

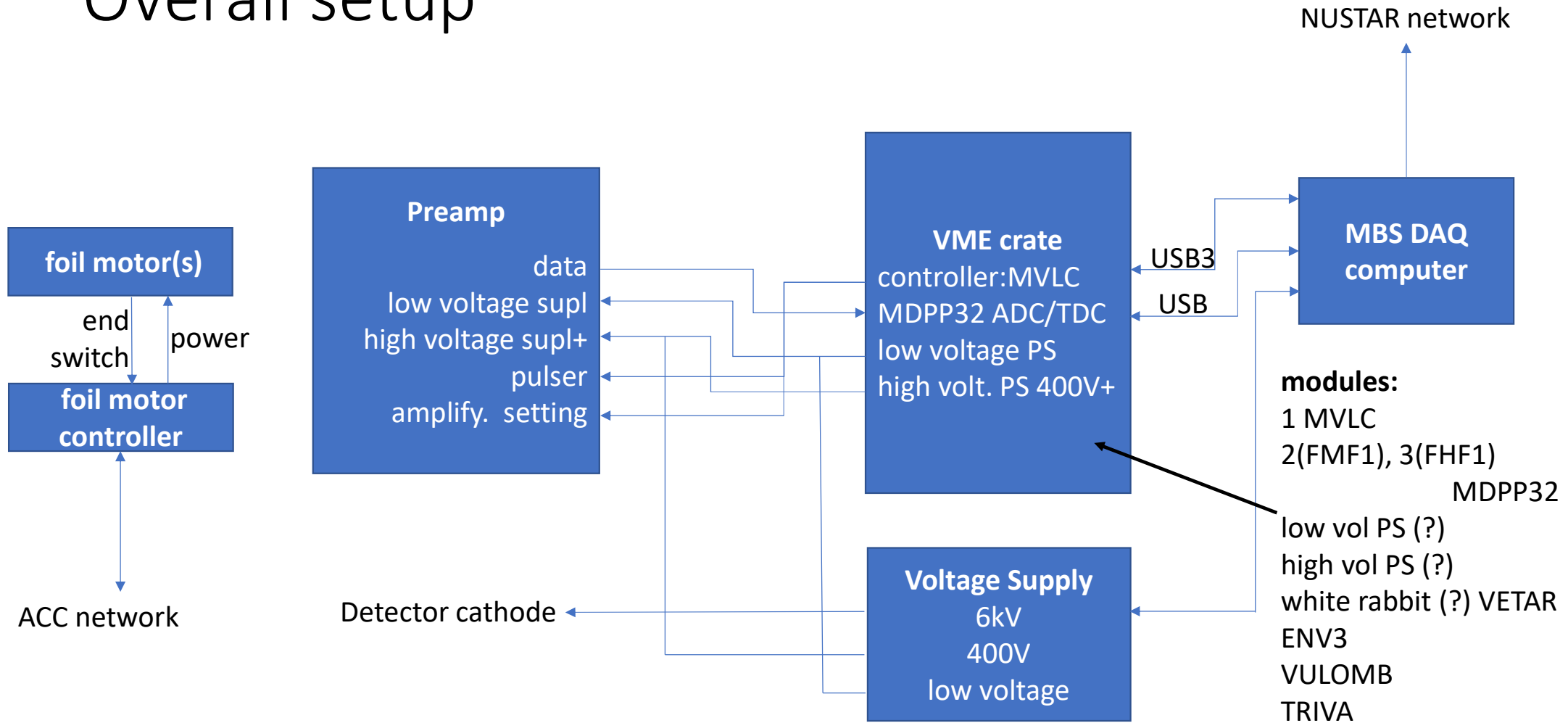
# SUPER-FRS DAQ workshop

## MUSIC

17. Nov. 2025

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# Overall setup



# MUSIC detector signals

- Control

- control preamplifier, via NUSTAR network

- amplification level
    - pulser signals

both signals are supplied by the VME crate controller and can be set via MBS commands, integration in SFRS device control still needed

- control stripper foil motors via Acc. network

- communication via acc network
    - FESA classes are written (Cosylab) and first tests are made
      - these classes can access all needed commands on the motor controller
      - Integration into SFRS device control still needed, to realise a move in/out with necessary checks
      - Connection to ELSA to inform main control room about status still needs to be made

# Trigger

- We expect a trigger signal as input to MUSIC
  - a self trigger is possible for commissioning
  - MUSIC will select a window
    - readout will then start some  $1\mu\text{s}$  before the trigger signal (buffer on the ADC)
    - readout will be in the order of  $8\mu\text{s}$  to get the full drift time
  - MDPP module has an
    - ADC section, which will provide a signal height corresponding to the amount of charge on the pad
    - TDC (CF) will provide the time of the signal
- The system is multi-hit capable, that means during an event several hits per channel can be read out.

# Signal Readout

- Setup of the MVLC (crate controller)
  - we are currently setting the MVLC using the MESYTEC provided software
  - It is possible to Send and receive commands/info to the controller via MBS
  - A script needs to be written, that can do the setup
  - Potentially one might want a user interface to control the setup (rather than editing the script by hand)
- Timing information:
  - So far we are undecided whether we will use
    - DAQ Bus to connect all devices (ToF, position, MUSIC,...) of one focal plane
    - Each system is receiving an independent white rabbit time stamp
  - I prefer the bus, and I would encourage to get a formal decision on this point asap.

# Physical Position of the systems

- Readout cable routing:
  - The readout cables go from the dome via a mobile cable handler leading the cable to the top of the big diagnostic chamber.
  - from there they need to go to the VME crate
  - cable characteristics:
    - We are using shielded bipolar cables.
    - There are a total of 96 channels for FHF1 and 64 channels for FMF1
    - We tested the cables up to 8m length
      - This would require the VME crate to be in the tunnel!
    - We should determine the shortest possible route to the VME crate outside the tunnel
      - With the upgraded pre-amplifier we can then try to test the cables (or find other cable types), which would allow us to place the VME crate outside of the tunnel.

# Physical Position of the systems

- Foil motor controller small (ca 15cm x 10cm x 10cm).
  - We know that we can transport the power over 8m.
  - If possible we would like to position the controller outside of the tunnel
    - we still need to do tests with longer cables

# Final thoughts

- July 25 run issues:
  - version of VETRA firmware introduced synchronisation issues
    - needs to be looked into by EEL
  - Some issues with compatibility between DRASI and MBS versions of lmd files
    - Do we have a clear definition on the format of mdl.