

Collaboration Meeting MVD Subgroup GSI, March 3, 2009

Thomas Würschig

Update on the MVD mechanics and presentation of a concept for the strip disks









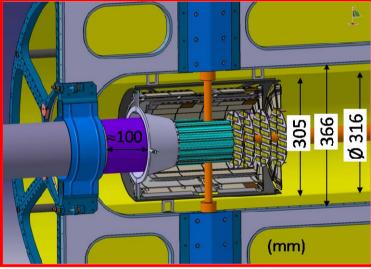
- Jülich, February 9-10, 2009
 - Participants
 - ✓ T. Stockmanns, H. Jäger (IKP, FZ Jülich)
 - ✓ D. Grunwald (ZAT, FZ Jülich)
 ✓ G. Giraudo (INFN Torino)
 ✓ L. Lambrecht (IKV Aachen)
 - ✓ Th. Würschig (HISKP, Uni Bonn)
 - > Program
 - ✓ Status in Bonn / Jülich / Torino; Presentation of IKV Aachen
 - ✓ Discussion:

Pixel design / Strip design / Cooling and integration / CAD conventions, CAD converter / Next steps and missing info





- Communication with Frascati
 - > Interface Central frame (CF) \leftrightarrow MVD \leftrightarrow (STT)



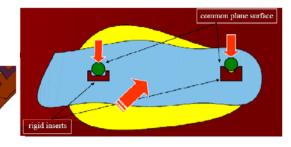
- ✓ Updated version of CF
- ✓ 41 x 35 mm² area at top and bottom over full length left for readout



G. Giraudo, D. Orecchini

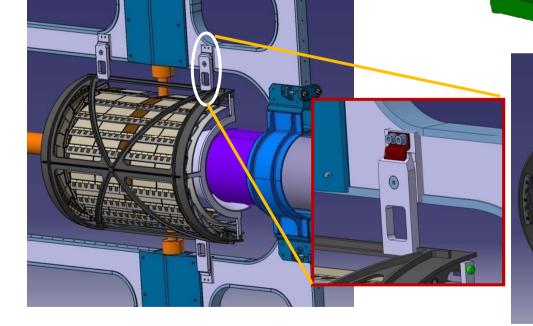


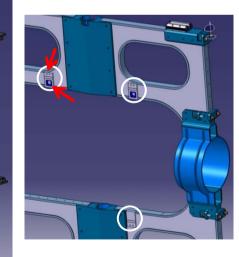
- Proposal for MVD coupling to CF
 - Based on ALICE ladder repositioning system
 - > 2 fixed points @ top and 3rd point
 - @ bottom define a plane



Precision < 6 μm

The SDD and SSD support structure for the ALICE Inner Tracking System. *G. Giraudo et all. 2009 JINST 4 P01003*



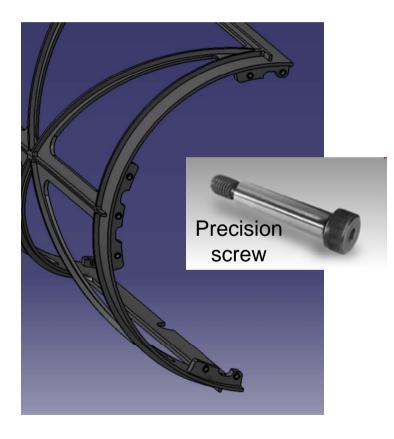




MVD global support ↔ barrel support

G. Giraudo

Common design for strip and pixel subsystem

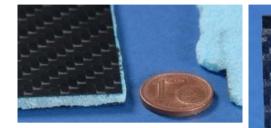


- Three fixing points for pixels
 Screw:
 1 x M4 + 2 x precision M4
- Four fixing points for strips
 Screw:
 2 x M4 + 2 x precision M4





- Carbon structure processing
 - Stave support: Sandwich structure
 - (Carbon Foam Carbon)

