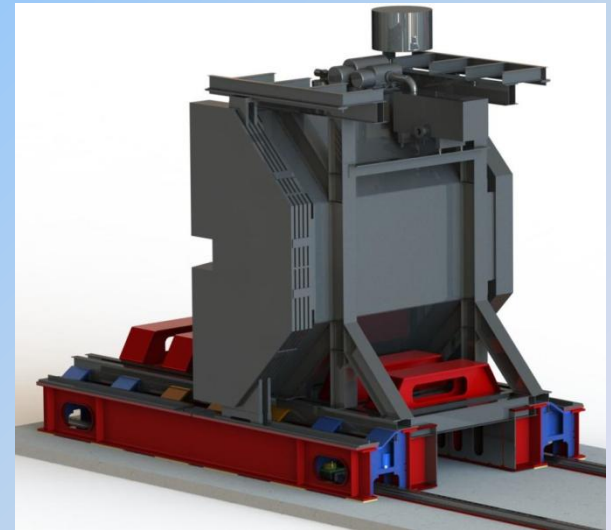
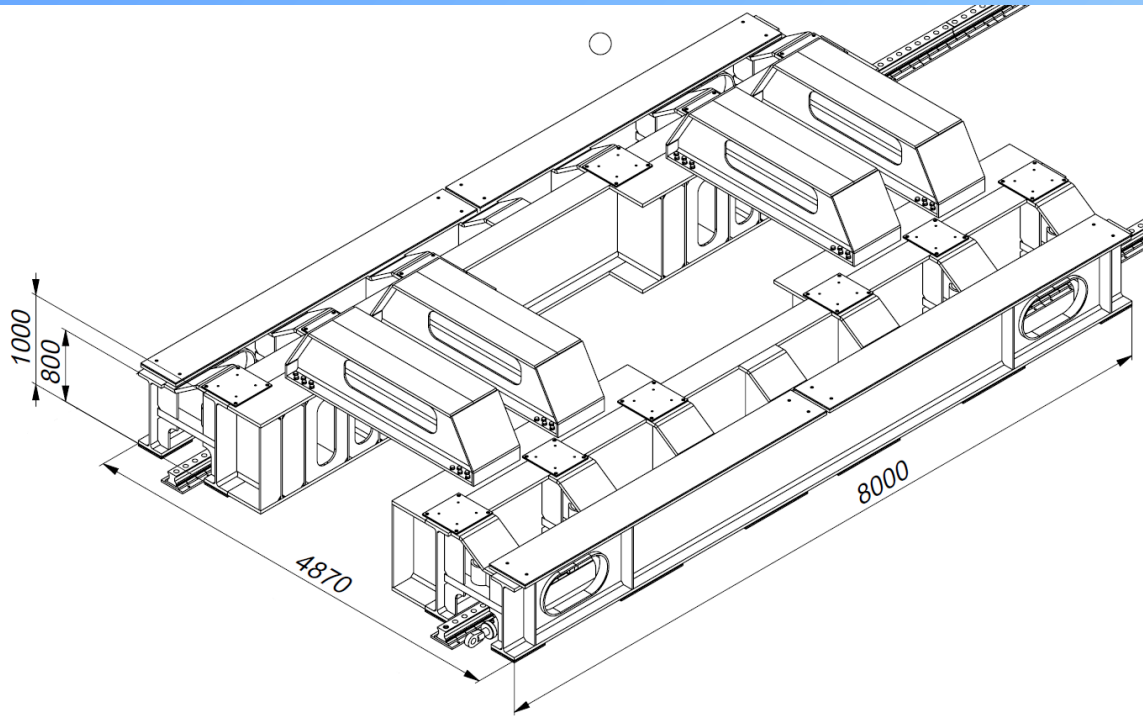


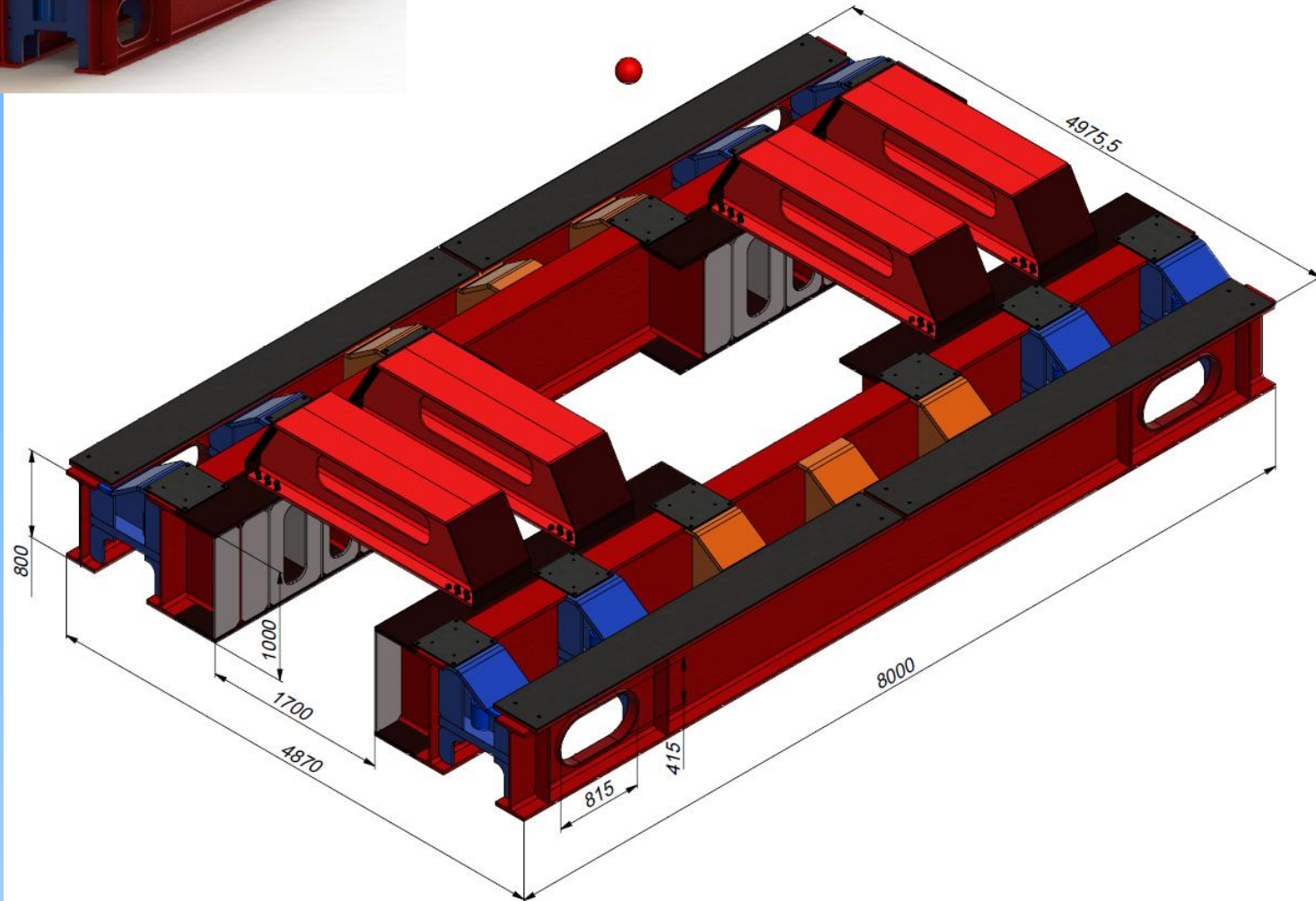
# Platform for Target Spectrometer using I-beam HEB 1000 with the cable window



