Comparison of Symplectic PIC, Symplectic Gridless Particle, and Non-Symplectic PIC for Long Term Space-Charge Simulation

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# A Symplectic Multi-Particle Tracking Model (1)

A formal single step solution

$$\begin{aligned} \zeta(\tau) &= \exp(-\tau(:H:))\zeta(0) & H = H_1 + H_2 \\ \zeta(\tau) &= \exp(-\tau(:H_1:+:H_2:))\zeta(0) \\ &= \exp(-\frac{1}{2}\tau:H_1:)\exp(-\tau:H_2:)\exp(-\frac{1}{2}\tau:H_1:)\zeta(0) + O(\tau^3) \\ \zeta(\tau) &= \mathcal{M}(\tau)\zeta(0) \\ &= \mathcal{M}_1(\tau/2)\mathcal{M}_2(\tau)\mathcal{M}_1(\tau/2)\zeta(0) \end{aligned}$$

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J. Qiang, "A Symplectic Multi-Particle Tracking Model for Self-Consistent Space-Charge Simulation," Phys. Rev. ST Accel. Beams 20, 014203 (2017).

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# A Symplectic Multi-Particle Tracking Model (2)

2<sup>nd</sup> order:

$$\begin{aligned} \zeta(\tau) &= \mathcal{M}(\tau)\zeta(0) \\ &= \mathcal{M}_1(\tau/2)\mathcal{M}_2(\tau)\mathcal{M}_1(\tau/2)\zeta(0) \end{aligned}$$

4<sup>th</sup> order

rder: 
$$\mathcal{M}(\tau) = \mathcal{M}_1(\frac{s}{2})\mathcal{M}_2(s)\mathcal{M}_1(\frac{\alpha s}{2})\mathcal{M}_2((\alpha - 1)s)\mathcal{M}_1(\frac{\alpha s}{2})\mathcal{M}_2(s)\mathcal{M}_1(\frac{s}{2})$$
  
where  $\alpha = 1 - 2^{1/3}$ , and  $s = \tau/(1 + \alpha)$ 

higher order: 
$$\mathcal{M}_{2n+2}(\tau) = \mathcal{M}_{2n}(z_0\tau)\mathcal{M}_{2n}(z_1\tau)\mathcal{M}_{2n}(z_0\tau)$$

where  $z_0 = 1/(2 - 2^{1/(2n+1)})$  and  $z_1 = -2^{1/(2n+1)}/(2 - 2^{1/(2n+1)})$ Symplectic condition:  $M_i^T J M_i = J$  M is the Jacobi Matrix of  $\mathcal{M}$ 

where J denotes the  $6N \times 6N$  matrix given by

$$J = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix} \text{ and } I \text{ is the } 3N \times 3N \text{ identity matrix}$$

Refs: E. Forest and R. D. Ruth, Physica D **43**, p. **105**, **1990**. H. Yoshida, Phys. Lett. A **150**, p. **262**, **1990**.









# A Symplectic Multi-Particle Tracking Model (3)

$$H_1 = \sum_i \mathbf{p}_i^2 / 2 + \sum_i q \psi(\mathbf{r}_i) \longrightarrow \mathcal{M}_i$$

• symplectic map for  $H_1$  can be found from charged particle optics method

$$H_{2} = \frac{1}{2} \sum_{i} \sum_{j} q\phi(\mathbf{r}_{i}, \mathbf{r}_{j}) \longrightarrow M_{2}$$
  

$$\mathbf{r}_{i}(\tau) = \mathbf{r}_{i}(0)$$
  

$$\mathbf{p}_{i}(\tau) = \mathbf{p}_{i}(0) - \frac{\partial H_{2}(\mathbf{r})}{\partial \mathbf{r}_{i}} \tau$$
  

$$M_{2} = \begin{pmatrix} I & 0 \\ L & I \end{pmatrix} \text{ To satisfy the symplectic condition: } L = L^{T}$$
  

$$L_{ij} = \partial \mathbf{p}_{i}(\tau) / \partial \mathbf{r}_{j} = -\frac{\partial^{2} H_{2}(\mathbf{r})}{\partial \mathbf{r}_{i} \partial \mathbf{r}_{j}} \tau$$

