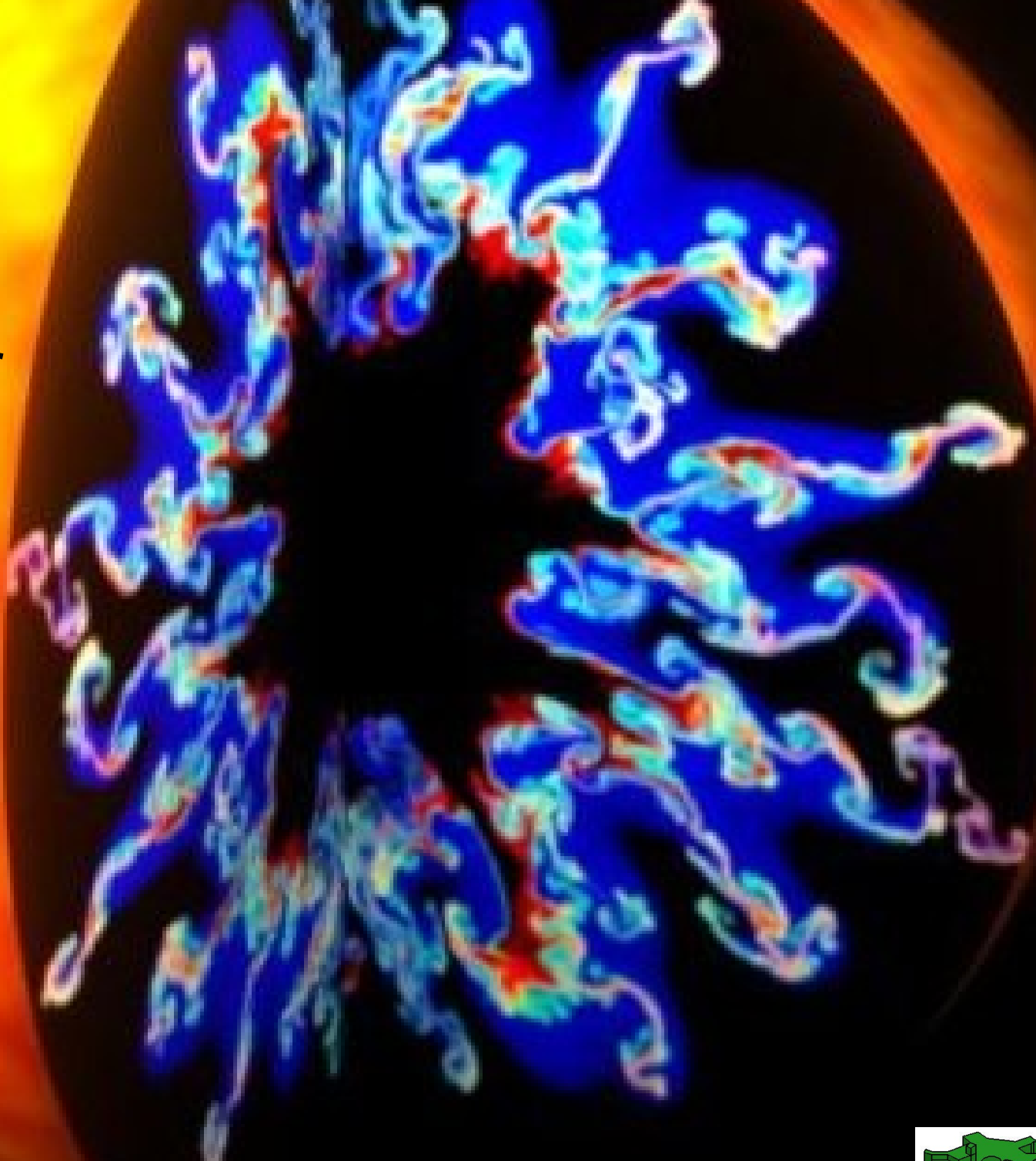


*Simulation of  
nuclear  
burning  
in  
astrophysics*

EMMI-JINA Workshop,  
GSI, Oct. 13, 2012



# Some Basic Hydrodynamics

Hydrodynamic equations are derivable from microscopic kinetic equations (Liouville, Boltzmann) under two assumptions

(i) microscopic behaviour of single particles can be neglected ( $\lambda_{\text{fmp}} \ll L$ )

(ii) forces between particles do saturate (short range forces!)

---> gravity must be treated as external force!

## hydrodynamic approximation holds

--> **set of conservation laws**

simplest case: single, ideal, non-magnetic fluid; no external forces

**mass:** 
$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$

**momentum:** 
$$\frac{\partial \rho \vec{v}}{\partial t} + \nabla \cdot (\rho \vec{v} \vec{v} + p \underline{\underline{I}}) = 0$$

**energy:** 
$$\frac{\partial \rho E}{\partial t} + \nabla \cdot ([\rho E + p] \vec{v}) = 0$$

hyperbolic  
system of  
PDEs

# hydrodynamic approximation holds

general case: additional equations and/or  
additional source terms

describe effects due to

viscosity (e.g., accretion disks)

reactions (e.g., nuclear burning, non-LTE ionization)

conduction (e.g., cooling of WD & NS; ignition of SNe Ia)

radiation transport (e.g., stars: photons; CCSNe: neutrinos)

magnetic fields (e.g., stars, jets, pulsars, accretion disks)

self-gravity (stars, galaxies, Universe)

relativity (jets, NS, BH, GRB)

viscous self-gravitating flow

mass: 
$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$

momentum: 
$$\frac{\partial \rho \vec{v}}{\partial t} + \nabla \cdot (\rho \vec{v} \vec{v} + p \underline{\underline{I}} - \underline{\underline{\pi}}) = -\rho \nabla \Phi$$

energy: 
$$\frac{\partial \rho E}{\partial t} + \nabla \cdot [(\rho E + p) \vec{v} + \vec{h} - \underline{\underline{\pi}} \vec{v}] = -\rho \vec{v} \nabla \Phi$$

Poisson equation

$$\Delta \Phi = 4\pi G \rho$$

## Astrophysical applications:

- viscosity & heat conduction often negligibly small  
(except in shock waves)
  - > **inviscous Euler eqs instead of viscous Navier-Stokes eqs are solved**
  
- numerical methods possess numerical viscosity  
(depending on grid resolution)
  - > **strange situation:**  
One tries to solve inviscid Euler eqs, but instead solves a viscous variant, different from Navier-Stokes eqs !!

## hydrodynamic equations are incomplete

(closure relation missing)

---> **equation of state** required to close system

$$p = p(\rho, T), \quad \varepsilon = \varepsilon(\rho, T)$$

## discontinuous solutions of Euler equations exist

(weak solutions: shocks, contact discontin.)

---> **conservation laws in integral form**

**jump conditions** (Rankine-Hugoniot)



## flows characterizable by dimensionless numbers

Reynolds number:  $Re = uL/\nu$  ( $\nu$  kinematic viscosity)

measures relative strength of inertia & dissipation; often very large in astrophysics ( $>10^{10}$ )

for all flows there exists a critical Reynolds number,

above critical Reynolds number flow becomes turbulent

---> Large Eddy Simulations (for star)

Prandtl number:  $Pr = \nu/\kappa$  ( $\sigma$ : conductivity)

measures relative strength of dissipation & conduction

# The Art of Computational Fluid Dynamics

## Hydrodynamic equations:

non--linear system of 1<sup>st</sup> order PDEs

one way to solve equations:

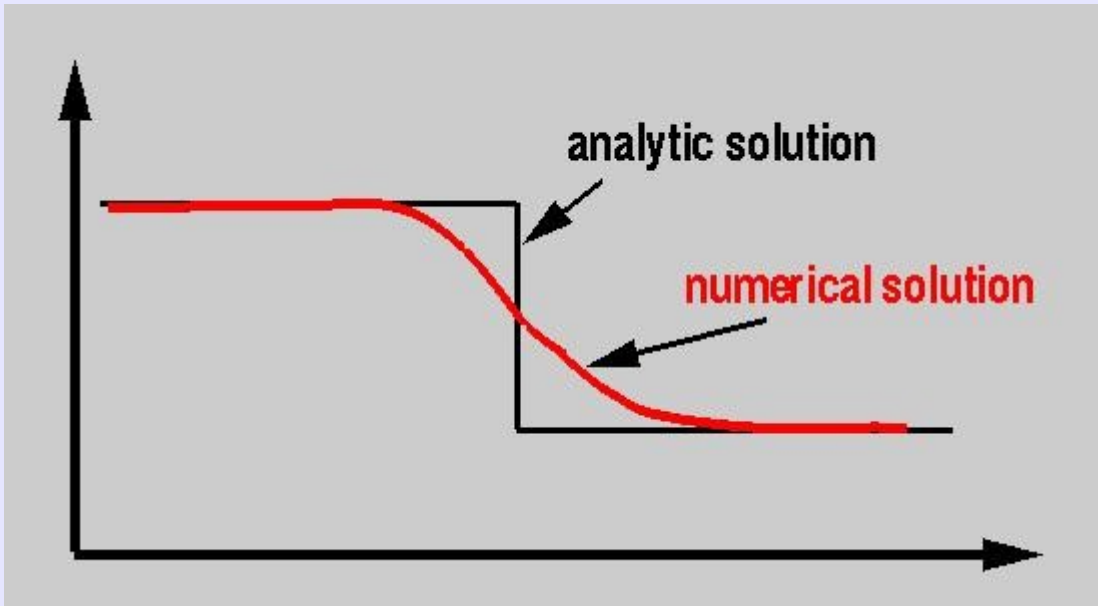
**discretization in space & time**

PDEs ---> set of coupled algebraic eqs

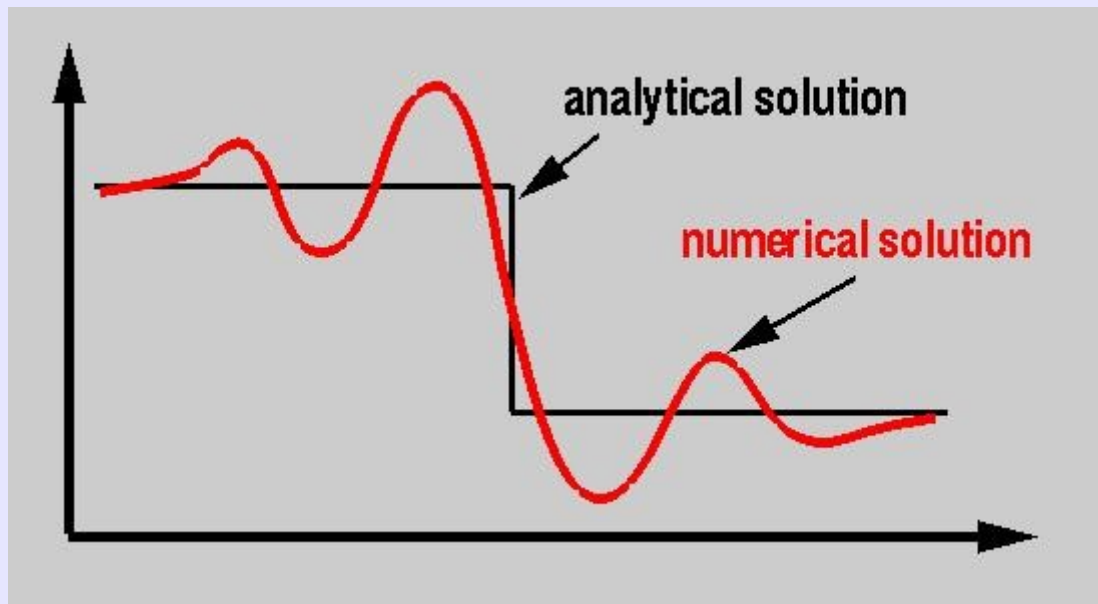
finite difference (FD), finite volume (FV),  
method of lines (MOL)

introduces unavoidable errors

--> It is crucial to use methods, which minimize  
the errors!



**numerical diffusion**



**numerical dispersion**

HD equations can be formulated with respect to  
two distinct classes of coordinate systems

Eulerian <====> fixed coordinates (time independent)

disadvantage: : numerical diffusion  
due to nonlinear advection terms ( $\mathbf{v} \text{ grad}$ )

Lagrangian <====> comoving coordinates

(moving with the fluid/gas)

advantage: no numerical diffusion of mass, etc

disadvantage: grid tangling (in case of shear or vortex flow)

--> rezoning required which causes  
numerical diffusion

--> major advantage lost!

====> Eulerian coordinates are to be preferred for multidimensional problems

but special efforts are necessary to minimize the inevitable numerical diffusion

---> use more accurate, high-order numerical schemes

alternative: free-Lagrange methods

i.e. grid free methods, where gradients are evaluated without the use of any grid

---> no grid tangling, no rezoning

most commonly used variant in astrophysics:

**S**moothed **P**article **H**ydrodynamics

## Finite volume schemes

- quasi-linear hyperbolic system of (1D) conservation laws for state vector  $U$

$$U_t(x, t) + F_x[U(x, t)] = 0$$

- or with the **Jacobian**  $A(u) \equiv \partial F / \partial U$  of the flux vector  $F(U)$

$$U_t + A(U) \cdot U_x = 0$$

- integration over **finite** (1D spatial control) **volume**

$$[x_1, x_2] \times [t_1, t_2]$$

$$\int_{x_1}^{x_2} U(x, t_2) dx = \int_{x_1}^{x_2} U(x, t_1) dx - \int_{t_1}^{t_2} F[U(x_2, t)] dt + \int_{t_1}^{t_2} F[U(x_1, t)] dt$$

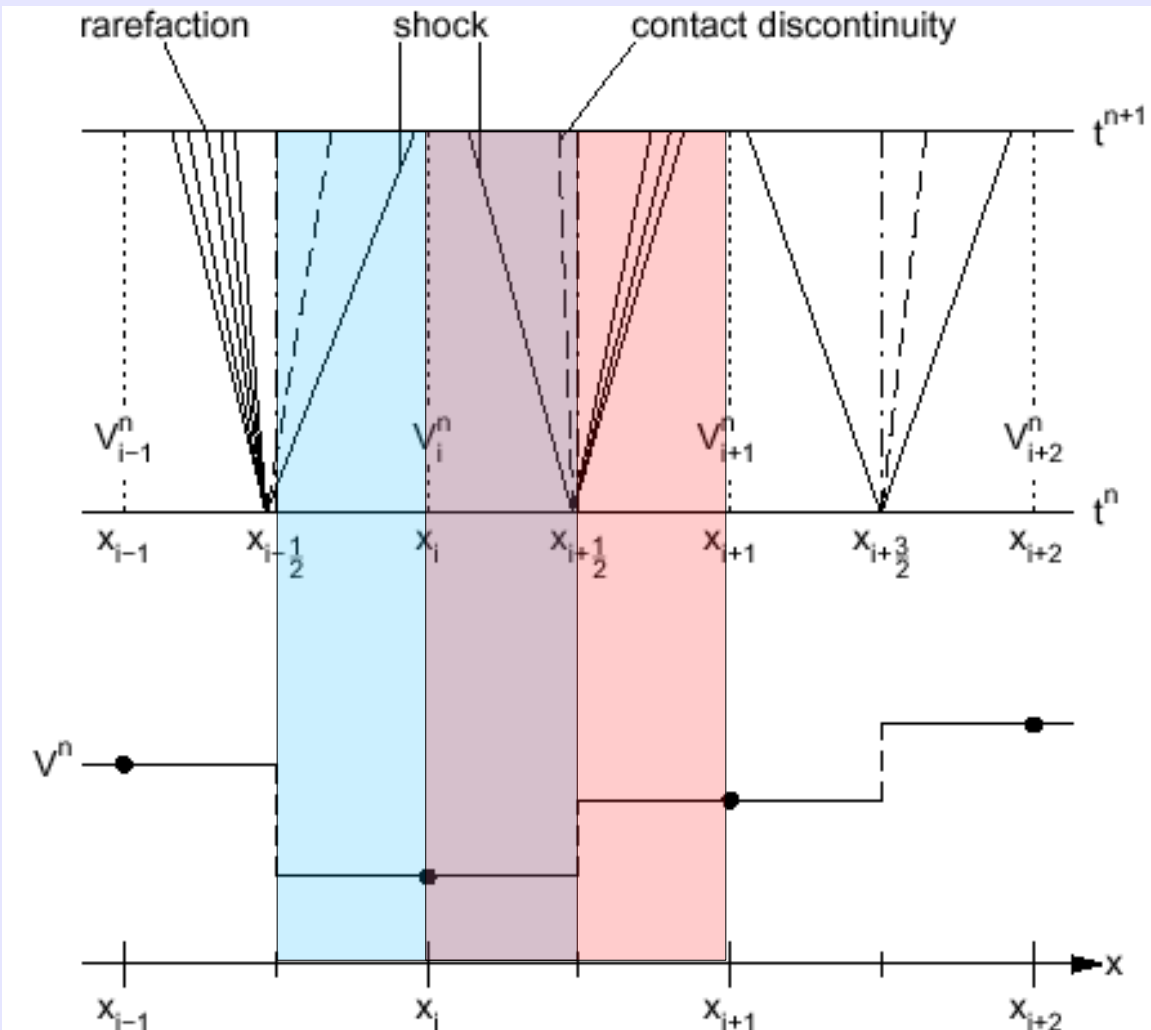
integral form allows proper handling of flow discontinuities!