Cracow University of Technology Mechanical Design Group

Edward Lisowski

# The platform for Target Spectrometer – main dimensions



# The interface between platform and yoke

platform – rear view  
(Old proposition Evgeny Koshunikov)

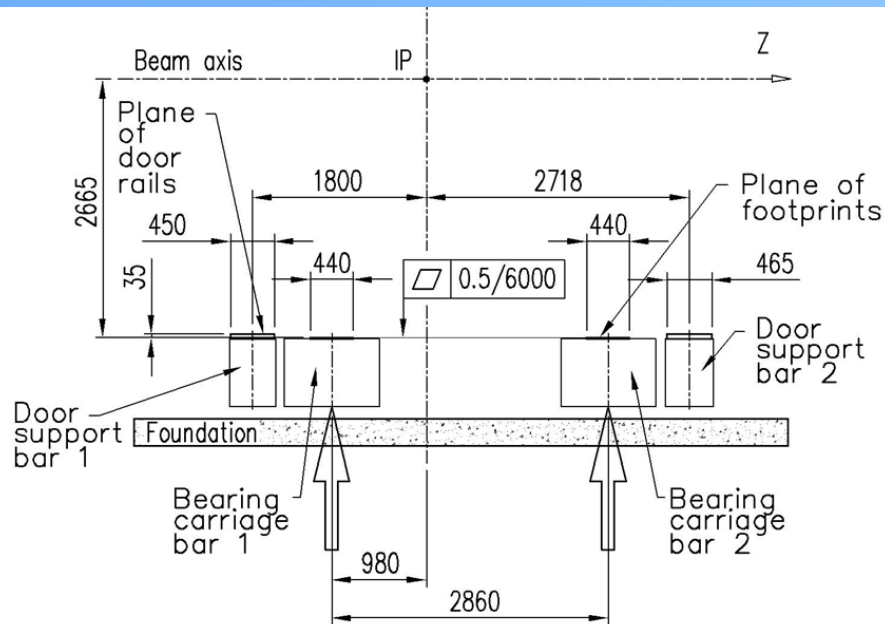
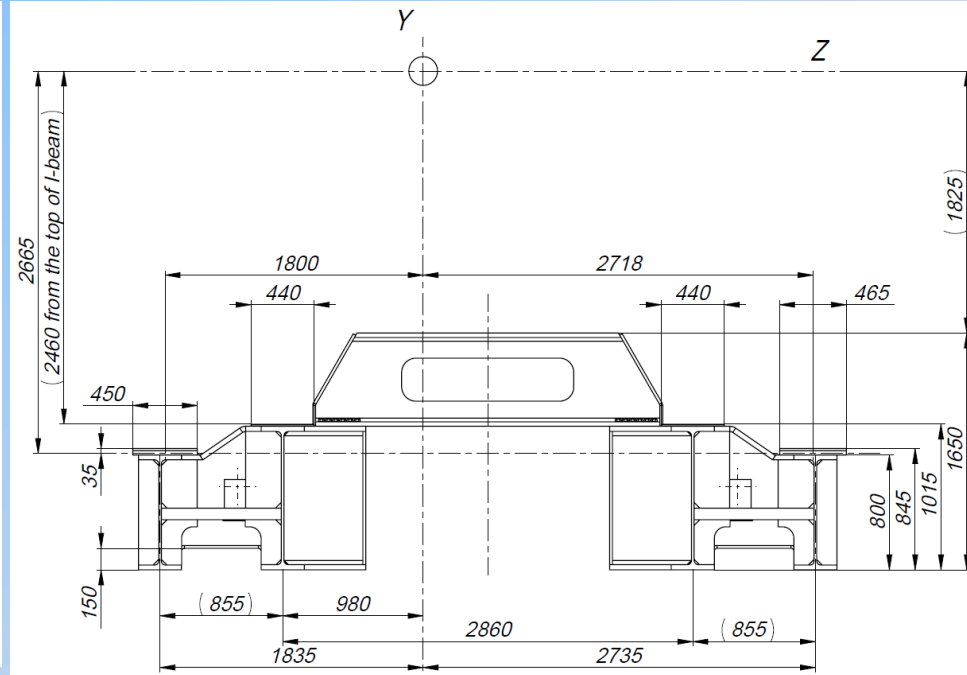