 $M_2$  will be symplectic if  $p_i$  is updated from  $H_2$  analytically







# Self-Consistent Space-Charge Transfer Map (1)

$$\phi(x = 0, y) = 0$$

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = -\frac{\rho}{\epsilon_0} \qquad \phi(x = a, y) = 0$$

$$\phi(x, y = 0) = 0$$

$$\phi(x, y = b) = 0$$

$$\rho(x, y) = \sum_{l=1}^{N_l} \sum_{m=1}^{N_m} \rho^{lm} \sin(\alpha_l x) \sin(\beta_m y)$$

$$\phi(x, y) = \sum_{l=1}^{N_l} \sum_{m=1}^{N_m} \phi^{lm} \sin(\alpha_l x) \sin(\beta_m y)$$

$$\rho^{lm} = \frac{4}{ab} \int_0^a \int_0^b \rho(x, y) \sin(\alpha_l x) \sin(\beta_m y) dxdy$$

$$\phi^{lm} = \frac{4}{ab} \int_0^a \int_0^b \phi(x, y) \sin(\alpha_l x) \sin(\beta_m y) dxdy$$
where  $\alpha_l = l\pi/a$  and  $\beta_m = m\pi/b$ 

$$\phi^{lm} = \frac{\rho^{lm}}{\epsilon_0 \gamma_{lm}^2}$$
where  $\gamma_{lm}^2 = \alpha_l^2 + \beta_m^2$ 





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# Self-Consistent Space-Charge Transfer Map (2)

$$\rho(x,y) = \frac{1}{N_p} \sum_{j=1}^{N_p} S(x-x_j) S(y-y_j)$$

$$\phi^{lm} = \frac{4\pi}{\gamma_{lm}^2} \frac{4}{ab} \frac{1}{N_p} \sum_{j=1}^{N_p} \int_0^a \int_0^b S(x - x_j) S(y - y_j) \sin(\alpha_l x) \sin(\beta_m y) dx dy$$

$$\phi(x,y) = 4\pi \frac{4}{ab} \frac{1}{N_p} \sum_{j=1}^{N_p} \sum_{l=1}^{N_l} \sum_{m=1}^{N_m} \frac{1}{\gamma_{lm}^2} \sin(\alpha_l x) \sin(\beta_m y) \int_0^a \int_0^b S(x-x_j) S(y-y_j) \sin(\alpha_l x) \sin(\beta_m y) dxdy$$

$$\phi(x_i, y_i) = \int_0^a \int_0^b \phi(x, y) S(x - x_i) S(y - y_i) dx dy$$

$$\varphi(x_i, y_i, x_j, y_j) = 4\pi \frac{4}{ab} \frac{1}{N_p} \sum_{l=1}^{N_l} \sum_{m=1}^{N_m} \frac{1}{\gamma_{lm}^2} \int_0^a \int_0^b S(x - x_j) S(y - y_j) \sin(\alpha_l x) \sin(\beta_m y) dx dy$$
$$\int_0^a \int_0^b S(x - x_i) S(y - y_i) \sin(\alpha_l x) \sin(\beta_m y) dx dy$$





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## Self-Consistent Space-Charge Transfer Map (3)

$$H_{2} = 4\pi \frac{K}{2} \frac{4}{ab} \frac{1}{N_{p}} \sum_{i=1}^{N_{p}} \sum_{j=1}^{N_{p}} \sum_{l=1}^{N_{p}} \sum_{m=1}^{N_{m}} \frac{1}{\gamma_{lm}^{2}}$$
$$\int_{0}^{a} \int_{0}^{b} S(x - x_{j}) S(y - y_{j}) \sin(\alpha_{l}x) \sin(\beta_{m}y) dx dy \int_{0}^{a} \int_{0}^{b} S(x - x_{i}) S(y - y_{i}) \sin(\alpha_{l}x) \sin(\beta_{m}y) dx dy$$





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## **Symplectic Gridless Particle Model**

$$\rho(x,y) = \sum_{j=1}^{N_p} w \delta(x-x_j) \delta(y-y_j)$$
w is the particle charge weight
$$H_2 = \frac{1}{2\epsilon_0} \frac{4}{ab} w \sum_i \sum_j \sum_l \sum_m \frac{1}{\gamma_{lm}^2} \sin(\alpha_l x_j) \sin(\beta_m y_j) \sin(\beta_m y_j) \sin(\alpha_l x_i) \sin(\beta_m y_i)$$

$$p_{xi}(\tau) = p_{xi}(0) - \tau \frac{1}{\epsilon_0} \frac{4}{ab} w \sum_j \sum_l \sum_m \frac{\alpha_l}{\gamma_{lm}^2} \sin(\alpha_l x_j) \sin(\alpha_l x_j) \sin(\alpha_l x_j) \sin(\beta_m y_j) \cos(\alpha_l x_i) \sin(\beta_m y_i)$$

$$p_{yi}(\tau) = p_{yi}(0) - \tau \frac{1}{\epsilon_0} \frac{4}{ab} w \sum_j \sum_l \sum_m \frac{\beta_m}{\gamma_{lm}^2} \sin(\alpha_l x_j) \sin(\alpha_l x_j) \sin(\alpha_l x_j) \cos(\beta_m y_i)$$

