

Improvement of the Implementation of the Riemann Tracking Algorithm

PANDA Meeting, GSI, March 2012

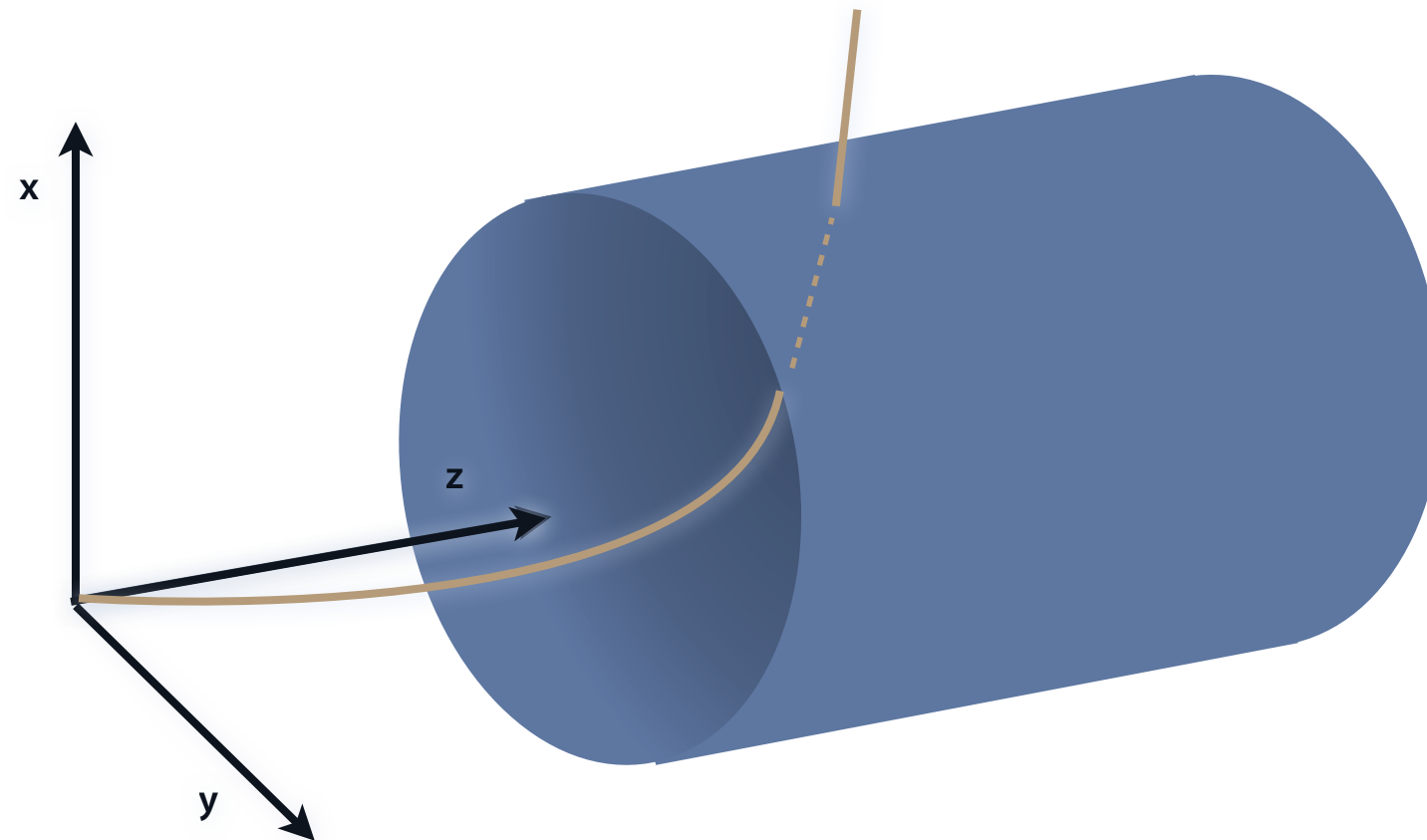
5 March 2012 | Andreas Herten

Outline

- Riemann Fit
 - Method
 - Implementation
- Improvement
- Done & To Be Done

- New method (~ 15 years old)
- Mainly by R. Frühwirth & A. Strandlie
- Non-iterative fitting by mapping data points onto a Riemann Sphere
 - Fast method

Riemann Fit: Method

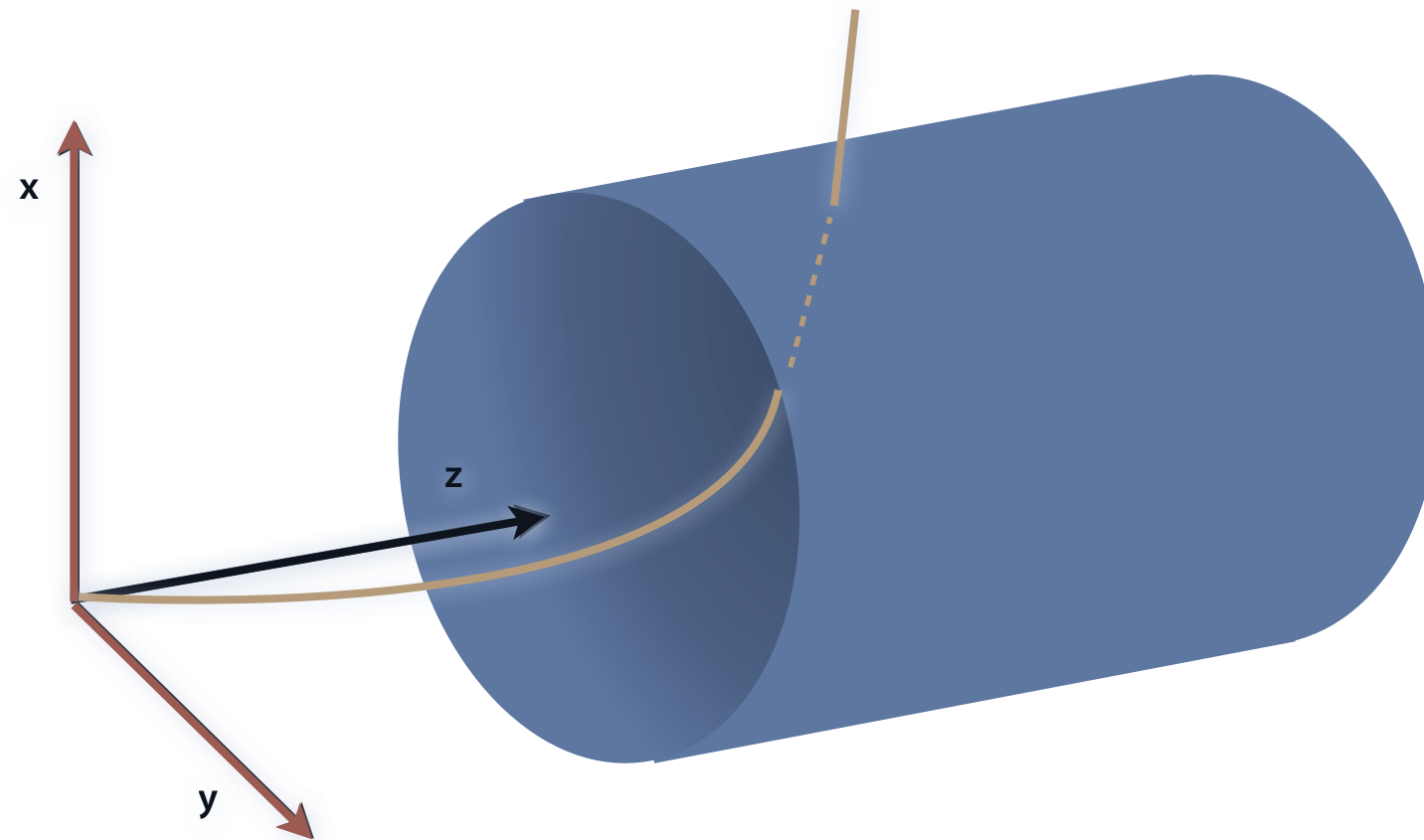


Barrel detector

3-d helix fit split up into two tasks:

- Circle $\rightarrow (x,y)$
- Linear $\rightarrow z$

Riemann Fit: Method

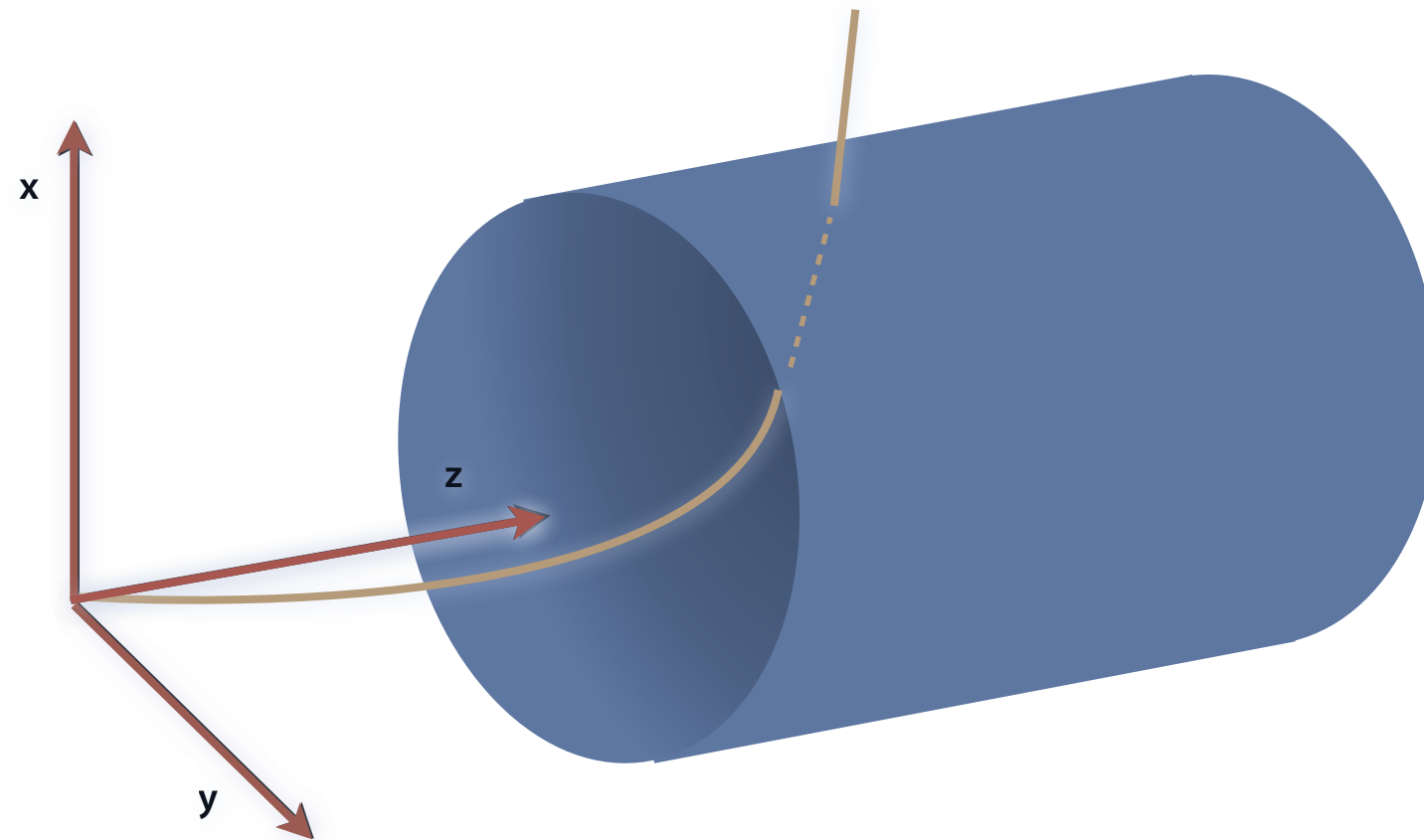


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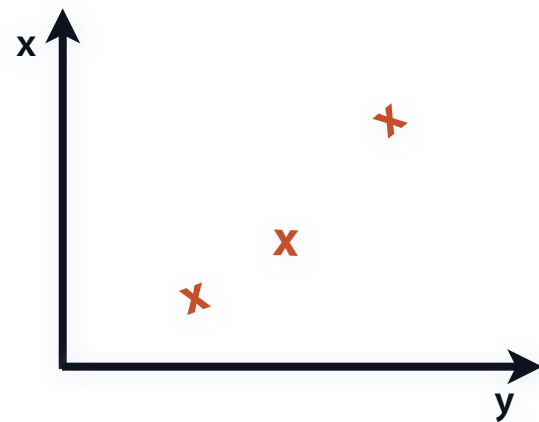


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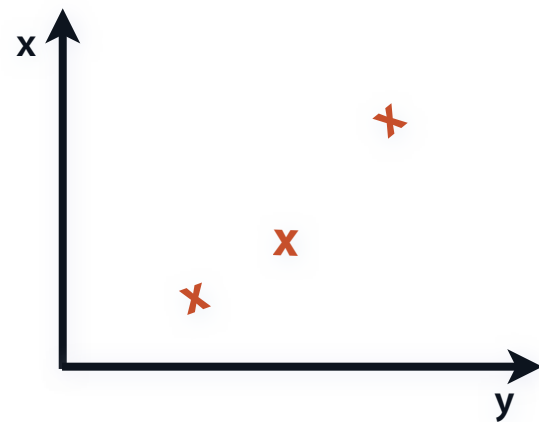
Riemann Fit: Method – (x,y)



I

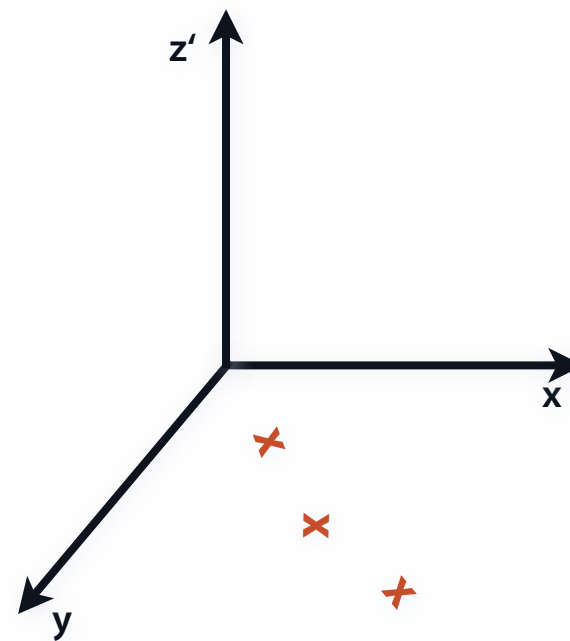
Hits in (x,y)

