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#### **Readout of the PANDA Electromagnetic Calorimeter,**

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### Pulse Detection: Pulse

- Baseline of the signal is continuously subtracted
- Once signal crosses detection threshold, samples are collected in a buffer until signal drops below threshold/4 (one pulse before detection threshold and one sample after end-of-signal threshold are included into the buffer)
- Pulse is detected if:
  - Number of samples in the buffer (waveform length) > min\_wf\_length
  - Number of samples in the buffer
  - Ratio Int/A (pulse area over amplitude)
  - Ratio Int/A (pulse area over amplitude)







#### **Pulse Detection: Pile-up**

#### Pulse pile-up is detected if:

Number of samples in the buffer
 OR

- > pileup\_wf\_length
- Ratio Int/A (pulse area over amplitude) > pileup\_IA

#### If pile-up is detected complete waveform is sent do EMC DC

Hint: if it is necessary to look at waveforms for debugging, set pileup\_wf\_length = 1

(all pulses will be treated as pile-up)

Hint: In waveform mode it is possible to request RAW ADC data (before subtraction of the baseline)





#### Pulse Detection: long pulses

**ADC** samples after base-line subtraction



Integration includes: one sample before Th\_d till last sample above Th\_d/4 If pulse has long tail it might become difficult to discriminate pile-up

#### MWD Filtering Pulse-Length reduction

Short Moving-Window Deconvolution is useful for shaped pulses as well



### **Dual-Gain Readout**

Pulse-detection is independent on **High** and **Low-gain channels**:

- Algorithms have different threshold but all other detection parameters are the same for each high- low-gain pair;
- If pulse is detected in both High and Low-gain channels then: if High-gain signal is close to clipping (ADC\_MAX\_VALUE-300), the High-gain hit is discarded, otherwise the low-gain hit is discarded
- It is possible to enable only high or low-gain hit data
  - in this case the clipping threshold has no effect;
  - effective for both hit and waveform data

## **Calibration and Combining**

Hit-data can be "calibrated" at the data concentrator:

- Calibration is linear: E = a + b\*ADC\_value
- Output is unsigned 16 bit data
- Calibration constants are different for high and low-gain channels

After calibration data from two photosensors (reading out same crystal) can be combined:

• "Combining" map is hard-coded:

channel #X at the DC input #0 is combined with channel #X at the DC input #1

- If pulse-amplitude of both hits is close (difference < 50%) average of energy and time-stamps are taken; new hit is marked as combined data
- Else, both hits are passed with corresponding flag-bit

# Calibration and Combining (in action)

Not combined hits (sigma for both channels ~12)



Same effect observed for the time-difference distributions

#### Precise Amplitude Measurement



Measured "maximum value" is always smaller than the pulse amplitude:

 Difference depends on pulse phase (fraction) between start of the pulse and phase of sampling clock

#### Correction for "Maximum"



#### Time Measurement



Time stamp: zero-crossing (linear regression) Analogue-like implementation:  $CFT(n) = MWD(n-d) - R \cdot MWD(n)$ 

- Delay d = signal rise time
- Fraction R to select most linear part of the signal leading edge (R=1/4)
- *N* number for the linear regression
- Symmetry against zero level

Linear regression induces some error in the time measurement

#### **Time-Stamp Correction**

- A correction LUT is calculated using measured waveform
- Correction is performed at the data concentrator
- There is one LUT for one DC (channel-to-channel pulseshape variations can not be corrected)



### **Correction in Action**



#### EMC Readout from the point of view of a user

#### Labview GUI

#### Small systems with one data concentrator can be controlled with GUI



# **CLI for Complex Systems**

The CLI package allows to control systems of any complexity:

mc [mykavats@kvis40	]:~/0_Work/PANDA_EMC/ProtoPD/	AQ2/Control	-
<u>File Edit View Search Terminal Help</u>	0		
mykavats@kvis40:Control\$ l			
bin C_src etc log root sr	c		
mykavats@kvis40:Control\$			
<pre>mykavats@kvis40:Control\$ l etc</pre>	/		
EMC_parameters.txt EMC_thresh	olds.dat readout_topol	ogy.txt	
mykavats@kvis40:Control\$			
mykavats@kvis40:Control\$ l bin	/		
emc_acquire_WF.sh	<pre>emc_set_thresholds.sh</pre>	PR_set_EMC_defaults	.sh
emc_reset_fibres.sh	<pre>emc_set_waveforms.sh</pre>	PR_status.sh	
emc_set_Calibrations.sh	lib_PR.sh	ss_StartDAQ.sh	
emc_set_Control.sh	PDAQ_Reciever_SB	ss_StopDAQ.sh	
emc_set_DCcontrol.sh	PR_clear_errors.sh	udp_SetDestination.	sh
emc_set_MWD.sh	PR_env.sh		
emc_set_thresholds_from_DB.sh	PR_init.sh		
mc [mvkavats@kvis4]	1:~/0 Work/PANDA EMC/ProtoPD	A02/Control	
File Edit View Search Terminal Hel			
mykayats@kyis40:Control\$ /bin	lome sot waveforms sh		
Nykavacsekvis40.concrots ./Din			
Isage · emc set waveforms sh F	 FF number [Channel]		
[wf length min] [w	f length nileun] [wf le	ngth max]	
[wf max size bo] [w	wf max size lol [cf de]	av]	C
Defaults:			
FFF number = -1 (all connect)	ed FFFs)		
(are connect - 1) (are connect)			
wf length min $-5$ (minimum a)	llowed wavelength)		