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# Symplectic PIC Model (1)

$$p_{xi}(\tau) = p_{xi}(0) - \tau 4\pi K \frac{4}{ab} \frac{1}{N_p} \sum_{j=1}^{N_p} \sum_{l=1}^{N_l} \sum_{m=1}^{N_m} \frac{1}{\gamma_{lm}^2} \int_0^a \int_0^b S(x - x_j) S(y - y_j) \sin(\alpha_l x) \sin(\beta_m y) dx dy$$
$$\int_0^a \int_0^b \frac{\partial S(x - x_i)}{\partial x_i} S(y - y_i) \sin(\alpha_l x) \sin(\beta_m y) dx dy$$

$$p_{yi}(\tau) = p_{yi}(0) - \tau 4\pi K \frac{4}{ab} \frac{1}{N_p} \sum_{j=1}^{N_p} \sum_{l=1}^{N_l} \sum_{m=1}^{N_m} \frac{1}{\gamma_{lm}^2} \int_0^a \int_0^b S(x - x_j) S(y - y_j) \sin(\alpha_l x) \sin(\beta_m y) dx dy$$

$$\int_0^a \int_0^b S(x - y_j) \sin(\alpha_l x) \sin(\beta_m y) dx dy$$

$$\int_0^{\infty} \int_0^{\infty} S(x - x_i) \frac{\partial S(y - y_i)}{\partial y_i} \sin(\alpha_l x) \sin(\beta_m y) dx dy$$

$$p_{xi}(\tau) = p_{xi}(0) - \tau 4\pi K \frac{4}{ab} \frac{1}{N_p} \sum_{j=1}^{N_p} \sum_{l=1}^{N_h} \sum_{m=1}^{N_m} \frac{1}{\gamma_{lm}^2} \sum_{I'} \sum_{J'} S(x_{I'} - x_j) S(y_{J'} - y_j) \sin(\alpha_l x_{I'}) \sin(\beta_m y_{J'})$$

$$\sum_I \sum_J \frac{\partial S(x_I - x_i)}{\partial x_i} S(y_J - y_i) \sin(\alpha_l x_I) \sin(\beta_m y_J)$$

$$p_{yi}(\tau) = p_{yi}(0) - \tau 4\pi K \frac{4}{ab} \frac{1}{N_p} \sum_{j=1}^{N_p} \sum_{l=1}^{N_h} \sum_{m=1}^{N_m} \frac{1}{\gamma_{lm}^2} \sum_{I'} \sum_{J'} S(x_{I'} - x_j) S(y_{J'} - y_j) \sin(\alpha_l x_{I'}) \sin(\beta_m y_{J'})$$

$$\sum_I \sum_J S(x_I - x_i) \frac{\partial S(y_I - y_i)}{\partial y_i} \sin(\alpha_l x_I) \sin(\beta_m y_J)$$

# Symplectic PIC Model (2)

$$\rho(x_{I'}, y_{J'}) = \frac{1}{N_p} \sum_{j=1}^{N_p} S(x_{I'} - x_j) S(y_{J'} - y_j),$$