Riemann Fit: Method – (x,y)



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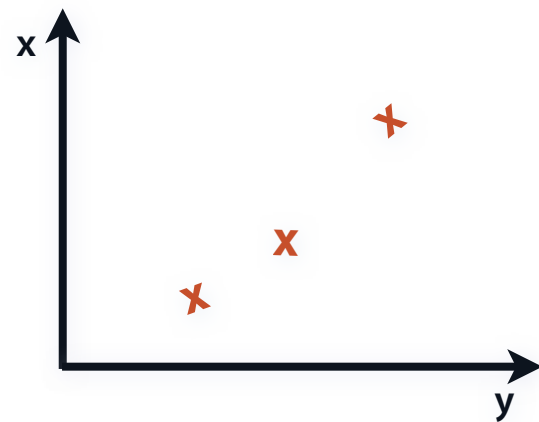
Hits in (x,y)



II

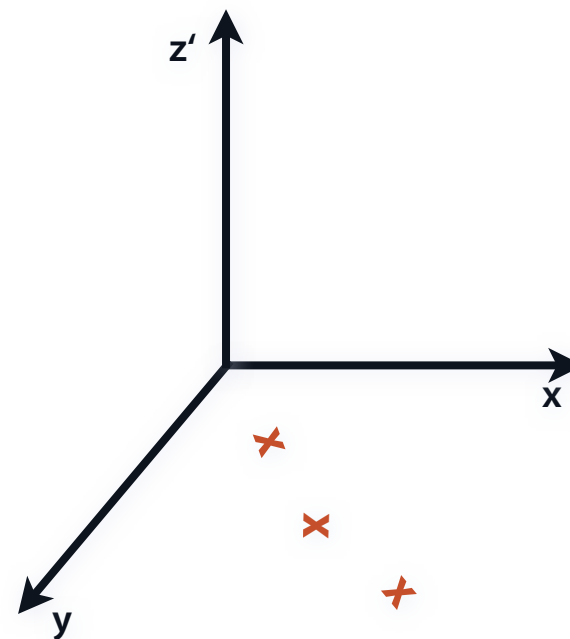
Expand to z'

Riemann Fit: Method – (x,y)



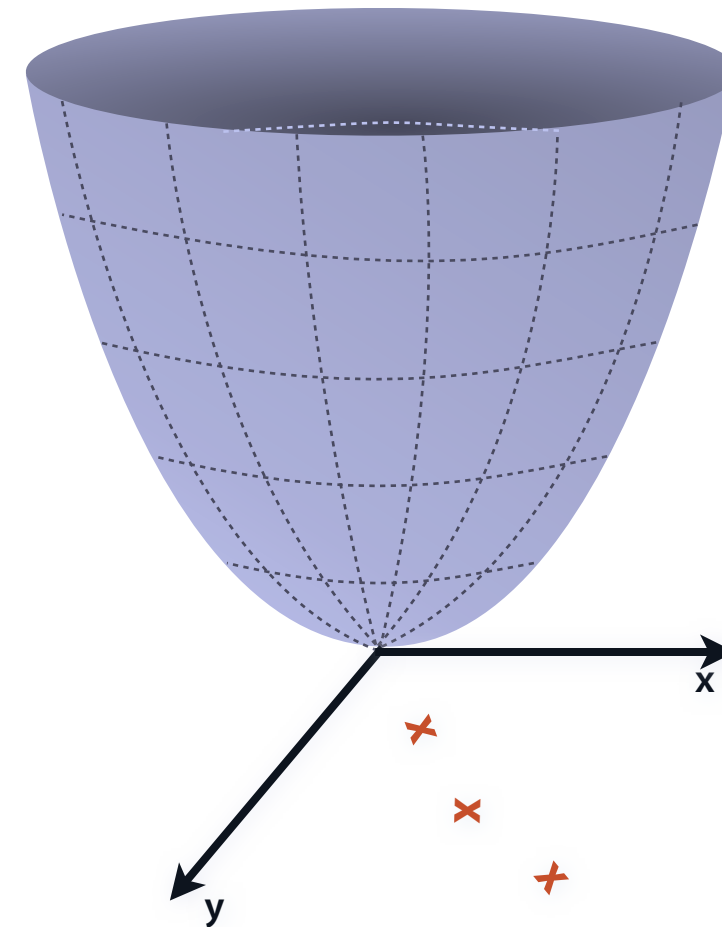
I

Hits in (x,y)



II

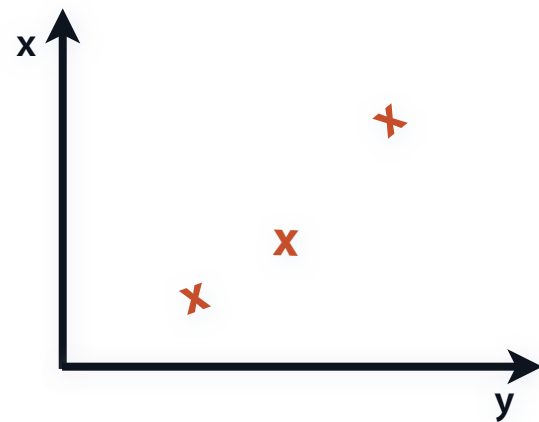
Expand to z'



III

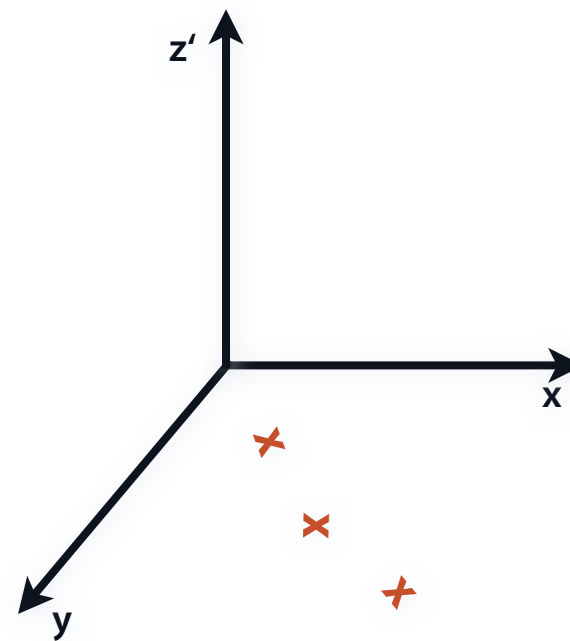
Riemann Surface
(paraboloid)

Riemann Fit: Method – (x,y)



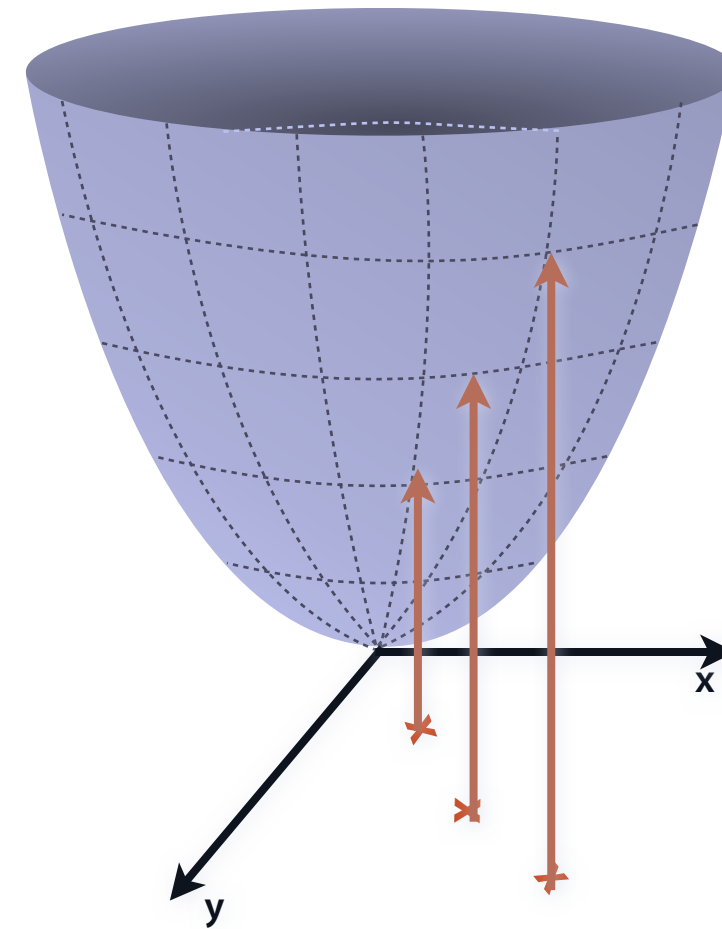
I

Hits in (x,y)



II

Expand to z'



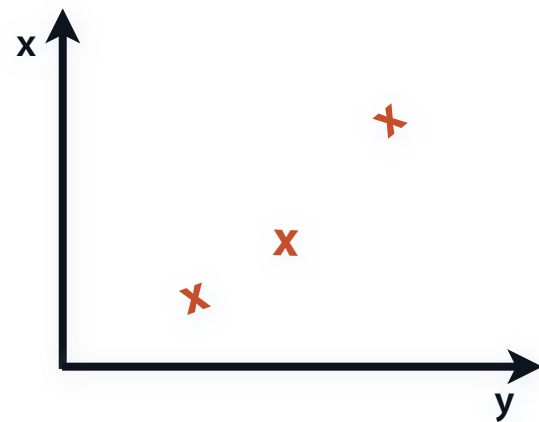
III

I

Riemann Surface
(paraboloid)

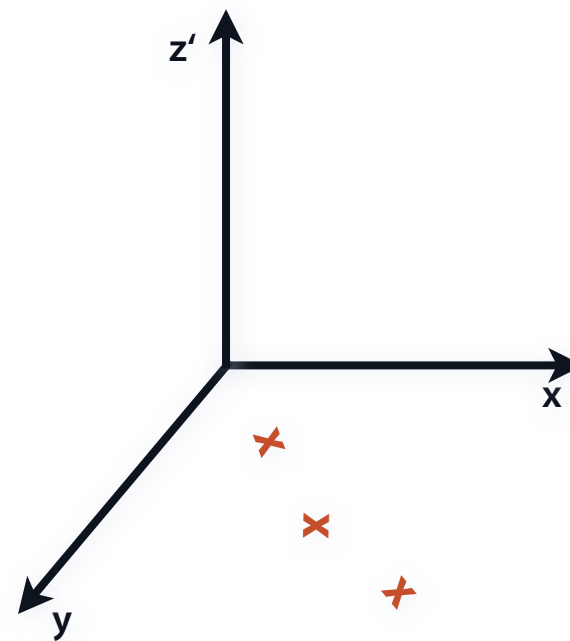
Map

Riemann Fit: Method – (x,y)



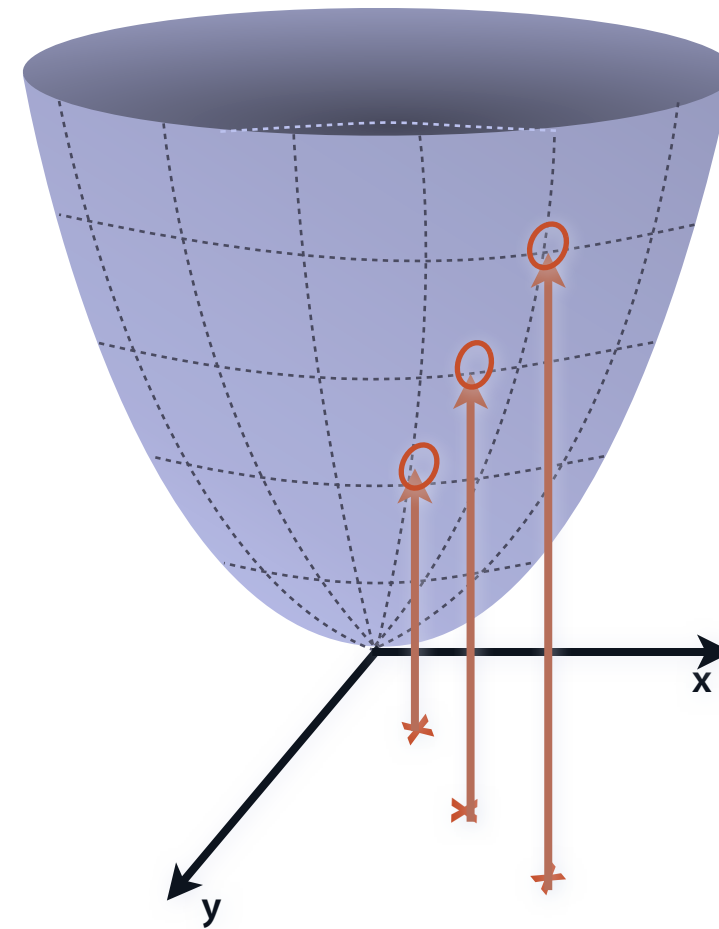
I

Hits in (x,y)



II

Expand to z'