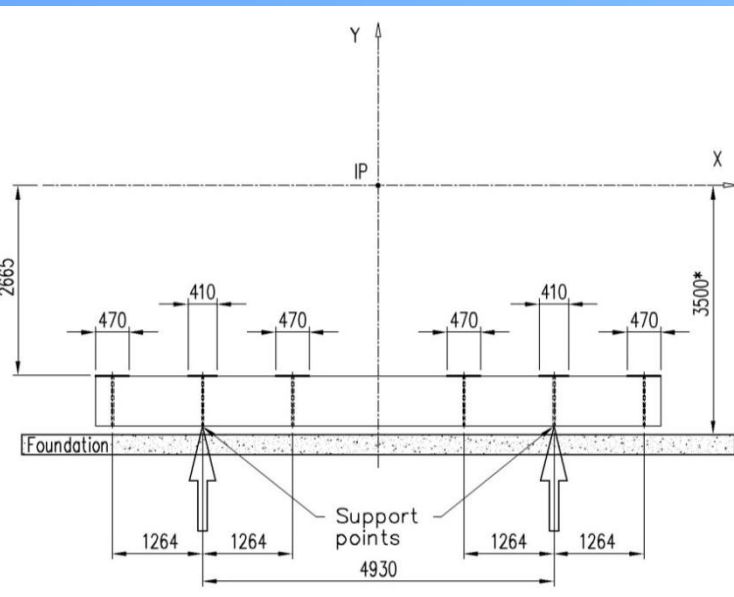
Fig. 2. End view of geometrical interface of the yoke and the transport carriage

The new platform – rear view

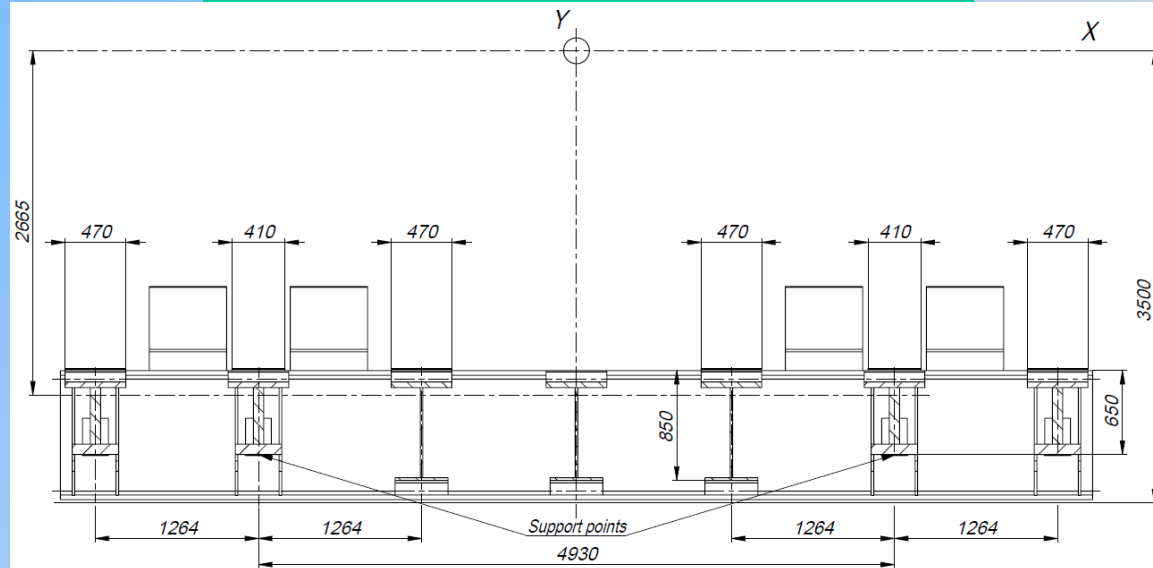


# The interface

platform – side view  
(old prop. Evgeny)



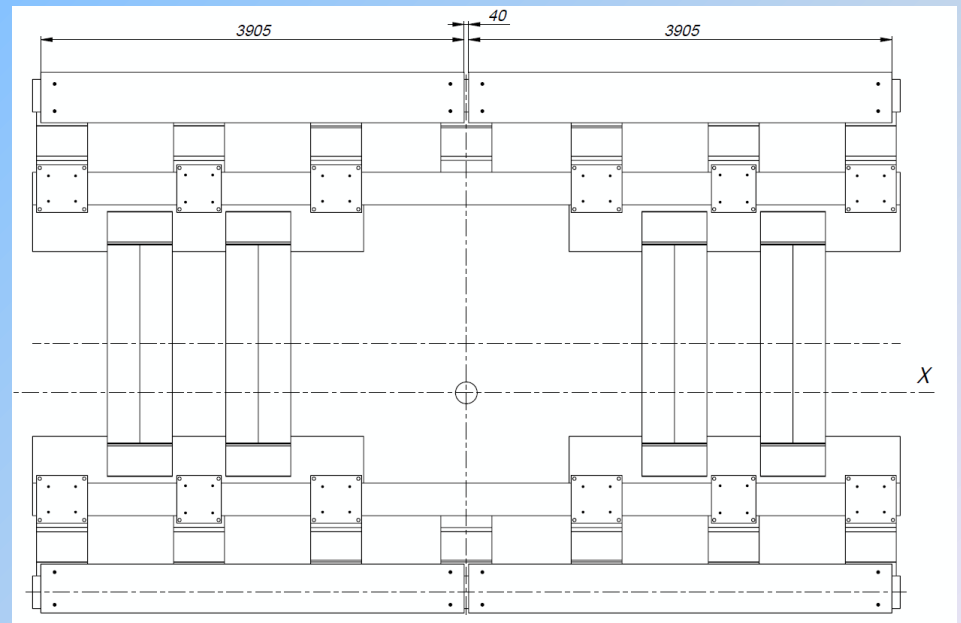
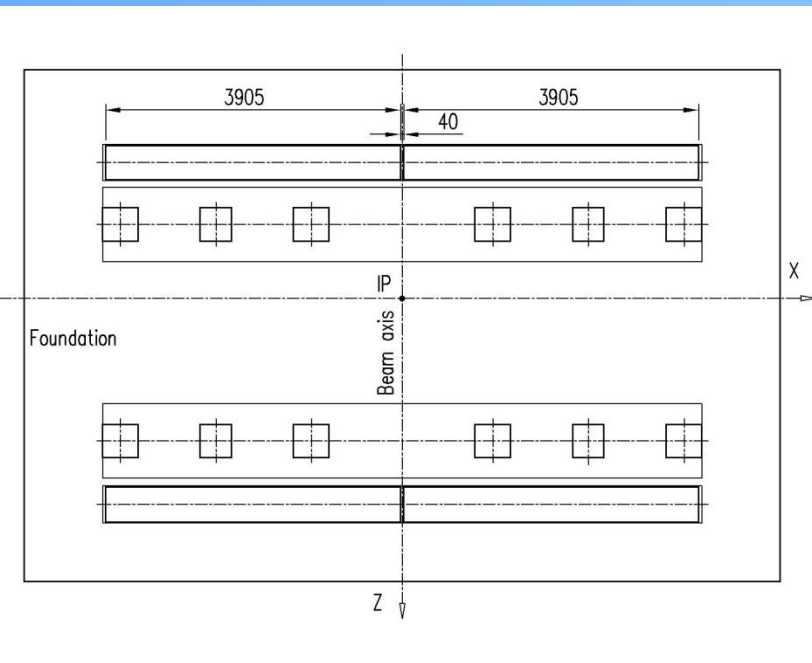
The new platform – side view



