

Requirements on small machines

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thanks to EBG MedAustron colleagues and the CERN magnet/ BTS experts

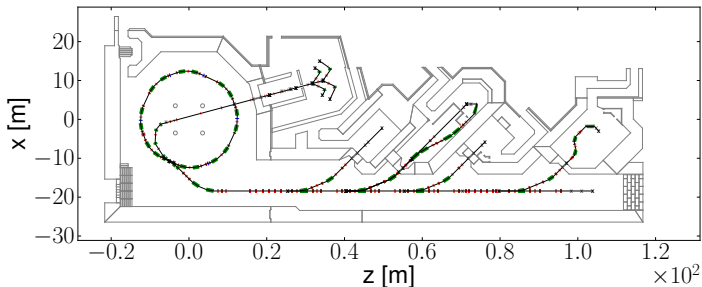
GSI, 02.12.13

OUTLINE

- ① What is special about small machines?
- ② Requirement finding
- ③ Practical examples
- ④ Summary

**What is special about
small machines?**

Small but beautiful



- ▶ Synchrotron based hadron therapy center
- ▶ Based on CERN-PIMMS & technical implementation by CNAO
- ▶ Accelerator developed under the guidance of / at CERN
→ incl. e.g. magnet design & magnetic measurements.
- ▶ Currently in the MEBT beam commissioning phase



Small machine specialties 1

- ▶ Often green-field facilities - little or no expertise
 - Staff learned previously on other types of machines
 - “wrong” specifications
 - Experts are only needed for some time and then move on
 - 24/7/365 operation with only rudimentary trained staff
- ▶ Very small optics team
 - No time for detailed studies
 - Once machine is set up, it must run maintenance free without experts
- ▶ Uptime requirements: $> 95\%$ @ 24/7/340

e.g. uninterrupted patient treatment
- ▶ Even less money, time, non-accelerator environment, ...

Small machine specialties 2

- ▶ Machines very densely packed
 - MedAustron synchrotron: 111 elements in 80m circumference
 - Elements influence each other
- ▶ Design and construction phase often overlapping
 - Some magnet parameters must be frozen before they are designed
- ▶ Some machines do not "care" about some emittance growth
- ▶ Multi-turn injections with design-60%-loss
 - Communication to injector guys who talk about 98%emittance...
- ▶ Many different cycles → automated cycle building

Small machines specialties 3

- ▶ Low energy \rightarrow Short magnets with large aperture
- ▶ Slow resonant extraction \rightarrow large horizontal aperture
- ▶ Large bending angles with small radius e.g. 90° , $r = 1.5\text{m}$
- ▶ Large edge-angles e.g. 23°
- ▶ Special magnets like betatron core, rotating elements. . .
- ▶ Off-momentum operation \rightarrow beam not centered in dispersive regions!

MedAustron: $\frac{\Delta p}{p}|_{center} = 3.5 \cdot 10^{-3} \rightarrow \Delta x = 2.8\text{cm}$

Small machine specialties 4

- ▶ “Large” number of different magnets but in small quantities
 - No real “series production”
 - e.g. MedAustron: 400 magnets, 52 different magnet types!
 - → try to use same laminations for different types
- ▶ Outsourcing to industry (partially including magnetic field measurements)

Requirement finding

Actually, it's quite basic

Requirement finding

- ▶ Analytical considerations (e.g. orbit, tune shift)
- ▶ Particle tracking studies
- ▶ Find out what's possible and design the machine accordingly
- ▶ See what other comparable machines required

Dipoles 1

- ▶ Field uniformity between dipoles:
 - Tolerances are set to what is feasible and then correctors are added as required by simulated orbit excursions.
 - HIT powers each dipole individually
- ▶ Field uniformity within individual dipoles:
 - Given by the slow resonant extraction
 - Preservation of spiral step from electric to at magnetic extraction septum.
 - MedAustron: For $\Delta B/B = \pm 2 \cdot 10^{-4}$ → the trajectory is shifted by 1 mm reducing the gap at the magnetic extraction septum

Dipoles 2 - Eddy currents

Case:

- ▶ Magnet laminations: 1.5 mm
- ▶ Vacuum chamber thickness: 0.3 mm
- ▶ \dot{B} : 3 T/s
- ▶ Field level: Injection: 7 MeV/u = 0.18 T

Effect:

- ▶ Field delays $\tau = 95\mu\text{s} \rightarrow$ B-train (during the resonant extraction wanted!)
- ▶ Nonlinearities: $\Delta B/B = 1.8 \cdot 10^{-3}$

MedAustron:

- ▶ Laminations: 1mm; Vacuum chamber: 0.4mm corrugated Inconell
- ▶ Particle tracking studies showed no effects for much thicker chambers...