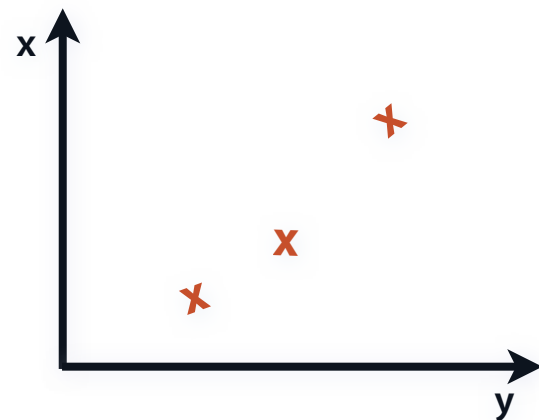
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Riemann Surface
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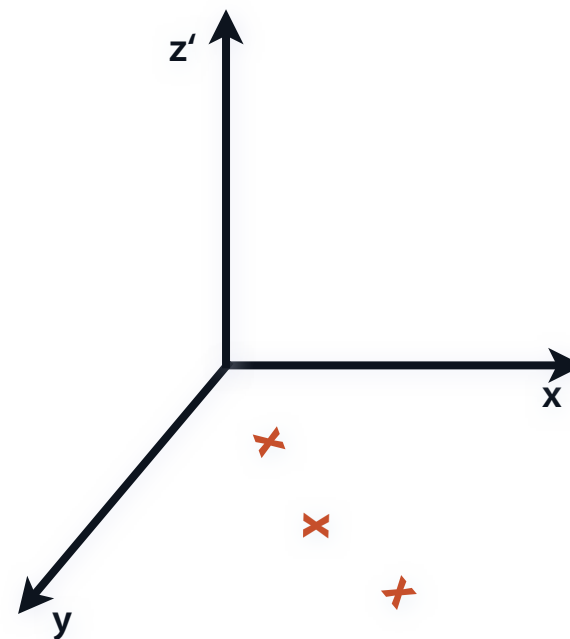
Map • Mark

Riemann Fit: Method – (x,y)



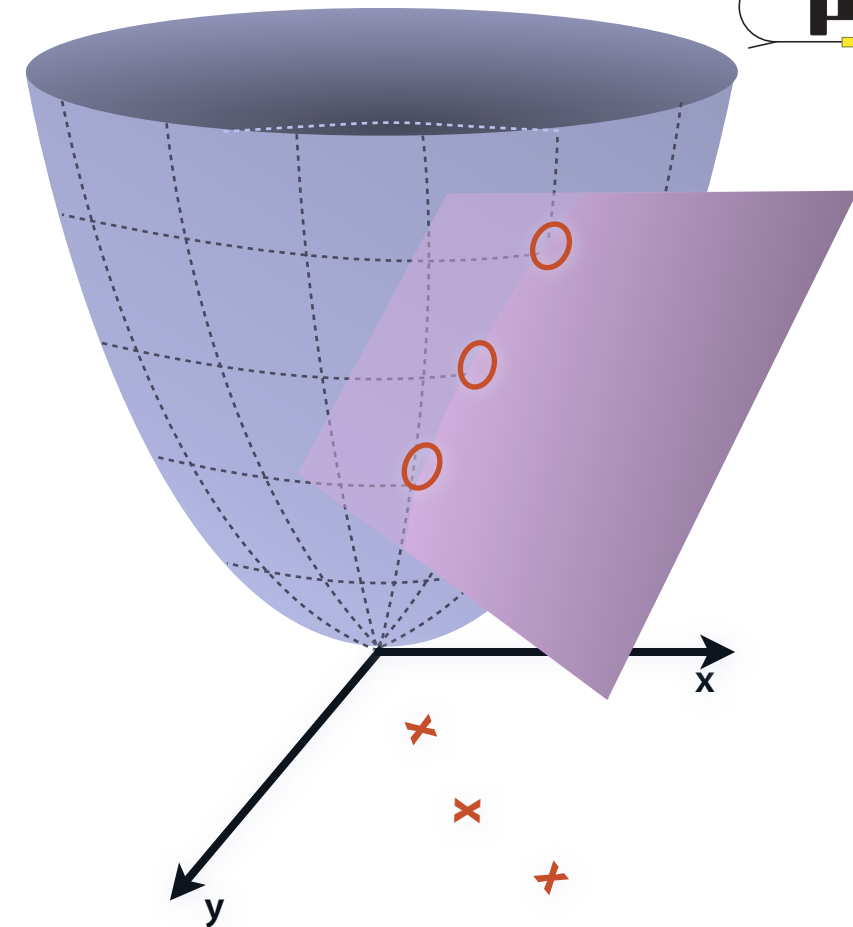
I

Hits in (x,y)



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Expand to z'



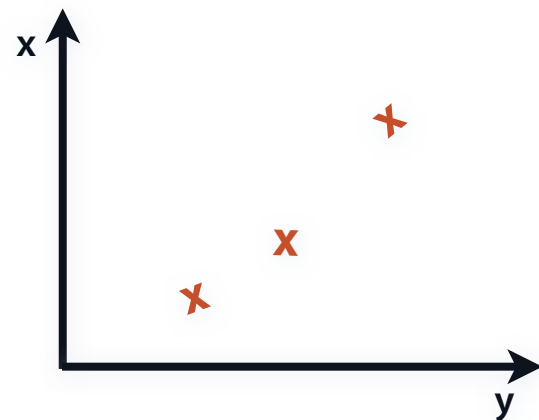
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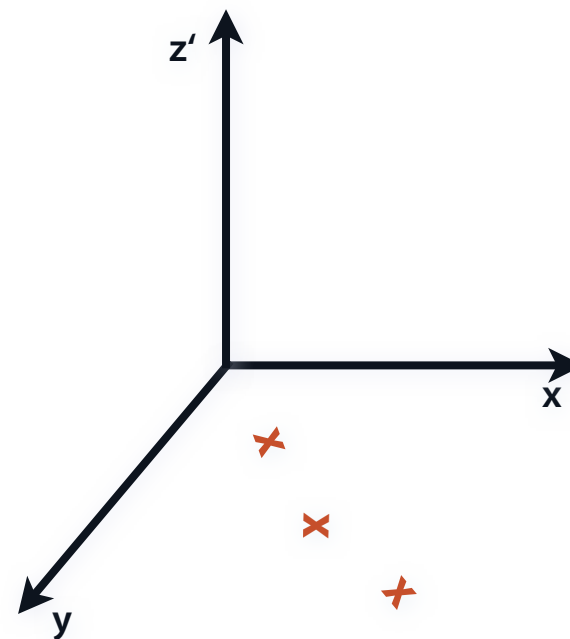
Map • Mark • Create plane

Riemann Fit: Method – (x,y)



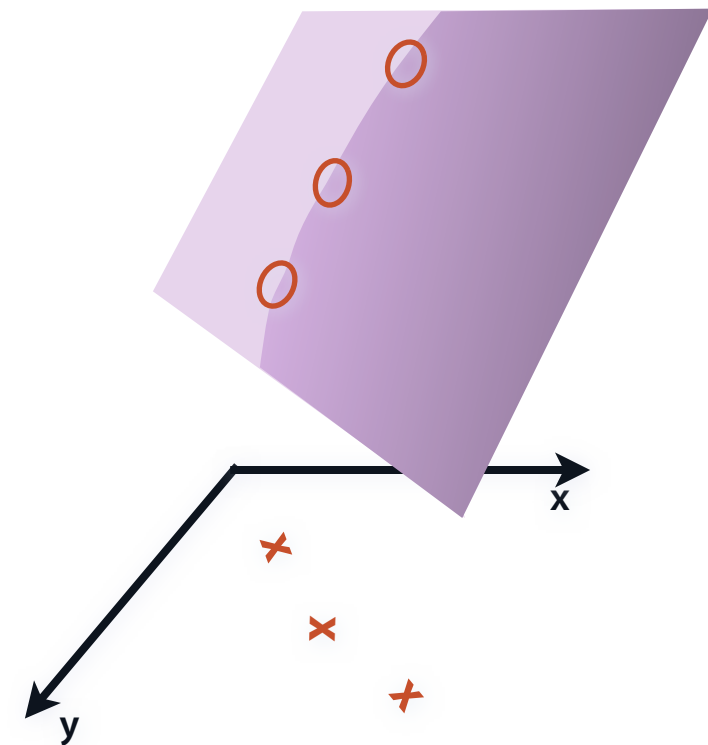
I

Hits in (x,y)



II

Expand to z'



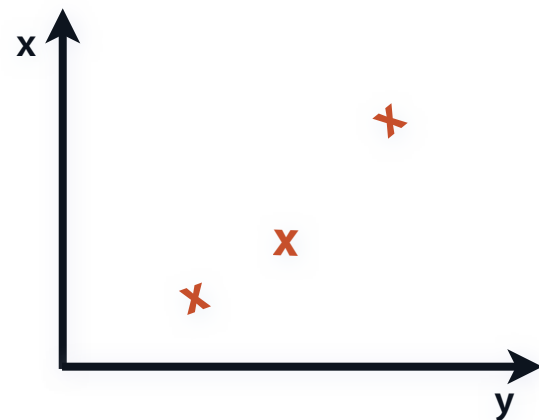
III

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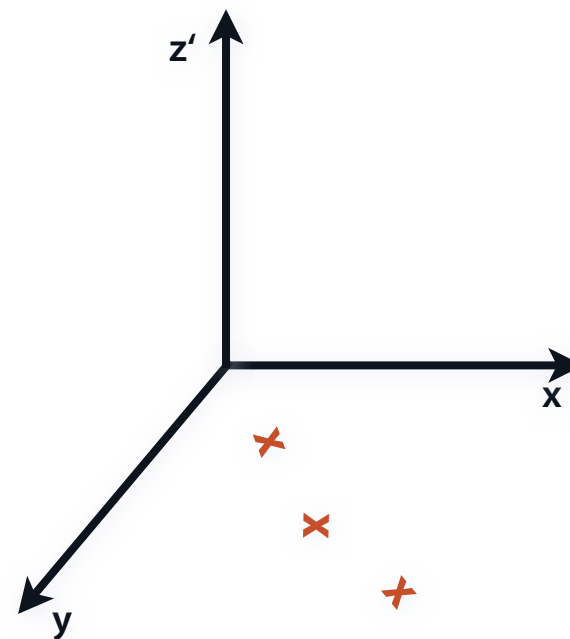
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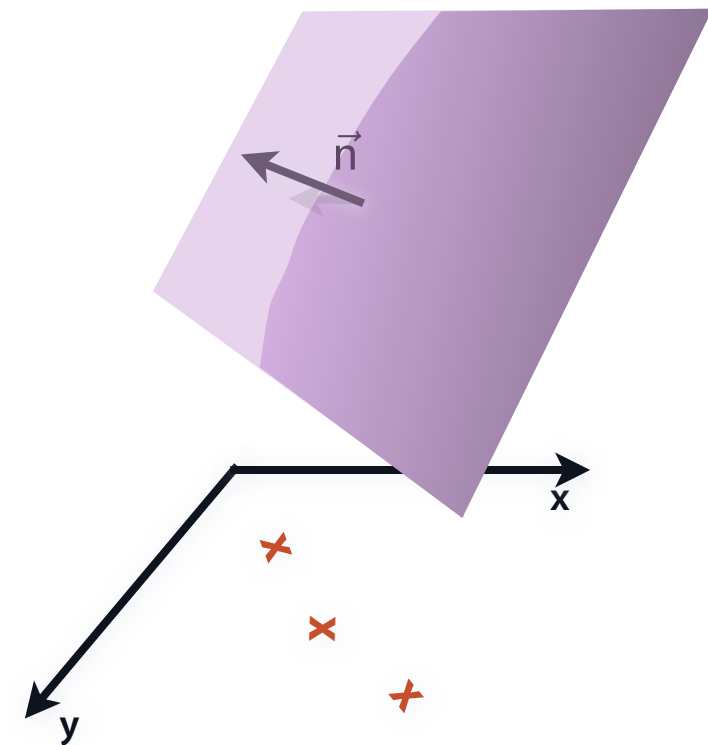
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Hits in (x,y)



II

Expand to z'



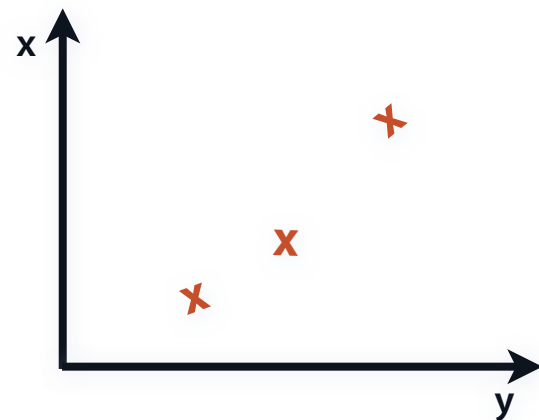
III

IV

Riemann Surface
(paraboloid)

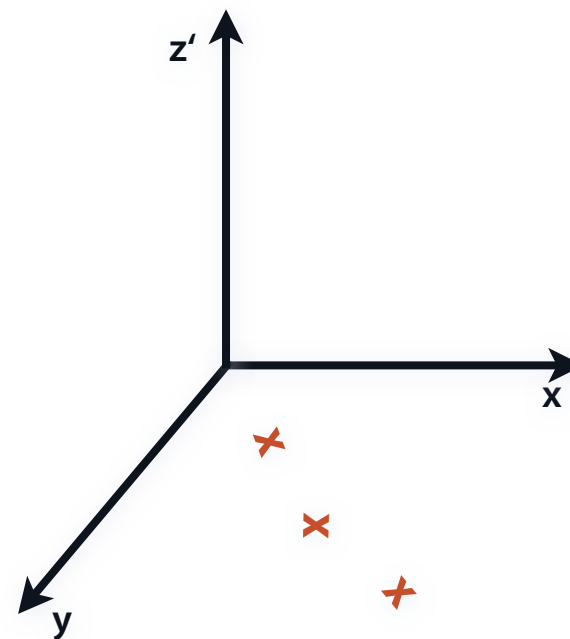
Map • Mark • Create plane • Normal vector

Riemann Fit: Method – (x,y)