$$p_{xi}(\tau) = p_{xi}(0) - \tau 4\pi K \sum_{I} \sum_{J} \frac{\partial S(x_{I} - x_{i})}{\partial x_{i}} S(y_{J} - y_{i}) \left[\frac{4}{ab} \sum_{l=1}^{N_{l}} \sum_{m=1}^{N_{m}} \frac{1}{\gamma_{lm}^{2}} \right]$$
$$\sum_{I'} \sum_{J'} \rho(x_{I'}, y_{J'}) \sin(\alpha_{l} x_{I'}) \sin(\beta_{m} y_{J'}) \sin(\alpha_{l} x_{I}) \sin(\beta_{m} y_{J}) \left[\frac{4}{ab} \sum_{l=1}^{N_{l}} \sum_{m=1}^{N_{m}} \frac{1}{\gamma_{lm}^{2}} \right]$$
$$p_{yi}(\tau) = p_{yi}(0) - \tau 4\pi K \sum_{I} \sum_{J} S(x_{I} - x_{i}) \frac{\partial S(y_{I} - y_{i})}{\partial y_{i}} \left[\frac{4}{ab} \sum_{l=1}^{N_{l}} \sum_{m=1}^{N_{m}} \frac{1}{\gamma_{lm}^{2}} \right]$$
$$\sum_{I'} \sum_{J'} \rho(x_{I'}, y_{J'}) \sin(\alpha_{l} x_{I'}) \sin(\beta_{m} y_{J'}) \sin(\alpha_{l} x_{I}) \sin(\beta_{m} y_{J})$$







# Symplectic PIC Model (3)

$$\begin{split} \phi(x_{I}, y_{J}) &= \frac{4}{ab} \sum_{l=1}^{N_{l}} \sum_{m=1}^{N_{m}} \frac{1}{\gamma_{lm}^{2}} \sum_{I'} \sum_{J'} \rho(x_{I'}, y_{J'}) \sin(\alpha_{l} x_{I'}) \sin(\beta_{m} y_{J'}) \sin(\alpha_{l} x_{I}) \sin(\alpha_{l} x_{I}) \sin(\beta_{m} y_{J}) \\ \mathbf{M}_{2} \longrightarrow \begin{bmatrix} p_{xi}(\tau) &= p_{xi}(0) - \tau 4\pi K \sum_{I} \sum_{J} \frac{\partial S(x_{I} - x_{i})}{\partial x_{i}} S(y_{J} - y_{i}) \phi(x_{I}, y_{J}) \\ p_{yi}(\tau) &= p_{yi}(0) - \tau 4\pi K \sum_{I} \sum_{J} S(x_{I} - x_{i}) \frac{\partial S(y_{J} - y_{i})}{\partial y_{i}} \phi(x_{I}, y_{J}) \\ S(x_{I} - x_{i}) &= \frac{1}{h} \begin{cases} \frac{3}{4} - \frac{(x_{i} - x_{I})^{2}}{h} S(x_{I} - x_{i}) \frac{\partial S(y_{J} - y_{i})}{\partial y_{i}} \phi(x_{I}, y_{J}) \\ \frac{1}{2} (\frac{3}{2} - \frac{|x_{i} - x_{I}|}{h})^{2}, & h/2 < |x_{i} - x_{I}| \le h/2 \\ 0 & \text{otherwise} \end{cases} \\ \frac{\partial S(x_{I} - x_{i})}{\partial x_{i}} &= \begin{cases} -2(\frac{x_{i} - x_{I}}{h})/h, & |x_{i} - x_{I}| \le h/2 \\ (-\frac{3}{2} + \frac{(x_{i} - x_{I})}{h})/h, & h/2 < |x_{i} - x_{I}| \le 3/2h, & x_{i} > x_{I} \\ (\frac{3}{2} + \frac{(x_{i} - x_{I})}{h})/h, & h/2 < |x_{i} - x_{I}| \le 3/2h, & x_{i} \le x_{I} \\ 0 & \text{otherwise} \end{cases} \end{split}$$



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## **Non-Symplectic PIC Model**

$$\begin{aligned} \frac{d\mathbf{r}_i}{ds} &= \mathbf{p}_i \\ \frac{d\mathbf{p}_i}{ds} &= q(\mathbf{E}_i/v_0 - a_z \times \mathbf{B}_i) \\ \mathbf{r}(\tau/2)_i &= \mathbf{r}(0)_i + \frac{1}{2}\tau\mathbf{p}_i(0) \\ E_x(x_I, y_J) &= -\sum_{l=1}^{N_l} \sum_{m=1}^{N_m} \alpha_l \phi^{lm} \cos(\alpha_l x) \sin(\beta_m y) \\ E_y(x_I, y_J) &= -\sum_{l=1}^{N_l} \sum_{m=1}^{N_m} \beta_m \phi^{lm} \sin(\alpha_l x) \cos(\beta_m y) \\ p_{xi}(\tau) &= p_{xi}(0) + \tau(\frac{qE_x^{ext}}{v_0} - qB_y^{ext}) + \tau 4\pi K \sum_I \sum_J S(x_I - x_i)S(y_J - y_i)E_x(x_I, y_J) \\ p_{yi}(\tau) &= p_{yi}(0) + \tau(\frac{qE_y^{ext}}{v_0} + qB_x^{ext}) + \tau 4\pi K \sum_I \sum_J S(x_I - x_i)S(y_J - y_i)E_y(x_I, y_J) \\ \mathbf{r}(\tau)_i &= \mathbf{r}(\tau/2)_i + \frac{1}{2}\tau\mathbf{p}_i(\tau) \end{aligned}$$



