

# Status of the Electrical Installation and the Operating Principle of the $\bar{P}$ ANDA Cluster-Jet Target's PLC

**Benjamin Hetz**

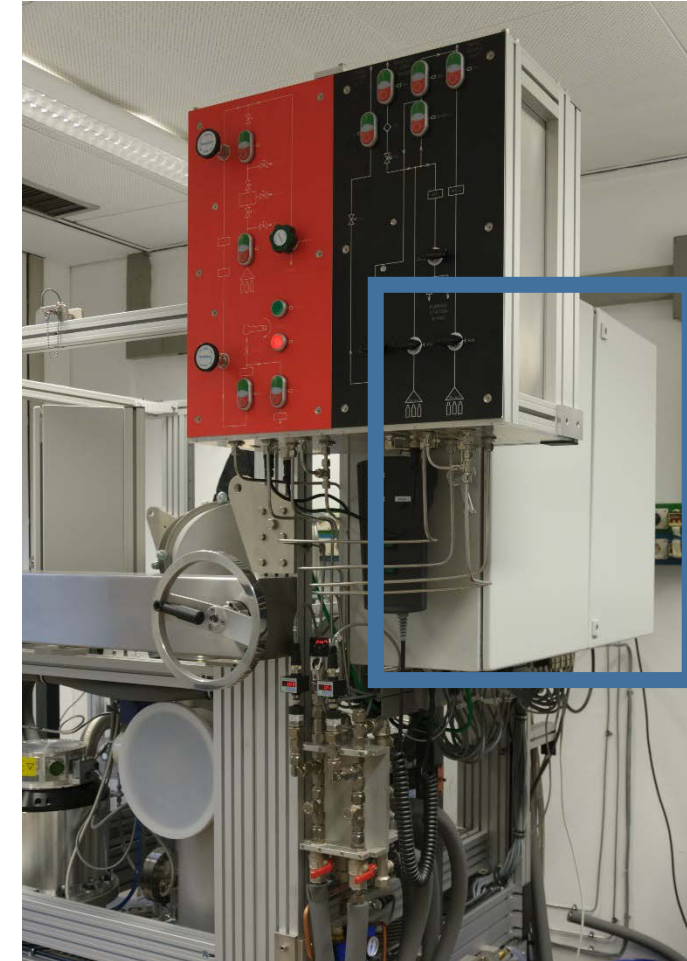
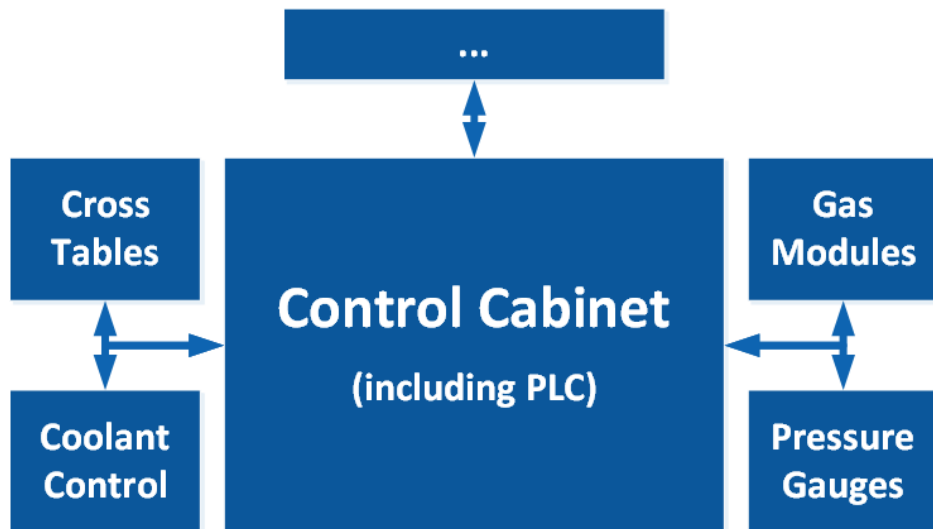
Westfälische Wilhelms-Universität Münster, Institut für Kernphysik

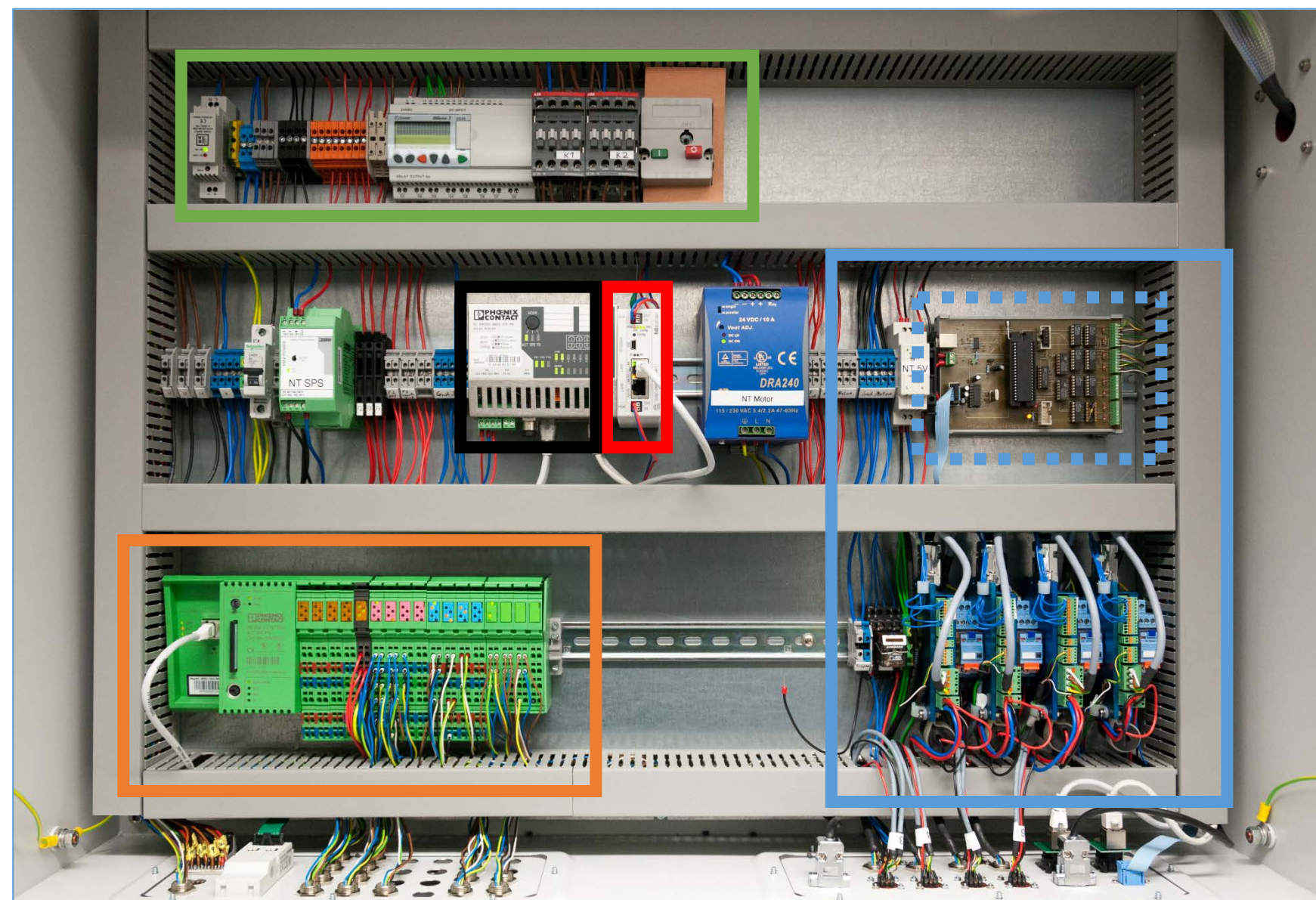
PANDA LIV. Collaboration Meeting Darmstadt, September 8th 2015



Neat new gadgets we have:

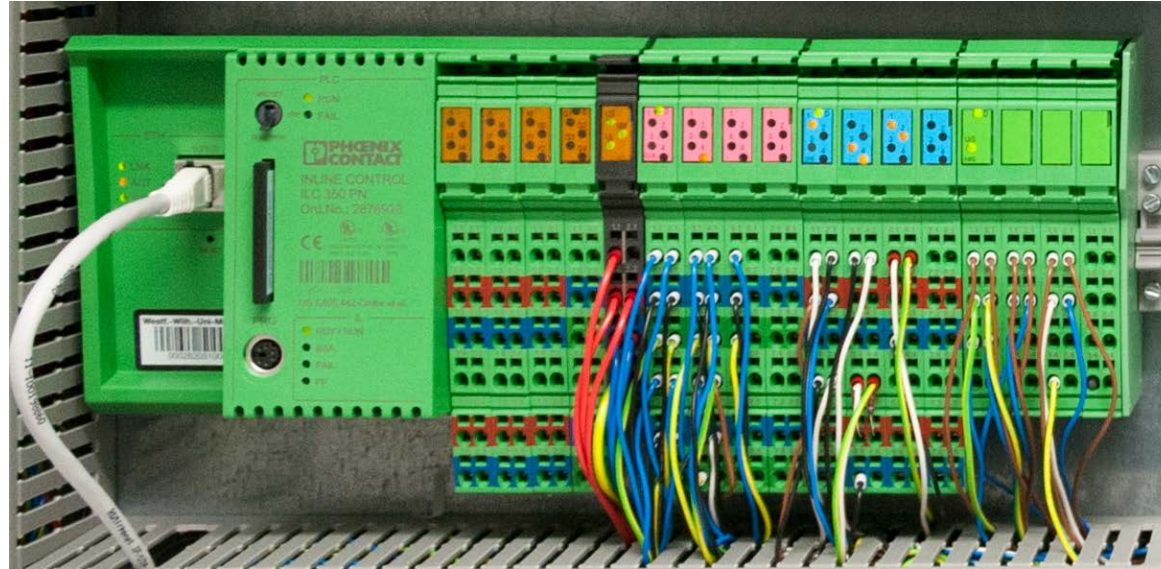
- Hitherto just e-mail messages from the target
- Uninterruptible Power Supply
- UMTS modem
- ✓ Our target can now message us on our mobiles during a power failure, critical errors ...
  
