



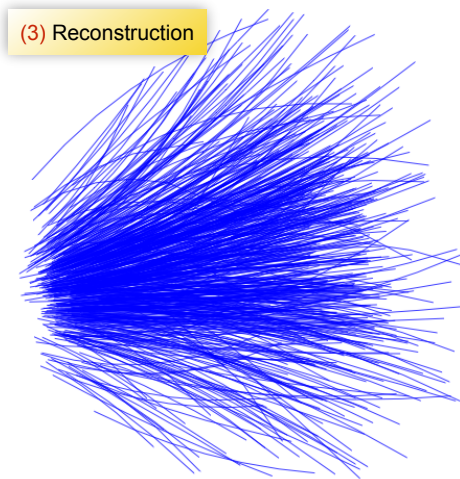
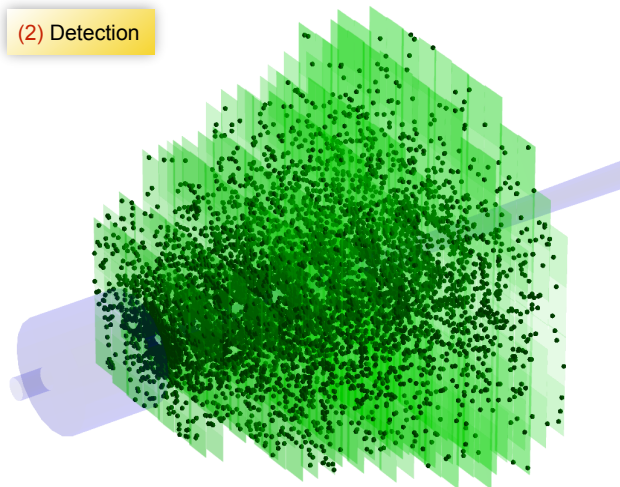
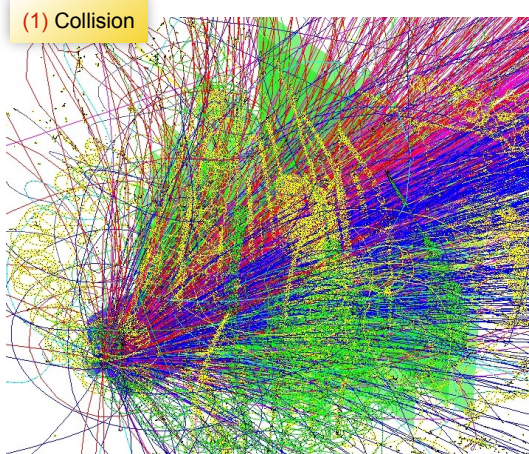
# Event Reconstruction on Many-Core Computer Architectures (CBM Experiment at FAIR)

XIIth Quark Confinement and the Hadron Spectrum

Ivan Kisel

Goethe-University Frankfurt am Main  
FIAS Frankfurt Institute for Advanced Studies  
GSI Helmholtz Center for Heavy Ion Research

# Reconstruction Challenge in CBM at FAIR/GSI

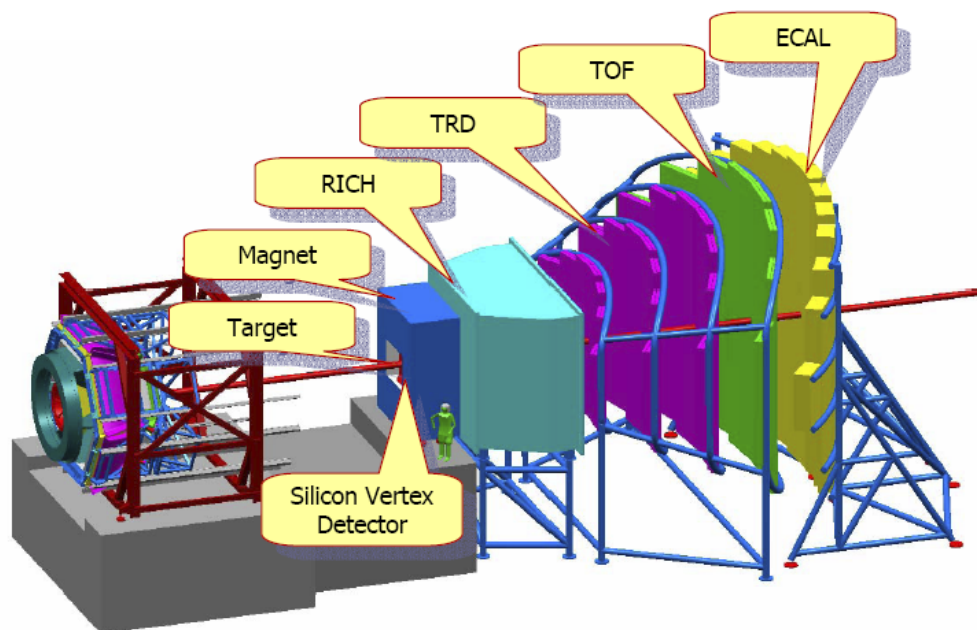


- Future **fixed-target heavy-ion** experiment
- $10^7$  Au+Au collisions/sec
- $\sim 1000$  charged **particles/collision**
- **Non-homogeneous** magnetic field
- **Double-sided strip detectors** (85% fake space-points)

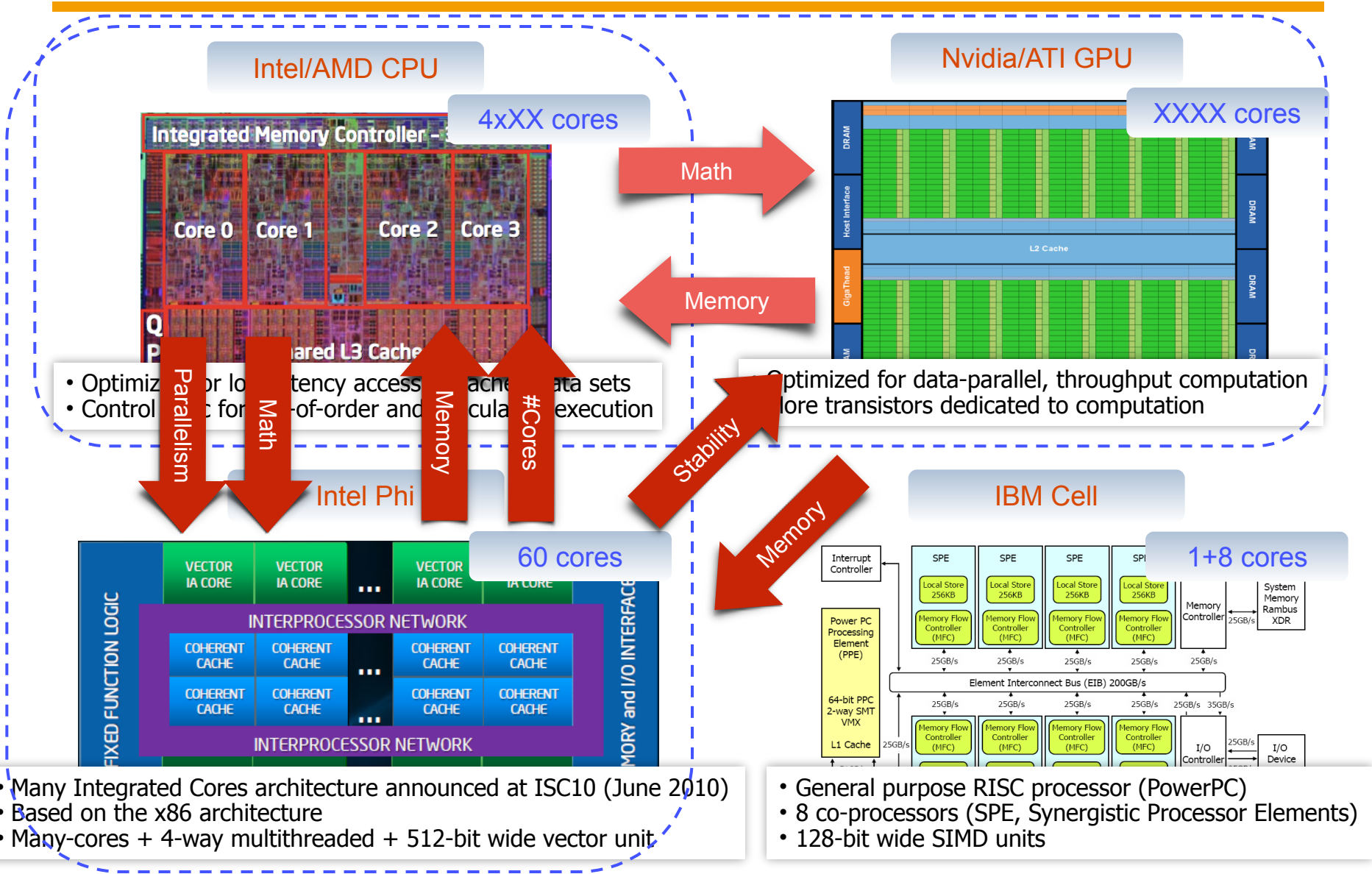
Full event reconstruction will be done **on-line** at the First-Level Event Selection (**FLES**) and **off-line** using the same **FLES** reconstruction package.

Cellular Automaton (CA) Track Finder  
Kalman Filter (KF) Track Fitter  
KF short-lived Particle Finder

All reconstruction algorithms are **vectorized** and **parallelized**.