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# Benchmark Case 1: FODO Lattice, Below 2<sup>nd</sup> Order Envelop Instability

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- 1 GeV proton beam
- FODO lattice
- 0 current phase advance: 85 degrees
- Initial 4D Gaussian distribution

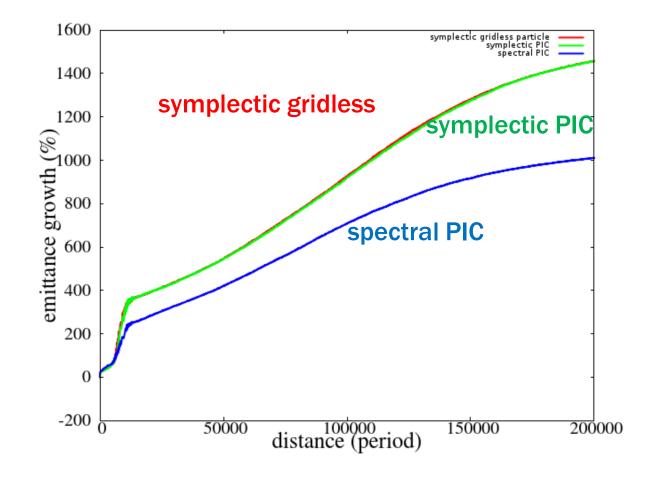








Significant Difference in Final 4D Emittances Between the Symplectic and the Non-Symplectic Methods (Strong Space-Charge: Phase Advance Change 85 -> 42)