## High resolution shock-capturing methods (HRSC)

- rely strongly on **hyperbolic & conservative** character of HD eqs (upwind method along characteristics)
- **shock-capturing ability**
  - \* discontinuities are treated consistently & automatically
  - \* scheme **reduces from high-order** accuracy in smooth regions **to 1<sup>st</sup> order** accuracy **at discontinuities**
- usually based on solution of **local Riemann problems** (discontinuous initial value problem) **at zone interfaces**



e.g., piecewise constant



## upwind schemes

numerical flux from exact or approximate solution of local Riemann problems (spectral information, i.e. Jacobian required)

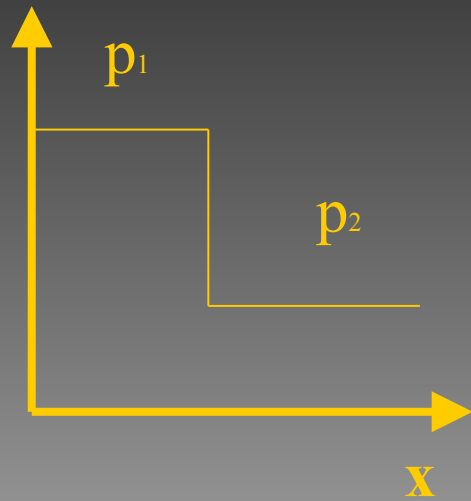
## central schemes

smooth numerical flux at cell centers by quadrature (averaging over Riemann fan)

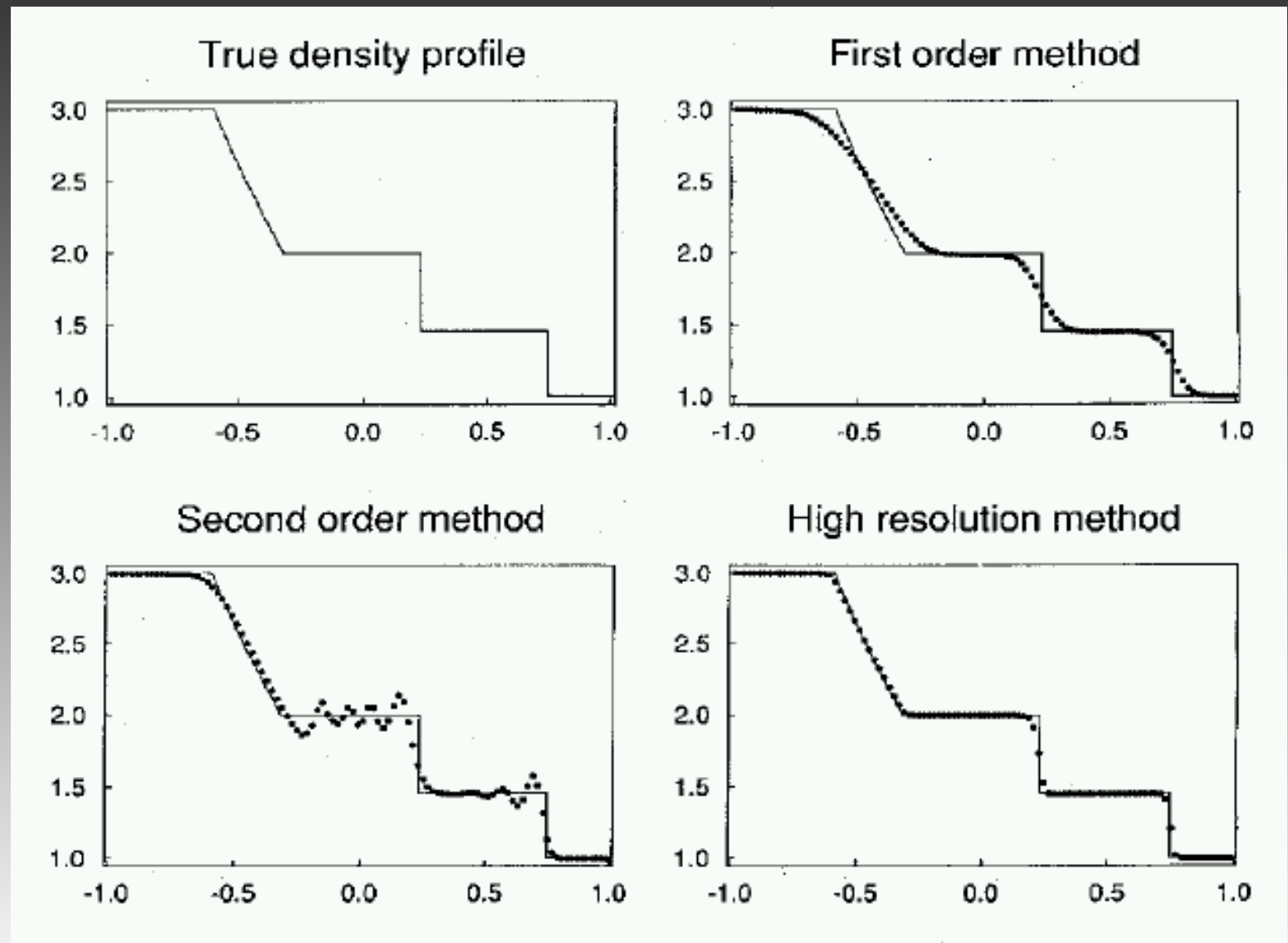
proto-types: 1<sup>st</sup> order Godunov (upwind), Lax-Friedrichs (central)

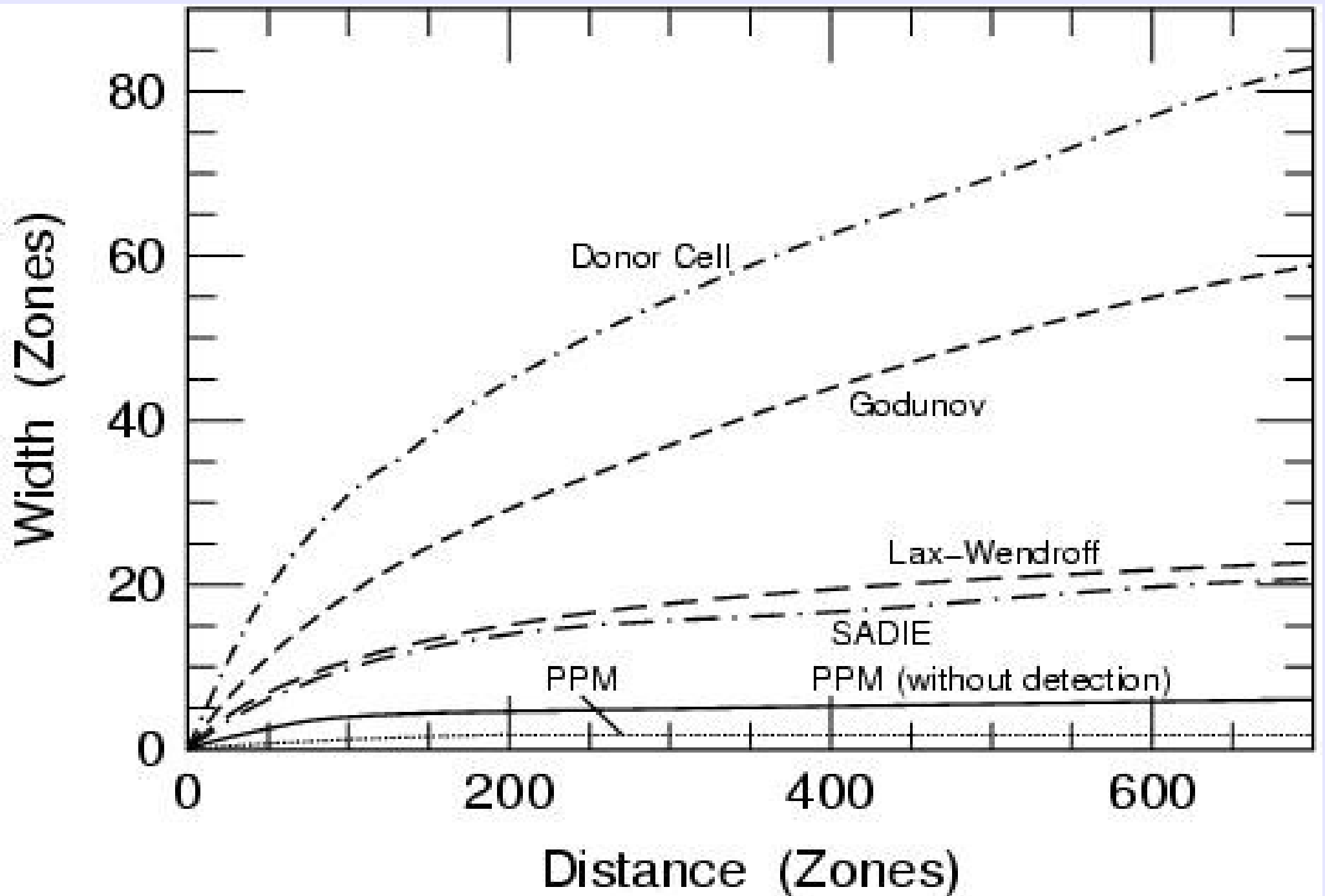
non-oscillatory higher-order extensions of both classes exist!

# Handling discontinuities



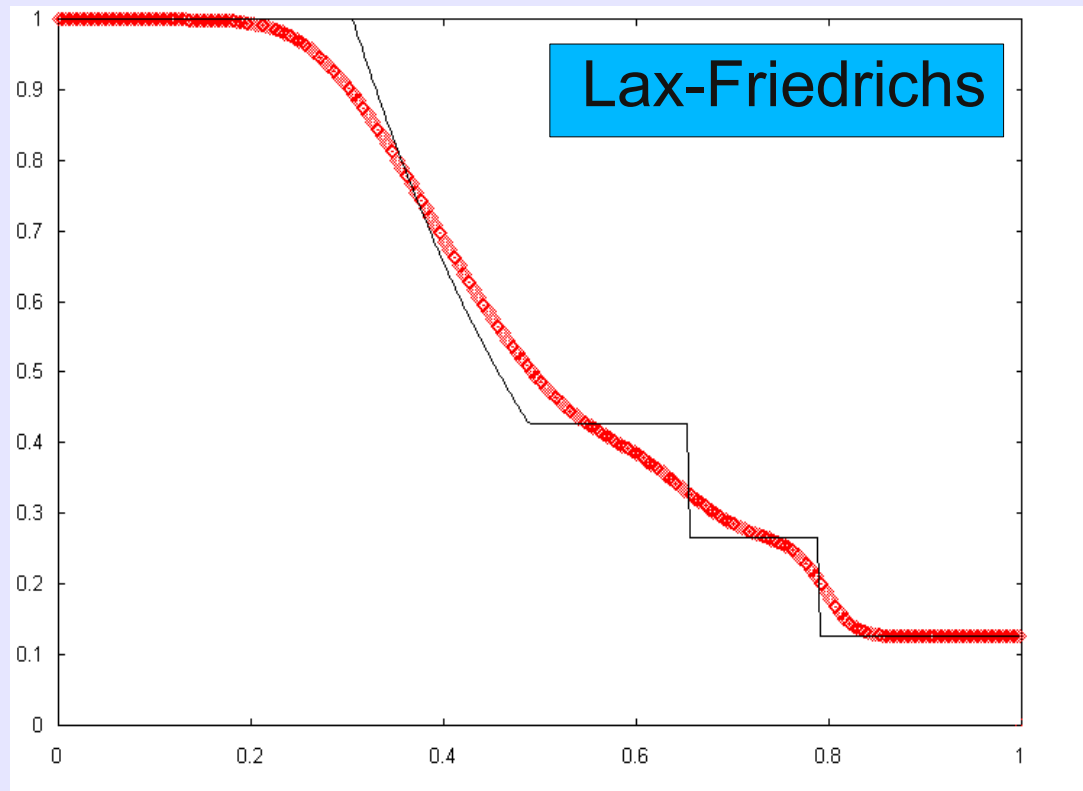
Example of a problem with discontinuous initial conditions





diffusivity of various finite volume methods

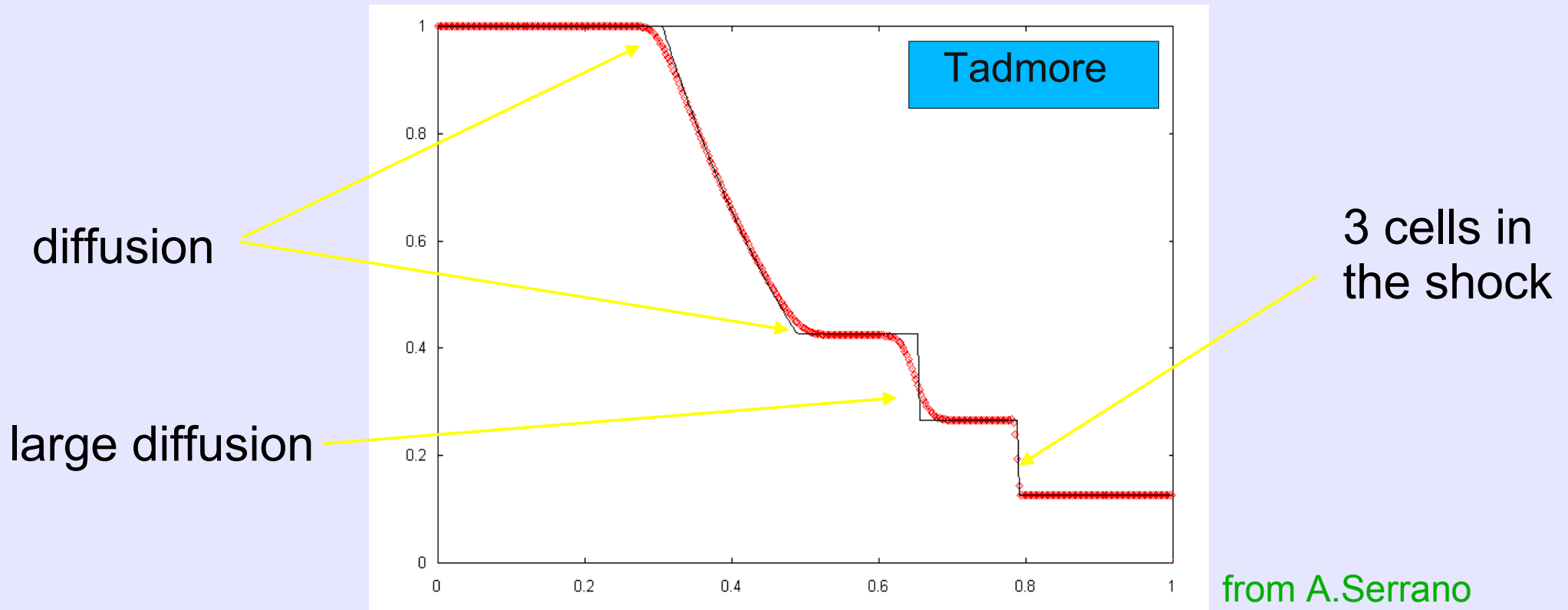
# Sod's shock tube test problem (N=400, CFL=0.3)



from A.Serrano

1<sup>st</sup> order central difference scheme  
simple, but very diffusive everywhere

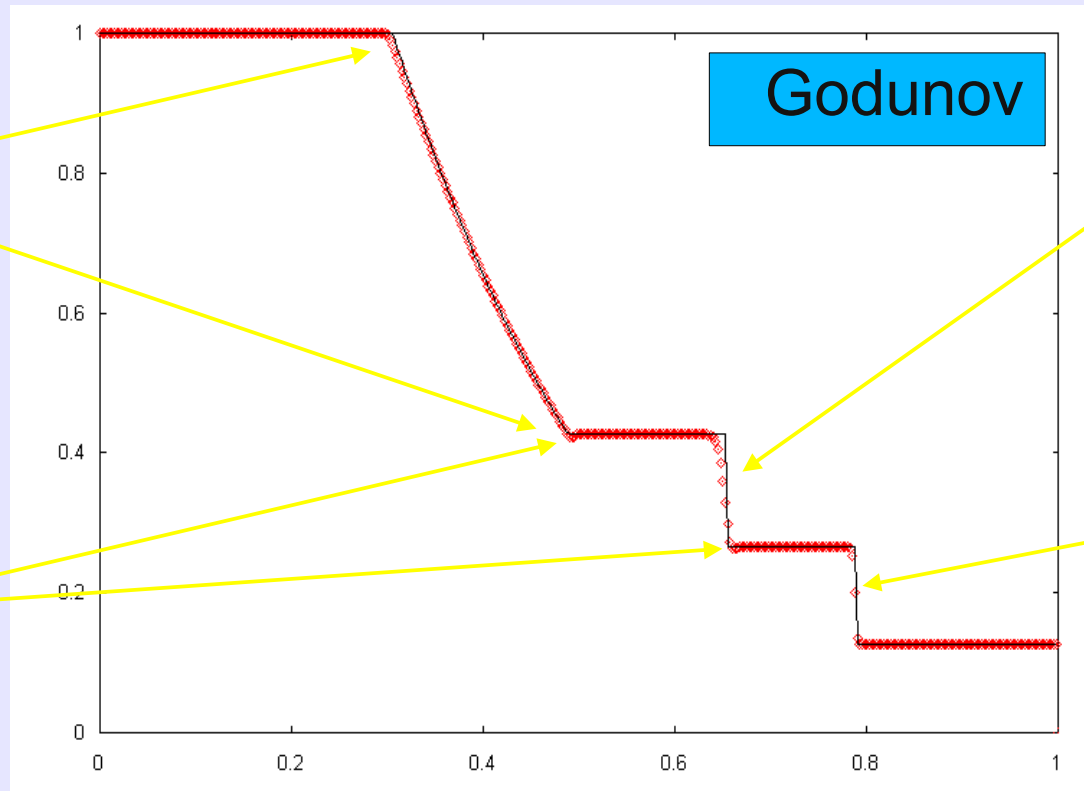
# Sod's shock tube test problem (N=400, CFL=0.3)