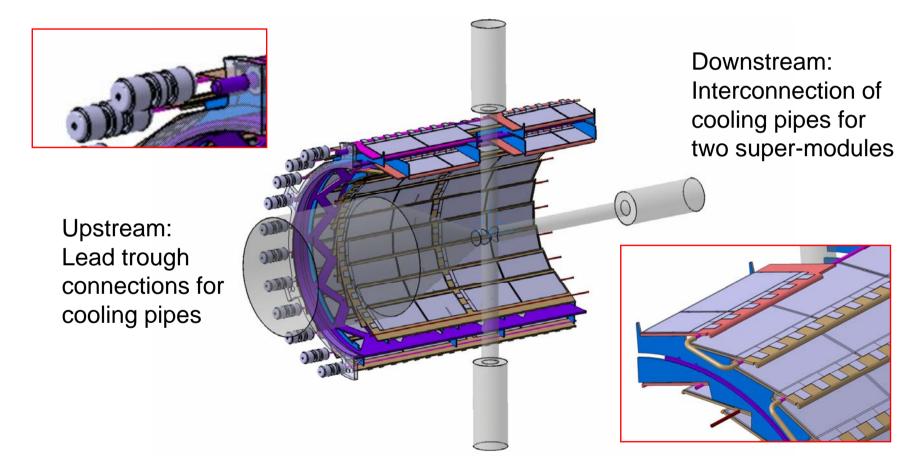


- Barrel support: Half-shell and saw-tooth support
 - \rightarrow 1st water cutting





• Strip barrel design



D. Grunwald

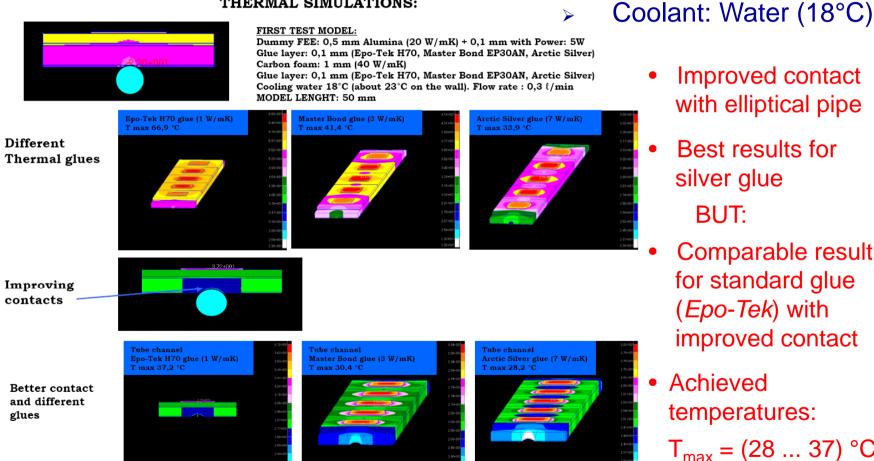


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Preliminary thermal simulations for pixel modules • S. Coli

THERMAL SIMULATIONS:



- Improved contact with elliptical pipe
- Best results for silver glue BUT:
- Comparable results for standard glue (*Epo-Tek*) with improved contact
- Achieved temperatures:

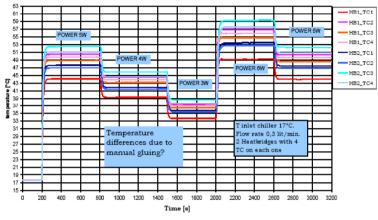
T_{max} = (28 ... 37) °C

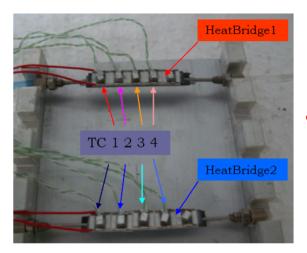




• Thermal measurements: built up and test of 1st prototype

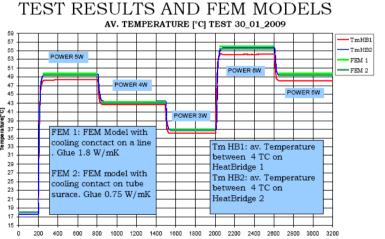
TEMPERATURE [°C] TEST 30_01_2009

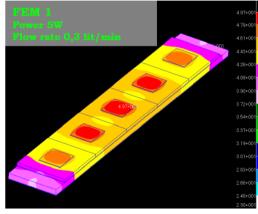




S. Coli

 Good agreement of mean value between FEM analysis and measurement





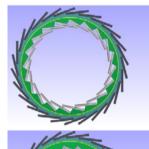
- Still bigger variations for single FEE dummies
 - → improvement of glue contact

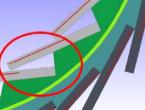




- Dedicated concept for strip disks ...more details later... Th. Würschig
- Design check for proposed modification in barrel 3 •

Default:





