

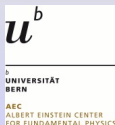
Real-time dynamics without Hamiltonians

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Outline

Introduction

Set-up of the problem

Real-time evolution in a large quantum system

Outlook

The Schwinger-Keldysh (closed-time) contour

- ▶ Quantum many-body system governed by $\hat{H}(t)$
- ▶ At some point in time $t = 0$, the initial state of the system is specified by a density-matrix $\hat{\rho}(0)$.
- ▶ Evolution of the density matrix: $\frac{d\hat{\rho}(t)}{dt} = -i[\hat{H}(t), \hat{\rho}(t)]$
- ▶ Formally solved as: $\hat{\rho}(t) = \hat{U}(t, 0)\hat{\rho}(0)[\hat{U}(t, 0)]^\dagger$

$$\begin{aligned}\hat{U}(t, t') &= \mathcal{T} \exp \left[-i \int_t^{t'} \hat{H}(\tau) d\tau \right] \\ &= \lim_{N \rightarrow \infty} e^{-i\hat{H}(t' - \delta_t)\delta_t} \dots e^{-i\hat{H}(t + \delta_t)\delta_t} e^{-i\hat{H}(t)\delta_t}\end{aligned}$$

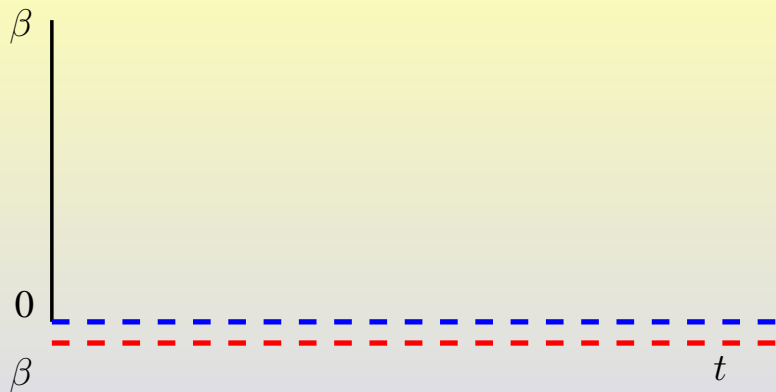
with $\delta_t = (t' - t)/N$.

- ▶ Expectation value of an observable:

$$\langle \hat{O}(t) \rangle = \text{Tr} \left\{ \hat{O} \hat{\rho}(t) \right\} = \text{Tr} \left\{ \hat{U}(0, t) \hat{O} \hat{U}(t, 0) \hat{\rho}(0) \right\}$$

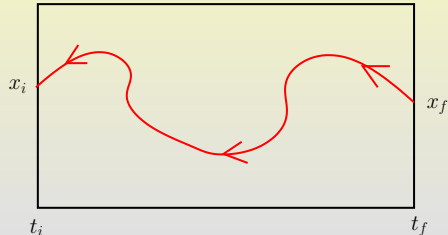
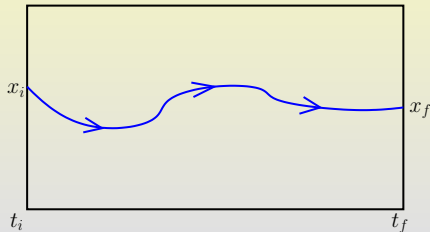
where the density matrix is normalized.