Gradient uniformity within individual quadrupoles

- ▶ Distortion of the working line in the tune diagram.
 - Requirement: $\Delta Q < \pm 0.00075$ in either plane. (together with other errors, $\Delta Q = \pm 0.001$)
 - $\rightarrow \Delta(GL)/(GL) = \pm 5 \cdot 10^{-4}$
- ▶ Stability of the extraction separatrix
 - $\mu_{x, MXR \rightarrow ESE} \rightarrow \alpha_{beam \text{ at } ESE}$
 - Separatrix angle change of 0.1 mrad \cong 1% beam loss on the septum wires.

\rightarrow in practice: fine tune for optimal performance

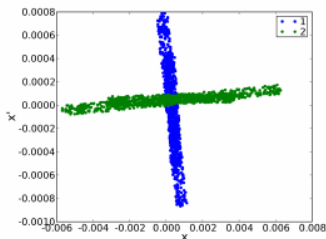
\rightarrow on the other hand: at MedAustron, the lattice tune defines the extraction energy...

HEBT: “Bar of charge” - error study

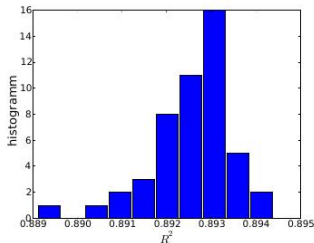
What is the figure of merit of the impact of field distortions on the horizontal phase-space of a slow resonantly extracted beam?

→ the R^2 of a line fit to it.

Bar of charge in H-phase space

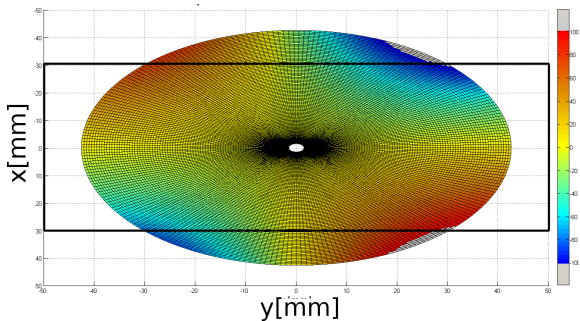


Simulation output: R^2 of line fit



Field quality measurement data representation

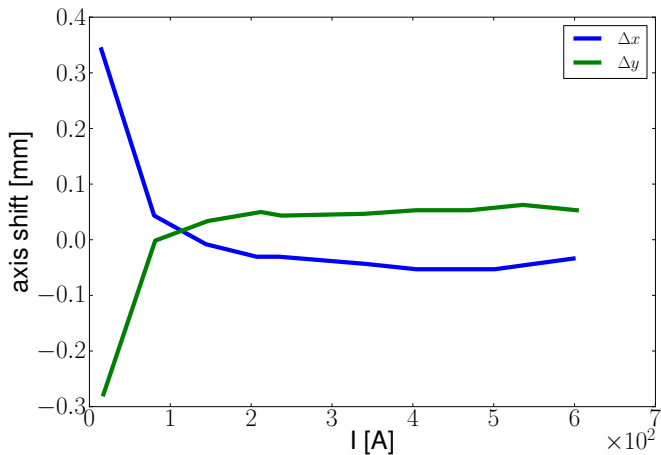
- ▶ Harmonic coefficients examples: see later
- ▶ 2D plot of $\Delta B/B$



Practical examples

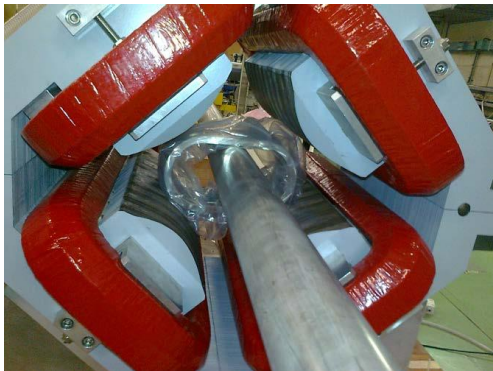
What we have encountered so far...

Quadrupoles: Systematic shift of the magnetic axis



Usually, simulations assume Gaussian distributed errors

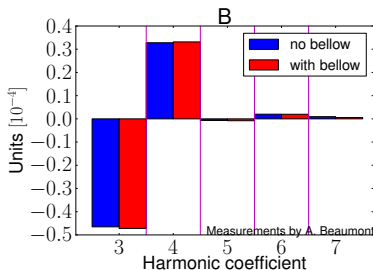
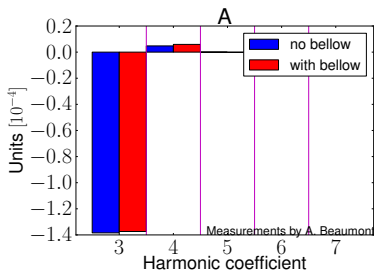
Space constraint: Bellows in Quadrupoles



Also: BPM in resonant sextupole (“fast” ramping)

Space constraint: Bellows in Quadrupoles (measurements)

MedAustron performed field quality comparison studies for with/without bellow.