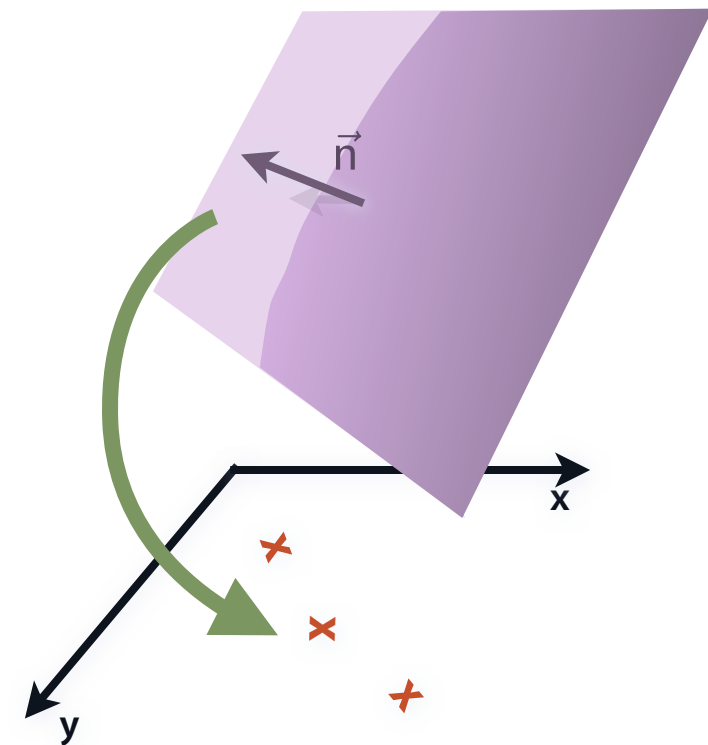
I

Hits in (x,y)



II

Expand to z'



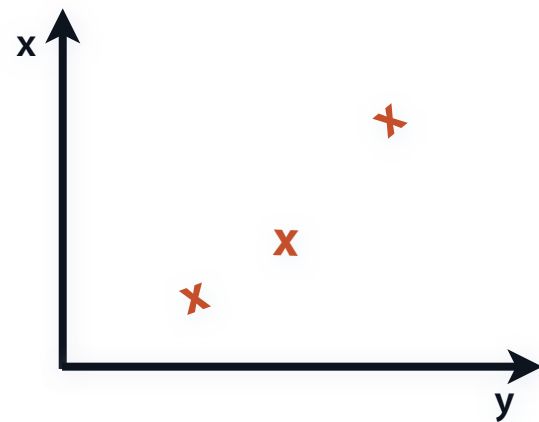
III

v

Riemann Surface
(paraboloid)

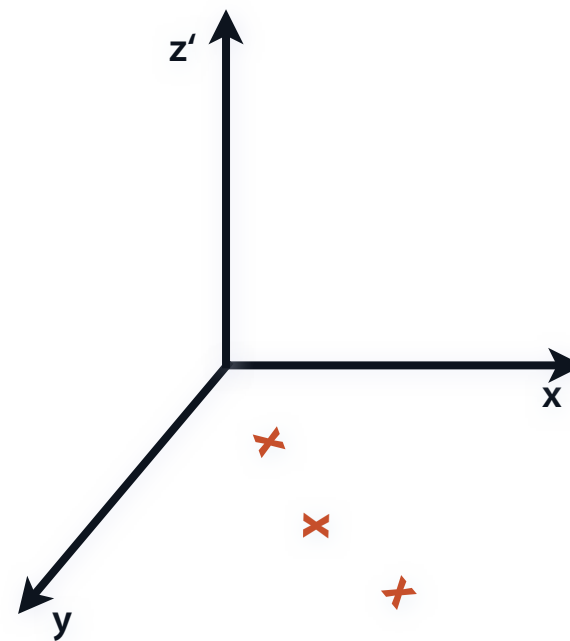
Map • Mark • Create plane • Normal vector
Map back

Riemann Fit: Method – (x,y)



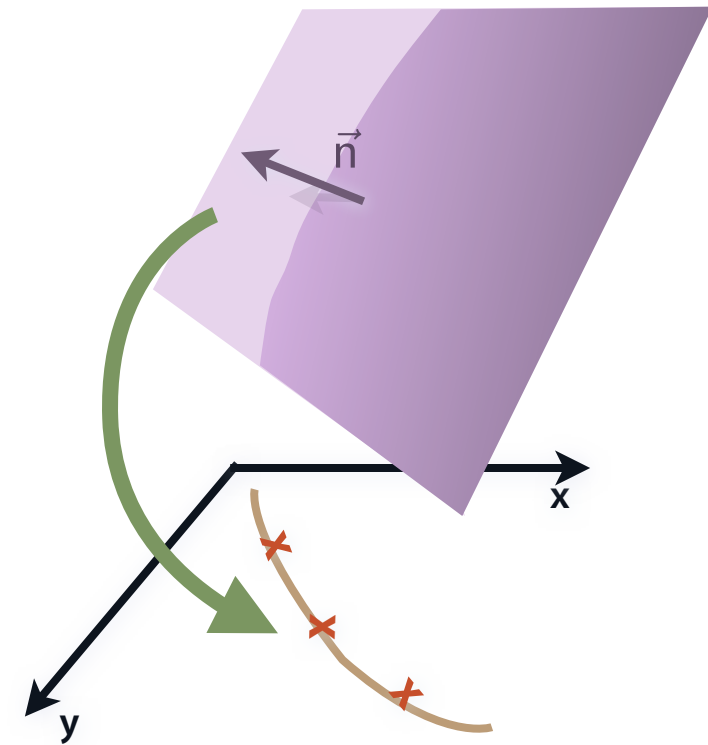
I

Hits in (x,y)



II

Expand to z'



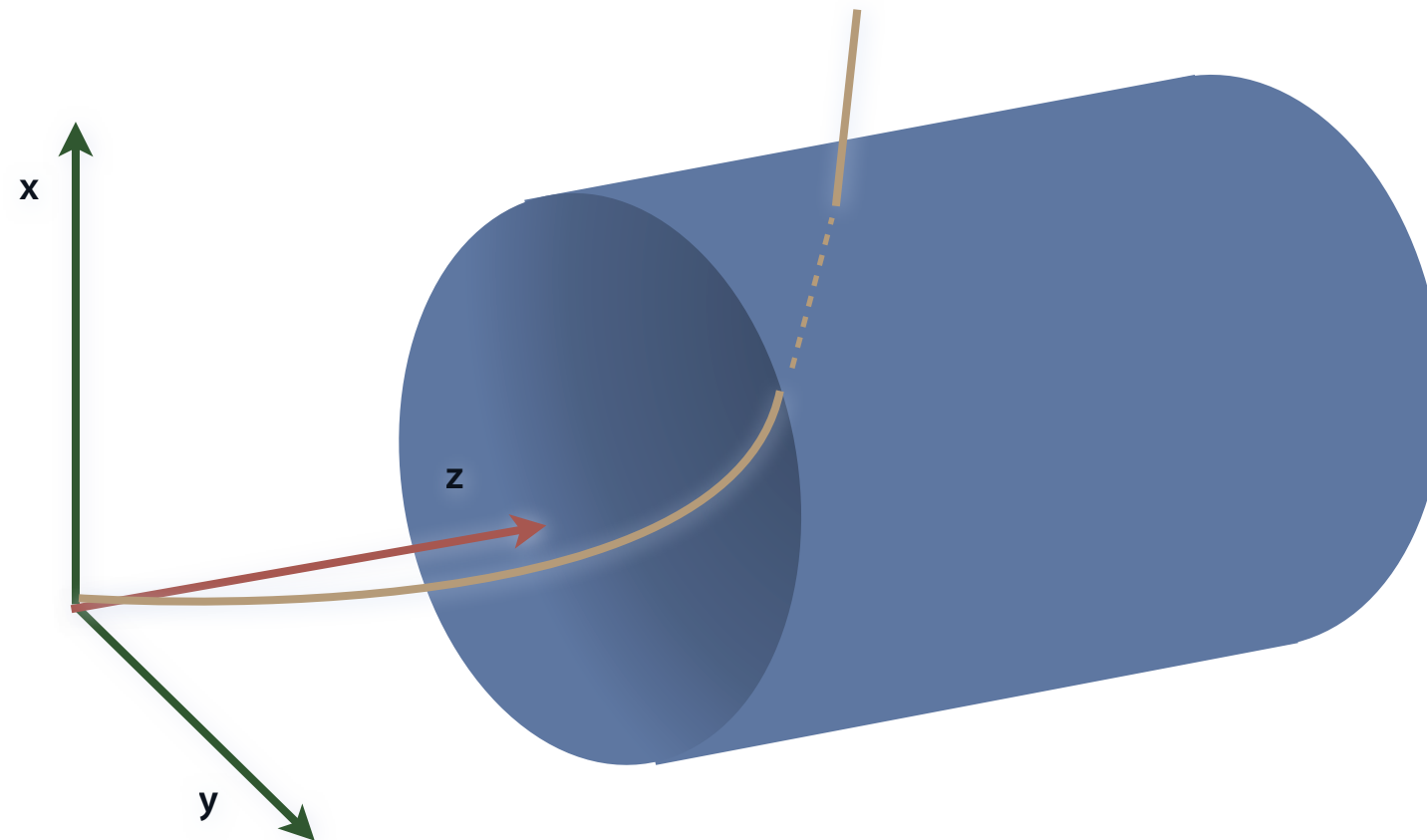
III

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Riemann Surface
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Map • Mark • Create plane • Normal vector
Map back

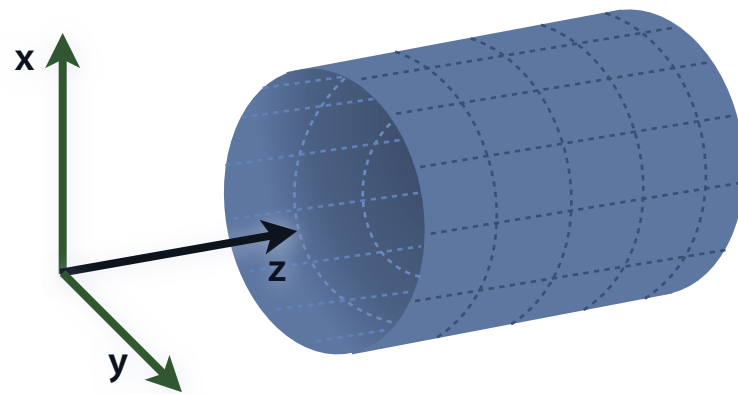
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3-d helix fit split up into two tasks:

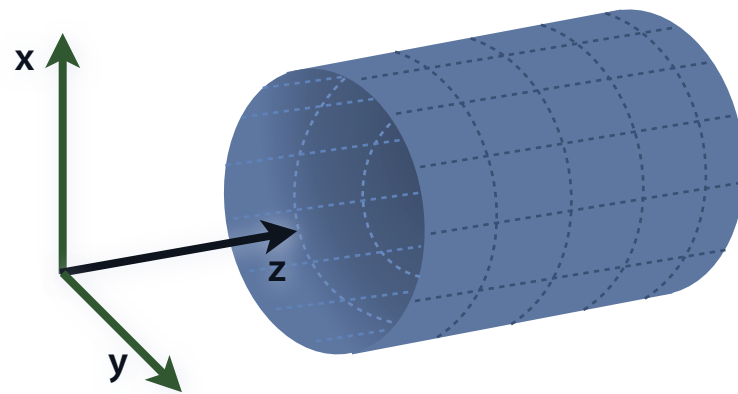
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Riemann Fit: Method – z



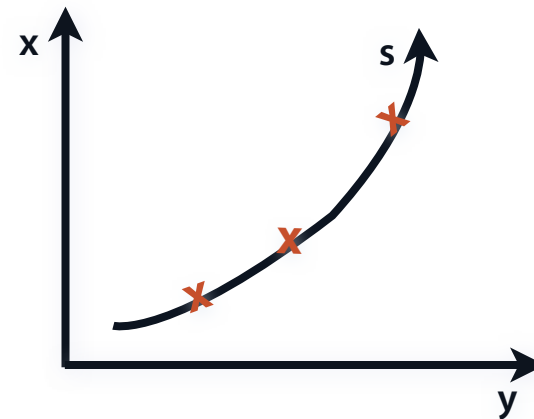
z position fixed

Riemann Fit: Method – z



I

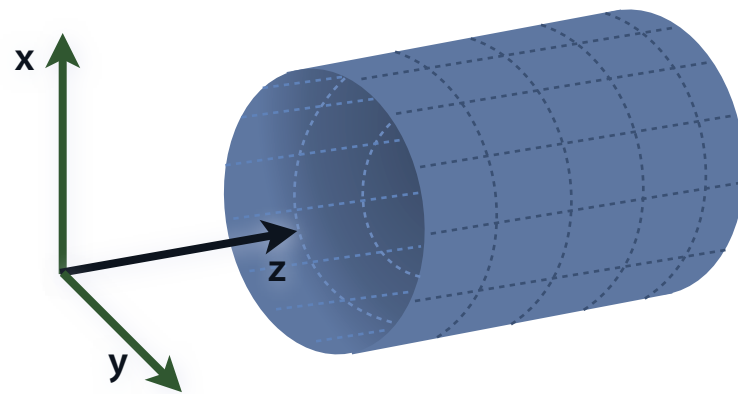
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II

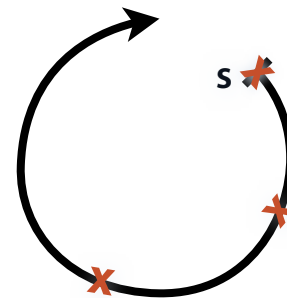
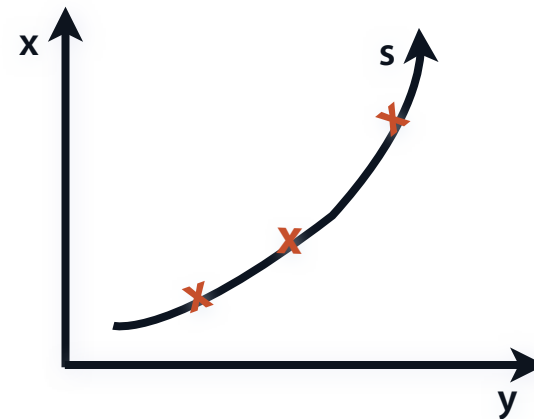
New value: s
Arc length on fitted circle
(from part 1)