# Many-Core CPU/GPU Architectures

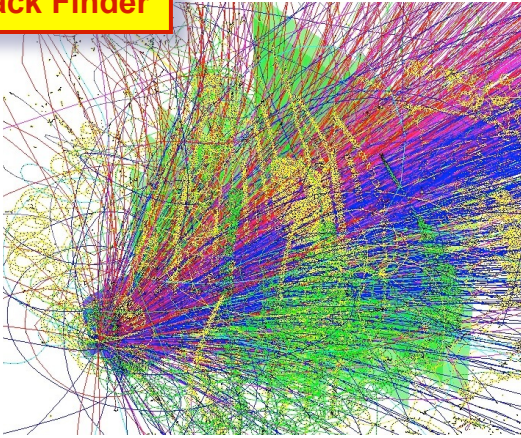


Future systems are heterogeneous, but using the same code

# Stages of Event Reconstruction

1

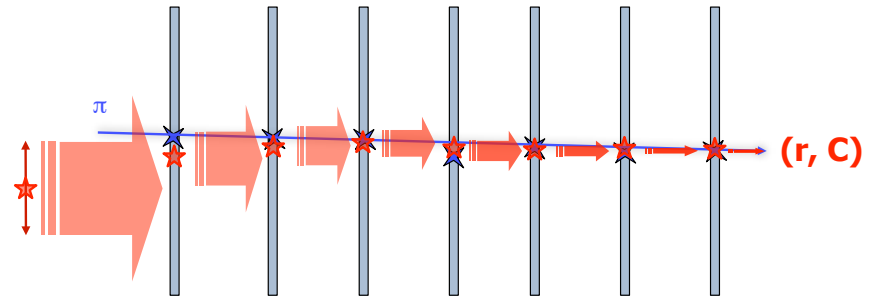
## Track Finder



- Cellular Automaton
- Track Following

2

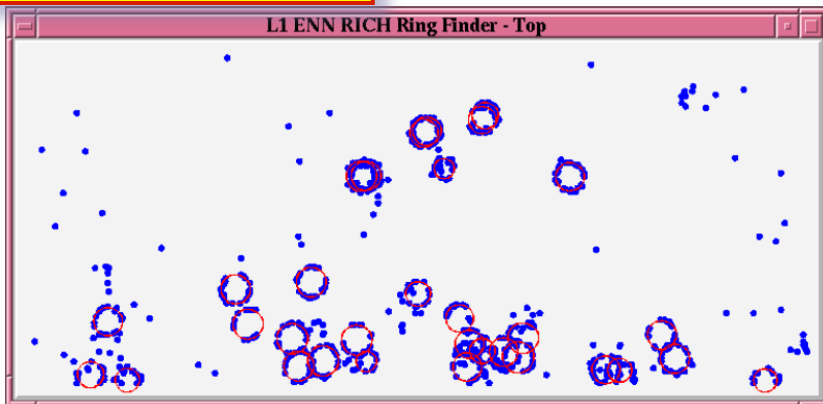
## Track Fitter



- Kalman Filter

3

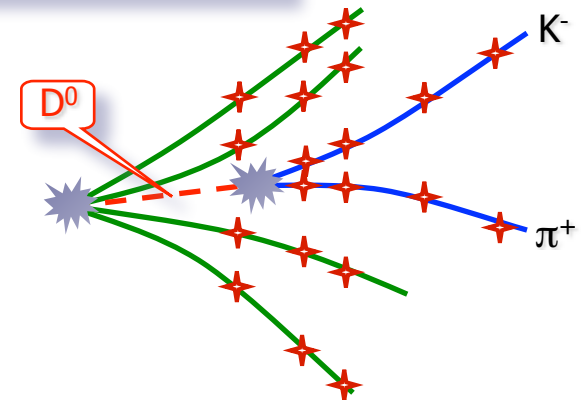
## Ring Finder (Particle ID)



- Hough Transformation
- Elastic Neural Net

4

## Short-Lived Particles Finder



- Kalman Filter



# Kalman Filter (KF) Track Fit Library

## Kalman Filter Methods

### Kalman Filter Tools:

- KF Track Fitter
- KF Track Smoother
- Deterministic Annealing Filter

### Kalman Filter Approaches:

- Conventional DP KF
- Conventional SP KF
- Square-Root SP KF
- UD-Filter SP
- Gaussian Sum Filter

### Track Propagation:

- Runge-Kutta
- Analytic Formula

## Implementations

### Vectorization (SIMD):

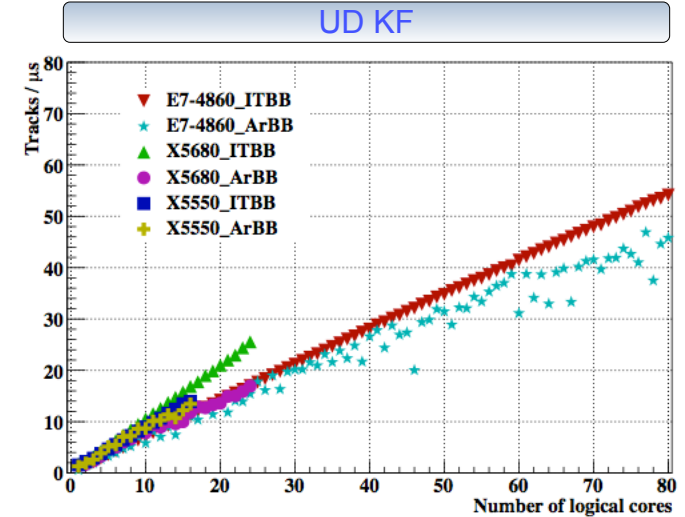
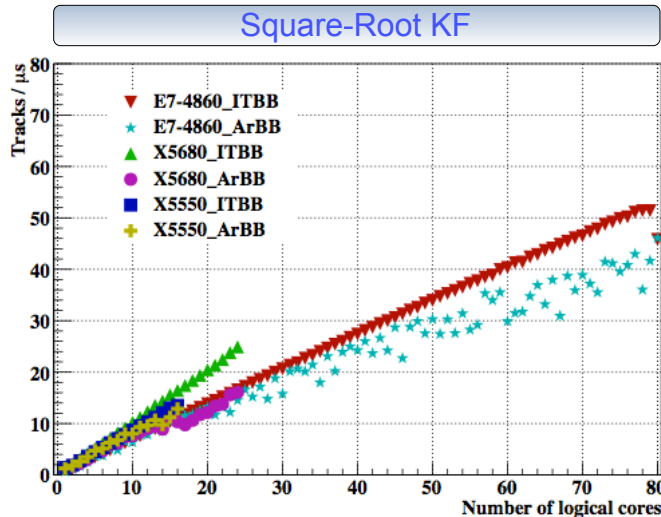
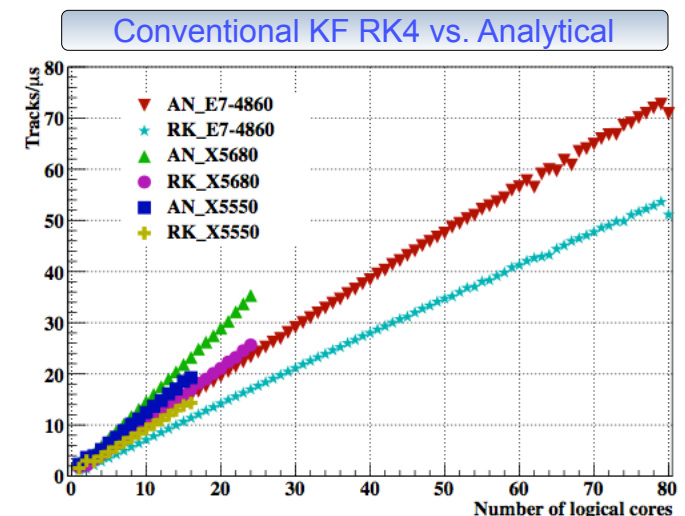
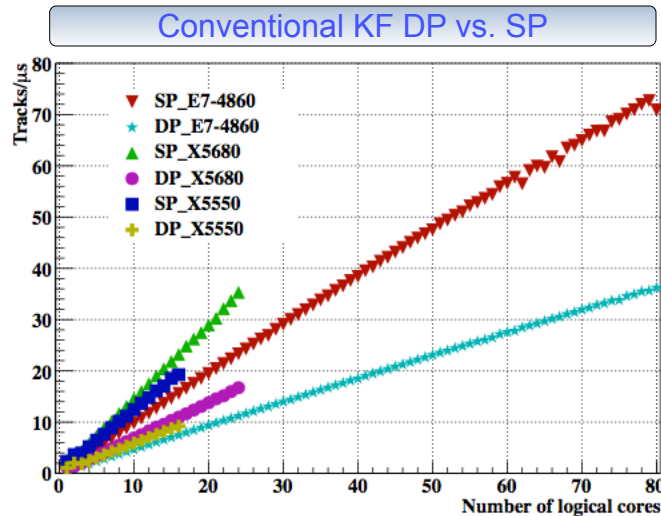
- Header Files
- Vc Vector Classes
- ArBB Array Building Blocks
- OpenCL

