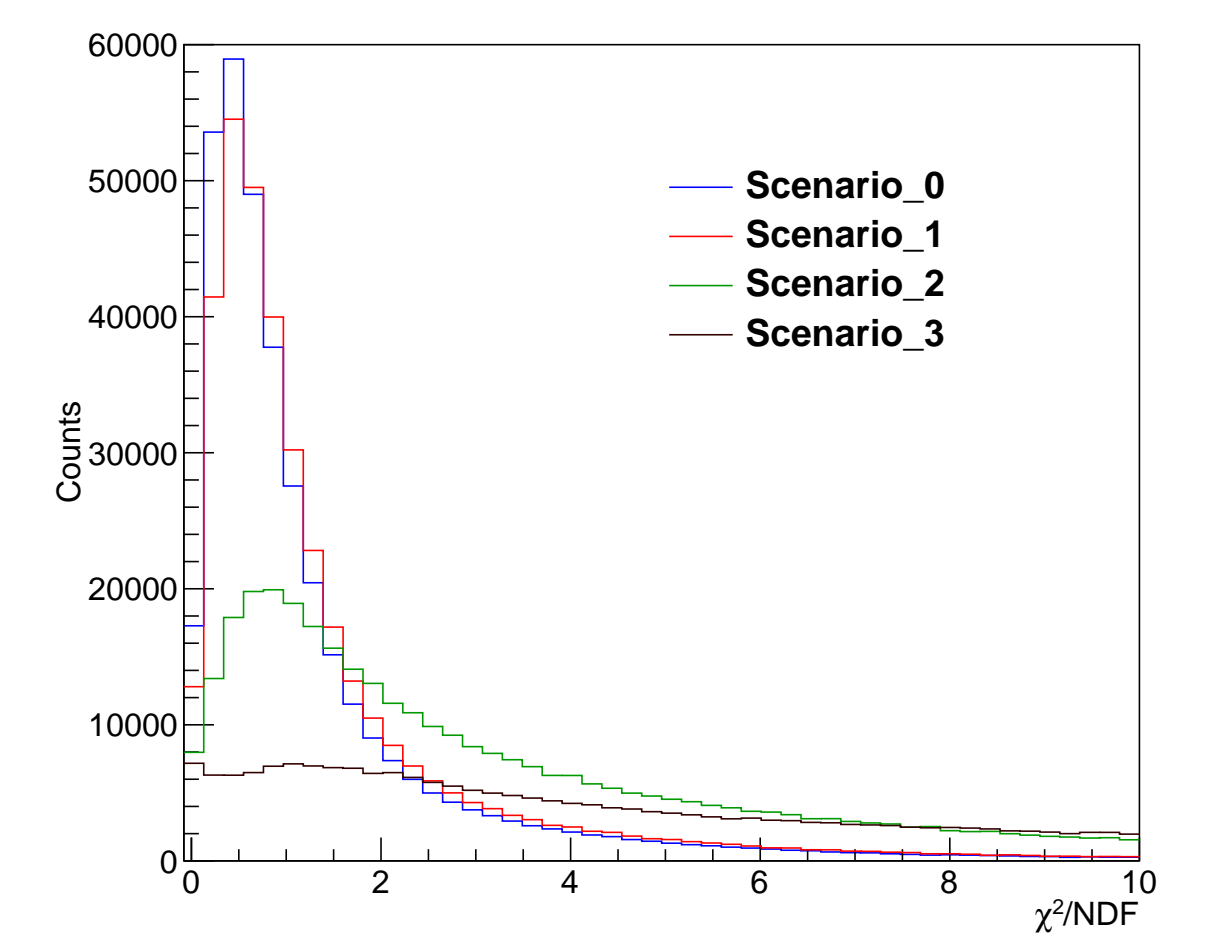


Fig. 7: Track Quality Evaluation in Terms of χ^2/NDF

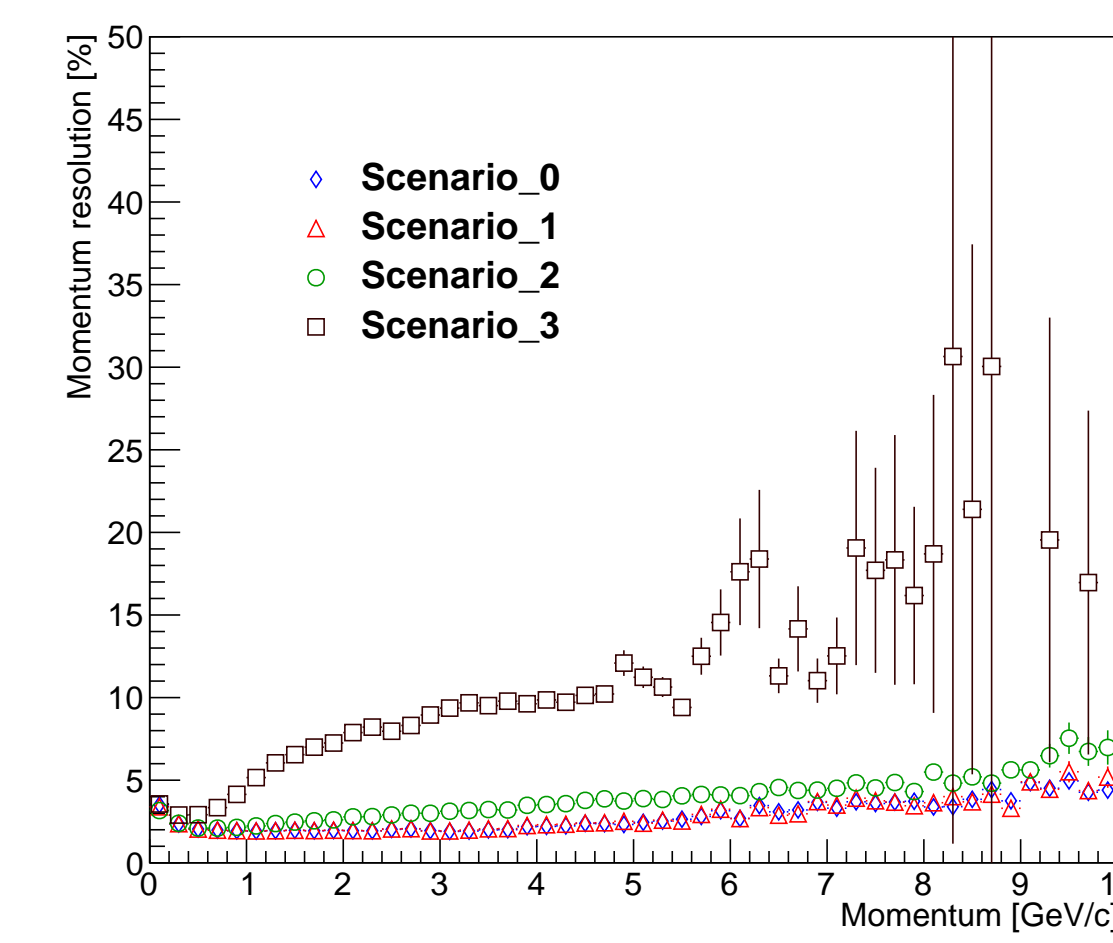


Fig. 6: Momentum Resolution vs. Momentum

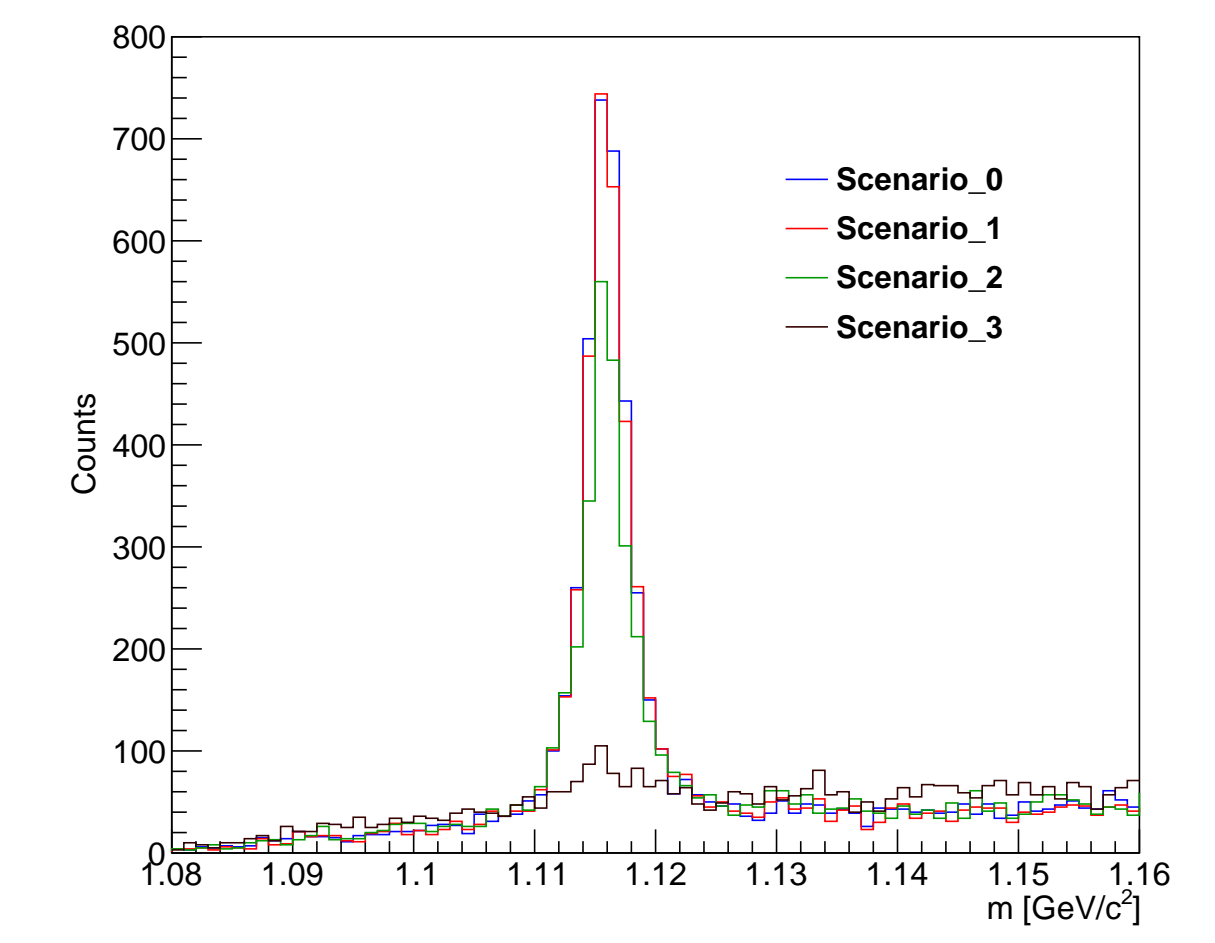


Fig. 8: Reconstructed mass of Λ as an Example

Conclusion

- So, this was the first successful attempt to apply the misalignment on the STS geometry. And there is a clear indication of deterioration of reconstructed track quality.
- Hit Residual calculation is still in progress and on the next step MILLEPEDE software package will be used to recover the misalignment. One Schematic work flow diagram is given below.

