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Integral and tensor interfaces and their use on supercomputers

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Challenges of modern computing infrastructure

- heterogeneity
 - processing units (CPUs, Accelerators, GPUs, TPUs)
 - memory spaces (shared disks, RAM, CACHE L1/L2/L3)
 - connections (InfiniBand, ...) (speeds vary for memory spaces)
- \rightarrow compilation/optimization every time
 - task distribution
 - avoiding idle processing units
 - avoid communication bottlenecks
- \rightarrow optimized task management (static / on the fly)
 - portability (software/performance)
 - supercomputers have a limited lifetime (about 3 years)
 - software gets regularly updated
- \rightarrow use standards



4608 nodes 2 CPUs per node 6 NVIDIA VOLTA GPUs 500 GB RAM picture from https://commons.wikimedia.org/wiki/File:Summit_(supercomputer).jpg node design: https: //docs.olcf.ornl.gov/systems/summit_user_guide.html#summit-nodes

Table: Number of basis functions / orbitals for different systems

element	range	basis	nao	nocc	nvir	nvir ⁴
SF ₆	-5 100	DZ	204	24	126	2.5E+8
		ΤZ	346	24	229	2.8E+9
		QZ	600	24	386	2.2E+10
UF ₆	-5000 20	DZ	551	146	197	1.5E+9
La-Porphyrin	-5 10	DZ	1093	67	550	9.1E+10

memory:

- 1C, nonrel. : $9.1E+10(\text{orbitals})*8(\text{real, double prec.}) \rightarrow 733 \text{ GB}$
- 2C, relativistic : 1.5E+12(spinor)*16(complex, double prec.) \rightarrow 23425 GB
- problem dependent expansion:
 - augmentation
 - polarization
 - core correlation

- separate code that provides functionalities using an interface
- advantages
 - highly performant / optimized code due to focused development
 - compilation / optimization by staff at computing facilities
- disadvantages
 - less control about code
 - optimization for different requirements
- requirement
 - standardized interface (compatibility with different versions)
 - usage by several programs / large user base
 - ongoing development / support
- examples (widespread use)
 - BLAS (vector/ matrix operations)
 - LAPACK (linear algebra functionalities)
 - OpenMP/MKL (shared memory distributed computation)
 - MPI (distributed memory distributed computation)

Integrals

focus on GTOs, example for libraries:

Name	algorithm	parallelization	seperate	used by
libint	Head-Gordon–Pople		1/05	ORCA, MPQC, GAMESS,
IIDINU	(Obara-Saika)	SIND, OF LINNIF	yes	BAGEL, ORCA, CP2K, PSI4
libcint	Rys	OpenMP	yes	pySCF, Chronus Quantum
GBTOlib	numerical	MPI, OpenMP	yes	UKRmol+, RMT
InteRest	Obara–Saika	OpenMP	no	DIRAC, RESPECT
HERMIT	McMurchie-Davidson	MPI	no	DIRAC, DALTON
AOINTS	Head-Gordon–Pople	OpenMP	no	Q-Chem
ABACUS	McMurchie-Davidson	MPI	no	CFOUR, ACES III, DALTON
MOLECULE	McMurchie-Davidson		no	CFOUR, MOLCAS, MOLPRO
SEWARD	Obara-Saika		no	MOLCAS

codes with their own routines

- MRCC (Obara-Saika)
- NWChem (Obara-Saika-Tracy / McMurchie-Davidson)
- TeraChem (McMurchie-Davidson)

Slater orbitals \rightarrow numerical integration (ADF) plane waves - periodic codes \rightarrow k-space integration

Integral libraries - Interfaces

libint

```
call compute_eri_f(1, deriv_order, am1, c1, alpha1, A, &
am2, c2, alpha2, B, &
am3, c3, alpha3, C, &
am4, c4, alpha4, D, &
F, erieval)
```

libcint

cint2e_ip1_cart(buf2e, shls, atm, natm, bas, nbas, env, 0_8)

GBTOlib

```
call eri_shell (lena, xa, ya, za, anorms, la, aexps, acoefs, &
lenb, xb, yb, zb, bnorms, lb, bexps, bcoefs, &
lenc, xc, yc, zc, cnorms, lc, cexps, ccoefs, &
lend, xd, yd, zd, dnorms, ld, dexps, dcoefs,
two_el_column, sph_ints)
```

InteRest

```
call interest_eri('||||', fijk|, gout,&
|k, ek,xk, yk, zk, ck,&
||, e|,x|,y|,z|,c|,&
|i, ei,xi,yi,zi,ci,&
|j, ej,xj,yj,zj,cj)
```



name	dist. mem.	PU	cont.	decomp.	spez. type
Cyclops (CTF)	\checkmark	CPU, GPU	\checkmark	\checkmark	sparse
DISTAL (sp-)	\checkmark	CPU, GPU	\checkmark	x	sparse
ExaTensor	\checkmark	CPU, GPU	\checkmark	x	х
ExaTN	(√)	CPU, GPU	\checkmark	\checkmark	х
PyTorch	х	CPU, GPU	\checkmark	x	sparse
NumPy	х	CPU	\checkmark	x	х
TACO	х	CPU, GPU	\checkmark	x	sparse
TAL_SH	х	CPU, GPU	\checkmark	x	х
TensorFlow	\checkmark	CPU, GPU, TPU	\checkmark	x	sparse
TiledArray	\checkmark	CPU, GPU	 ✓ 	x	block sparse

