

# **SODANET Specifications**

## **And Current Status of the Implementation**

M. Drochner, M. Kavatsyuk, H. Kleines, P. Lemmens,  
J. Michel, M. Palka, P. Schakel



# SODA Workshop (January, GSI)


## Responsibilities, time scales, resource requirements

- Study group to define SODA protocol for SODAnet
  - Myroslav Kavatsyuk, {Chair} Peter Lemmens, Peter Schakel, (KVI), Marek Palka (Krakow), Matthias Drochner, Harald Kleines (Jülich), Jan Michel (Frankfurt, consulting)
    - Results should be reported during the April DAQ Workshop
- Feasibility of synchronous timing with TRB V3 (jitter measurement)
  - Marek Palka (Krakow), Jan Michel (to be approved by J.Stroth)
    - Should be ready by mid February
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- Implementation SODAnet source on TRB3
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## Open questions

- Explore potential synergies between CBMnet and SODAnet
- Explore hardware options for burst-building network

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      - Results should be reported during the April DAQ Workshop
  - Tested by Jan Michel and Michael Traxler (January 16):
    - Synchronous connection works for TRB V3
    - First recovery of a clock: 30 ps jitter (10 ps from oscilloscope)
    - 6 recoveries in chain: 40 ps jitter
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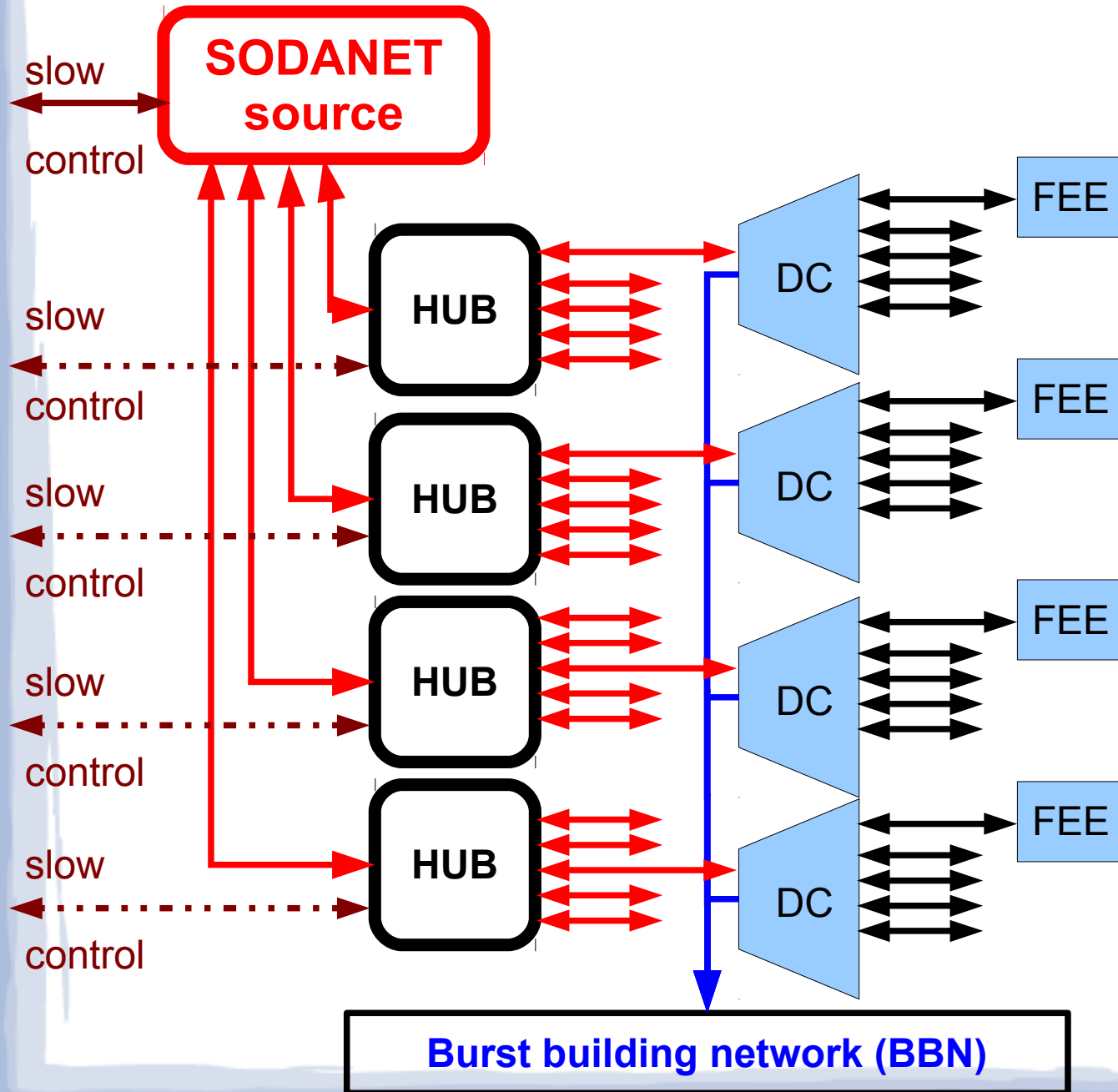
## Design considerations:

- Preserve readout topology as defined in the PANDA TPR
- Reuse as much as possible code of the TRBNET
- Key changes of the TRBNET compatible with the CBMNET protocol

## SODANET provides:

- synchronization of the FEE
- Continuous monitoring of the DC/FEE functionality
- Rough (initial) time calibration of the propagation time of the synchronization signal
- Transfer of a slow-control (FEE configuration/status) information: low priority, transmission of a slow-control package can be interrupted at any time by a synchronization package

# SODANET Topology



## SODANET link:

- Bidirectional
- Synchronous (only in one direction)
- Transfer:
  - source → DC: synchronization information and FEE configuration
  - DC → source: slow control, used for time calibration

## Data link (DC → BBN):

- Unidirectional Ethernet

## Link DC ↔ FEE:

- Bidirectional, synchronous
- Protocol up to subsystem

# SODANET Synchronous Packages

**SODANET protocol foresees two types of sync. packages:**

- Command data: issued at any time
- Super-burst start (**super burst = 16 bursts of 2.4  $\mu$ s**): issued at the beginning of each Super-burst

## Package structure

K (FB)	Data 31-24	K (FB)	Data 23-16	K (FB)	Data 15-8	K (FB)	Data 7-0
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### Command package:

- Bit 31: 0
- Bit 30: Time calibration
- Bit 29: DAQ start
- Bit 28: DAQ stop
- Bit 27: Reset
- Bits 26-8: reserved
- Bits 7-0: CRC checksum (CRC8-CCITT)

### Super-burst start package:

- Bit 31: 1
- Bits 30-0: Super-burst number



- Have highest priority (interrupt any other transfer)
  - Each received SODANET packed – acknowledged:
    - continuous monitoring of the readout
  - Malfunction of one of the DC/FEE → trigger slow control;  
the malfunction DC – added to the list of non-uses recipients
  - Burst counting (within Super-burst) – at each DC
- Error handling:
- DC checks if received super-burst number is sequential
  - In case of error:
    - the DC uses number distributed by the SODANET,
    - set special error bit in the output data,
    - informs slow-control system
  - If part of SODANET message is missing:
    - DC uses super-burst number from a local counter,
    - reports problem to the slow-control system.





- Dedicated “time calibration” command is defined
- Once the command is received:
  - reply sent to the transmitter side,
  - original message is forwarded further through the network.
- Propagation time:
  - calculated at the transmitter side
  - stored in a register
  - the register values – read out by a slow control system.
- The delay data – used to pre-calculate signal-propagation delays ( ~10 ns precision)
- Delay values – used at the DC to delay  
SODANET-synchronisation signals,  
before redistribution to FEE.
- The longest delay value – used by the SODANET source to  
**send synchronisation commands prior to a bunch crossing**

## Compatibility mode of operation

- External “trigger” signal is feed to one of  
the DC/SODANET source
- “trigger” is timestamped, and sent  
to the burst-building network
- Event builder will select only hits with timestamps, which are  
in coincidence with the “trigger” signal



# DC Output Data-format

- DC can start transmitting FEE data once it is available  
(without waiting till the end of a super-burst)
- If no data are available –  
DC sends an empty package at the end of the Super-burst

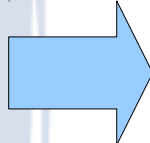
## Data-package

31	16	15	0
last-packet flag; packet number		data size in bytes	
Not used (same as HADES)		Not used (same as HADES)	
Status and error		System ID	
Super-burst number			
Data			