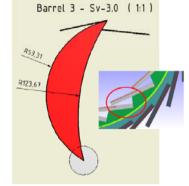
- Sensor at innermost radius
- Readout position at outer radius

Proposed modification: Readout at innermost radius Sensor position

at outer radius

PROS

- Better access to readout electronic
- ... But: is this really necessary and realistic?
 - ✓ In operation there is NO access to the whole MVD at all
 - ✓ In test phase: fully equipped MVD barrel layer must be taken apart even for the modified version to reach the regions of interest WITHOUT any danger of destroying the neighbouring modules



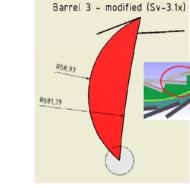
Default: Maximum bending radius: 124 mm

CONS

- More material load at inner radii
- > Higher radial tilting angle for the super-modules
 - → Higher variation of radius of the sensor's active area
 - → Much bigger gap for bending radii
 - → Less space in between subsequent super-modules
- Referring momentum range of the gap in the bending radius reaches a highly populated region of the PANDA experiment!



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Maximum bending radius 6 x higher!

Proposed modification:



• Discussions

- > Pixel design:
 - ✓ Arrangement of pixels in the forward disks
 - ✓ Pixel module types
 - ✓ Cooling
- Strip design:
 - ✓ Arrangement of super-modules in barrel part
 - ✓ Shape of the barrel stave support
 - Super-module positioning (barrel part)
 - ✓ Cooling
- Integration:
 - \checkmark Support for strip disks \leftrightarrow global MVD support
 - \checkmark Support for strip barrel layers \leftrightarrow global MVD support





Conclusions: Pixel part

- > Implementation of different module sizes
 - ✓ Different lengths
 - ✓ Number of rows: one or two
 - ✓ Basic unit: 10 mm x 10 mm
- \rightarrow Number of different module types should be minimized (4 ... 6)
- > Work out of two designs
 - Optimized coverage ↔ Minimized material *
- * Realistic considerations of technical limitations (e.g. cooling, spatial safety margins)
- \rightarrow Input to simulations \rightarrow Results basics for optimisation





Conclusions: Pixel part

- Cooling
 - ✓ Coolant: water 18°C
 - ✓ Better contacts improve efficiency
 - \checkmark Water flow does not have such big impact
 - ✓ Best cooling temperature for pixel modules roughly 30°C
- → Study of effects for silicon sensors in this temperature region w.r.t. thermal runaway necessary! (also valid for strip part)

Conclusions: Strip part

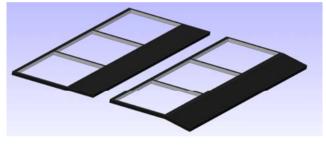
- Forward part: New disk concept
- \rightarrow Best solution for optimized coverage and minimized material budget





Conclusions: Strip part

- Barrel layer: Implementation of modified stave support
 - ✓ Deflection of the plane supporting the FEE + cooling pipe
 - Deflection angle = tangential tilting of the super-modules



- → More radial space and prevention of collision between super-modules (FEE plane || next sensor plan)
- \rightarrow Production feasible in carbon resulting in an even stiffer structure
- Barrel stave positioning
- \rightarrow Adaptation of "clip" technology used in ALICE as one option





Conclusions: Integration

- Forward part
- → Decoupling of pixel and strip part to MVD frame applying new concept
- \rightarrow Maybe additional support for pixel disks by strip disk part necessary
- Barrel part
- \rightarrow Adaptation of the strip barrel support to the modified MVD frame

CAD hierarchy

MVD pixel/ strip version	
MVD part:	All barrel layer = Hshell (half-shell) All disk layer = Fwd (forward part)
Layer:	All super-modules forming a half-layer → Functional level, (mechanically) not a "real" one
Super-module:	Module + support + cooling pipe → Smallest mechanically independent unit
Module: Sensor, frontend, cable (maybe additional support) → smallest electronically independent unit (= readout channels) → mechanically (mostly) not independent	
Sensor: Act	tive and passive volume





Concept for the forward silicon strip disks



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- Interesting solution for LAMBDA wheel at HERMES experiment
 - Setup:
 - ✓ Double sided trapezoidal strip sensor sensors (DSSD) (thickness: 300 μ m; stereo angle: 30°; pitch: ≈160 μ m)
 - 2 disk layers with a distance of 5 cm
 - Inner radius: 9 cm / Outer radius: 33 cm
 - Severe boundary conditions ($R_{max} = 34$ cm)
 - FEE: 0.4 W / 128 channel (HELIX chip)





