# CA package for MVD & STT tracking

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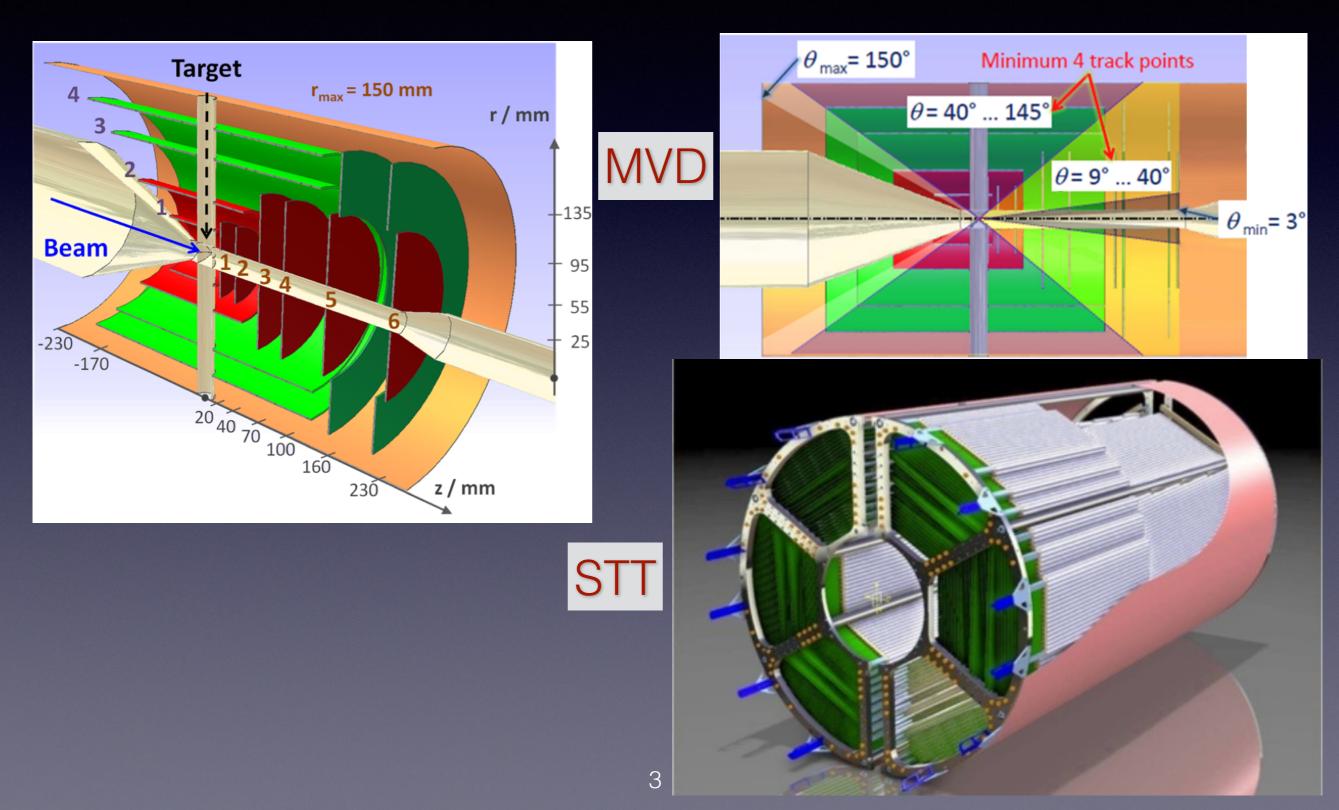


PANDA collaboration meeting Bochum, 1 March 2016

## Outline

- Introduction
- Cellular Automaton tracking
- Current Status & Activity
- Forward & Barrel Tracking
- Outlook

