Software Developments for Hyperon Physics with PANDA@HADES

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PANDA CM Computing Session

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Tools For Hyperons at PANDA@HADES

Outline and Purpose of this Presentation

- Show software work PANDA members are doing also outside of PandaRoot
- Identify further connections to PandaRoot and collaborations

Outline

- Straw Tracking Stations
 - Tracking
 - Calibration
 - Alignment
- KinFit Experiment independent fitting library

General HADES

High-Acceptance Di-Electron Spectrometer

- Operating at GSI at SIS18 since 2001
- Precise spectroscopy of e^+e^- pairs and charged hadrons
- pp and heavy ion (e.g. Ag-Ag, Au-Au) collisions
- Main purpose: Dense nuclear matter properties via in-medium hadron properties
- Hyperon physics a hot topic lately
- Acceptance of detector: ${\sim}15\text{-}85^\circ$



Hyperons in the forward direction

- HADES missing low angular region where many hyperon decay products go
- Good idea to put a forward detector at low angles?



Figure from: Eur. Phys. J. A (2021) 57 :138

Forward Detector Upgrades

- Covers angles between ${\sim}1\text{-}7^{\circ}$
- Straw Tracking Stations (STS)
 - Based on PANDA design
 - Geometrical track
 Reconstruction
 - 8 double layers of straws
- Forward Resistive Plate Chamber (fRPC) timing detector
 - Momentum estimation
 - Magnetic field free region, mass hypothesis of protons currently assumed
- Used in feb21 proton test beam data taking and feb22 proton beam physics run



STS



Plane orientations: STS1: 0° , 90° , 90° , 0° STS2: 0° , 90° , $+45^{\circ}$, -45° Allows for 3D reconstruction

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Tracking, Clustering in Double Layers

Current tracking implemented by Rafal Lalik, based on CBM-MUCH and COSY-TOF code



- Pre-clustering in double layers
- Hits in configurations that are unlikely to have been created by different particles
- Reduce combinatorics and runtime

Figure from: Eur. Phys. J. A (2021) 57 :138

Tracking







Picture credit R. Lalik.

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Tracking High Resolution

- Every combination of wire center ± drift radius tested due to ambiguity
- Gives up to 2¹⁶ combinations

$$\chi^2 = \frac{1}{N} \sum_{i=0}^{N} \left(\frac{\Delta r_i(P)}{\sigma_{r_i}} \right)^2$$

- Δr_i (P) = distance between the i wire and the track drift radius
- σr_i = uncertainty



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Calibration



- Work by Gabriela Pérez Andrade
- Minimum time and t_{max} for integration found from signal shape
- Fit to drift-time spectrum used as input to tracking

Alignment

- pp-elastic scattering
- Measure one proton in main HADES where alignment is fairly well under control
- Use elastic scattering conditions to find the other proton in Forward Detector
- Re-calculate the angles of the forward going proton from the angles of the Main HADES proton
- Plot residuals between track and wire
- Shift the planes according to mean value



Left: residuals of original tracks after alignment

Possible outlook to test Millipede II [*] for alignment

[*] $https: //www.desy.de/ \sim kleinwrt/MP2/doc/html/index.html$

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KinFit, general

- KinFit: Experiment independent kinematic fitting tool
- Work by Jana Rieger, Waleed Esmail and myself
- Built using cmake, written in C/C++
- Developed within HADES and PANDA@HADES
- Intrinsically using HADES track parametrization (although user can construct their particle objects and pass to the fitter)
- Will be distributed via github
- Kinematic Track fitting: Track parameters are adjusted to fulfill the constraints using Lagrange multiplier method [*]

[*] A. G. Frodesen, O. Skjeggestad, Probability and Statistics in Particle Physics, Universitetsforlaget, Bergen, Norway, 1979

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KinFit, constraints

• Mass Constraint

• Geometric vertex Constraint

• Optimize track parameters with the constraint that the minimum track distance should be zero

• 3C Constraint

- Direction of the Neutral decay particle and that of the final state particle tracks
- 4-momentum of all the final state particles (*e.g.* p and π^-) at the decay vertex is conserved

4C Constraint

- 4-momenta of all-final state particles conserved w.r.t. beam-target system
- Missing particle constraint

Example Channel



- 3C constraint applied to proton + pion from decay + Λ
- 4C constraint applied to both protons + kaon + pion + beam-target system

Iterative Procedure

$$\chi^2 = \sum_{i=1} \frac{y_i - \eta_i}{\sigma_i^2} \quad \approx minimum$$

- y vector with measured track parameters
- η vector with improved track parameters
- σ uncertainties

$$\mathcal{L} = (y - \eta)^T V^{-1} (y - \eta) + 2\lambda^T f(\eta, \xi) \approx minimum$$

- *f* constraint equation(s)
- λ Lagrange multipliers
- ξ vector with unmeasured parameters
- V covariance matrix

$$f_k = f(\eta_1, \eta_2, ..., \eta_N, \xi_1, \xi_2, ..., \xi_J) = 0, \qquad k = 1, 2, ..., K$$

Iterative Procedure

$$r = f^{\nu} + F^{\nu}_{\eta}(y - \eta^{\nu})$$
$$S = F^{\nu}_{\eta}V(F^{\nu}_{\eta})^{T}$$

