

Pellet tracking system for PANDA is designed to provide:

- pellet positions ($\sigma \approx 0.1$ mm accuracy) at a hadronic event
- useful information for ≈ 90 % of the hadronic events

Design studies are described in the **PhD** thesis of **Andrzej Pyszniak**: *Development and Applications of Tracking of Pellet Streams* (January 2015) (see e.g. New_PANDA_Website Documents)

The tracking system is separated (geometrically, mechanically, electronically etc.) from target generator and target dump. In principle it can be used together with any target generator, but only

in "Pellet TRacking mode" operation it provides useful tracking info.

For pellet "Pellet High Luminosity mode" and for Cluster-Jet, it mainly could provide only stream (jet) position and time structure info.



Tracking system design



Two 40 cm long sections UPPSALA of the target pipe, one UNIVERSITET at the generator and one at the dump are reserved for tracking

equipment.



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Tracking section (TDR 2012). Design idea with 4 measurement levels, each with 2 lasers and 2 LS-cameras. Level spacing: 60 mm

cameras.

3 measurement levels at the pellet dump



UPTS pellet generator



UPTS provides a pellet stream according to PANDA tracking mode operation requirements.

($\Phi_{\rm stream}$ ≈ 3 mm, $\Phi_{\rm pellet}$ ≈ 25 µm, v ≈ 70 m/s, f ≈ 15 k/s, ...)

A PTR pellet stream with high availability and reliability is necessary for the continued preparation of the pellet tracking system ... but

... operation at TSL from 2016 is very uncertain

The UPTS generator, together with the WASA generator framework and dump, might become a suitable standalone target (test) setup



The WASA pellet generator in its support framework was removed from the WASA-at-COSY setup October 2015.



UPTS in operation. Visual inspection of pellets and pellet stream in the trackingdevelopment chamber (≈2 m below the pellet generator).(CM in June 2015).

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Pellet stream (and bouncing pellets) seen in the laser beams above skimmer.



Pellet stream ($\Phi \approx 2.5$ mm) in the tracking chamber



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UPTS pellet tracking development setup. Multi-camera readout prototype system



Information from the individual cameras.

Reconstructed pellet tracks.





First tests with six synchronized cameras at UPTS in a pellet run with the prototype CamControl readout (June 2015).

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Multi camera readout development

Multi-camera readout system

From project description by Andrzej Pyszniak (June 2015)



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Remaining work

- Continue synchronization of cards and cameras in pellet runs.
- Implementation in the PTR data handling and analysis software.
- Extensive complete tests with different multi-camera setups ...



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Prototype of integrated PTR measurement level module

Difficult to obtain the necessary alignment accuracy (< 0.01 mm) with independent camera and laser adjustment at the measurement positions (below).

Instead an integrated measurement level module that can be aligned externally and then be installed at the tracking section is being prepared (right).

Tests of first version were done in June 2015.

TDR 2012: Tracking section with lasers and LS-cameras mounted in independent holders.





Integrated measurement level with 2 lasers and 2 LS-cameras being aligned in a desktop setup using 5 fishing lines.





Connections between the Pellet tracking system and other systems (sub-projects):

System	Item	Status	
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Vacuum	Piping and pumping at upper yoke-pit.	Not clear.	
Vacuum, Physics, Accelerator	Vacuum at IP region. Need for more pumps at target dump.	Reduces pressure at least with 50% (Report by J.Löfgren, Apr 2014)	
Target dump, Vacuum	Pumps and piping in lower yoke-pit. Space for 3-layer PTR section. Access.	No draft design available?	
Accelerator	Beam size vertically \approx 5 mm for PTR mode.	Not clear. (Simple?)	
Pellet target generator	PTR mode operation ($\Phi_{stream} \approx 3 \text{ mm}$, $\Phi_{pellet} \approx 25 \ \mu\text{m}$, v $\approx 70 \text{ m/s}$, f $\approx 15 \text{ k/s}$,)	Parameters well known. (Std pellet target operation so far).	
Pellet target	Valves, pumps, skimmers, access space etc. just below the target generator.	No draft design available yet. Approximate space requirement for the PTR section itself is well known.	
Control, monitoring	Eventual usage of PTR info	Not started.	
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Fitting of the PTR system in the recesses in the iron yoke.

General comment:

The space needed for the actual PTR equipment is given in the TDR, i.e. for each section 0.4 meter height and 0.5 meter radially. This equipment fits in both the upper $(1x1.2 \text{ m}^2)$ and lower $(1x1 \text{ m}^2)$ rectangular shaped "pits". The PTR section will extend to ≈ 100 mm inside the yoke surface. (Then the pellet generator section can be placed at 2.2 m distance from the accelerator beam (≈ 0.85 m more distant than at WASA)).

In addition, space for installation, adjustment and access for fine-tuning/service during operation is required.

Some comments and conclusions from the model study (February 2013).