- Electrical installation mostly done on target frame side
- Electrical installation of 19" rack cabinet is ongoing
- Skimmer and collimator cross tables are controllable
- PLC putted into operation
- All valves controllable via the (preliminary) Slow Control and the gas modules



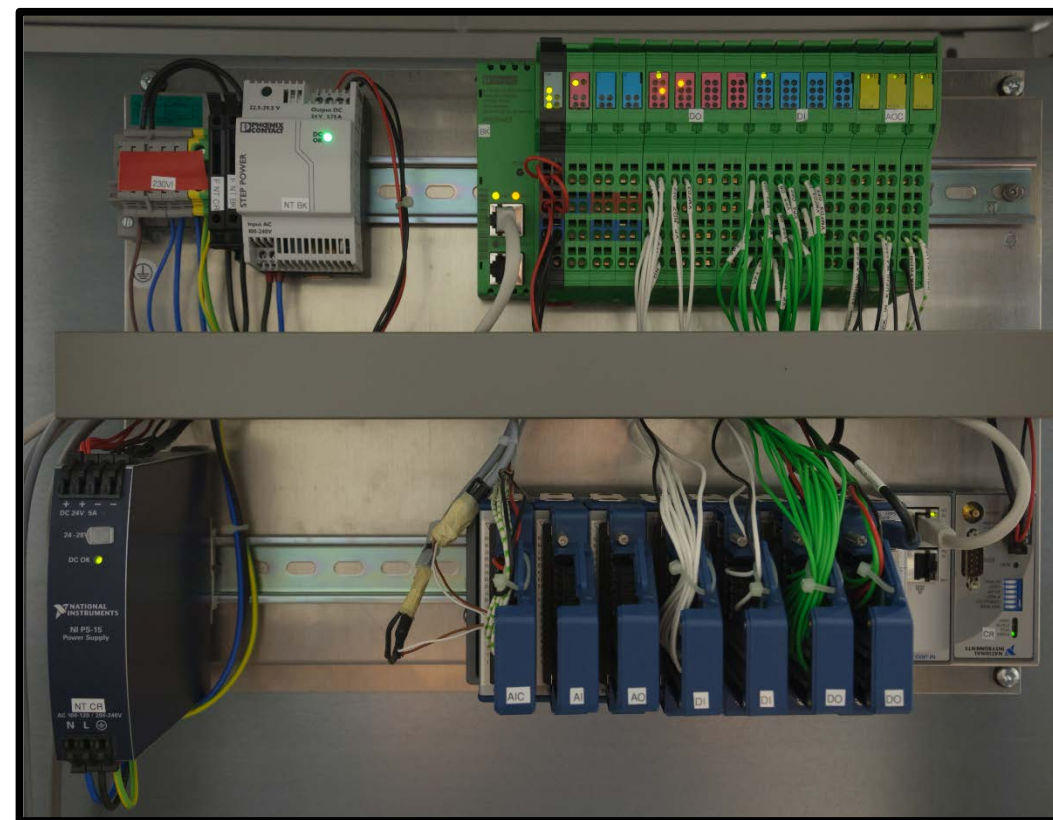


- automatic lifting system
- skimmer and collimator cross tables control
- absolute rotation encoders (dotted)
- gas modules-PROFIBUS gateway
- main PLC
- PROFIBUS gateway



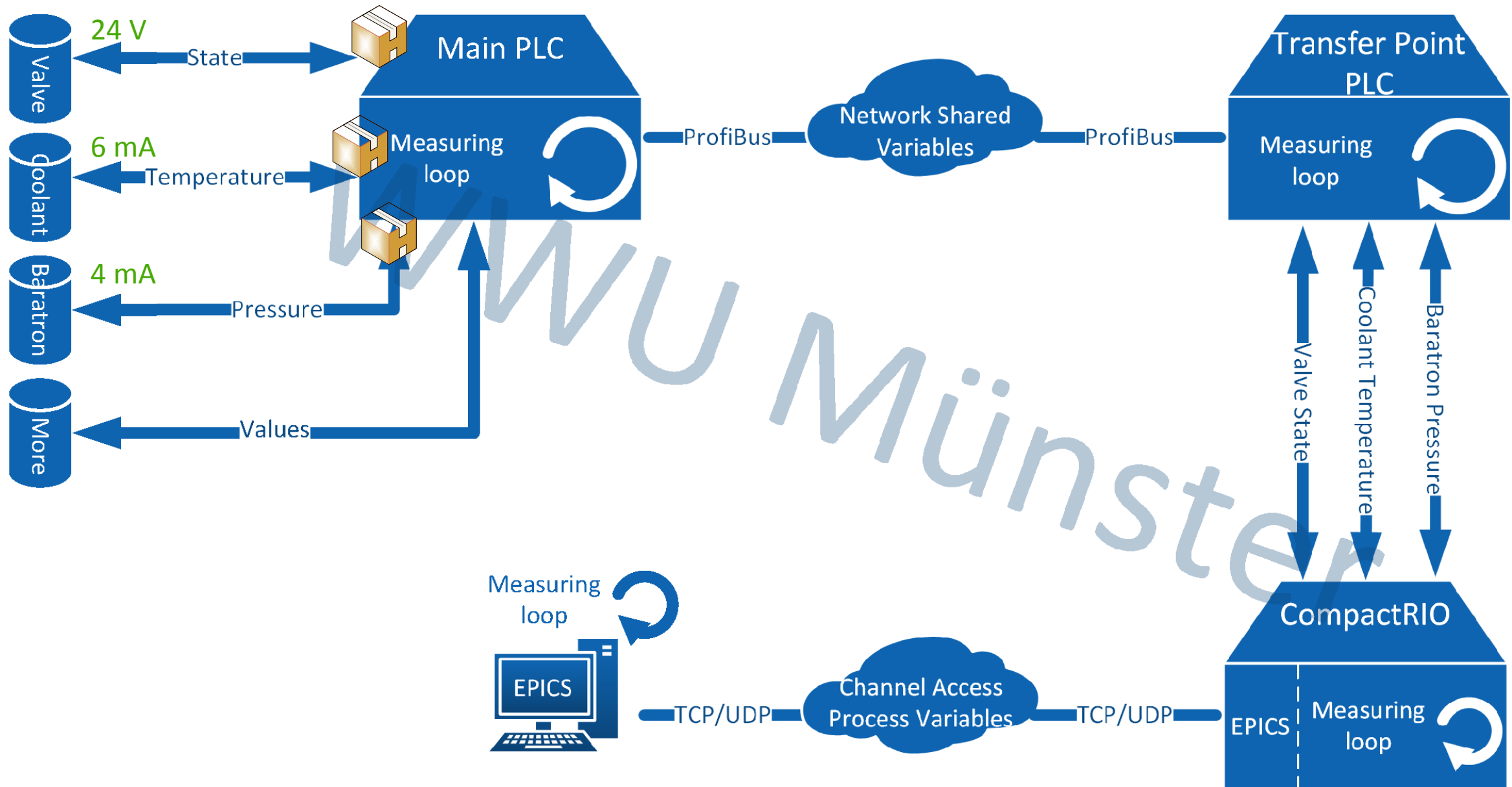


- **Digital Outputs** (0V/24V): Open valve - close valve (pulsed), ...
  - **Digital Inputs** (0/24V): Valve states (open/closed), ...
  - **Analogue Lines** (4-20 mA): Coolant Temperature, Pressures, ...
- Every measurement is given as an voltage/current value to the main PLC inputs. Same is done for the PLC outputs
    - No need to care about protocol details
  - Every measurement is digitized by the main PLC and is then also accessible by the transition point PLC