 F_{η} is a $K \times N$ Jacobian matrix $(F_{\eta} = \frac{\partial f}{\partial \eta})$ ν is the iteration number

$$\xi^{\nu+1} = \xi^{\nu} - (F_{\xi}^{T}S^{-1}F_{\xi})^{-1}F_{\xi}^{T}S^{-1}r$$
$$\lambda^{\nu+1} = S^{-1}\left(r + F_{\xi}(\xi^{\nu+1} - \xi^{\nu})\right)$$
$$\eta^{\nu+1} = y - VF_{\eta}^{T}\lambda^{\nu+1}$$

$$V^{Final} = V - V \left[F_{\eta}^{T} S^{-1} F_{\eta} - ((F_{\eta}^{T} S^{-1} F_{\xi}) (F_{\xi}^{T} S^{-1} F_{\xi})_{\text{T}}^{-1} (F_{\eta}^{T} S^{-1} F_{\xi})_{\text{T}}^{T}) \right]_{\text{T} \circ \text{C}} V_{\text{C}}$$

Classes

Ľ	KFitDecayBuilder.h
Ľ	KFitNeutralCandFinder.h
Ľ	KFitParticle.h
Ľ	KFitRootAnalyzer.h
Ľ	KFitVertexFinder.h
Ľ	KinFitter.h

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HADES track paremtrization

HADES track parameters:

- Momentum 1/p [a.u.]
- Polar angle θ [radians]
- Azimuthal angle ϕ [radians]
- R [mm] distance between beam axis and point of closest approach of track to beam axis
- Z [mm] z coordinate of point of closest approach of track to beam axis

Any point, \vec{p} , on straight line can be found from $\vec{p} = \vec{b} + t\vec{d}$ where t is a real number

Base: $\vec{b} = (b_x, b_y, b_z)$ and direction: $\vec{d} = (d_x, d_y, d_z)$ vectors uniquely define a straight line in 3D Can be constructed from HADES track

Can be constructed from HADES track parameters:

$$\begin{cases} b_x = R \cdot \cos(\phi + \pi/2) \\ b_y = R \cdot \sin(\phi + \pi/2) \\ b_z = Z \end{cases}$$
$$\begin{cases} d_x = \sin(\theta) \cdot \cos(\phi) \\ d_y = \sin(\theta) \cdot \sin(\phi) \\ d_z = \cos(\theta) \end{cases}$$

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Error Estimates



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Missing particle, Constraint equations

$$f = \begin{cases} \sum_{i=1}^{N} p_i \sin \theta_i \cos \phi_i + p_{\text{miss},x} - p_{\text{ini},x} = 0 \quad (p_x), \\ \sum_{i=1}^{N} p_i \sin \theta_i \sin \phi_i + p_{\text{miss},y} - p_{\text{ini},y} = 0 \quad (p_y), \\ \sum_{i=1}^{N} p_i \cos \theta_i + p_{\text{miss},z} - p_{\text{ini},z} = 0 \quad (p_z) \\ \sum_{i=1}^{N} \sqrt{p_i^2 + m_i^2} + \sqrt{p_{\text{miss}}^2 + m_{\text{miss}}^2} - E_{\text{ini}} = 0 \quad (E) \end{cases}$$

The sums are over all measured particles and ini is initial system. miss corresponds to missing particle

Missing Particle Fit, How to use the code

```
#include "TLorentzVector.h"
#include "KinFitter.h"
Double_t mass;
TLorentzVector ppSystem(p1,p2,p3,E);
KinFitter fitter(cand_vector);
void addMomConstraint(ppSystem, mass); // Choose
    momentum constraint for missing particle
fitter.fit();
TLorentzVector getMissingDaughter(); // Retrieve the
    missing daughter after the fit
```

χ^2 and Probability

- 1-to-1 correspondence
- Shape of χ^2 distribution determined by number of degrees of freedom
- Probability distribution should be uniformly distributed between 0 and 1
- Overestimation of errors → p-distribution pulled to higher values
- Underestimation of errors \rightarrow p-distribution pulled to lower values

• Example from toy MC

•
$$pp \rightarrow pK^+\Lambda$$
, $\Lambda \rightarrow p\pi^-$

• 3C fit



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- Example from toy MC
- $pp \rightarrow pK^+\Lambda$, $\Lambda \rightarrow p\pi^-$
- Simple fit



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Pull distributions

Ideally N(0,1) distributed

$$pull = \frac{x_{fit} - x_{meas}}{\sqrt{\sigma_{fit}^2 - \sigma_{meas}^2}}$$

- Overestimation of errors → narrower peak
- Underestimation of errors \rightarrow broader peak

Example from toy MC

•
$$pp \to pK^+\Lambda$$
, $\Lambda \to p\pi^-$

• 3C fit



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Resolutions

- Example from toy MC
- $pp \rightarrow pK^+\Lambda$, $\Lambda \rightarrow p\pi^-$
- 3C fit
- Resolution greatly improved after fitting



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Runtime of code

- stl chrono
- i7-1185G7 processor at 3.00GHz
- Average processing time of 1000 fits
- SImilar performance for all constraints

Stage	Fitting	Initialization	Vertex Finding	Neutral Candidate Finding
Time / event [μ s]	10	1	1	1

Table: Runtime of different parts of KinFit.

Possible PandaRoot Connections

- Incorporate functionality from the DecayTreeFitter for sequential decays into KinFit/HYDRA (HADES Software) or make the DecayTreeFitter independent from PandaRoot
- Exporting the Rho package to HYDRA?
- For tracking in the STS, test ACTS when possible to use for gaseous detectors
- High level QA for tracking used at HADES, interesting to also try PANDAs advanced low-level trackingQA?
- Calibration (to some extent also alignment) procedure for STS applicable for PANDA
- Test other PandaRoot (tracking) algorithms with STS?

Thank you!

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