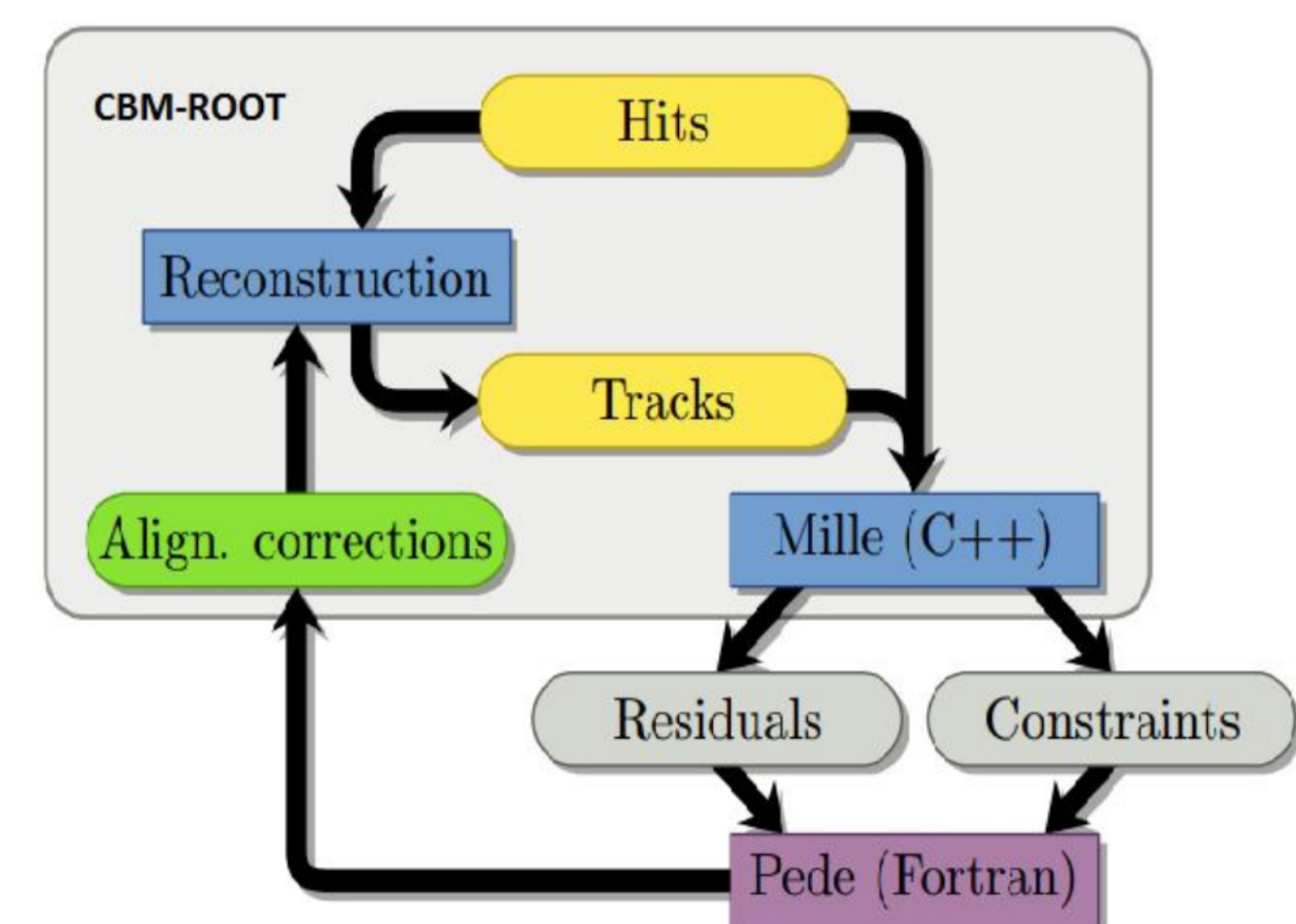


Fig. 9: Workflow Schematic Diagram

References

References

- [1] S. Das and H. R. Schmidt et al., CBM Progress Report, 2016
- [2] V. Blobel and C. Kleinwort, A New Method for the High-Precision Alignment of Track Detectors, 2002. arXiv:hep-ex/0208021.
- [3] V. Blobel. Millepede II. Institut für Experimentalphysik, Universität Hamburg, 2007. url: <http://www.desy.de/~blobel/mptalks.html>.
- [4] R. Frühwirth, Nucl. Instr. and Meth. A 262 (1987) 444
- [5] Impact of CMS silicon tracker misalignment on track and vertex reconstruction, Nucl. Instr. and Meth. A 566 (2006) 45-49
- [6] <http://aliceinfo.cern.ch/Offline/Activities/Alignment.html>