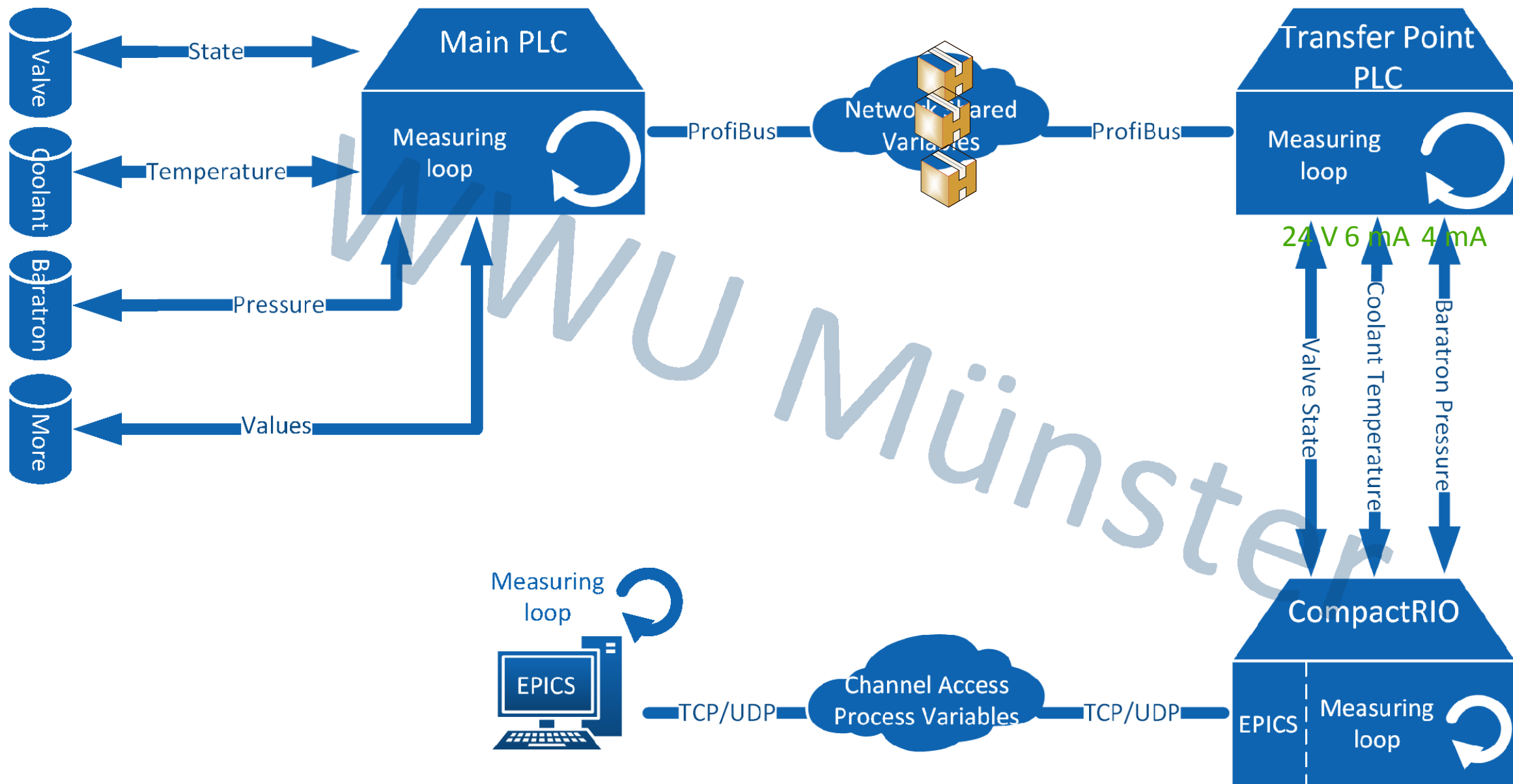


- Transition point PLC is connected/synced via PROFIBUS with the main PLC
- Transition point PLC is mirroring main PLC inputs/outputs
- Every PLC output is directly connected to a CompactRIO input and vice versa
- CompactRIO is just reading/writing analogue/digital signals