GbE paket builder in FPGA (HADES) can be reused to pack data

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## Implementation status

- ✓ Cleaned-up SODANET VHDL repository (files, relevant only for the SODANET)
  - ✓ Implemented synchronous transmission at **100 MHz** on the main and preferential FPGAs of a TRB board [hardware test]
- ✓ Super-burst generator (source) [tested with simulations]
- ✓ Package builder (source) [tested with simulations]
- ✓ Package handler (source/hub/DC) [tested with simulations]
- Interface of the SODANET to the TRB slow control
  - Feedback handler (time calibration, monitoring)
  - Fix synchronous-transmission frequency at **77.76 MHz**  
(design does not work yet at 125 MHz)
  - Jitter cleaner add-on



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**Thank you for your attention!**



**KVI**



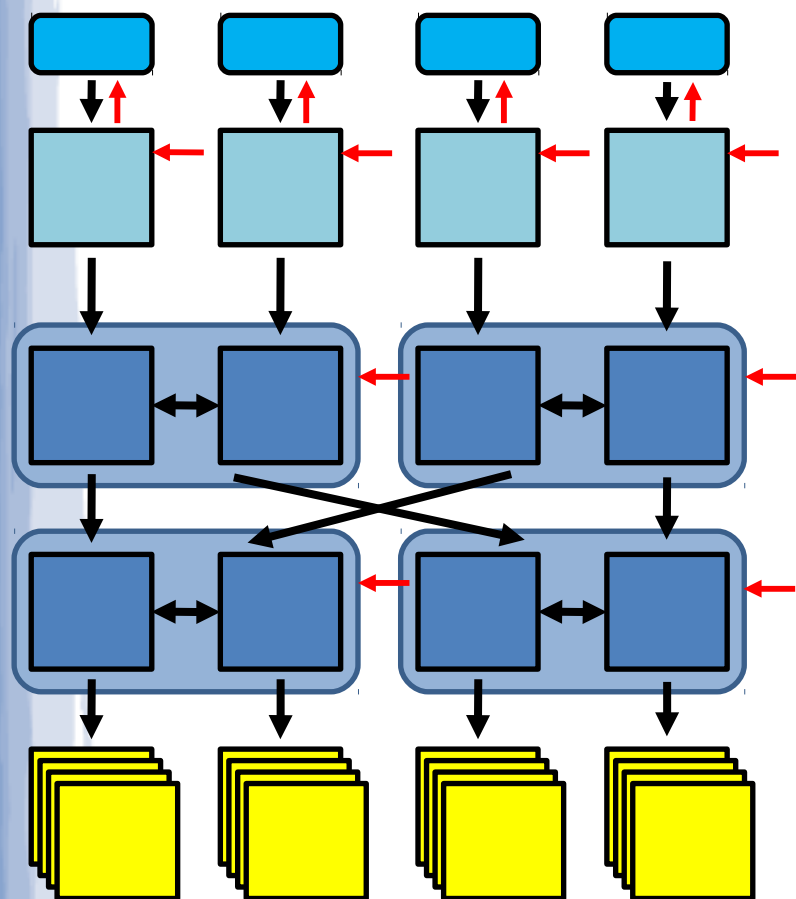
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**GSII**

# PANDA Readout

using **Data links** ( ← ) and Time distribution ( ← ) "SODA"

*[I. Konorov et al., NSS/MIC Conf. Rec., 2009 IEEE, DOI 10.1109/NSSMIC.2009.5402172]*



**Detector Front-ends**

Hit detection,  
feature-extraction

**Data  
Concentrator**

Combine  
several Front-Ends

**First Stage  
"Event" Builder**

**Second Stage  
"Event" Builder**

Time-ordering (building  
physics events)

**Compute  
Node**

On-line processing of  
complete events,  
Accept/reject decision



# Time-Synchronisation: Requirements

... To be precisely defined

- **Desired:**

- Distribution of clock (154.52 SONET standard)
- Distribution of synchronisation commands (Start, Stop, Calibration light-flash, etc.)
- Acceptable jitter:
  - < 20 ps (TOF, DIRC)
  - < 100 ps (EMC)
  - < 200 ps (STT, MWD, etc.)
- Signal distributed over an optical fibre

- **Optional:**

- Measurement of a signal-propagation time (cable length)
- Distribution of detector-configuration data
- Configuration of the burst-building network
- Slow control for small subsystems