

# Integration of magnetic measurement data in magnetic field simulations by BEM-based discrepancy modeling

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# Agenda

*Learning from data through the lens of models is a way to exploit structure in an otherwise intractable problem [1]*

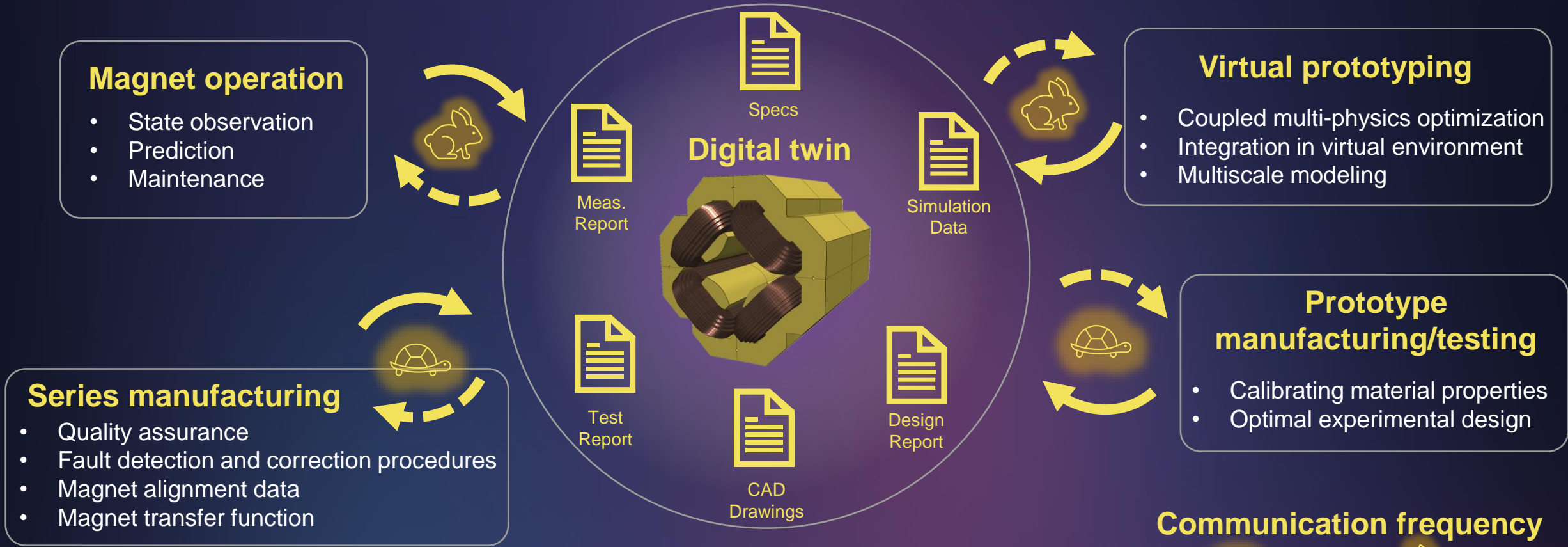
- The lifecycle of the accelerator magnet
- Hybrid modeling (Newton to Kepler)
  - Calibrated models
  - Delta models
- Integration in the life cycle management
- Conclusion

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# Accelerator magnet life cycle



**Product life cycle**

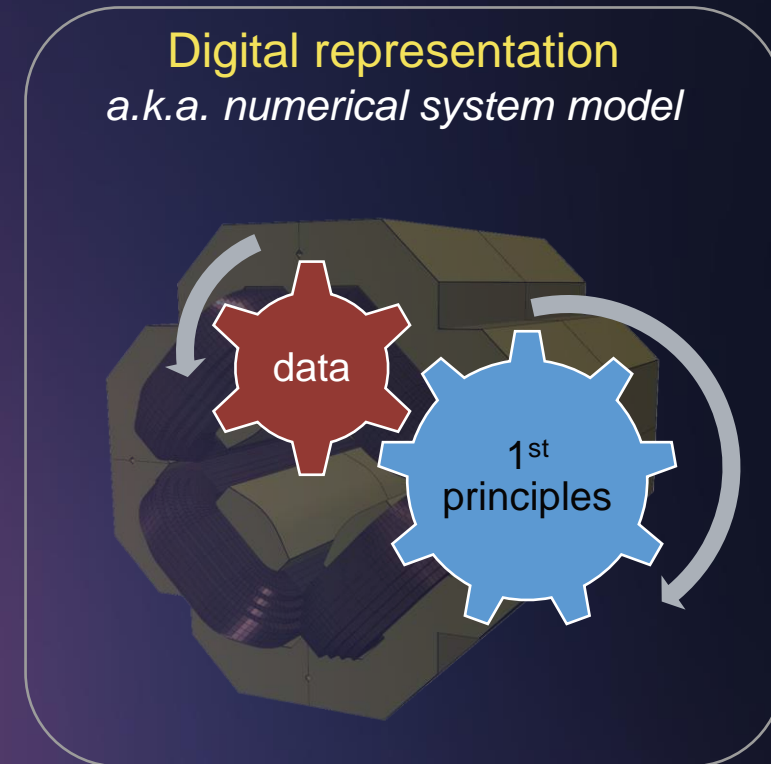
→ Principles of systems modeling  
→ Document based information exchange  
→ Communication frequency depends on the application  
→ Data management services → EMB, EMB-based, NORMA, PLM