# Reading Measurement Values from the PLC

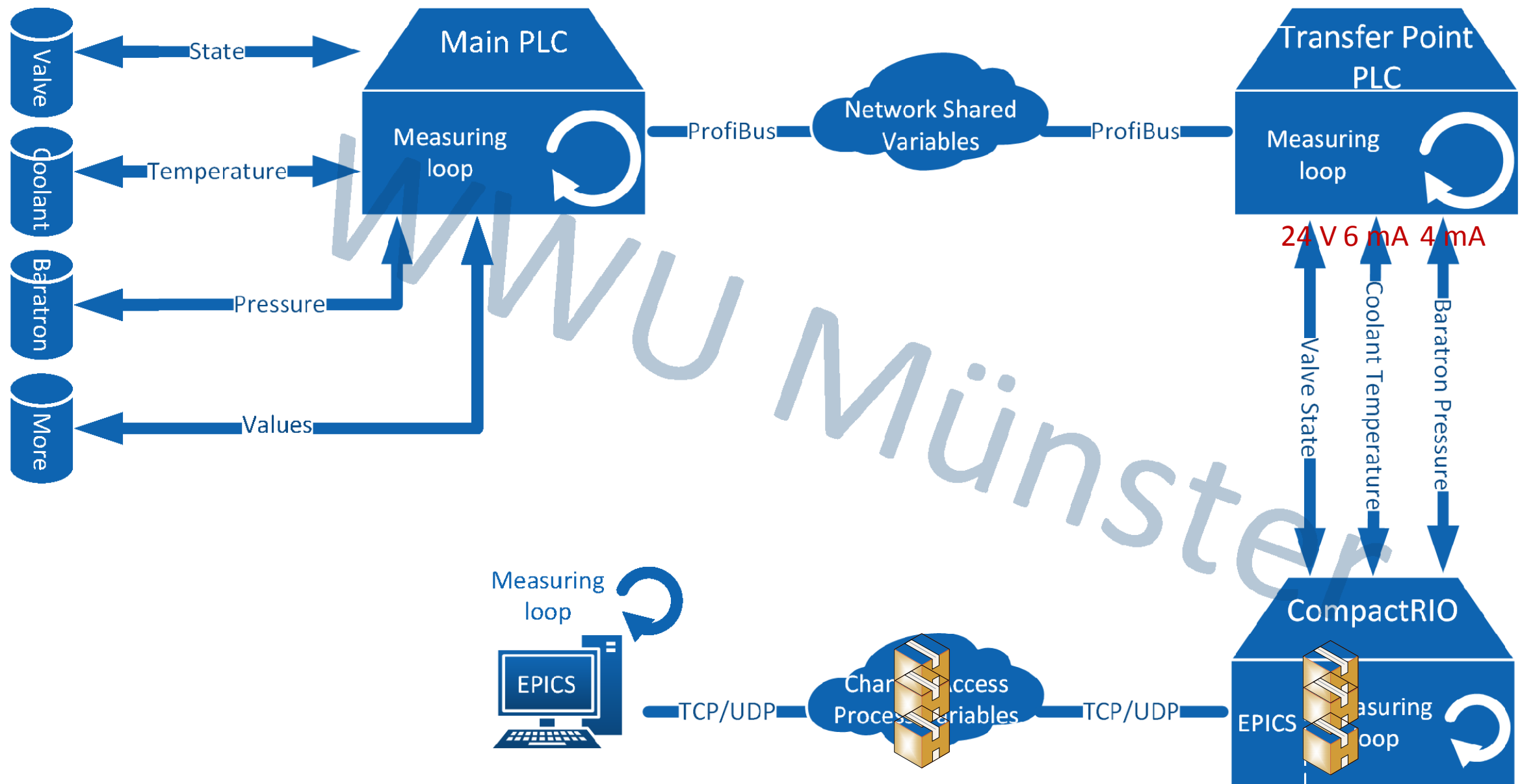


# Reading Measurement Values from the PLC

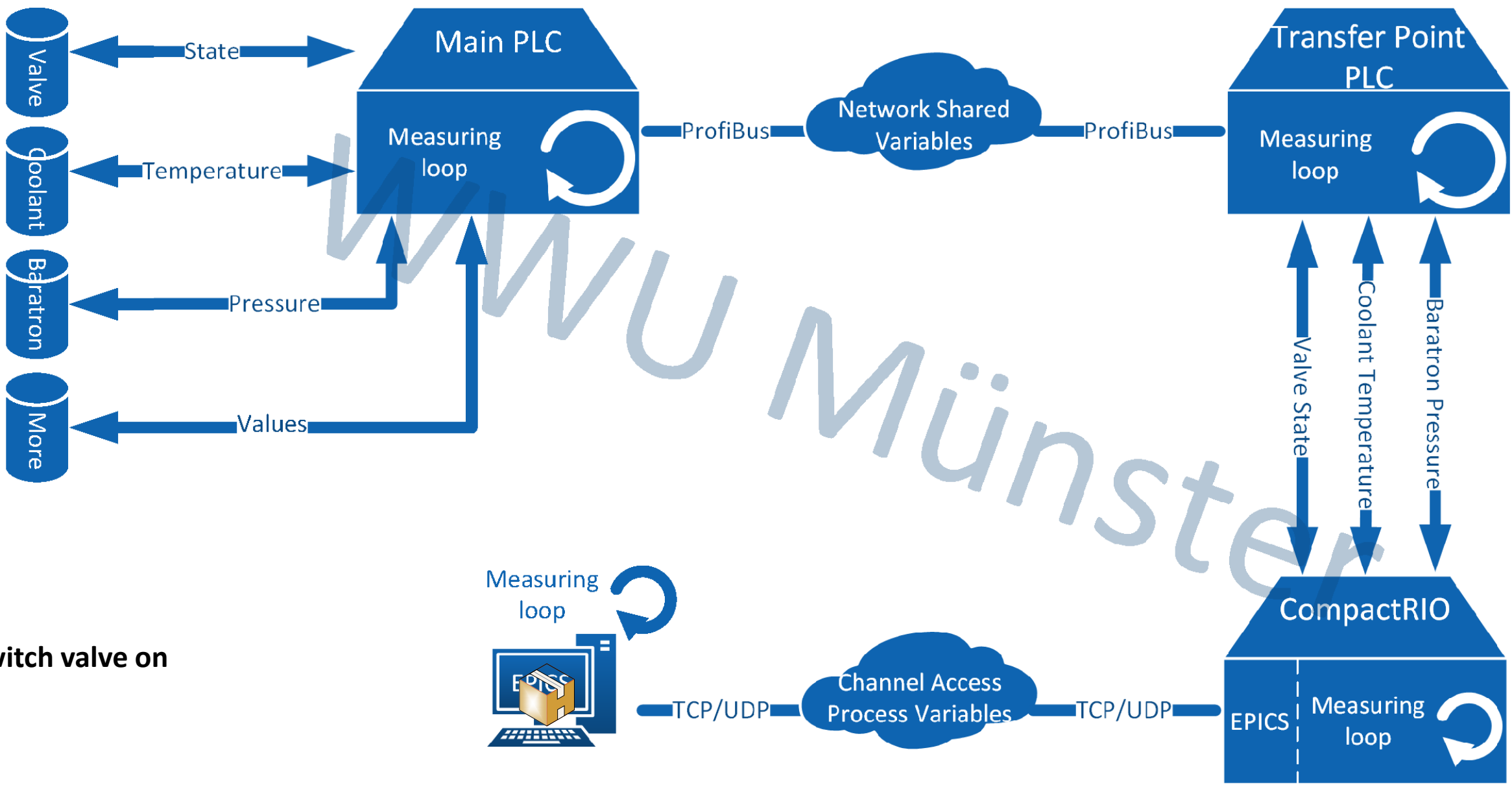




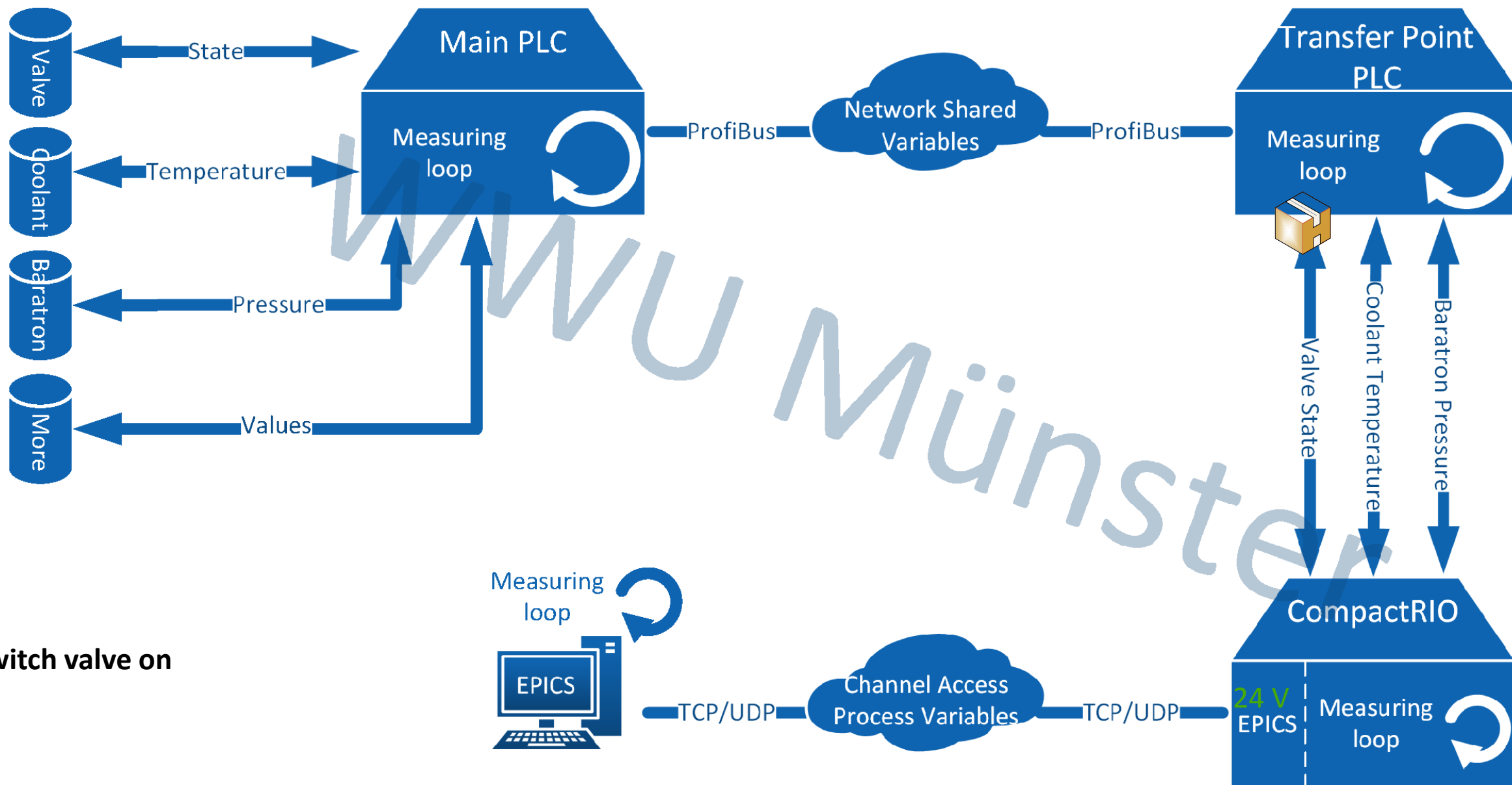
# Reading Measurement Values from the PLC

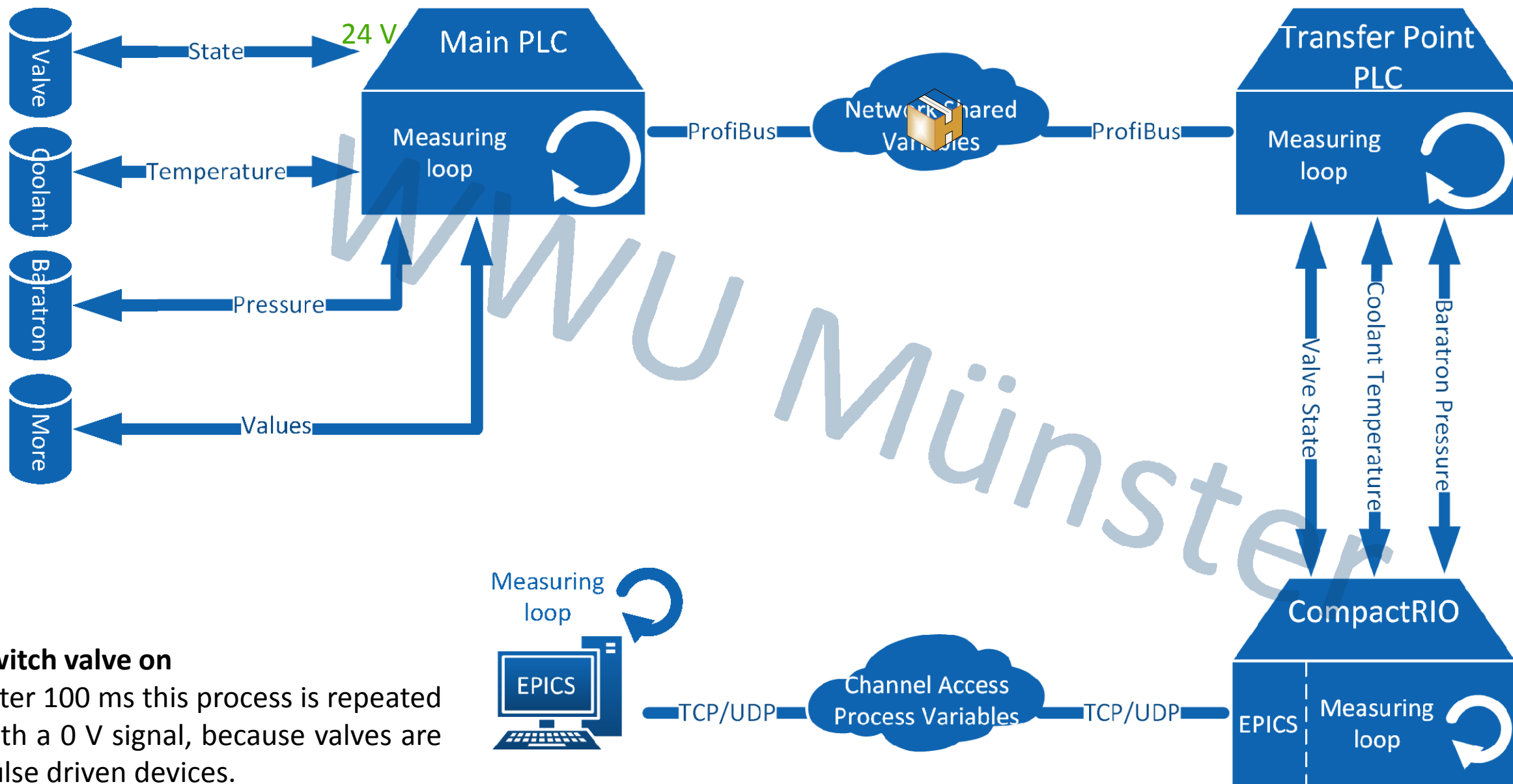






**Switch valve on**





## Switch valve on

After 100 ms this process is repeated with a 0 V signal, because valves are pulse driven devices.