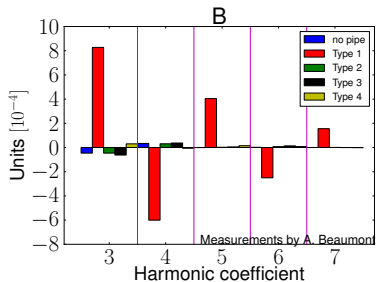
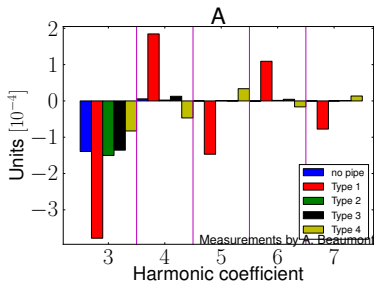
→ luckily no effect (in DC..)

Vacuum pipe welding technology



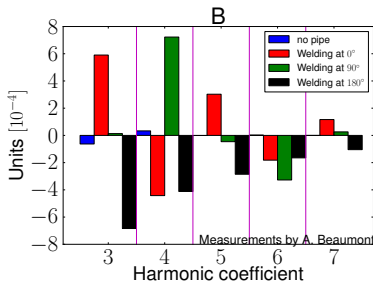
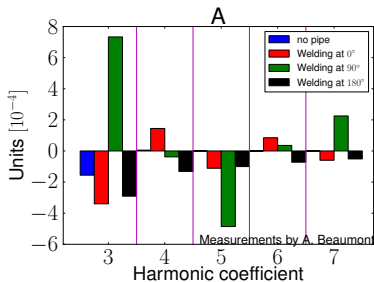
- ▶ Permanent magnet shows significantly magnetic properties at one position on the ring over its full length
- ▶ Location of the weld difficult to detect visually.

Choice of vacuum pipe welding technology



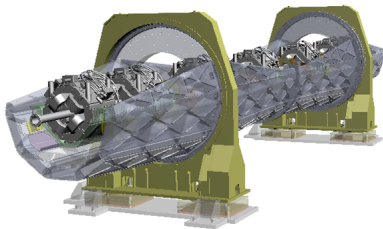
Field quality degraded by up to a factor 23!

Vacuum pipe welding: At which angle to put it?



→ The angular location of the weld does have quite an impact...

Rotator

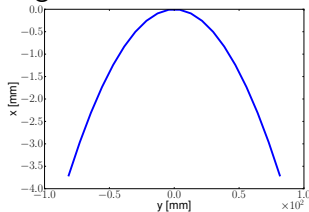


- ▶ Can the magnet be turned without loss of field quality, moving magnet axis center?
- ▶ Field measurements performed for the different angles

Large angle magnets continued

- ▶ Optics model: Quad - Dipole - Quad
- ▶ Inherent nonlinearities & coupling
 - Very large beam off-sets due to beam scanning
 - Quadrupole powered in series with scanning magnet (like PSI - gantry 2)
 - MAD-X 2nd order, other simulation programs completely fail...
- ▶ How to compare to magnet designer tracking?
- ▶ No dedicated vacuum chamber
- ▶ And then we drill a hole into the yoke....

(for X-ray "beam eye view", PSI - gantry 2)



Some more...

- ▶ Magnetic septa
 - Stray field measured where circulating one is
 - MedAustron: ramps while beam is already circulating in synchrotron...
- ▶ Coating of ceramic chambers in fast pulsed magnets magnets
 - Why in low intensity machines? (charging up). Coating specs?
 - Impact on rise time?
- ▶ Solenoid: (first iteration): only had two alignment target holders....
- ▶ Betatron core (Induction acceleration for driving the beam into the resonance)
 - Beam must not see any magnetic field
 - Power converter control loop on induced voltage of pick-up coil
- ▶ Insulate chambers on one side? Grounding of them?

Summary

- ▶ Do not under-estimate small machines
- ▶ Simulations always assume a sum of all effects! e.g. incl alignment, incl vacuum chambers...
- ▶ Extend to: “beam meets vacuum chamber meets magnets” ...
- ▶ There must be a common understanding and very close communication!

Acknowledgements

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