The Schwinger-Keldysh (closed-time) contour



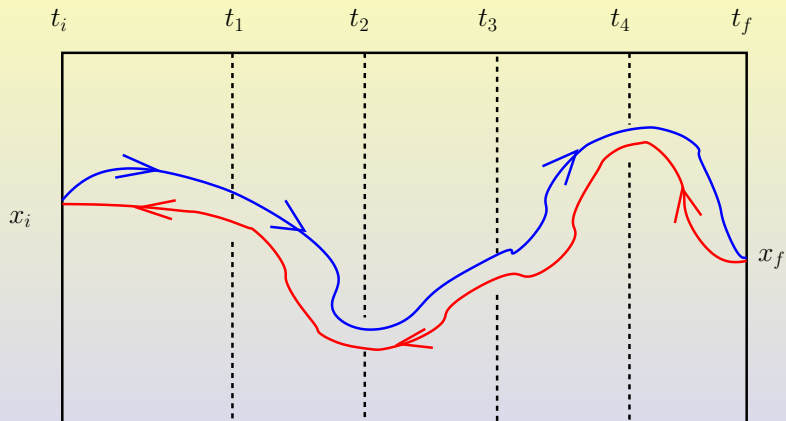
- ▶ “forward-backward” evolution along the real-time contour.
- ▶ Entanglement in quantum systems presents a major obstacle for numerical methods
- ▶ Idea: make **repeated measurements** on the system to reduce entanglement

Measurements to help us out



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Path-Integral with measurements

- ▶ General quantum system with (possibly) time-dependent Hamiltonian.
- ▶ Time-evolution $t_k \rightarrow t_{k+1}$ described by $U(t_{k+1}, t_k) = U(t_k, t_{k+1})^\dagger$.
- ▶ At time t_k ($k \in \{1, 2, \dots, N\}$) observable O_k measured with eigenvalue o_k .
- ▶ Represented by the Hermitian operator P_{o_k} : projects on to the sub-space of the Hilbert space spanned by eigenvectors of O_k with eigenvalue o_k .
- ▶ Consider an initial state, specified by a normalized density matrix $\rho = \sum_i p_i |i\rangle\langle i|$; with $0 \leq p_i \leq 1$ and $\sum_i p_i = 1$.
- ▶ Probability of making a single measurement of O_k at time t_k while evolving from t_i to t_f is:
$$p_{\rho f}(o_k) = \sum_i \langle i | U(t_i, t_k) P_{o_k} U(t_k, t_f) | f \rangle \langle f | U(t_f, t_k) P_{o_k} U(t_k, t_i) | i \rangle p_i$$
- ▶ With many measurements,
$$p_{\rho f}(o_1, o_2, \dots, o_N) = \sum_i \langle i | U(t_i, t_1) P_{o_1} U(t_1, t_2) P_{o_2} \dots P_{o_N} U(t_N, t_f) | f \rangle \langle f | U(t_f, t_N) P_{o_N} \dots P_{o_2} U(t_2, t_1) P_{o_1} U(t_1, t_i) | i \rangle p_i$$

Away with the Hamiltonian!

- ▶ Matrix elements of both $U(t_{k+1}, t_k)$ and P_{o_k} are in general complex, leading to a severe complex weight and/or sign problem.
- ▶ Measurements disentangle the quantum system, and are expected to alleviate the sign-problem.
- ▶ Take an extreme case: switch off the Hamiltonian completely for the real-time evolution. $U(t_{k+1}, t_k) = \mathbb{I}$

- ▶ Time-evolution is driven entirely by (non-commuting) measurements!

- ▶ With only the measurements:

$$\begin{aligned} p_{\rho f}(o_1, o_2, \dots, o_N) &= \sum_i \langle i | P_{o_1} P_{o_2} \dots P_{o_N} | f \rangle \langle f | P_{o_N} \dots P_{o_2} P_{o_1} | i \rangle p_i \\ &= \sum_i p_i \langle ii | (P_{o_1} \otimes P_{o_1}^T) (P_{o_2} \otimes P_{o_2}^T) \dots (P_{o_N} \otimes P_{o_N}^T) | ff \rangle \end{aligned}$$

- ▶ Insert complete sets of states: $\sum_{n_k} |n_k\rangle \langle n_k| = \mathbb{I}$; $\sum_{n'_k} |n'_k\rangle \langle n'_k| = \mathbb{I}$
- ▶ In the doubled Hilbert space of states $|n_k n'_k\rangle$, for both pieces of the Keldysh contour (using $\langle n_0 n'_0 | = \langle ii |$ & $|n_{N+1} n'_{N+1}\rangle = |ff\rangle$):

$$p_{\rho f}(o_1, o_2, \dots, o_N) = \sum_i p_i \sum_{n_1 n'_1} \dots \sum_{n_N n'_N} \prod_{k=0}^N \langle n_k n'_k | P_{o_k} \otimes P_{o_k}^T | n_{k+1} n'_{k+1} \rangle$$

