



**FSP ALICE**  
Erforschung von  
Universum und Materie



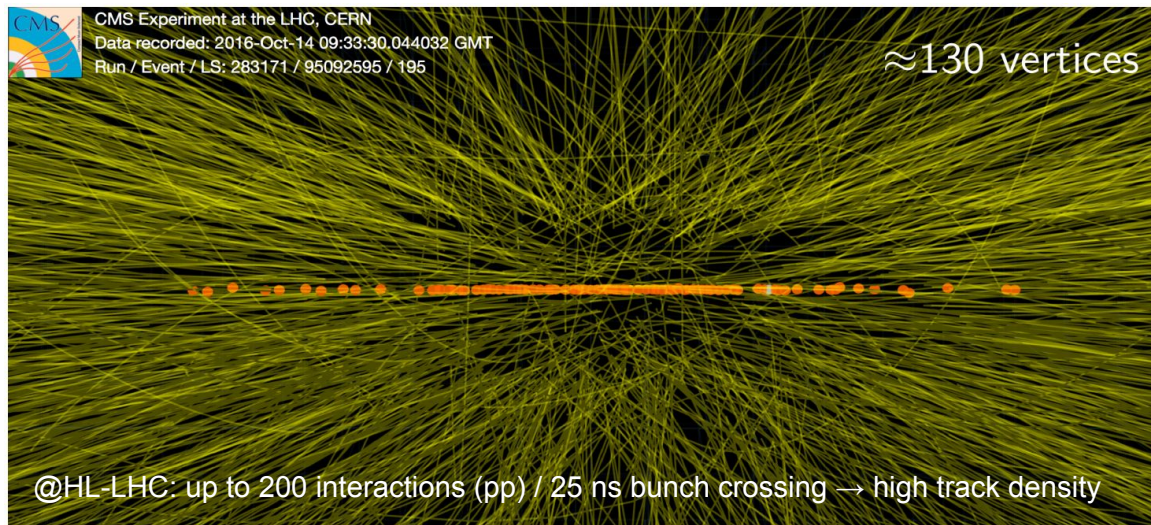
DPG Spring Meeting Köln, 10.03 - 14.03.2025

# Precision redefined: Unlocking new frontiers with Monolithic Active Pixel Sensors (MAPS)

**Bogdan Mihail BLIDARU**  
(GSI Helmholtzzentrum für Schwerionenforschung GmbH, Darmstadt)

12.03.2025

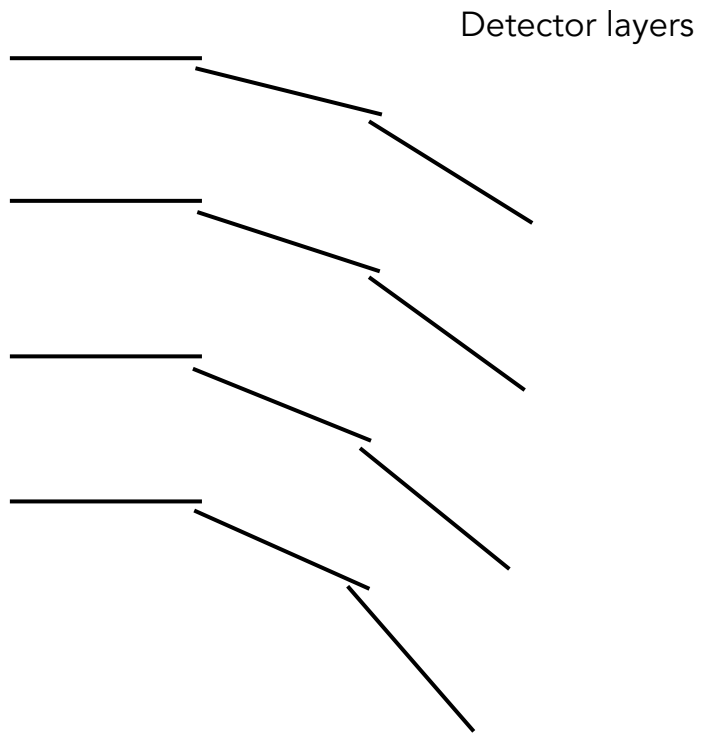
- ⇒ A common challenge in experiments:  
confusion scales with the number of collisions and/or the **track multiplicity**
- ⇒ How to tackle this problem in our trackers?



- ⇒ The rise of **pixel sensors**
  - detectors at accelerators
- ⇒ (some) current **MAPS**  
(monolithic active pixel sensor)  
technologies and advances

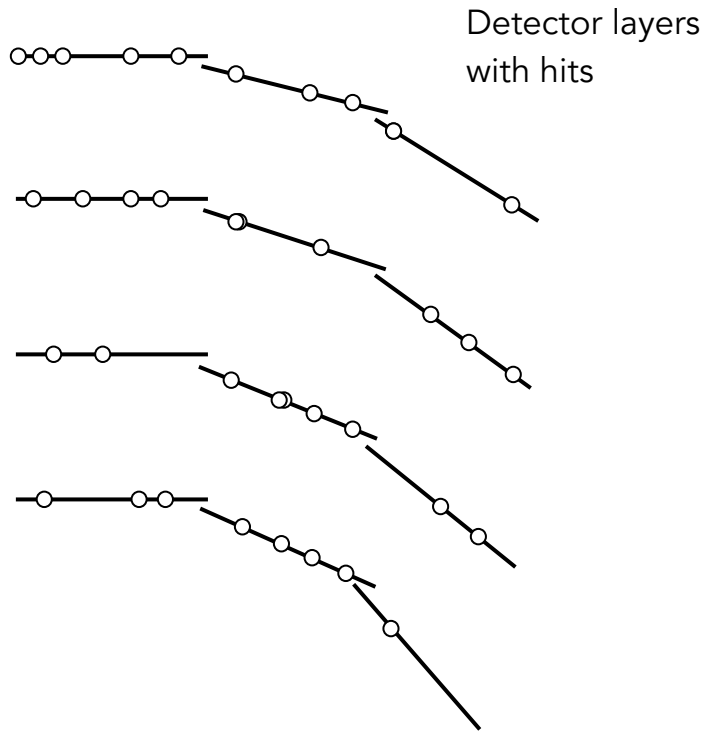
Information collated from various sources (list not exhaustive):  
ECFA, L. Linssen, E. Sicking, R. Santoro, A. Kluge, M. Mager,  
J. Pater, S. Spannagel, F. Hugging, M. Winter, L. Huth,  
P. Leitao, F. Reidt, W. Snoeys

# From hits to tracks



X ← One collision just occurred

# From hits to tracks



➡ **Snapshots** of collision

Canon EOS RP Mirrorless Camera



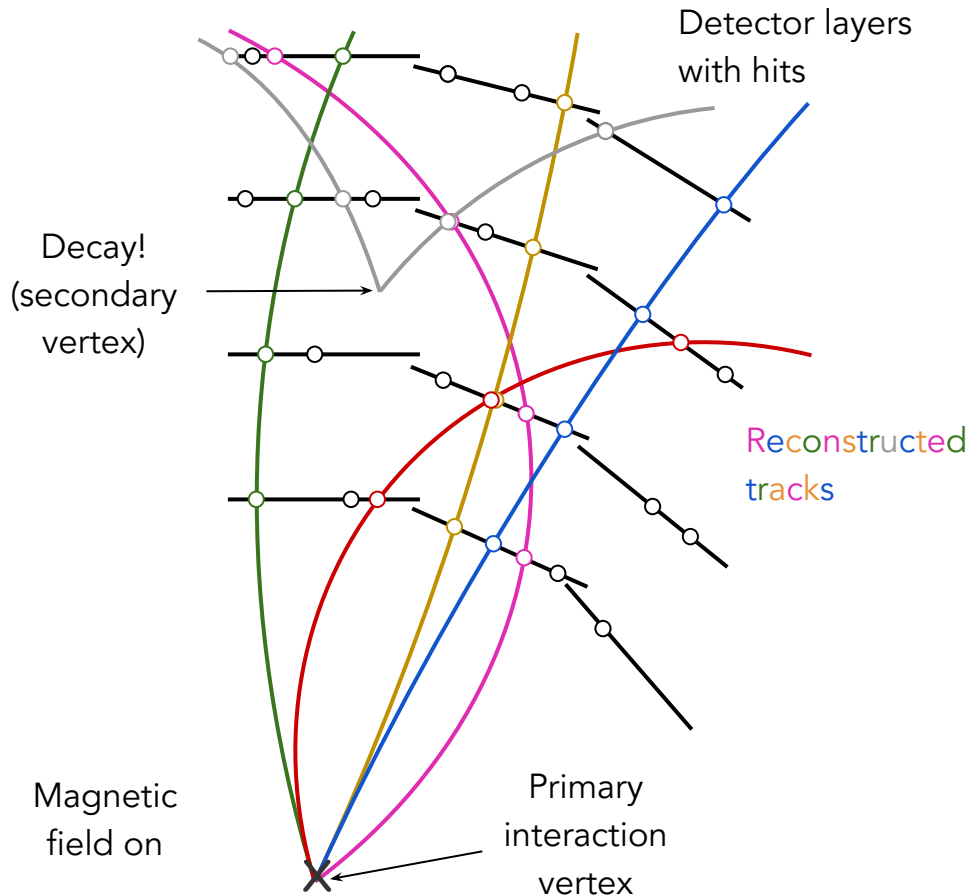
➡ Particles need to be tracked with detectors  
▶ **Surround** the collision point

➡ Name of the game: associate points  
to tracks (of particles)

