# Hit reconstruction in the CBM Silicon Tracking System

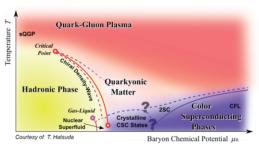
 $\underline{\mathsf{Hanna}}\ \mathsf{Malygina}^{123}$  for the CBM collaboration

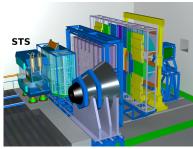
<sup>1</sup>Goethe University, Frankfurt; <sup>2</sup>KINR, Kyiv, Ukraine; <sup>3</sup>GSI, Darmstadt

MT student retreat, Darmstadt, January 2017



# Compressed Baryonic Matter experiment @ FAIR

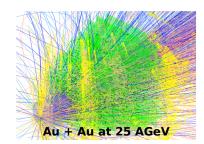




- QCD-diagram at moderate temperature and high baryonic density;
- extensive physical program: rare probes, complex trigger signatures:
  - high interaction rate:  $10^5..10^7$  interactions/s;
  - no hardware trigger;
- ightharpoonup Au + Au SIS100 SIS300: 2..45 AGeV.



# Silicon Tracking System (STS) – main tracking detector system

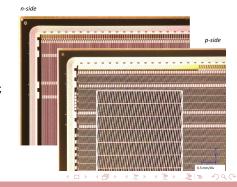


## Design:

- ▶ 8 tracking stations in a 1 T dipole magnet;
- b double-sided micro-strip Si sensor:  $\sim 300 \, \mu \mathrm{m}$  thickness,  $58 \, \mu \mathrm{m}$  strip pitch,  $7.5^{\circ}$  stereo-angle;
- ► radiation hard:  $10^{14} \, 1 \, \mathrm{MeV \, n_{eq}/cm^2}$ ;
- fast free-streaming read-out electronics out of the acceptance.

## Requirements:

- momentum resolution  $\lesssim 1.5\%$ ;
- high reconstruction efficiency;
- hit rates up to  $20\,\mathrm{MHz/cm^2}$ ;
- no hardware trigger.

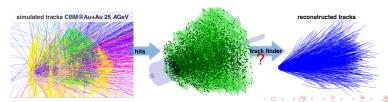


### Reconstruction chain

 Digitization: modelling the relevant processes from a particle track within a sensor up to a digital signal in each read-out channel (digi);

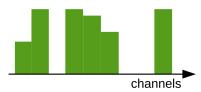
#### Reconstruction:

- 1. several (neighbouring) digis from one side of sensor combine to cluster;
- 2. combine 2 clusters from opposite sides of sensor to hit;
- 3. 4-8 hits from different layers of sensors (stations) combine to track.
- No hardware trigger → no events → time slices (~ 100..1000 events) → time coordinate for every stage time-based reconstruction;
- Do not store all data (1 TB/s) → software trigger: on-line event reconstruction and selection → fast algorithms.

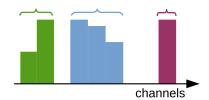


# Cluster finding

#### Fired channels:



#### Clusters:



- Neighbouring digis (which presumably originate from the same incident particle) combine to a cluster;
- Additionally, analyse time difference before adding a digi into the cluster;
- Estimate cluster centre using measured charges q<sub>i</sub>.

# Cluster position finding algorithm

## Centre-Of-Gravity algorithm (COG):

$$x_{\rm rec} = \frac{\Sigma x_i q_i}{\Sigma q_i} \\ x_i - \text{the coordinate of $i$th strip,} \\ q_i - \text{its charge,} \\ i = 1..n - \text{the strip index in the $n$-strip cluster.}$$

COG is biased:  $\langle x_{\text{true}} - x_{\text{rec}} \rangle \equiv \langle \Delta x \rangle \neq 0$  for  $n \geq 2$  at fixed  $q_2/q_1$ .

