# **Generation of Transfer Maps**



### **Motivation**

Goal: identification of magnetic field errors

- compare predicted to measured trajectories
- minimize discrepancy
  - vary multipole strengths
  - gradient-based optimization algorithms

#### Require

tracking differentiable w.r.t. multipole strengths

# Hamiltonian Dynamics

#### Hamiltonian

$$H = c\sqrt{m^2c^2 + \left(\vec{p} - e\vec{A}(\vec{q})\right)^2} + e\phi(\vec{q})$$
(1)

eqn. of motion

$$\dot{q}_{i} = \frac{\partial H}{\partial p_{i}}$$

$$\dot{p}_{i} = -\frac{\partial H}{\partial q_{i}}$$
(2)
(3)

transfer map  $\Leftrightarrow$  solution of eqn. of motion

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# Formal Solution of Eqn. of Motion

Poisson bracket

$$f,g\} = \sum_{i=1}^{n} \frac{\partial f}{\partial q_i} \frac{\partial g}{\partial p_i} - \frac{\partial g}{\partial p_i} \frac{\partial g}{\partial q_i}$$

express eqn. of motion via Poisson bracket

$$\vec{z} = [q_1, ..., q_n, p_1, ..., p_n]^T$$

$$\dot{\vec{z}} = -\{H, \vec{z}\} = -\underbrace{\{H, \cdot\}}_{\text{diff, operator}} \vec{z}$$
(5)
(6)

(4)

(7

formal solution

$$\vec{z}(t) = \mathbf{e}^{-t\{H,\cdot\}}\vec{z}(0)$$

# **Transfer Map**

transfer map  ${\cal M}$ 

$$\vec{z}(t) = \mathcal{M}\vec{z}(0) = \mathbf{e}^{-t\{H,\cdot\}}\vec{z}(0)$$
(8)

### Thin-lens Approximation

factorize

$$\mathbf{e}^{-t\{H,\cdot\}} \approx \prod_{i} \mathbf{e}^{-t\mathbf{c}_{i}\{H_{drift},\cdot\}} \mathbf{e}^{-td_{i}\{H_{kick},\cdot\}}$$

calculate each factor analytically

#### TPSA

truncate to power N

$$\mathbf{e}^{-t\{H,\cdot\}} \approx \sum_{k=0}^{N} \frac{1}{k!} \left(-t\{H,\cdot\}\right)^{k}$$

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## **Dual Numbers**

- extend real numbers  $z_{dual} = a + \epsilon b$ 
  - **a**,  $b \in \mathbb{R}$
  - special element  $\epsilon \neq 0$ :  $\epsilon^2 = 0$
- all arithmetic operations defined

$$(a + \epsilon b) + (c + \epsilon d) = (a + c) + \epsilon (b + d)$$

- $a + \epsilon b) * (c + \epsilon d) = (a + c) + \epsilon (ad + bc)$
- etc...
- generalization to hyperdual numbers  $\epsilon_1$ ,  $\epsilon_2$ ,  $\epsilon_3$ , ...

## **Dual Numbers: Application**

let  $f : \mathbb{R} \to \mathbb{R}$ 

• using dual numbers yields f(a) and derivative f'(a)

$$f(\mathbf{a} + \epsilon \mathbf{b}) = f(\mathbf{a}) + \epsilon f'(\mathbf{a})\mathbf{b}$$
(9)

- hyperdual numbers: series expansion of f
- works for any computer program

differentiation defined

 $\bullet \ \partial \left[ f(a) + \epsilon f'(a) \right] = f'(a)$ 

• implementation of differential operators  $\Rightarrow$  Poisson bracket

# **Generation of Transfer Map**

(hyper-) dual numbers

calculation of

$$\mathcal{M} = \mathbf{e}^{-t\{H(\vec{z}),\cdot\}} \vec{z} \approx \sum_{i=1}^{N} \left(\frac{-t\{H(\vec{z}),\cdot\}}{i!}\right)^{i} \vec{z}$$
(10)

for some numerical  $\vec{z}$ 

 $\Rightarrow$  get  $\mathcal{M}$  as a power series expanded around  $\vec{z} = 0$ 

### Outlook

#### generate thick-lens based transfer map

- differentiable w.r.t. to multipole components
- enables application of gradient-based optimizers
- successfully implemented
- alternative to thin-lens tracking
  - avoid choice of split scheme
  - potentially more computationally efficient
    - one map per element vs many drifts / kicks

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