

Status of Pellet Tracking and some Vacuum system considerations

Work during the Spring:

- Tracking system design. Continued work on lower section and algorithms (Andrzej Pyszniak)
- Multi-camera readout system.
- Vacuum and target thickness studies at COSY and implications for PANDA.

(Johan Löfgren: Project work on vacuum calculations) (COSY accelerator team: Target thickness measurements) (ANKE colleagues: Experience from studies at cluster-jet)



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UPPSALA team

Senior researchers: PhD student: Engineers: Project worker: Hans Calén, Kjell Fransson, Pawel Marciniewski Andrzej Pyszniak Carl-Johan Fridén, Elin Hellbeck Johan Löfgren

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Tracking system design status (June 2014)

A detailed system design study for PANDA, based on the upper tracking section (generator), was presented January 2013:

Various aspects of pellet behavior and detection were simulated using realistic parameter distributions from UPTS tests.

The resolution and efficiency were determined by using a first version of pellet tracking algorithm.

- \rightarrow Transverse position resolution is $\sigma \approx$ 100 µm
- \rightarrow Vertical resolution is $\sigma \approx$ 800 μm (with 10 μs cycle cameras)
- → Efficiencies >70 % as specified in Target TDR can be achieved; i.e. useful info for a proper combination of pellet rate (around 10 k/s) and acc.beam size (5-10 mm)



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A detailed design study for the lower section (dump) has now been done.

This section is necessary for tuning and checks, but gives also an improvement of vertical position resolution...



A lower tracking section with 3 levels...

Cameras with f = 25 mm opticsand 10 µs exposure cycle

IMPROVES vertical position resolution from $\sigma \approx 800 \ \mu m$ to $\sigma \approx 100 \ \mu m$

with an efficiency \approx 80% for a PR=5k/s

.... but the efficiency drops to ≈ 55 % at PR=15k/s when using the first (fast) version of pellet tracking algorithm.

The **pellet tracking algorithm** has now been developed and gives increased efficiency numbers......



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Pellet tracking algorithm efficiency improved.

Tracking system design

| PELLET rate 5 k/s | | | | | |
|---------------------|-----------------------|------------------------|-------------------------|------------------|--|
| Camera cycle/exp | Algorithm # levels | Tracking efficiency | Algorithm efficiency | Correct- ness | |
| 6.5/5µs | Old 4 | 54.3% | 60.6% | 94.7% | |
| | New 4 | 70.9% | 77.6% | 98.5% | |
| | New 7 | 91.6% | 97.1% | 99.1% | |
| 4/4 μs | Old 4 | 70.7% | 74.8% | 95.0% | |
| | New 4 | 83.1% | 86.7% | 98.4% | |
| | New 7 | 92.7% | 95.3% | 99.2% | |

Tracking

efficiency

47.4%

69.4%

85.6%

62.0%

80.0%

88.9%

Algorithm

efficiency

53.2%

76.0%

90.7%

65.3%

83.5%

91.4%

Correct-

ness

83.5%

96.6%

97.2%

87.8%

97.4%

97.6%



3 measurement levels at the pellet dump

| PTR status |
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PELLET rate 14 k/s

Camera

6.5/5 μs

4/4 μs

cycle/exp

Algorithm

levels

Old 4

New 4

New 7

Old 4

New 4

New 7



Old (simple and fast) tracking algorithm.

Example of some pellet tracking performance numbers. Occupancy of acc. beam region ($\phi=5$ mm). **Compare tracking prediction (trk) with mc reality (plt).**

| Compare | tracking | g prediction (t | rk) with mc reali | ity (plt). | |
|---|--------------|-----------------|-------------------|-------------------------------|-------------------|
| Note: In this example a "trk" is based on full and correct information from all detection levels, a condition which is very strong There is also room for improvement of the tracking procedure | | | | | |
| Cam cycle | Plt rate | Prb for no plt | Prb for 1 plt | Correct match | ~~ _{7,3} |
| <u>(</u> μ S) | <u>(k/s)</u> | when no trk | when 1 trk | <u>when 1 plt & 1 trk</u> | Ŭ |
| t4/e4 | 5 | 0.87 | 0.76 | 0.98 | |
| t2/e2 | 5 | 0.88 | 0.82 | 0.99 | |
| t4/e4 | 14 | 0.61 | 0.57 | 0.92 | |
| t2/e2 | 14 | 0.63 | 0.62 | 0.96 | |

Effect of detection inefficiency.