# NI CompactRio-9074

400 MHz, FPGA, 128 MB Ram, 512 MB Hard Disk, 1 RS232, 2 x 100 Mbit/s Lan Connectors

NI-9208  
16 (4-16 mA)  
Channels

CI

NI-9205  
16 (24 V)  
Channels

AI

NI-9264  
16 (24 V)  
Channels

AO

NI-9425  
2 x 32 (24 V)  
Channels

DI1 DI2

NI-9476  
2 x 32 (24 V)  
Channels

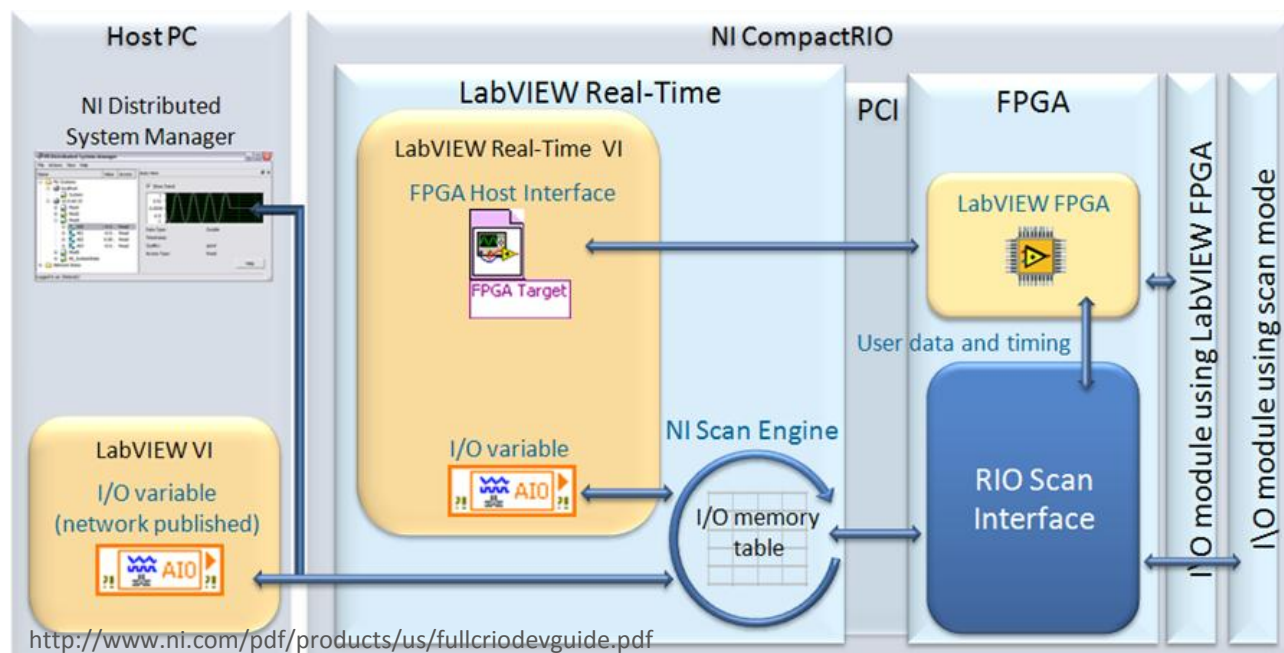
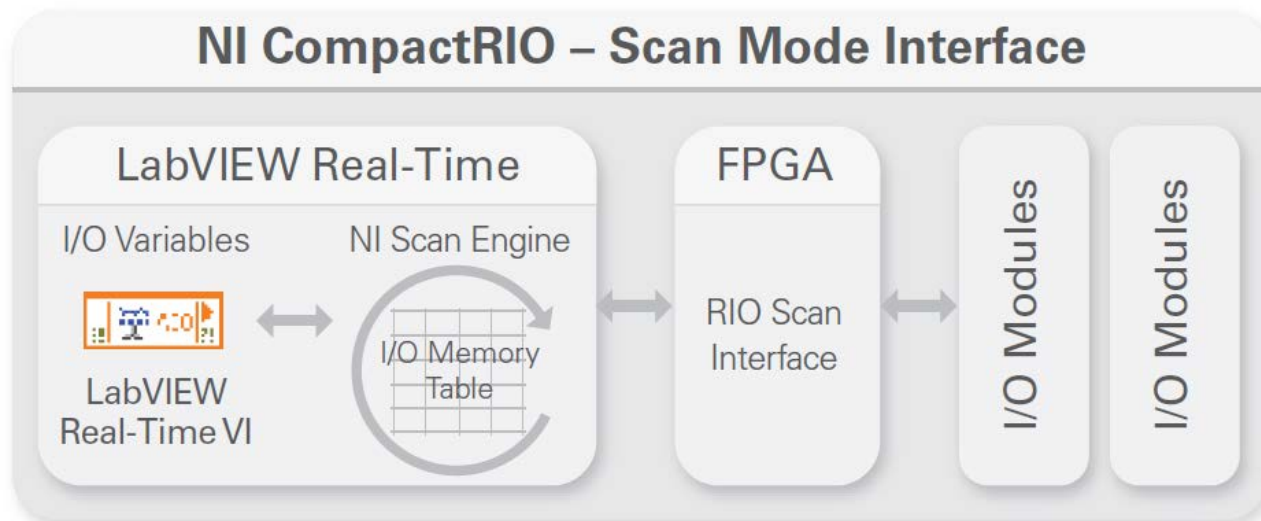
DO1 DO2

NI-9871  
4x RS485

RS485







Different programming modes:

- Direct FPGA programming
- Scan Mode

Rule of thumb:

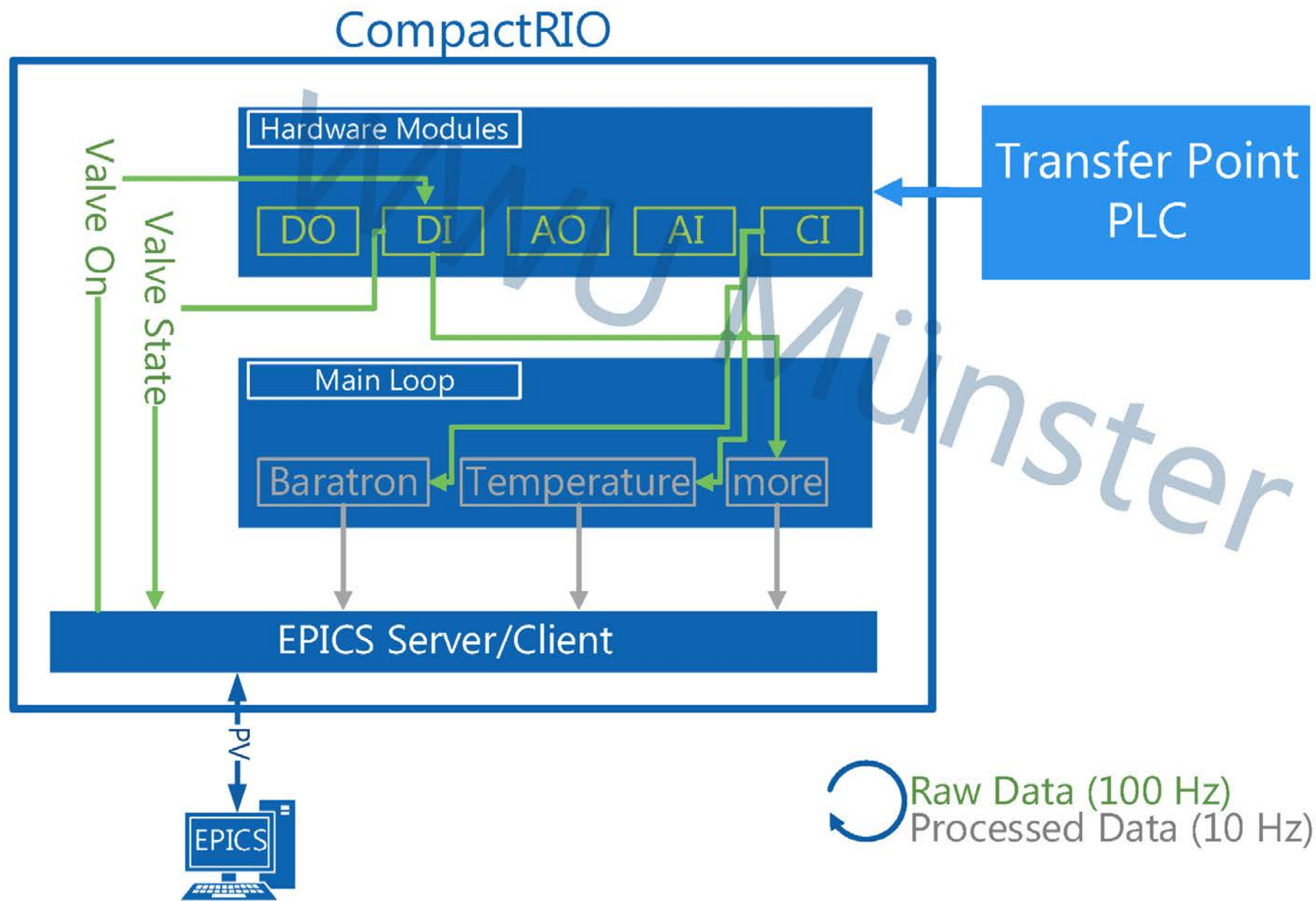
- FPGA if frequency > 500 Hz or CPU usage > 60%