Riemann Fit: Method – z



I

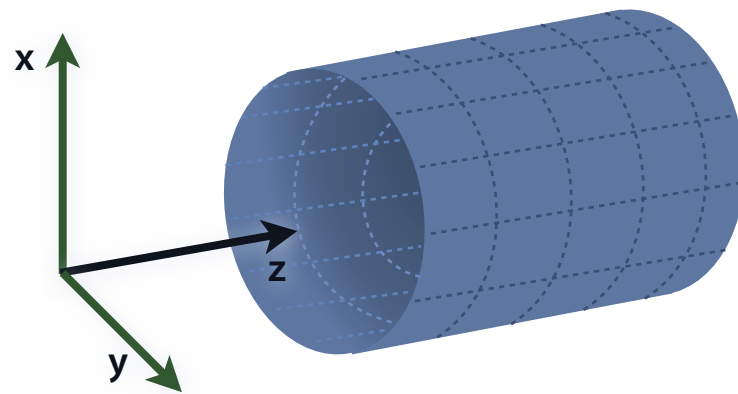
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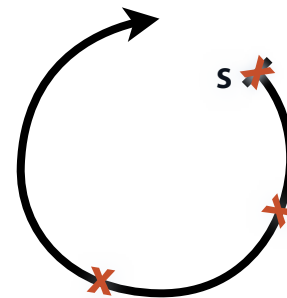
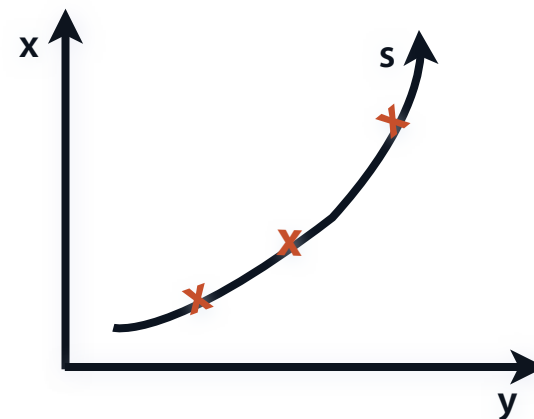
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Riemann Fit: Method – z



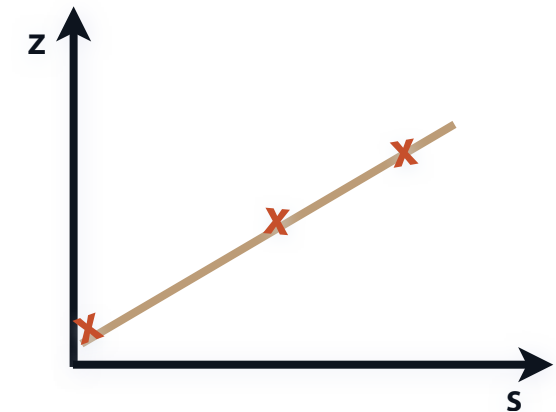
I

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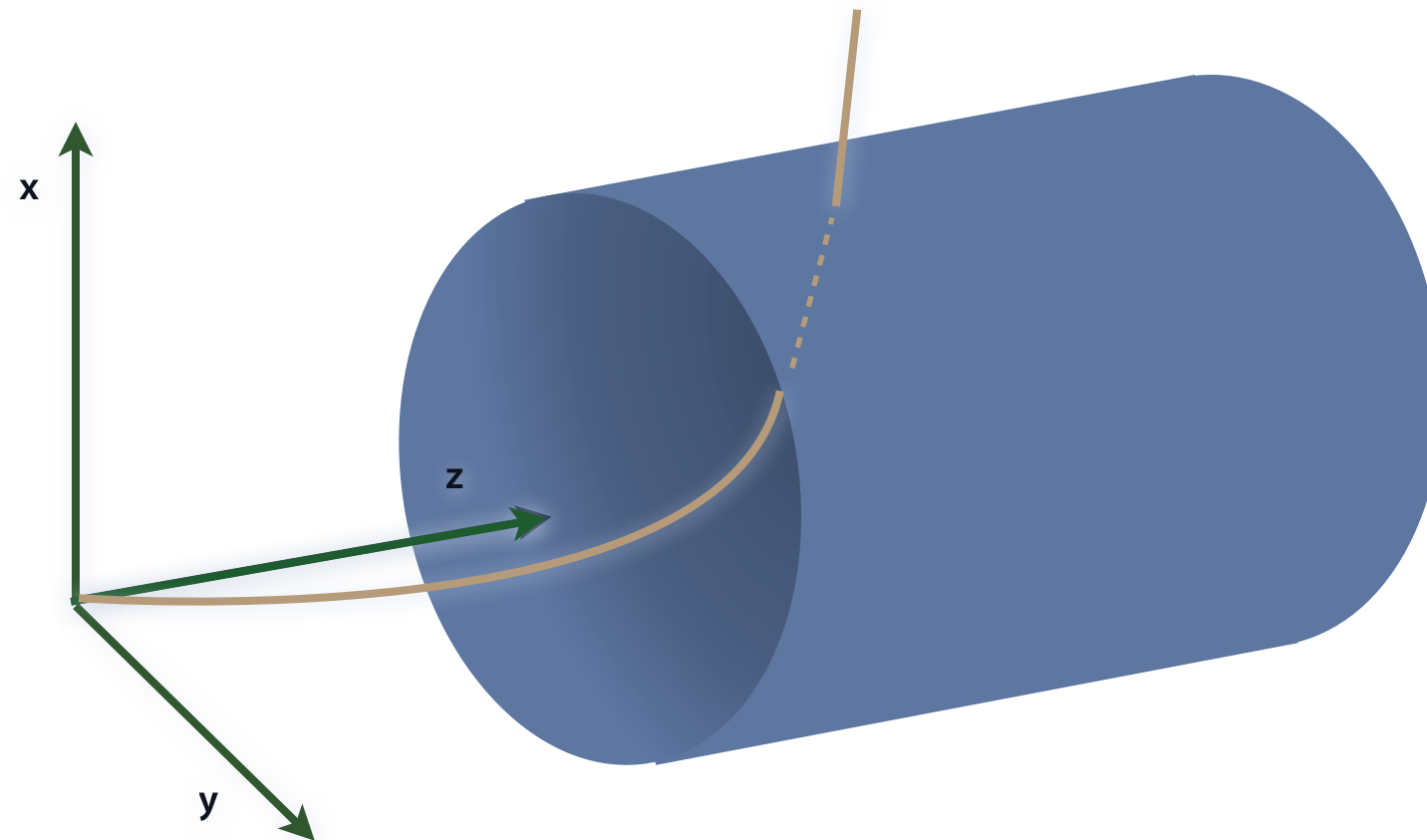
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III

Points in z vs s
Regression
Ideal helix = Hits on straight line

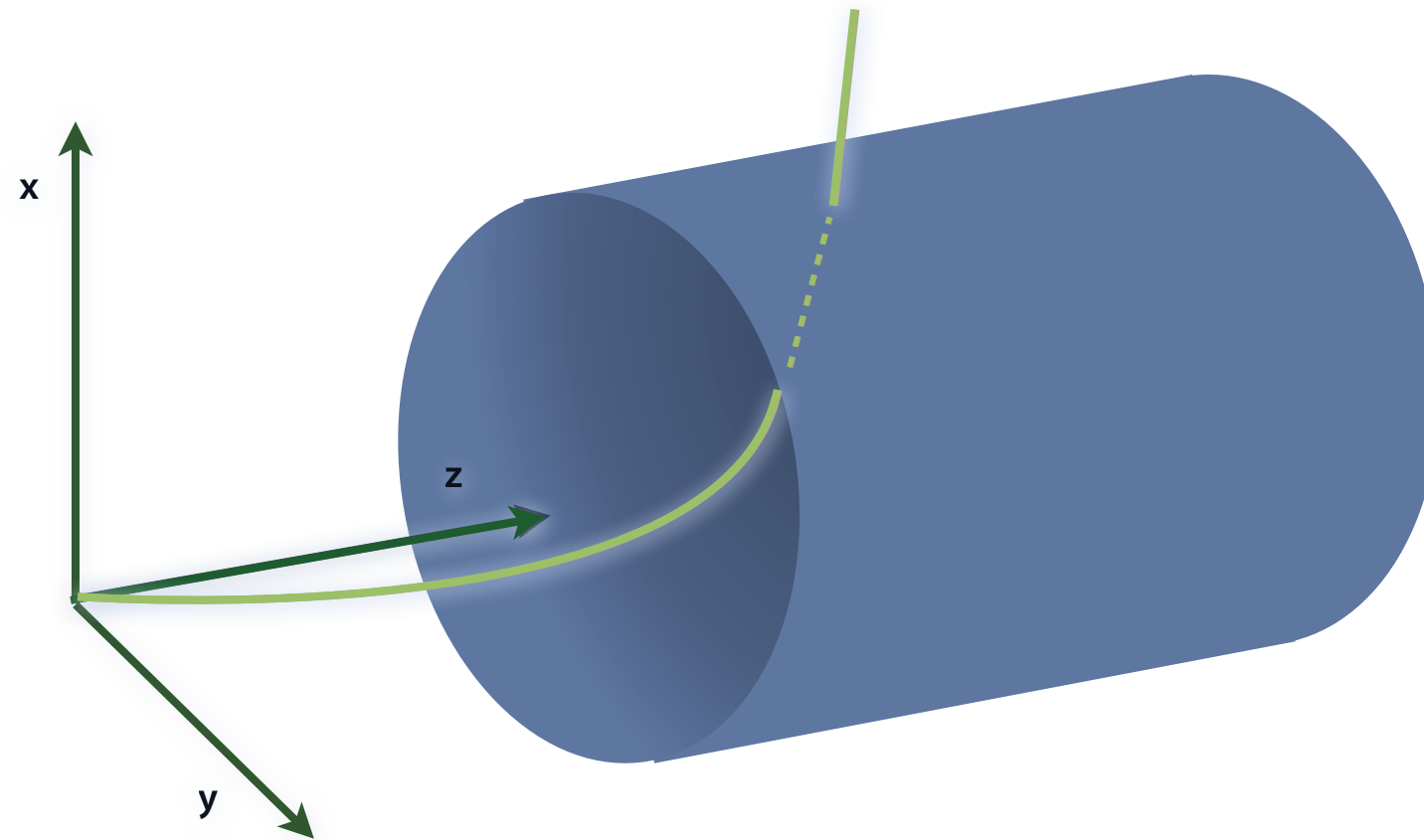
Riemann Fit: Method



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Riemann Fit: Method



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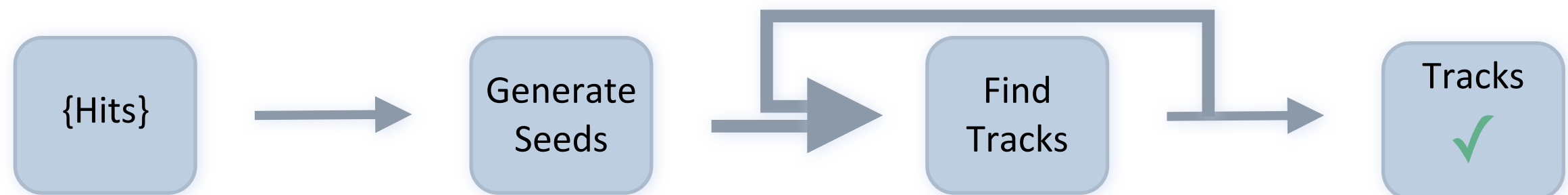
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Riemann Fit: Implementation

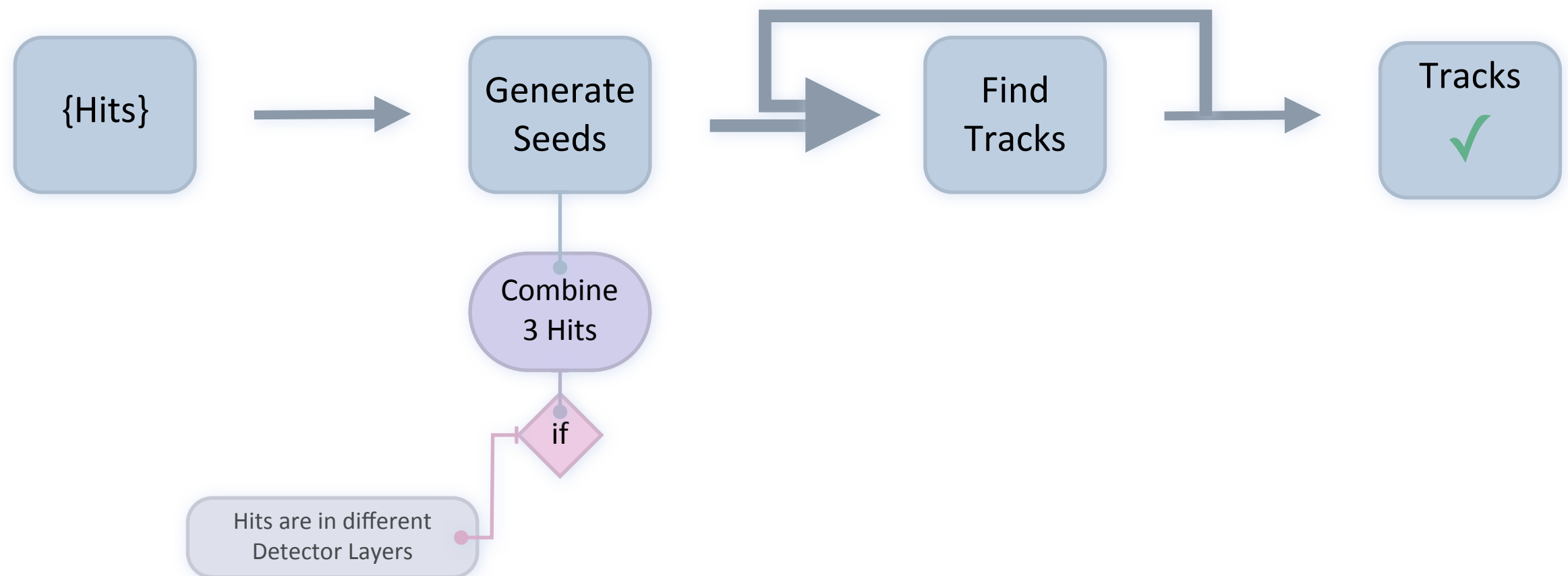
- Riemann Fit
 - Track finding & pre-fitting
 - Input parameter for Kalman Filter
 - More precise