### Introduction



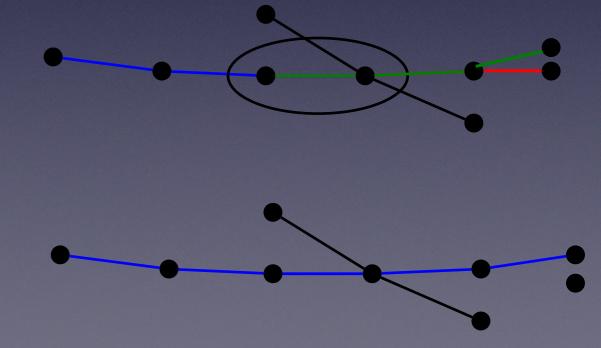
### Cellular Automaton Tracking

- \* Input/Initialisation
- \* Tracklet construction \* Parameters
  - = Singlets

Kalman Filter

- Doublets
- **Triplets**
- \* Evolution
  - Neighbour Search
  - Track Construction
- \* Performance evaluation

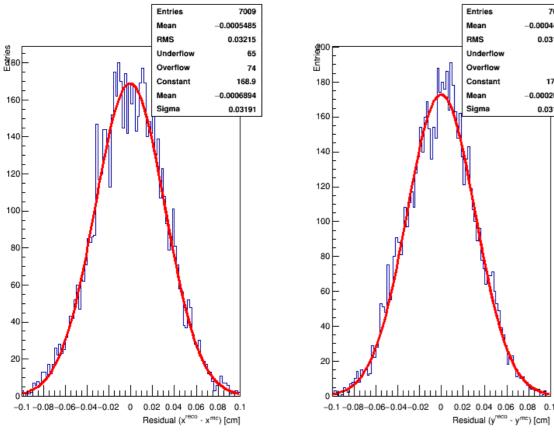
- Extrapolation (Runge-Kutta 4th order method)
- Update (using measurement information)