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Camera deadtime fraction of 20% in this example gives about 20% reduced tracking performance.

Dub for no ult

Low pellet rate and high time resolution improves tracking performance (as expected).

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| Cam cycle | Pit rate | Pro for no pit | Profor 1 pit | Correct match |
|-----------|----------|----------------|--------------|-------------------------------|
| (μS) | (k/s) | when no trk | when 1 trk | <u>when 1 plt & 1 trk</u> |
| t4/e4 | 5 | 0.87 | 0.76 | 0.98 |
| t6.25/e5 | 5 | 0.82 | 0.68 | 0.95 |
| t4/e4 | 14 | 0.61 | 0.57 | 0.92 |
| t6.25/e5 | 14 | 0.52 | 0.48 | 0.83 |
| | | | | |

Dub far 1 mlt



Occupancy of acc. beam region (\$\$\phi=5\$ mm)\$. Compare tracking prediction (recons.) with mc reality (true) pellet.

Case 0) **NO PELLET IN THE ACC. BEAM**

The 4-level variant corresponds to usage of the upper tracking section only and the 7-level variant to usage of also the dump section.

| | Algorithm | Probability | | Proba | ability |
|-------------|------------|---------------|----------|---------------|----------|
| Camera | | of no | | of no | |
| cycle, | S(imple), | recons | . true | true | recons. |
| pellet rate | A(dvanced) | pellet in the | | pellet in the | |
| | | beam i | region | beam | region |
| | and number | (time fr | action) | whe | n no |
| | of levels | | | recons. | true |
| | | | | pellet is | s in the |
| | | | | beam | region |
| | | | | | |
| 4/4 μs, 5 | S 4-lev | 0.78 | 0.70 | 0.87 | 0.96 |
| k/s | A 4-lev | 0.74 | 0.70 | 0.89 | 0.95 |
| | A 7-lev | 0.72 | 0.70 | 0.98 | 0.998 |
| 4/4 μs, | S 4-lev | 0.54 | 0.36 | 0.61 | 0.91 |
| 14 k/s | A 4-lev | 0.45 | 0.36 | 0.71 | 0.86 |
| | A 7-lev | 0.39 | 0.36 | 0.94 | 0.99 |

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Occupancy of acc. beam region (\$\$\phi=5\$ mm)\$. Compare tracking prediction (recons.) with mc reality (true) pellet.

Case 1) ONE PELLET IN THE ACC. BEAM

The 4-level variant corresponds to usage of the upper tracking section only and the 7-level variant to usage of also the dump section.

| | Algorithm | Probability of | | Probab | oility of |
|-----------|------------|----------------|----------|-------------|-----------|
| Camera | | exact | tly one | one-m | atching |
| cycle, | S(imple), | recons | true | true | recons. |
| pellet | A(dvanced) | pellet | t in the | pellet in t | he beam |
| rate | | beam | region | region | when |
| | number of | (time f | raction) | exact | ly one |
| | levels | | | recons. | true |
| | | | | pellet i | s in the |
| | | | | beam | region |
| 4/4 µs, 5 | 5 S 4-lev | 0.20 | 0.25 | 0.75 | 0.58 |
| k/s | A 4-lev | 0.22 | 0.25 | 0.73 | 0.64 |
| | A 7-lev | 0.24 | 0.25 | 0.96 | 0.93 |
| 4/4 μs, | S 4-lev | 0.33 | 0.37 | 0.52 | 0.46 |
| 14 k/s | A 4-lev | 0.36 | 0.37 | 0.57 | 0.56 |
| | A 7-lev | 0.37 | 0.37 | 0.89 | 0.89 |