# The interface

platform – top view  
(old prop. Evgeny)

The platform – top view



## The platform – top and end views



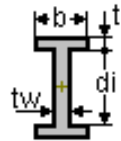
# Data of a single I-beam HEB 1000

Mass 314 kg/m, EN 10034;

Material stal S355 EN 10025,  $R_e=355\text{MPa}$

Moment of Inertia (Principal Coordinate System)

$6.2859\text{e}+09 \text{ [mm}^4\text{]}$

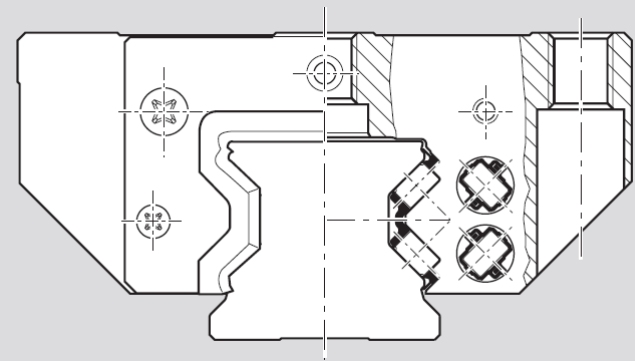
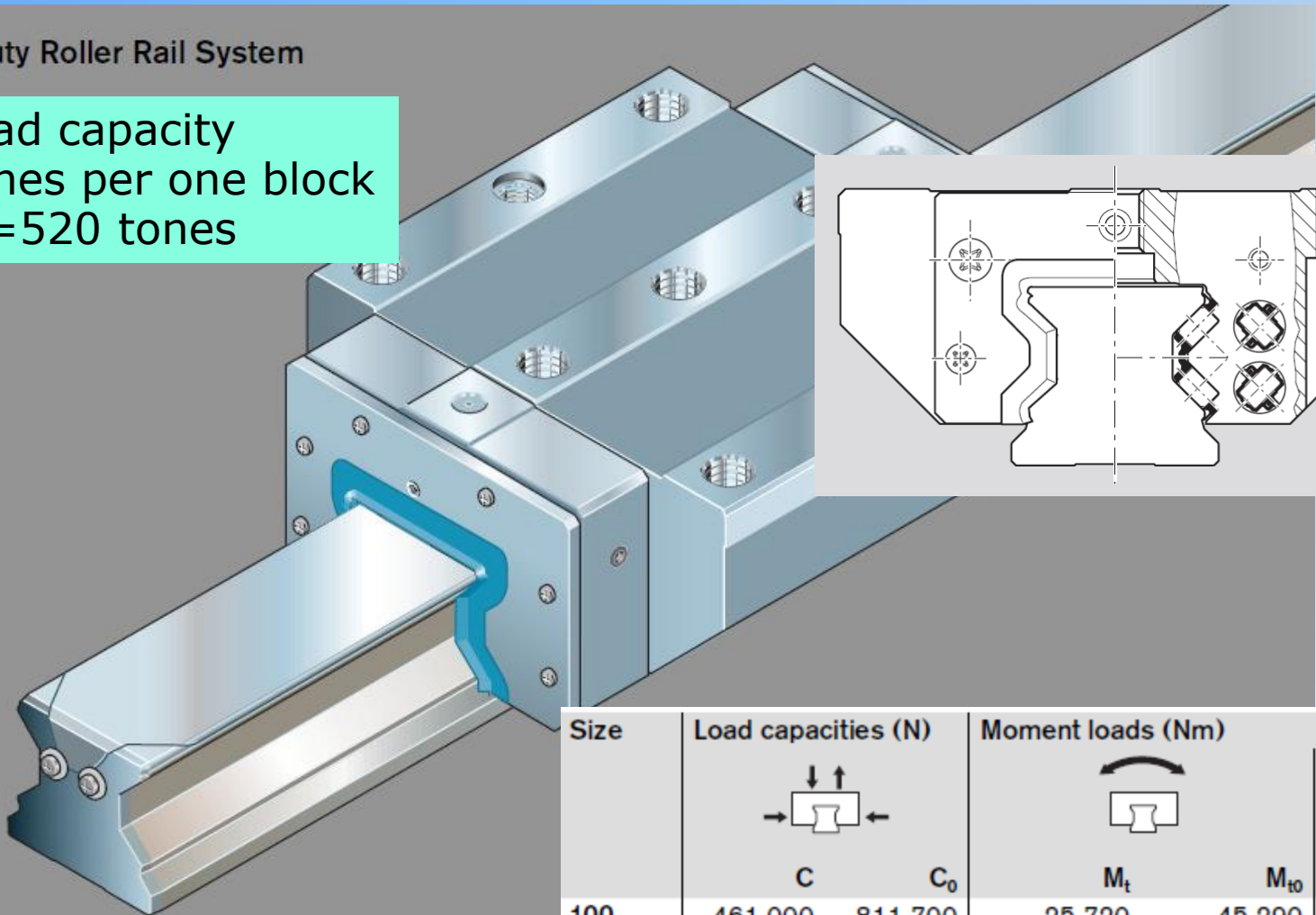
Beam Section "BeamSection1"	
Property	Value
Type	I Beam 
Dimensions	$b = 300 \text{ [mm]}$ $t = 36 \text{ [mm]}$ $d_i = 928 \text{ [mm]}$ $t_w = 19 \text{ [mm]}$
Area	$39232 \text{ [mm}^2\text{]}$
J	$1.07201\text{e}+07 \text{ [mm}^4\text{]}$
Moment of Inertia (Principal Coordinate System)	$\begin{bmatrix} 1.6253\text{e}+08 & 0 \\ 0 & 6.2859\text{e}+09 \end{bmatrix} \text{ [mm}^4\text{]}$





