

# CA Tracking

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# Outline

- Introduction
- Cellular Automaton tracking
- Current Status & Results
- Summary & Outlook

# Introduction

- Tracking in forward detectors for the PANDA experiment is considered in this presentation:
  - MVD (Forward part)
  - FTS
- Features, Results and Perspectives of the CA approach are discussed.

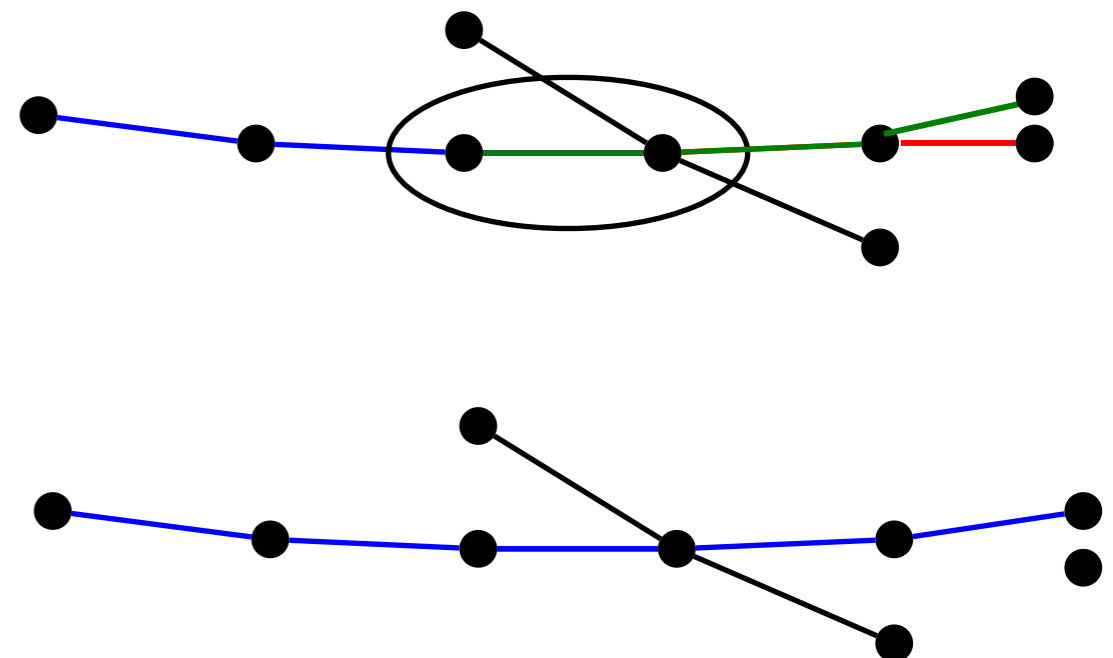
# Cellular Automaton Tracking

- **Input/Initialisation**
- **Tracklet construction**
  - **Singlets**
  - **Doublets**
  - **Triplets**
- **Evolution**
  - **Neighbour Search**
  - **Track Construction**
- **Performance evaluation**