#### Two symplectic approaches show good agreement.

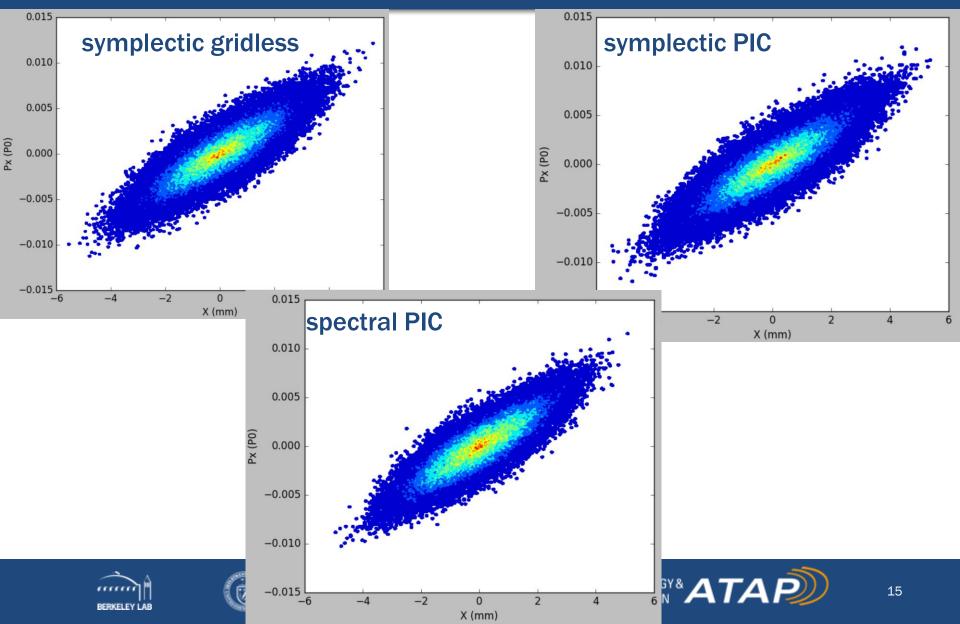




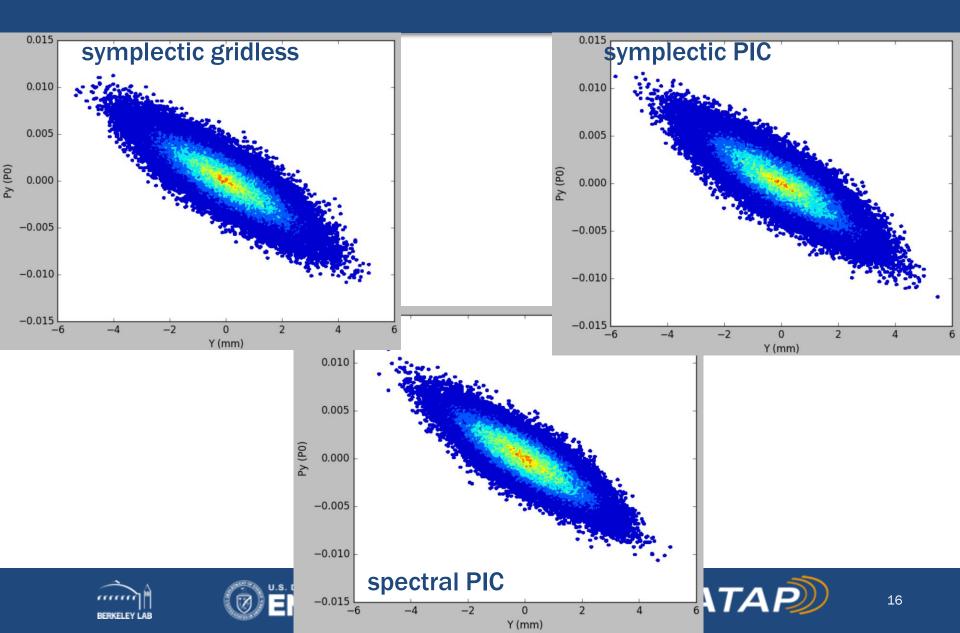
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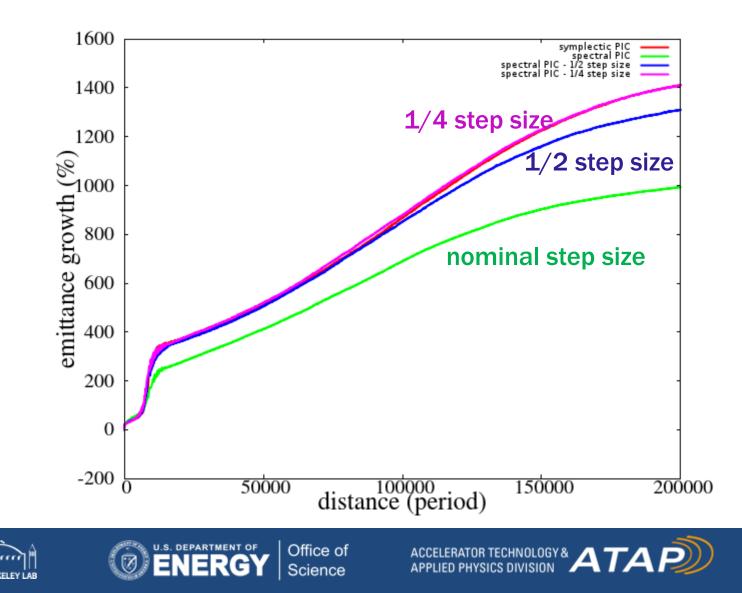
# Final Beam X-Px Phase Spaces Have Similar Shapes Non-Symplectic Model Has Smaller Area