X

← One collision just occurred

# From hits to tracks



⇒ **Snapshots** of collision

Canon EOS RP Mirrorless Camera



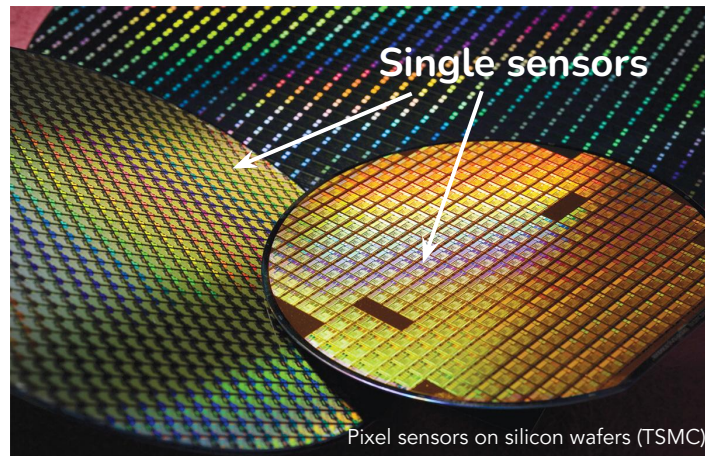
We need just the sensor

⇒ Particles need to be tracked with detectors  
‣ **Surround** the collision point

⇒ Name of the game: associate points to tracks (of particles)  
‣ **Pixel sensors**

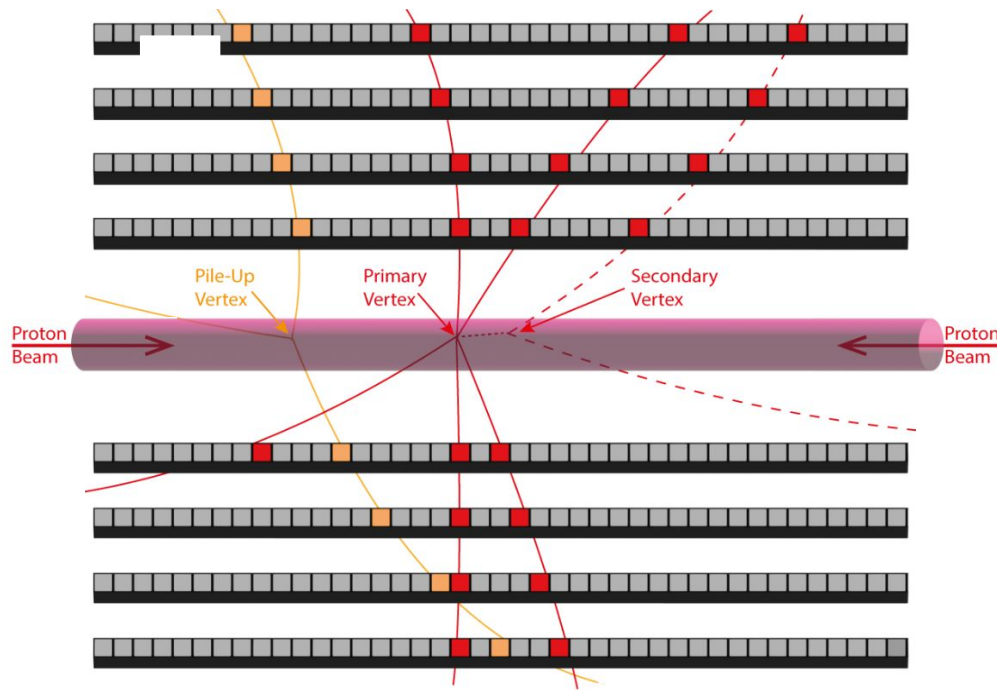


- Tracking & vertexing
- High granularity
- Close to the interaction point
  - harsh environment
- Ubiquitous
- Various designs for various experimental needs



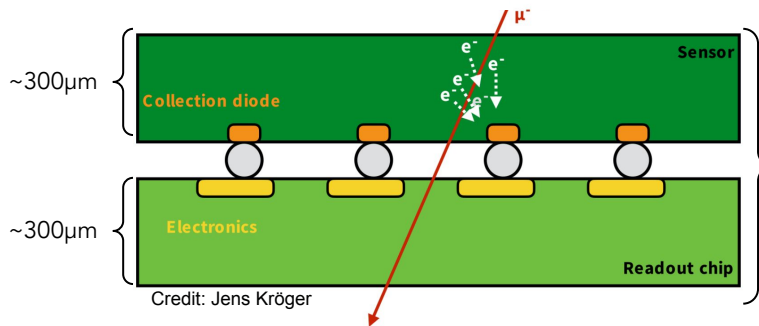
# Requirements of a vertex detector

- ➡ **Position resolution** ( $\sim \mu\text{m}$ )
  - ▶ where the particle was
  - distinguish secondary vertices
- ➡ **Timing resolution** ( $\sim \text{ns}$ )
  - ▶ when the particle passed
  - Overlapping signals
- ➡ **Efficiency** ( $> 99\%$ )
- ➡ **Radiation tolerance** (hardness)
  - ▶ keep working under particle-induced radiation exposure



<https://arxiv.org/pdf/2501.06896>

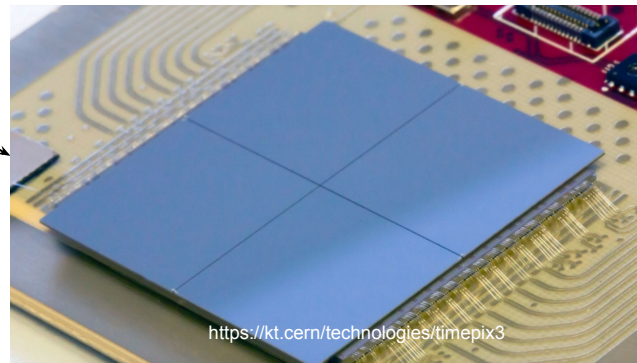
# Hybrid vs monolithic designs



Hybrid pixel sensor

- ▶ high radiation hardness
- ▶ fast (charge collection via drift)
- ▶ complex fabrication
- ▶ large material budget (thick)

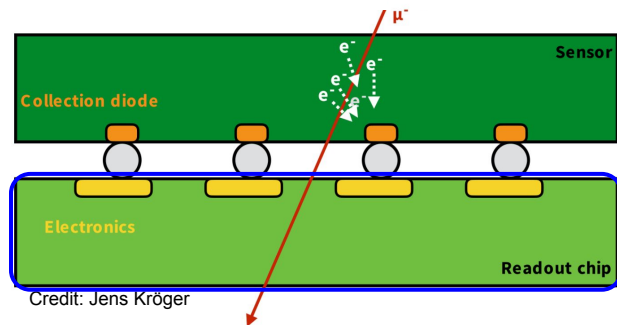
**Example** of readout chip: Timepix4 chip  
▶ 4 edgeless Si sensors on top



Other examples: VeloPix, FE-I4, RD53A, ITkPixV2, ...

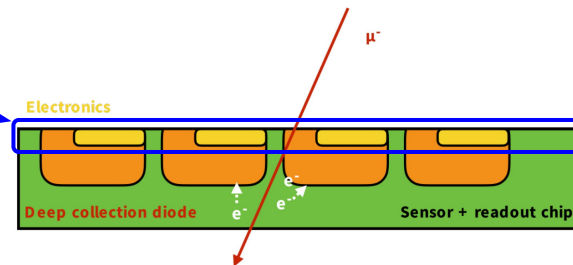


# Hybrid vs monolithic designs



Hybrid pixel sensor

- ▶ high radiation hardness
- ▶ fast (charge collection via drift)
- ▶ complex fabrication
- ▶ large material budget (thick)



Monolithic pixel sensor

- ▶ moderate radiation hardness
- ▶ commercial process (cheap)
- ▶ complex design
- ▶ low material budget (thin)
- ▶ slow and fast → 2 variants

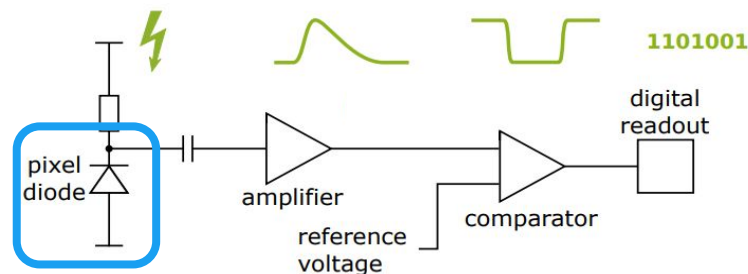
The technology choice is application driven

# Working principle of MAPS

Operation principle of a CMOS MAPS:

- ➡ energy loss via **ionization** → electron-hole pairs
- ➡ movement (drift and/or diffusion) **induces a current**
- ➡ signal is **amplified & discriminated**

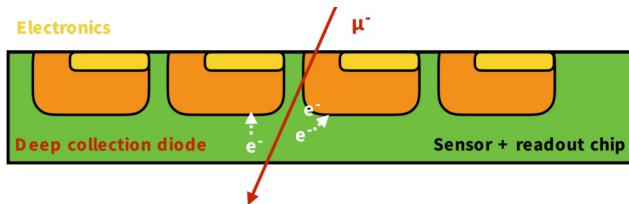
Simplified schematic



50  $\mu\text{m}$  thin sensor → drift:  $\sim 1\text{ns}$   
→ diffusion: up to 100ns

Front-end can be made slow →  
less power consumption

## Large diode design



- ⇒ Large bias voltage ( $\sim 100$  V)
- ⇒ Radiation tolerance
- ⇒ However, large diode
  - large input capacitance ( $> 100$  fF ; noisy)
  - increased power consumption