## An unbiased algorithm:

2-strip clusters:

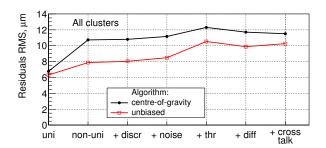
$$x_{\rm rec} = 0.5 (x_1 + x_2) + \frac{p}{3} \frac{q_2 - q_1}{\max(q_1, q_2)}, \quad p - \text{strip pitch};$$

*n*-strip clusters (Analog head-tail algorithm<sup>1</sup>):

$$x_{\text{rec}} = 0.5 (x_1 + x_n) + \frac{p}{2} \frac{\min(q_n, q) - \min(q_1, q)}{q}, \quad q = \frac{1}{n-2} \sum_{i=2}^{n-1} q_i$$

R. Turchetta, "Spatial resolution of silicon microstrip detectors", 1993  $_{<\Box}$   $_{>}$   $_{<\Box}$   $_{>}$   $_{<}$   $_{>}$   $_{$ 

# Residuals comparison for COG and the unbiased algorithms



500 minimum bias Au+Au events at 10 AGeV are simulated with the realistic STS geometry.

- Non-ideal effects make the performance comparable;
- The unbiased algorithm is faster and simplifies the hit position error estimation.



#### Hit reconstruction



- ▶ number of fakes can be estimated as:  $(n^2 n) \tan \alpha$ , where  $\alpha$  is stereo-angle between strips;
- smaller stereo-angle leads to worse spatial resolution;
- analysis of time difference between clusters allows to keep fake hits rate low for the time-based reconstruction.

	Event-based	Time-based
Efficiency	98 %	97 %
True hits	55 %	53 %

Event-based: minimum bias events Au+Au @ 25 GeV; Time-based: time slices of 10 μs, interaction rate 10 MHz.

# Hit position error: basic ideas

Why care: A reliable estimate of the hit position error  $\Rightarrow$ 

get proper track  $\chi^2 \Rightarrow$ 

discard ghost track candidates ⇒

improve the signal/background and keep the efficiency high.

**Method**: Calculations from first principles and independent of:

simulated residuals:

measured spatial resolution.

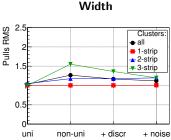
$$\sigma^2 = \sigma_{\rm alg}^2 + \sum_i \left(\frac{\partial x_{\rm rec}}{\partial q_i}\right)^2 \sum_{\rm sources} \sigma_j^2,$$

 $\sigma_{\rm alg}$  – an error of the cluster position finding algorithm;

 $\sigma_i$  – errors of the charge registration at one strip, among them already included:

- $\bullet$   $\sigma_{\text{noise}} = \text{Equivalent Noise Charge};$
- $\sigma_{\text{discr}} = \frac{\text{dynamic range}}{\sqrt{12} \text{ number of ADC}};$
- $\triangleright$   $\sigma_{\text{non-uni}}$ .

# Verification: hit pull distribution



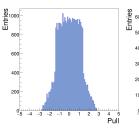
+ noise

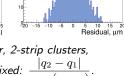
500 mbias events Au+Au @ 10 AGeV

$$ightharpoonup$$
 pull =  $\frac{\text{residual}}{\text{error}}$ ;

- pull distribution width must be  $\approx 1$ ;
- pull distribution shape must reproduce residual shape.

# Shape



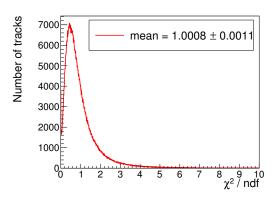


Ideal detector, 2-strip clusters, residuals at fixed:  $\frac{|q_2-q_1|}{\max(q_1,q_2)}$ 



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# Verification: track $\chi^2$ distribution



10 000 minimum bias events Au+Au @ 10 AGeV

•  $\chi^2$  distribution for tracks: mean value must be  $\approx 1$ .



# Summary

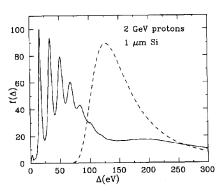
- Wide physical program of the CBM experiment: rare probs and complex trigger signatures
  - ▶ high interaction rate, no hardware trigger ⇒ free-streaming electronics and time-based reconstruction.
- Two cluster position finding algorithm were implemented for the STS: Centre-Of-Gravity and the unbiased. The last
  - gives similar residuals as the Centre-Of-Gravity algorithm;
  - simplifies position error estimation.
- Developed method of hit position error estimation yields correct errors, that was verified with:
  - hit pulls distribution (width and shape);
  - track  $\chi^2/\mathrm{ndf}$  distribution.
- Time-based reconstruction algorithms show sufficient reconstruction quality and time performance.