- Interesting solution for LAMBDA wheel at HERMES experiment
 - Concept:
 - ✓ Wire bonding (17 μ m *Al*): sensor ↔ capton foil ↔ FEE
 - Carrier board (multi layer Kapton-Copper OFHC) for each sensor
 - Carrier boards connected to support (bars) to form a rigid structure
 - Connection of these (super-)modules to outer frame





 Interesting solution for LAMBDA wheel at HERMES experiment

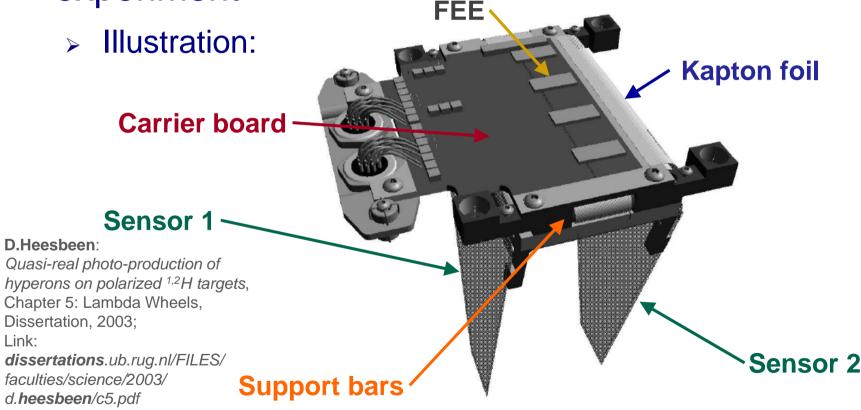


Figure 5.2: Computer aided drawing of a Lambda Wheels silicon detector module.





- Interesting solution for LAMBDA wheel at HERMES experiment
 - > Illustration:

D.Heesbeen:

Quasi-real photo-production of hyperons on polarized ^{1,2}H targets, Chapter 5: Lambda Wheels, Dissertation, 2003; Link: **dissertations**.ub.rug.nl/FILES/ faculties/science/2003/ d.**heesbeen**/c5.pdf

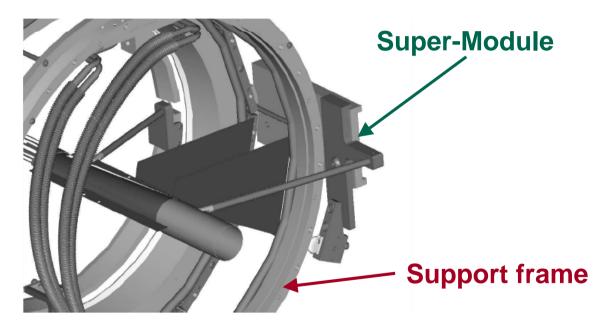


Figure 5.1: Computer aided drawing of the frame of the Lambda Wheels with one module installed for ease of reference. The lepton beam enters the tapered wake field suppressor from the left.





- Adaptation of the HERMES concept for the strip disks of the MVD (incl. additional forward disks)
 WHY?
 - Similar conditions
 - \checkmark R_{max} = 34 cm \leftrightarrow 28 cm (MVD)
 - Layer distance like for MVD
 - Sensor dimensions + pitch ~ $\frac{1}{2}$ size for MVD
 - Same number of frontend chips
 - Comparable global support concept: frame
 - Existing prototypes show feasibility of the concept! Details:

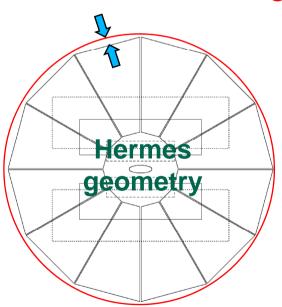
dissertations.ub.rug.nl/FILES/faculties/science/2003/d.heesbeen/c5.pdf

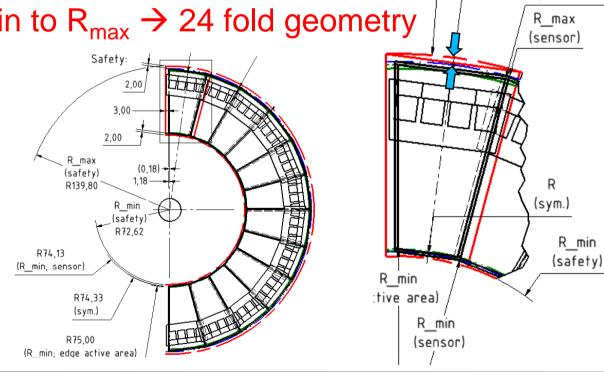




(active area)