(PU \ldots processing units), (cont. \ldots contraction), (decomp. \ldots decomposition) a larger list can be found on arxiv^1

Tensor libraries

¹C. Psarras, L. Karlsson, J. Li, P. Bientinesi; *The landscape of software for tensor computations*, https://doi.org/10.48550/arxiv.2103.13756

- currently there is a change from GPUs to Accelerators, some are developing for TPUs
 - \rightarrow heterogeneity will increase and requires adaptation of the codes
- tensor libraries are often designed for a specific purpose
 - \rightarrow other functionalities might be inefficient or missing
- task distribution and scheduling is part of the library, but they might become separated (e.g. StarPU, PaRSEC)
- parallelism strategy: data / task / mixed based parallelism (splitting in domains)
- synchronous and asynchronous communication: polling/push communication, one-sided communication



ExaCorr Implementation

- a new Coupled Cluster implementation in DIRAC² using the ExaTensor tensor library³
- ExaTensor
 - tensor library that uses up to several 1000 nodes
 - tensors are distributed over several nodes
 - mainly focused on distributed contractions:



- node level parallelization by TALSH
- TALSH
 - single node version / part
 - enables the use of GPUs

²DIRAC, a relativistic ab initio electronic structure program, written by H. J. Aa. Jensen, R. Bast, A. S. P. Gomes, T. Saue and L. Visscher, see http://www.diracprogram.org
 ³Lyakh, D. I., Int. J. Quant. Chem., 2019, 119, e25926

3 levels of parallelization

- separate memory
 - MPI (MPICH, OpenMPI)
 - required data has to be sent to MPI process
 - parallelization different nodes
- shared memory
 - OpenMP, MKL
 - access the same memory
 - parallelization on a node
- GPUs
 - CUDA



Figure: ExaTensor structure^a

^aLyakh, D. I., Int. J. Quant. Chem., **2019**, 119, e25926

create tensor

```
ierr=exatns_tensor_create(tensor,"tensor_name",tensor_id,
tensor_root,EXA_DATA_KIND_C8)
```

initialize tensor

```
ierr=exatns_tensor_init(tensor,'ZERO')
```

contraction

```
ierr=exatns_tensor_contract(
"S(a,b,i,j)+=V(a,b,c,d)*T(c,d,i,j)",s2,vvvv,t2,scalar)
```

apply a method

ierr=exatns_tensor_transform(tensor,method)

extract results:

ierr=exatns_tensor_get_scalar(tensor,value)

• release memory

```
ierr=exatns_tensor_destroy(tensor)
```

Interface⁴ to ExaTensor



⁴J. V. Pototschnig, A. Papadopoulos, D. I. Lyakh, M. Repisky, L. Halbert, A. S, P. Gomes, H. J. Aa Jensen, L. Visscher, *J. Chem. Theory Comput.*, **2021**, 17, 5509-5529, doi: 10.1021/acs.jctc.1c00260

Experiences - Implementation

- interface allows quick implementation (especially if efficiency optimizations are hidden)
- sometimes additional functionalities are required
 - \rightarrow cooperation with the developer
 - \rightarrow access to the source code
 - (e.g. update of orbital energies for denominator)
- newer code uses modern functionalities of compiler \rightarrow stability / testing of this functionality might be lacking (e.g. ExaTensor works with GNU 8, 11 and higher but not with 9 and 10)
- newer code uses modern functionalities of MPI
 - \rightarrow functionalities might not be available / tested

(e.g. routines for one-sided communication (MPI-3 standard) were not available on Fugaku)

ExaCorr - Scaling

- usable up to 2050 MPI processes
- small scaling example:

Table: Timings in seconds for CCSD computations for UF₆ with 146 occupied and 394 virtual spinors.

np	t,	t _{cc}	tΛ
32	621	5246	not finished
64	446	4521	not finished
128	462	4138	2712
256	369	3880	2531
512	459	3974	2561



Table: CCSD expectation value calculations for the uranyl tris-nitrate complex $([UO_2(NO_3)_3]^-)$ using the X2C atomic mean-field Hamiltonian