- **Parameters**

- **Kalman Filter**

- **Extrapolation**
- **Update**



# Current Status and Results

- Efficiencies
- Residuals and Pulls
- Fitting Approaches
- Activities

# Efficiencies

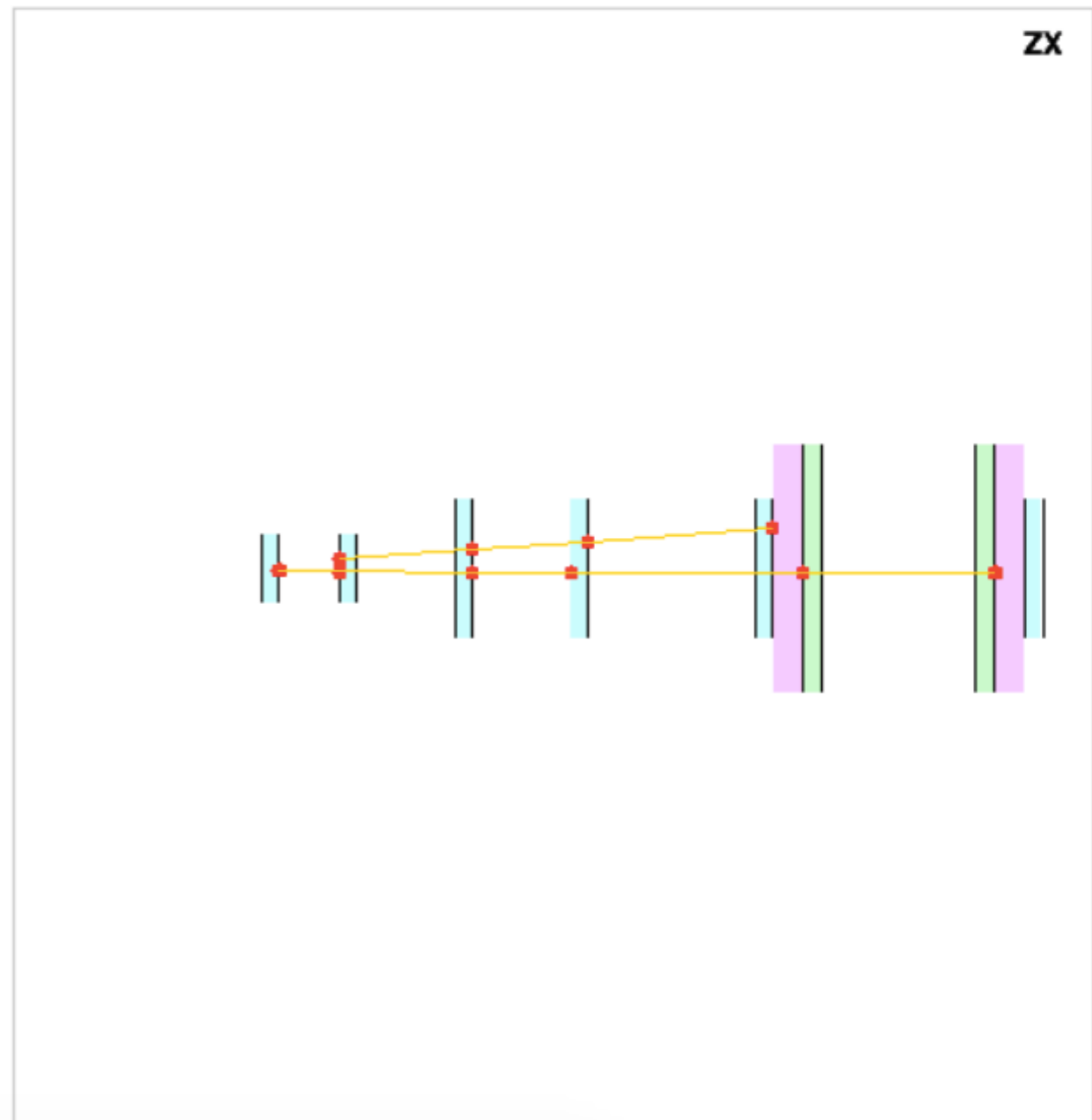
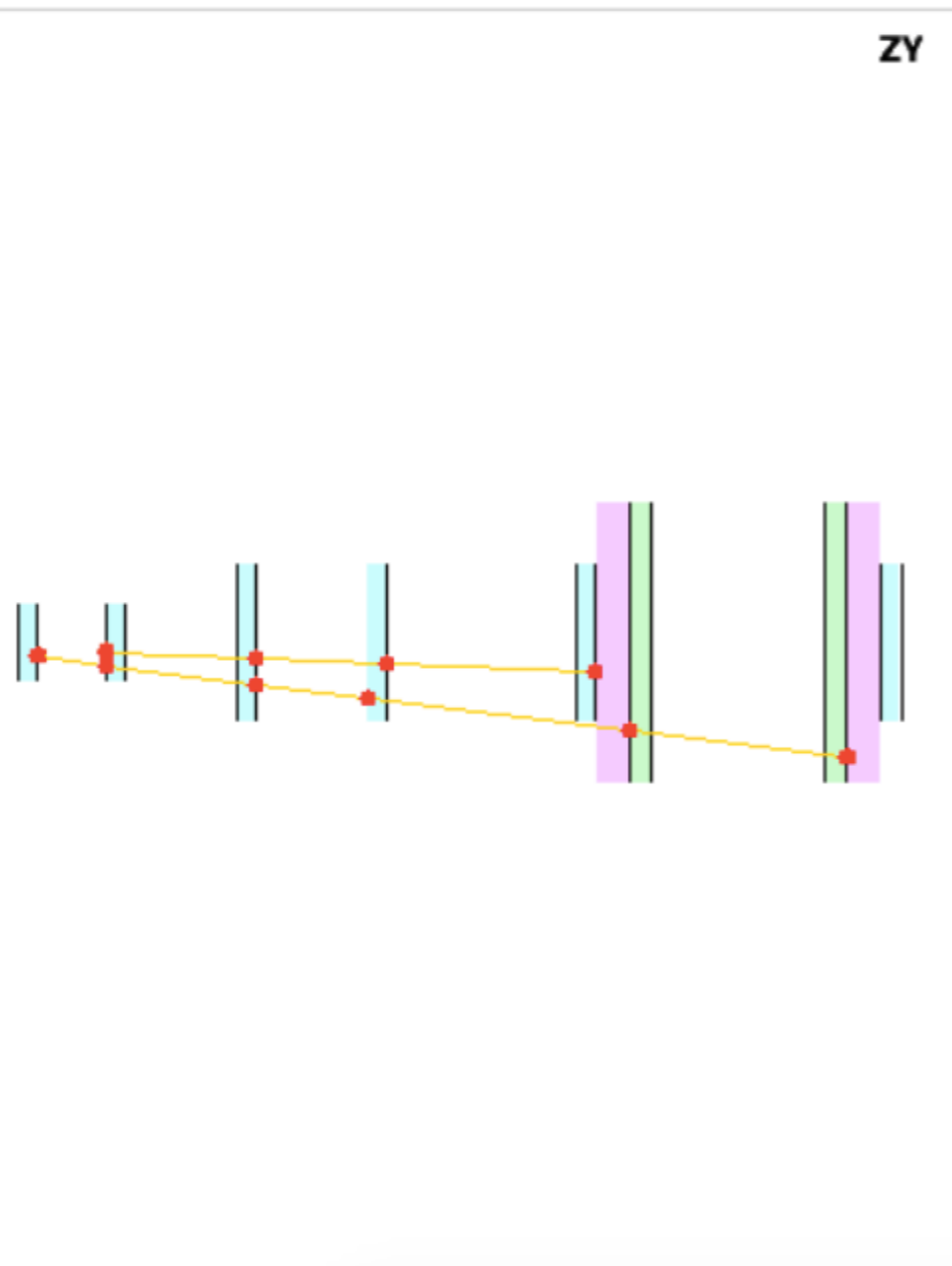
1000 BoxGenerator events  
purity=100%