### Parallelization (many-cores):

- Open MP
- ITBB
- ArBB
- OpenCL

### Precision:

- single precision SP
- double precision DP

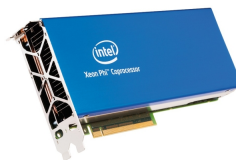
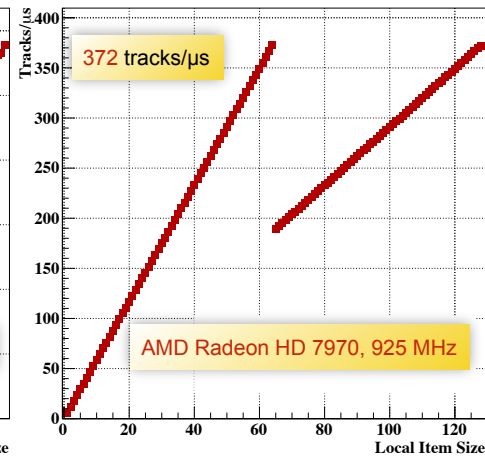
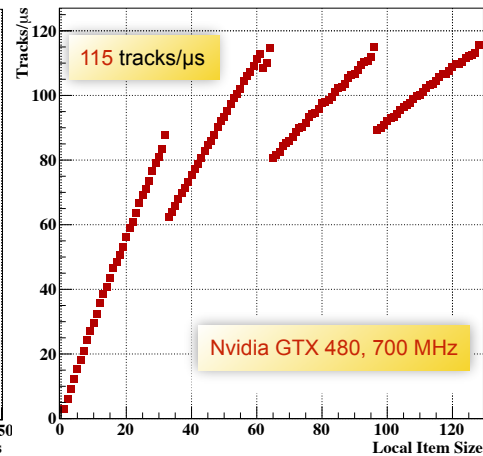
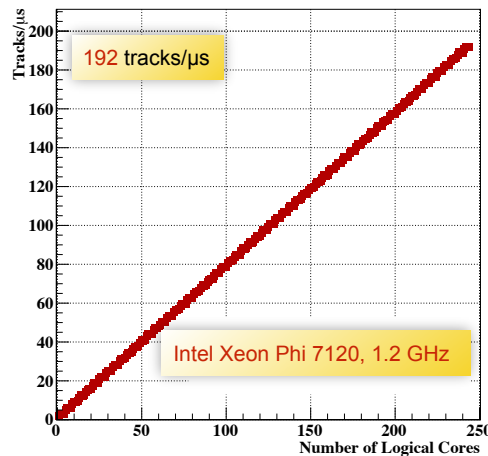
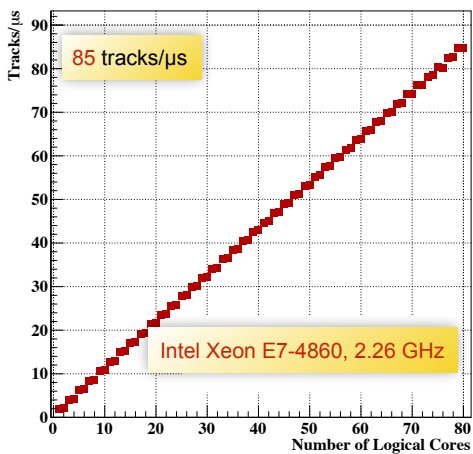


Comp. Phys. Comm. 178 (2008) 374-383

Strong many-core scalability of the Kalman filter library

with I. Kulakov, H. Pabst\* and M. Zyzak (\*Intel)

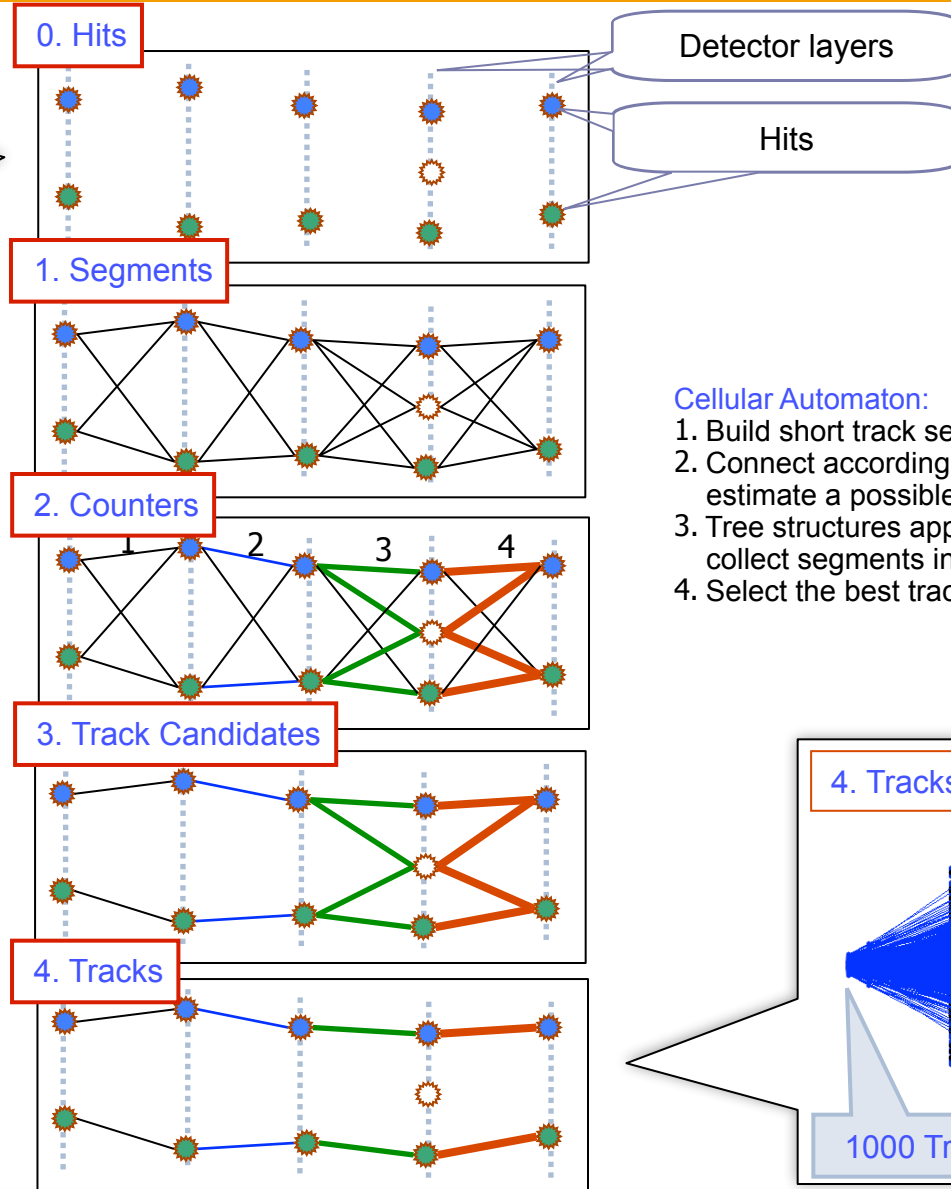
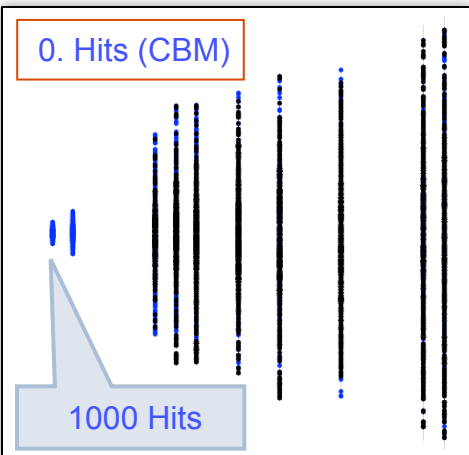
# Kalman Filter (KF) Track Fit Library



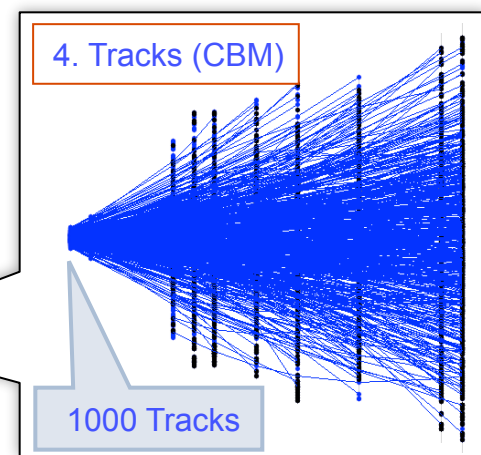
- **Scalability** with respect to the **number of logical cores** in a CPU is one of the most important parameters of the algorithm.
- The scalability on the **Intel Xeon Phi** coprocessor is **similar** to the **CPU**, but running **four threads per core** instead of two.
- In case of the **graphic cards** the set of tasks is divided into **working groups** of size **local item size** and **distributed** among **compute units** (or streaming multiprocessors) and the **load of each compute unit** is of the particular **importance**.

Full portability of the Kalman filter library

# Cellular Automaton (CA) Track Finder



- Cellular Automaton:
1. Build short track segments.
  2. Connect according to the track model, estimate a possible position on a track.
  3. Tree structures appear, collect segments into track candidates.
  4. Select the best track candidates.