Pumps in the pit.

In the upper pit, bent pump pipes with angle valves (VAT S57 DN100) can be put in 2 quadrants. The space for each pump can then be $200 \times 200 \times h300 \text{ mm}^3$ (in quadrant corners). A 250-300 l/s turbo would fit geometrically in this space. The pumps can be removed when not needed. The flanges are at 250 mm above the pit floor and centered at 200 / 240 mm distance from the pit walls. The flange on the main valve (VAT S10 DN160) is at height 200 mm.

Installation of PTR section.

Mechanics for cameras and lasers should be attached and aligned before installation in the pit. The PTR section should then be attached to the target pipe. The access to the flange above the main valve (VAT S10 DN160) might be too difficult. If so the space can be increased by extending the PTR section a few cm.

Access to PTR components during pellet operation.

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PANDA CM RUB, Sept 2013 Hans Calén Fine-adjustment of cameras and lasers must be done with pellet beam. Then human access to the equipment is needed when the pellet generator and dump are in place (also for possibility to replace malfunctioning cams, lasers, LEDs ...).

This mainly concerns the design and configuration of equipment placed just outside the pits.

Camera electronics.

Might be disturbed by pumps and magnetic field. The closest distances of camera to yoke iron and of camera to pump are 200-250mm Cameras need air cooling (small fans may do the job)

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Space available for piping and "extra" pumps in the upper recess in the iron yoke.

Pump chamber for the cluster source

Place for 100mm pipes and angle valves in two corners? (Need h ≈ 250 mm at a few positions.) These pipes would be blinded during cluster source operation.

Sketch from Alexander Täschner's presentation at CM in Paris 2012-09-10







Photos of PTR yoke-pit model. 20130227



PTR status Panda CM Vienna November 2015 Hans Calén The photos show top views (from "upstream") of the paper model of the upper yoke pit (l=1200, w=1000, h=620 mm). Only the two lowest PTR detection levels (out of four) are included. Foam plastic blocks illustrate the sizes of cams and lasers. The full height of a detection level is $\approx 60 \text{ mm}$. The shaft of the main valve (VAT S10 DN160) is seen down to the right. In the upper corners of the photos, angle valves (VAT S57 DN100) are seen. The flange is at position 200mm and 240mm from the walls and 250mm above the floor.



Space available in the lower recess in the iron yoke.

The PTR measurement level configuration for the lower section at the dump is not decided yet. The lower yoke pit will be slightly smaller (l =1000, w=1000, h=510 mm) than the upper one.

An arrangement of piping for "extra" pumps as the one shown below might be used.



The photo shows a side view (from "downstream") of the paper model of the upper yoke pit (l =1200, w=1000, h=620 mm).

Pipes and "CF90" flanges for pumps (in two alternative configurations) with the heights of the flanges above the floor are indicated.



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Summary of comparison between target related background conditions at WASA and at ANKE.

Target condition studies at COSY

		WASA pellet	ANKE cluster-jet
	Target beam size	Φ = 3.8 mm	Φ = 10 mm
	Target thickness	2 - 6 · 10 ¹⁵ at./cm ² (H ₂ ,D ₂)	$0.3 \cdot 10^{15} \text{ at./cm}^2 (\text{H}_2)$
	Pressure in scattchamber	pprox 10 ⁻⁶ mbar (modelled)	pprox 10 ⁻⁶ mbar (guess)
1	Background level expected from vacuum situation	≈ 0.01 % (H ₂)	≈ 0.05 %
2	Background level from event reconstruction	≈ 0.2 % (eg pp@0.5 GeV)	≈1%
	Results from COSY beam energy loss measurements:	May 2014, pd @1GeV	2004, pp @2.65 GeV (published 2008)
	Target thickness	58.0·10 ¹⁴ at./cm ²	2.60·10 ¹⁴ at./cm ²
	Thickness no target	0.12·10 ¹⁴ at./cm ²	0.14·10 ¹⁴ at./cm ²
3	Thickness rest gas expected background level	< "no target" value < 0.004%	0.07·10 ¹⁴ at./cm ² 0.02 %

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There are certainly differences between the pellet and the cluster-jet target situation but nothing very dramatic (or unexpected*) was found in this study. All 3 methods, give physics background levels that

are \approx 5 times higher for Anke CJT than for Wasa PT.

*) e.g. from experience at CELSIUS



Some features of the background condition measurements at WASA and at ANKE.

Target condition studies at COSY

	WASA pellet	ANKE cluster-jet
Geometry at interaction region Pumping of interaction region	Narrow cross. Accelerator pipe Φ =60 (Pellet pipe Φ =5). Upstr and downstr ≈ 1 m	Big box lwh=900x700x200 (Cluster pipe Φ =38). Direct (?) on the box
Vacuum measurements	in pellet pipe up/down and acc.beam pipe (scattering chamber) ≈ 1 m from IP	upstream of the scattering chamber
Background measurement i.e. event detection and reconstruction	External detection of photons and protons. Complete eta/pi0 production	Internal detection of single protons/deutrons. Single tracks
COSY beam energy loss measurement	Worked (despite small space in scatt.chamber)	Worked well

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The three type of measurements should be done at the same time or under same conditions. This was unfortunately not the case for the presented studies.

