

Luminosity Fit and Influence of Beam Parameters

S. Pflüger

spfluege@gmail.com

Helmholtz Institute Mainz
(HIM)

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The Model

$$N(p) = L \cdot (\sigma(p) \cdot \epsilon(p)) \otimes Res$$

- ⊙ N : measured number of events
- ⊙ p : phase space variables
- ⊙ σ : cross section
- ⊙ ϵ : detection efficiency (without smearing)
- ⊙ Res : resolution function of detector
- ⊙ L : luminosity (fit param.)

INFLUENCE OF THE BEAM PARAMETERS

Categories

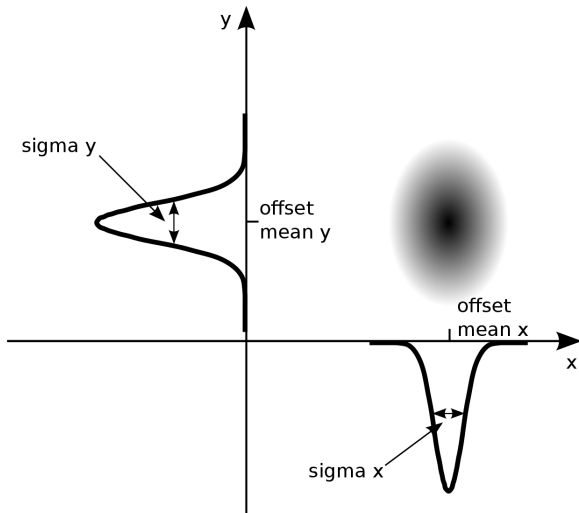
beam offset

- ⊙ displacement of the IP (here only in x and y)
- ⊙ beam offset is a pure acceptance effect \rightarrow can be completely corrected by acceptance correction
- ⊙ note: beam offset is equivalent to displacement of detector vertical to beam axis

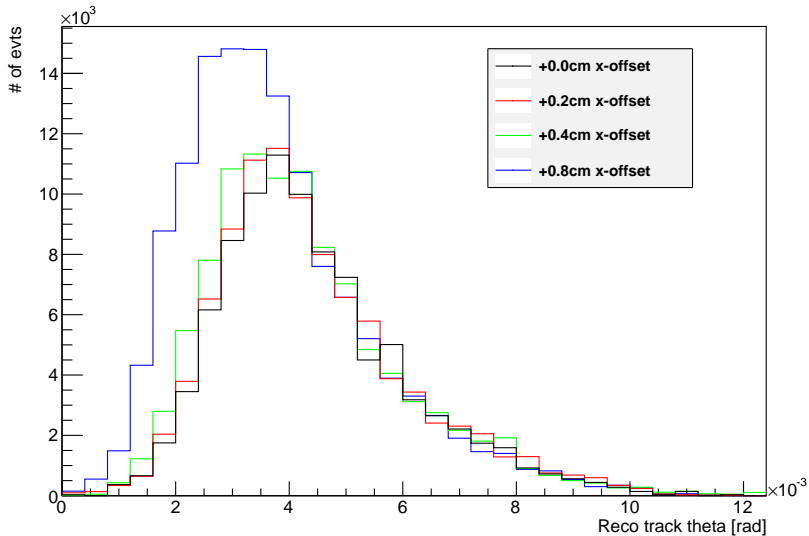
oblique beam

- ⊙ \bar{p} enter with an angle w.r.t. z -axis
- ⊙ angle modifies true distribution (MC truth) but also the acceptance
- ⊙ problem: cannot be measured directly
- ⊙ basic model needs modification
- ⊙ note: beam divergence is just an additional angular resolution