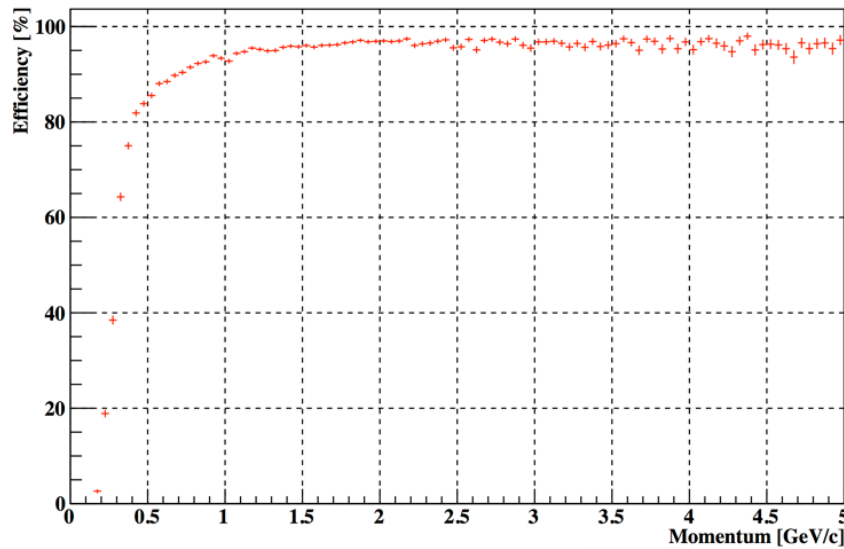
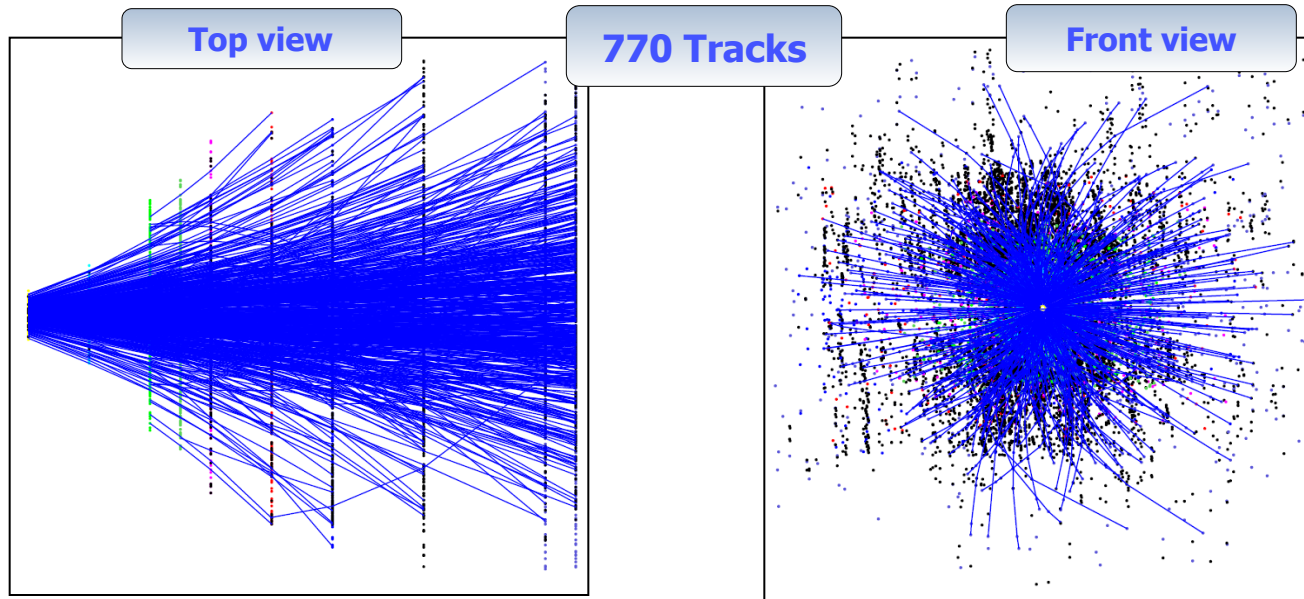


- Cellular Automaton:
- local w.r.t. data
  - intrinsically parallel
  - extremely simple
  - very fast

Perfect for many-core CPU/GPU !

Useful for complicated event topologies with large combinatorics and for parallel hardware

# CA Track Finder: Efficiency



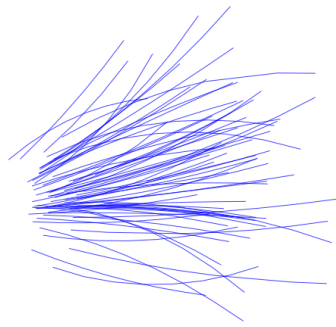
	Efficiency, %	
	mbias	central
Primary high- $p$ tracks	97.1	96.2
Primary low- $p$ tracks	90.4	90.7
Secondary high- $p$ tracks	81.2	81.4
Secondary low- $p$ tracks	51.1	50.6
All tracks	88.5	88.3
Clone level	0.2	0.2
Ghost level	0.7	1.5
Reconstructed tracks/event	120	591
Time/event/core	8.2 ms	57 ms

Efficient and clean event reconstruction

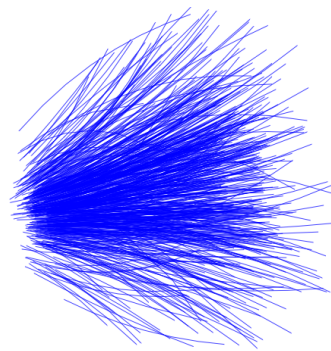


# CA Track Finder at High Track Multiplicity

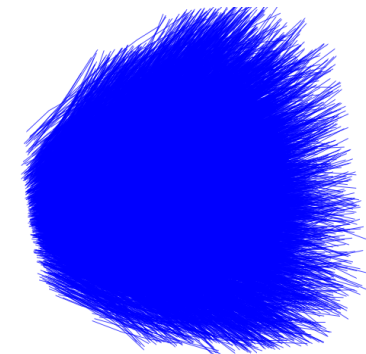
A number of minimum bias events is gathered into a group (super-event), which is then treated by the CA track finder as a single event



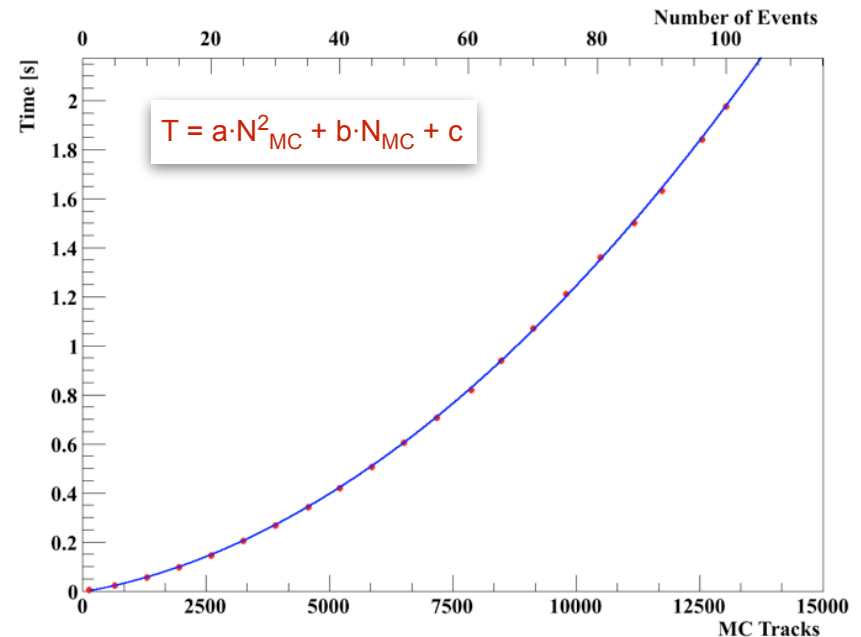
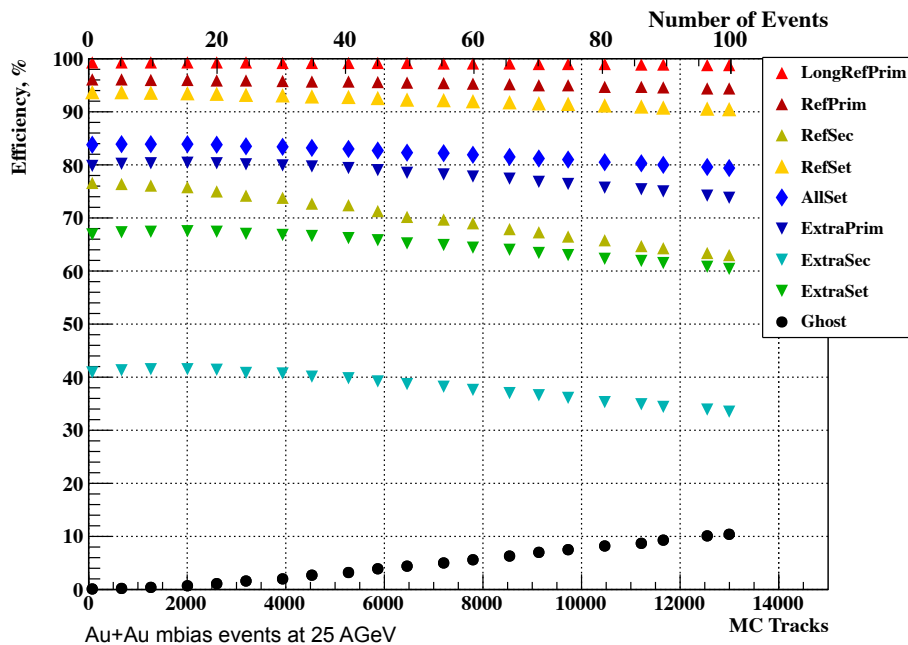
1 mbias event,  $\langle N_{reco} \rangle = 109$



5 mbias events,  $\langle N_{reco} \rangle = 572$

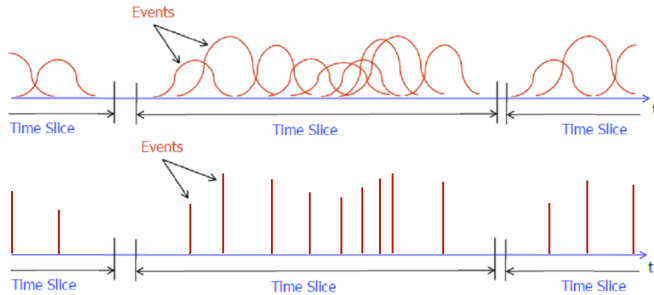


100 mbias events,  $\langle N_{reco} \rangle = 10340$



Stable reconstruction efficiency and time as a second order polynomial w.r.t. to track multiplicity

