

LabIOC

EPICS Channel Access server and client implemented in LabVIEW



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Features:

- Implemented purely in LabVIEW (not depending on EPICS base)
- LabIOC server publishes data stored in record database into Channel Access
- LabIOC client can read/write using Channel Access
 - Tested with EPICS 3.14 and EPICS 7
 - caget, caput, camonitor
 - Automatic monitoring, channel reconnection in background, batch connect/read/write

Not implemented:

- Many record types needed for processing inside EPICS database (only AI, AO, BI, BO, LONGIN, LONGOUT, MBBI, MBBO, STRINGIN, STRINGOUT implemented, no record links)
- Some fields of records (e.g. SCAN, all records behave as configured with SCAN=Passive)
- Reading .db files of EPICS base







- Server VI placed parallel to other loops (we had terrible results with asynchronously called server on cRIO), methods for starting/stopping the server
- Database methods for creating records, dbGet, dbPut
- Database can exist without Channel Access server for sharing data between parts of an application































- Interface for PV names (caget, caput) or channel references which are returned by PV search
- Data returned as variant or typecasted automatically (.vim functions), optional status, severity and time fields
- Functions for single PV and batch processing
- Cache of open TCP connections and channels
- Search and reconnect engine running in background



















































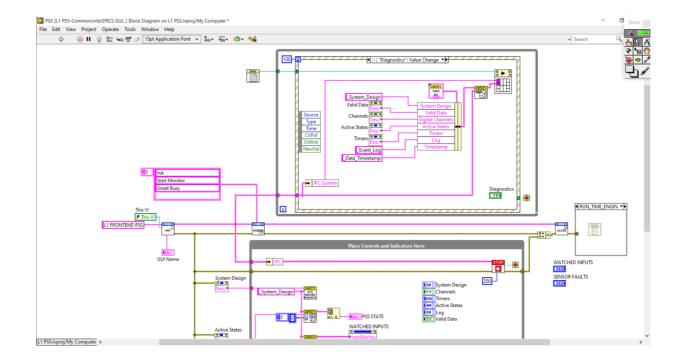








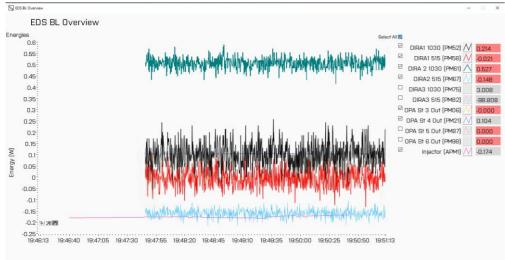
- Framework for building user interfaces on top of LabIOC client
- Automatic binding of an indicator to PV name specified in its description
- Descriptions can be hardcoded or read from configuration database -> easy-tomake, reusable GUIs
- Sometimes simple value display is not enough – GUIs are normal VIs and can be fully customized

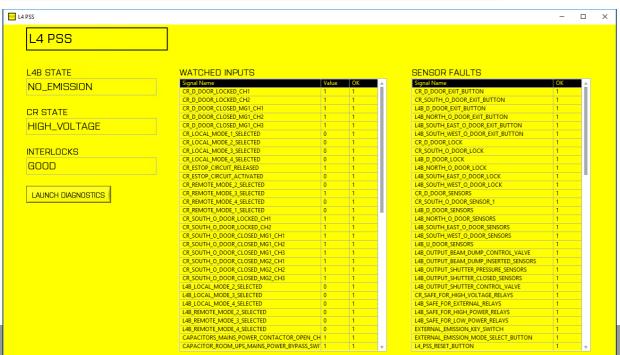












beamlines L3BT-S1-C514:IMG L3BT-S4-C516:IMG 5516083 Motor 1 Motor 1 0 1M 2M 3M 4M 5M 6M 7M 8M 9M 10M D 1M 2M 3M 4M 5M 6M 7M BM 9M 1DM 8767060 Motor 2 Motor 2 D 1M 2M 3M 4M 5M 6M 7M 8M 9M 1DM D 1M 2M 3M 4M 5M 6M 7M 8M 9M 1DM Step Size Cam1 Step Size Cam2

E3 Alignment



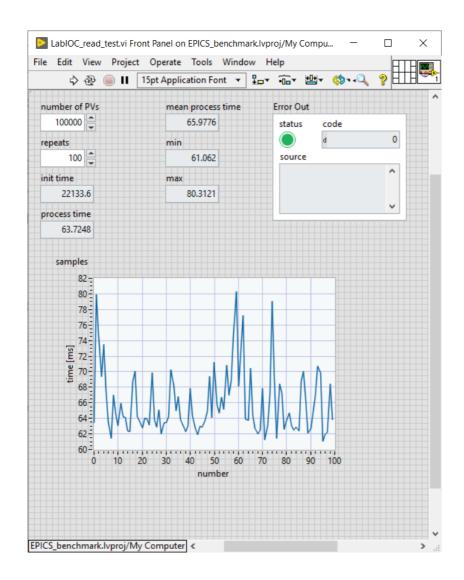




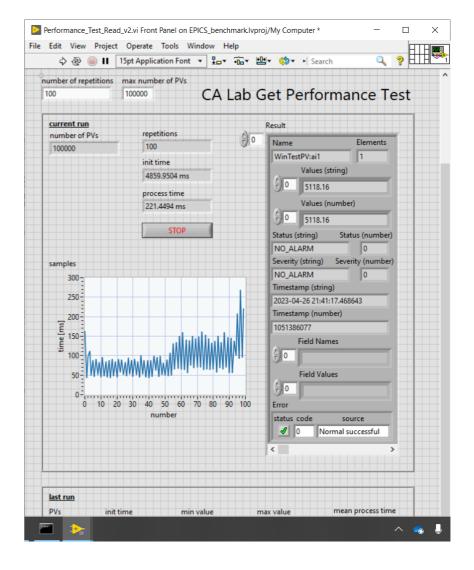
- LabIOC server
 - Publishing 4 camera images (.png ~ 300kB each) @ 10 Hz + hundreds of scalar variables
- LabIOC client
 - Benchmarked at HZB together with CALab
 - Both libraries optimized based on benchmarks, very similar results of latest versions







Performance







Thank you for attention

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