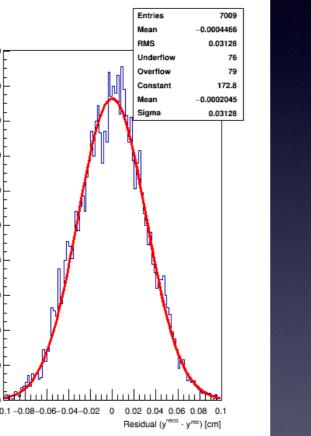


### Current status & activity

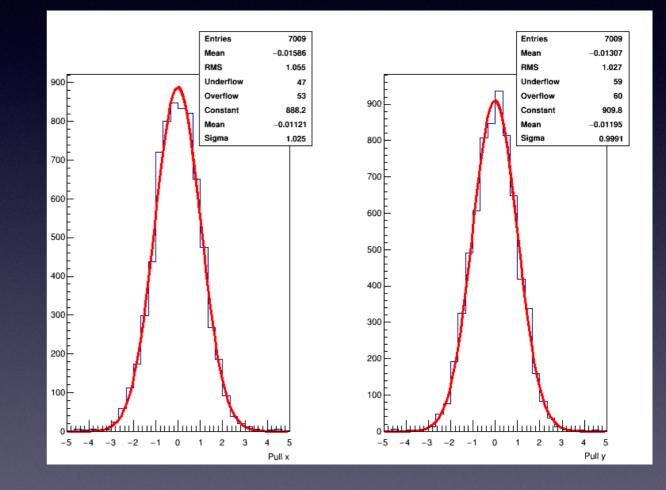
## Hits

#### Residuals





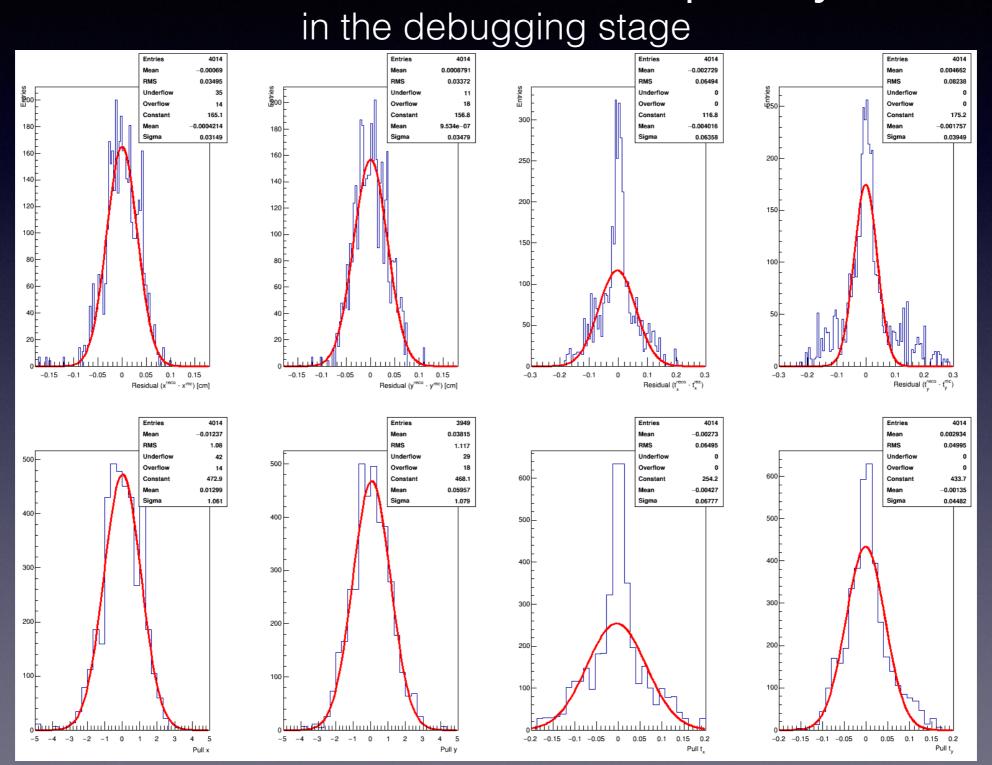
#### Pulls



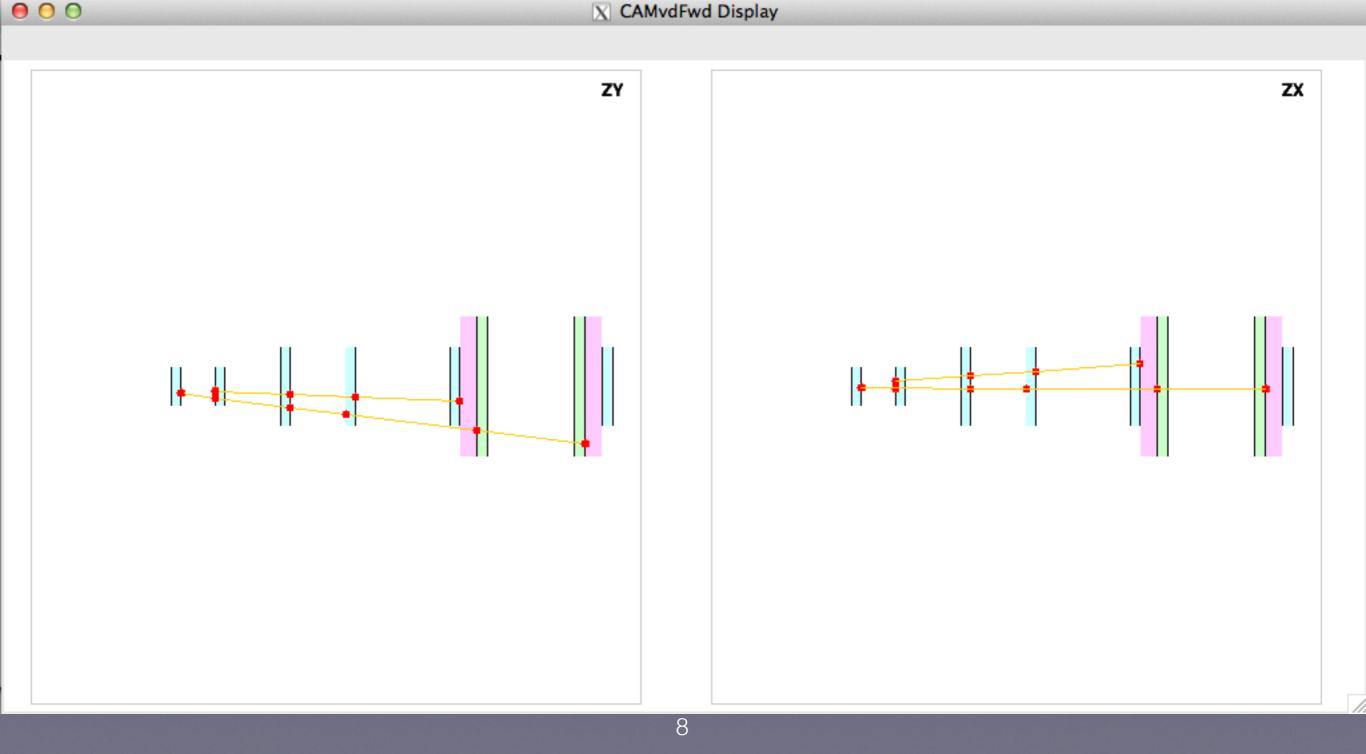
For debugging:

hits were simulated from a gaussian distribution with respect to mc-points

# Fit quality (reconstructed tracks with purity=100%)



#### Event Display Reconstructed Tracks



# Efficiency

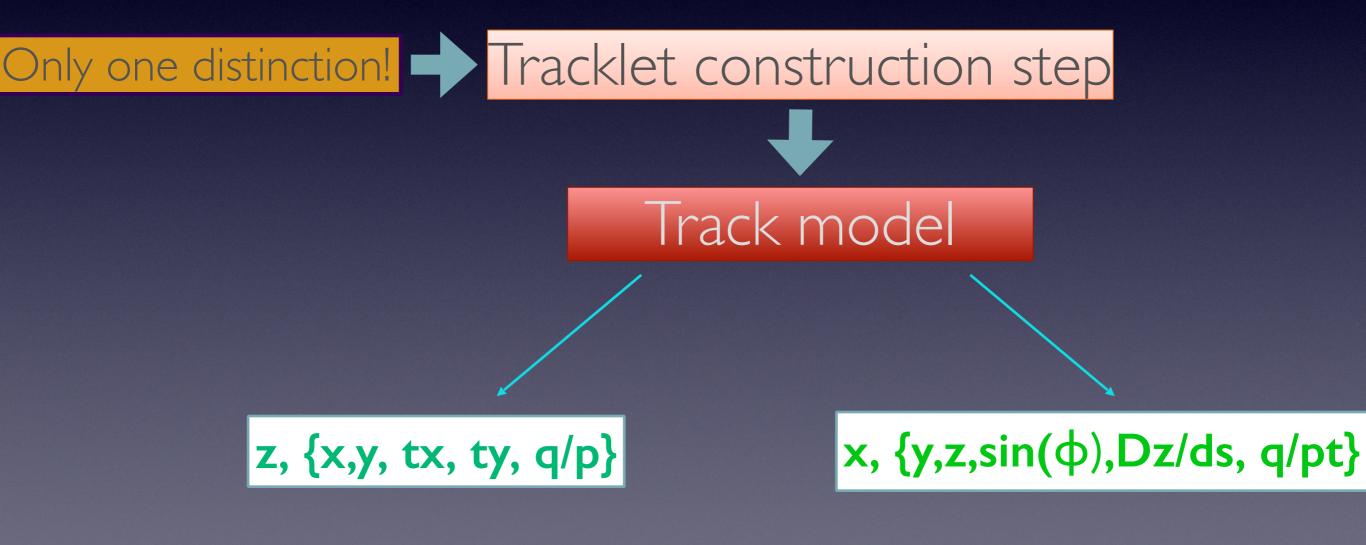
# 1000 events purity=100%

Reconstructable track: >= 3 consecutive MC points

	Efficiency,%	Ghost/ev	Clone/ev	Tracks/ev
triplets	100	12.5	9.5	1
track candidates	100	71.6	50.5	1
tracks	No selection yet because of KF debugging			