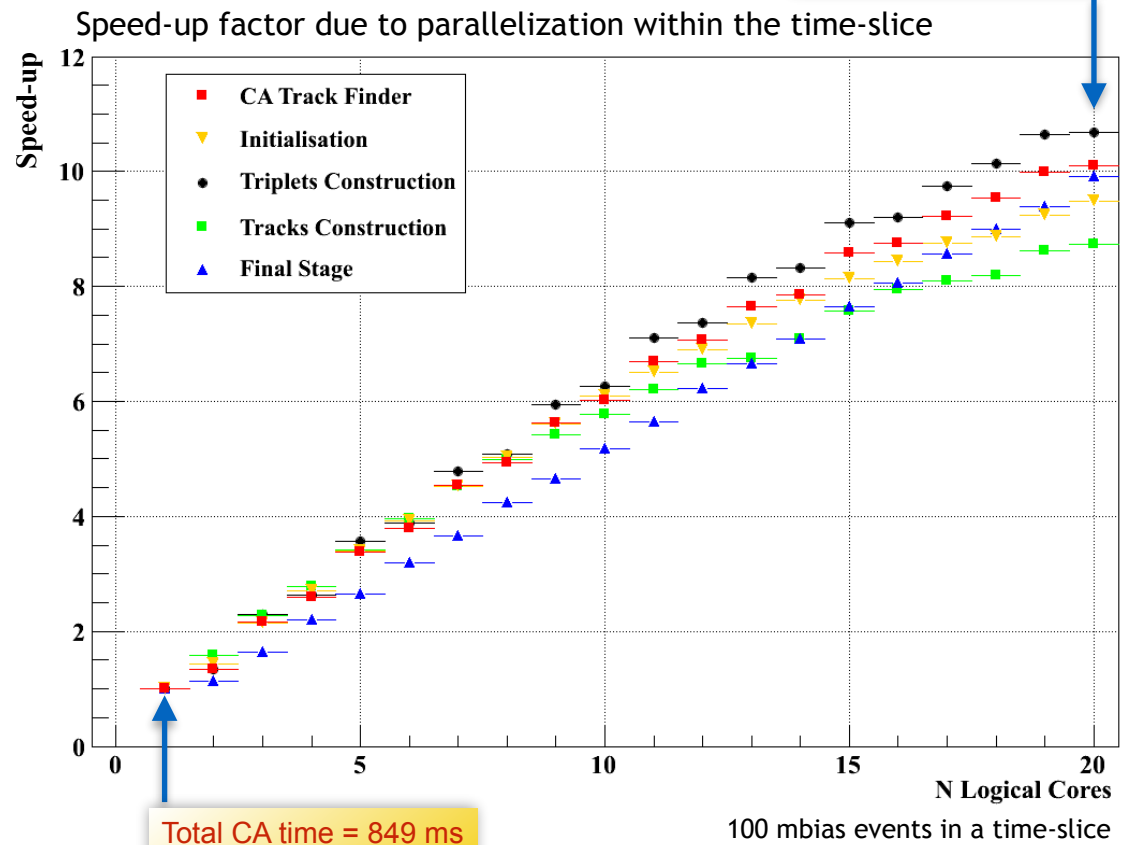
# Time-based (4D) Track Reconstruction with CA Track Finder



- The **beam** in the CBM will have **no bunch structure**, but continuous.
- Measurements in this case will be **4D** (x, y, z, t).
- Significant **overlapping of events** in the detector system.
- Reconstruction of **time slices** rather than events is needed.

Stage of the algorithm	% of total execution time		
Initialisation	8		
Triplets construction	64		
Tracks construction	15		
Final cleaning	13		

Efficiency, %	3D	3+1 D	4D
All tracks	83.8	80.4	83.0
Primary high- <i>p</i>	96.1	94.3	92.8
Primary low- <i>p</i>	79.8	76.2	83.1
Secondary high- <i>p</i>	76.6	65.1	73.2
Secondary low- <i>p</i>	40.9	34.9	36.8
Clone level	0.4	2.5	1.7
Ghost level	0.1	8.2	0.3
Time/event/core, ms	8.2	31.5	8.5

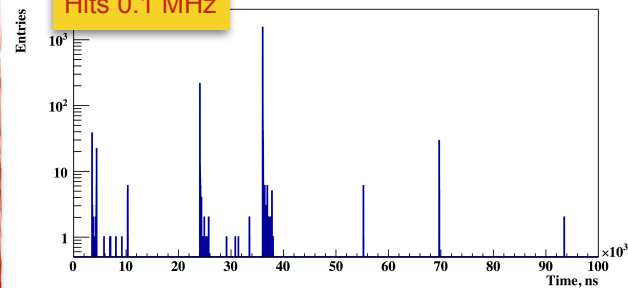


4D event building is scalable with the speed-up factor of 10.1; 3D reconstruction time 8.2 ms/event is recovered in 4D case

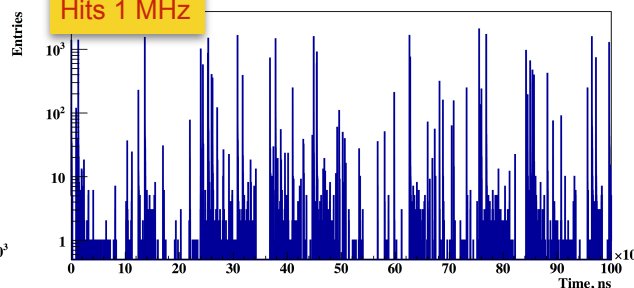
# 4D Event Building at 10 MHz

## Hits at high input rates

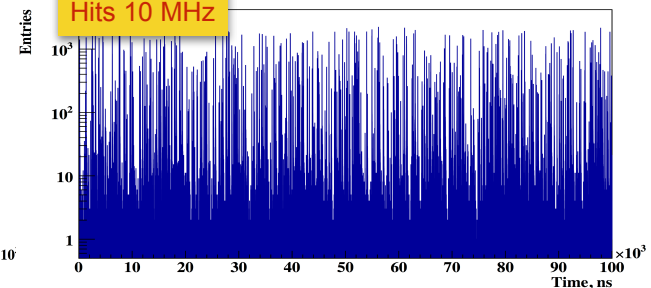
Hits 0.1 MHz



Hits 1 MHz

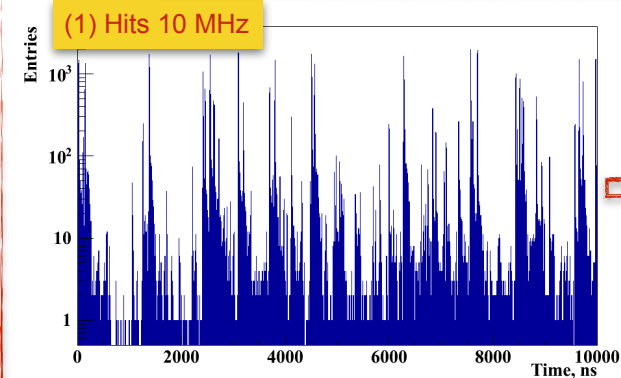


Hits 10 MHz

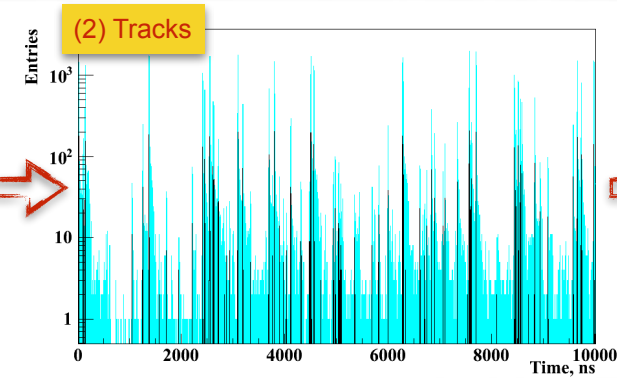


## From hits to tracks to events

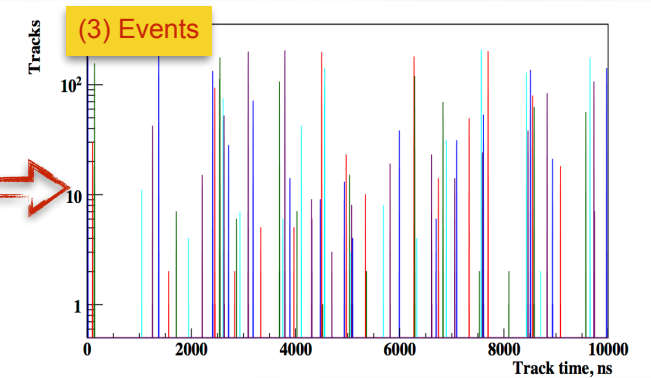
(1) Hits 10 MHz



(2) Tracks



(3) Events



Reconstructed tracks clearly represent groups, which correspond to the original events  
83% of single events, no splitted events, further analysis with TOF information at the vertexing stage

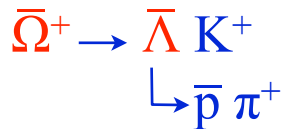
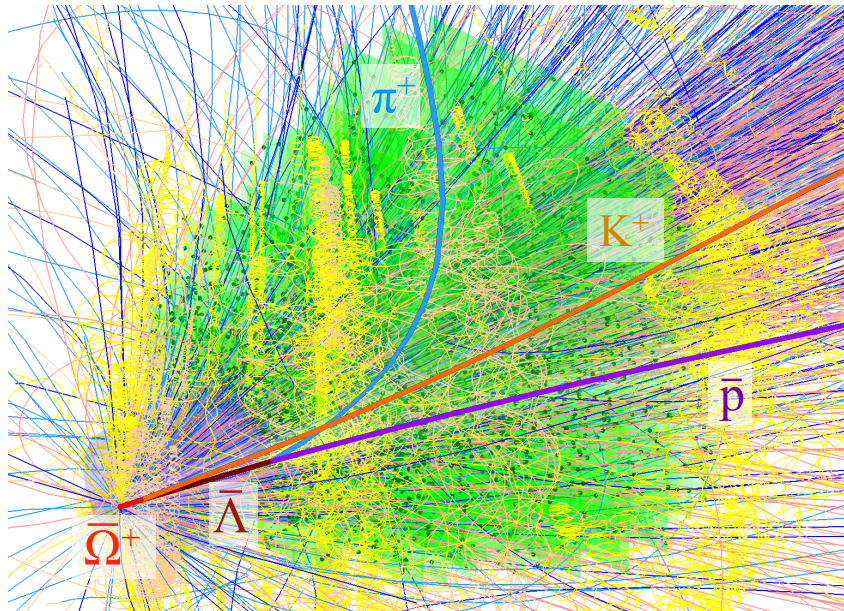
# KF Particle: Reconstruction of Decayed Particles