# Linear Motion drive system Rexroth

## Heavy Duty Roller Rail System

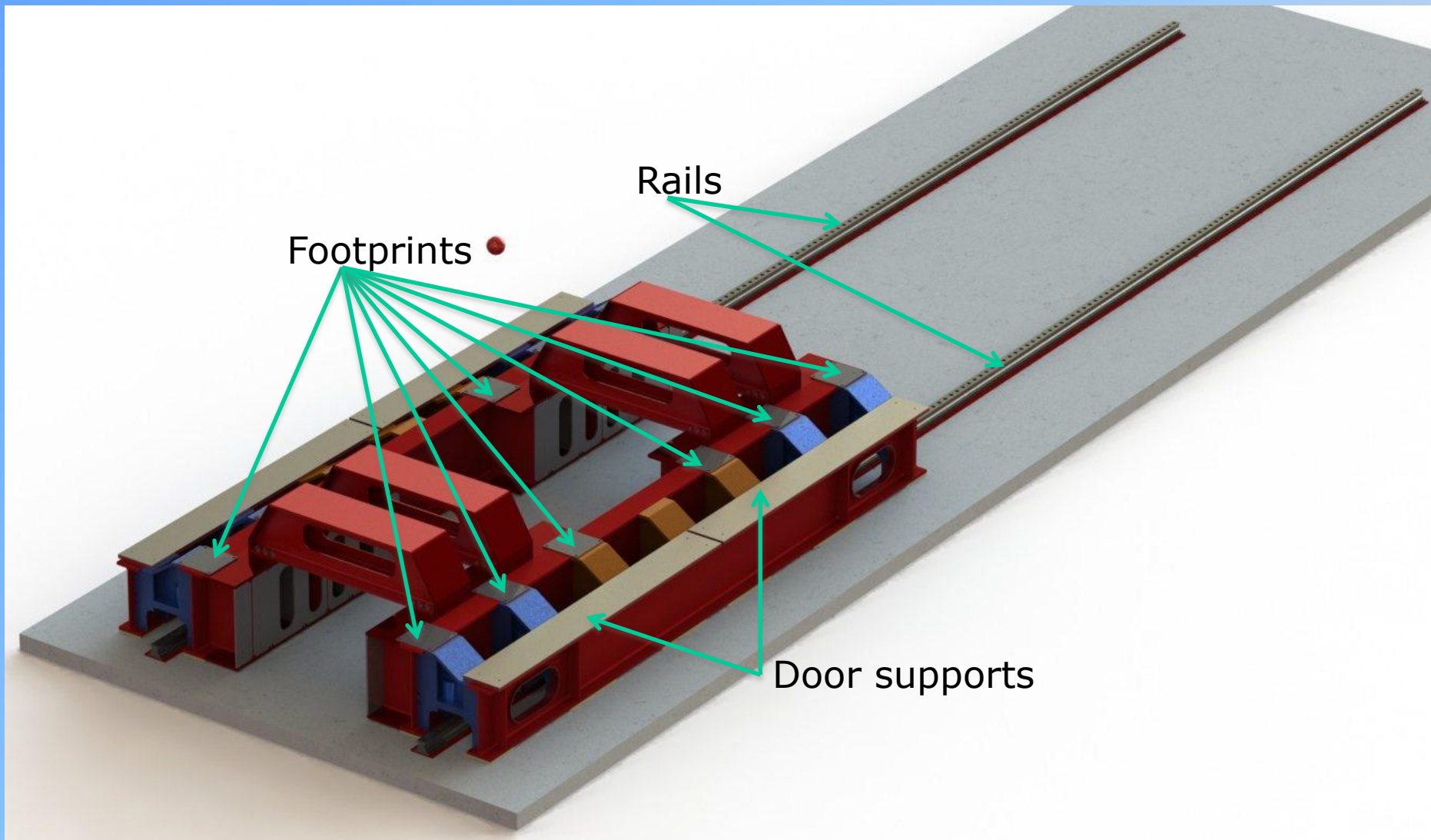
Max load capacity  
130 tones per one block  
 $4 \times 130 = 520$  tones