# Summary

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  - hit pulls distribution (width and shape);
  - track  $\chi^2/\mathrm{ndf}$  distribution.
- Time-based reconstruction algorithms show sufficient reconstruction quality and time performance.

- non-uniform energy loss in sensor: divide a track into small steps and simulate energy losses in each of them using Urban model<sup>1</sup>;
- drift of created charge carriers in planar electric field
- movement of e-h pairs in magnetic field (Lorentz shift)
- diffusion
- cross-talk due to interstrip capacitance
- modeling of the read-out chip

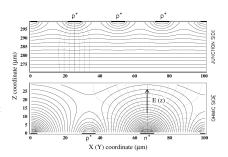


Energy losses of  $2 \, \mathrm{GeV}$  protons in  $1 \, \mu\mathrm{m}$  of Si (solid line) $^2$ .



<sup>&</sup>lt;sup>1</sup> K. Lassila-Perini and L. Urbán (1995)

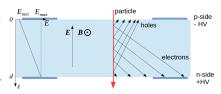
- non-uniform energy loss in sensor
- drift of created charge carriers in planar electric field: non-uniformity of the electric field is negligible in 90% of the volume;
- movement of e-h pairs in magnetic field (Lorentz shift)
- diffusion
- cross-talk due to interstrip capacitance
- modeling of the read-out chip



Calculated electric field for sensors with strip pitch  $25.5\,\mu\mathrm{m}$  on the p-side and  $66.5\,\mu\mathrm{m}$  on the n-side<sup>1</sup>.

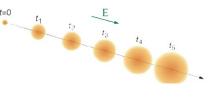
<sup>1</sup> S. Straulino et al. (2006)

- non-uniform energy loss in sensor
- drift of created charge carriers in planar electric field
- movement of e-h pairs in magnetic field (Lorentz shift): taking into account the fact that Lorentz shift depends on the mobility, which depends on the electric field, which depends on the z-coordinate of charge carrier;
- diffusion
- cross-talk due to interstrip capacitance
- modeling of the read-out chip



Lorentz shift for electrons and holes in Si sensor.

- non-uniform energy loss in sensor
- drift of created charge carriers in planar electric field
- movement of e-h pairs in magnetic field (Lorentz shift)
- diffusion: integration time is bigger than the drift time: estimate the increase of the charge carrier cloud during the whole drift time using Gaussian low;
- cross-talk due to interstrip capacitance
- modeling of the read-out chip

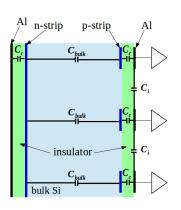


Increasing of charge cloud in time.

- non-uniform energy loss in sensor
- drift of created charge carriers in planar electric field
- movement of e-h pairs in magnetic field (Lorentz shift)
- diffusion
- cross-talk due to interstrip capacitance:

$$Q_{\text{neib strip}} = \frac{Q_{\text{strip}}C_{\text{i}}}{C_{\text{c}} + C_{\text{i}}};$$

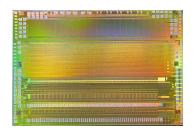
modeling of the read-out chip



Simplified double-sided silicon microstrip detector layout.



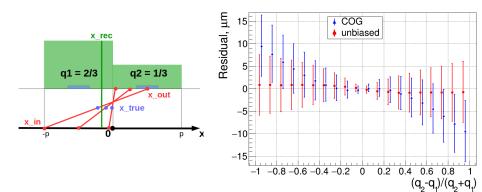
- non-uniform energy loss in sensor
- drift of created charge carriers in planar electric field
- movement of e-h pairs in magnetic field (Lorentz shift)
- diffusion
- cross-talk due to interstrip capacitance
- modeling of the read-out chip:
  - noise: + Gaussian noise to the signal in fired strip;
  - threshold;
  - digitization of analog signal;
  - time resolution:
  - dead time.



STS-XYTER read-out chip for the CBM Silicon Tracking System.



# Residuals comparison for 2 CPFAs: 2-strip clusters



Ideal detector model & uniform energy loss. Error bars: RMS of the residual distribution.

 $q_{1,2}$  – measured charges on the strips.