Riemann Fit: Implementation

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- Riemann Fit

- Mitglied der Helmholtz-Gemeinschaft



Riemann Fit: Implementation

- Riemann Fit

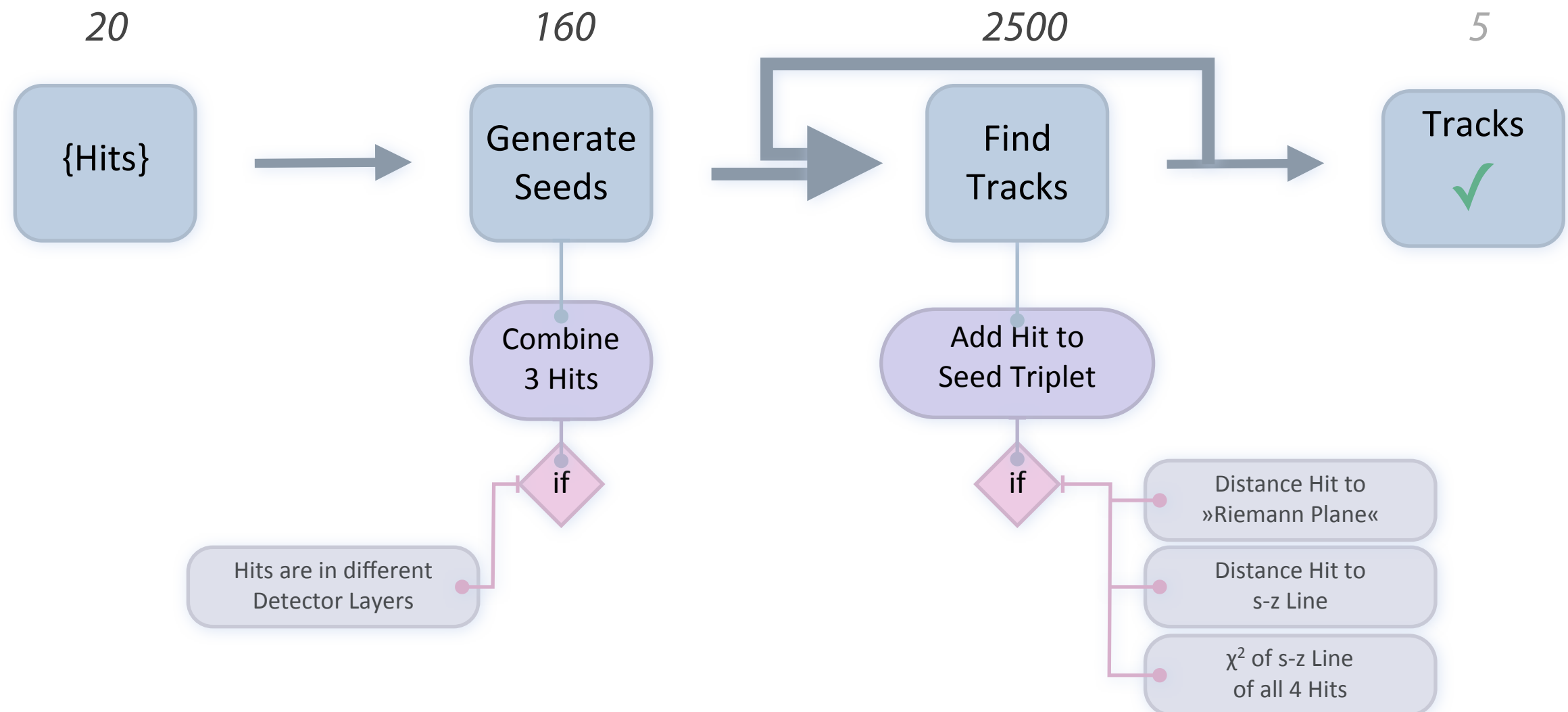
- Track finding & pre-fitting

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- More precise

Problem:

Many unrealistic combinations →
Many unnecessary computations



Riemann Fit: Implementation

- Riemann Fit

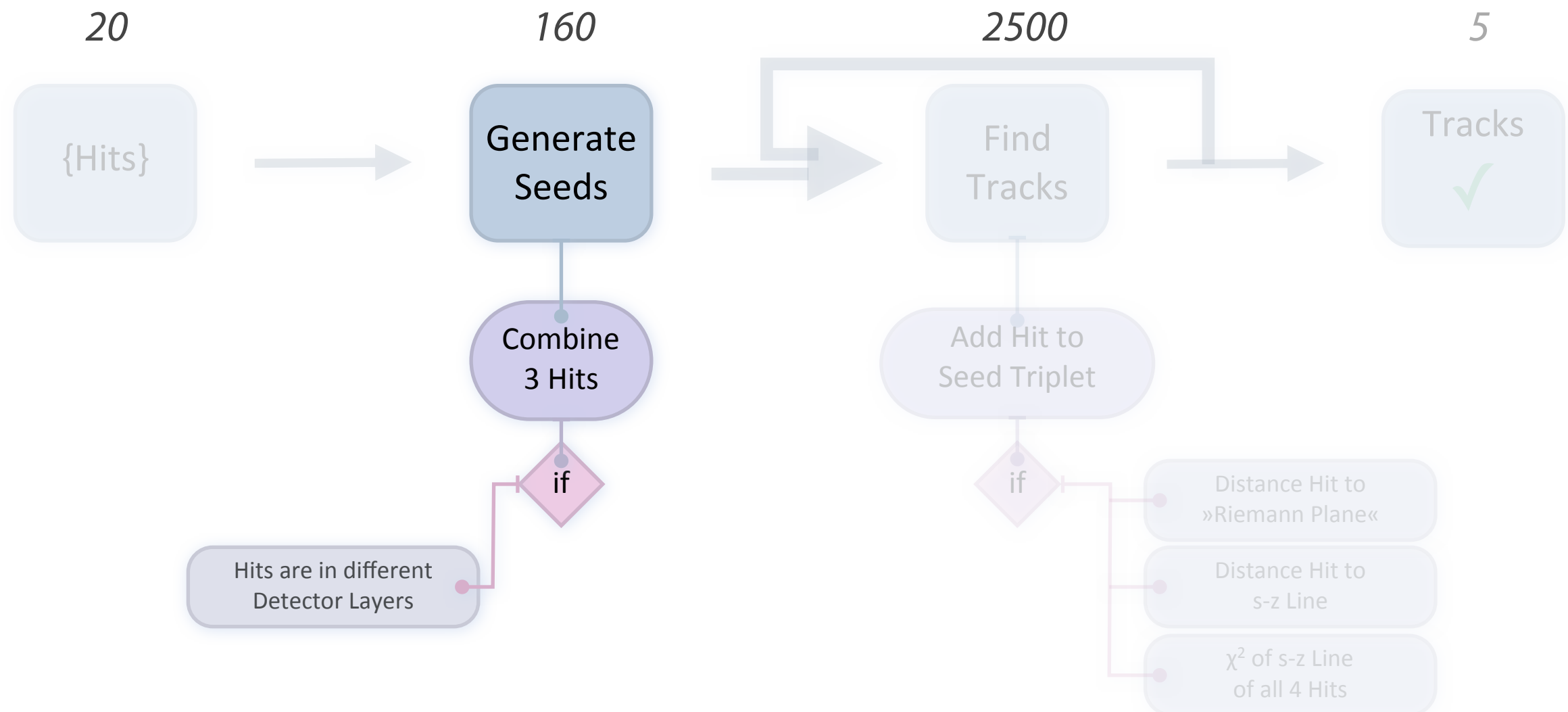
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Solution:

Add an *early* quality criterion



Riemann Fit: Implementation

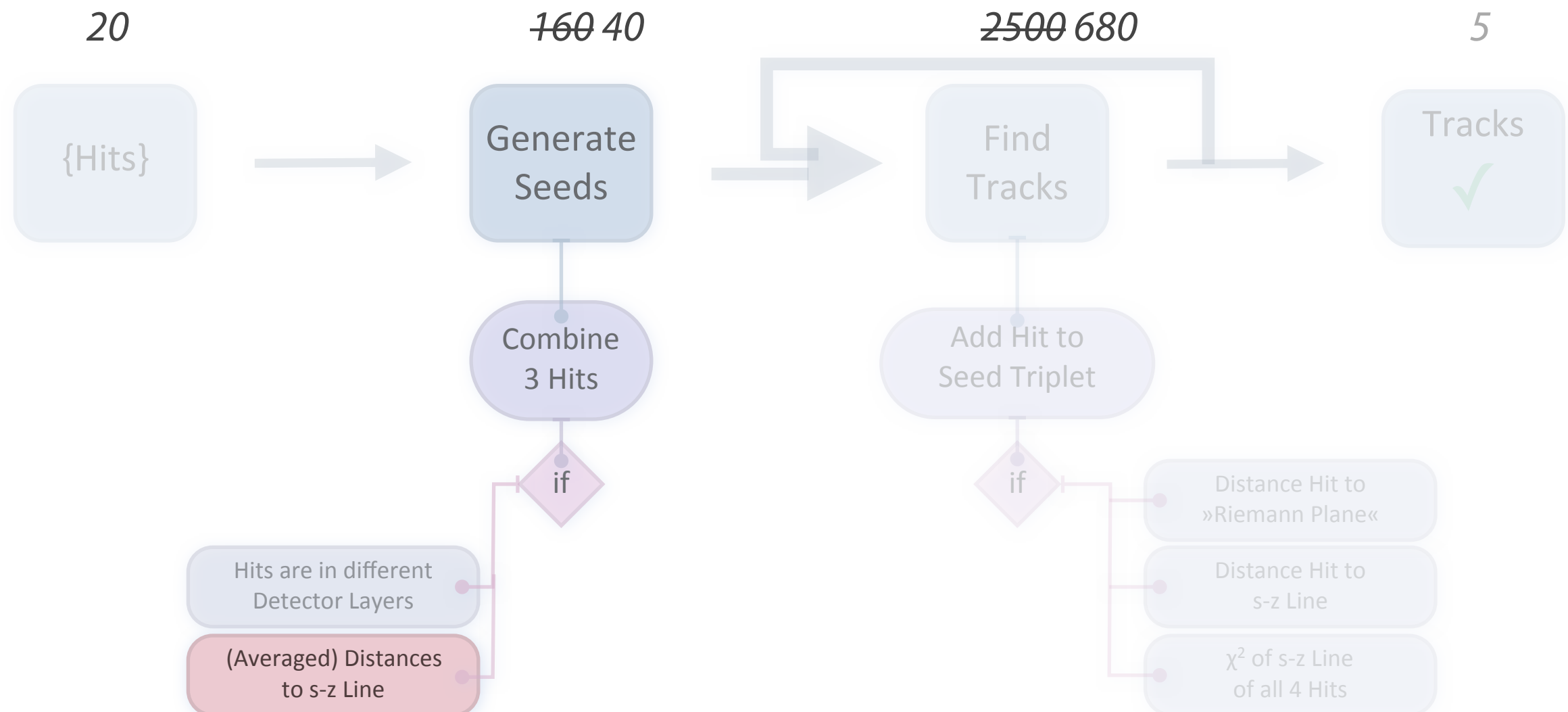
- Riemann Fit

- Track finding & pre-fitting

- Input parameters

- More precise

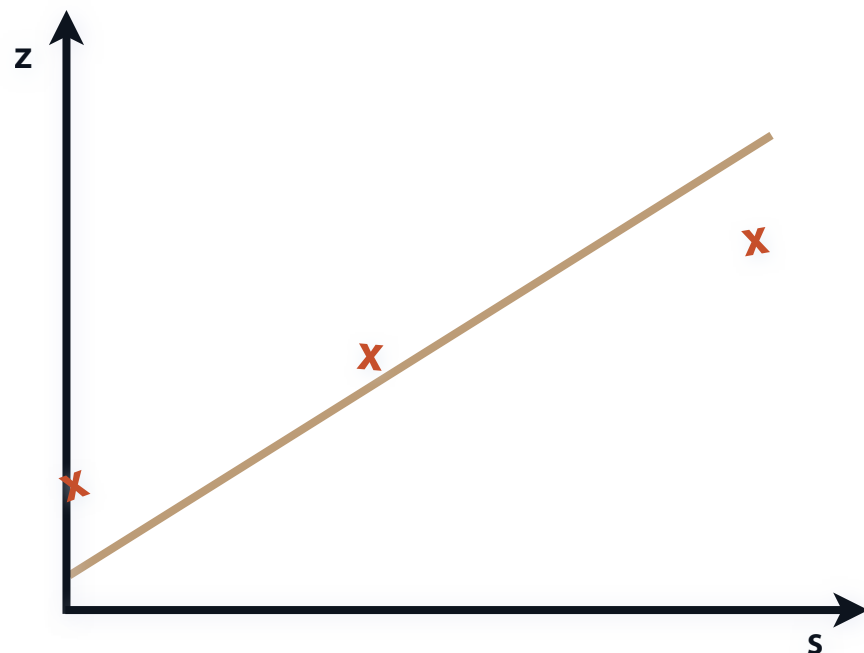
Solution:
Add an *early* quality criterion



- s-z Diagram
 - At triplet generation three points are used to create a circle
 - Helix information of s-z fit is *at this point* not really used for anything
 - Change that! Use s-z helix propagation as quality criterion!