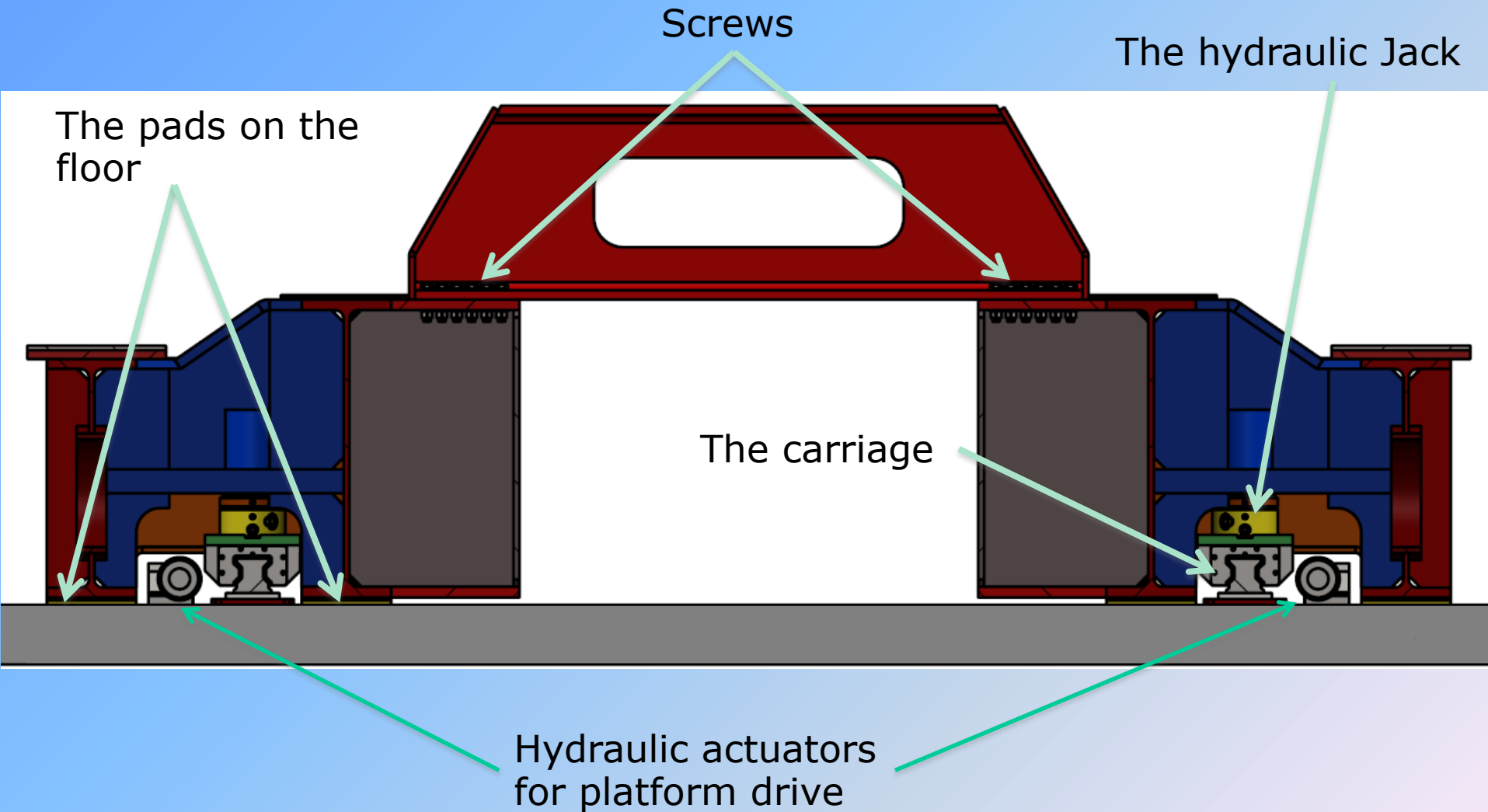
Size	Load capacities (N)		Moment loads (Nm)	
	 C                      C <sub>0</sub>		 M <sub>t</sub> M <sub>t0</sub>	
100	461 000	811 700	25 720	45 290
125	757 200	1 324 000	54 520	95 330