State vector

Position, direction, momentum  
and energy

$$\mathbf{r} = \{ \mathbf{x}, \mathbf{y}, \mathbf{z}, p_x, p_y, p_z, E \}$$

Central AuAu event at 25 AGeV simulated with UrQMD



## Concept:

- Mother and daughter particles have the same state vector and are treated in the same way
- Reconstruction of decay chains
- Kalman filter based
- Geometry independent
- Vectorized
- Uncomplicated usage

## Functionality:

- Construction of short-lived particles
- Addition and subtraction of particles
- Transport
- Calculation of an angle between particles
- Calculation of distances and deviations
- Constraints on mass, production point and decay length
- KF Particle Finder

KFParticle provides uncomplicated approach to physics analysis (used in CBM, ALICE and STAR)



# KF Particle Finder Algorithm

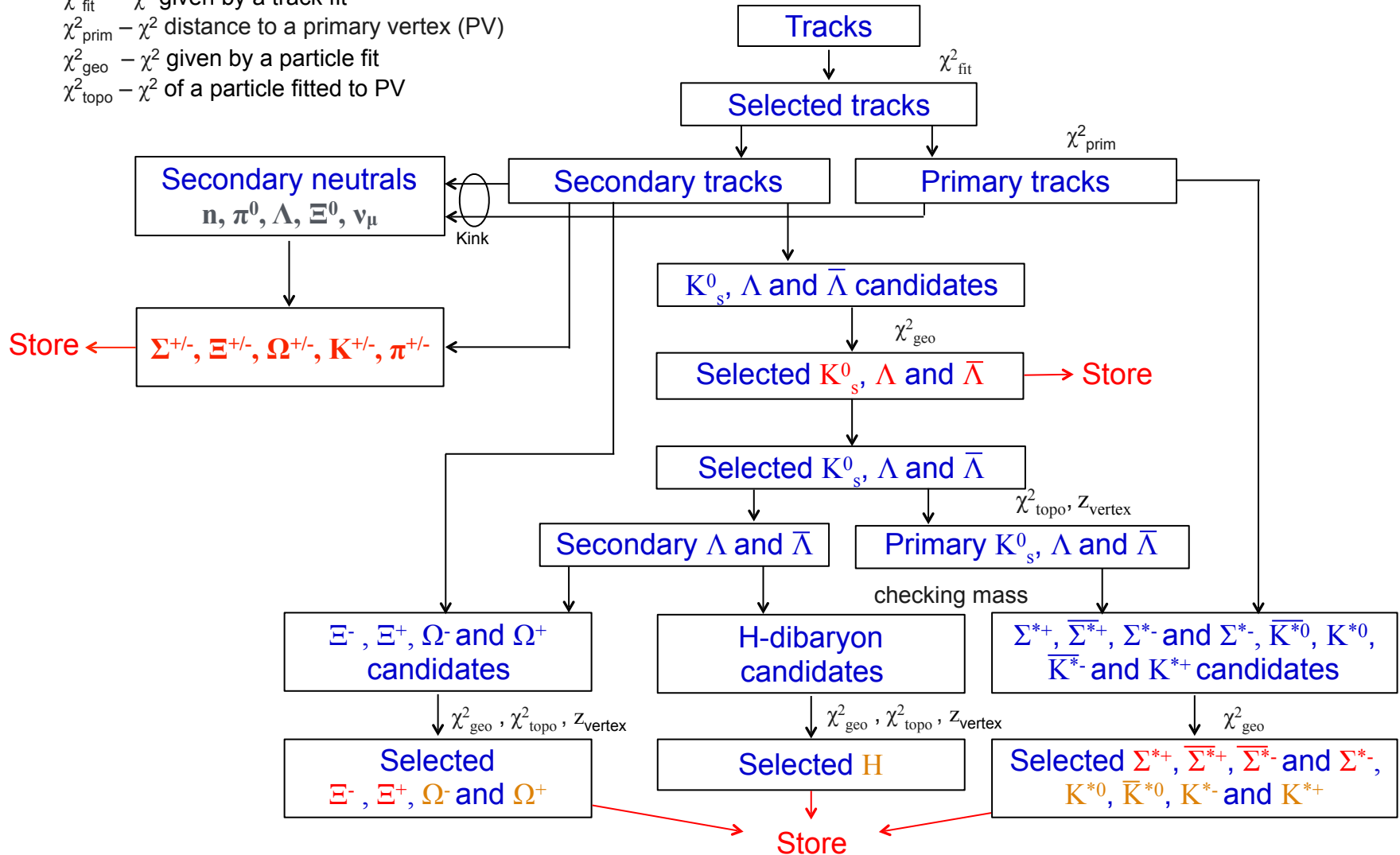
Selection criteria:

$\chi^2_{\text{fit}}$  –  $\chi^2$  given by a track fit

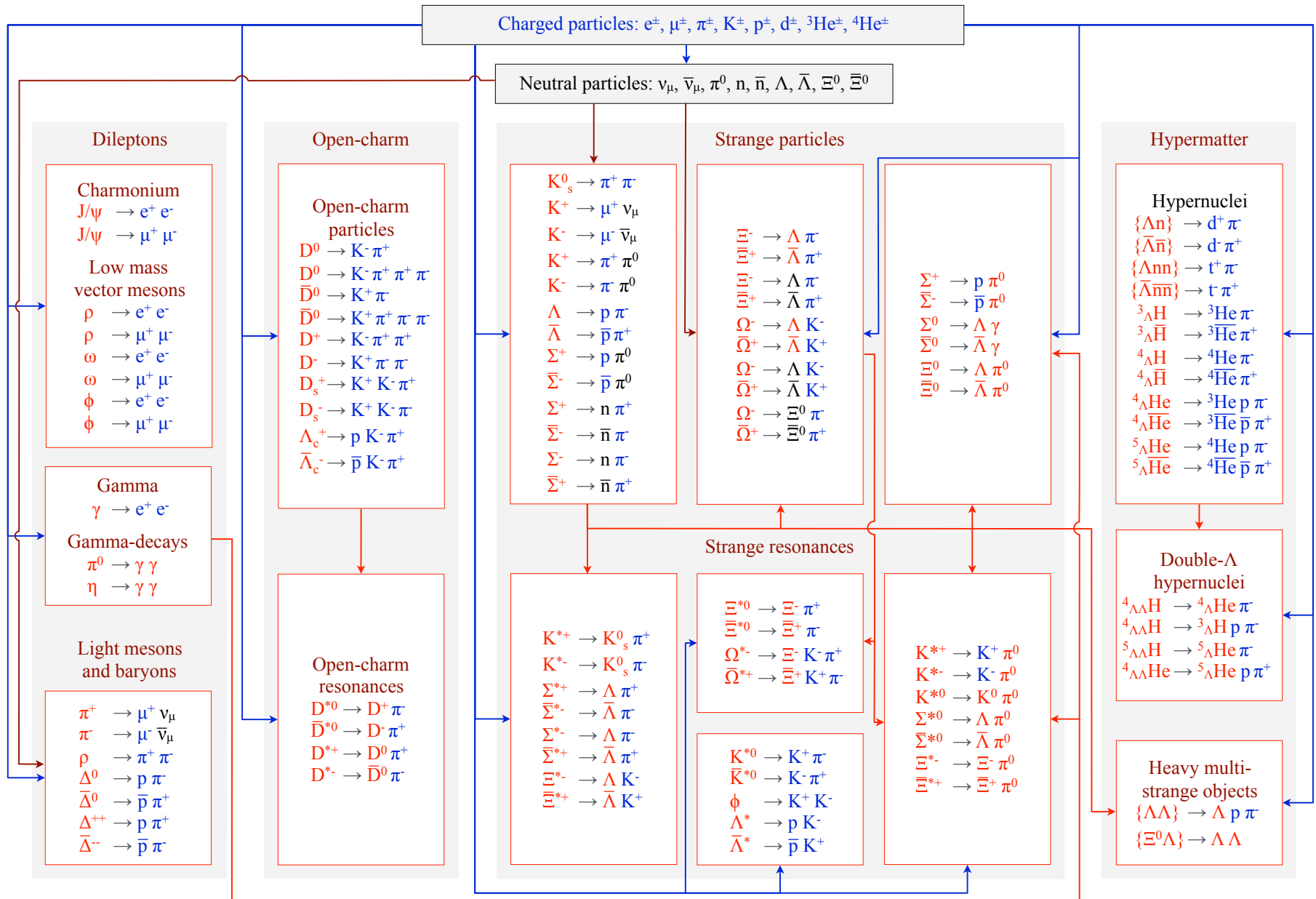
$\chi^2_{\text{prim}}$  –  $\chi^2$  distance to a primary vertex (PV)