- Adaptation of the HERMES concept for the strip disks of the MVD (incl. additional forward disks) (safety) What is different? R (sym.) R max
 - > Smaller margin to $R_{max} \rightarrow 24$ fold geometry

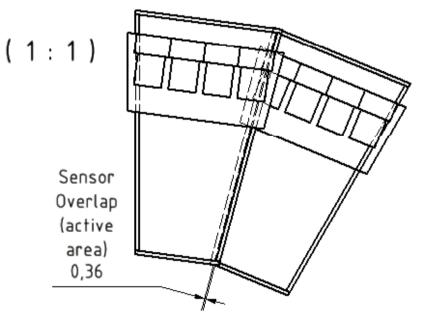




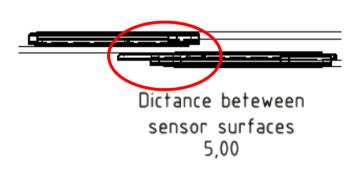




- Adaptation of the HERMES concept for the strip disks of the MVD (incl. additional forward disks)
 What is different?
 - Sensor overlap



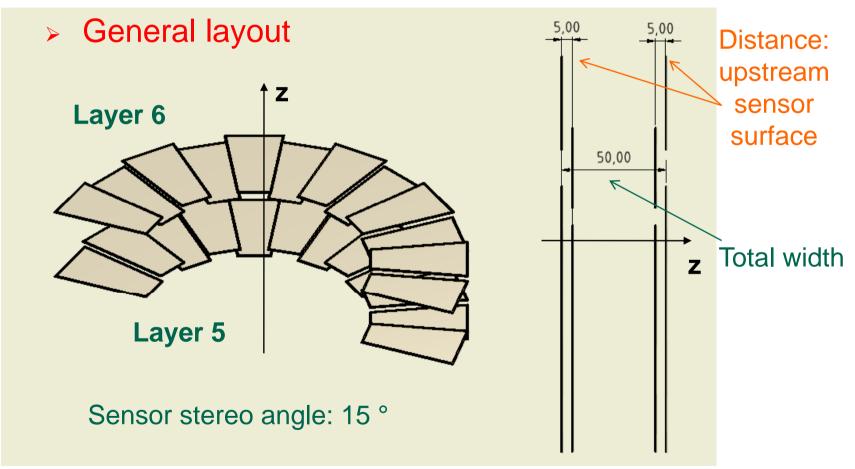
- → Shift of subsequent sensor
 - → Two different z-position within one disk layer







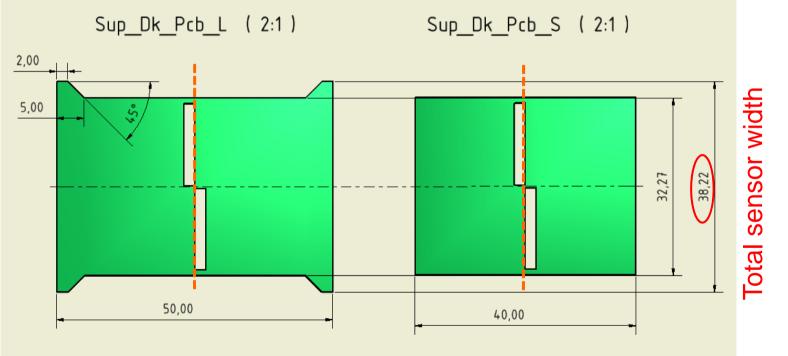
• Implementation of the new disk concept







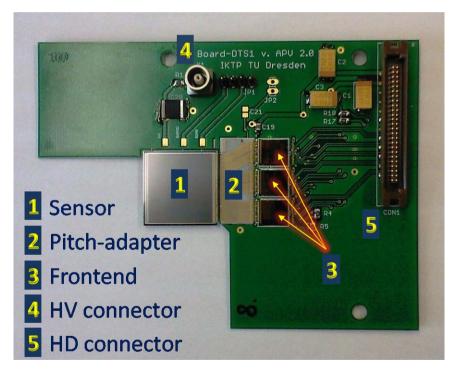
- Implementation of the new disk concept
 - > 2 carrier board with different shapes
 - Complete readout for both sensors
 - Later: Modifications for 1 carrier board / sensor possible