**Communication frequency**

 slow  fast  
**Development life cycle**

# Challenges

- *Complex (non-linear) dynamic system*
  - Interplay of iron saturation, hysteresis and eddy currents
  - Superconductor magnetization
  - Temperature effects
- *Computational costs*
  - A complete 3D magnet simulation does not allow for fast predictions
- *Tough requirements for machine operation*
  - Field stability at 1 unit in 100 000
  - Field quality at 1 unit in 10 000



→ *Measurement data needs to be integrated in the numerical model to enable accurate predictions*

→ *Hybrid models integrate first principle and data driven models in a joint architecture*

# The field simulation software ROXIE

Routine for the Optimization of Magnet X-sections, Inverse Field Computation and Coil End Design

- *Developed for the design of the superconducting magnets for the LHC*
- *The standard tool for the design of  $\cos(\theta)$  magnets*
- *Features the calculation of 3D fields and iron magnetization*
- *Based on the coupling of boundary and finite elements (BEM-FEM), see [4]*

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RRR  RRR  000  000  XXX  XXXX  IIII  EEEE
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Routine for the Optimization of magnet X - sections,
Inverse field calculation and coil End design
VERS.22, UPDATE 0.1, 2022

(C) BY STEPHAN RUSSENSCHUCK,
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```

ROXIE default output

[4] S. Russenschuck, "ROXIE: Routine for the optimization of magnet X-sections, inverse field computation and coil end design.," in 1<sup>st</sup> International ROXIE Users Meeting and Workshop, Geneva, Switzerland, CERN Yellow Reports: Conference Proceedings, 3 1998.

# Agenda

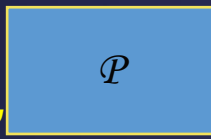
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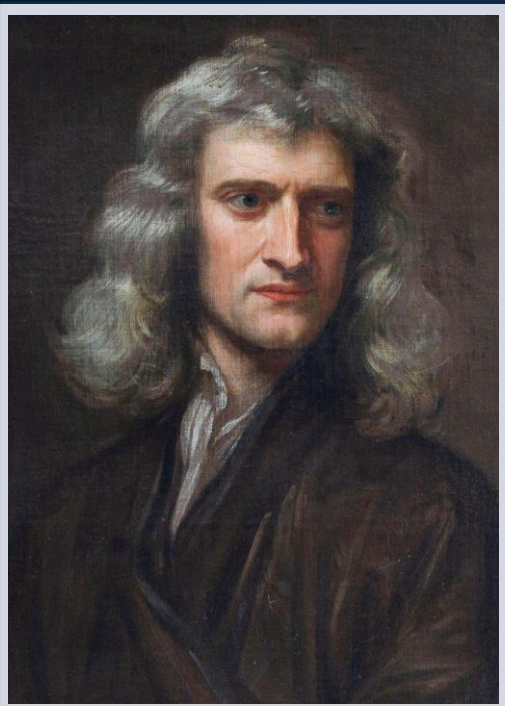