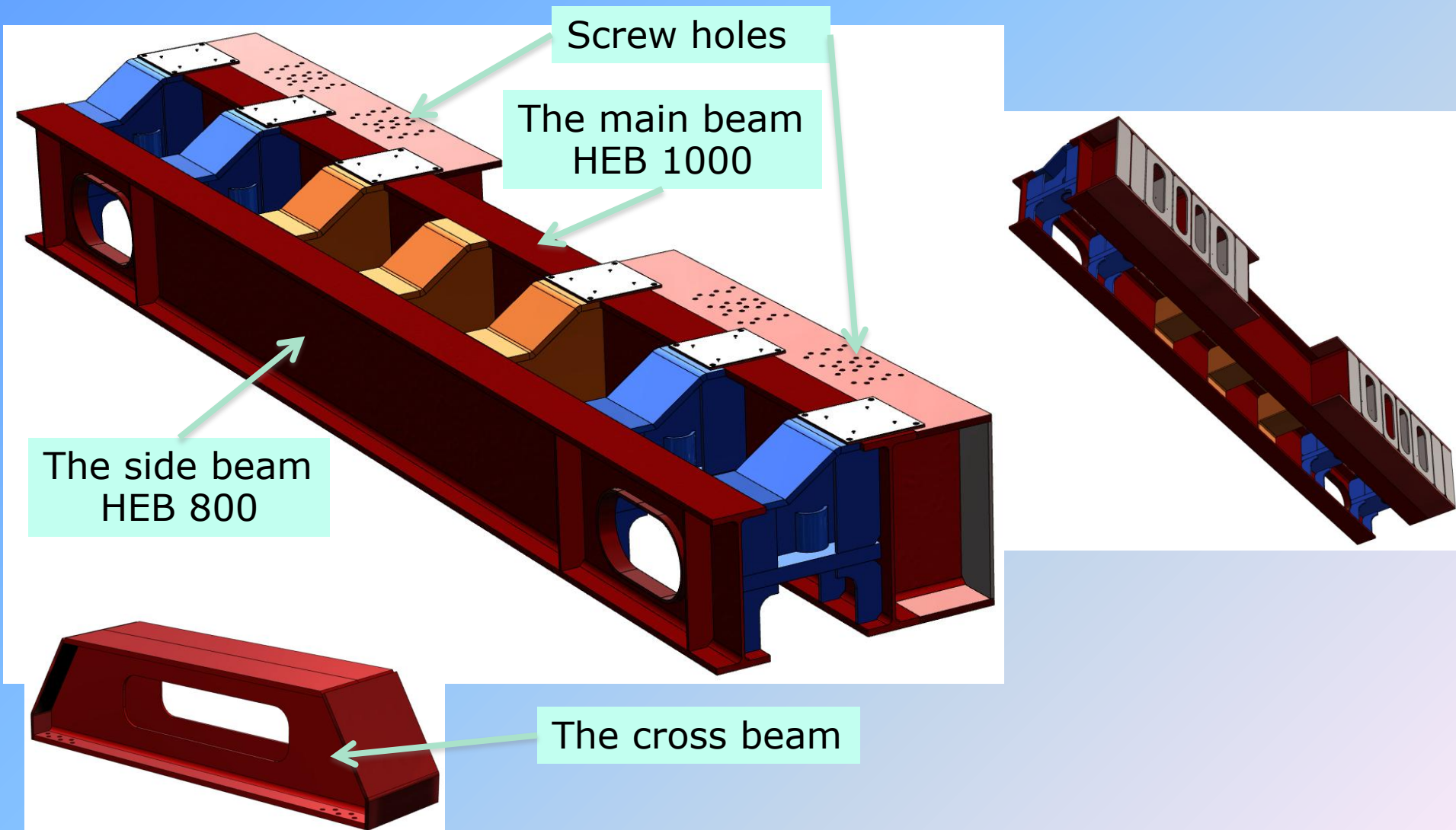
# The model of the platform with rails



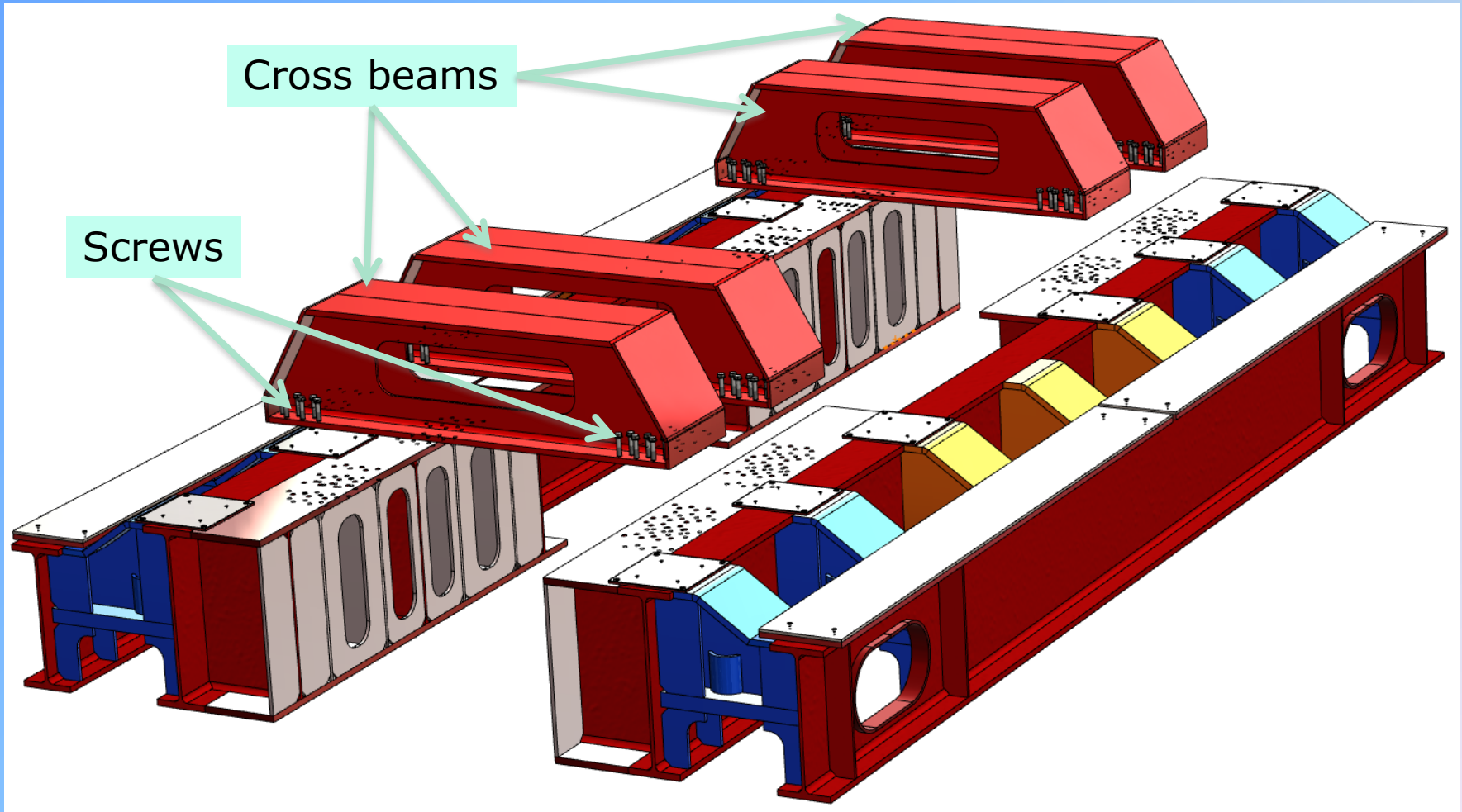
# Rear view of the platform



# Main components of the frame to assembly

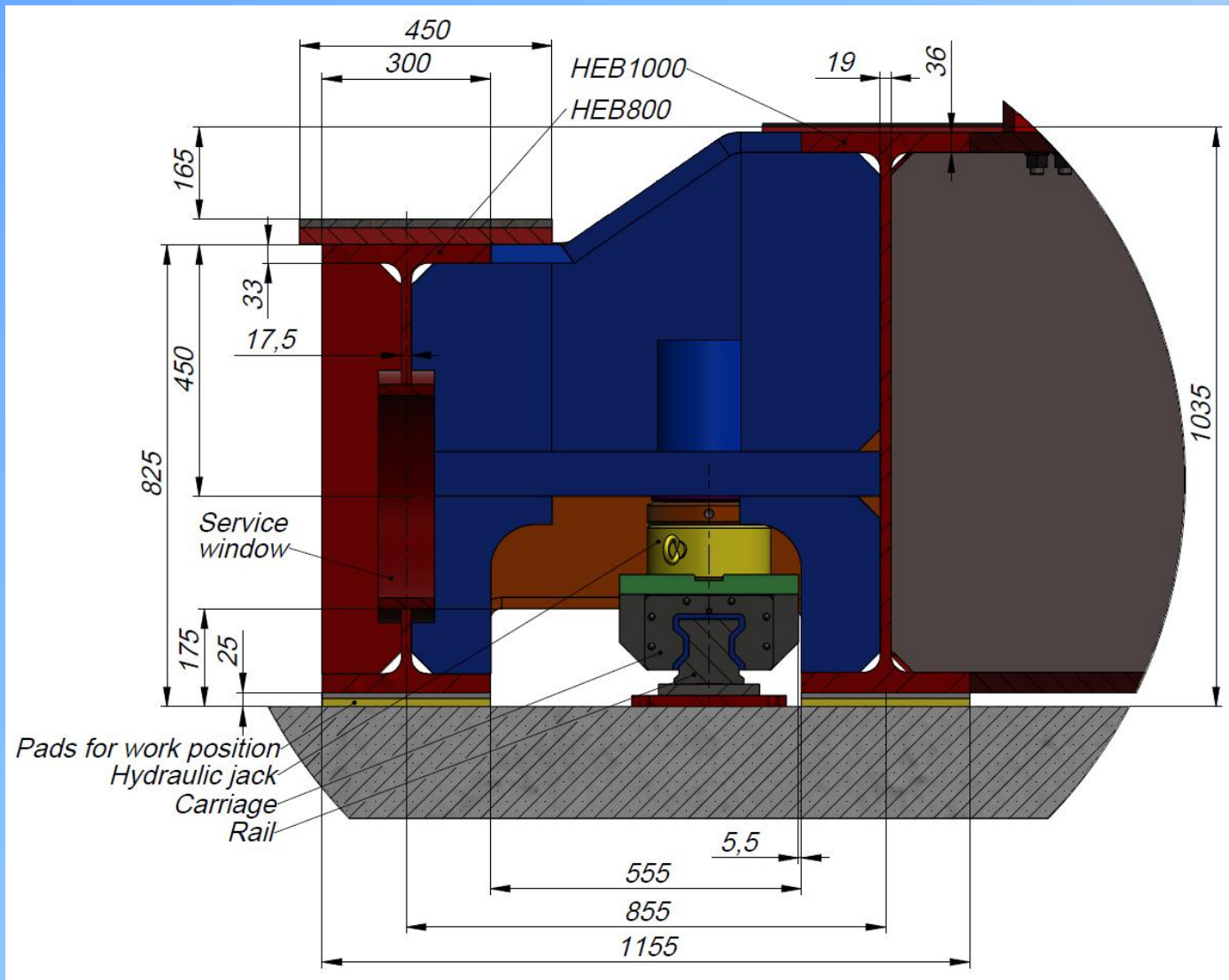