# Unbiased cluster position finding algorithm (CPFA), n-strip clusters

formula for unifrom energy loss:

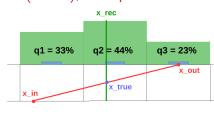
$$x_{\text{rec}} = 0.5 (x_1 + x_n) + \frac{p}{2} \frac{q_n - q_1}{q},$$

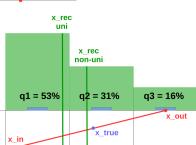
$$q = \frac{1}{n-2} \sum_{i=2}^{n-1} q_i;$$

formula for **non-uniform** energy loss (head-tail algorithm $^{1}$ ):

$$x_{\rm rec} = 0.5 \left( x_1 + x_n \right) + \frac{p}{2} \frac{\min(q_n, q) - \min(q_1, q)}{q},$$

 $^{1}\,$  R. Turchetta, "Spatial resolution of silicon microstrip detectors", 1993





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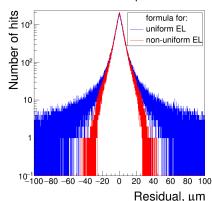
$$x_{\text{rec}} = 0.5 (x_1 + x_n) + \frac{p}{2} \frac{q_n - q_1}{q},$$
  
$$q = \frac{1}{n-2} \sum_{i=1}^{n-1} q_i;$$

formula for non-uniform energy loss (head-tail algorithm<sup>1</sup>):

$$x_{\text{rec}} = 0.5 (x_1 + x_n) + \frac{p}{2} \frac{\min(q_n, q) - \min(q_1, q)}{q},$$

 $^{1}\,$  R. Turchetta, "Spatial resolution of silicon microstrip detectors", 1993

#### Residuals for 3-strip clusters



# Estimation of hit position error

$$\mbox{Hit position error: } \sigma^2 = \sigma_{\rm alg}^2 + \sum_i \left( \frac{\partial x_{\rm rec}}{\partial q_i} \right)^2 \sum_{\rm sources} \sigma_j^2,$$

 $\sigma_{\rm alg}$  – an error of the unbiased CPFA:

$$\sigma_1 = \frac{p}{\sqrt{24}}, \qquad \sigma_2 = \frac{p}{\sqrt{72}} \frac{|q_2 - q_1|}{\max(q_1, q_2)}, \qquad \sigma_{n>2} = 0.$$

 $\sigma_i$  – errors of the charge registration at one strip, among them already included:

- $ightharpoonup \sigma_{\text{noise}} = \text{Equivalent Noise Charge};$
- $\sigma_{\text{discr}} = \frac{\text{dynamic range}}{\sqrt{12} \text{ number of ADC}};$
- $ightharpoonup \sigma_{
  m non-uni}$  is estimated assuming:
  - registered charge corresponds to the most probable value of the energy loss;
  - incident particle is ultrarelativistic ( $\beta \gamma \gtrsim 100$ ).
- $ightharpoonup \sigma_{\rm diff}$  is negligible in comparison with other effects.



# Error due to non-uniform energy loss

The contribution from the non-uniformity of energy loss is more difficult to take into account because the actual energy deposit along the track is not known. The following approximations allow a straightforward solution:

- the registered charge corresponds to the most probable value (MPV) of energy loss;
- the incident particle is ultrarelativistic ( $\beta \gamma \gtrsim 100$ ).

The second assumption is very strong but it uniquely relates the MPV and the distribution width (Particle Data Group)

$$MPV = \xi[eV] \times (\ln(1.057 \times 10^6 \xi[eV]) + 0.2).$$

Solving this with respect to  $\xi$  gives the estimate for the FWHM (S. Merolli, D. Passeri and L. Servoli, Journal of Instrumentation, Volume 6, 2011)

$$\sigma_{\rm non} = w/2 = 4.018\xi/2.$$



# 1-strip clusters: why not $\sigma_{method} = p/\sqrt{12}$ ?

In general, for all track inclinations:

$$N = \int_{x_{in}} \int_{x_{out}} P_1(x_{in}, x_{out}) dx_{in} dx_{out} = p^2;$$

Particullary, for **perpendicular** tracks:  $x_{in} = x_{out}$ 

$$N = \int_{x_{in}} P_1(x_{in}, x_{out}) dx_{in} = p;$$