2<sup>nd</sup> order central difference scheme

good at shocks, very diffusive at contacts

# Sod's shock tube test problem (N=400, CFL=0.3)



very good resolution

small undershoots

very well resolved contact

3 cells in the shock

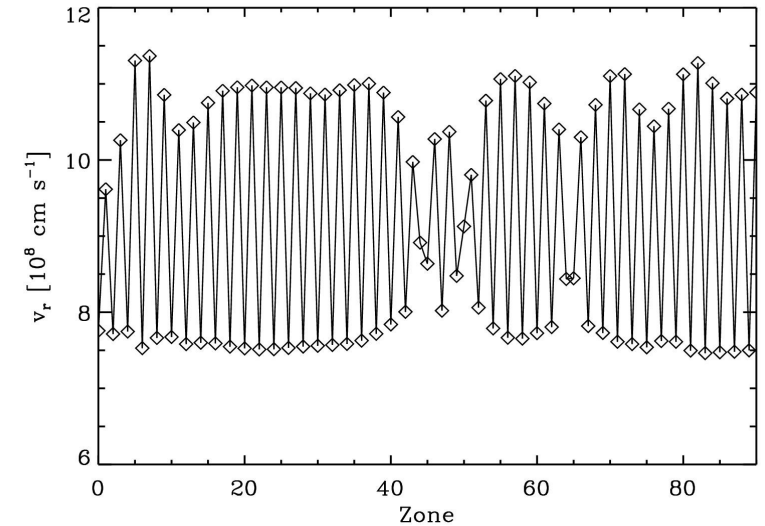
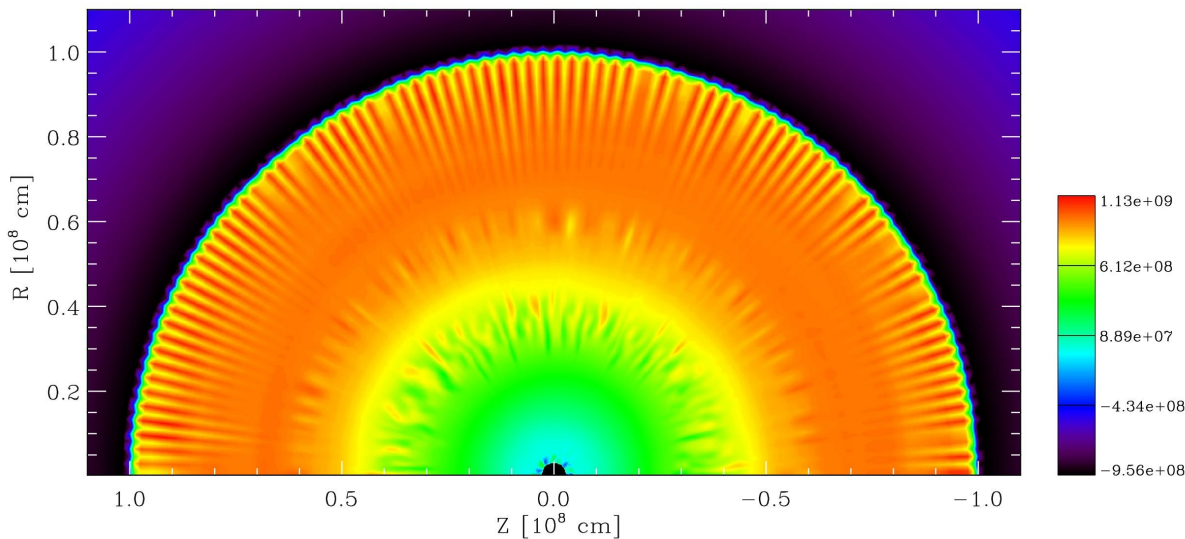
from A.Serrano

Riemann solver, 1<sup>st</sup> order reconstruction  
accurate description of all wave structures

Be aware: even exact Riemann solvers have flaws!

(Quirk 1994)

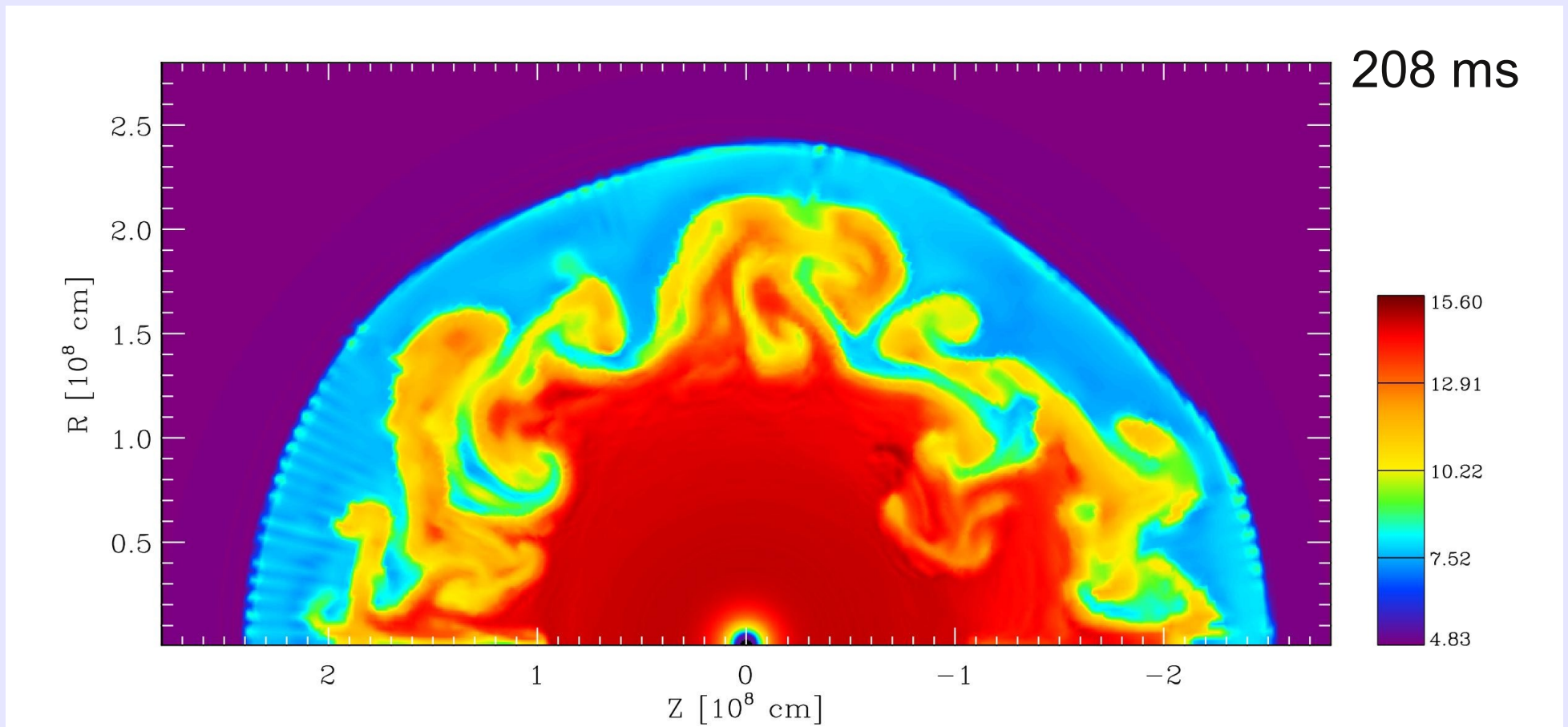
Odd-even decoupling when simulating  
grid-aligned shocks with exact Riemann solvers  
and directional splitting (cross dissipation missing!)



early neutrino heating phase in a  
core collapse supernova simulation

## Simulating multi-dimensional flow

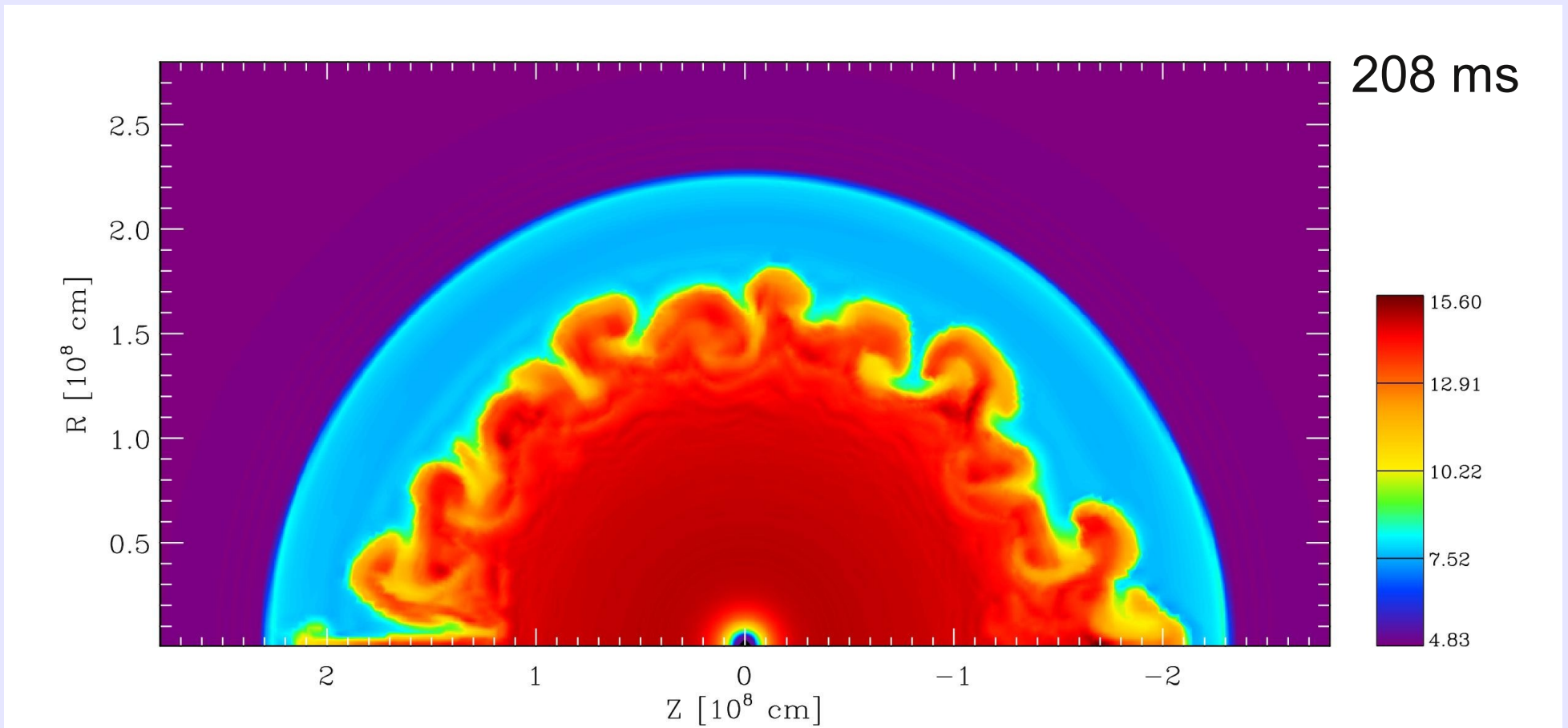
- neutrino hot bubble entropy with 'sticks'





## Simulating multi-dimensional flow

- neutrino hot bubble entropy without 'sticks'  
---> 40% more nickel



# Simulation of Multi Fluid Flow

- ▶ *thermonuclear reactions* if density and temperature sufficiently high
- ▶ astrophysical situations (in particular in stellar explosions): large number of different types of reactions involved
- ▶ grouped according to number of participants in interactions:
  - one-body reactions ( $\beta$ -decays, electron captures, photo-disintegrations),
  - two-body reactions,
  - three-body reactions
- ▶ notation:
  - $\lambda_j$ : reaction rates for 1-body
  - $\langle j, k \rangle$ : thermally averaged cross sections and relative velocities in the center-of-mass system for 2-body
  - $\langle j, k, l \rangle$ : same for 3-body
  - $N_A$ : Avogadro number

→ expression for the *change in specific abundance*  $Y_i$  of species  $i$ :

$$\dot{Y}_i = \sum_j c_i^j \lambda_i^j Y_j + \sum_{j,k} c_i^{j,k} \rho N_A \langle j, k \rangle Y_j Y_k + \sum_{j,k,l} c_i^{j,k,l} (\rho N_A)^2 \langle j, k, l \rangle Y_j Y_k Y_l$$

coefficients  $c$ :

$$\begin{aligned} c_i^j &= \pm N_i \\ c_i^{j,k} &= \pm \frac{N_i}{N_j! N_k!} \\ c_i^{j,k,l} &= \pm \frac{N_i}{N_j! N_k! N_l!}, \end{aligned}$$

note:

- ▶  $N_{i,j,k,l}$ : number of particles participating in reaction
- ▶ factorials in denominator prevent double counts
- ▶  $\pm$  stand for particle creation/destruction

advantage of using *specific abundances*

$$Y_i = \frac{n_i}{\rho N_A} :$$

values unaffected by expansion and contractions (unlike number densities  $n_i$ ); changes in  $Y_i$  really require nuclear processes or mixing

## nuclear reaction network

$$\dot{Y}_i = \sum_j c_i^j \lambda_i^j Y_j + \sum_{j,k} c_i^{j,k} \rho N_A \langle j, k \rangle Y_j Y_k + \sum_{j,k,l} c_i^{j,k,l} (\rho N_A)^2 \langle j, k, l \rangle Y_j Y_k Y_l \quad (110)$$

- ▶ set of coupled nonlinear ODEs
- ▶ nonlinearity due to dependence of reaction rates on second or higher powers of  $Y_i$
- ▶ stiffness due to vastly different values of  $Y_i$  and of reaction rates (may depend on high powers of  $T$  and  $\rho$ )
- ▶ nonlinearity  $\rightarrow$  analytic solution virtually impossible
- ▶ numerical approach inevitable

for convenience of discussion of numerical solution strategies: rewrite (110)

$$\frac{dY_i}{dt} = f_i(\rho, T, Y_1, \dots, Y_N), \quad (i = 1, \dots, N, \text{ number of species})$$

## numerical solution of a nuclear reaction network

$$\frac{dY_i}{dt} = f_i(\rho, T, Y_1, \dots, Y_N), \quad (i = 1, \dots, N, \text{ number of species})$$

- ▶ approximate left hand side by *finite difference*:

$$\frac{dY_i}{dt} \approx \frac{Y_i^{n+1} - Y_i^n}{\Delta t},$$

→ finite difference scheme by evaluating  $f_i$  numerically

- ▶ simple approach:  
either at time step  $t^n$

$$Y_i^{n+1} = Y_i^n + \Delta t f_i^n$$

or at time step  $t^{n+1} = t^n + \Delta t$ :

$$Y_i^{n+1} = Y_i^n + \Delta t f_i^{n+1}.$$

→ *Euler method* for solving the ODEs: 1st-order accurate in time

- ▶ 1st variant: explicit *Forward Euler* scheme  
can be implemented in a straightforward way  
but: numerical difficulties near steady state and equilibrium solutions

## numerical solution of a nuclear reaction network

- ▶ 2nd variant: the implicit *Backward Euler* method generally preferred  
implicit → more implementation effort: set of coupled nonlinear equations, *solved by matrix manipulation techniques*
- ▶ abbreviation: Backward Euler in *vector notation*:

$$\mathbf{Y}^{n+1} = \mathbf{Y}^n + \Delta t \mathbf{f}^{n+1} = \mathbf{Y}^n + \Delta t \mathbf{f}(\mathbf{Y}^{n+1}).$$

- ▶ expand  $\mathbf{f}(\mathbf{Y}^{n+1})$  into *Taylor series* about known  $\mathbf{f}(\mathbf{Y}^n)$   
retain first-order terms only (↔ Newton's method):

$$(\mathbf{Y}^{n+1} - \mathbf{Y}^n) \left( \frac{\mathbf{I}}{\Delta t} - \mathbf{J} \right) = \mathbf{f}(\mathbf{Y}^n), \quad (111)$$

$\mathbf{I}$ : identity matrix  $I_{ij} = \delta_{ij}$

$\mathbf{J}$ : Jacobian matrix

# numerical solution of a nuclear reaction network

►  $J$ : Jacobian matrix

$$J = \frac{\partial f(Y^n)}{\partial Y^n}$$

represents the flow (nuclei per second) into and out of isotope

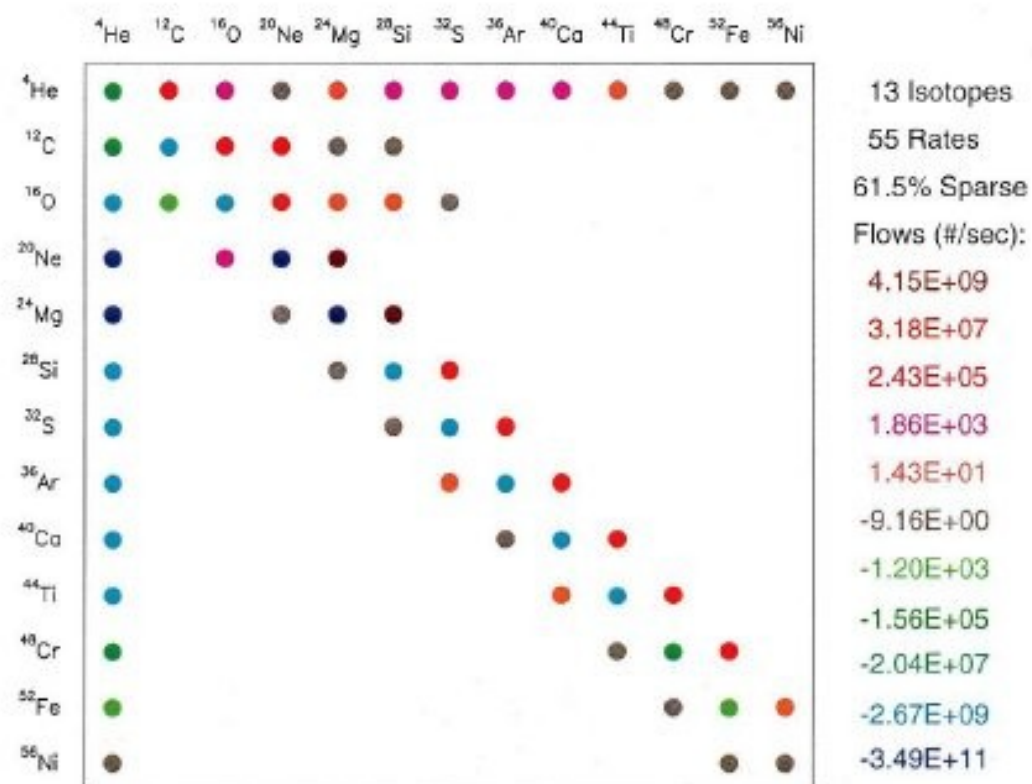
in principle, matrix completely filled  
(all isotopes interact)

however: many entries very small  
→ omitted

→ in practice:

*sparse Jacobian matrix*

(usually diagonally dominant)





# numerical solution of a nuclear reaction network

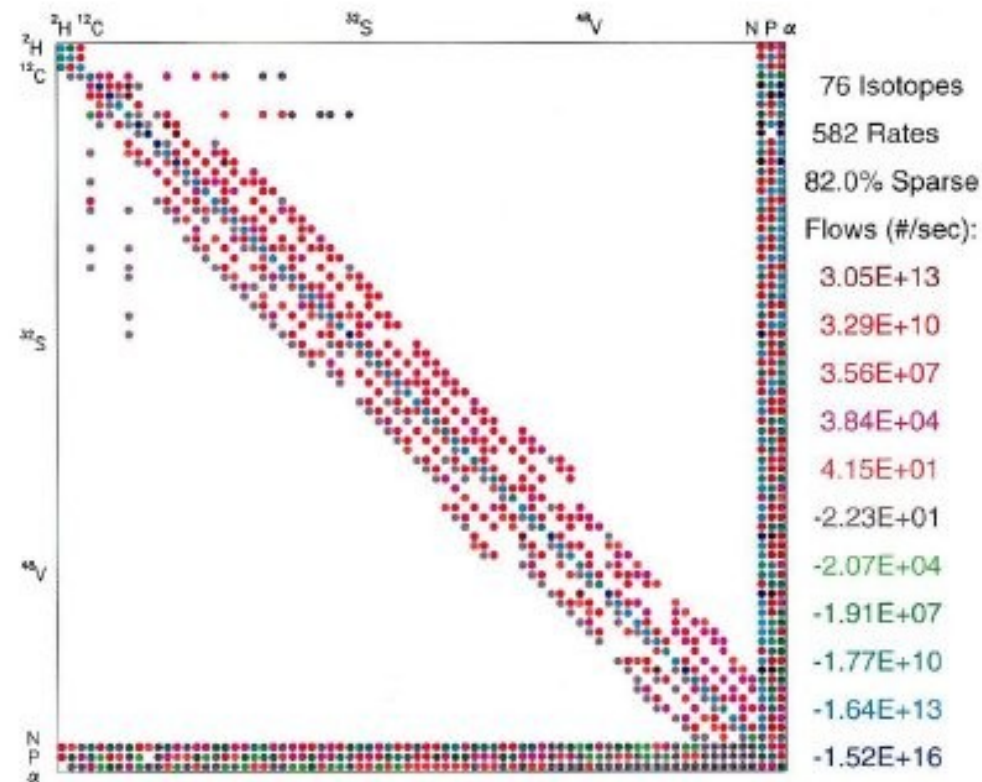
- ▶  $J$ : Jacobian matrix

$$J = \frac{\partial f(Y^n)}{\partial Y^n}$$

represents the flow (nuclei per second) into and out of isotope

in principle, matrix completely filled  
(all isotopes interact)  
however: many entries very small  
→ omitted

→ in practice:  
*sparse Jacobian matrix*  
(usually diagonally dominant)



# numerical solution of a nuclear reaction network

- ▶  $J$ : Jacobian matrix

$$J = \frac{\partial f(Y^n)}{\partial Y^n}$$

represents the flow (nuclei per second) into and out of isotope

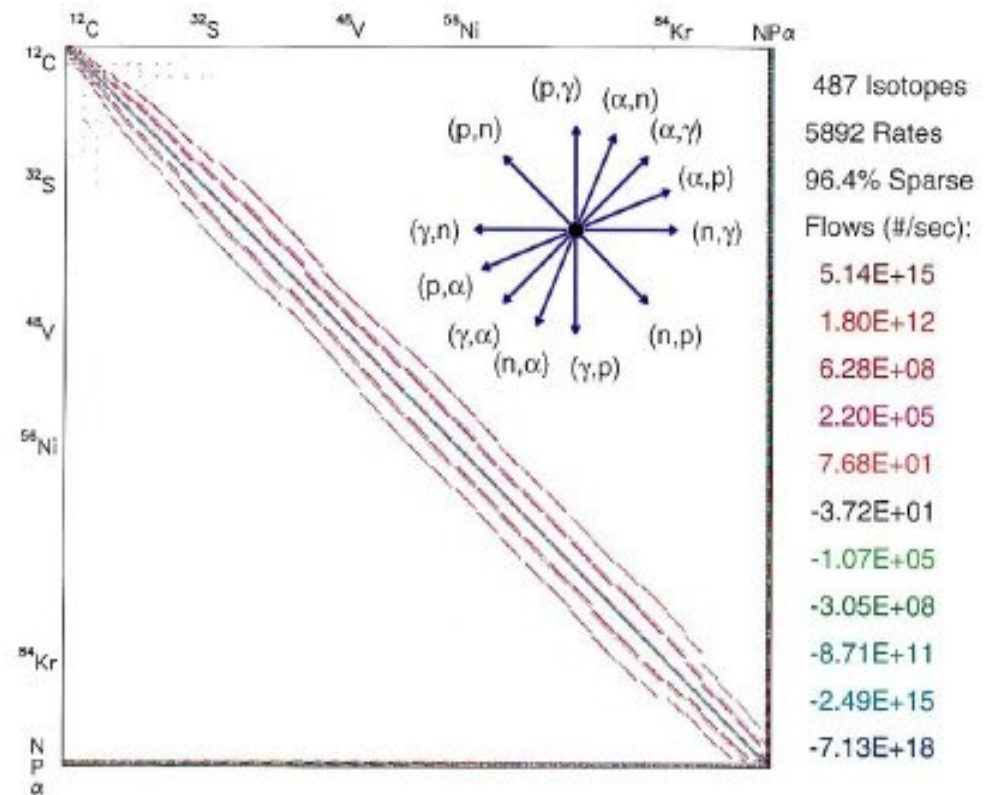
in principle, matrix completely filled  
(all isotopes interact)

however: many entries very small  
→ omitted

→ in practice:

*sparse Jacobian matrix*

(usually diagonally dominant)



## numerical solution of a nuclear reaction network

solve

$$(Y^{n+1} - Y^n) \left( \frac{I}{\Delta t} - J \right) = f(Y^n)$$

- ▶ evaluate Jacobian matrix
- ▶ evaluate  $f(Y^n)$
- ▶ invert matrix

$$\frac{I}{\Delta t} - J$$

- ▶ back substitution to determine  $Y^{n+1}$
- ▶ matrix inversion, e.g. by linearization → *semi-implicit scheme*

## Coupling hydrodynamics and reaction source terms

- ▶ *interdependencies* of hydro and reactions:
  - ▶ reactions change hydrodynamic states  
→ releasing (or consuming) energy,  
convert species
  - ▶ reaction rates sensitively depend on thermodynamic state  $(T, \rho)$
- ▶ coupling is *local in space*

reflected by *extension to the Euler equations*:

- ▶ add extra equation accounting for *species balance*

$$\frac{\partial \rho Y_i}{\partial t} = -\nabla \cdot (\rho Y_i \mathbf{v}) + \rho f(Y_i) \quad i = 1 \dots N \quad (112)$$

$f(Y_i)$ : *source term* accounting for production or destruction of species  $i$  by nuclear reactions

## Coupling hydrodynamics and reaction source terms

- ▶ *energy balance* completed with *source term*  $S = S(f(Y_i))$  due to nuclear energy release/consumption:

$$\frac{\partial \rho e_{\text{tot}}}{\partial t} = -\nabla \cdot (\rho e_{\text{tot}} \mathbf{v}) - \nabla \cdot (P \mathbf{v}) + \rho S(f) \quad (113)$$

$\Delta m_i = (m_i - A_i m_u) c^2$ : mass excess [MeV]

$m_u$ : atomic mass unit [MeV]

- ▶ energy source term [ $\text{erg cm}^{-3} \text{s}^{-1}$ ]

$$S = -9.644 \times 10^{17} \rho \sum_i \Delta m_i c^2 f_i \frac{\text{erg}}{\text{cm}^3 \text{s}^1}$$

→ together with appropriate equations for mass and momentum conservation:

*reactive Euler equations*

(here without external forces, e.g. gravity)

# Self-gravitating multi-dimensional multi-fluid ideal flow

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$

$$\frac{\partial \rho \vec{v}}{\partial t} + \nabla \cdot (\rho \vec{v} \vec{v}) + \nabla P + \rho \nabla \Phi = 0$$

$$\frac{\partial \rho E}{\partial t} + \nabla \cdot ([\rho E + P] \vec{v}) + \rho (\vec{v} \cdot \nabla) \Phi = \rho \dot{Q}_{\text{nuc}}$$

$$\frac{\partial \rho X_i}{\partial t} + \nabla \cdot (\rho X_i \vec{v}) = \rho \dot{X}_i, \quad \sum_i X_i = 1$$

$$X = Y * A$$

Simulations of **core collapse & thermonuclear supernovae** require a numerical treatment of **multi-fluid flow**

- Non-linear discretization of advection terms

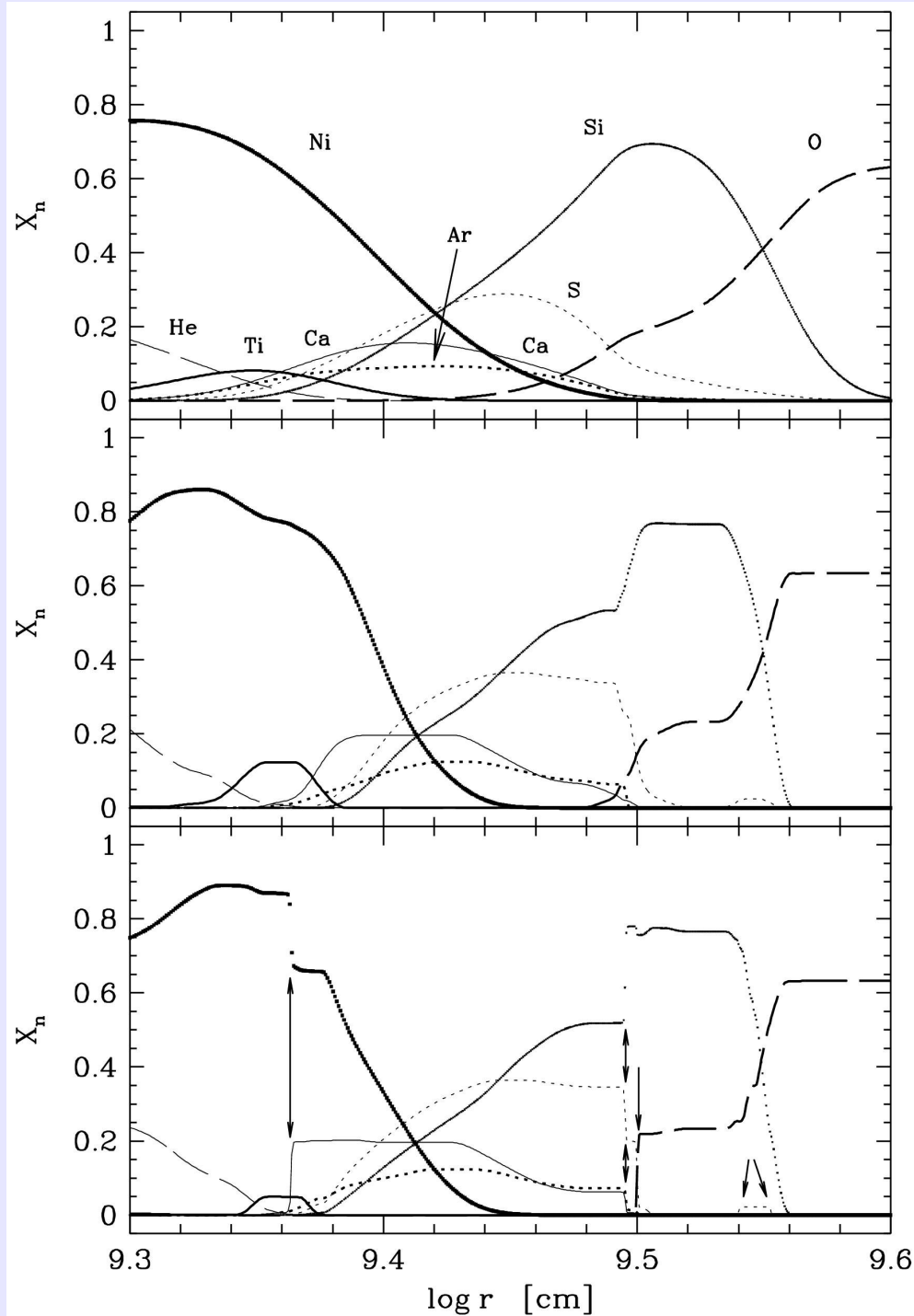
$$\sum_i X_i \neq 1$$

-->

- **Consistent Multi-fluid Advection** (Plewa & Müller '99)
  - (a) renormalization of mass fraction fluxes
  - (b) conservative species advection
  - (c) contact steepening to reduce numerical diffusion

# Simulating multi-fluid flow

Composition profiles  
in the ejecta of a  
15 solar mass star  
at 3 sec



**CMAZ**

(total flattening)

**FMA**

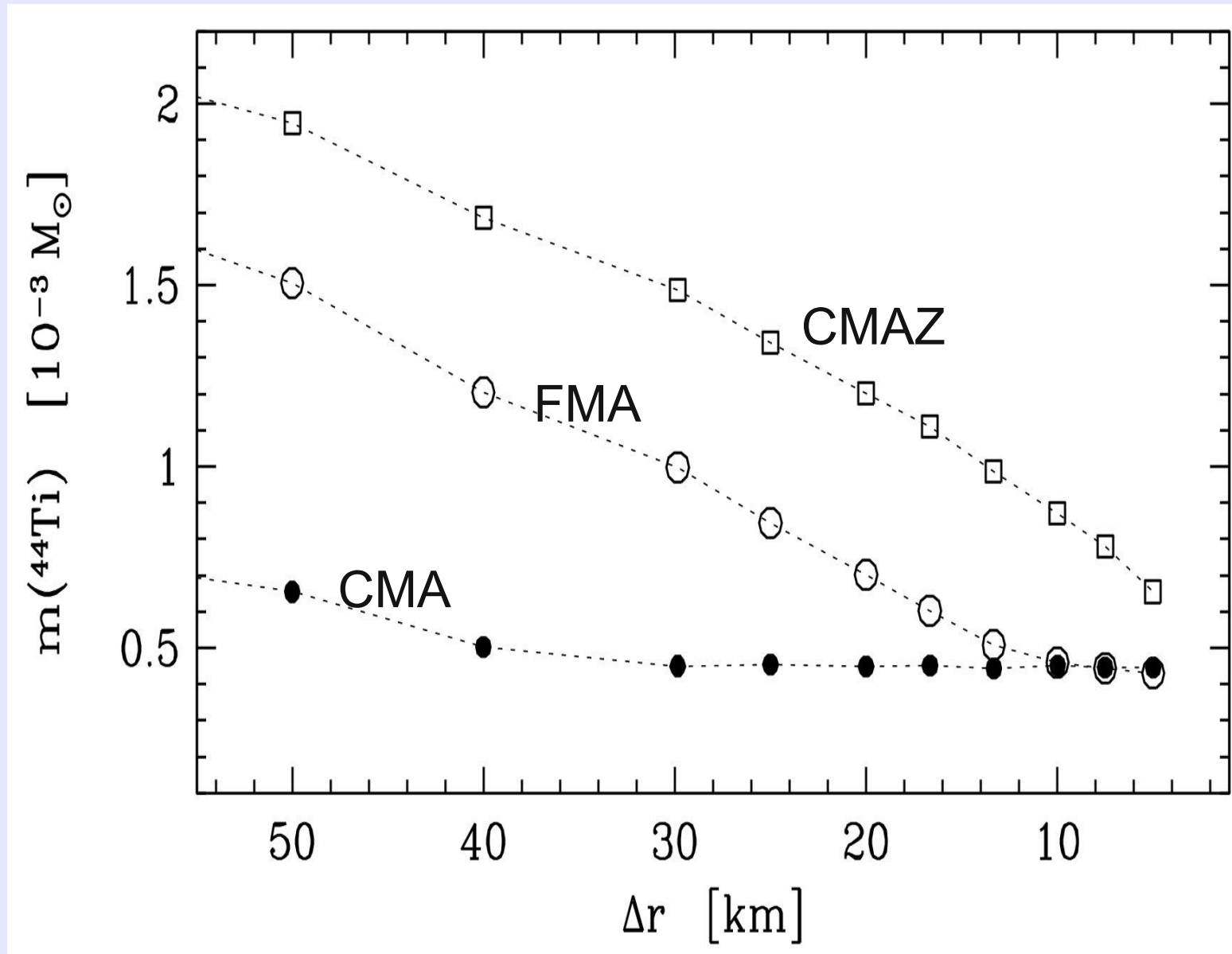
(Fryxell, Müller &  
Arnett 1989)

**CMA**

(Plewa & Müller  
2001)



## Simulating multi-fluid flow



dependence of  $^{44}\text{Ti}$  production on grid resolution

# Thermonuclear burning & nucleosynthesis

- Common practice nowadays

- \* 1D: online reaction network (several 100 species)