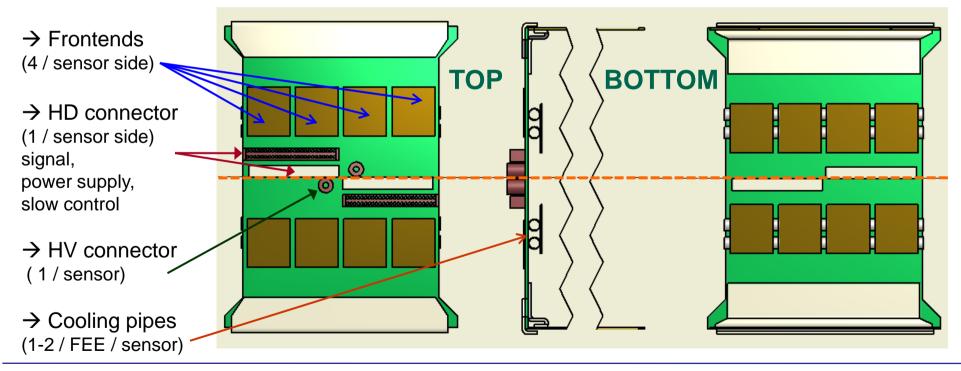
- Implementation of the new disk concept
 - > Equipped carrier boards
 - Master prototype: DTS L-board







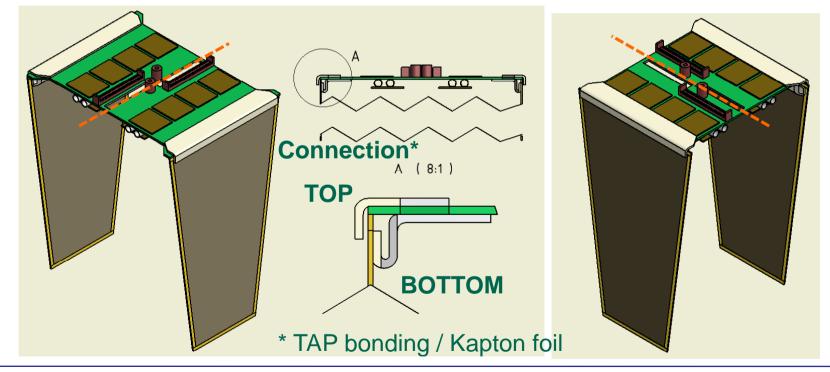
- Implementation of the new disk concept
 - > Equipped carrier boards
 - Complete readout for both sensors
 - Later: Modifications for 1 carrier board / sensor possible







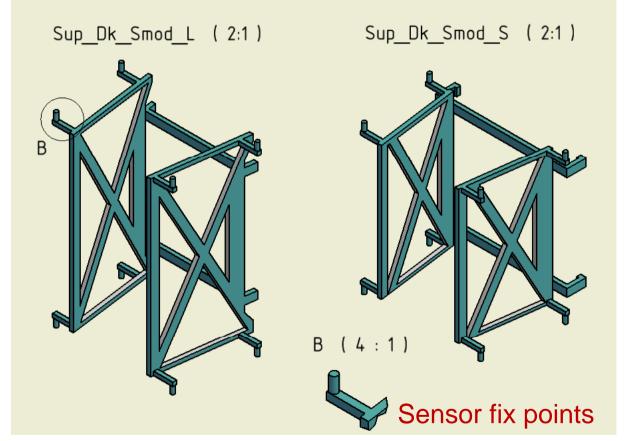
- Implementation of the new disk concept
 - Module: Equipped carrier boards + connected sensors
 - Complete readout for both sensors
 - Later: Modifications for 1 carrier board / sensor possible