OCC.	vir.	np	cost	cost/np	walltime	T1	q_{zz}
dyall.v2z							
106	534	160	9.14E+14	1.00	3h34	0.0126	10.02
156	534	160	1.98E+15	2.17	5h33	0.0103	9.70
156	818	360	1.09E+16	5.30	11h21	0.0102	8.48
202	534	400	3.32E+15	1.45	8h02	0.0091	9.73
202	680	2050	8.72E+15	0.75	12h28	0.0090	8.89
202	818	2050	1.83E+16	1.56	18h23	0.0089	8.59
202	896	2050	2.63E+16	2.25	23h04	0.0089	8.54
dyall.v3z							
106	694	480	2.61E+15	0.95	6h	0.0139	10.29
156	694	480	5.65E+15	2.06	10h24	0.0114	10.04
156	944	2050	1.93E+16	1.65	17h48	0.0104	9.99

 \rightarrow Problem: the number of nodes is determined by the memory demand

- high memory demand, supercomputers have relatively small memory per PU:
 - $\bullet~$ Summit: 2 CPUs + 6 GPUs + 512 GB RAM / node
 - Fugaku: 50 CPUs + 32 GB RAM / node
 - $\bullet~$ Lumi: 128 CPUs + 512 GB RAM / node
 - \rightarrow number of nodes was decided by memory demand
 - \rightarrow scaling hard to show as we cannot go to smaller node numbers
- optimization
 - size of tensor pieces
 - large packages more efficient, but less parallelization is possible
 - different contractions require different settings, e.g.: full vs. partial contraction square vs. rectangular contraction
 - \rightarrow size and distribution of tensor pieces / communication settings
- restrictions on supercomputers
 - \bullet time limits: supercomputers have rather strict wall time limits (4 24 h) \to required restart files for computations that need more time
 - only allow computations that use a large number of nodes \rightarrow scripting can be used to run computations in parallel

Molecular Tricks

- for larger system we are running out of steam
 - \rightarrow efficient libraries will not be sufficient
- methods used in molecular computations
 - symmetry

point groups, antisymmetry, ...

of course, it is extensively used for atoms

Iocalization

applid in:

- \rightarrow multilevel methods (e.g. QM-MM)
- \rightarrow linear scaling methods
- reducing basis / orbital spaces especially for correlated methods, via cutoffs / thresholds / localization
- ensor / matrix representation techniques

e.g. sparse tensors, ...

Optimization of strategies

energy threshold

Table: Ionization potential in eV of YbF for different numbers of correlated spinors employing the dyall.v2z basis set.

threshold _{low}	threshold _{high}	nocc	nvir	% occ	% vir	CCSD
-20	2.3	49	89	63	21	4.49
-20	6	49	137	63	32	5.89
-20	150	49	267	63	63	5.89
-20	10000	49	367	63	86	5.89
-3	40	31	213	40	50	5.95
-20	40	49	213	63	50	5.90
-60	40	61	213	78	50	5.90
-400	40	77	213	99	50	5.90
exp						$5.91{\pm}0.05^{5}$

natural orbitals⁶

select optimized orbitals to treat correlation

⁵Kaledin, L. A.; Heaven, M. C.; Field, R. W., J. Mol. Spectrosc., 1999,193, 285–292
 ⁶X. Yuan, L. Visscher, A. S. P. Gomes; J. Chem. Phys., 2022,156, 224108

- tensors in 2 dimensions (matrices) have a unique representation by using SVD (singular value decomposition)
- for higher dimension it is not unique anymore
- take as an example the 4 dimensional two electron integrals (depictions ⁷
- tensor decomposition
 - computing the representation
 - example: Cholesky

⁷Benedikt, U.; Auer, H.; Espig, M.; Hackbusch, W.; Auer, A. A.; *Molecular Physics* **2013**, 111. 2398.

Table: Cholesky decomposition for H_2O in the QZ basis

δ	М	% AO	$\Delta E(H)$	t _{trans.}	t _{dec.}	Chol. %	$\frac{dec.}{trans.}$ %
1.0E-03	760	3.1	2.24E-06	865	27	57.7	3.1
1.0E-04	936	3.8	3.14E-08	1044	40	69.6	3.8
1.0E-05	1138	4.6	9.01E-09	1285	58	85.7	4.5
1.0E-06	1409	5.7	2.49E-09	1563	86	104.3	5.5
1.0E-07	1644	6.7	6.54E-10	1874	116	125.0	6.2
1.0E-08	1903	7.7	7.52E-11	2167	154	144.6	7.1

- so far only used in the AO to MO transformation
- can be applied in SCF
- CCSD and EOM can be performed without ever constructing the 4-index quantities⁸

⁸Epifanovsky, E.; Zuev, D.; Feng, X. T.; Khistyaev, K.; Shao, Y. H.; Krylov, A. I. *J. Chem. Phys.*, **2013**, 139, 134105 challenges for supercomputers

- memory to CPU ratio
- allocation for shorter highly parallel computations
- software availability / compatibility

challenges for libraries

demand

integral and tensor libraries are mostly used by quantum chemists

interface

no standard defined

Conclusion

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Discussion Initializers

- standards for integral interface
- standards for tensors interface
- pitfalls of porting software
- strategies for memory reduction