- \* 2D/3D reduced network for energy generation +  
**post-processing**

- Multi-dimensional flows

Lagrangian codes inappropriate

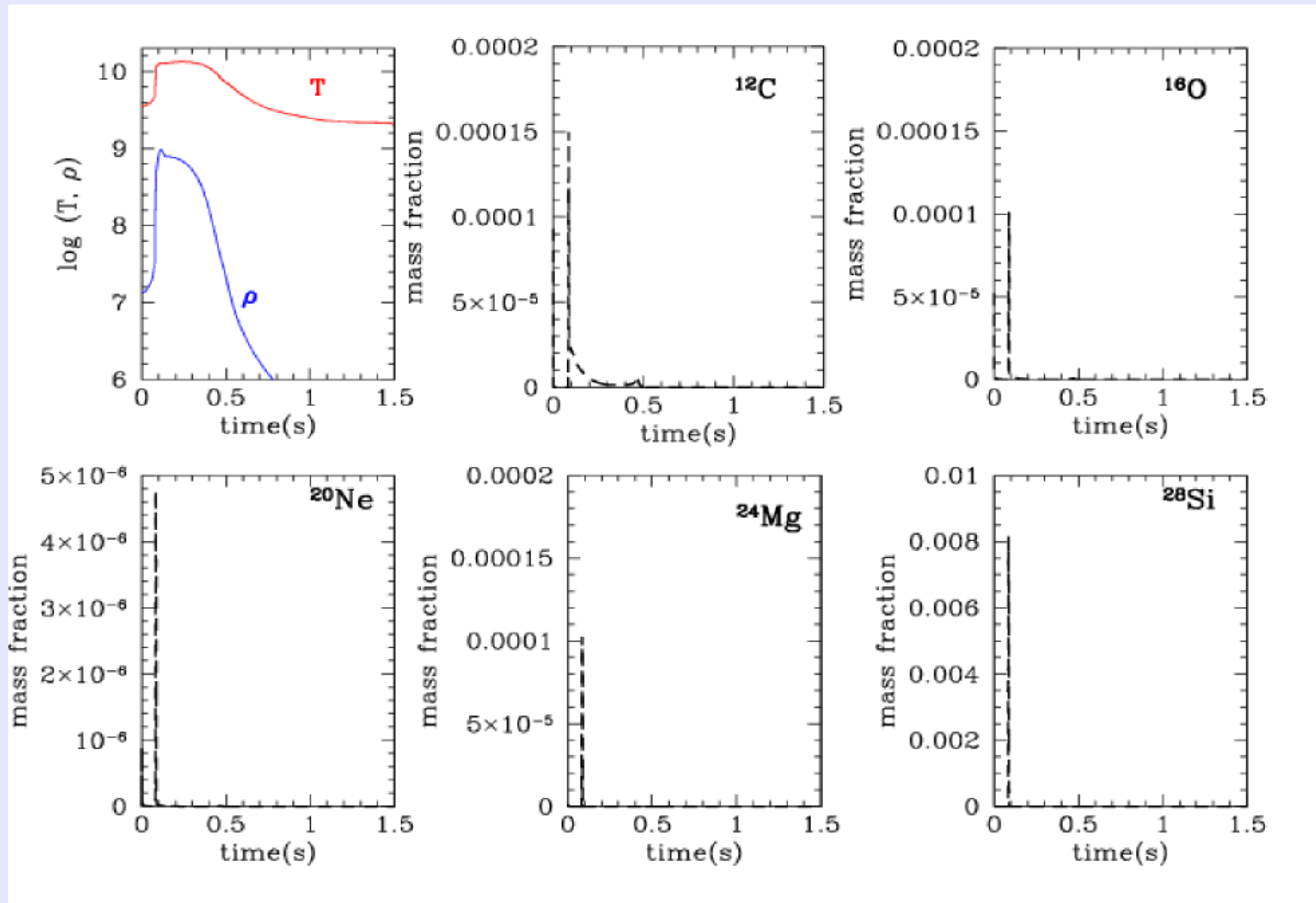
--> Eulerian codes extended by

**marker particle method**

set of marker particles properly distributed across regions expected to burn --> **advected** with the flow

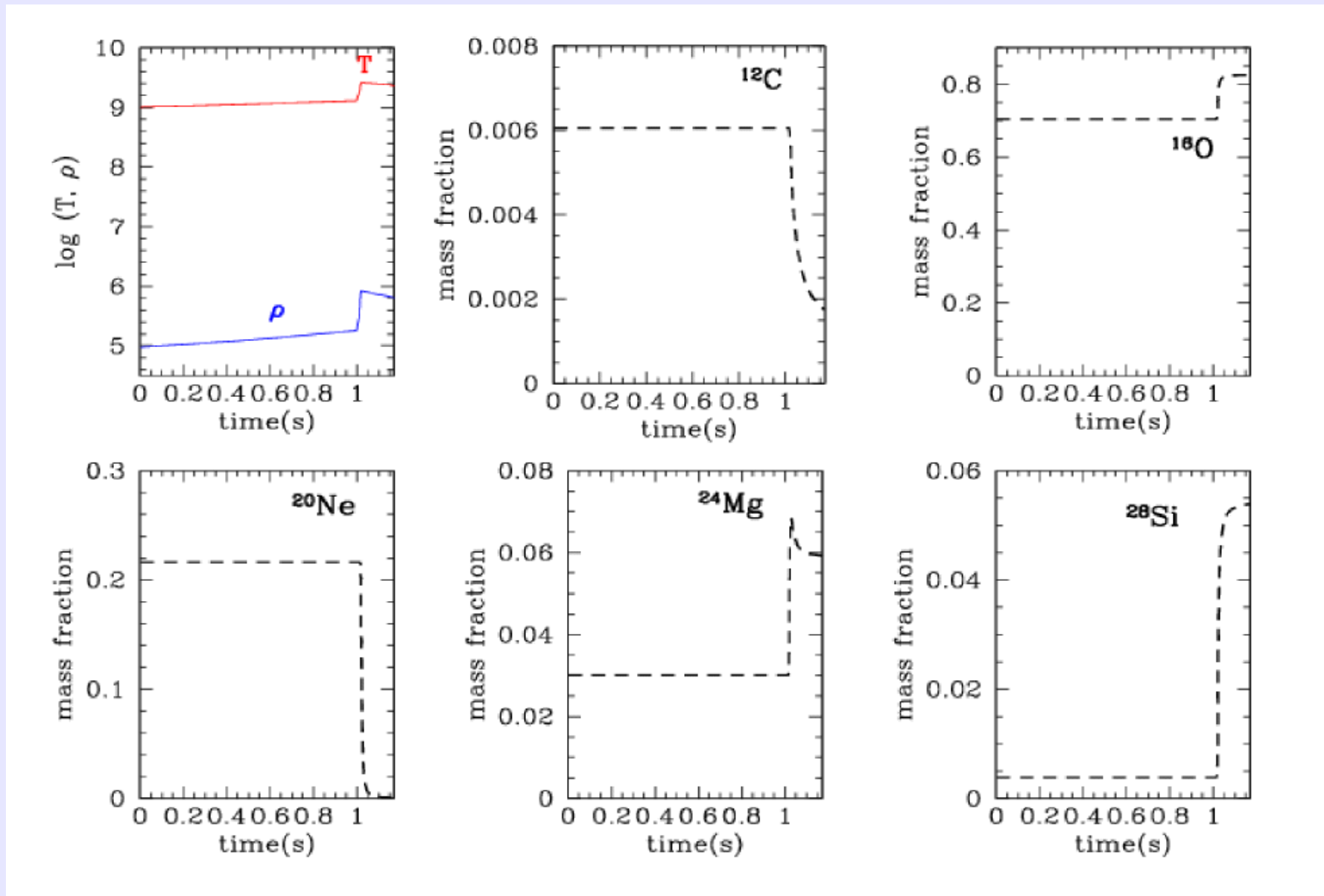
--> **(T,  $\rho$ ) history** recorded for post-processing

# Marker particle nucleosynthesis



From a SNe Ia simulation using marker particles and post-processing  
(Travaglio et.al 2003)

# Marker particle nucleosynthesis



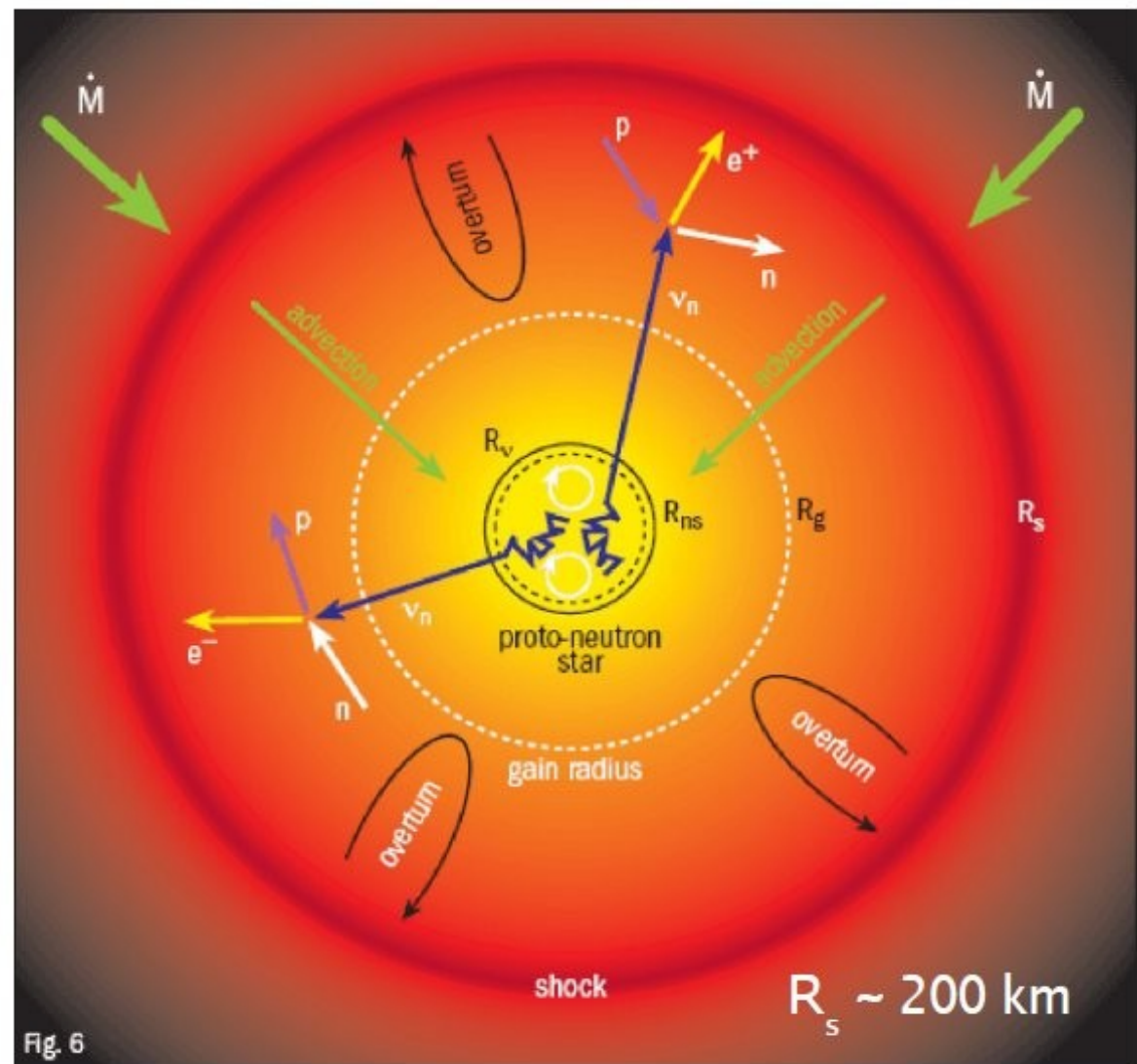
From a SNe Ia simulation using marker particles and post-processing  
(Travaglio et.al 2003)

# Example I

Nucleosynthesis and  
Rayleigh-Taylor instabilities  
in the envelopes of  
core-collapse supernovae

# Neutrinos & SN Explosion Mechanism

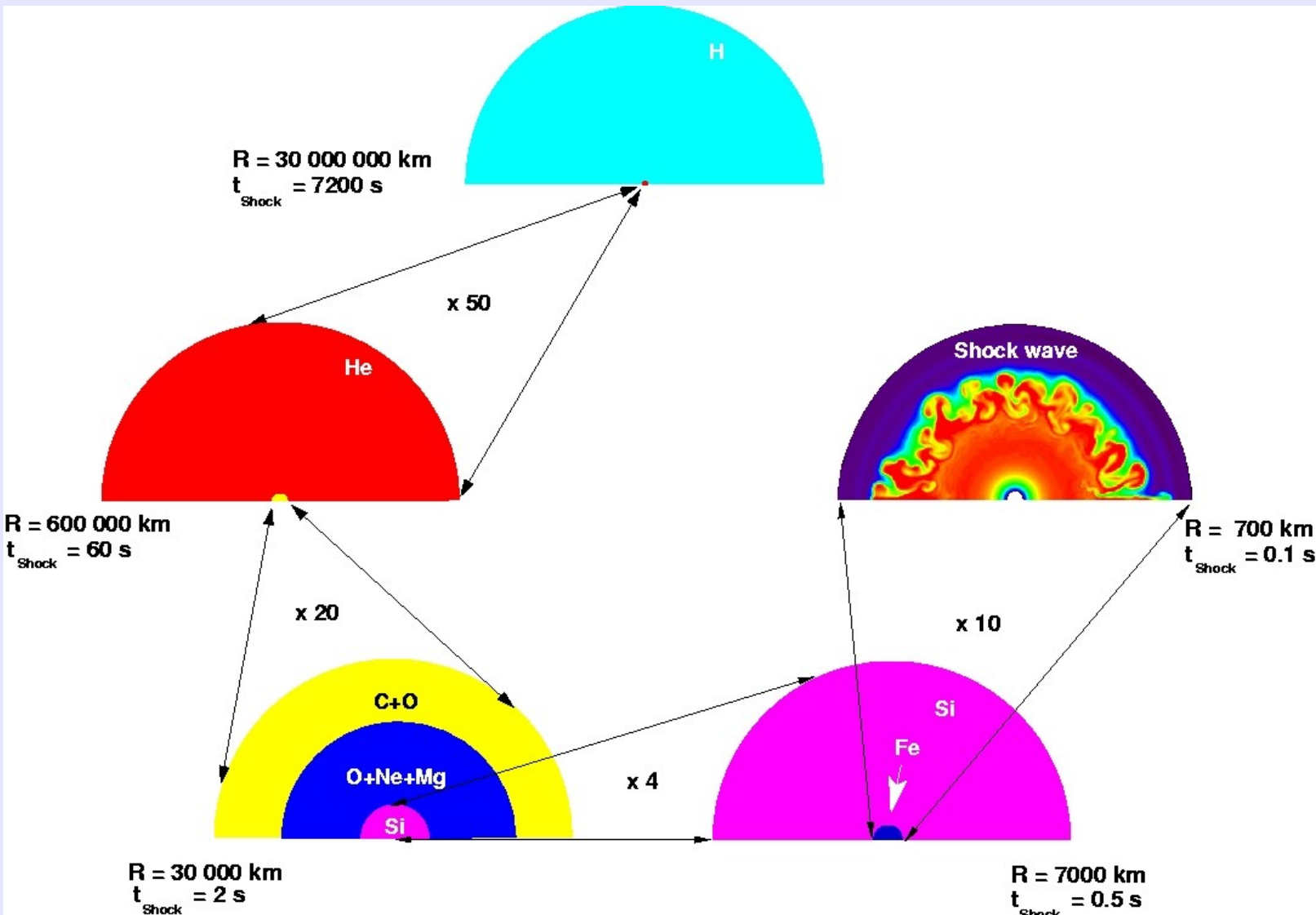
**Paradigm:** Explosions by the neutrino-heating mechanism, supported by hydrodynamic instabilities in the postshock layer



- “Neutrino-heating mechanism”: Neutrinos ‘revive’ stalled shock by energy deposition (Colgate & White 1966, Wilson 1982, Bethe & Wilson 1985);
- Convective processes & hydrodynamic instabilities support the heating mechanism (Herant et al. 1992, 1994; Burrows et al. 1995, Janka & Müller 1994, 1996; Fryer & Warren 2002, 2004; Blondin et al. 2003; Scheck et al. 2004,06,08).