A concrete example

- ▶ Don't pay attention to the "intermediate" measurement results!
- ▶ The probability $p_{\rho f}$ to reach the final state $|f\rangle$:

$$p_{\rho f} = \sum_{o_1} \sum_{o_2} \cdots \sum_{o_N} p_{\rho f}(o_1, o_2, \dots, o_N) = \sum_i p_i \sum_{n_1, n'_1} \cdots \sum_{n_N, n'_N} \prod_{k=0}^N \langle n_k n'_k | \tilde{P}_k | n_{k+1} n'_{k+1} \rangle$$

$\tilde{P}_k = \sum_{o_k} P_{o_k} \otimes P_{o_k}^T$, summing over all possible measurement results.

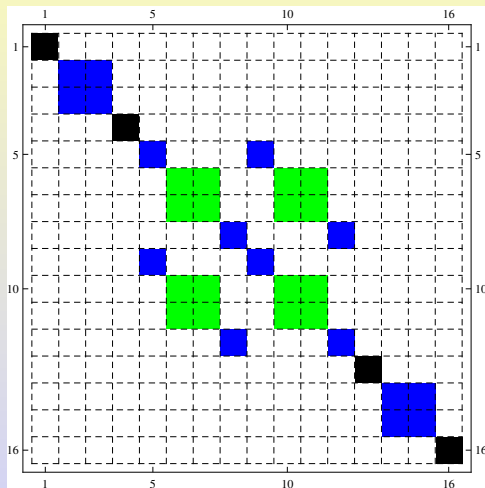
- ▶ Example: Two spins \vec{S}_x and \vec{S}_y forming **total spin** eigenstates:
 $|11\rangle = \uparrow\uparrow$, $|10\rangle = \frac{1}{\sqrt{2}}(\uparrow\downarrow + \downarrow\uparrow)$, $|1-1\rangle = \downarrow\downarrow$; $|00\rangle = \frac{1}{\sqrt{2}}(\uparrow\downarrow - \downarrow\uparrow)$
- ▶ Projection operator on spin-1:
 $P_1 = |11\rangle\langle 11| + |10\rangle\langle 10| + |1-1\rangle\langle 1-1|$
- ▶ Projection operator on spin-0: $P_0 = |00\rangle\langle 00|$

$$P_1 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad P_0 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{2} & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

- ▶ Negative entries in P_0 give rise to a sign problem. ◻

The sign-problem and it's solution

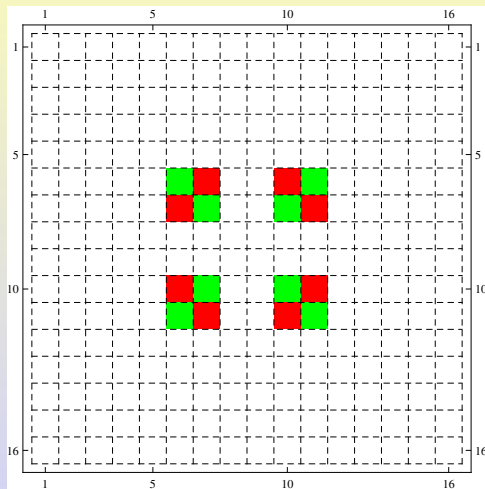
In the doubled Hilbert space, $P_1 \otimes P_1^T$ is a 16×16 matrix with entries:



Legend: black $\rightarrow 1$; blue $\rightarrow \frac{1}{2}$; green $\rightarrow \frac{1}{4}$; red $\rightarrow -\frac{1}{4}$