## Example: MuPix family

- mu3e experiment

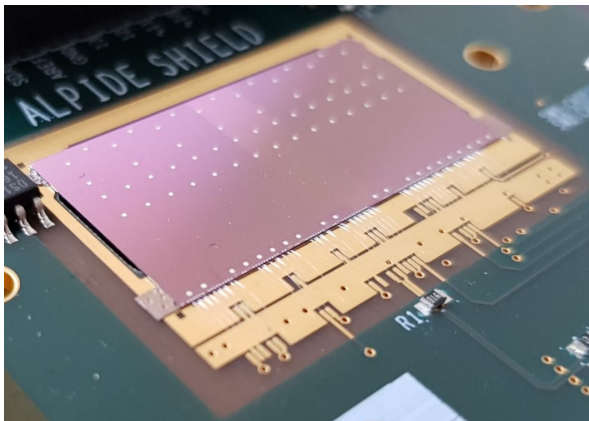


[https://indico.psi.ch/event/11934/contributions/31741/attachments/20076/32580/Prep\\_Review\\_Mupix11.pdf](https://indico.psi.ch/event/11934/contributions/31741/attachments/20076/32580/Prep_Review_Mupix11.pdf)

# HR-MAPS (High resistivity MAPS)

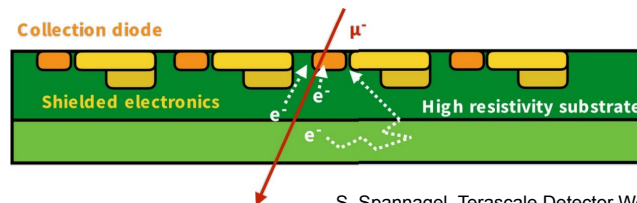
**Example:** ALPIDE sensor

► ALICE experiment @ CERN → ITS



<https://ep-es.e.web.cern.ch/project/alice-its>

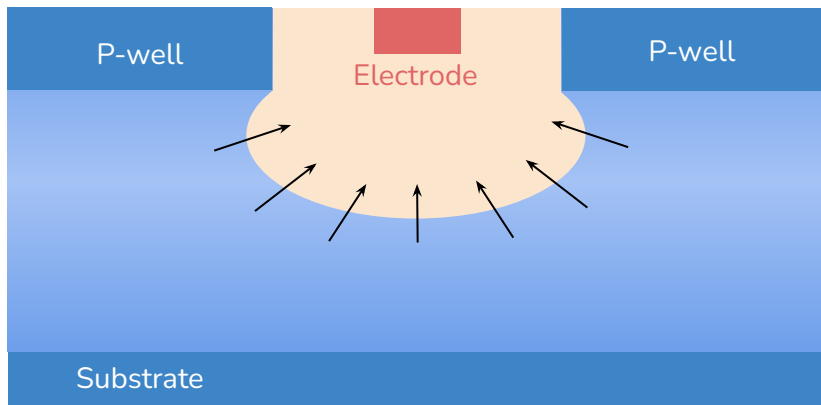
## Small diode design



S. Spannagel, Terascale Detector Workshop 2023

- ⇒ **High-resistivity** material (less dopants)
- ⇒ Small capacitance (little noise)
- ⇒ Slow (front-end)
  - **low power** → air cooling (low material)
- ⇒ Diffusion dominated
  - **moderate** radiation hardness

## Standard process

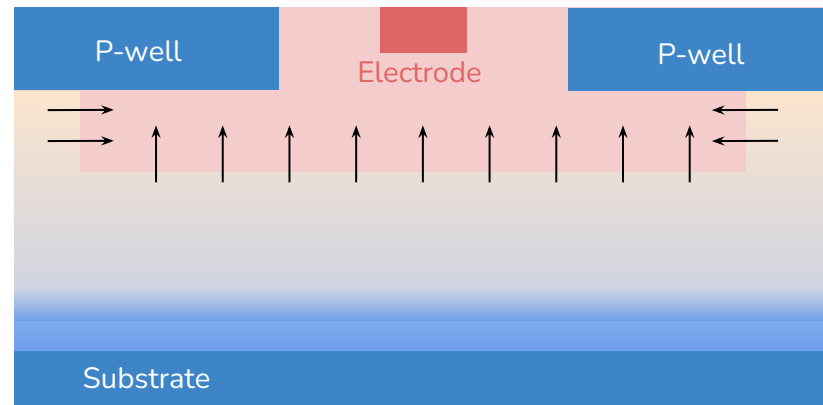


- Diffusion** dominated
- ▶ sensor not fully depleted

**improvement**



## Modified process



- Drift** dominated
- ▶ sensor can be fully depleted
  - ▶ **improved radiation hardness !!**
  - ▶  $E_{\text{field}}$  in corners

- ➡ Distinction HV & HR-MAPS (fast vs slow ↔ radiation tolerance) not so obvious anymore
- ➡ **Still, the front-end is slow (intentionally!)**
  - ▶ low power dissipation → air cooling → low material budget

- ⇒ How well a sensor **withstands radiation** damage over time
- ⇒ Pixel detectors built and installed → **no** way to **access** them for years!
- ⇒ Two main types of damage:

Ionizing radiation → charge buildup



<https://santafeglass.com/wp-content/uploads/2024/02/foggy-window-1.jpeg>

**Surface damage** → electronics

High energy particles (eg: n, p) displacing Si atoms



<https://www.reddit.com/media?url=https%3A%2F%2Fi.redd.it%2Ffx2rvnybbjwa1.jpg>

**Bulk damage** → defects



# What to pick?

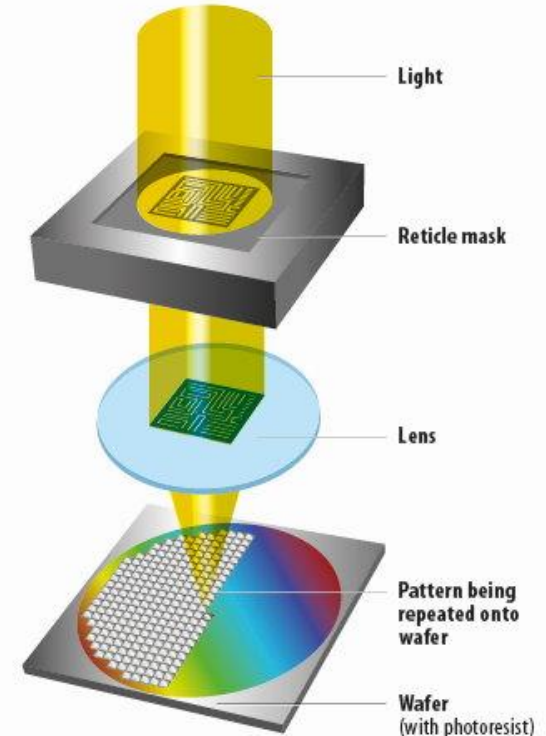
---



- ⇒ Hybrid and HV-MAPS
  - ▶ **need:** radiation hard → fast → large power consumption → cooling required → large material budget
- ⇒ HR-MAPS
  - ▶ **need:** small material budget → small power dissipation → sensor (circuitry) **made** slow **intentionally**

- ➡ **CMOS** : technology used in commercial electronic components
  - ▶ the **dominant** image sensing device
  - ▶ made of transistors
  - ▶ CMOS node ~ how small a transistor is (180 nm, 65 nm)
- ➡ **Pixel sensor**:
  - ▶ array of tiny pixels (each contains circuitry for signal processing)
  - ▶ e.g. camera in your smartphone
- ➡ **Photolithography**
  - ▶ transfer pattern, move and repeat