- observations imply that **non-radial flow and mixing** are common in core collapse supernovae
- theoretical models based on **delayed explosion mechanism** predict non-radial flow and mixing due to
  - **Ledoux convection inside the proto-neutron star**  
(due to deleptonization and neutrino diffusion)
  - **convection inside neutrino heated hot bubble**  
(behind shock wave due to neutrino energy deposition)
  - **Rayleigh-Taylor instabilities in stellar envelope**  
(due to non-steady shock propagation; triggered by hot bubble)

# Numerical challenges (I): extreme range of scales both in time & space has to be treated properly



scale problem  
in CCSNe:

$$l_{\text{NS}} \sim 10^6 \text{ cm}$$

$$l_{\text{star}} \sim 10^{13} \text{ cm}$$

$$\tau_{\text{NS}} \sim 10^{-3} \text{ s}$$

$$\tau_{\text{sh}} \sim 10^4 \text{ s}$$

--> factor  $10^7$



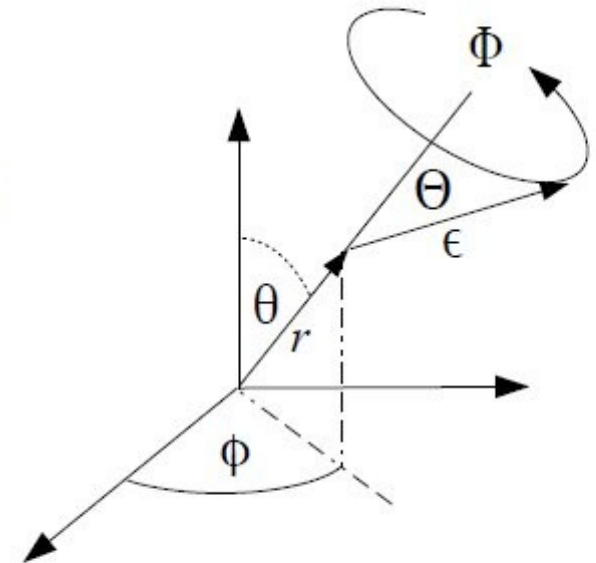
# The Curse and Challenge of the Dimensions

Boltzmann equation determines neutrino distribution function in 6D phase space and time

$$f(r, \theta, \phi, \Theta, \Phi, \epsilon, t)$$

Integration over 3D momentum space yields source terms for hydrodynamics

$$Q(r, \theta, \phi, t), \dot{Y}_e(r, \theta, \phi, t)$$



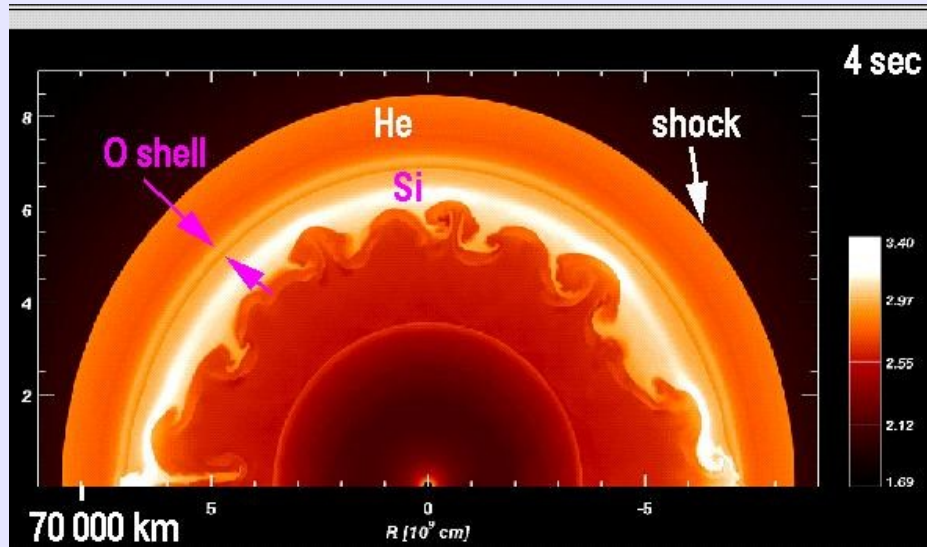
## Solution approach

- **3D** hydro + **6D** direct discretization of Boltzmann Eq. (code development by Sumiyoshi & Yamada '12)
- **3D** hydro + two-moment closure of Boltzmann Eq. (may be next feasible step on way to full 3D)
- **3D** hydro + "**ray-by-ray-plus**" variable Eddington factor method (method used at MPA/Garching)
- **2D** hydro + "**ray-by-ray-plus**" variable Eddington factor method (method used at MPA/Garching)

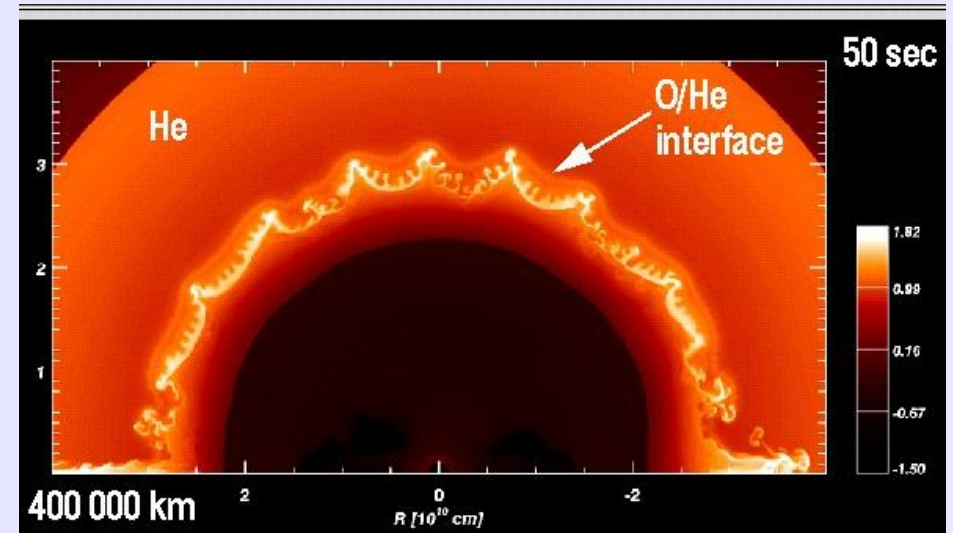
## Required resources

- $\geq 10\text{--}100$  PFlops/s (sustained!)
- $\geq 1\text{--}10$  Pflops/s, TBytes
- $\geq 0.1\text{--}1$  PFlops/s, Tbytes
- $\geq 0.1\text{--}1$  Tflops/s,  $< 1$  TByte

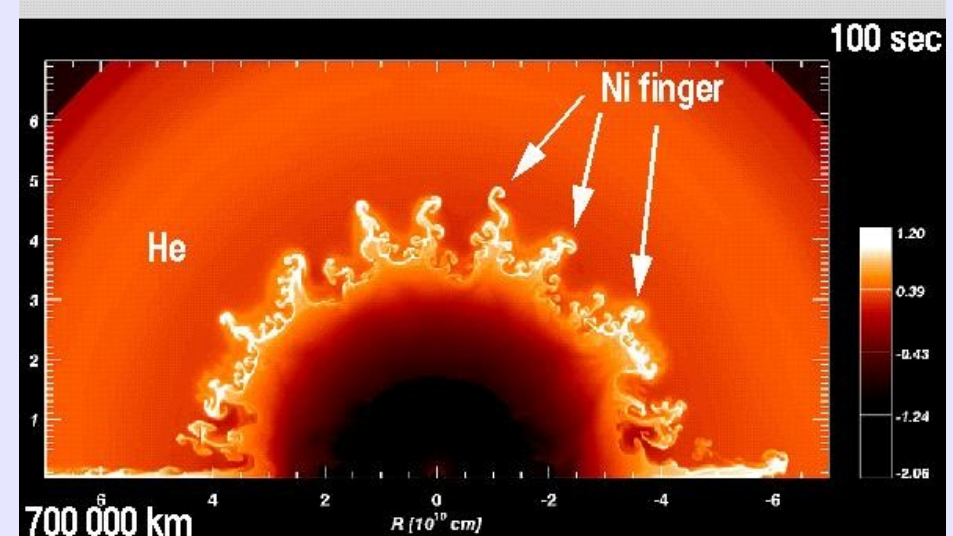
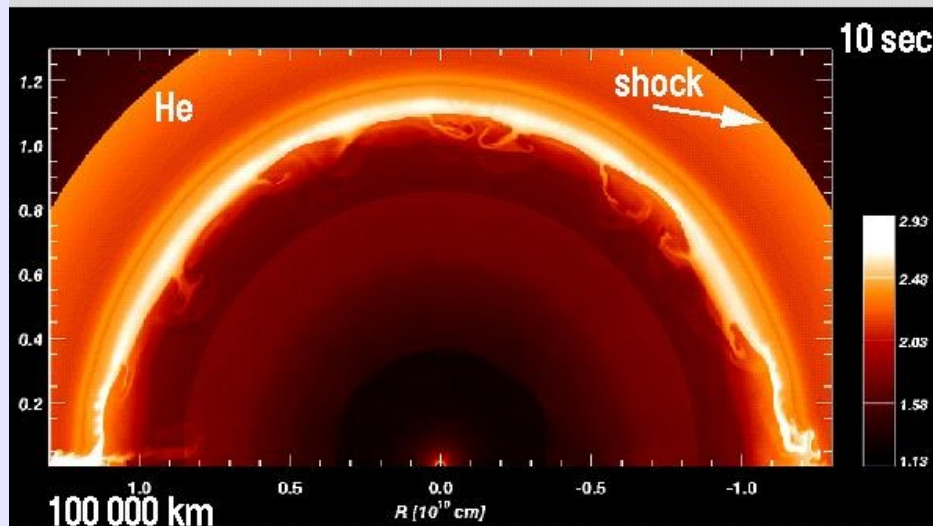
# Instabilities, mixing and nucleosynthesis in stellar envelope



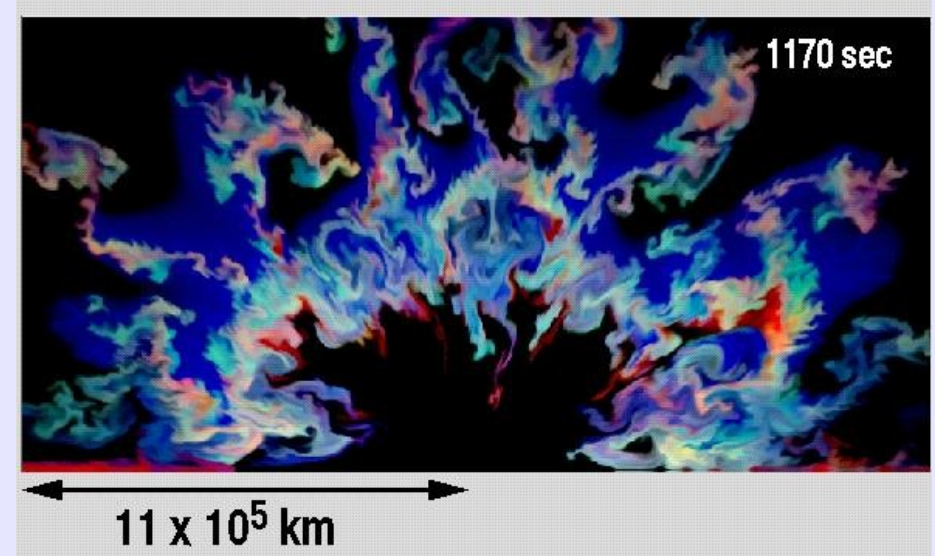
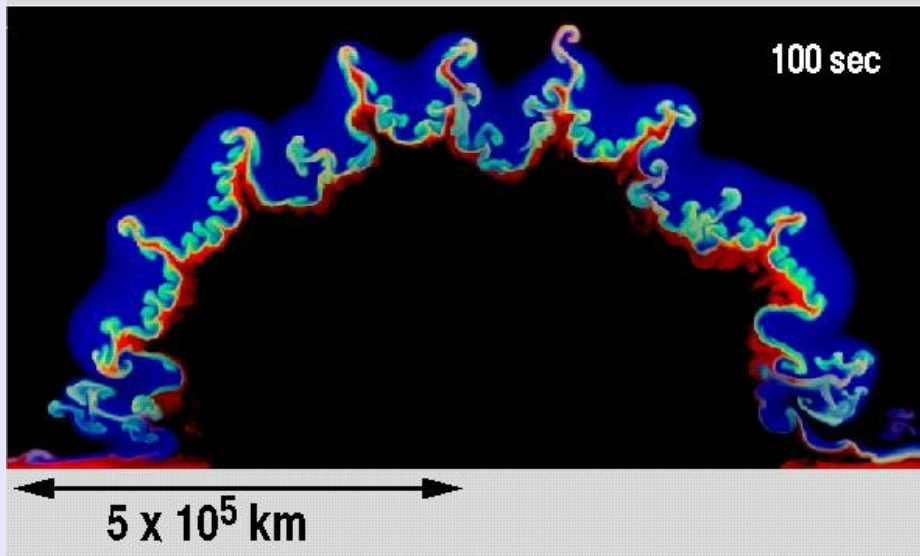
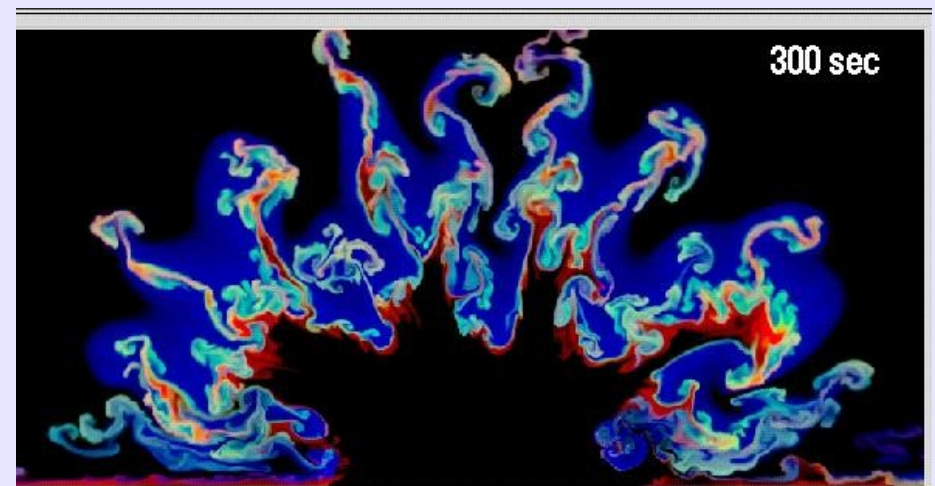
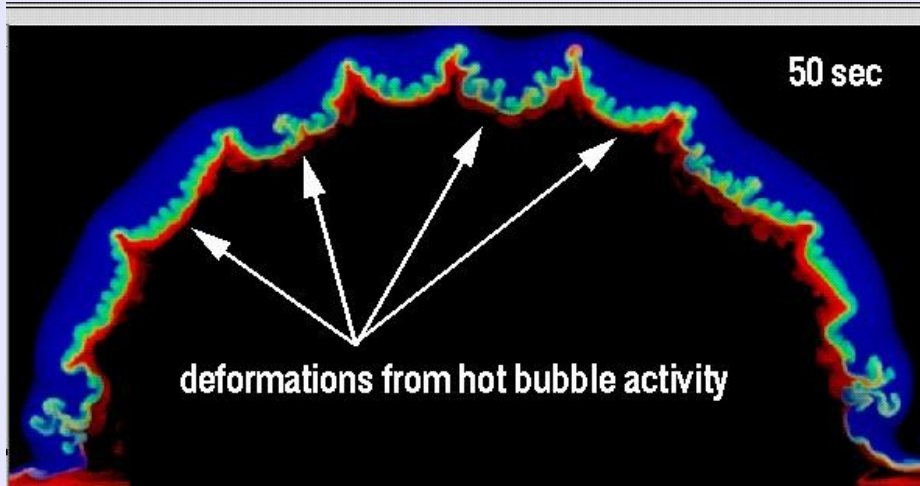
density



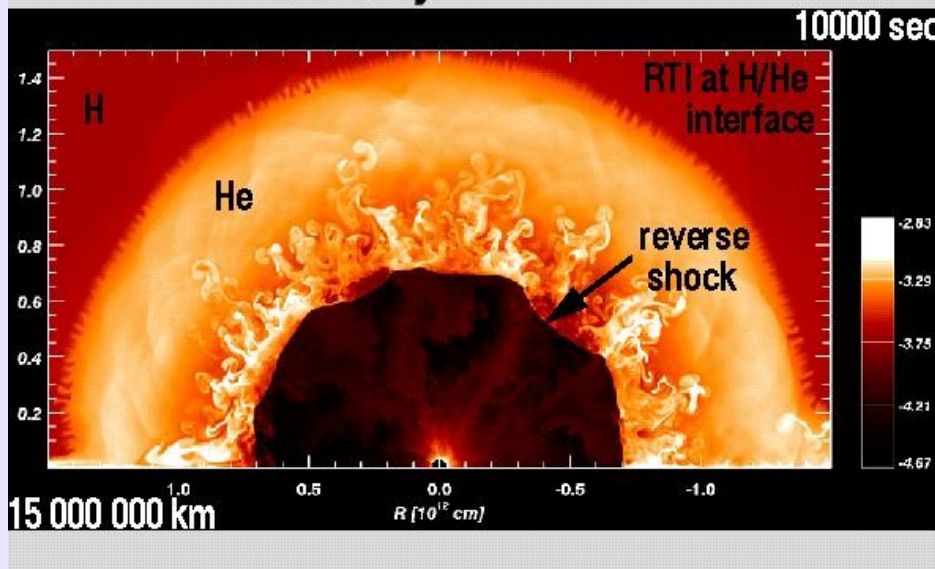
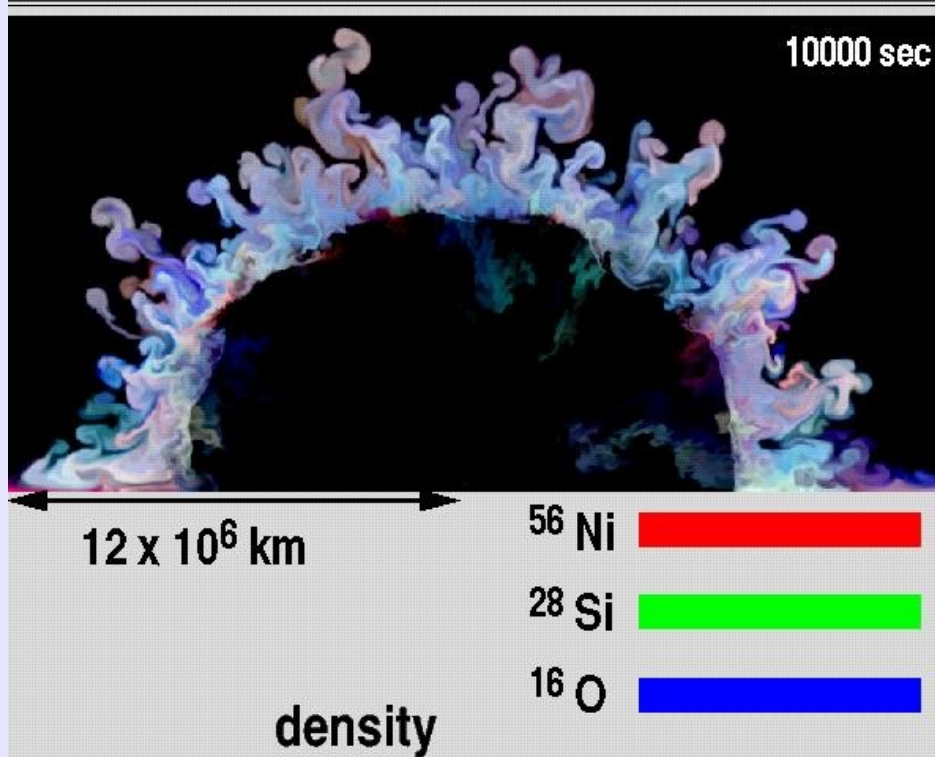
density