Reconstructable track:  
>= 3 consecutive MC points

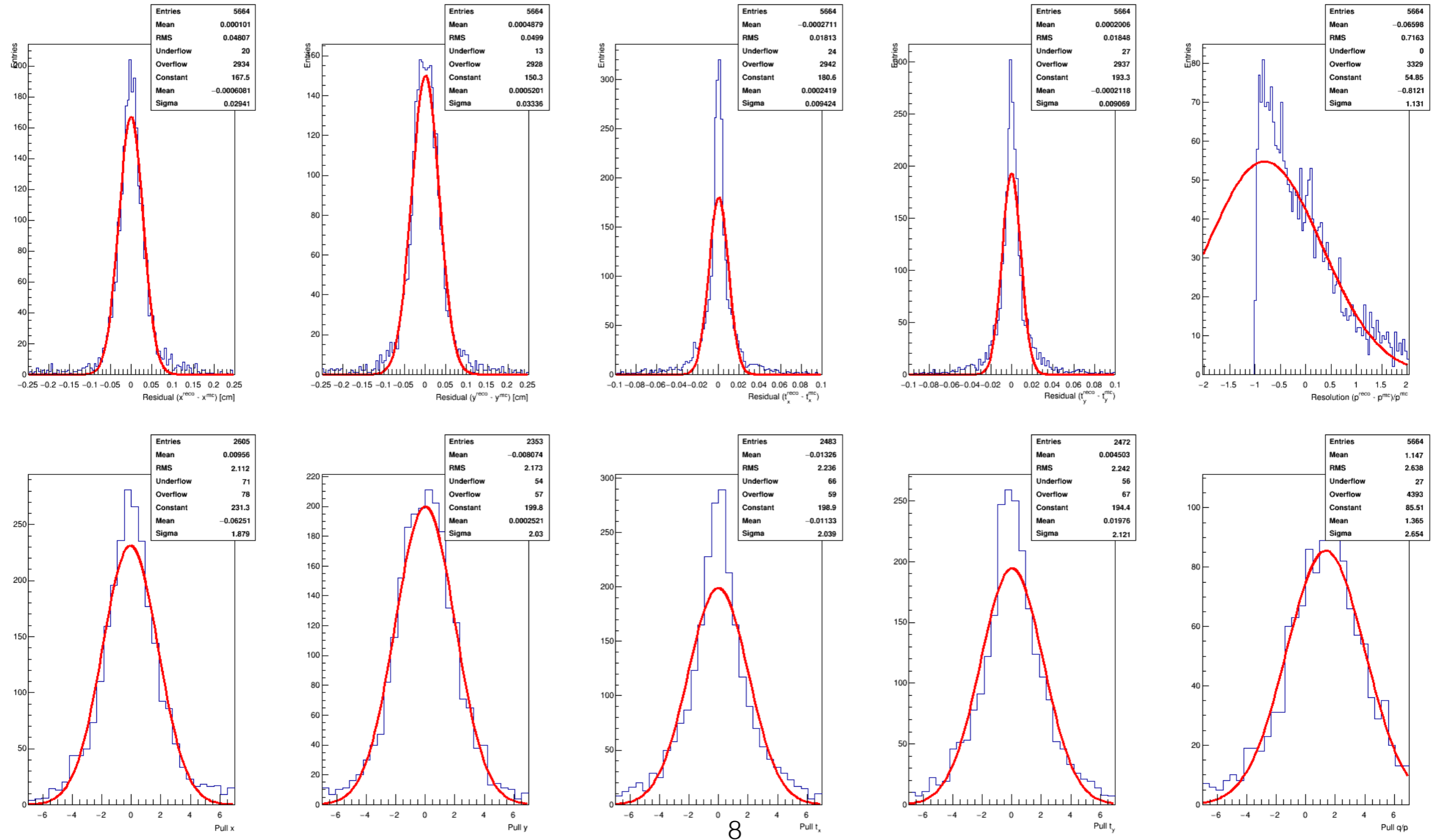
	Efficiency,%	Ghost/ev	Clone/ev	Tracks/ev
triplets	100	12.5	9.5	1
track candidates	100	71.6	50.5	1
tracks	No selection yet because of KF debugging ...			

# Event Display

## Reconstructed Tracks



# Residuals and Pulls





# Fitting Approaches

- Runge-Kutta 4th order method

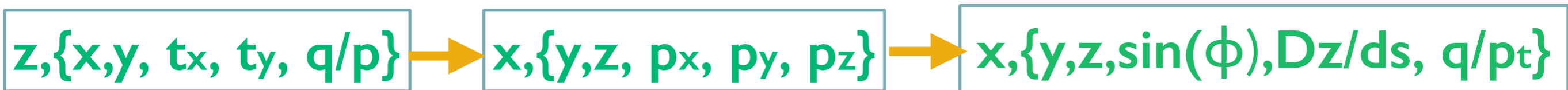
- Standard iterative extrapolation method of the KF.
- Restricted to one track-model as far as calculations are performed only in the track parameter space.

- Analytic Formula

- Direct calculation of the extrapolated parameters.
- Same precision as the RK4-method.

- **Feature:**

- Extrapolate in the space of physical parameters (e.g.  $\{x,y,z,p_x,p_y,p_z\}$ ) rather than being restricted to the track model parameters space.
- Opportunity to perform track model parameters conversion into physical parameters and vice versa.
- For example, if a track has to be propagated from a forward detector station to a barrel detector station the following conversion could be implemented:



# Activities

- Both track propagation approaches were studied and have shown almost same results.
- *GenFit* fitting package is being explored currently to compare track fitting quality with other packages.

# Summary & Outlook

- Fwd Mvd tracking almost done (~80%).
- The obtained experience and code to be implemented (next week starting) in:
  - **Fwd MVD + FTS.**
  - **FTS standalone** (based on I.Kulakov code).