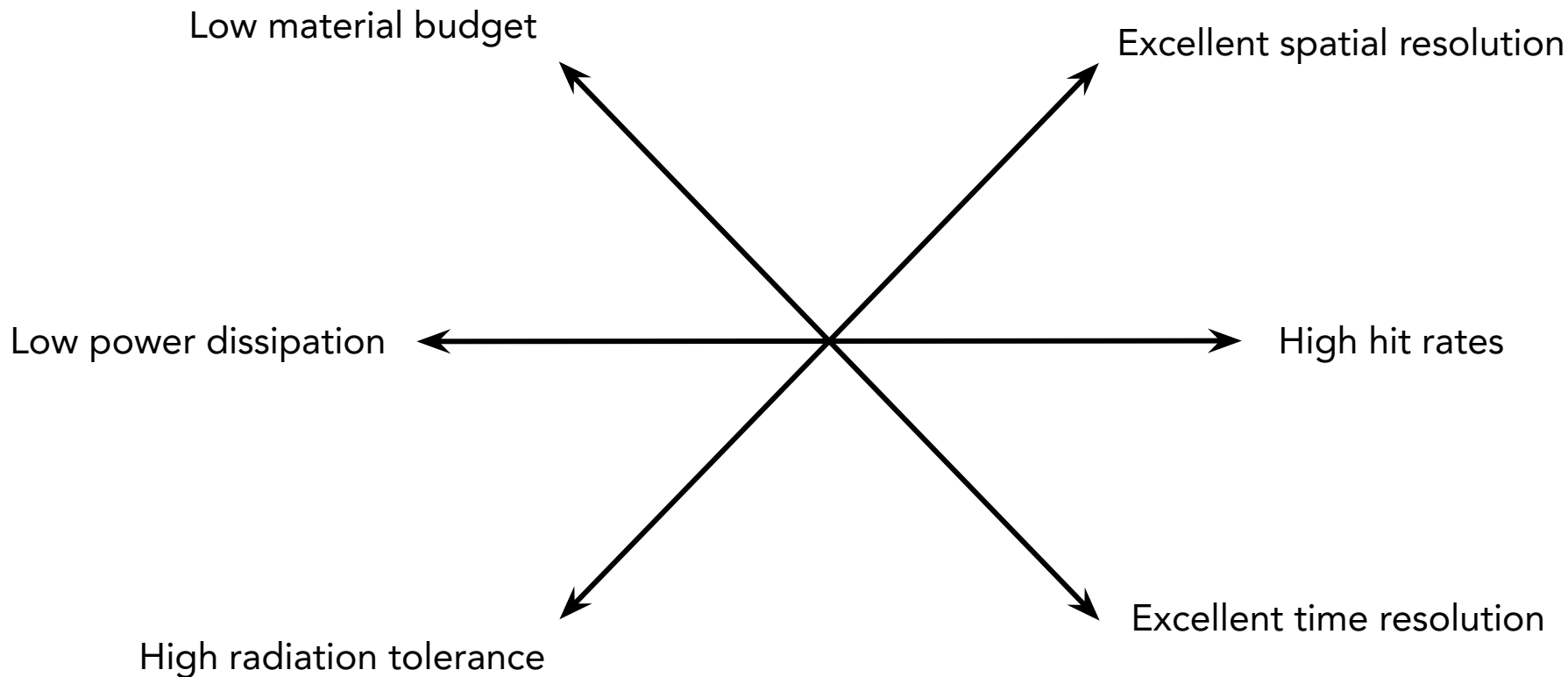
## Photolithography



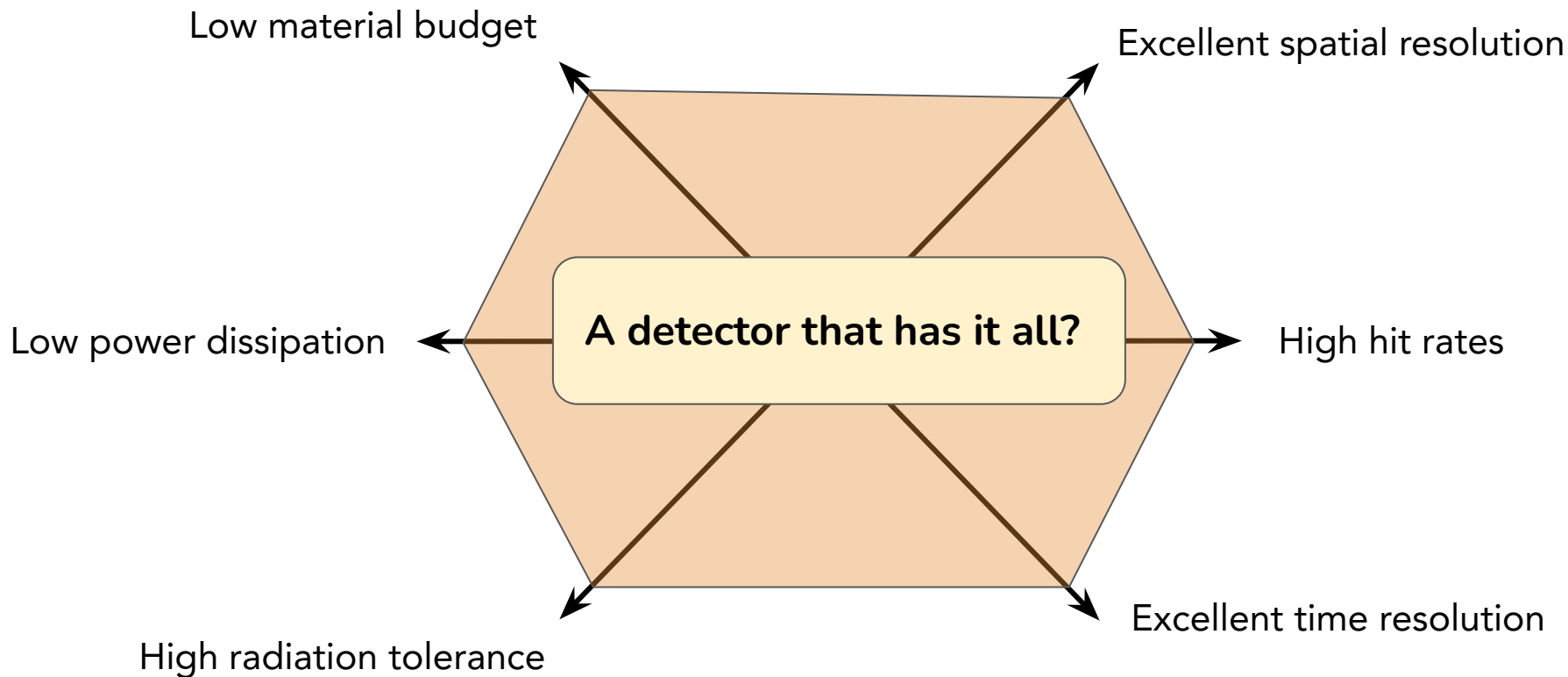
<https://www.mmmwealth.com/p/asml-deep-dive-is-the-moat-as-strong>

Consumer market	Physics
<b>Slow</b> (rolling shutter, readout = row by row) (few hundred fps)	<b>Excellent time resolution</b> (down to 25 ns) (few hundred <b>million</b> fps)
No time info stored	<b>Timestamp</b> required
<b>Small fill factor</b> (<80%) (= sensitive/total area)	<b>100%</b> (don't miss particles)
<b>70-80% efficiency</b> (enhanced images)	<b>&gt;99%</b>
—	<b>Radiation tolerant</b>
<b>Small pixels</b> (~1 $\mu\text{m}$ ) (1-4 transistors)	<b>Large pixels</b> (10–100 $\mu\text{m}$ ) (~few hundred transistors)