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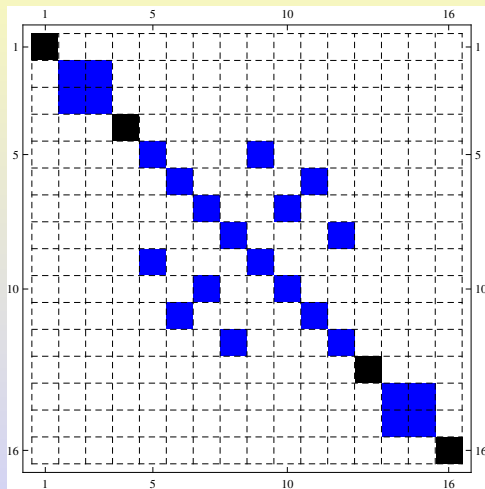
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The sign-problem and it's solution

$\tilde{P} = P_0 \otimes P_0^T + P_1 \otimes P_1^T$ is a 16×16 matrix with entries:

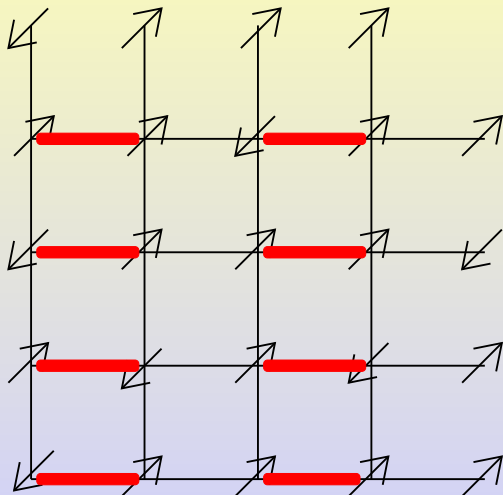


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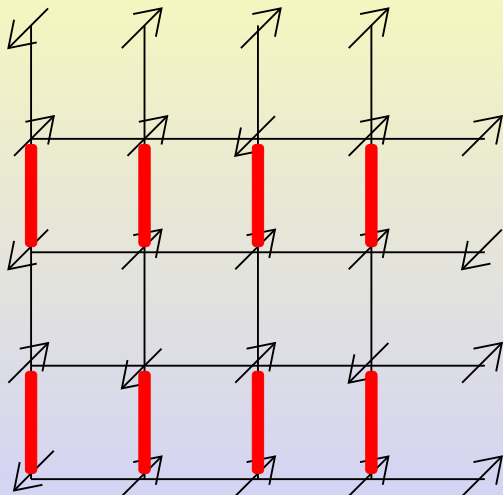
Extension to large systems

- ▶ Example of two-spin system easily extendable to large systems.
- ▶ System of quantum spins $\frac{1}{2}$ on a square lattice $L \times L$ with periodic boundary conditions.
- ▶ To define the initial density matrix $\hat{\rho} = \exp(-\beta\hat{H})$, use the Heisenberg anti-ferromagnet: $\hat{H} = J \sum_{\langle xy \rangle} \vec{S}_x \cdot \vec{S}_y$; $J > 0$.
- ▶ Real-time evolution is driven via measurements of the total spin $(\vec{S}_x + \vec{S}_y)^2$ of the nearest-neighbor spins \vec{S}_x and \vec{S}_y .