# Hybrid modeling [5]

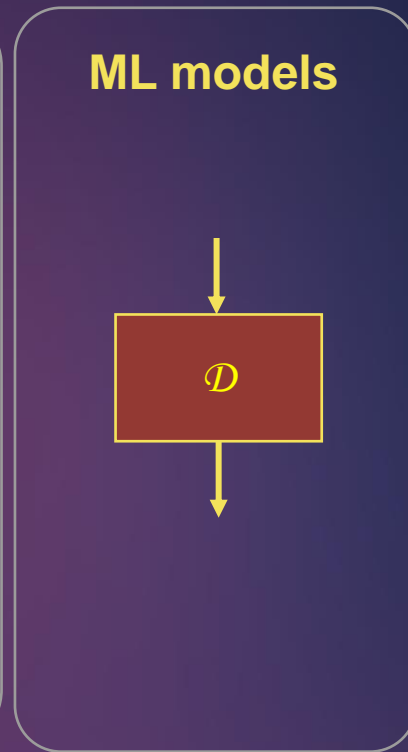
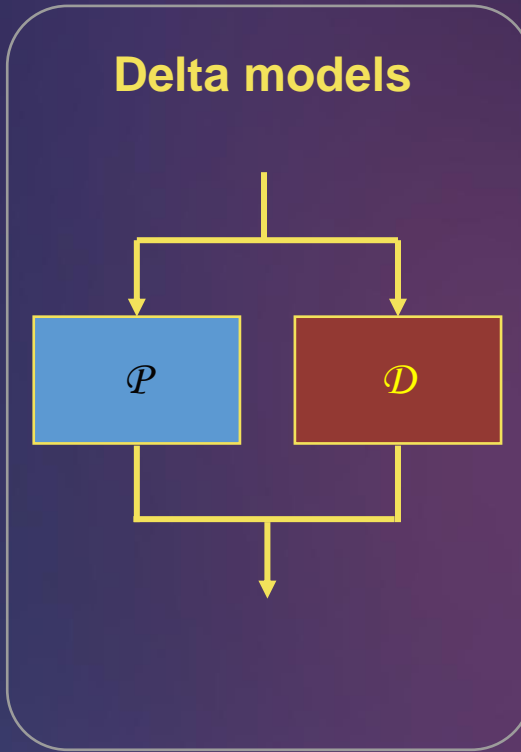
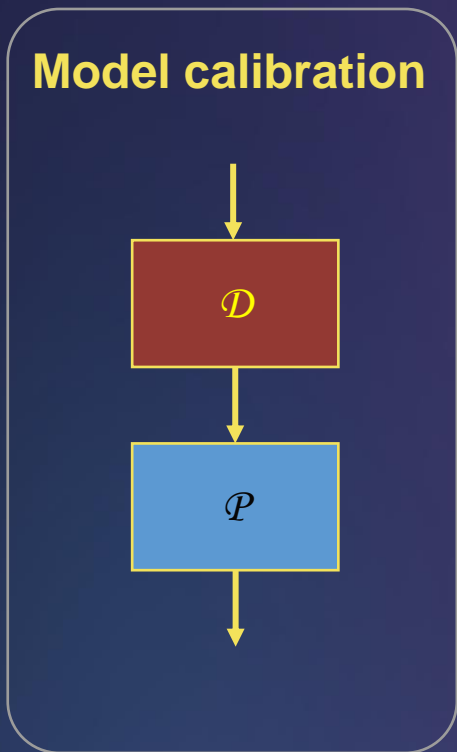
1<sup>st</sup> principle modeling  
“Newtonian paradigm”



Machine learning (ML)  
“Keplerian paradigm”



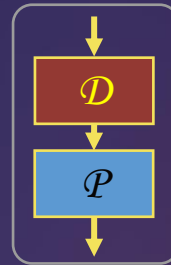
[https://commons.wikimedia.org/wiki/File:Sir\\_Isaac\\_Newton\\_by\\_Sir\\_Godfrey\\_Kneller,\\_Bt.jpg](https://commons.wikimedia.org/wiki/File:Sir_Isaac_Newton_by_Sir_Godfrey_Kneller,_Bt.jpg)



[https://de.wikipedia.org/wiki/Johannes\\_Kepler#/media/Datei:Portrait\\_Confused\\_With\\_Johannes\\_Kepler\\_1610.jpg](https://de.wikipedia.org/wiki/Johannes_Kepler#/media/Datei:Portrait_Confused_With_Johannes_Kepler_1610.jpg)



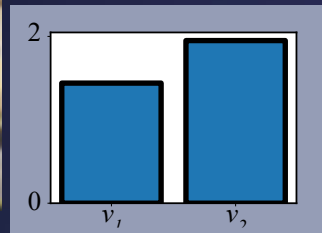
# Model calibration [6]