wf\_length\_pileup = 50 (length at which pulse is considered as pile-up)
wf\_length\_max = 100 (maximum length of a waveform)
wf\_max\_size\_hg = 0 (take waveforms for high gain of max length)

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wf_max_size_lg = 0 (take waveforms for low gain of max length)
```

cf\_delay = 3 (delay for\_constant fraction filter)

- Allows to set registers for all available FEEs or for selected channel
- Provides complete logging of changes
- Can be extended to control another SODANET compatible subsystems

All tools use **trbcmd** command-line tool – once PANDA run control is established should be rewritten to use **trblib** and standard DB 16

# SODANET Topology



#### **SODANET link**:

- Bidirectional
- Synchronous (only in one direction)
- Transfer:
  - <u>source</u> → <u>DC</u>: synchronization information and FEE configuration
  - <u>DC</u> → <u>source</u>: slow control, used for time calibration

#### Data link (DC → EB):

- Unidirectional Ethernet
- Link DC ↔ FEE:
  - Bidirectional, synchronous
  - Protocol up to subsystem

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- Sub-system identifier – used by shell scripts
- FPGA unique identifier used once to set TRB address
- TRB address used to access registers
- Seed for FEE unique ID (sid\_FEE)

Each EMC FEE is addressed by the input number at the DC (fibre\_numb)

**FEE\_id** = EMC\_DC\_id\_multiplier \* (sid\_FEE\*EMC\_DC\_Ninputs + fibre\_numb)

**ADC\_channel** = FEE id\*16 + channel#

#### Default Settings (etc/EMC\_parameters.txt)

If parameters are not specified directly for the command the default values from etc/EMC\_parameters.txt are been used



#### Default Settings (etc/EMC\_parameters.txt)

# emc_set_MWD.sh mwd_width=0 mwd_tau=1	Parameters of the MWD filtering. If mwd_width=0, filtering is off
<pre># emc_set_Control.sh reset_all=0 invert_inputs=0 clear_errors=1 enable_waveforms=1 channel_freq_meas=0 res_fpga_mon=1 fpga_mon_addr=0</pre>	Invert ADC inputs
<pre># emc_set_DCcontrol.sh enable_data_cn=1 enable_wfdata_cn=1 disable_packet_limit=0 source_mux_stat=0</pre>	Allow data flow to compute nodes
	Allow waveform-data flow to compute nodes

# **Typical Session**

Enter working directory (optional) > cd ~/Control Set shell environment ./bin/PR env.sh > . Initialize log file (log/daq.log) > ./bin/PR init.sh Sets TRB addresses to all devices Sets FEE id for all EMC FEEs > ./bin/PR set EMC defaults.sh Sets default values for all EMC FEEs and DCs. If compute nodes not used, sets destination for UDP packets > ./bin/udp SetDestination.sh 0x682346923 192 168 1 1 Starts data-receiving program on "DAQ" PC > ./bin/PDAQ Reciever SB root/data.root Enable data taking by FEEs > ./bin/ss StartDAQ.sh

> ./bin/ss\_StopDAQ.sh

### **Additional Tools**

- On-line monitoring of incoming data:
  - Waveform data
  - Hit data
  - For all available ADC channels, or only for selected
- Automatic tool which collects given number of (raw-data) waveforms from all available ADC channels (high and low gain), calculates noise level, deduces thresholds (in terms of multiple of RMS value), stores new threshold values in DB (ASCII) and sets values to all available FEEs
- Root macros which allow:
  - Calculate threshold values from given waveforms
  - Calculate correction LUTs (amplitude and timing)
  - Simulate feature-extraction algorithms on waveform data

# Summary

The EMC readout is ready for non-expert operation and should be used by different groups to find possible bugs

Some parameters should be optimised for different amplifiers:

- Energy measurement by amplitude or integral?
- What is the best MWD filtering?
- Is pulse-shape stable enough to benefit from correction LUTs?
- What are the optimal hit-detection parameters
- Can "hits-combining" be used to decrease hit-detection thresholds?

Optimisations should be done using measurements with EMC prototypes and simulations (simulation root macro is provided)