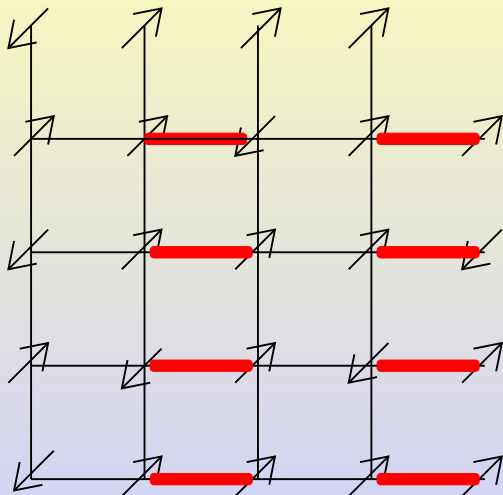
Non-commuting measurements



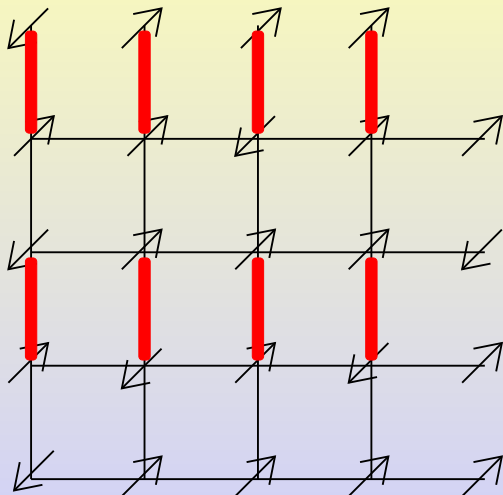
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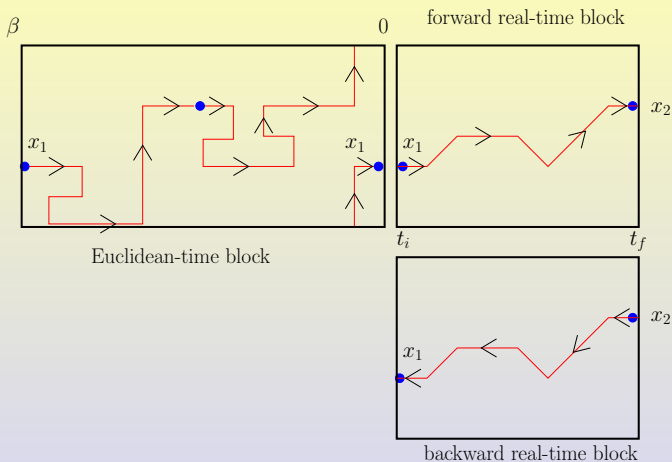
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- ▶ Real-time evolution is driven via measurements of the total spin $(\vec{S}_x + \vec{S}_y)^2$ of the nearest-neighbor spins \vec{S}_x and \vec{S}_y .
- ▶ The particular measurement sequence is arbitrary; but well defined and corresponds to a definite “real-time physics”.
- ▶ The existing highly efficient loop-cluster algorithm for anti-ferromagnets can be naturally extended to this particular case of real-time evolution.
- ▶ Resulting clusters are closed loops extending in both Euclidean and real-time, which are updated together.

An example of a cluster

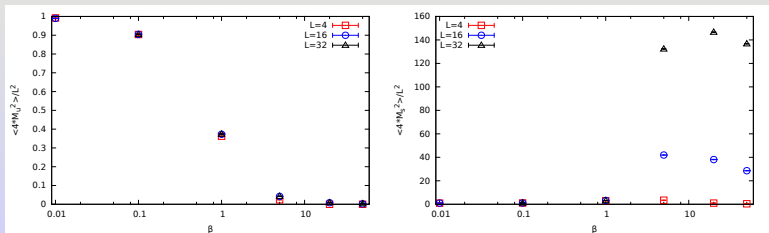


Identical clusters in the forward and backward real-time evolution is due to the condition that we have summed over “all intermediate measurements” \rightarrow cluster bonds are decided with the matrix elements in the matrix $\tilde{P} = P_1 \otimes P_1^T + P_0 \otimes P_0^T$.

Properties of the initial state

- ▶ Initial state is the ground state (or thermal ensemble depending on inverse temperature β) of the Heisenberg anti-ferromagnet in (2+1)-d.
- ▶ At low-T (large β), there is a strong Néel order which disappears for higher temperature.
- ▶ Diagnostics for measuring the ferromagnet and the Néel orders are the uniform and staggered magnetization:

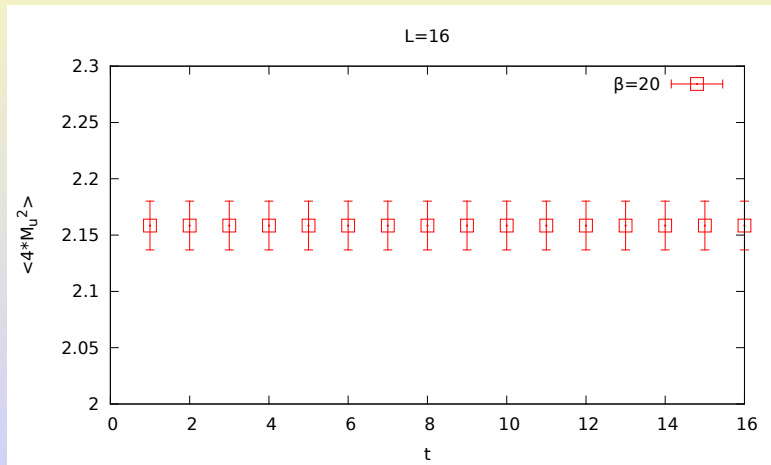
$$M_u = \frac{1}{2} \sum_x S_x^3; \quad M_{stag} = \frac{1}{2} \sum_x (-1)^{x_1+x_2} S_i^3$$



Uniform (left) and staggered (right) magnetization for a 2-d Heisenberg model

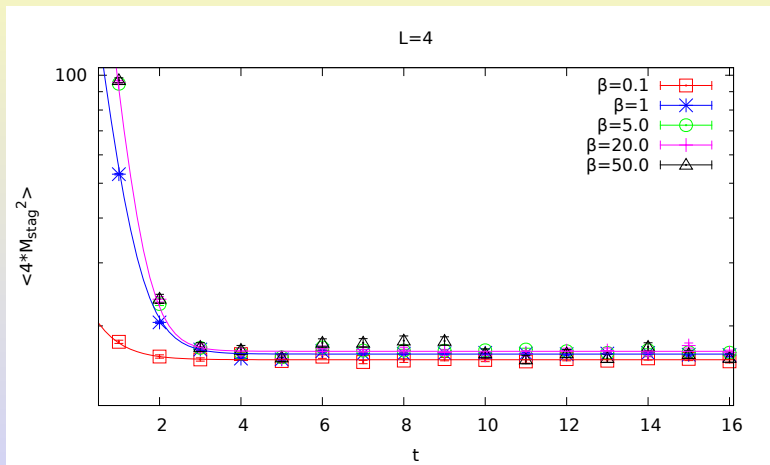
Uniform magnetization

The uniform magnetization $M_u = \frac{1}{2} \sum_x S_x^3$ should be constant since it commutes both with the Hamiltonian and the measurement.



Staggered magnetization

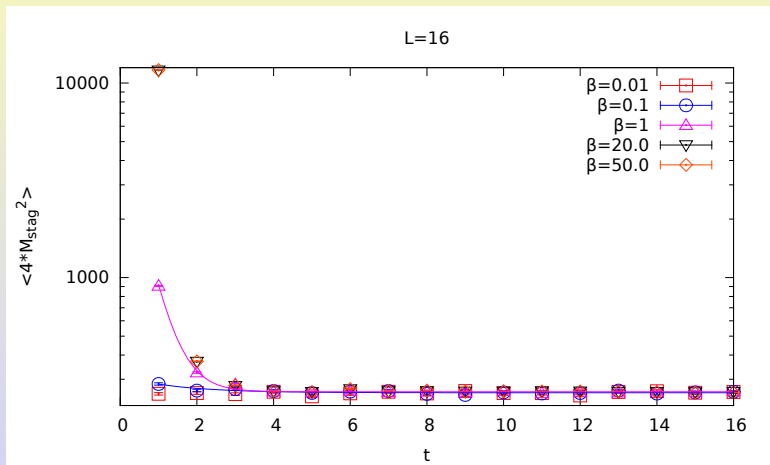
The staggered magnetization is destroyed by the measurements, and a new state is established.



Lines are fit to $A \exp(-N/\tau) + B$

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In progress

- ▶ Larger lattices (obvious!)
- ▶ Keep track of measurements → brings back the sign problem due to measurement of a singlet
- ▶ "Tunable" sign problem. More measurements make the sign problem more severe.
- ▶ Can we solve it? → adapt the nested-cluster algorithm
- ▶ Immediate generalizations to different models.
- ▶ Reverse engineering: think of a Hamiltonian which will allow for positive matrix elements and/or a case where a sign problem, can be solved by meron (and fermion-bag) methods.

Thank you for your attention!