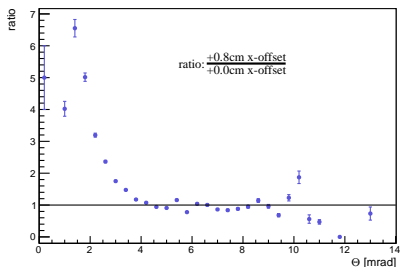
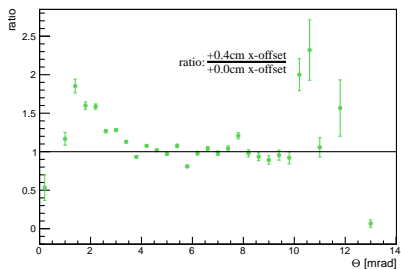
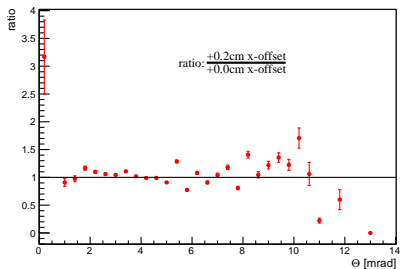
BEAM OFFSET PARAMETRIZATION



RECONSTRUCTION WITH BEAM OFFSET



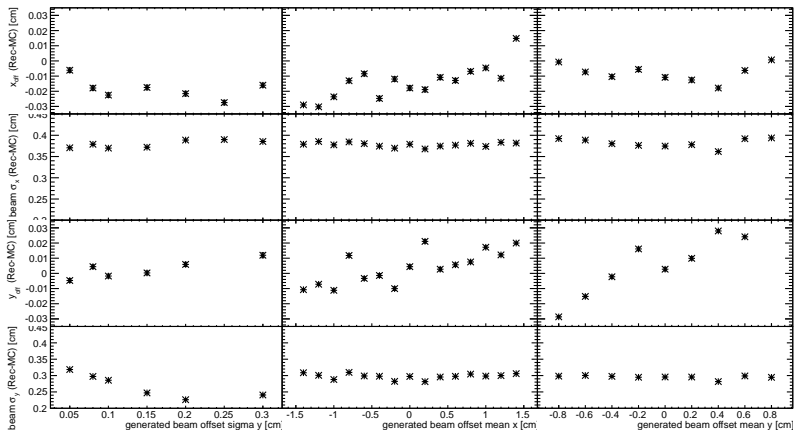
RECONSTRUCTION WITH BEAM OFFSET CONTD.



BEAM OFFSET CONCLUSION

- ⊙ precise determination of beam offset required for good acceptance description
- ⊙ how precise can our detector measure the beam offset?

BEAM OFFSET DEPENDENCIES: RESULTS



$x_{\text{off}} = 0.00 \text{ cm}$
 $y_{\text{off}} = 0.00 \text{ cm}$
 beam $\sigma_x = 0.08 \text{ cm}$
 beam σ_y was varied

x_{off} was varied
 $y_{\text{off}} = 0.00 \text{ cm}$
 beam $\sigma_x = 0.08 \text{ cm}$
 beam $\sigma_y = 0.08 \text{ cm}$

$x_{\text{off}} = 0.40 \text{ cm}$
 y_{off} was varied
 beam $\sigma_x = 0.08 \text{ cm}$
 beam $\sigma_y = 0.08 \text{ cm}$

BEAM PARAMETER DEPENDENCIES

Conclusions

- ⊙ x - and y -offset can be measured upto $300\mu m$ precision
- ⊙ σ_x and σ_y differences have constant offset from zero \rightarrow detector resolution

Outlook

- ⊙ include smearing in z (however influence will be minor)
- ⊙ additionally tilt the beam

THE LUMINOSITY FIT IN PRACTICE

ROOT

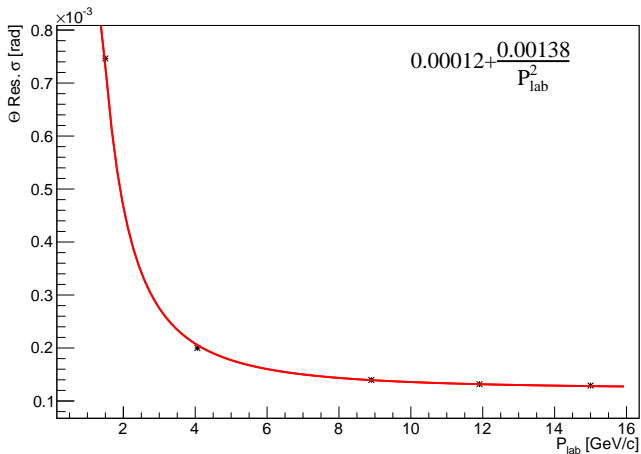
- ⊙ Pro: user has full control over procedure
- ⊙ Con: most implementations have to be written by user
- ⊙ currently: complete in 1D