Forward & Barrel tracking

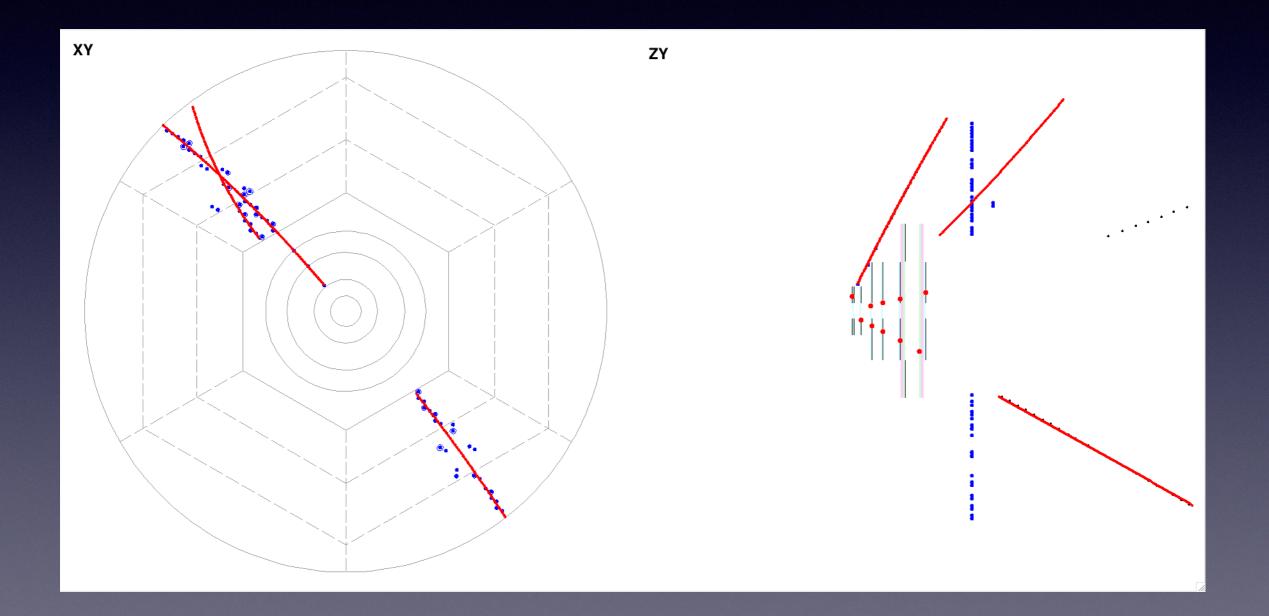
#### Forward & Barrel Tracking



#### Forward & Barrel Tracking

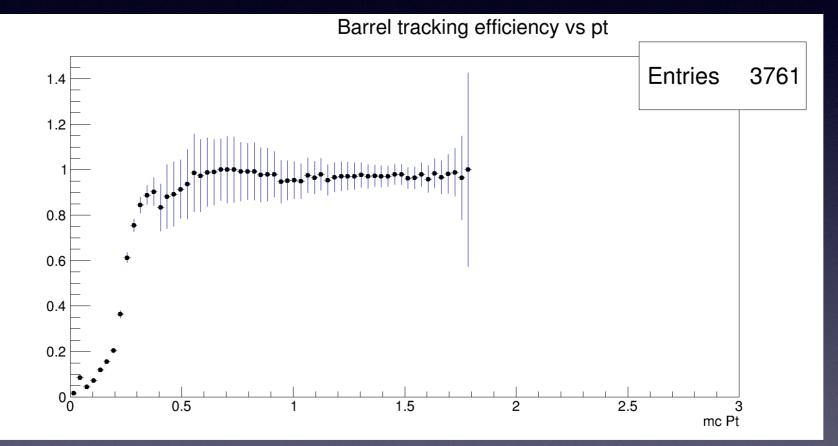
- Milestones
  - <u>Design:</u>
    - Final stages of reorganisation of the code-architecture.
  - Abstraction:
    - Making the Barrel&Forward code absolutely identical, implementing only the KF-part so that it is suitable for both track-models.

#### Barrel MVD+STT event



# Barrel part MVD+STT efficiency

primary MC tracks, >=5 barrel hits, Pt>.5



 Efficiency: ~ 97.0 %

 Fake rate:
 1.0 %

 Clone rate:
 2.0 %

## Outlook

- Debug the Kalman Filter track fit in the magnetic field
- Track reconstruction efficiency in the forward part of MVD
- Code vectorisation for faster performance
- Combined forward MVD + barrel MVD + STT tracking