# Pixel detectors – orders of magnitude



# Pixel detectors – orders of magnitude



# Pixel detectors – orders of magnitude

Low material budget

Excellent spatial resolution

Low power dissipation

High hit rates



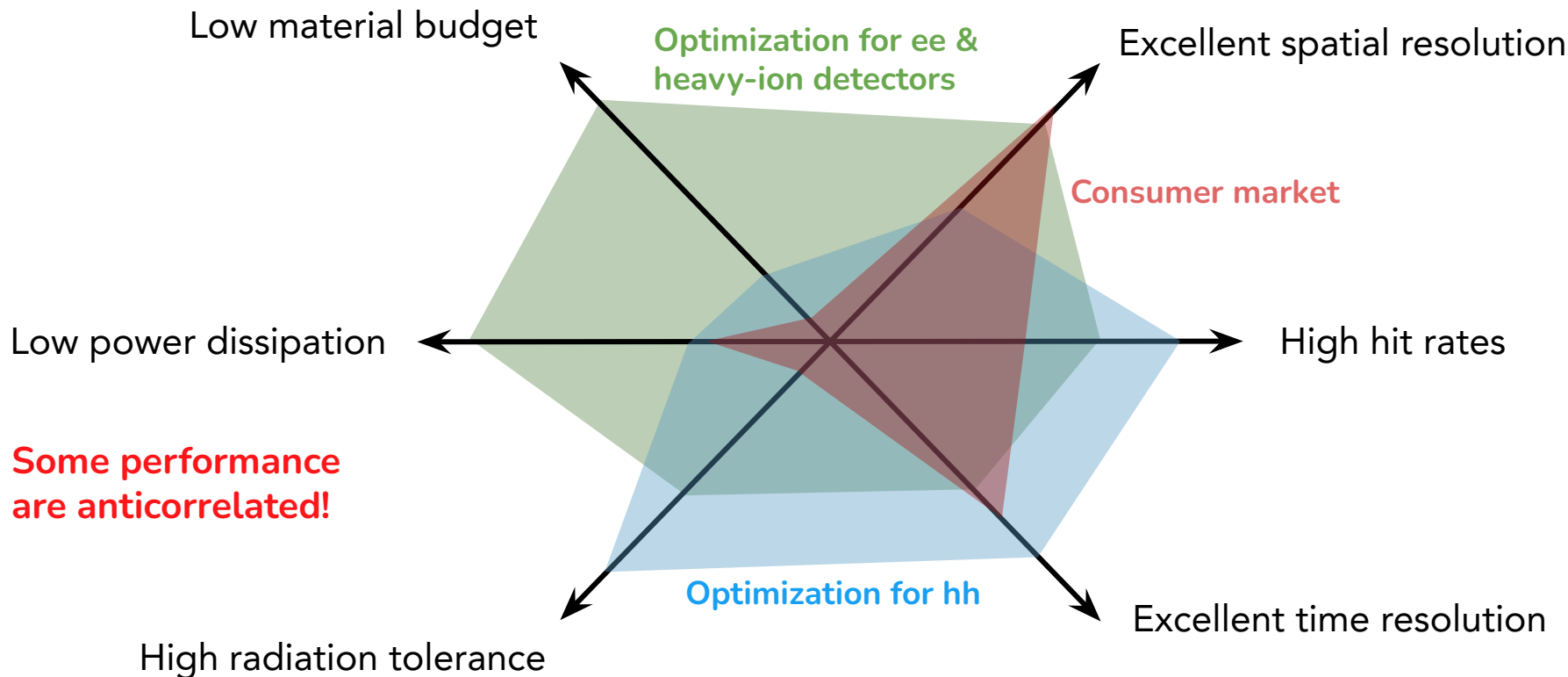
High radiation tolerance

Excellent time resolution

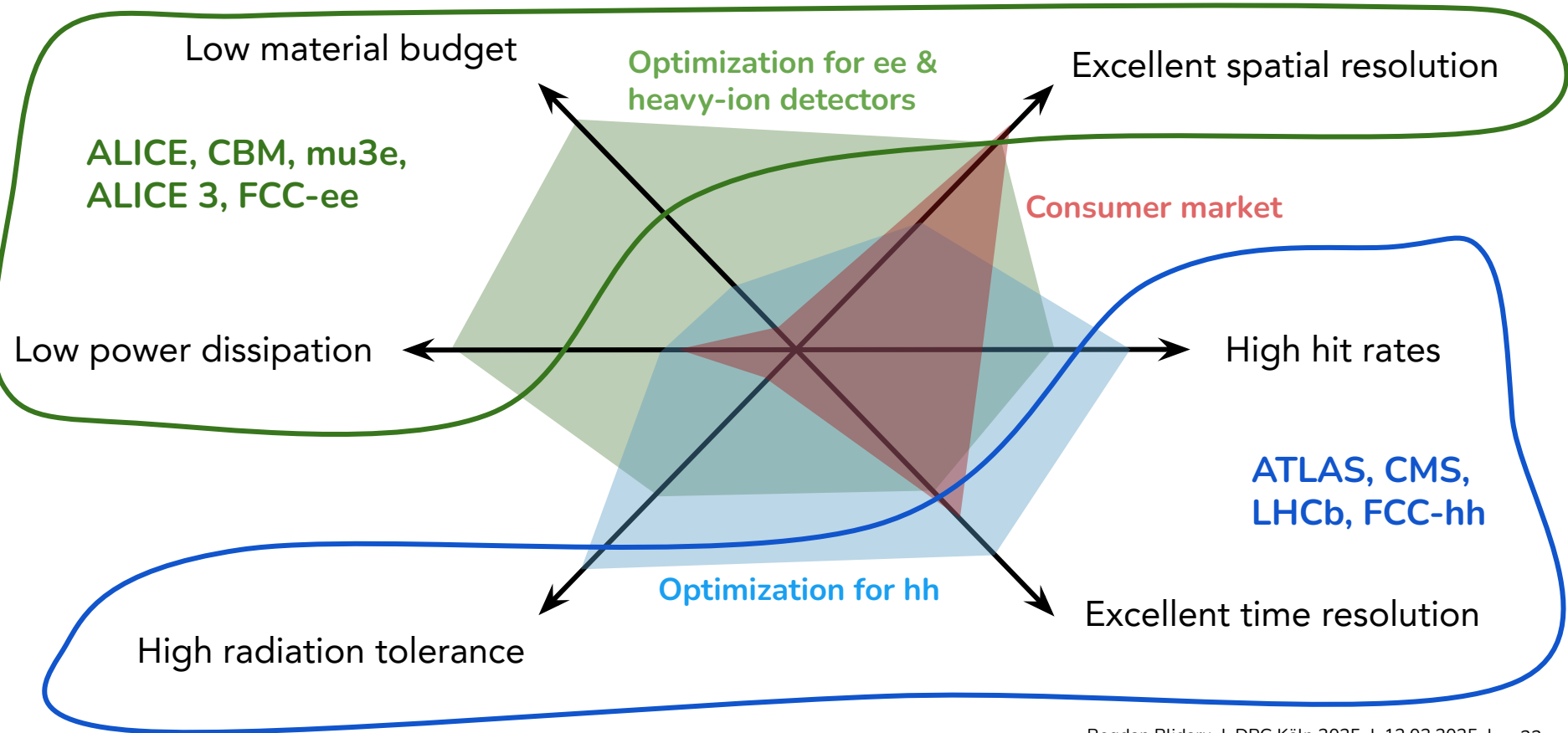
**So far, no single chip satisfies all requirements. For now compromises have to be made depending on the needs of the specific application**



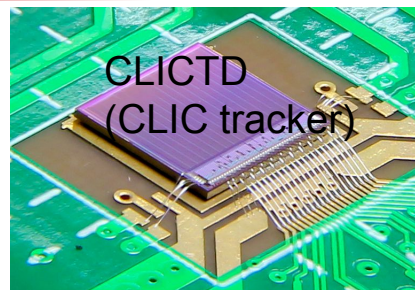
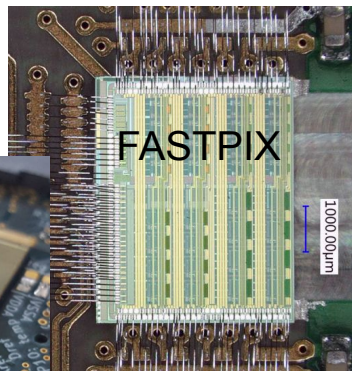
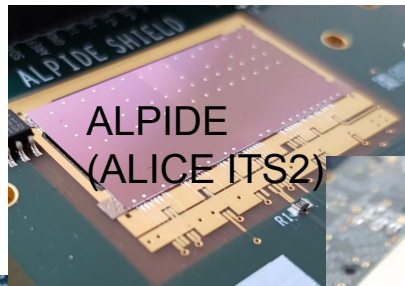
# Pixel detectors – orders of magnitude



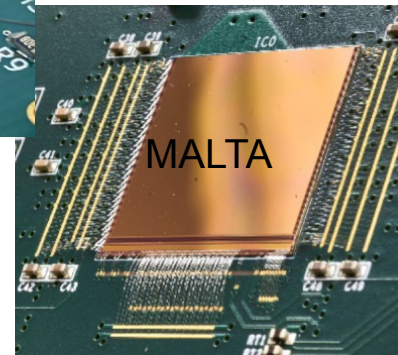
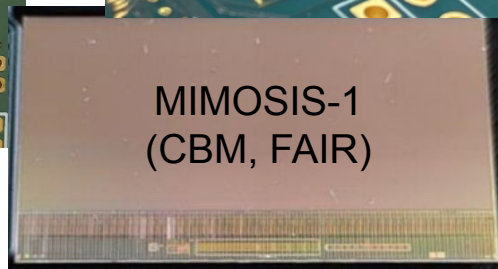
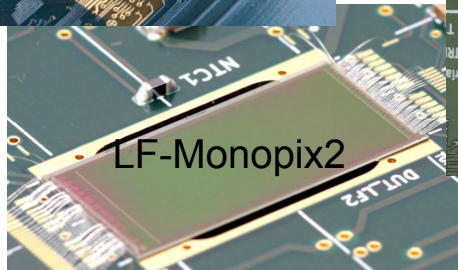
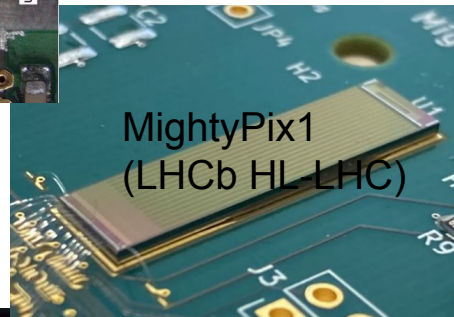
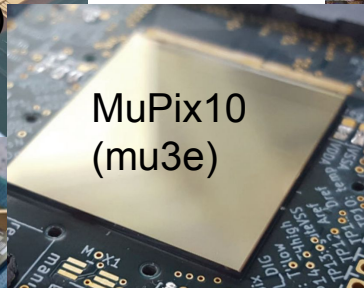
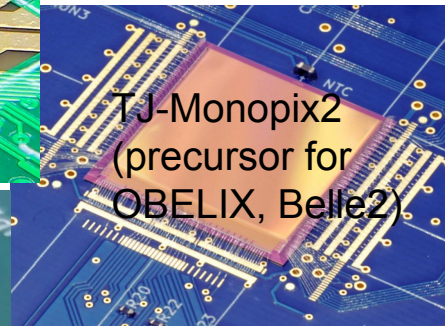
# Pixel detectors – orders of magnitude



# A myriad of MAPS



List by no means exhaustive,  
sensors not to scale



130-180nm CMOS MAPS technologies

# What can we do with MAPS?

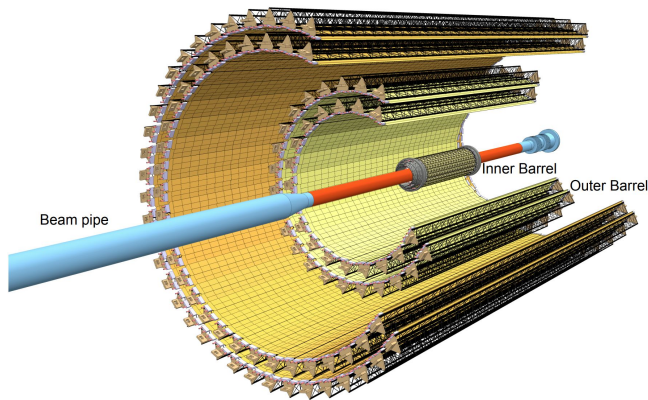
---

## Disclaimer

- ➡ Next: unique application of MAPS for heavy-ion physics
- ➡ From the perspective of ALICE → ITS3
  - reflects personal work & exciting directions

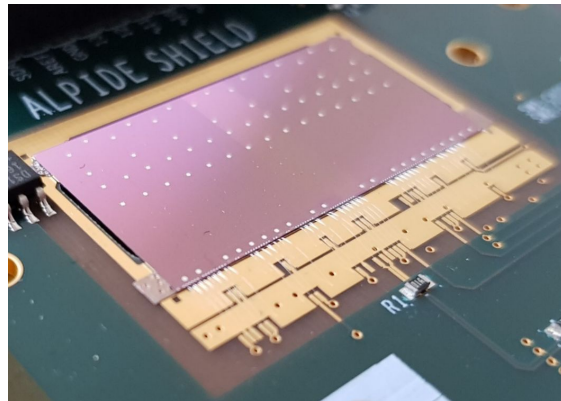
## ALICE ITS2 at CERN

- ▶ **largest MAPS** in operation ( $10\text{m}^2$ )
- ▶ 12.5 Gpx particle camera