RooFit

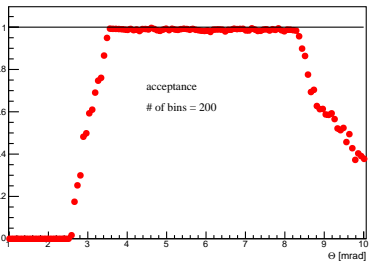
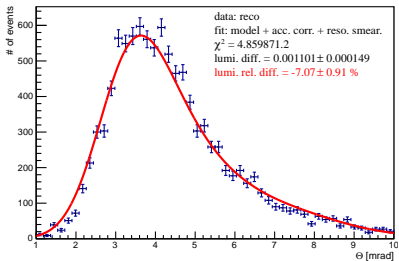
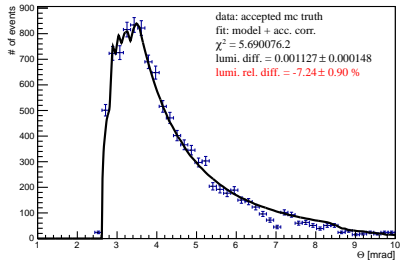
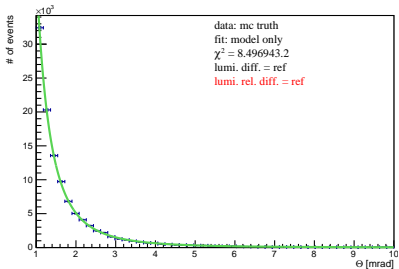
- ⊙ Pro: many nice features for model description (convolution and background modelling)
- ⊙ Cons: normalization difficulties and only very limited extension possibility
- ⊙ currently: not properly working yet

PARAMETRIZATION OF θ RESOLUTION

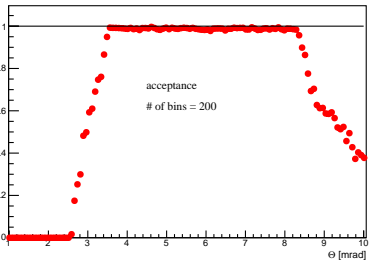
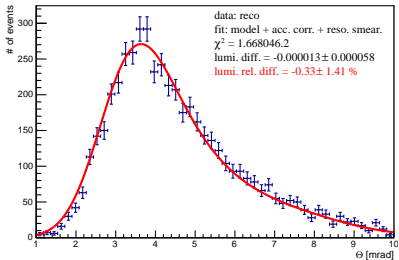
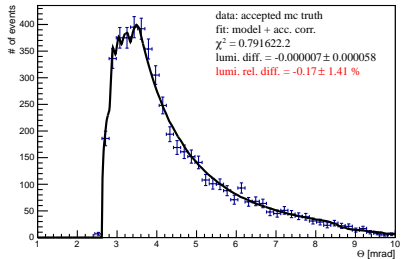
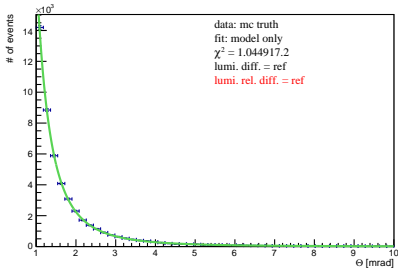
Major Dependence: P_{lab}



RESULT: DPM DATA + FIT AT $P_{lab} = 1.5\text{GeV}$



RESULT: TOY MC DATA + FIT AT $P_{lab} = 1.5\text{GeV}$



CONCLUSION

- ⊙ fit results look promising apart from model discrepancy to DPM generator
- ⊙ luminosity fit is on the verge of its first release
- ⊙ However: many more things that need to be implemented
 - ▷ influence of the beam
 - ▷ include inelastic component
 - ▷ etc.

END

Thanks for Your Attention!