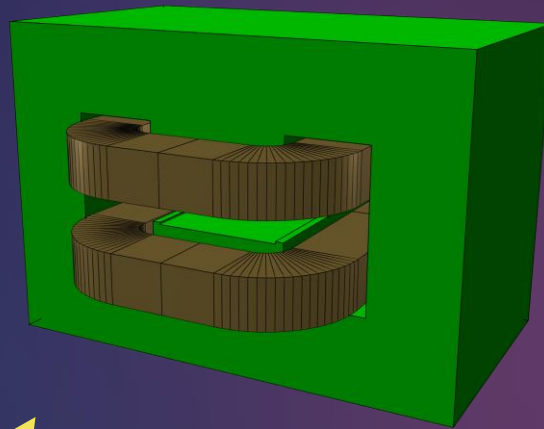
## Calibration test campaign



Resulting parameters

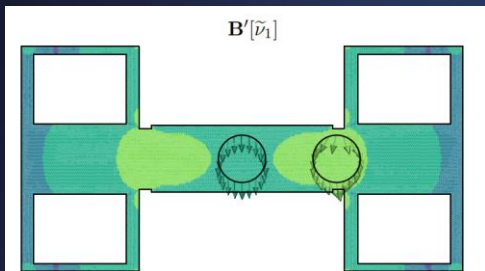


Digital twin



## Design of a test campaign

Design of experiment (DOE)  
optimal sensor placement

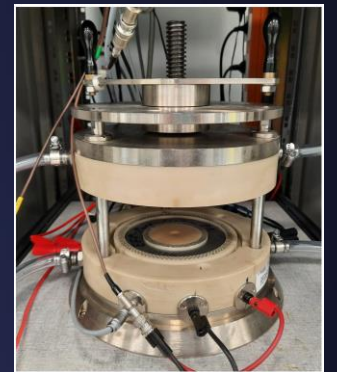


## Magnet manufacturing QA

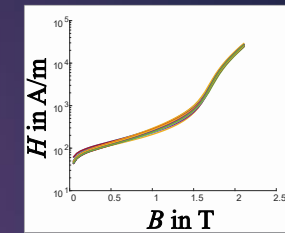
Material Specimen



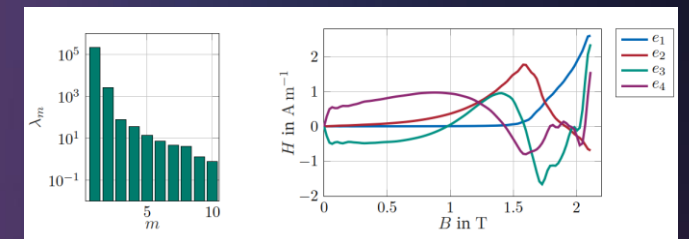
Permeameter



H(B)-curve

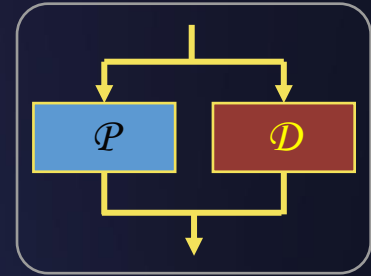
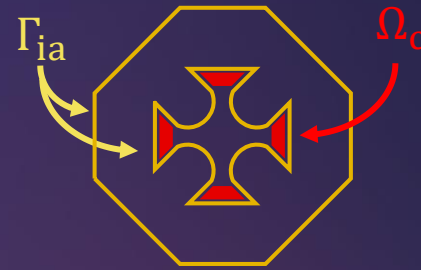


Pattern recognition (KLE)



# Delta models

- **The discrepancy** between measurement and simulation **may not vanish** after magnet calibration
- **The discrepancy** drives the delta model
- *The delta model may be used to understand the **origin of the discrepancy***
- *The predictions of the updated model are **matching our observations***



## ROXIE boundary integral equation for field evaluation

$$A(\mathbf{r}) = \int_{\Gamma_{ia}} \underbrace{A(\mathbf{r}')}_{\substack{\text{MVP} \\ \text{ROXIE} \\ \text{BEM-FEM}}} \partial_n u^*(\mathbf{r}, \mathbf{r}') dr' - \int_{\Gamma_{ia}} \underbrace{\partial_n A(\mathbf{r}')}_{\substack{\text{normal} \\ \text{derivative} \\ \text{ROXIE} \\ \text{BEM-FEM}}} u^*(\mathbf{r}, \mathbf{r}') dr'$$

$$+ \int_{\Omega_c} \underbrace{J(\mathbf{r}')}_{\substack{\text{Current} \\ \text{density in} \\ \text{coil domain}}} u^*(\mathbf{r}, \mathbf{r}') dr'$$

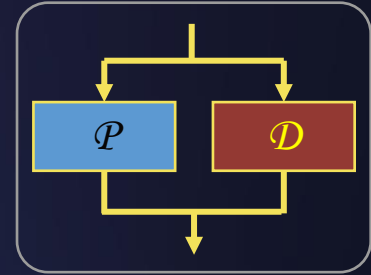
**Data driven update**

$$+ \int_{\Gamma_{ia}} \underbrace{\text{curl}_{\Gamma_{ai}} v}_{\substack{\text{fictitious} \\ \text{sources}}} u^*(\mathbf{r}, \mathbf{r}') dr'$$

$u^*$  Greens function

$$\Delta u^*(\mathbf{r}, \mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}')$$

# Delta models - Data driven model update



## Minimum energy solution

minimize  $E(v)$   
subject to:  $H(v) = y - \tilde{y}$

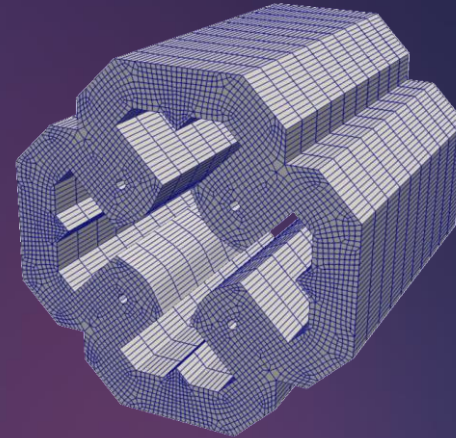
## Discretized on boundary mesh

minimize  $\frac{1}{2} v^T W v$   
subject to:  $H v = y - \tilde{y}$

→ *Model update is obtained by quadratic programming*

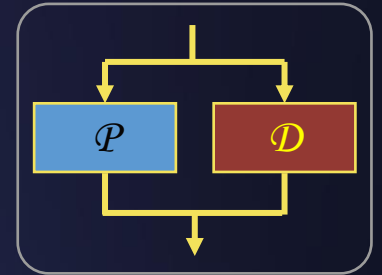
→ *We use the python software for convex optimization “cvxopt”*