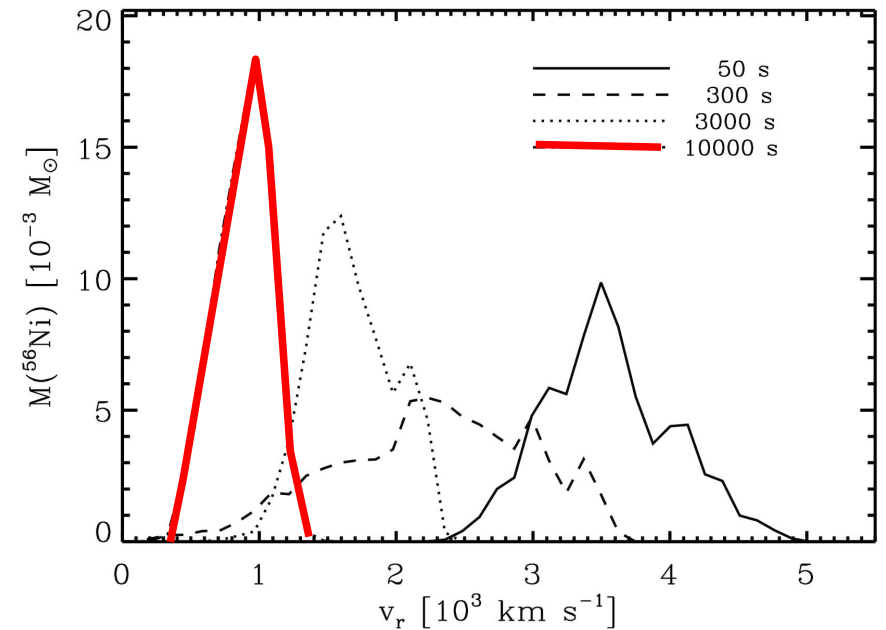
# Rayleigh-Taylor instabilities & mixing in stellar envelope



# Instabilities, mixing and nucleosynthesis in envelope



AMR simulation of shock propagation through stellar envelope (Kifonidis, Plewa, Janka & Müller 2003)



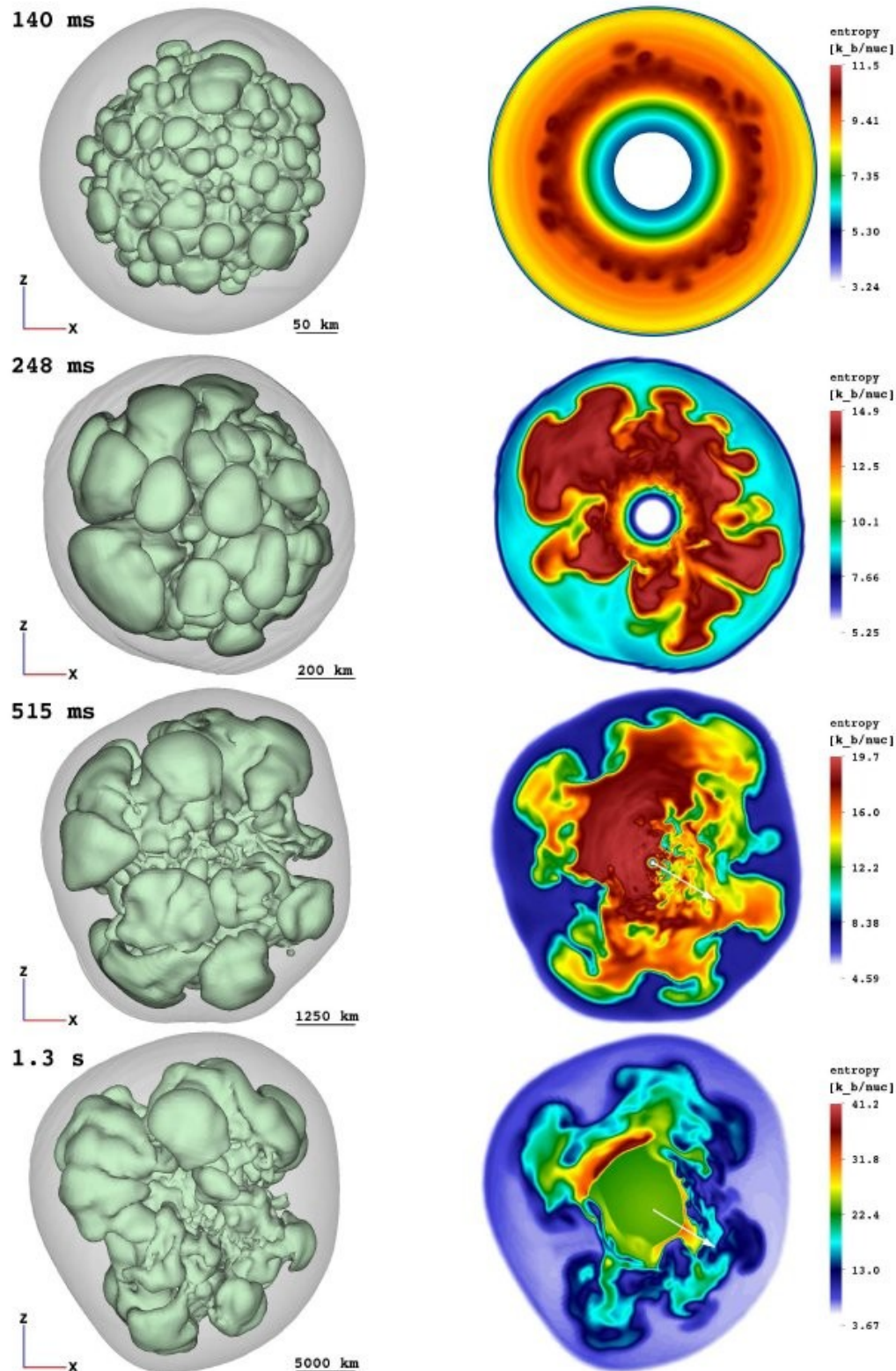
- results of simulations in accordance with observations of SNe Ib/Ic
- simulations do not reproduce large velocities of Fe/Ni observed in SN 1987A

Entropy-isosurfaces (left) of the SN shock (grey) & high-entropy bubbles (green), and entropy distribution in a cross-sectional plane (right)

*NS accelerates due to asymmetric distribution of the ejecta*

*ejecta distribution becomes dipolar with more dense, low-entropy matter concentrated in hemisphere of kick direction*

*essentially spherically symmetric neutrino wind bubble develops*



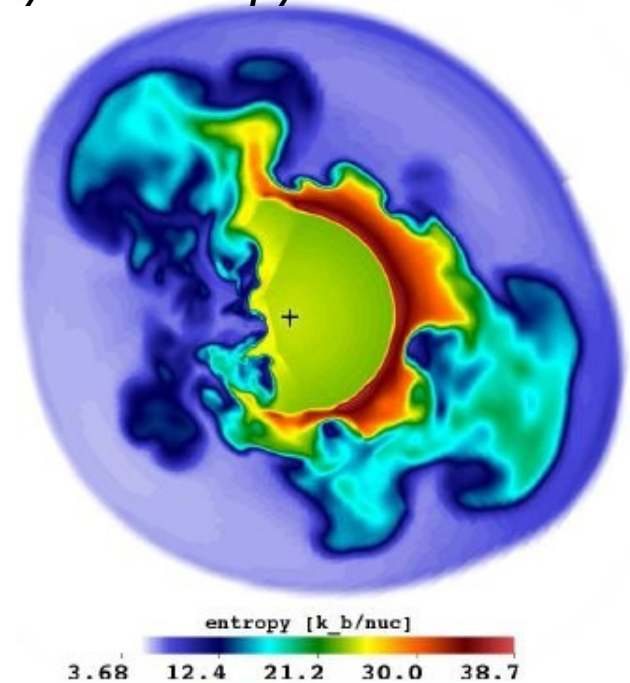
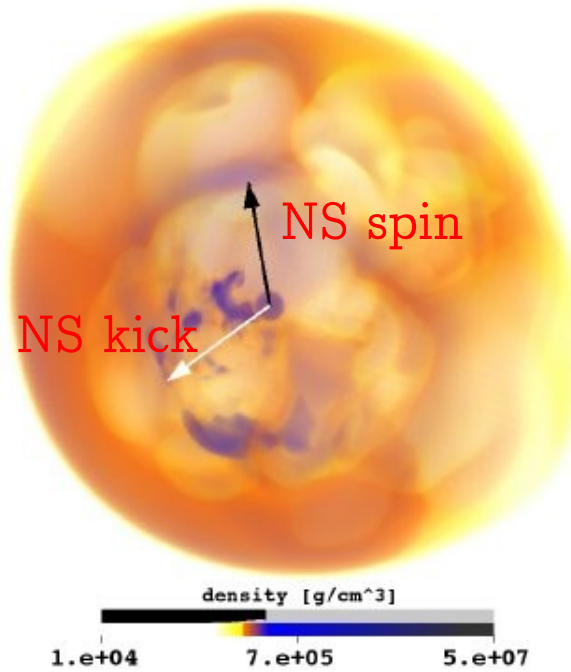
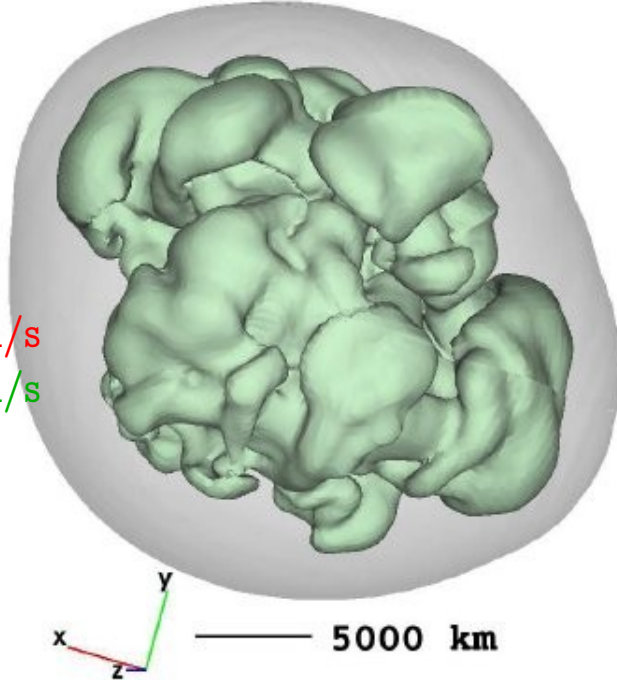
Wongwathanarat, Janka & Müller *ApJL* 725 ('10) 106; arXiv:1210.8148 ('12)

SN shock & bubbles

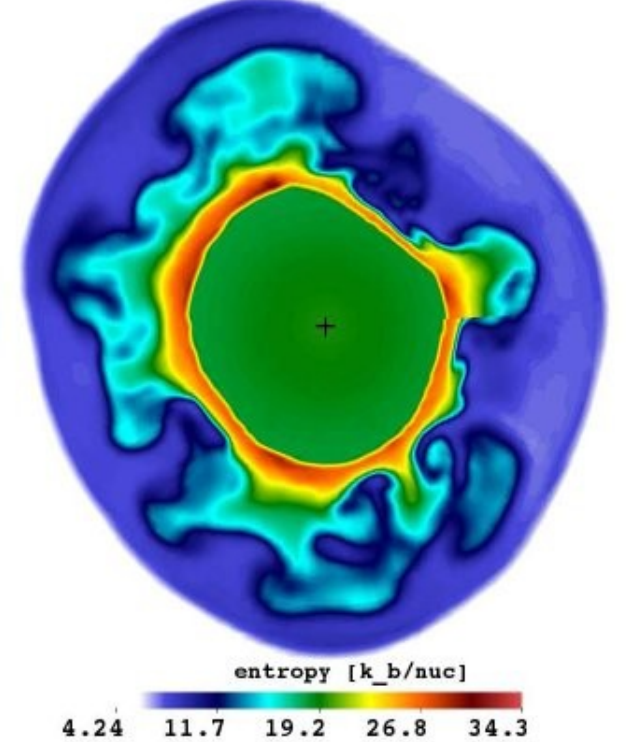
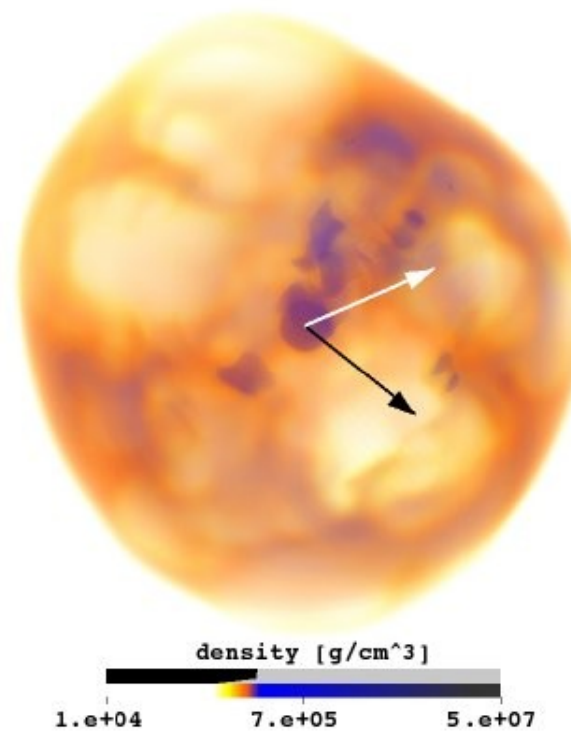
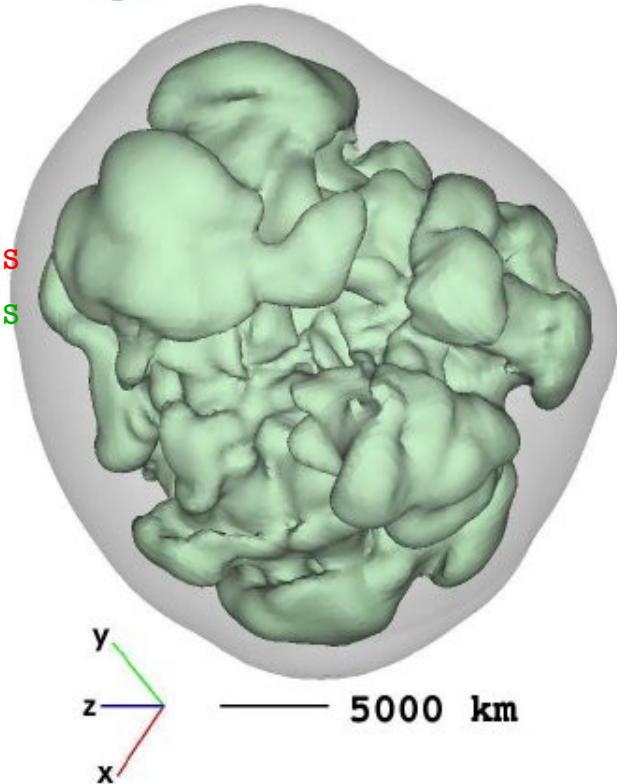
ray-casting images of the density

entropy distribution

W15-1  
1.3s  
331km/s  
524km/s



L15-2  
1.4s  
78km/s  
95km/s



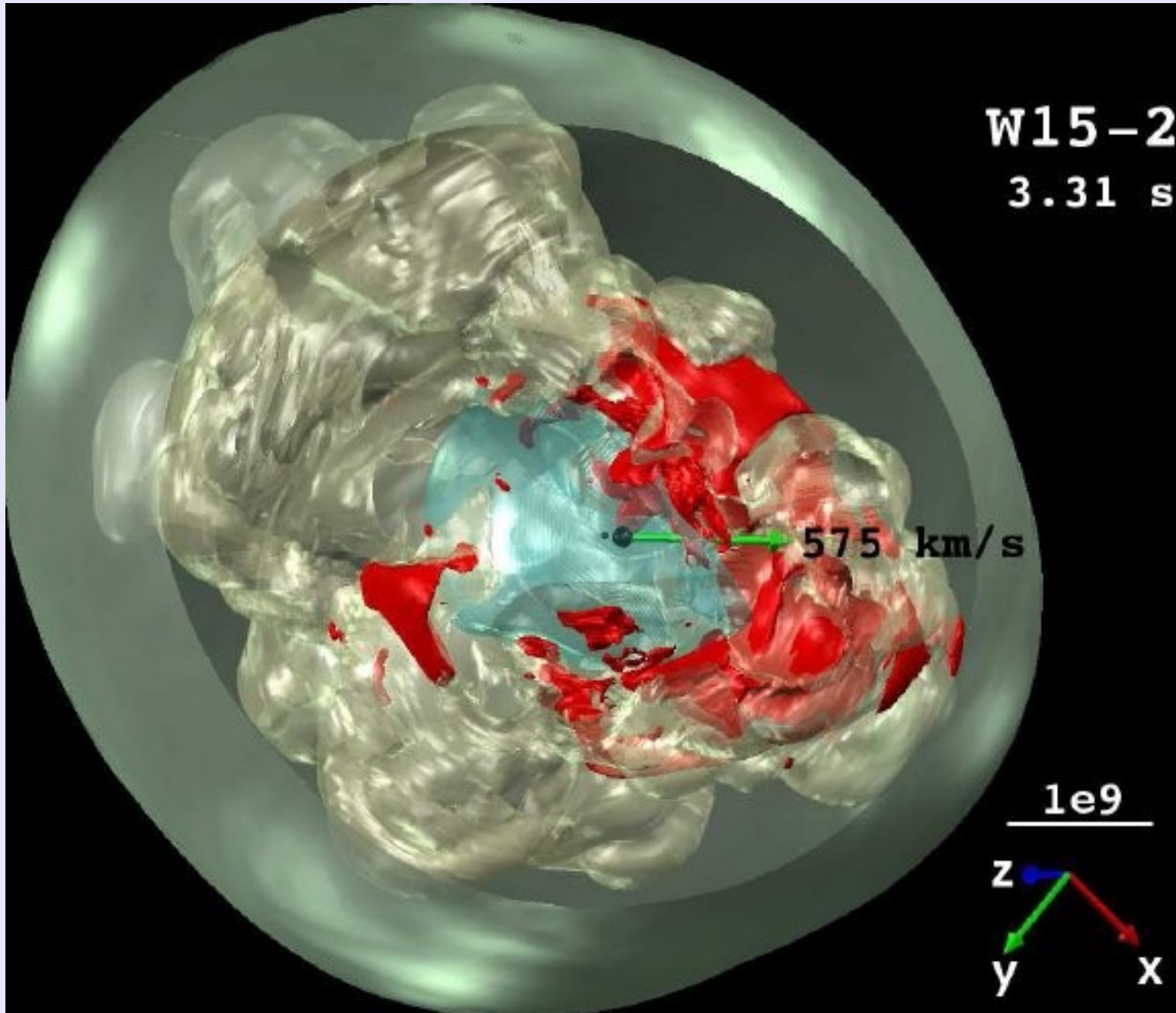
# neutron star recoil by gravitational tug-boat mechanism