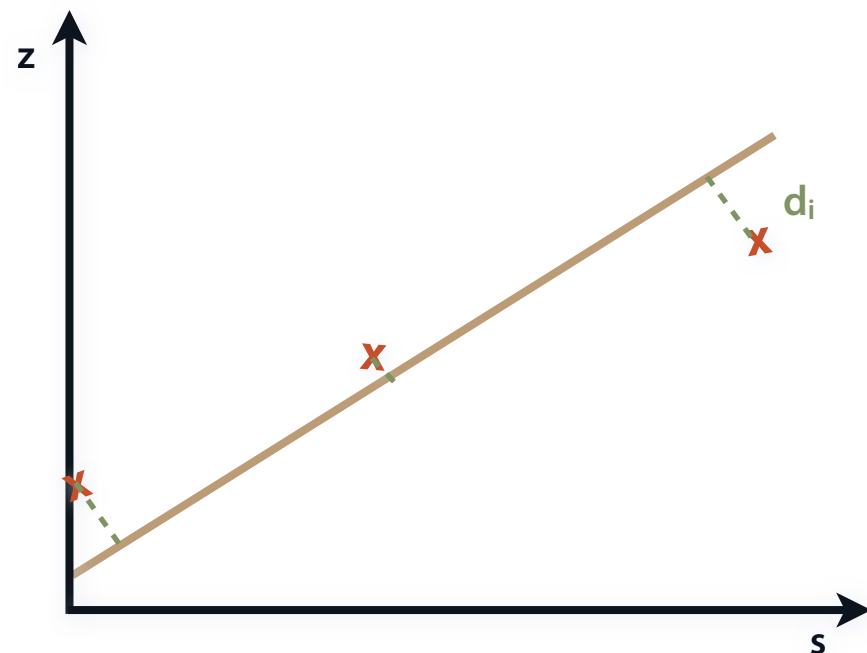
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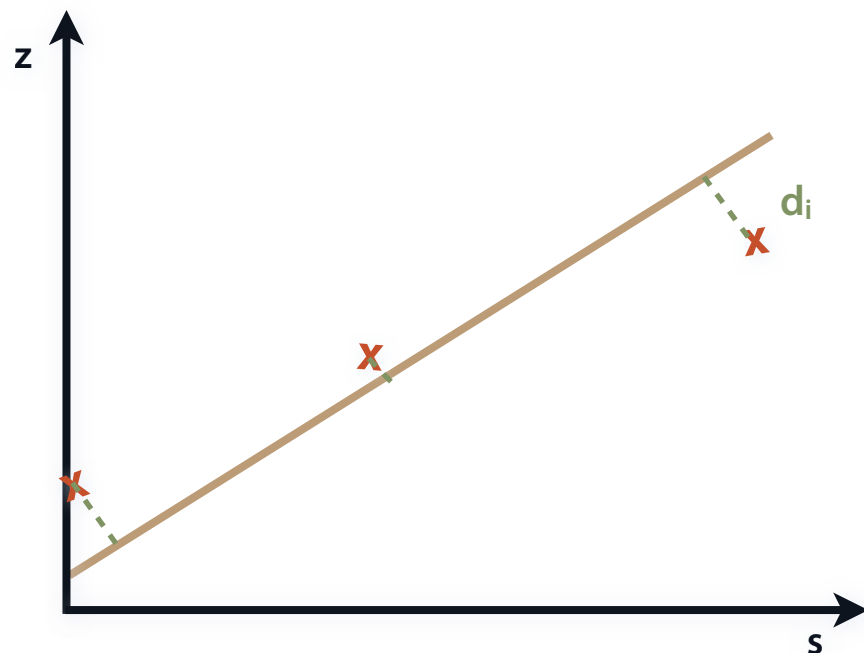
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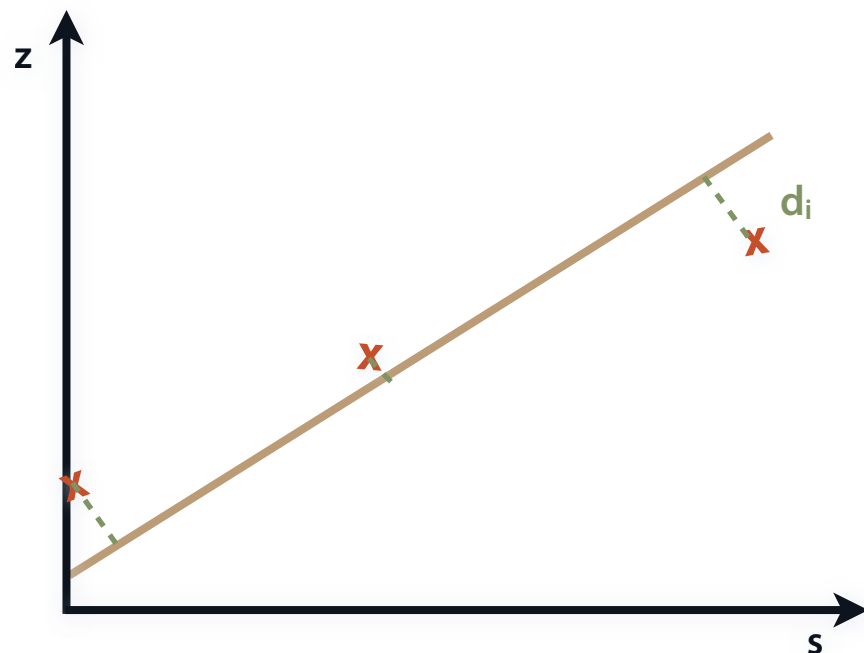
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$$\sqrt{\sum_{i=1}^3 d_i^2} =$$

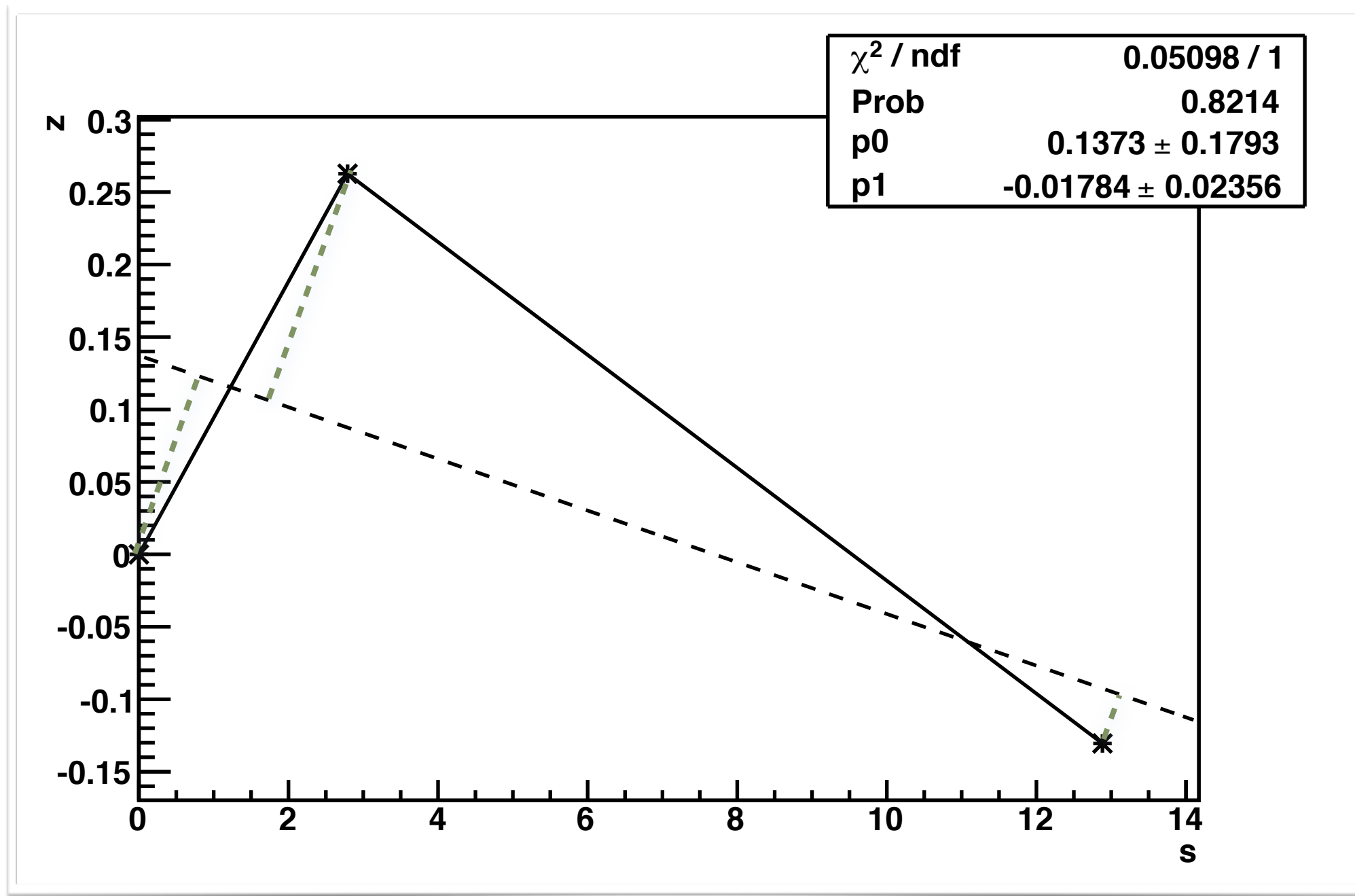
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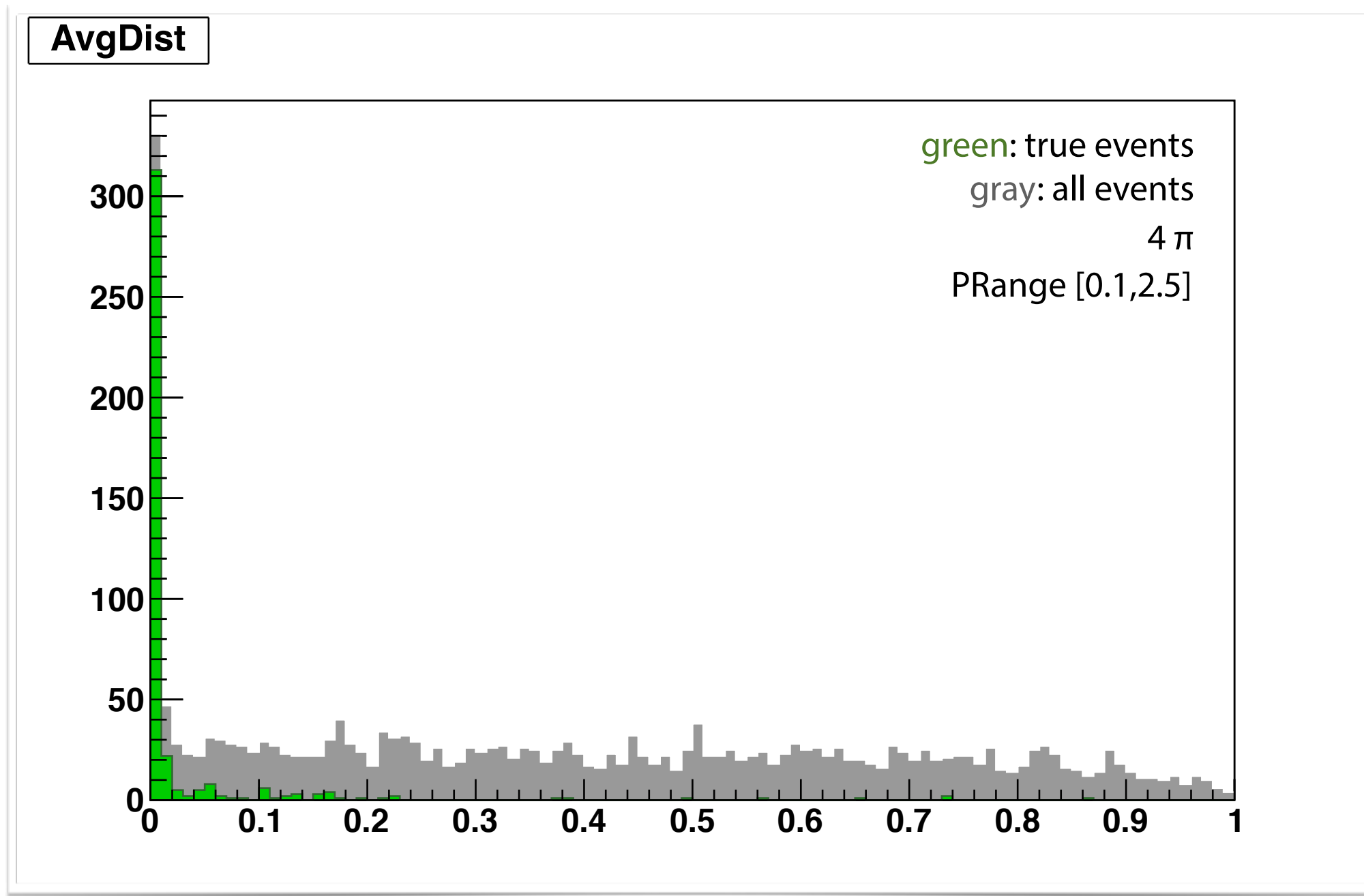