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Multi camera readout development: status

Multi-camera system

Software: Project works by Malte Albrecht, Madhu Thelajala and Geng Xiaoxiu





CAMCTRL FPGA board (ATLB developed for WASA trigger) is used for readout of up to 8 CAMLINK FPGA boards. **FPGA Software:**

- Control and readout of camera link board ready
- VME readout ready

CAMLINK FPGA card is used for readout of 2-4 cameras: 1'st prototype board debugged and software developed 2 boards of a modified version were produced and tested **FPGA Software:**

 Camera link readout and pellet recognition implemented Communication with camera and CAMCTRL board works

Remaining tasks

- More work on synchronization of boards and cameras
- Implementation in the PTR readout system
- (Camera link readout for 200 kHz cameras)



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Closed shutter ($P_s = measured$)

*P*₅/*P* **P** [mbar] Meas.pt. PEG3 200×10^{-6} 1.00 PEG4 11×10^{-6} 0.92 PEGa1 11×10^{-6} 1.10 PEG5 0.043×10^{-6} 0.86 PEGb1 1.5×10^{-6} 1.00 PEG7 0.015×10^{-6} -Int. pt. 0.046×10^{-6} -

P [mbar] P_{o}/P Meas.pt. PEG3 180×10^{-6} 0.99 PEG4 13×10^{-6} 0.99 PEGa1 16×10^{-6} 1.00 PEG5 0.74×10^{-6} 0.81 PEGb1 125×10^{-6} 0.957 PEG7 0.23×10^{-6} 1.21×10^{-6} Int. pt.

Open shutter ($P_o = measured$)

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Background study at WASA pp-> pp π^0 run (π^0 -> $\gamma\gamma$)



WaC Pellet vacuum

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PHYSICAL REVIEW SPECIAL TOPICS - ACCELERATORS AND BEAMS 11, 052801 (2008)

Determination of target thickness and luminosity from beam energy losses

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The repeated passage of a coasting ion beam of a storage ring through a thin target induces a shift in the revolution frequency due to the energy loss in the target. Since the frequency shift is proportional to the beam-target overlap, its measurement offers the possibility of determining the target thickness and hence the corresponding luminosity in an experiment. This effect has been investigated with an internal proton beam of energy 2.65 GeV at the COSY-Jülich accelerator using the ANKE spectrometer and a hydrogen cluster-jet target. Possible sources of error, especially those arising from the influence of residual gas in the ring, were carefully studied, resulting in an accuracy of better than 5%. The luminosity determined in this way was used, in conjunction with measurements in the ANKE forward detector, to determine the cross section for elastic proton-proton scattering. The result is compared to published data as well as to the predictions of a phase shift solution. The practicability and the limitations of the energy-loss method are discussed.





A) Cosy Beam (CB) energy loss measurements

| (CJ=Cluster-Jet) | Targ | et thickne | SS | [10 ¹⁴ at | ./cm ^{2[·]} |
|----------------------|-------|------------|-----|----------------------|-------------------------------|
| Total (CB on CJ) | Т | = 2.8 | | | |
| Ring (no CJ) | R | = 0.14 | 5% | 6 | |
| Rest gas (CB off CJ) | Rg | = 0.034 | 1.2 | 2% | |
| (Rest Gas (CB on CJ | J) RG | i = 0.069 | 2. | 5% esti | m.) |
| | | | | | |

Cluster Jet CJ = T-R-RG = 2.6

B) Vacuum (gauge) measurements

average in Cosy Ring (183m) and at Anke (+/-5m)

| Anke (CB on CJ) | 4E-8 | RG = 0.047 |
|------------------|---------------|---|
| Anke (CB off CJ) | 2E-8 | Rg = 0.024 |
| Ring (no CJ) | 2E-9 | $R = 0.018 - 0.043$ (air $-H_2$) |
| Total (CB on CJ) | | Τ= |
| Vacuum [| <u>mbar]-</u> | →Target thickn. [10 ¹⁴ at./cm ²] |









Target conditions at ANKE Cluster-Jet

What info exist about background conditions at ANKE ?