ejecta  
morphology  
of high kick  
models  
(575 km/s)

red:  
high density  
clumps

beige & blue  
surfaces:  
outer & inner  
boundary of  
inner ejecta

outermost  
surface:  
SN shock



# Explosion and NS properties for all simulated 3D models

1.1 - 1.4 s

3.1 - 3.4 s

Model	$M_{\text{ns}}$ [ $M_{\odot}$ ]	$t_{\text{exp}}$ [ms]	$E_{\text{exp}}$ [B]	1.1 - 1.4 s		3.1 - 3.4 s		3.1 - 3.4 s		$J_{\text{ns},46}$ [ $10^{46}$ g cm <sup>2</sup> /s]	$\alpha_{\text{sk}}$ [ $^{\circ}$ ]	$T_{\text{spin}}$ [ms]
				$v_{\text{ns}}$ [km/s]	$a_{\text{ns}}$ [km/s <sup>2</sup> ]	$v_{\text{ns},v}$ [km/s]	$\alpha_{\text{kv}}$ [ $^{\circ}$ ]	$v_{\text{ns}}^{\text{long}}$ [km/s]	$a_{\text{ns}}^{\text{long}}$ [km/s <sup>2</sup> ]			
W15-1	1.37	246	1.12	331	167	2	151	524	44	1.51	117	652
W15-2	1.37	248	1.13	405	133	1	126	575	49	1.56	58	632
W15-3	1.36	250	1.11	267	102	1	160	-	-	1.13	105	864
W15-4	1.38	272	0.94	262	111	4	162	-	-	1.27	43	785
W15-5-lr	1.41	289	0.83	373	165	2	129	-	-	1.63	28	625
W15-6	1.39	272	0.90	437	222	2	136	704	71	0.97	127	1028
W15-7	1.37	258	1.07	215	85	1	81	-	-	0.45	48	2189
W15-8	1.41	289	0.72	336	168	3	160	-	-	4.33	104	235
L15-1	1.58	422	1.13	161	69	5	135	227	16	1.89	148	604
L15-2	1.51	382	1.74	78	14	1	150	95	4	1.04	62	1041
L15-3	1.62	478	0.84	31	27	1	51	-	-	1.55	123	750
L15-4-lr	1.64	502	0.75	199	123	4	120	-	-	1.39	93	846
L15-5	1.66	516	0.62	267	209	3	147	542	106	1.72	65	695
N20-1-lr	1.40	311	1.93	157	42	7	118	-	-	5.30	122	190
N20-2	1.28	276	3.12	101	12	4	159	-	-	7.26	43	127
N20-3	1.38	299	1.98	125	15	5	138	-	-	4.42	54	225
N20-4	1.45	334	1.35	98	18	1	98	125	9	2.04	45	512
B15-1	1.24	164	1.25	92	16	1	97	102	1	1.03	155	866
B15-2	1.24	162	1.25	143	37	1	140	-	-	0.12	162	7753
B15-3	1.26	175	1.04	85	19	1	24	99	3	0.44	148	2050



**prediction of an observable  
fingerprint** (in case of high kicks):

Ni production enhanced in  
direction of stronger  
explosion

**i.e. opposite to NS kick  
direction** (black arrow)!

model W15-2

*Wongwathanarat, Janka & Müller  
ApJL 725 (2010) 106;  
arXiv:1210.8148 (2012)*

365 ms

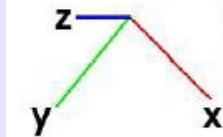
Ni mass per  
solid angle [g]

6.6e+29

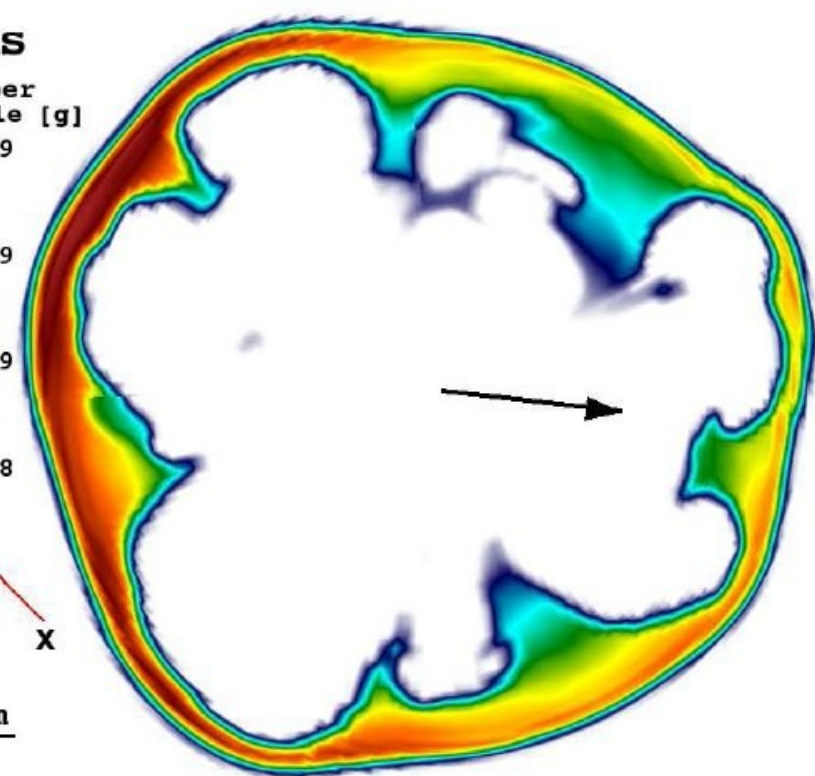
4.4e+29

2.2e+29

1.2e+18



500 km



515 ms

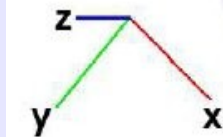
Ni mass per  
solid angle [g]

1.7e+30

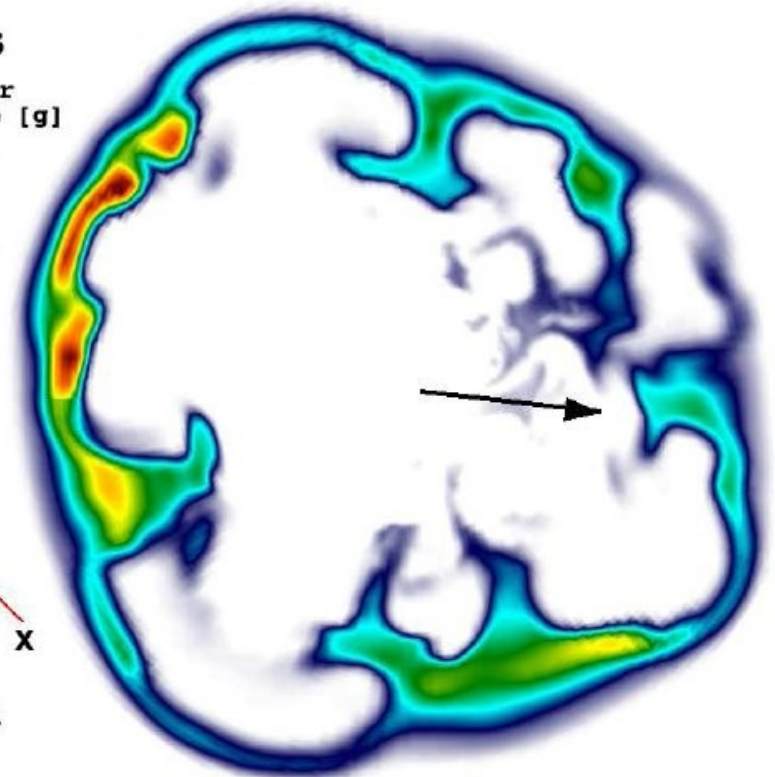
1.1e+30

5.6e+29

4.2e+17



1000 km



*Hemispheric ejecta yields for the high-kick models W15-1/2 & moderate-kick models L15-1/2*

*Tracer: yield of Fe-group nuclei in neutrino-processed ejecta, some undetermined fraction of which may be  $^{56}\text{Ni}$*

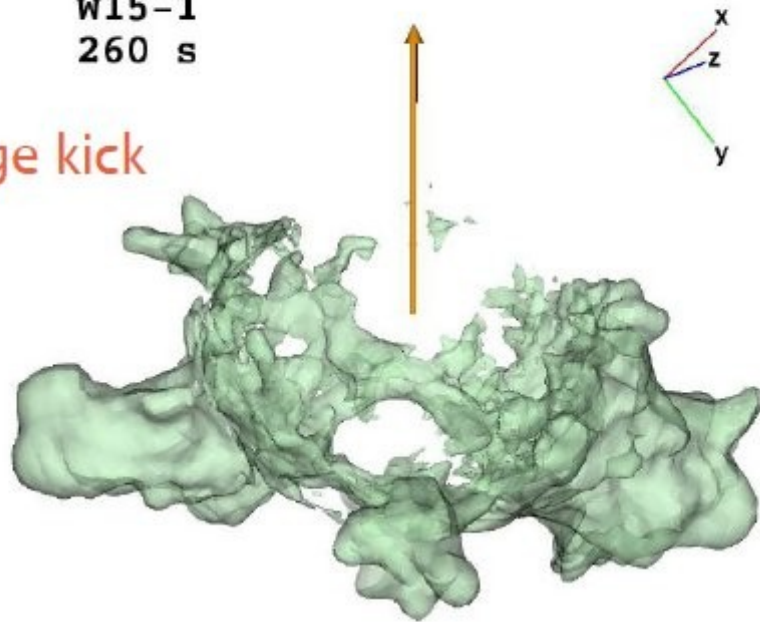
Model	$^4\text{He}$ [ $M_\odot$ ]		$^{12}\text{C}$ [ $10^{-1} M_\odot$ ]		$^{16}\text{O}$ [ $10^{-1} M_\odot$ ]		$^{20}\text{Ne}$ [ $10^{-2} M_\odot$ ]		$^{24}\text{Mg}$ [ $10^{-2} M_\odot$ ]	
	North	South	North	South	North	South	North	South	North	South
W15-1	2.78	2.66	1.18	1.10	3.68	3.75	8.90	8.49	2.41	2.85
W15-2	2.78	2.65	1.16	1.12	3.43	3.84	8.67	8.49	2.16	2.86
L15-1	2.39	2.34	0.90	0.87	2.77	2.89	5.00	5.06	2.12	2.49
L15-2	2.40	2.39	0.89	0.87	2.85	2.79	5.21	4.88	2.47	2.42

Model	$^{28}\text{Si}$ [ $10^{-2} M_\odot$ ]		$^{40}\text{Ca}$ [ $10^{-2} M_\odot$ ]		$^{44}\text{Ti}$ [ $10^{-3} M_\odot$ ]		$^{56}\text{Ni}$ [ $10^{-2} M_\odot$ ]		Tracer [ $10^{-2} M_\odot$ ]	
	North	South	North	South	North	South	North	South	North	South
W15-1	1.88	2.92	1.33	4.81	0.68	2.43	1.26	4.28	2.23	6.08
W15-2	1.74	2.83	1.27	4.66	0.81	2.17	1.37	4.09	2.22	6.27
L15-1	1.75	2.33	1.76	2.47	1.49	2.40	1.34	1.87	4.78	7.20
L15-2	2.13	2.15	2.54	2.74	2.32	2.55	1.81	1.89	8.68	9.74

# Neutron Star Recoil and Nickel Production

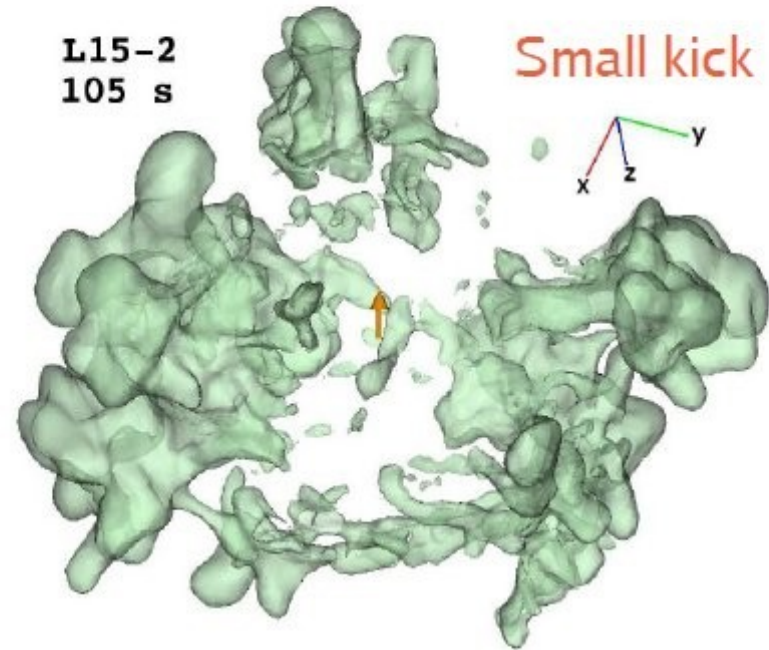
W15-1  
260 s

Large kick

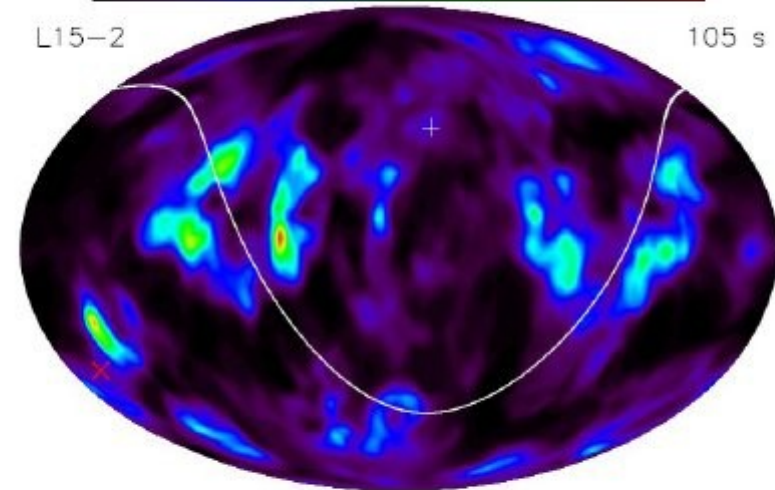
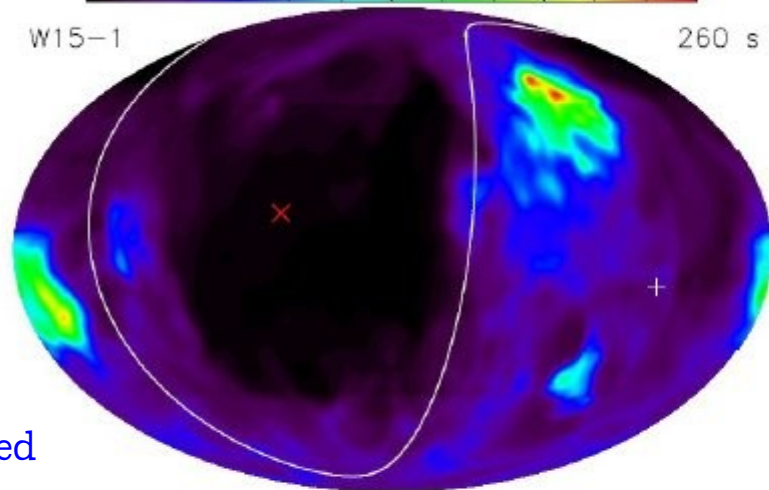


L15-2  
105 s

Small kick



nickel  
distribution  
of a large  
and  
small kick  
model



4π maps of  
the integrated  
nickel mass  
per solid angle

## conclusions

**non-radial flow and early mixing occurs** in 2D/3D core-collapse supernova models because of

- **neutrino-driven hydrodynamic instabilities** in the supernova engine (producing NS kicks, and spins)
- **shock-induced Rayleigh-Taylor instabilities** in the stellar envelope

## open questions

- dependence on explosion energy, progenitor, 2D/3D modeling?
- relative importance and interplay of the neutrino-driven and shock-induced instabilities?
- can we deduce from observations of young supernova remnants the operation of the supernova engine?
- influence of (rapid) rotation and (strong) magnetic fields?