



EMC Feature Extraction Algorithms

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Test Setups







Digitized Signals











D – Delay **MA** – Moving Averaging **Trig** – Trigger logic









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Time stamp generation:

- Explicit Constant Fraction
- Constant Fraction
- Leading Edge





LNP Signals







Moving Window Deconvolution





Preamplifier signal trace (80µs long)

Resulting signal after Moving Window Deconvolution (MWD) filtering:

$$MWD_{M}(n) = x_{n} - x_{n-M} + \frac{\ln 2}{\tau} \sum_{i=n-M}^{n-1} x_{i}$$

The M value defines the length of the flat top!!!

A. Georgiev, W. Gast, IEEE Trans. Nucl. Sci. NS-40 (1993) 770; J. Stein *et al.*, Nucl. Instr. Meth. B 113 (1994) 141.



LNP Signal







LNP Signal







To achieve best signal/noise ratio one has to average signal within 300 - 400 nsec



SKV

Digital filtering (Time resolution)











Still contain time information (base line == 0, by defenition)

Easy to make trigger

SKVI

Digital filtering (Time resolution)





Get precise timing



Make trigger / Get rough timing



Summary



- Presented feature-extraction algorithms provide additional (to analogue) noise reduction, good energy and time resolution
- The walk effect for the digital implementation of CFD has to be investigated in more details
- VHDL implementation is in progress (all "building blocks" are implemented; expected tests with hardware end of summer)
- Performance of algorithms with ASIC signals will be tested with cosmic and γ rays (prototype build by GSI)
- Continuous sampling has advantages over analogue "zero suppression" (analogue discriminators)