## Boundary mesh

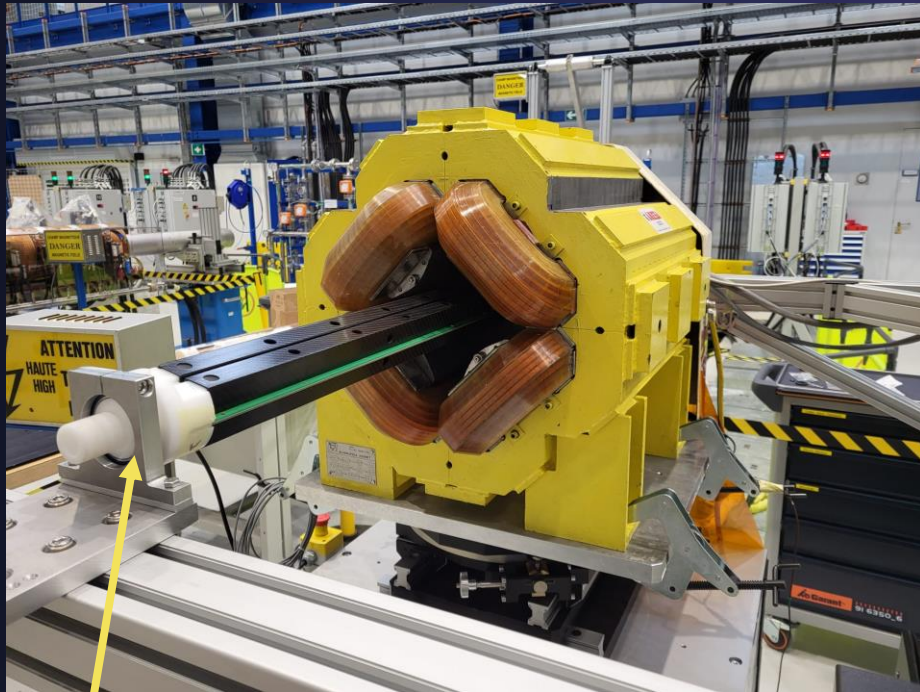


- $E(\cdot)$  Energy functional
- $W$  Energy matrix
- $H(\cdot)$  Observation operator
- $H$  Observation matrix
- $y$  Measurement data
- $\tilde{y}$  Predicted measurements

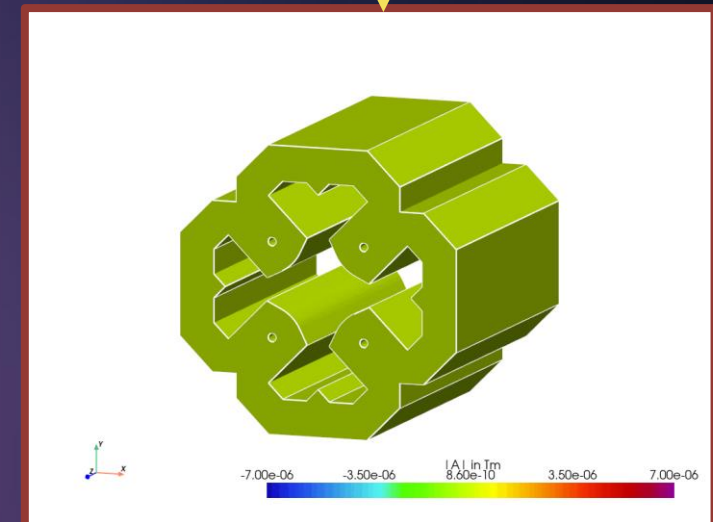
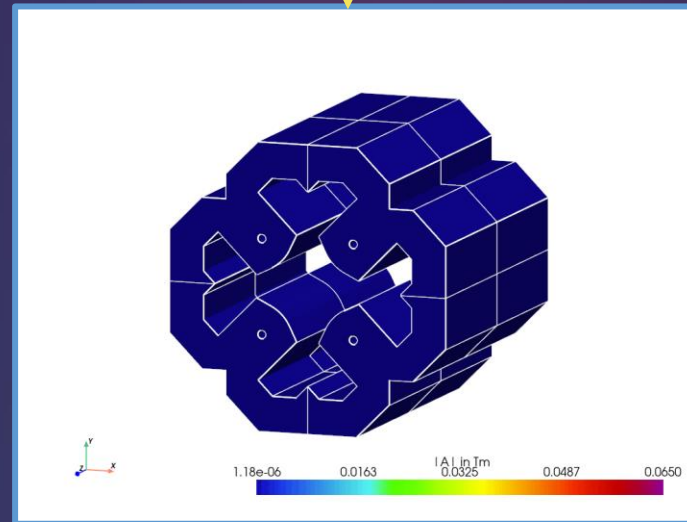
# Example integrated field measurement