The measurement of background event level is higher than what is expected from both vacuum and acc.beam energy loss measurements. It must be understood why



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Comments on expected background conditions at PANDA from the measurements at COSY.

	Pellet (PTR mode)	Cluster-jet	
Basic parameters: Target beam size Target thickness	Φ = 4 mm 2 · 10 ¹⁵ at./cm ² (H ₂)	Φ = 4-15 mm (oval) 1 · 10 ¹⁵ at./cm ² (H ₂)	
Background expected at PANDA from just scaling up WASA / ANKE values due to 10x worse vacuum.	Bg event level 2% in vertex-z distr. <10% of target thickn. due to rest-gas	Bg event level 10% in vertex-z distr. ≈25% of target thickn. due to rest-gas	
Expectations from differences of PANDA with respect to WASA and ANKE			
Narrow cross. Accelerator and target pipe Φ =20.	Target pipe wider than at WASA (Φ =5). Good (?).	Target pipe tighter than at ANKE (Φ =38). Bad (?).	
Better skimming of the target beam at the generator.	Better catching of skimmed- off pellets and a second skimmer at the PTR section. Good !	A narrow oval skimmer should reduce the gas load with 65% compared to a std round one. Good !	
Better target dump.	Better pumping and maybe improved dump design (needs testing). Good !	Yes ? (Lack of knowledge about ANKE dump)	



Figure 9.2: Cross section of the Target Spectrometer with detector components in light gray. The target and dump lines are marked in red. The antiproton beam line, as well as the cluster-jet target and the target beam dump, is marked in blue. The dimensions are given in mm. The diameters refer to inner diameters of the tubes.

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PANDA vacuum



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Pumping capacity cases. (The TDR case is given for reference only).

Pumps	TDR	LOW	NOM inal	EXTRA
Generator	720 l/s	2650 l/s	4000 l/s	
Dump	-	1000 l/s	1000 l/s	NOM+500 l/s
Upstream	2000 l/s	1000 l/s	1500 l/ s	
Downstream	1400 l/s	500 l/s	3000 l/ s	

Vacuum pressures for different cases compared to the case with nominal (WaC) pumping capacity.

Cases	Upstr	IP	Downstr
NOM inal pumping WaC	1.8e-6	14.e-6	0.05e-6
EXTRA 500 1/s pump at dump	42 %	43%	45%
LOWer pumping capacity	150%	112%	640 %
Narrow forw pipe L=23->77 cm	102%	106%	50%

- It seems difficult to influence the pressure at the IP dramatically with the present pump configuration.
- The vacuum upstream and downstream is just proportional to the pumping capacity there.
- The upstream pressure is higher since there the gas is pumped away.



• Good pumping in the target pipe is most important.

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Pellet target modes of operation

PELLET TRACKING (PTR) MODE:

-Useful tracking information available for most interaction events

PELLET HIGH LUMINOSITY (PHL) MODE:

- High and even target thickness for highest luminosity



UPTS Pellet Generator ... something for PANDA

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Background study at WASA pp-> pp π^0 run (π^0 -> $\gamma\gamma$)



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WaC Pellet vacuum



PANDA pellet tracking

Project planning and status (November 2015)

Ongoing: Multi-camera r/o and control being tested. Measurement level module prototype being tested.

Time line: Need for new funding to start the preparation of the main part of the equipment. Then it may take 1-2 years if our expert personnel is available. Present funding (CTS see below) makes possible only the preparation of one (out of seven) detection module during 2015-16

Risks: Evaluation done (Autumn 2013 (TDR), Feb 2015 (SG)).

Funding:Running:SRC application 2015-18 rejected Nov2014.No new try !HPH2020 application rejected New try in 2016?

Equipment: KAW application was (strongly) rejected Oct13. CTS appl. (30k€) approved Nov 2014 !

SG comment: "Funding remains an open problem"

The pellet tracking project is not in the PANDA cost book and it is not a Swedish FAIR in-kind contribution. It can therefore not get part of the dedicated SRC support for PANDA. We see no possibility for substantial financing at present.

Project plan for the pellet tracking system developments 2015-2018

Jan 2015



(pers=personnel, eqpt=equipment, cons=consumables, eng=engineer, res=researcher, UPTS=Uppsala Pellet Test Station, TSL=The Svedberg Laboratory, UU=Uppsala Univ., JU=Jagiellonian Univ., EC=European Commission, HP3=Hadron Physics 3, SRC=Swedish Research Council, CTS=Carl Tryggers Foundation)