$$\sqrt{\sum_{i=1}^3 d_i^2} = \text{AvgDist}$$

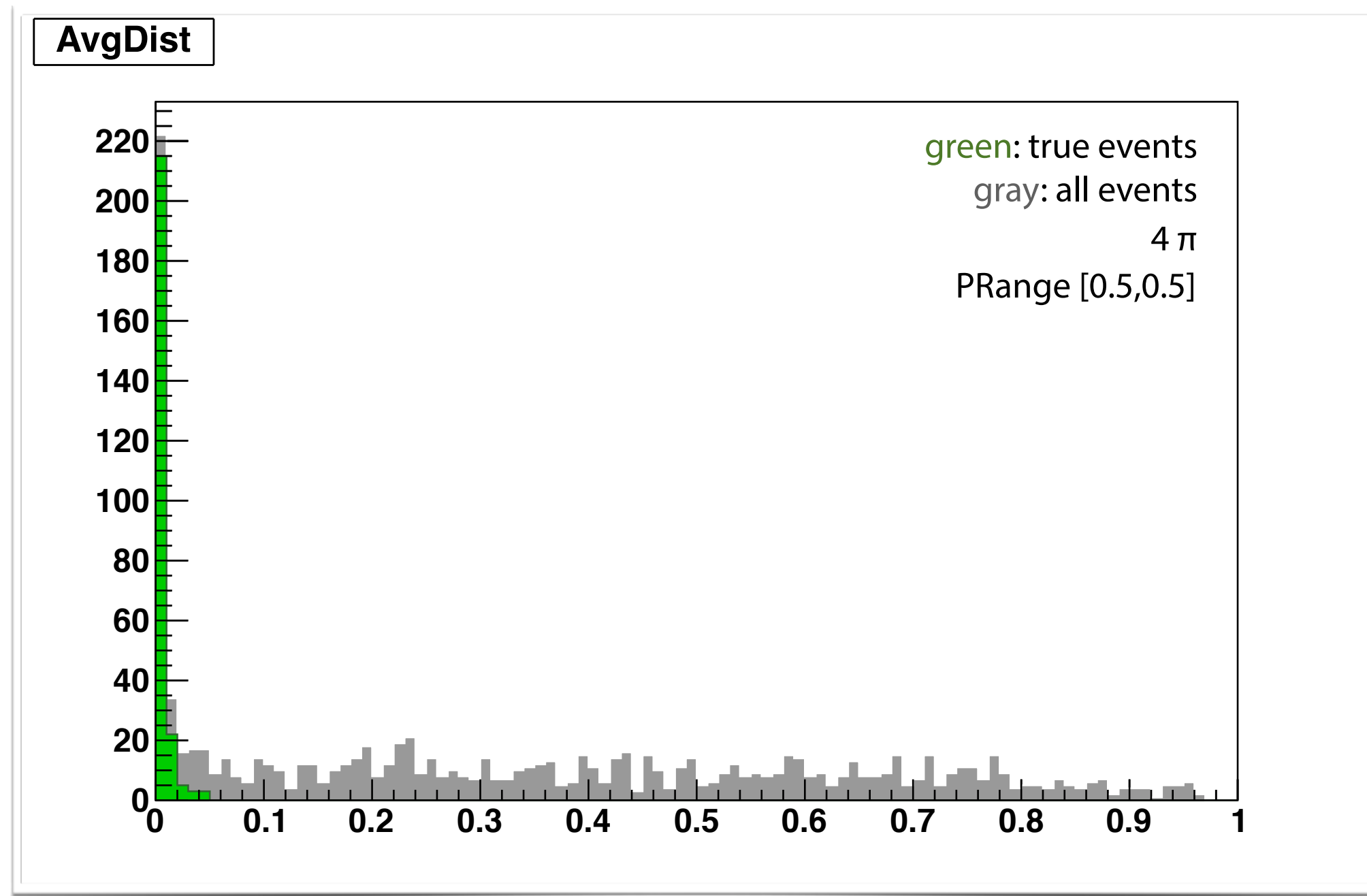
Improvement: AvgDist – Calculation



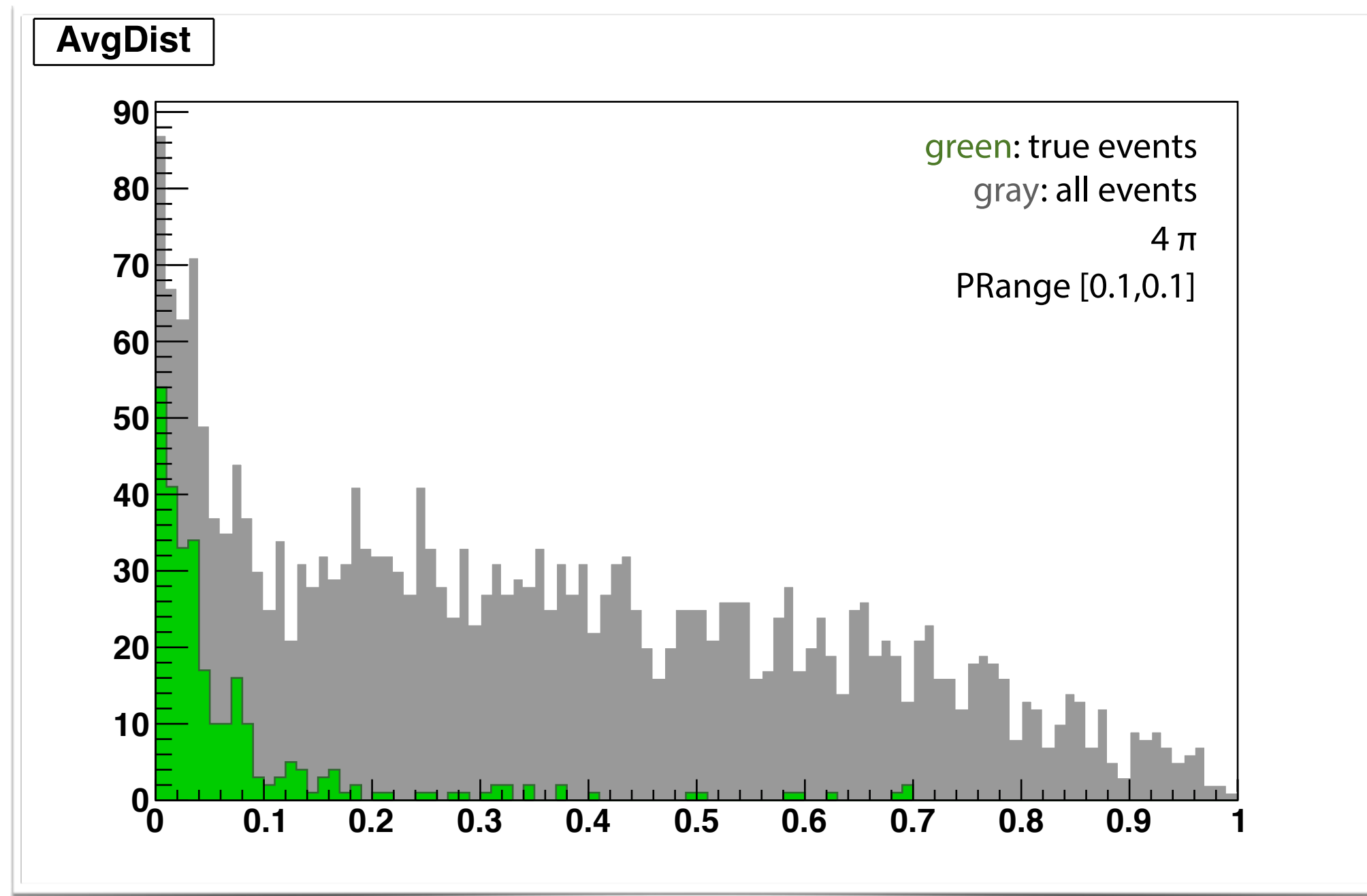
Improvement: AvgDist – Distribution



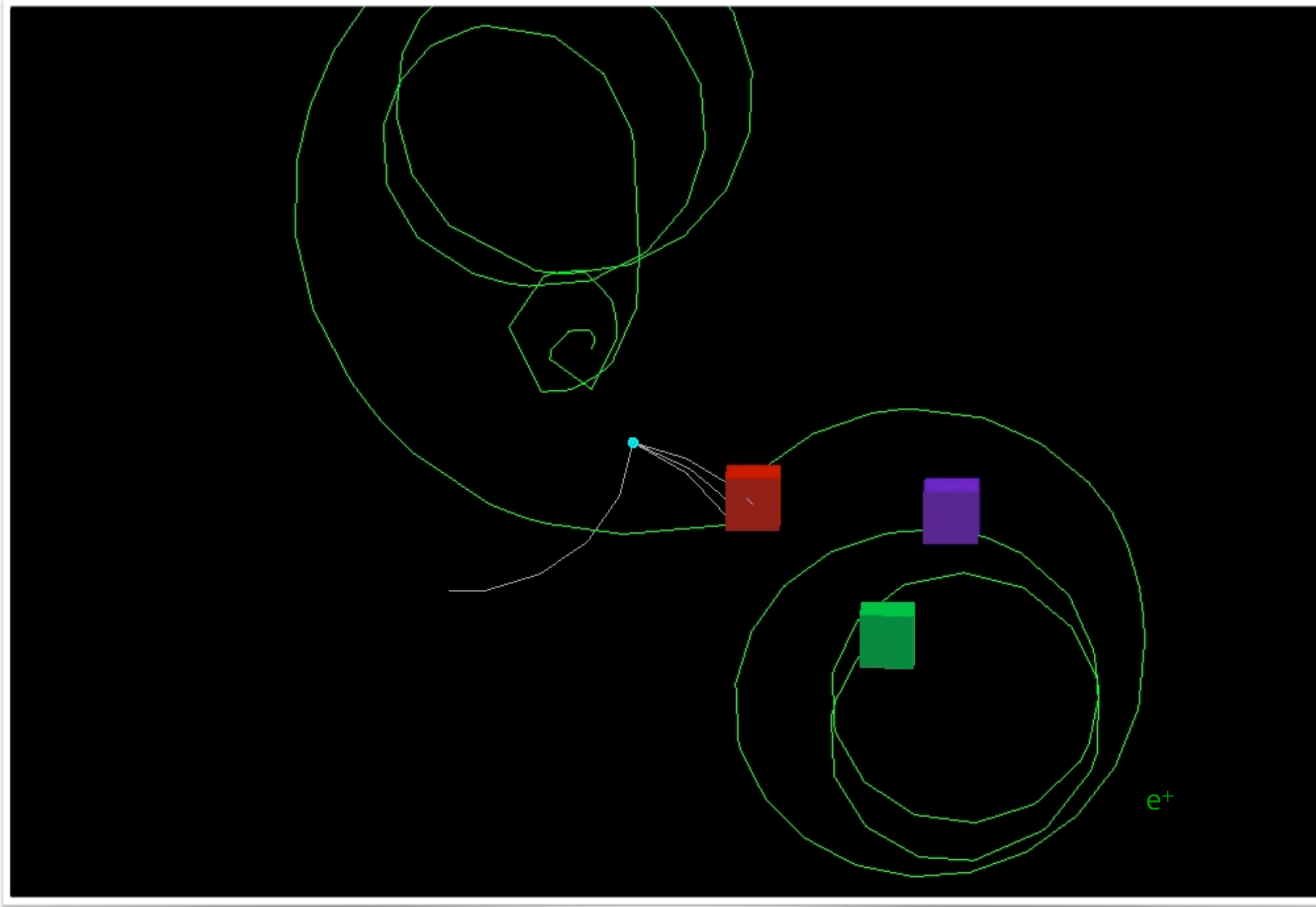
Improvement: AvgDist – Distribution



Improvement: AvgDist – Distribution



Improvement: AvgDist – Event Display



- Done:
 - Look at AvgDist of particles with broad distributions of momenta
 - Investigate noticeable events at high AvgDist being *true*
 - Explanation: Low-momentum, curling particles
- Currently Doing:
 - Analyse low-momentum (p_t) particles
 - Gather information for cut parameter
- To Be Done:
 - Efficiency / Purity
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 - Find
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 - Gather information for cut parameter
 - To Be Done:
 - Efficiency / Purity
 - Cut Parameter
 - Find
 - Implement into PandaRoot
- Speed up Riemann fit

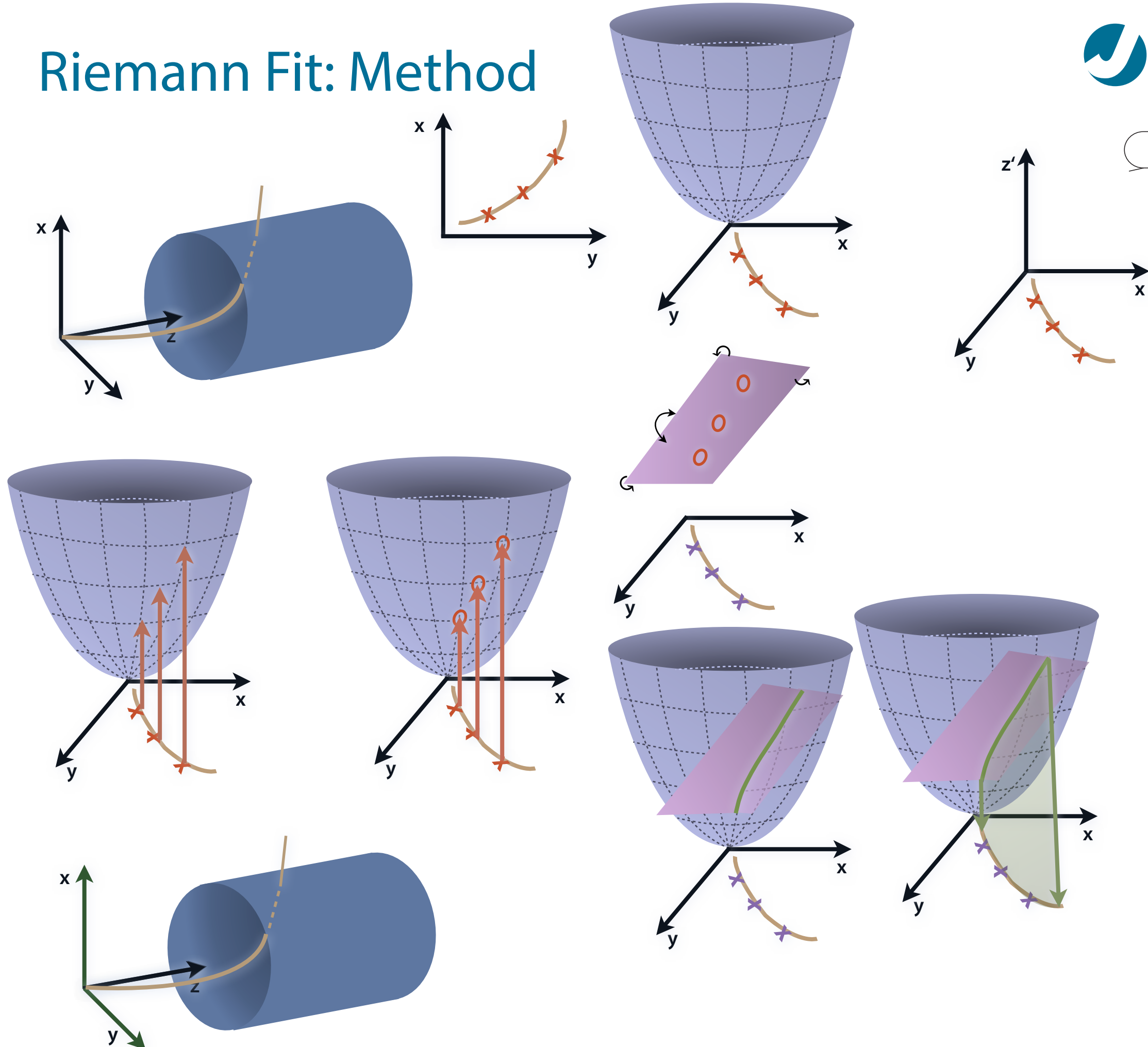
Thank you for your attention!



Backup

More is more.

Riemann Fit: Method



Riemann Fit: Method