ELASTIC CROSS SECTION

$$\frac{d\sigma}{dt} = \frac{d\sigma_C}{dt} + \frac{d\sigma_{int}}{dt} + \frac{d\sigma_H}{dt}$$

with

$$\frac{d\sigma_C}{dt} = \frac{4\pi\alpha_{EM}^2 G^4(t)}{\beta^2 t^2}$$

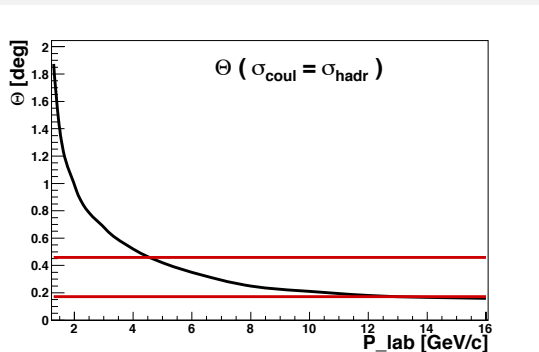
$$\frac{d\sigma_{int}}{dt} = \frac{\alpha_{EM}\sigma_{Total}}{\beta|t|} G^2(t) e^{\frac{1}{2}Bt} (\rho \cos(\delta) + \sin(\delta))$$

$$\frac{d\sigma_H}{dt} = A_1 \cdot \left[e^{t/2t_1} - A_2 \cdot e^{t/2t_2} \right]^2 + A_3 \cdot e^{t/t_2}$$

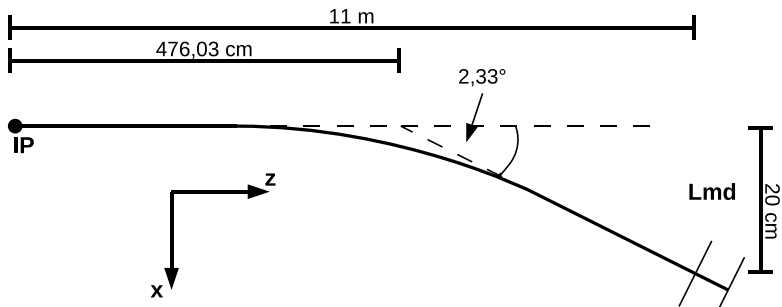
LUMINOSITY MEASUREMENT CONCEPT

\bar{p} - p Elastic Scattering

- ⊙ process with good knowledge: Coulomb scattering
- ⊙ minimal background at low momentum transfers
- ⊙ note: for now inelastic background is neglected

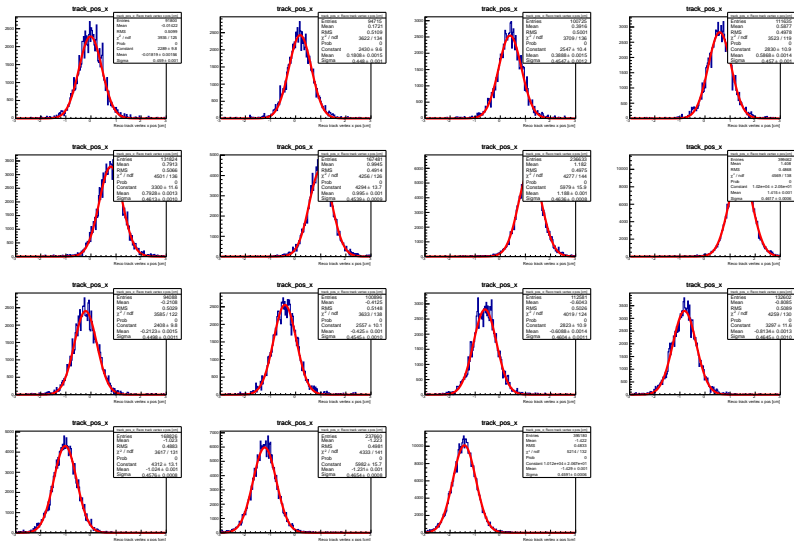


DETECTOR PLACEMENT



⊙ here: $E_{\text{beam}} = 1.5 \text{ GeV}$

BEAM OFFSET FIT EXAMPLE



DETECTOR RESOLUTION SMEARING