### **Final Y-Py Phase Space Show Similar Shapes**

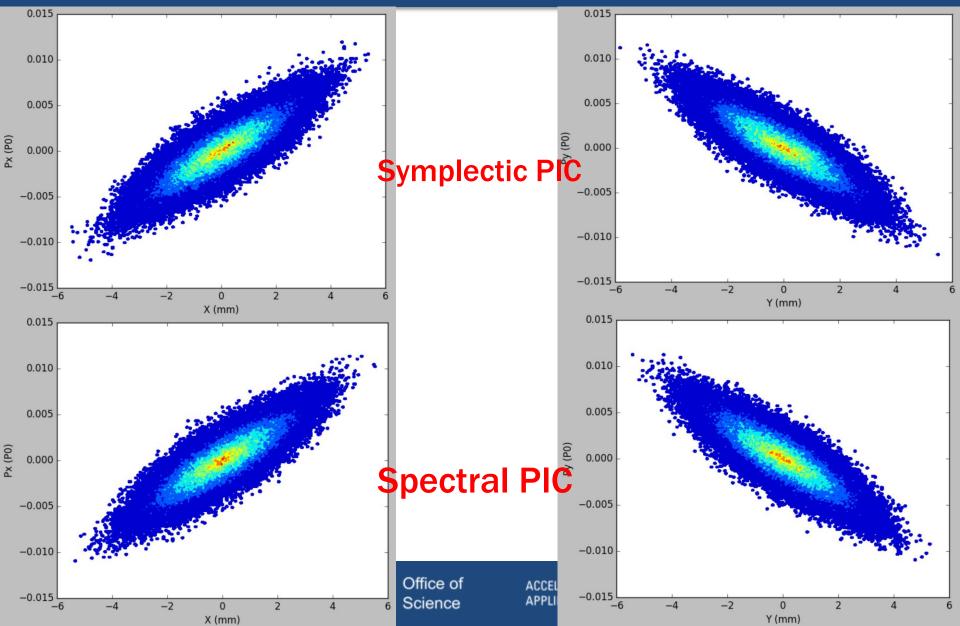


# Finer Step Size Needed for Non-Symplectic PIC (Symplectic PIC vs. Non-Symplectic PIC)



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# Final Transverse Phase Space: Symplectic PIC vs. Spectral PIC



## Benchmark Case 2: 1 Turn = 10 FODOs + 1 Sextupole

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- 0 current tune 2.417
- sextupole KL = 10 T/m/m