TDR ITS Upgrade  
CERN-LHCC-2013-024

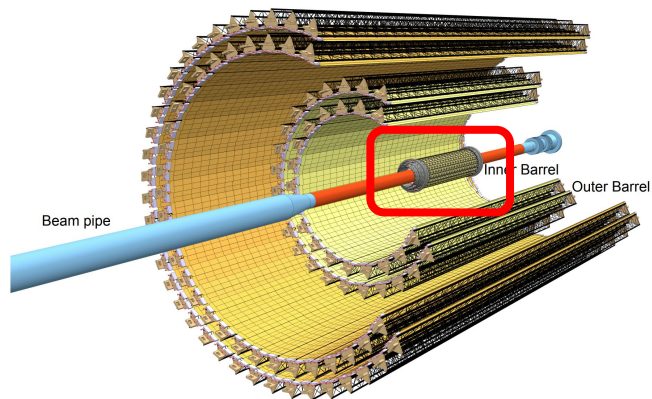
## ALPIDE sensors



- ▶ **Tailored** for ALICE needs
- ▶ Not suited for high rates and high radiation damage!
- ▶ Slow sensor (**intentionally** → front end)
- ▶ Moderate radiation damage

## ITS2 Inner Barrel

- ▶ 3 layers ALPIDE staves



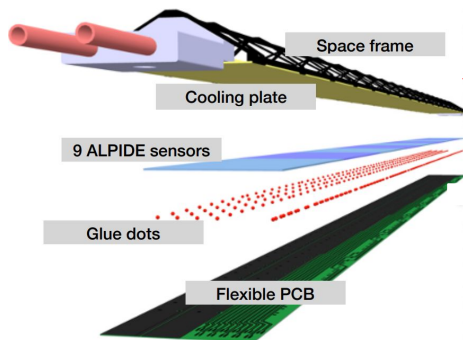
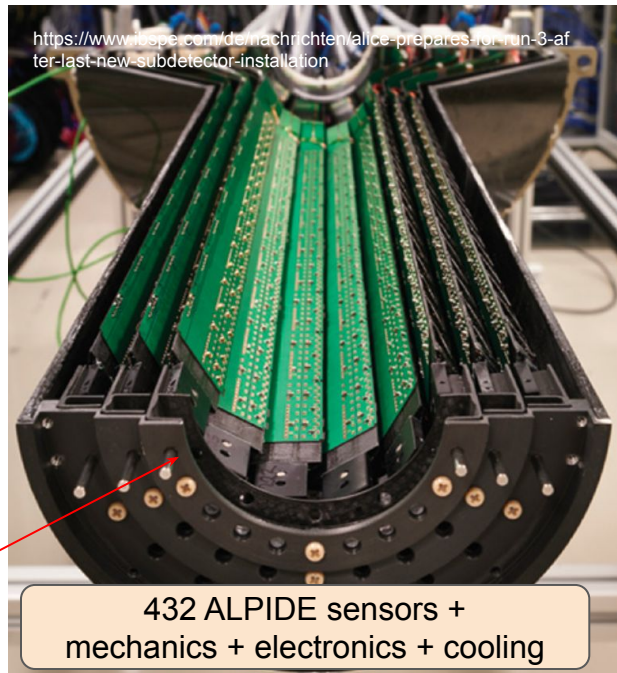
TDR ITS Upgrade  
CERN-LHCC-2013-024



## ITS2

- ▶ position resolution limited at low momentum by **material budget**

ITS2 bottom Inner Barrel (half)

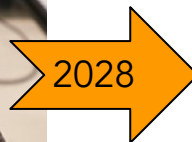
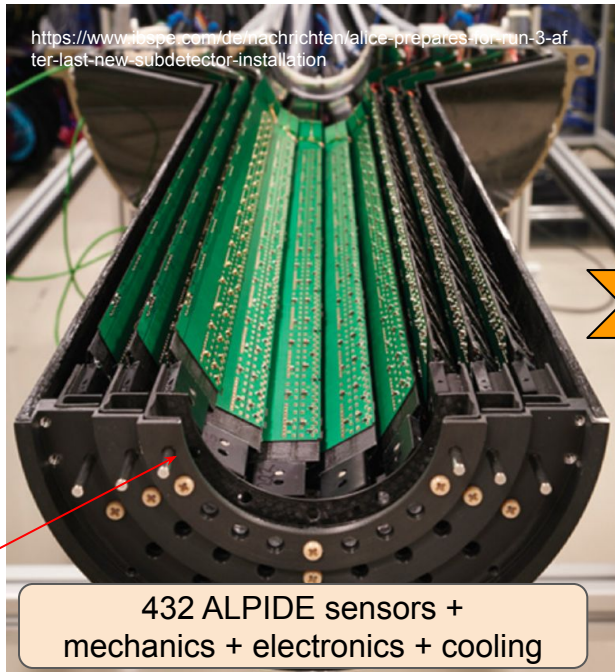


# From ITS2... to ITS3

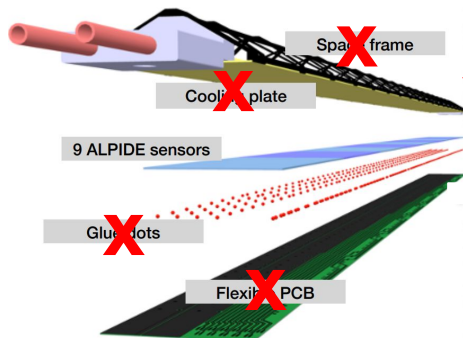
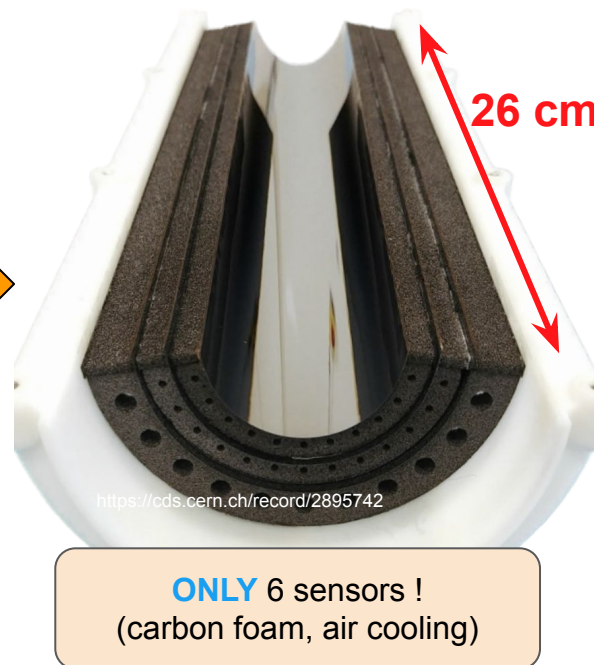
## ITS3 upgrade

- ▶ replace the 3 inner layers of the ITS2
- ▶ **ultra light**, **wafer-scale**, **curved sensors** in 65nm

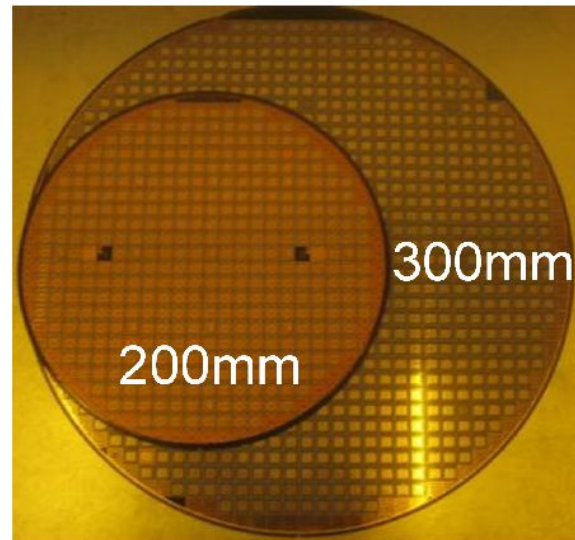
ITS2 bottom Inner Barrel (half)



ITS3 bent sensors (half)

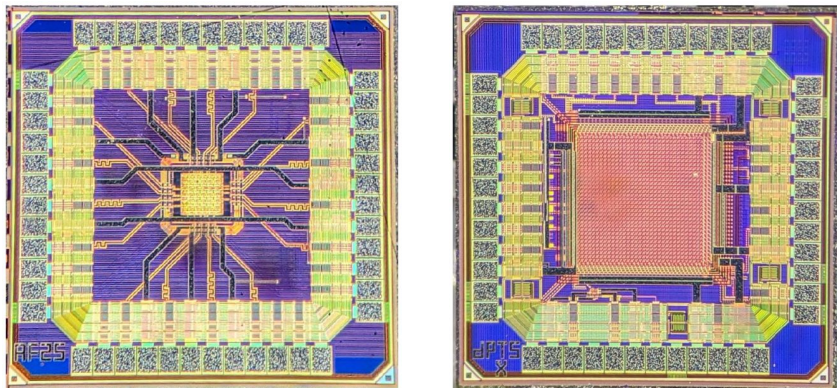


- ⇒ Change to **65 nm**
- ⇒ **More compact logic**
  - smaller pixels (more radiation hard)
- ⇒ **Larger wafers**
- ⇒ Companies phasing out **old technology**
- ⇒ Why not lower?
  - **cost**
  - **design complexity**
  - fit transistors
- ⇒ Large interest (ECFA DRD3)
  - the technology for future accelerator experiments