$\chi^2_{\text{geo}}$  –  $\chi^2$  given by a particle fit

$\chi^2_{\text{topo}}$  –  $\chi^2$  of a particle fitted to PV



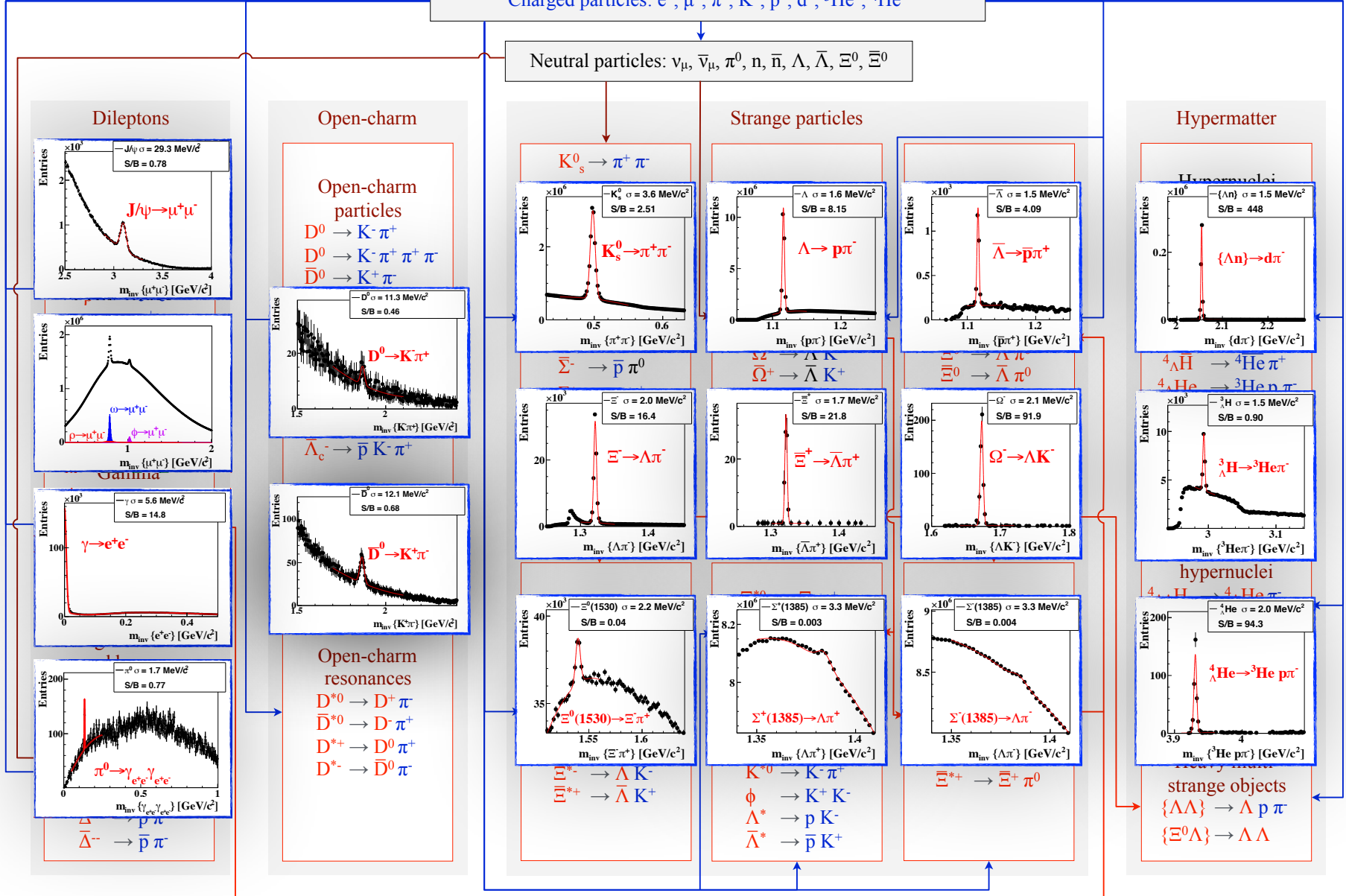
# KF Particle Finder for Physics Analysis and Selection



# KF Particle Finder for Physics Analysis and Selection

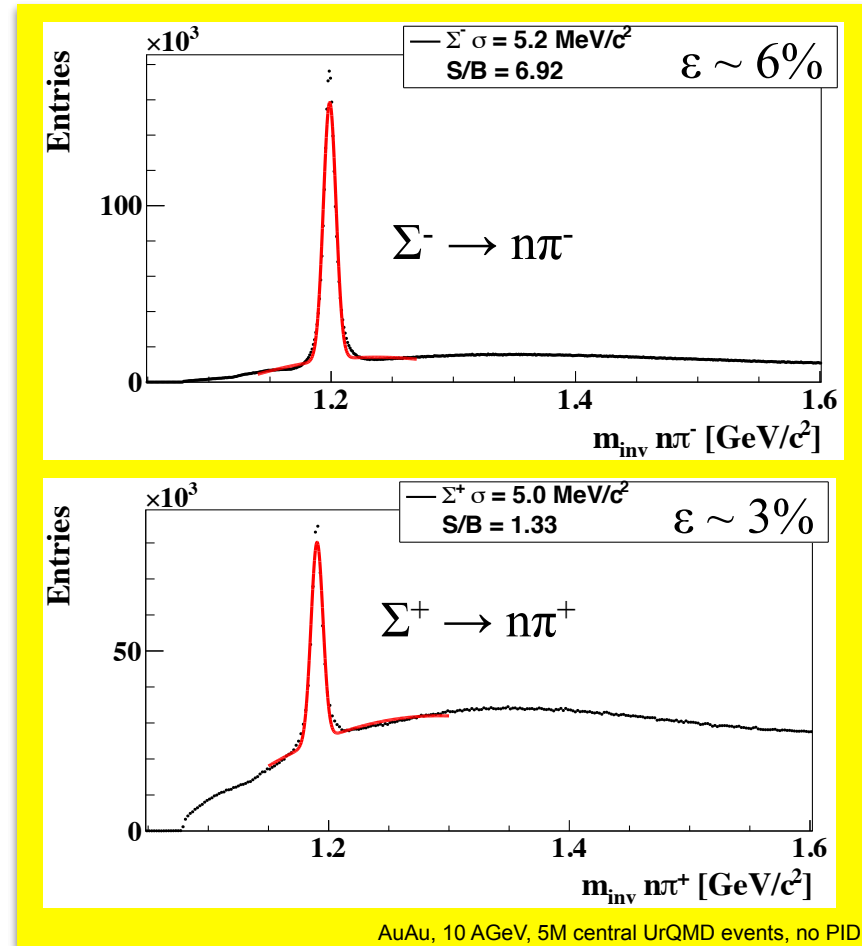
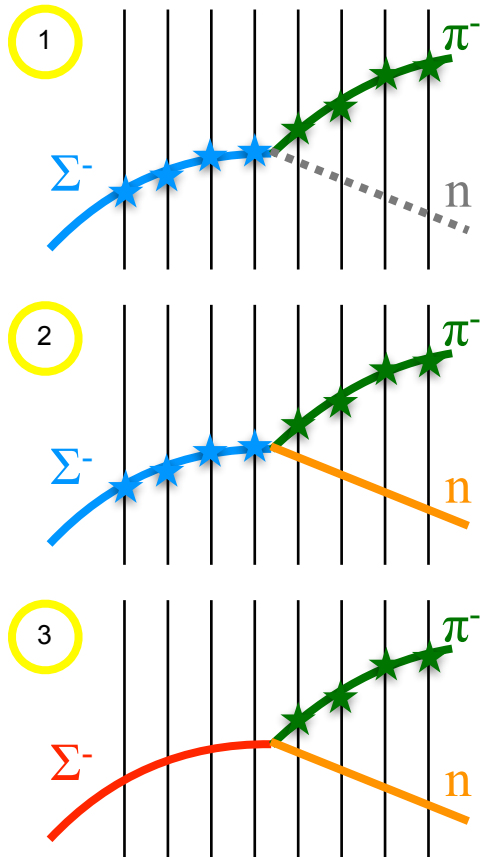
Charged particles:  $e^\pm, \mu^\pm, \pi^\pm, K^\pm, p^\pm, d^\pm, {}^3\text{He}^\pm, {}^4\text{He}^\pm$

Neutral particles:  $\nu_\mu, \bar{\nu}_\mu, \pi^0, n, \bar{n}, \Lambda, \bar{\Lambda}, \Xi^0, \bar{\Xi}^0$