Quadrupole magnet on test bench



Rotating coil measurement system





# Example 3D field mapping [7]

## Curved dipole magnet on test bench



## Model update ( $v_0 \rightarrow v_1$ ) by means of a linear Kálmán filter

$$Q_1 = (H^T R^{-1} H + Q_0^{-1})^{-1}$$

$$(H^T R^{-1} H + Q_0^{-1}) v_1 = H^T R^{-1} y + Q_0^{-1} v_0$$

$Q_0$  Prior covariance matrix

$Q_1$  Posterior covariance matrix

$H$  Observation matrix

$R$  Measurement covariance matrix

$y$  Measurement data

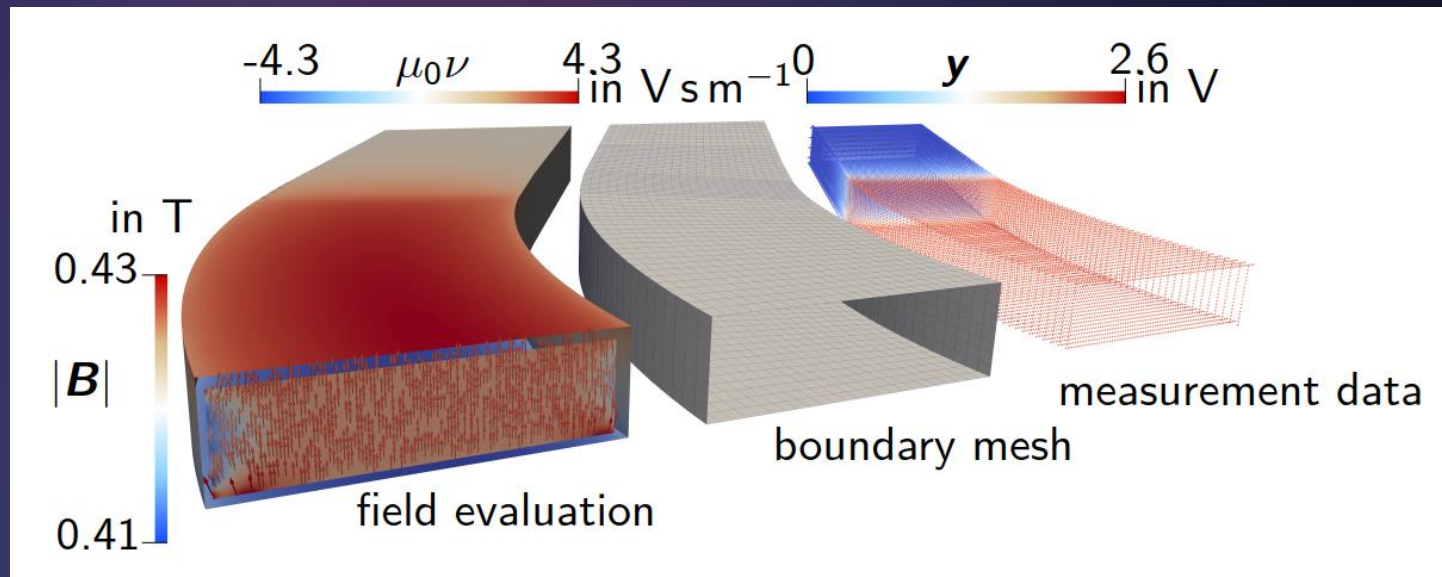


# Example 3D field mapping [7]

Curved dipole magnet on test bench



Measurement data, boundary mesh and model update

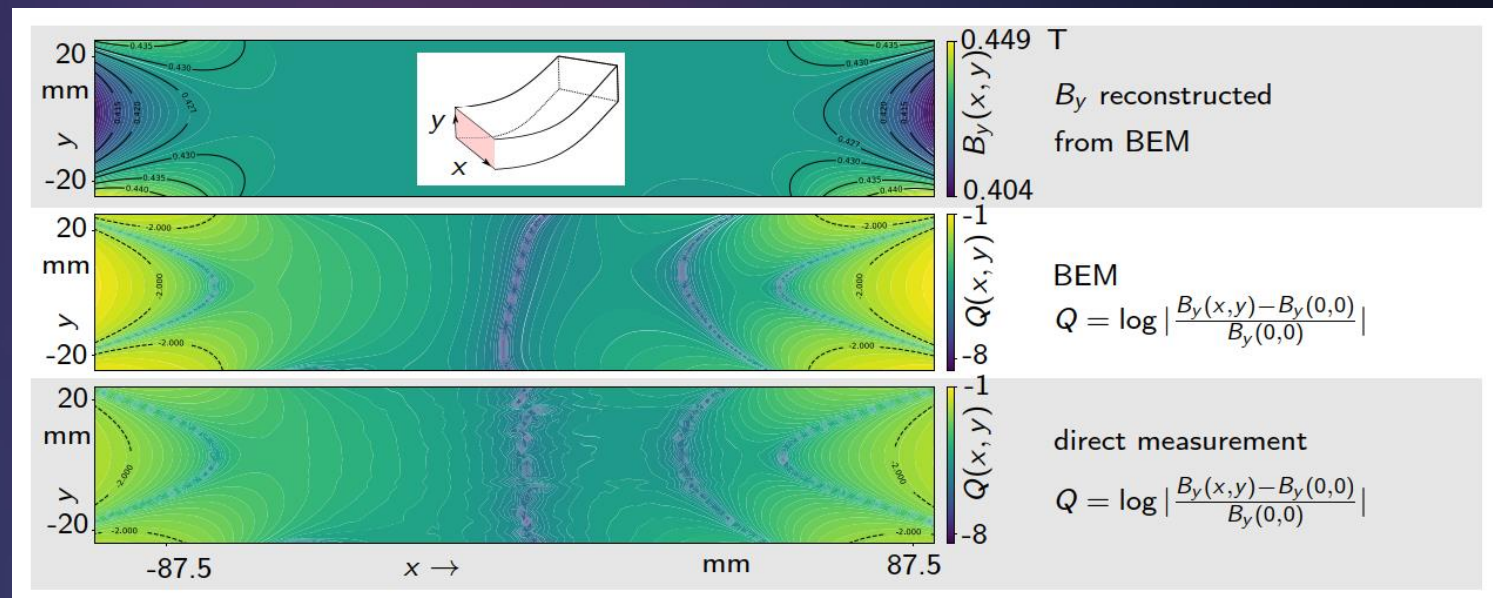


# Example 3D field mapping [7]

## Curved dipole magnet on test bench



## Validating the field evaluation





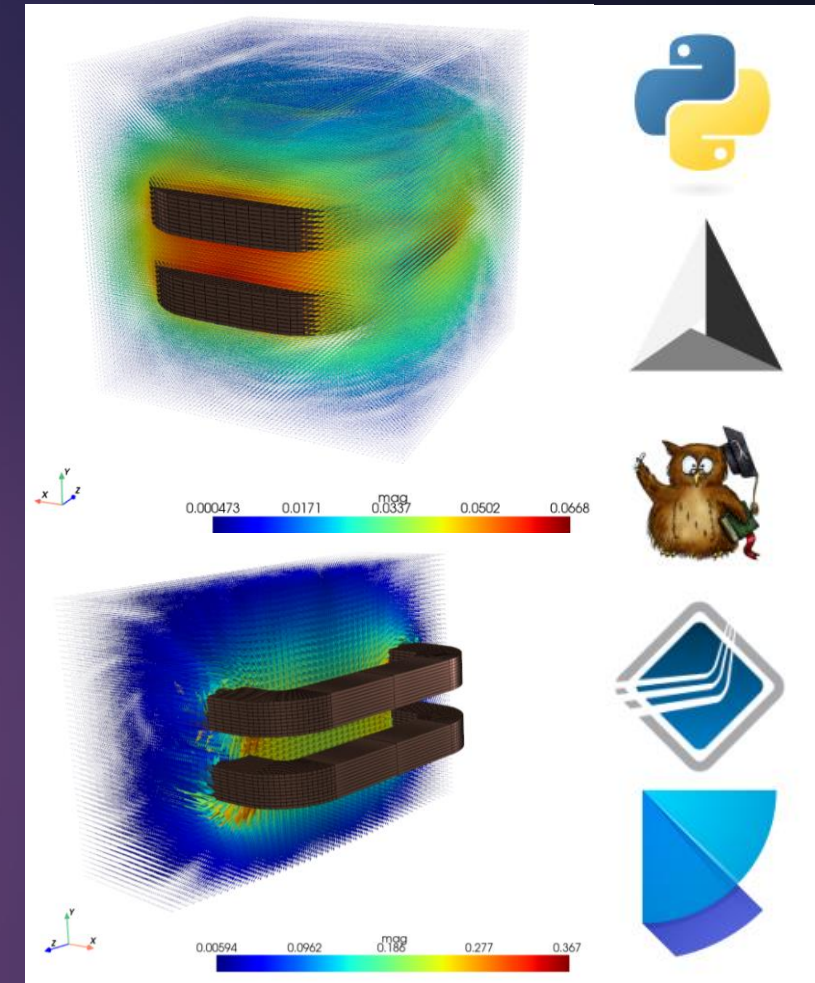