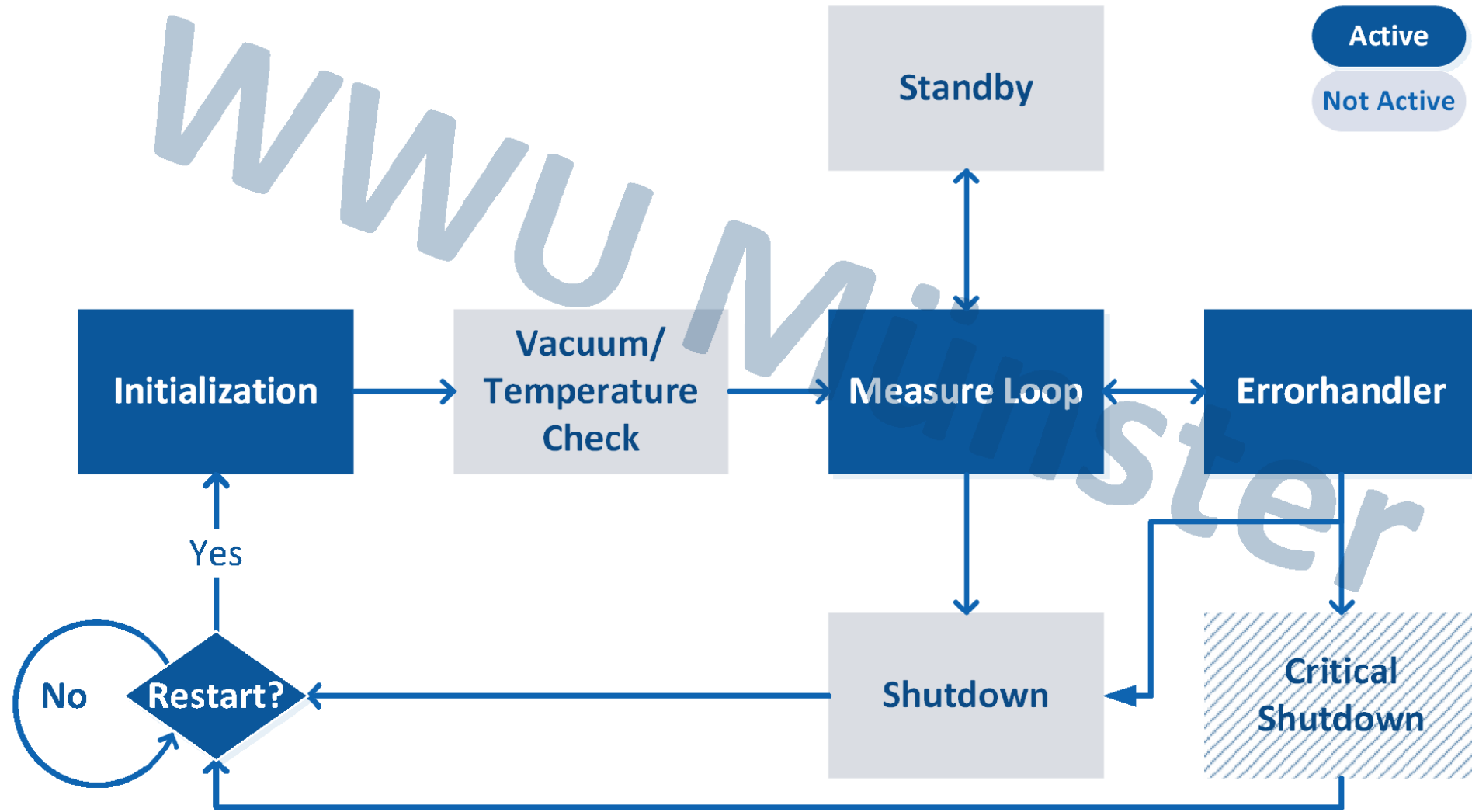
Advantages of Scan Mode:

- More simple Programming
- Dynamically initialize/detect modules
- Fault Engine available
- Diagnostic and Debugging

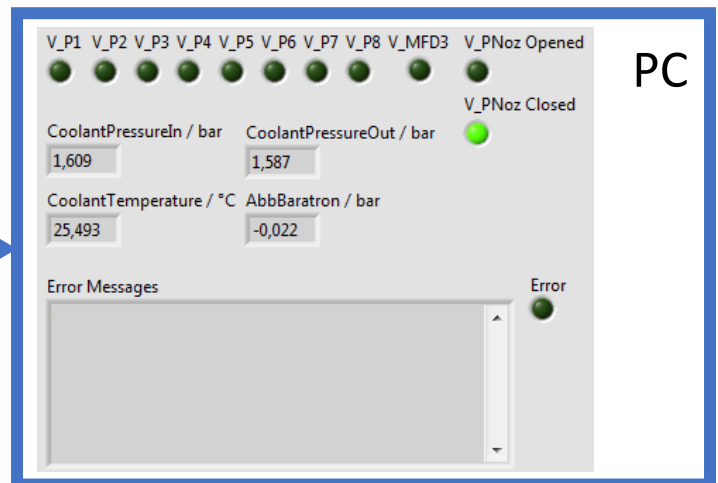
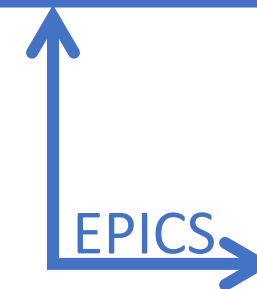
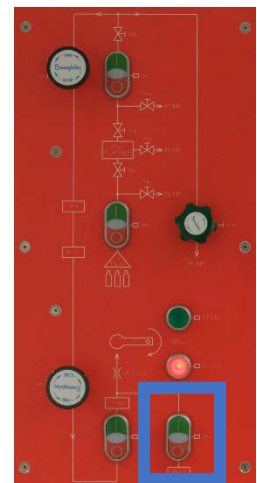
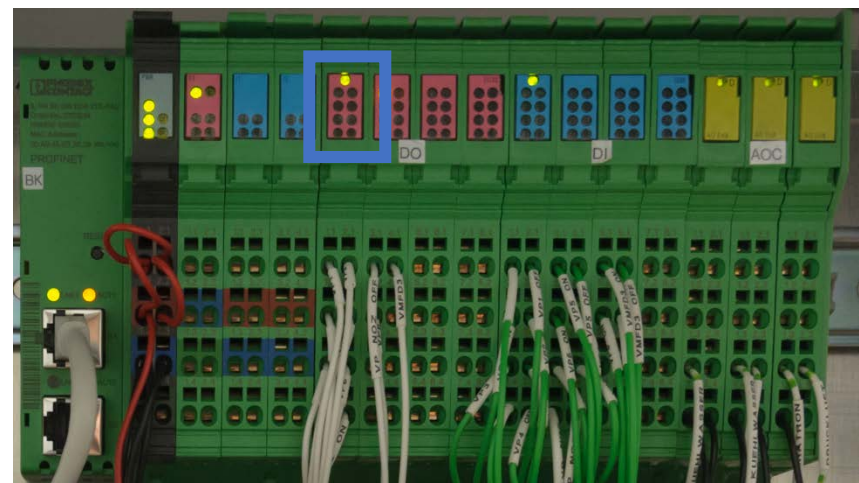
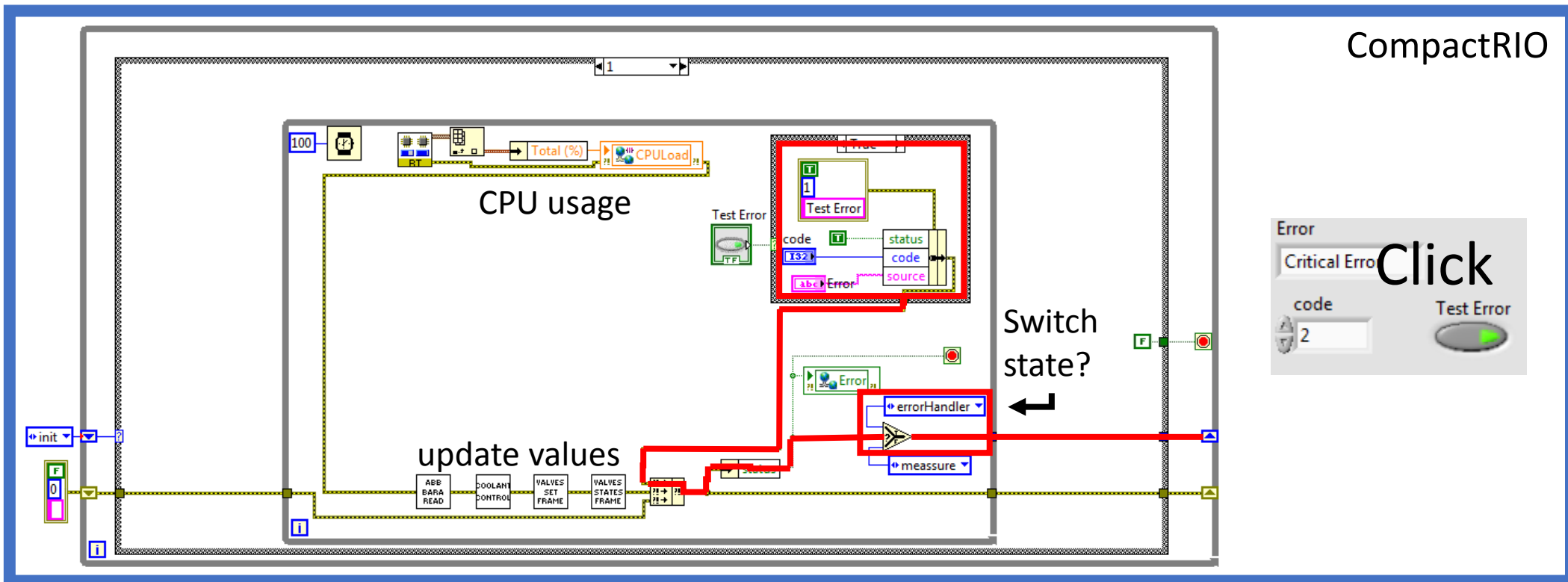
If more speed is needed: Hybrid Mode