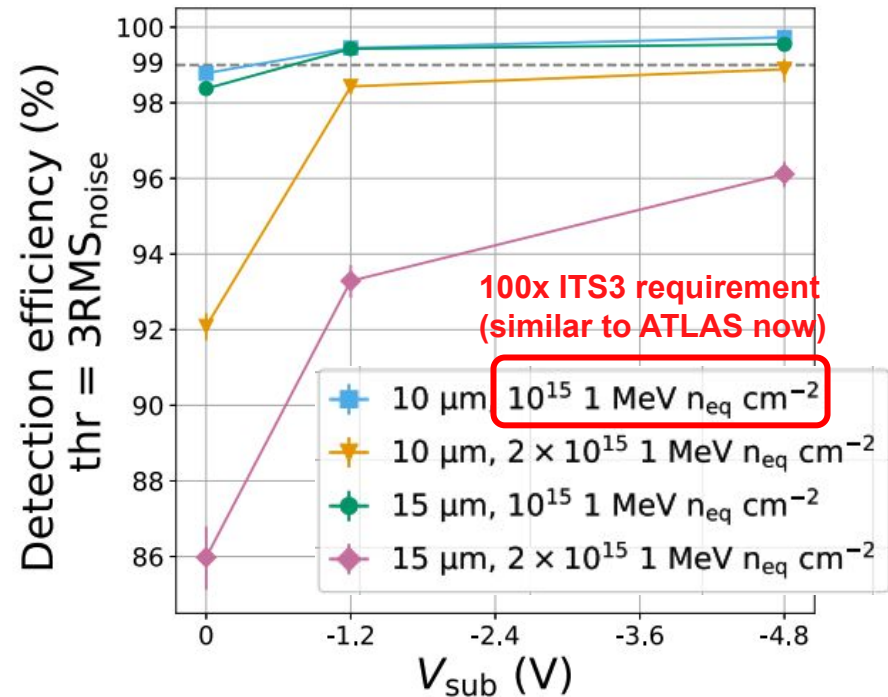
<https://ieeexplore.ieee.org/document/6142403>

# 65nm qualification studies

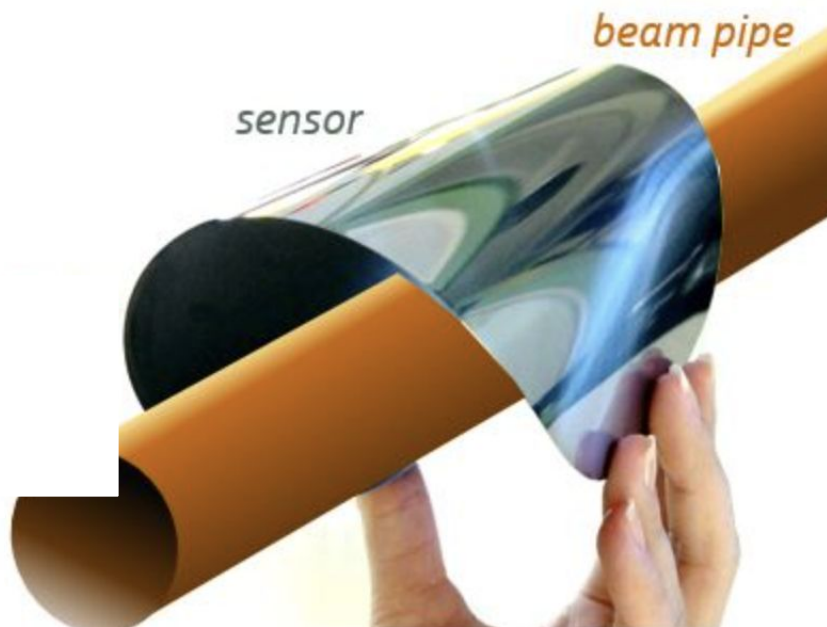


## Qualifying 65nm for usage in HEP

- ➡ Prototypes work very well!
- ➡ **>99%** detection efficiency after large radiation load
- ➡ Suited for ALICE ITS3 and even ALICE 3



More info: NIM A 1069 (2024) 169896



Not trivial!

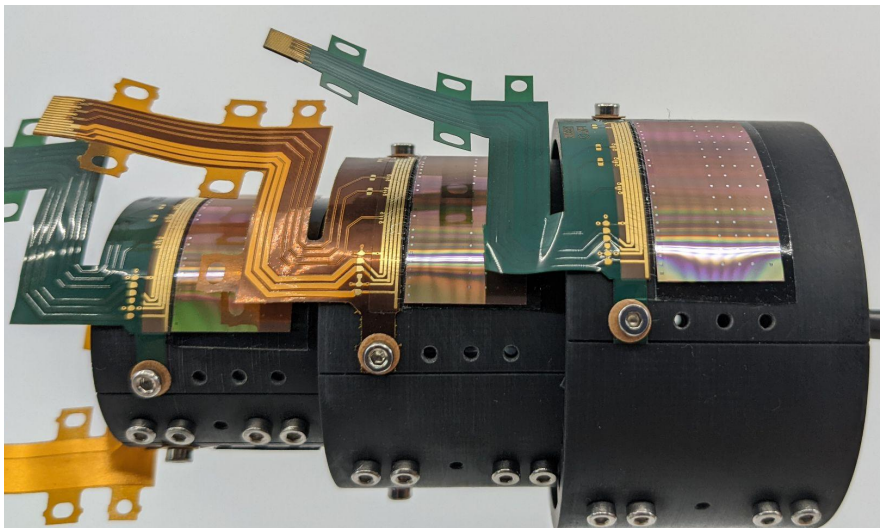
- ▶ must not break
- ▶ retain functionality



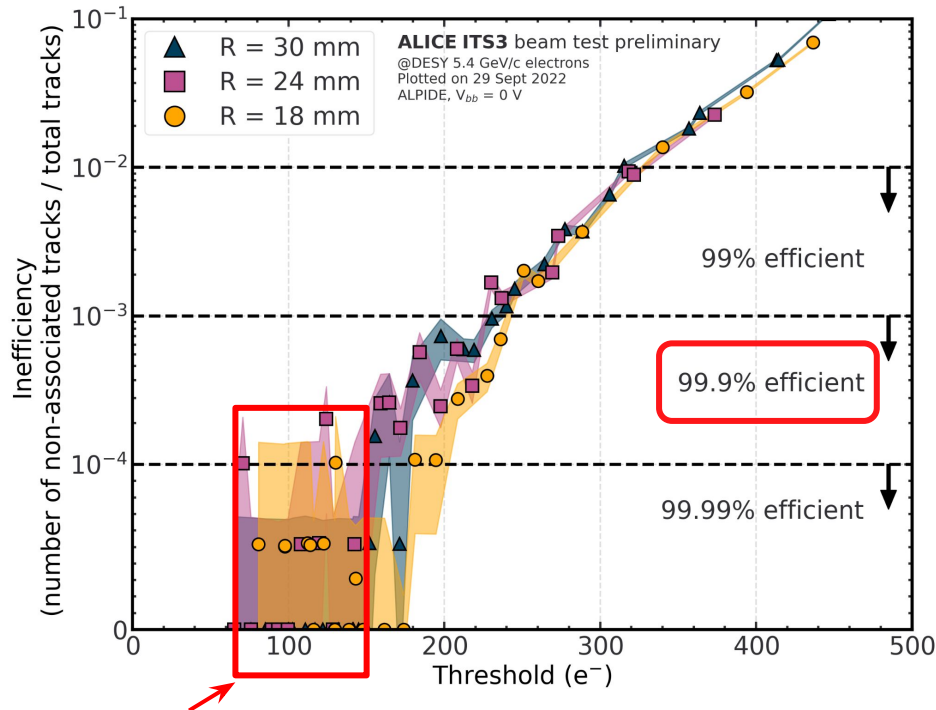
# Bending sensors

Bent MAPS **working well!** Performance unchanged!

➡ attractive design choice for other experiments



More details:  
10.1016/j.nima.2021.166280

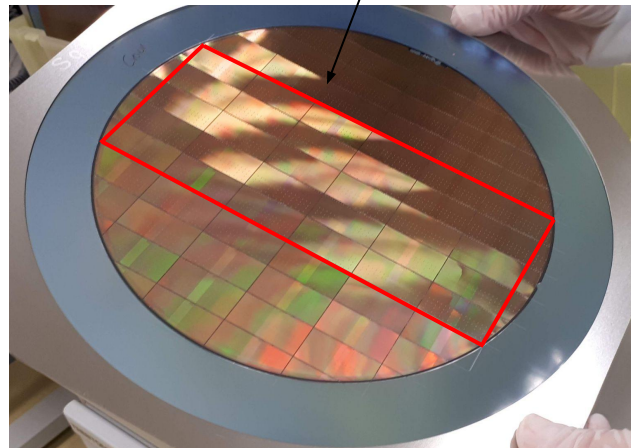




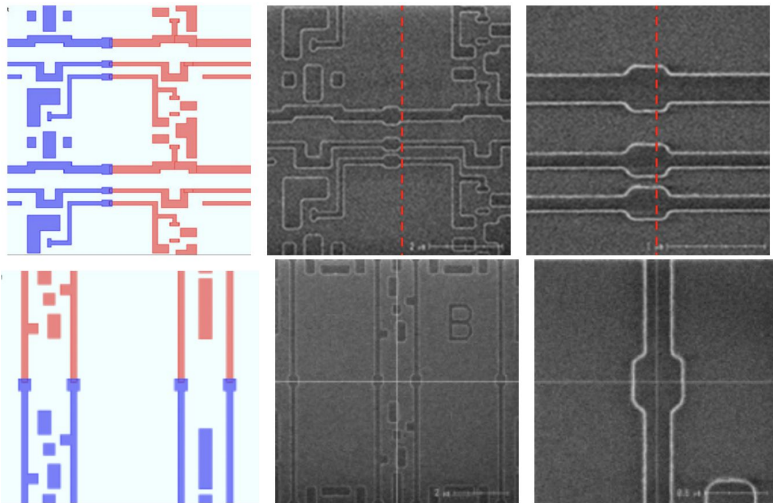
## Going wafer-scale

- ➡ Size of sensors is limited to  $\sim 3 \times 2.5 \text{ cm}^2$
- ➡ Solution: **stitching**
  - ▶ concatenation of different parts of the mask (alignment  $\sim \text{nm}$ )
  - ▶ **repetitive element** (pixel matrix) and a periphery (power and data to outside)

What we want: make this **one single sensor**!