Here are some notes from discussions with Ralf Schleichert, Michael Hartmann and other ANKE colleagues during last months

- Spacious scattering chamber (90x70x20 cm³) with Ø =38mm entrance and exit pipes for jet and Ø =60mm pipes for Cosy beam.
- Vacuum p $\approx 10^{-7}$ mbar. Two 3000 l/s cryos pump on the scattering chamber.
- Sharp and uniform jet profile Ø ≈ 10 mm (FW)
- Target thickness up to $1\cdot 10^{15}$ at./cm2 for H2 and $3\cdot 10^{14}$ at./cm² for D₂.
- Background due to rest gas has been estimated from vertex z-position distribution of reconstructed charged particle events (elastic scattering?).

The level interactions outside of the jet is typically around 1% of the value inside the jet region .

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the ANKE cluster-jet target.

Figure 6.2: The target is projected onto a plane in the telescope by the selection of a fixed angle. The image (squares) is compared with the distribution from Monte Carlo simulations (line) [62] assuming a rectangular shaped target with a length of 9.5 mm.



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WASA target thickness estimate from COSY-beam energy loss measurement in a pd run @1GeV in May

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big pellets should be expected.



Summary of comparison between target related background conditions at WASA and at ANKE.

| | WASA pellet | ANKE cluster-jet |
|---|--|--|
| Target beam size | Φ = 3.8 mm | Φ = 10 mm |
| Target thickness | Few times 10 ¹⁵ at./cm ² | Up to 10 ¹⁵ at./cm ² (H ₂) |
| Pressure in scattchamber | ≈ 10 ⁻⁶ mbar | ≈ 10 ⁻⁶ mbar (guess) |
| Background level expected from vacuum situation | ≈ 0.01 % | ≈ 0.05 % |
| Background level from event reconstruction | ≈ 0.2 % | ≈ 1 % |
| Results from COSY beam energy loss measurements: | May 2014, pd @1GeV | 2004, pp @2.65 GeV (published 2008) |
| Target thickness | 58.0·10 ¹⁴ at./cm ² | 2.60·10 ¹⁴ at./cm ² |
| Thickness no target | 0.12·10 ¹⁴ at./cm ² | 0.14·10 ¹⁴ at./cm ² |
| Thickness rest gas | < "no target" value | 0.07·10 ¹⁴ at./cm ² |

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PANDA CM GSI, June 2014 Hans Calén There are certainly differences between the pellet and the cluster-jet target situation but nothing really dramatic or unexpected was found in this (rough) study.



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Figure 9.2: Cross section of the Target Spectrometer with detector components in light gray. The target and dump lines are marked in red. The antiproton beam line, as well as the cluster-jet target and the target beam dump, is marked in blue. The dimensions are given in mm. The diameters refer to inner diameters of the tubes.









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Summary (June 2014) Status of tasks connected to FP7 HP3 FutureJet:

3.6 Pellet track processing and optimization of pellet detection points

Detailed design simulations, based on the tracking section at the generator, for PANDA was done *(Milestone 13 report ... January 2013)*. Now the lower section at the dump is also included in the design ...

3.7 Multi-camera readout system

h-w: 2nd version of CAMLINK FPGA board tested and works... s-w: Complete readout chain (camera-to-computer) works. Preparing for operation with 4 cameras under real conditions.

Status of other tasks:

- Results of vacuum measurements at WASA (COSY) has been analyzed and compared with background in hadronic event distributions. The results are used in evaluation of the vacuum situation at PANDA, e.g. for the need of "extra" pumps etc
- A comparison between target related background conditions at WASA and at ANKE (COSY) was done.

The real physics background level seems to be much higher than what is expected from vacuum conditions for both pellet and cluster-jet target.