- Scan Engine and use of FPGA
- Disadvantages:
  - Little more overhead
  - Whole Module only accessible through direct FPGA programming
  - Less simple programming

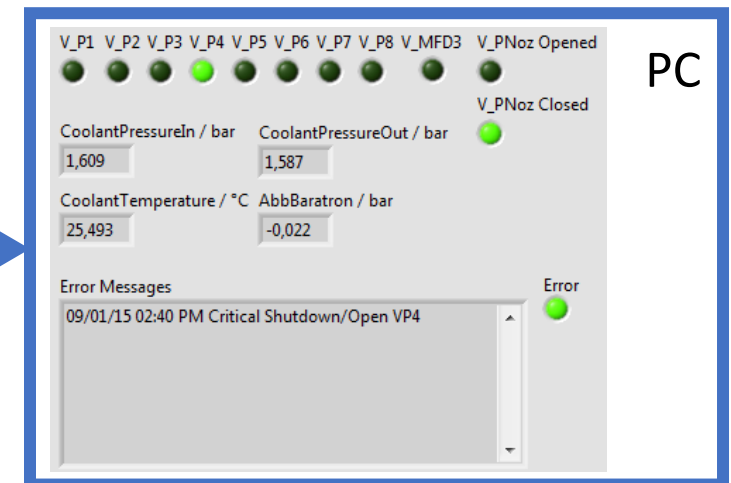
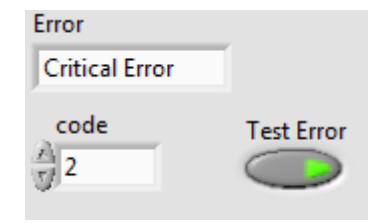
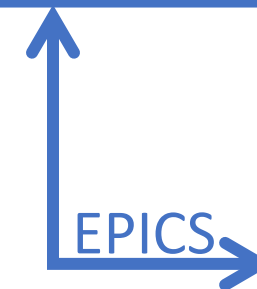
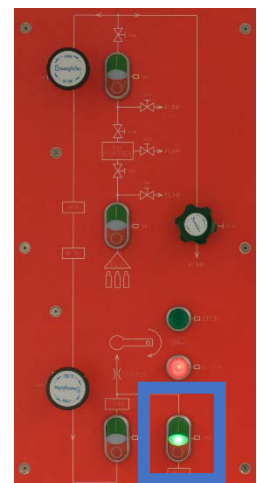
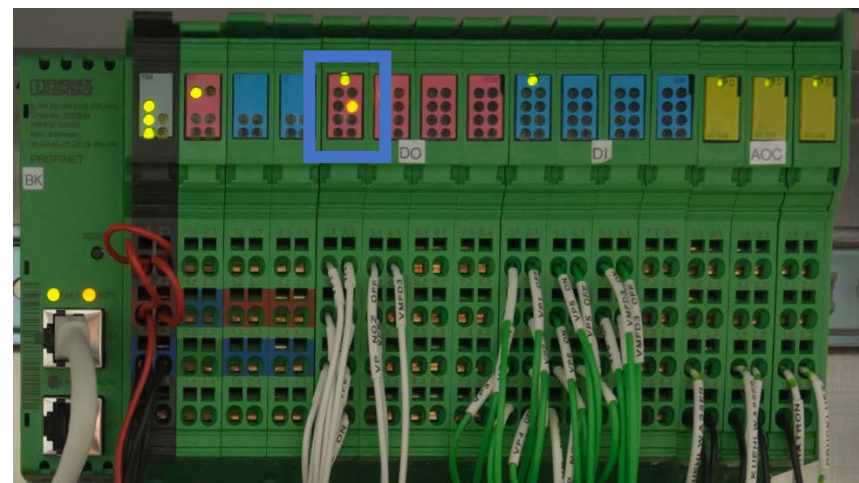
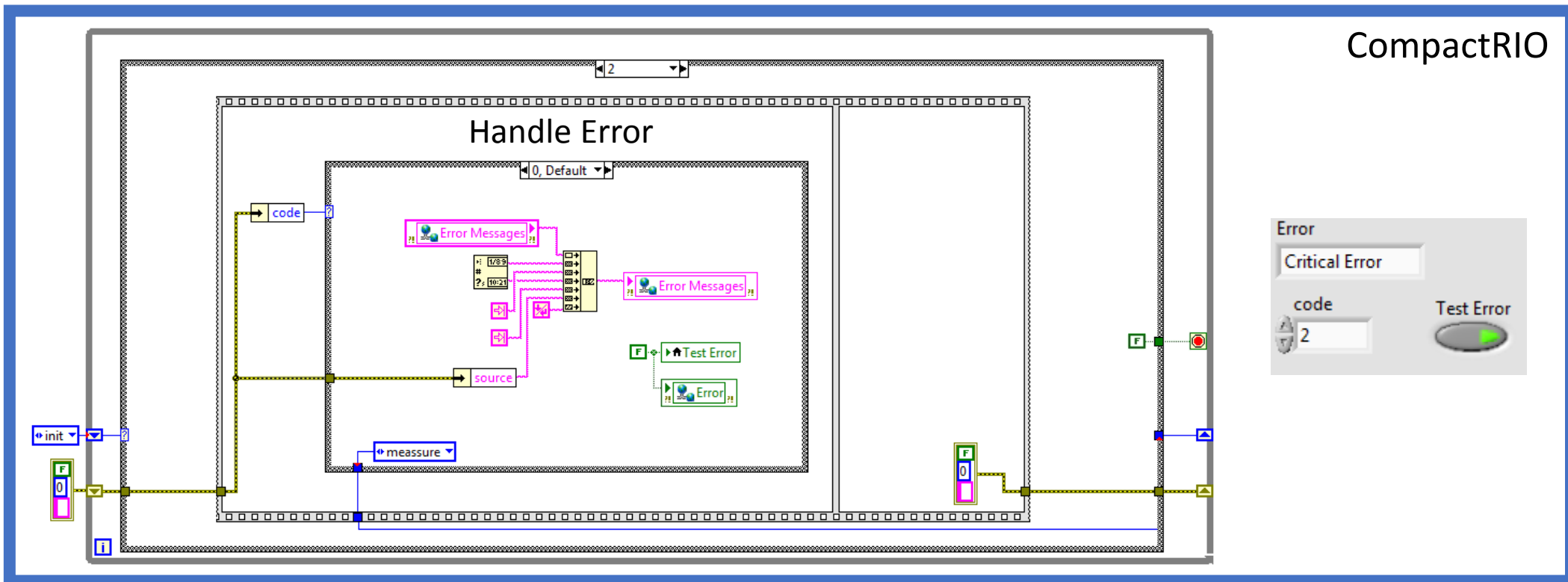