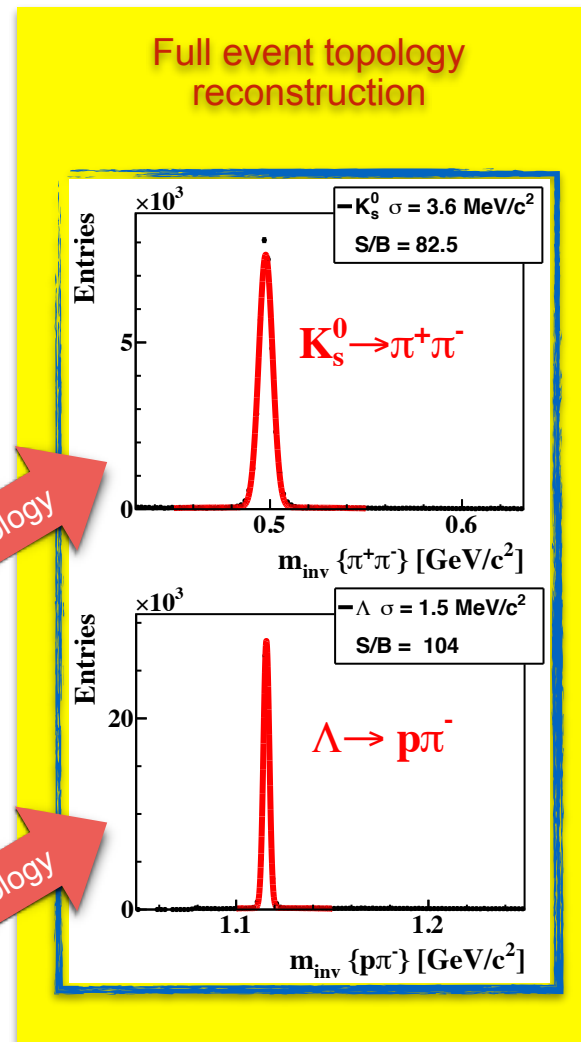
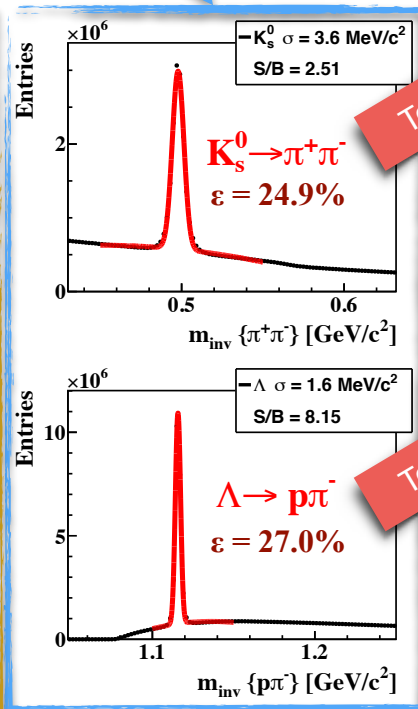
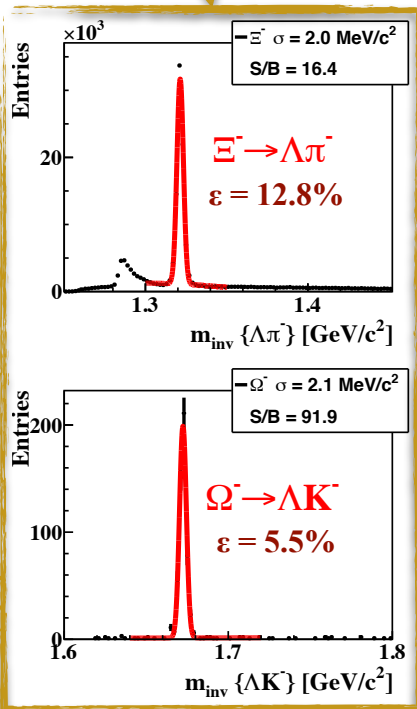
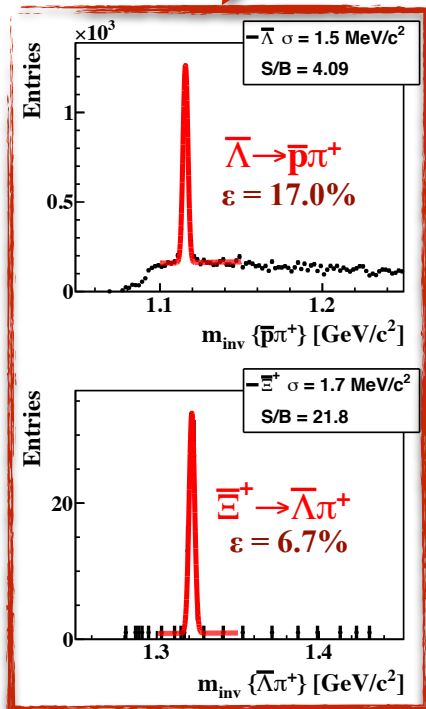
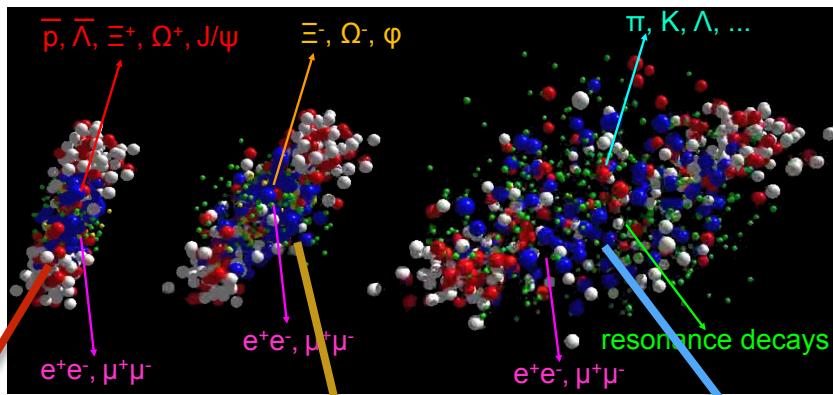
# Decays with Neutral Daughter

- Some particles ( $\Sigma^+$  and  $\Sigma^-$ ) have channels with at least **one neutral daughter**.
- A lifetime is sufficient to be registered by the tracking system:  $c\tau = 2.4$  cm for  $\Sigma^+$  and  $c\tau = 4.4$  cm for  $\Sigma^-$ .
- Can not to be identified by the PID detectors.
- Identification is possible by the decay topology using the **missing mass method**:
  1. Find tracks of  $\Sigma$  and its charged daughter (kink);
  2. Reconstruct a neutral daughter from the mother and the charged daughter;
  3. Reconstruct  $\Sigma$  mass spectrum from the charged and obtained neutral daughters.





# Clean Probes of Collision Stages



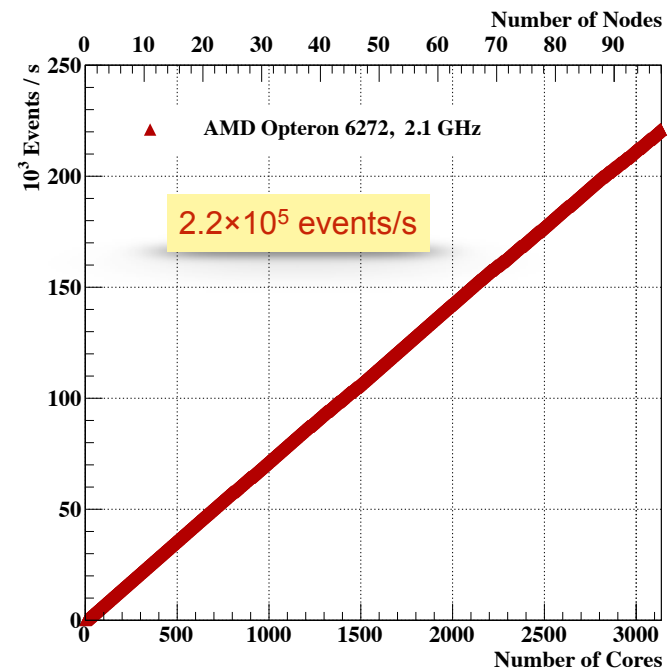
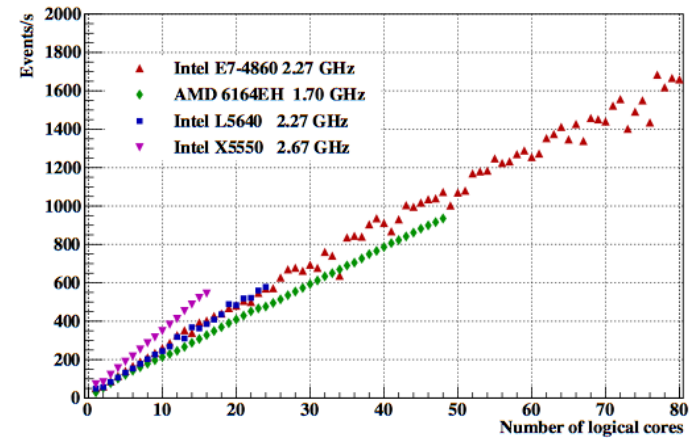
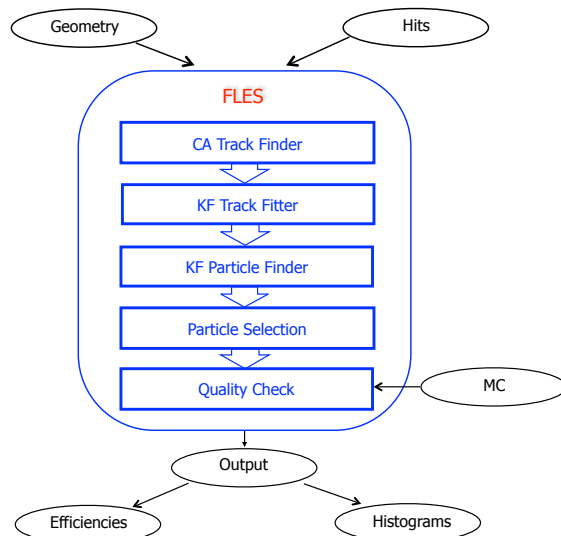
AuAu, 10 AGeV, 80K mbias UrQMD events, no PID

AuAu, 10 AGeV, 5M central UrQMD events, realistic PID

Topology

Topology

# CBM Standalone First Level Event Selection (FLES) Package



The first version of the FLES package is vectorized, parallelized, portable and scalable up to 3 200 CPU cores

# Parallelization in the CBM Event Reconstruction

**CPU - Full reconstruction**

**CPU - Tracking**

Algorithm	SIMD	ITBB, OpenMP	CUDA	OpenCL CPU/GPU	Phi	ArBB
Hit Producers						
STS KF Track Fit	✓	✓	✓	✓/✓	✓	✓
STS CA Track Finder	✓	✓				
MuCh Track Finder	✓	✓	✓			
TRD Track Finder	✓	✓	✓			
RICH Ring Finder	✓	✓			✓/✓ GPU/Phi - Selection	
KF Particle Finder	✓	✓		✓/✓	✓	
Off-line Physics Analysis	✓					
FLES Analysis and Selection	✓	✓				

**All - Benchmark**

Andrzej Nowak (OpenLab, CERN) by Hans von der Schmitt (ATLAS) at GPU Workshop, DESY, 15-16 April 2013

	SIMD	Instr. Level Parallelism	HW Threads	Cores	Sockets	Factor	Efficiency
MAX	4	4	1.35	8	4	691.2	100.0%
Typical	2.5	1.43	1.25	8	2	71.5	10.3%
HEP	1	0.80	1	6	2	9.6	1.4%
CBM@FAIR	4	3	1.3	8	4	499.2	72.2%

Parallelization becomes a standard in the CBM experiment

# Summary

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- The Kalman Filter track fit library is vectorized, parallelized and portable to CPU/Phi/GPU architectures.
- The Cellular Automaton track finder is vectorized and parallelized between CPU cores.
- The KF Particle Finder for reconstruction of short-lived particles is vectorized and portable to CPU/Phi architectures.
- Online physics analysis approaches are under investigation.

**More details:**

- V. Akishina, 4D event reconstruction in the CBM experiment, PhD Thesis, Uni-Frankfurt, 2016
- M. Zyzak, Online selection of short-lived particles on many-core computer architectures in the CBM experiment at FAIR, PhD Thesis, Uni-Frankfurt, 2016