With the present vacuum system design, much worse conditions than those we have at WASA are anticipated ! Events from "rest-gas" must be included in simulations so we can be able to judge if this is a serious problem

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Comments regarding new vacuum estimates for PANDA (Presented in the target group meeting, CM at GSI March 2014)

Results of vacuum measurements at WASA (COSY) have been analyzed and were compared with "rest-gas" background in hadronic event distributions. Vacuum calculations, modelling WASA, reproduce well all the gauge readings both with pellets ON and OFF. From the results we expect that 0.5% of the total target thickness is due to residual gas in the narrow Be-pipe (I=200 mm, diam.=60 mm). From the event analysis we expect around 10%. The difference may be due to non optimal pellet stream conditions (that should be easy to improve in a new target design).

For making estimates for PANDA, the target cross was exchanged with the one for PANDA while the WASA pumping sections were kept in the model (the pumping capacity is similar). The calculations now gives 10 times higher pressure than in WASA at the interaction point for both pellets ON and OFF. From this we expect that 5% of the total target thickness will be due to residual gas in the narrow part of the PANDA beampipe (I=700 mm, diam.=20 mm). This should be considered as a lower limit. What the rest-gas background level in the event analysis will be, depends on the real quality of the target and accelerator beams.

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PANDA CM GSI, June 2014 Hans Calén Compared with the results presented in the Target TDR, the new calculations give 4 times lower pressure for pellets ON and 5 times higher pressure for pellets OFF at the interaction point. The TDR calculations actually gives a pressure with cluster-beam ON which is 60% lower than the pressure from the new calculations with pellets OFF.

With the present PANDA vacuum system design, much worse conditions than those we have at WASA must be anticipated !



PANDA pellet tracking system

Project planning (June 2014)

Design: Conceptual and system design ready (TDR +++). **Detailed mechanical design remains.** Detailed camera r/o and control system in progress. Preparation of a tracking section for PANDA: Not funded. Evaluation done (most recent one in autumn 2013). **Risks**: Financing, applications: (Approval of TDR may help ...) Running: SRC application 2015-18 submitted. HPH application 2015-17 to be submitted. Equipment: KAW application was (strongly) rejected. CTS application(30k€) 2015-16 submitted. No other possibility in SE at present. Time line: If applications for running are successful some design and development work can continue. If the CTS application is approved one (of seven) detection module can be prepared. Preparation of main equipment must still wait.

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| C LARGE C | PTR items for FAIR Risk Management |
|----------------------------|---|
| | PTR-001 |
| | Multi-Camera readout.Delay Many other tasks relies on tests with |
| UNIVERSITET | multi-camera setup (mainly resource issue) |
| | PTR-002 |
| | Operation in magnetic field. Tests done, (if problems later design shielding) |
| | PTR-003 |
| | Overheating of cameras. Studies done, (if problems later provide cooling) |
| | PTR-004 |
| | Too poor conditions for pellet detection at the dump.Tests done at UPTS(adapted design) |
| | PTR-005 |
| | Instability of mechanical alignment. Design (minimize risk, allow fine-tuning) |
| | PTR-006 |
| | Too poor access for mechanical tuning and replacement of malfunctioning parts. |
| | Design (allow fine-tuning, special tools) |
| PTR status | PTR-007 |
| | Insufficient resources for development and preparation of a full prototype section. |
| PANDA CM GSI, June 2014 | Mainly personnel. No financing |
| Hans Calén | PTR-008 |
| | Insufficient resources for preparation of full system to be installed at PANDA. |
| | Equipment and personnel. No financing |
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Project plan for the pellet tracking system developments 2014-2017



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(23) (pers=personnel, eqpt=equipment, cons=consumables, eng=engineer, res=researcher, UPTS=Uppsala Pellet Test Station, TSL=The Svedberg Laboratory, UU=Uppsala Univ., JU=Jagiellonian Univ., EC=European Commission, HP3/H=Hadron Physics 3/Horizon, SRC=Swedish Research Council, JCHP-FFE=Jülich Center for Hadron Physics – Fremde Forschung und Entwicklung)