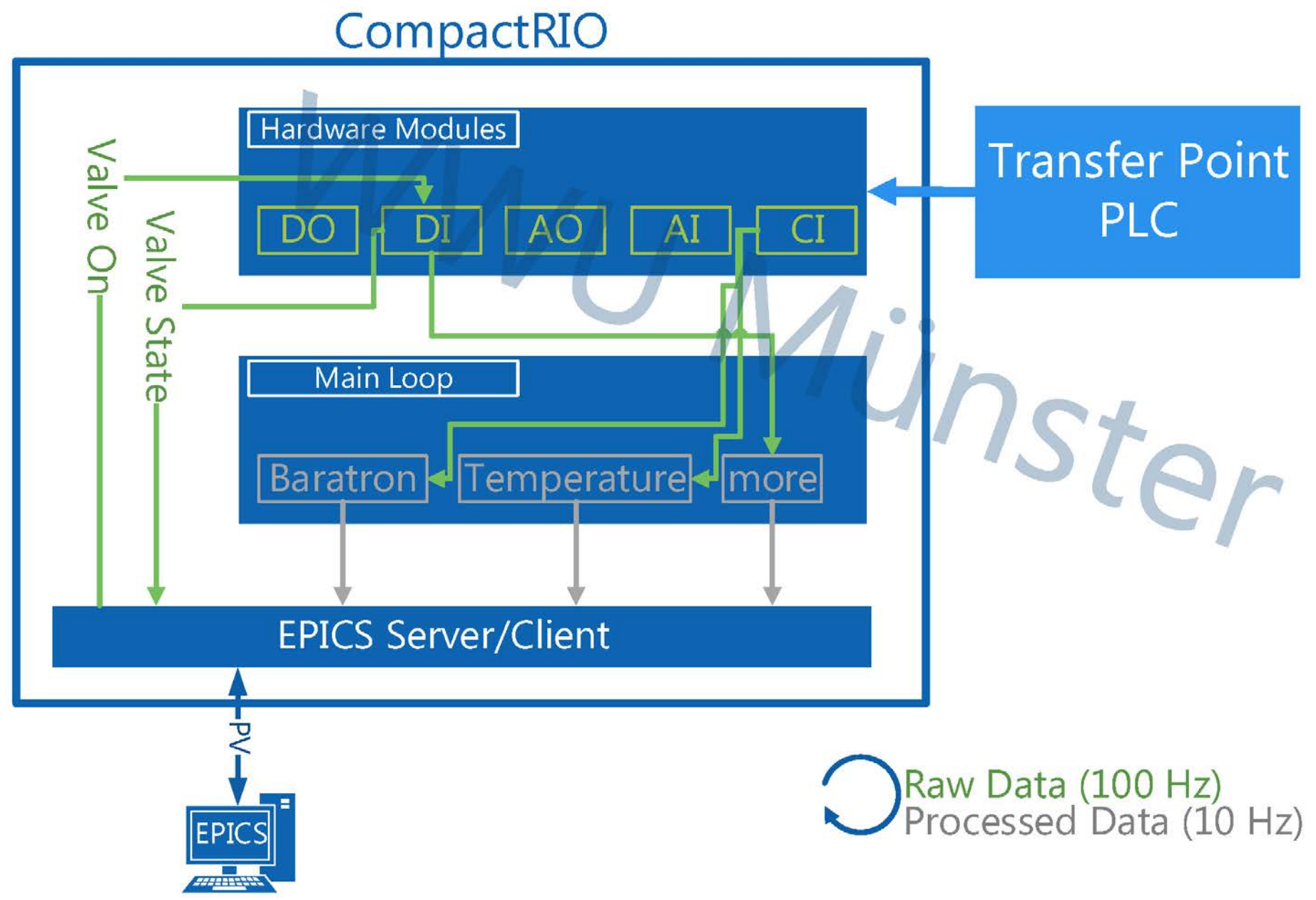


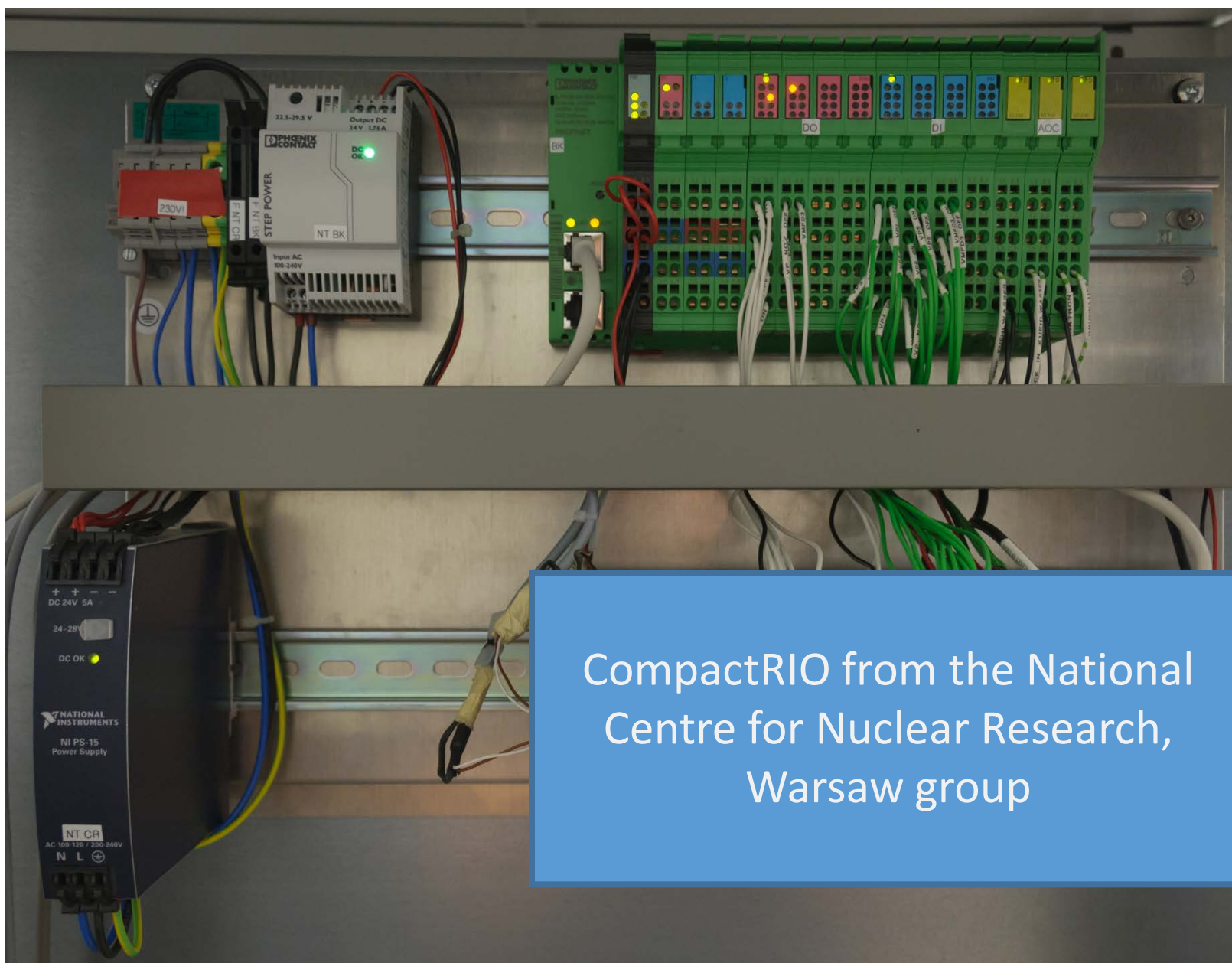
# Example Run of the Infinite State Machine





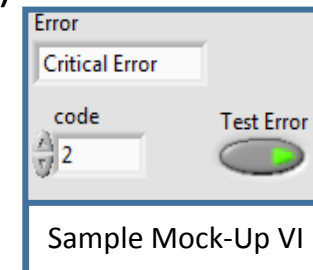






## Replace recipe for our CompactRIO with the Warsaw one:

- Plug'n'Play design – „simple“ 1:1 rewiring
- No need to know where the devices are located and which connectors are used
- Final Slow Control just needs to know which value ranges and input formats (voltage/current/...) are given
  - Examples:
    - Baratron measurand range: 0 bar – 30 bar → value range: 4 mA – 20 mA
    - Open Valve: 100 ms pulse on the corresponding DI line of the transfer point PLC
- Exceptions:
  - Only talking about devices connected to the PLC, no RS232/RS485/LAN/... devices
  - Current outputs of the spherical joint cross table potentiometer directly connected to CompactRIO and given to our cross table control as EPICS Process Variable
- Simple PLC design/connection interface has advantages
  - For the Slow Control team testing their code while the target is not accessible during assembly/future beam times
  - Via function generators, mock-up VIs, loop back VIs... (we use this techniques also for non PLC devices)





## Collaboration between Münster and Warsaw group:

- Detailed lists of all parts and measurands, flow charts, concept papers, ...
  - Already shared with Warsaw group
  - Happy to help if some information is missing/outdated
  - Missing manuals
- Share our know-how gained by using our preliminary Slow Control
- Looking forward to have constructive discussions about problems and ideas
- Welcome you to our institute to have a look at the target and its control devices