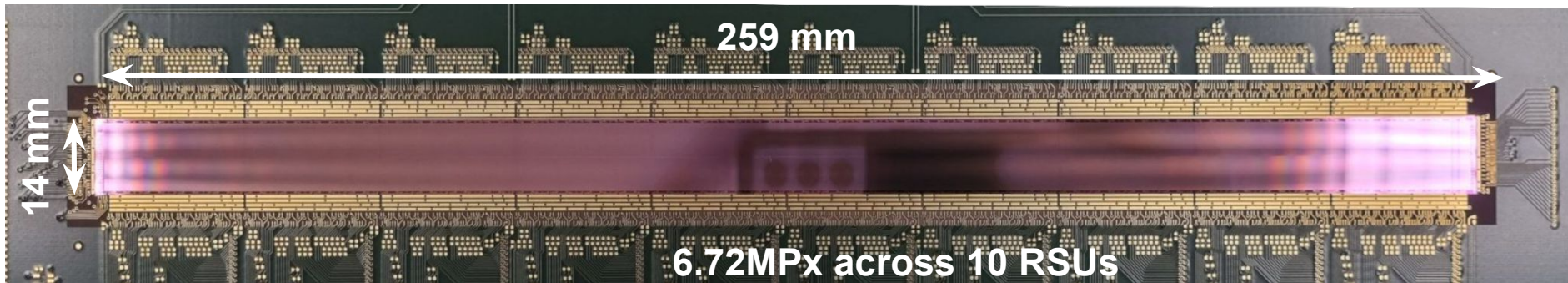
<https://cds.cern.ch/record/2748315>



[https://www.jstage.jst.go.jp/article/elex/13/15/13\\_13.20160441/\\_pdf/-char/en](https://www.jstage.jst.go.jp/article/elex/13/15/13_13.20160441/_pdf/-char/en)

## MOSS (MOnolithic Stitched Sensor)

- ▶ **fully functional** ITS3 **stitching demonstrator**
- ▶ confirmation of expected performance from small-scale prototypes



<https://indico.cern.ch/event/1255624/contributions/5443786/>

## MOSAIX

- ▶ upcoming second iteration stitched sensor (design being finalized, submission 2025)
- ▶ **full size**, fully functional, **stitched sensor prototype** for the ITS3

Andrea Dainese (HK 39.1)

## Future detectors

- ▶ predominantly made with silicon technologies

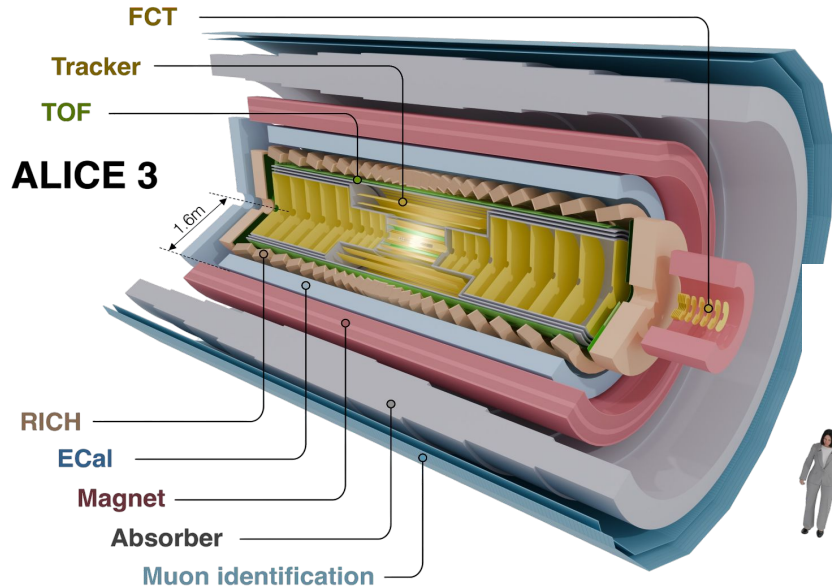
## ALICE 3 (2036+)

- ▶ tracking by Si **MAPS** → evolution from ITS3
- ▶ timing by fast Si

## Big challenges

- ▶ Large area to instrument (**70m<sup>2</sup>**)
- ▶ Sensors in vacuum
- ▶ 2.6m long staves

ATLAS pixel detector (2030+):	13m <sup>2</sup>
CMS pixel detector (2030+):	5m <sup>2</sup>
Belle II pixel detector (2030+):	1m <sup>2</sup>
CBM MVD pixel detector (2028+):	0.1m <sup>2</sup>



[https://alice-collaboration.web.cern.ch/menu\\_proj\\_items/ALICE-3](https://alice-collaboration.web.cern.ch/menu_proj_items/ALICE-3)

# Why are MAPS a must-have?

---

- ⇒ MAPS matured in the past years
  - a **plethora of prototypes** and full detectors
    - fast detectors, radiation hard
    - slower, low mass
- ⇒ CMOS MAPS are and will continue to be a **key technology** for future trackers
- ⇒ Developments in the direction of
  - timing, radiation hardness
  - all-in-one sensor (?)
- ⇒ Many institutes involved and collaborating

**GSI:** Detector Laboratory, C. Schmidt, M. Deveaux, C. Simmons, R. Visinka, O. Kiselev, P. Gasik, ...

**Heidelberg University:** A. Schöning, V. Angelov, mu3e colleagues

**CERN:** M. Mager, M. Suljic, F. Reidt, W. Snoeys, G.A. Rinella, L. Musa, A. Kluge, M. Keil, H. Hillemanns, A. Junique, P. Martinengo, M. Winter, M. Campbell, W. Riegler, M. Colocci, L. Lautner, M. Angeletti, C. Gargiulo, ...

**IPHC Strasbourg:** J. Baudot, A. Dorokhov, A. Maire, ...

**DESY:** S. Spannagel, L. Huth, R. Diener, N. Meyners, M. Stanitzki, P. Schutze, H. Wennlöff, F. Feindt, S. Lachnit, A. Simancas, S.R. Daza, G. Vignola, ...

**KIT:** M. Caselle, F. Simon, ...

**My colleagues** (GSI & HD): S. Masciocchi, A. Dubla, R. Auerbeck, D. Miskowiec, A. Schmah, K. Schweda, P. Becht, S. Groß-Bölting, M. Menzel, B. Buttwill, J. Hensler, A. Kaiser, F. Koenigstein

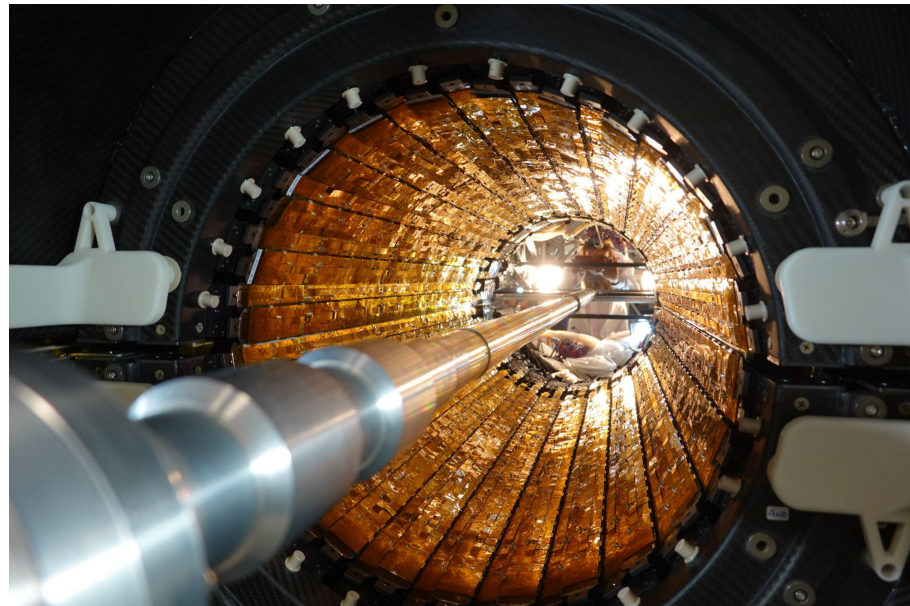
**ALICE Germany** colleagues involved in MAPS

# Thank you!

---

*"From their beginnings at CERN half a century ago, silicon pixel detectors for particle tracking have blossomed into a vast array of beautiful creations that have driven numerous discoveries, with no signs of the advances slowing down"*

– Chris Damerell (Rutherford Appleton Laboratory)  
(<https://cerncourier.com/a/tracking-the-rise-of-pixel-detectors/>)



<https://cerncourier.com/a/alice-tracks-new-territory/>