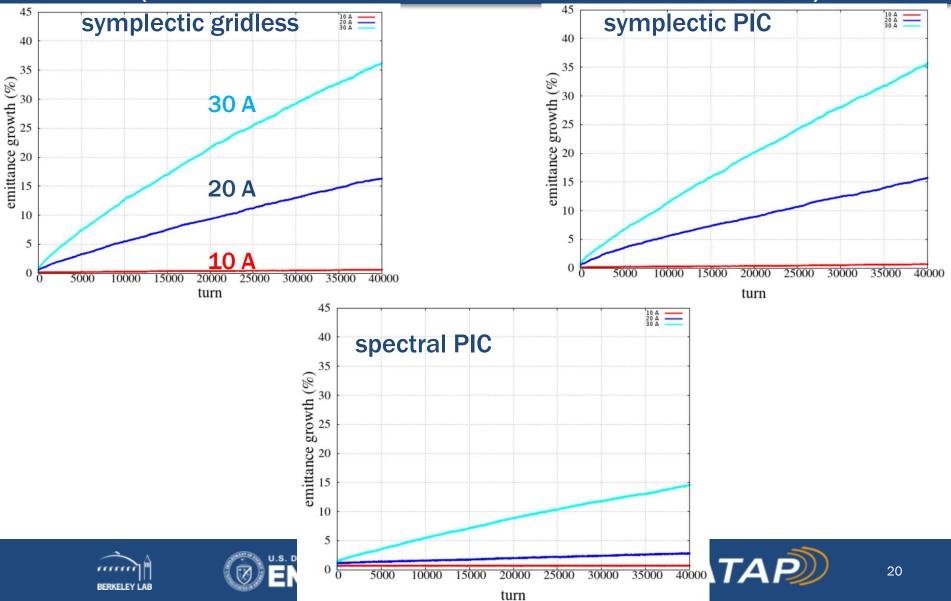




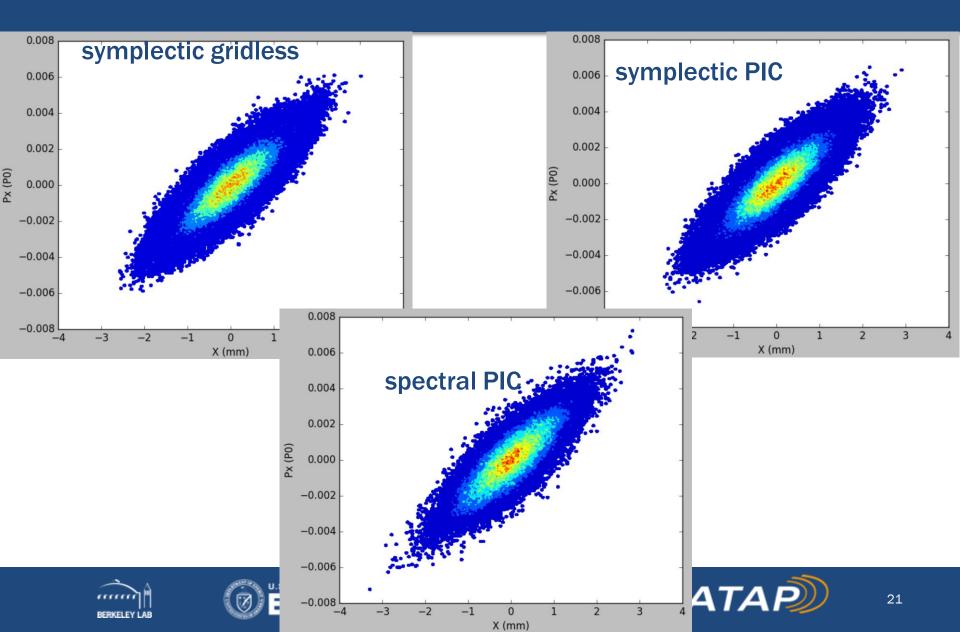




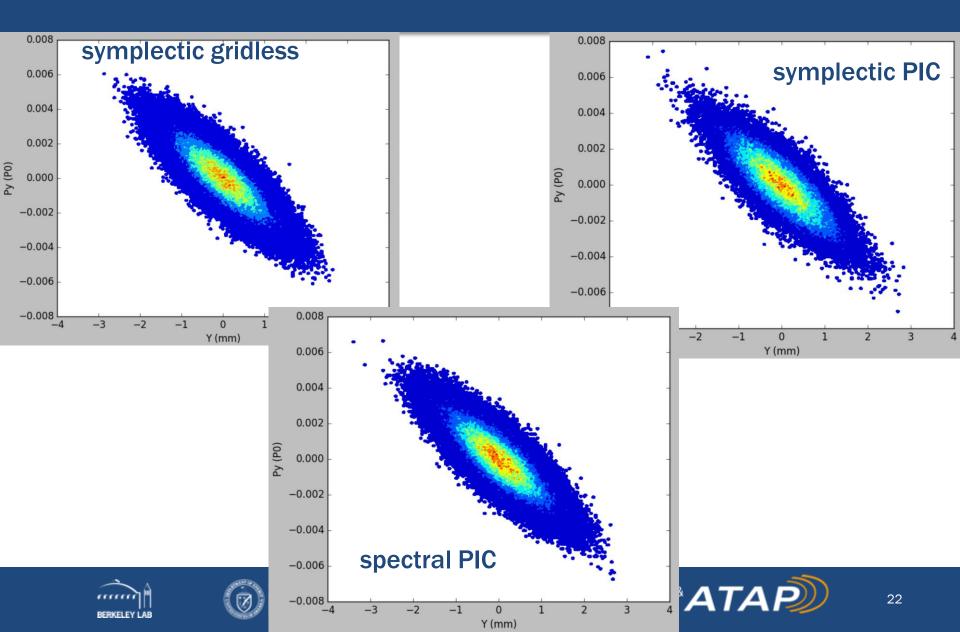
## Non-Symplectic PIC Shows Much Less Emittance Growth Compared with Two Symplectic Models (4D Emittance Evolution with Different Currents)



### Final Beam X-Px Phase Spaces Have Similar Shapes

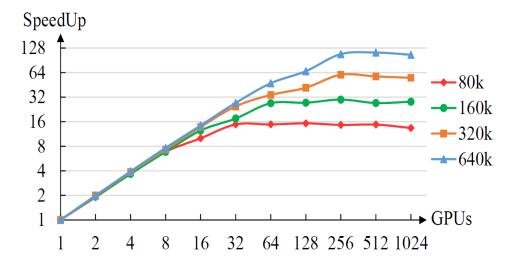


## Final Beam Y-Py Phase Spaces Have Similar Shapes



# **Computational Complexity**

- Symplectic PIC/Spetral PIC: O(Np) + O(Ng log(Ng)), parallelization can be a challenge
- Symplectic gridless particle: O(Nm Np), easy parallelization



Z. Liu and J. Qiang, "Symplectic multi-particle tracking on GPUs," submitted to Computer Physics Communications, 1997.





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# Summary

- Using the same step size, same number of modes, with sufficient grid points, the symplectic PIC and the symplectic gridless particle model agree with each other very well.
- Using same step size, the non-symplectic PIC yields significantly different emittance growth.
- All three models show similar final phase space shapes.
- Using sufficient small step size, all three methods converge to the similar emittance growth (Is this too optimistic?)
- For small number of modes and particles used, the symplectic gridless particle model can be computationally efficient; otherwise, the symplectic PIC model would be more efficient.

# Thank You!