- Implementation of the new disk concept
 - Support structure

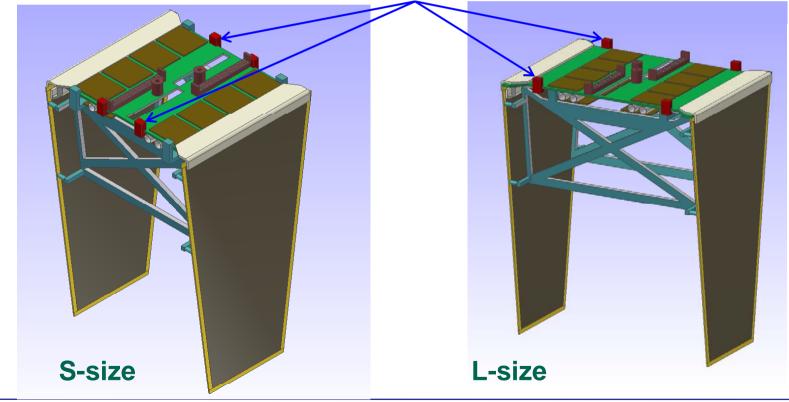






- Implementation of the new disk concept
 - Super-modules: Modules + support

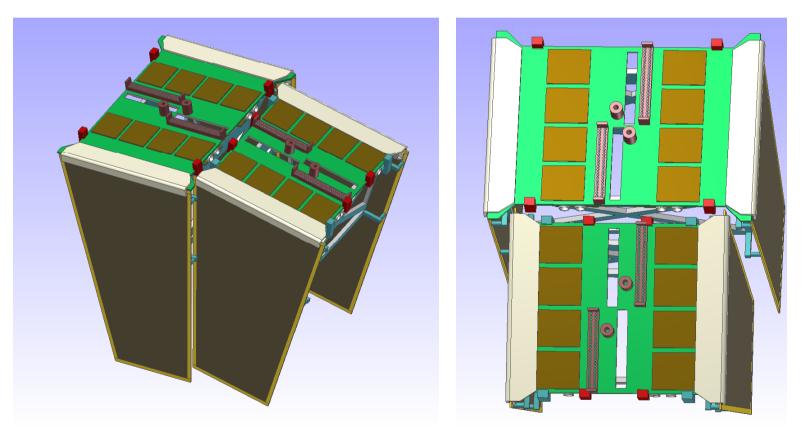
+ connection to global support







- Implementation of the new disk concept
 - Super-modules

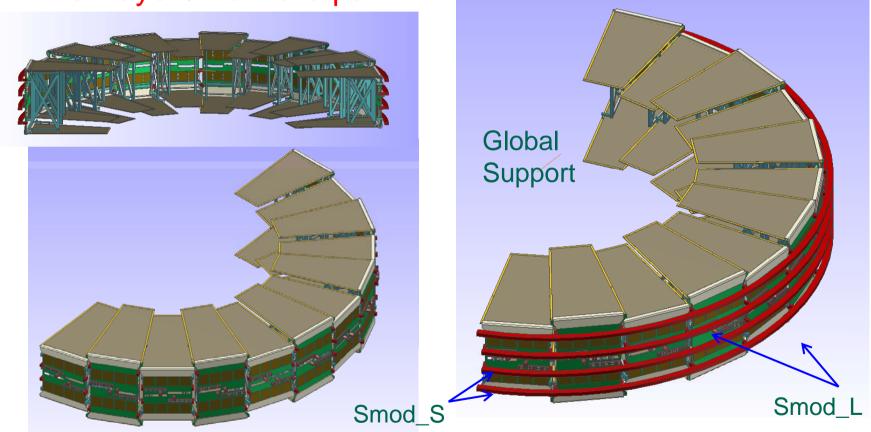






• Implementation of the new disk concept

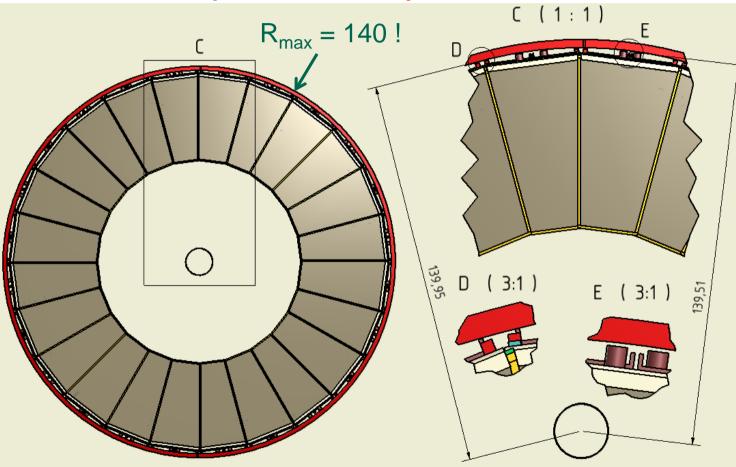
Disk layer / Forward part







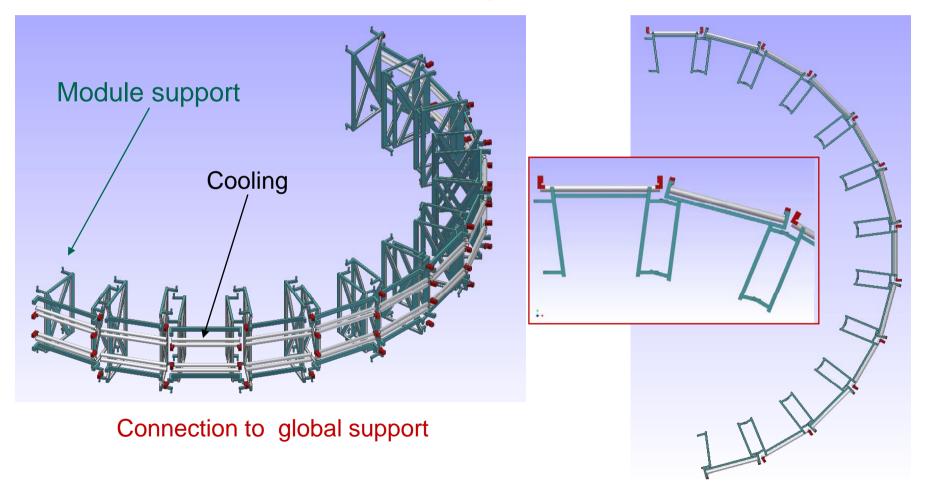
New disk concept: Boundary conditions fulfilled







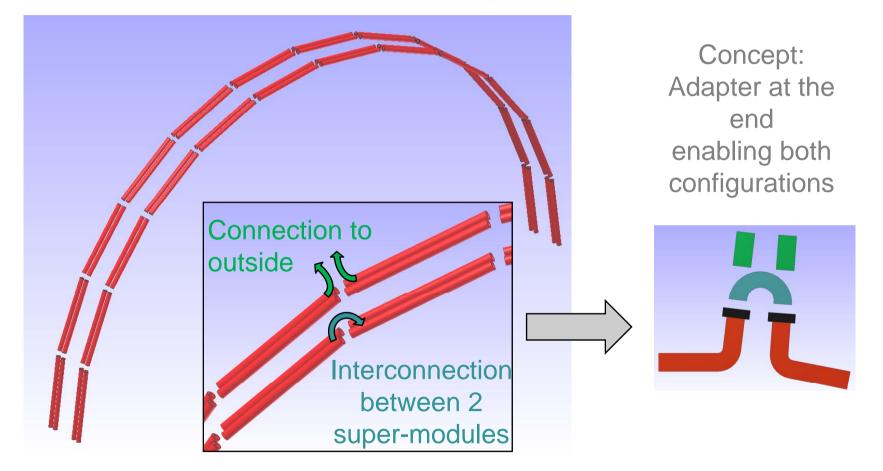
New disk concept: Cooling + support







New disk concept: Cooling







Summary and open items



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- Introduction of regularly MVD mechanics meetings
 - In-person meetings of at least 2 days
 - Very efficient and very important for coordination at the current stage of development
- Main topics at last meeting
 - > Pixel disks occupancy
 - Strip barrel design details and new strip disk concept
 - Cooling and integration items
 - Coordination of next steps
 - > Open questions and to whom to address
- Next meeting foreseen in Torino, April 2009







- Beam target geometry ...more details in Mechanics session...
 - > Axial position and aperture angle of cone (upstream)
 - Maximal angle < 21°
 - > Target pipe diameter
 - Clear definition inner / outer radius
 - Changes of section in the target pipe
 - > Upstream flange in front of CF
 - Axial position and size

... Meeting (at least 2 day workshop) with beam-target group and other groups involved **urgently needed** ...







Cabling

✓ More details on numbers and spatial occupancy

Cooling

- ✓ Water cooling sufficient everywhere, especially for pixel part?
 - → Best material for thin pipes is dependent on coolant!
- ✓ What about sensor properties when working around 30°C?
- ✓ Machining of thin pipes (\emptyset 2 mm):
 - Transforming a round shape to an elliptical one
 - Feasibility of bending \rightarrow bending radius

• Pixel super-modules

✓ Module sizes proposed in CAD models achievable?