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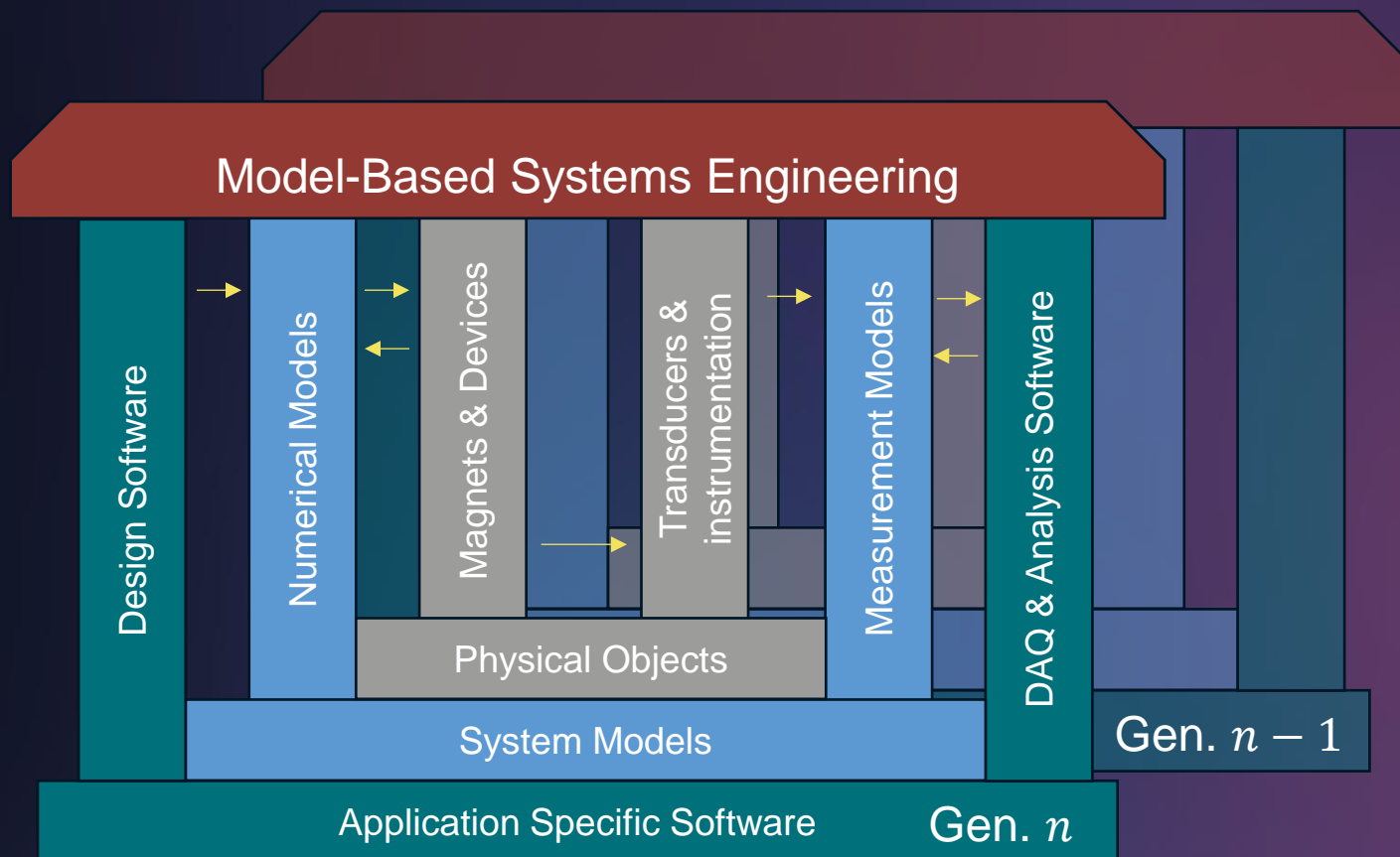
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# The ROXIE evaluator

- The ROXIE evaluator is python package for the **advanced post-processing and reverse engineering**
- We make extensive use of GMSH **for mesh operations and shape functions**
- **Performant C++ extensions** are used for the BEM matrix assembly
- The C++ code leverages on **vectorization (EigenC++)**  
**parallelization (OpenMPI)**
- It features a **Multi Level Fast Multipole Method (MLFMM) for accelerated field evaluation**
- The **poetry packaging manager** is used for platform independence and dependency tracking



# Integration



All systems models must be:

- **Exchangeable**
- **Versioned**
- **Integratable**

Application specific software for ROXIE

- **ROXIE API**
- **ROXIE evaluator**

The goal is to integrate our models in **pyMBSE** [8], a python toolbox for the self-contained **multi model execution**

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# Conclusion

- We use **hybrid modeling** to integrate magnetic measurement data in numerical field simulations
- Model calibration techniques alone are **sometimes not sufficient to find a match** between measurements and simulations
- Delta models are used to **compensate for discrepancies**
- They can provide an **indication of the cause of the differences**
- Our post-processing techniques leverage on **boundary integral equations**
- We follow the principles of model-based systems engineering to integrate the numerical models and simulation data in the **development and product lifecycle**