# Main components of the frame to assembly

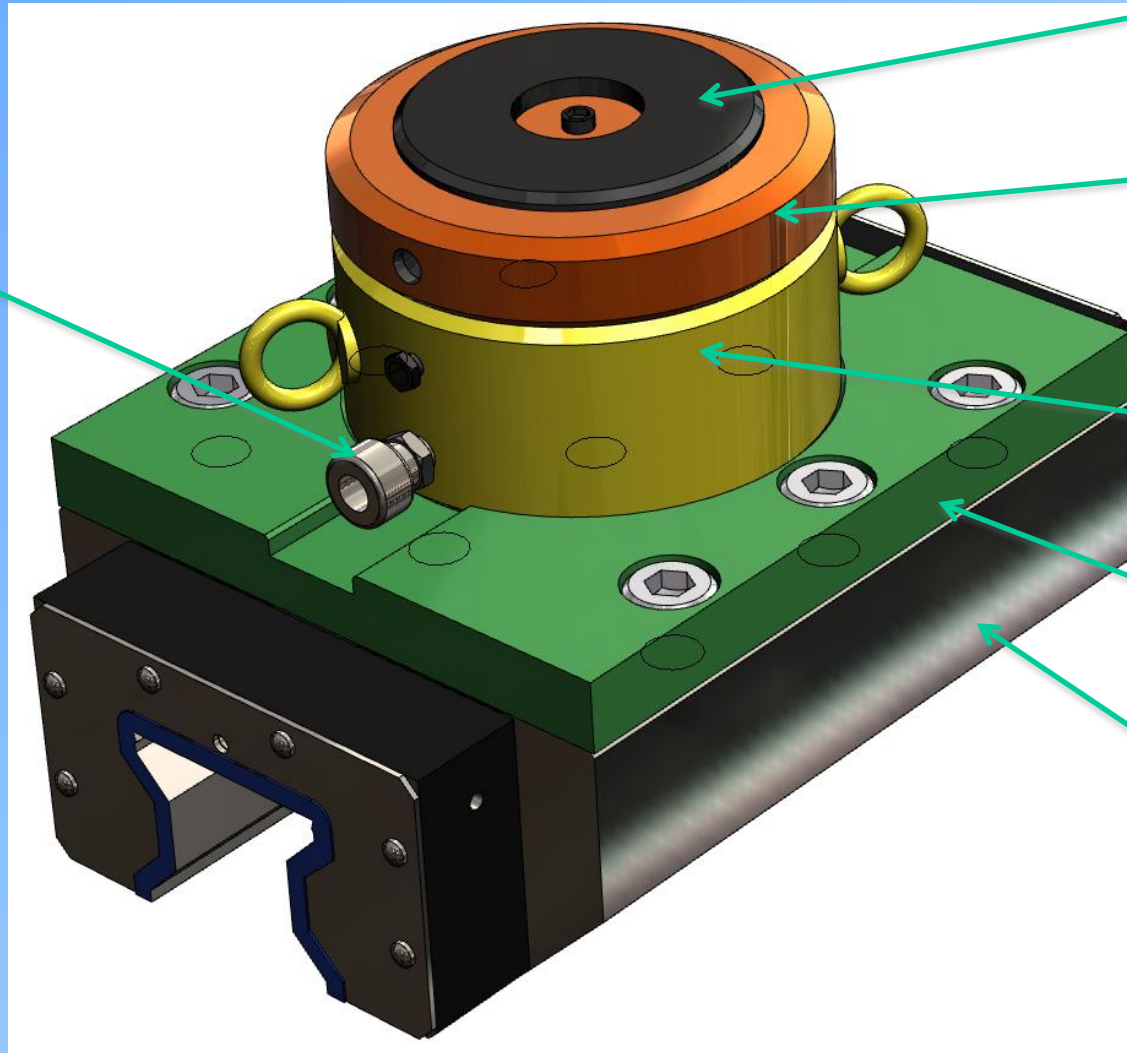




# Moving the Target, view of the carriage area



# View of the carriage outside before assembly



Hydraulic  
connector

Jack-head

Jack-head  
ring

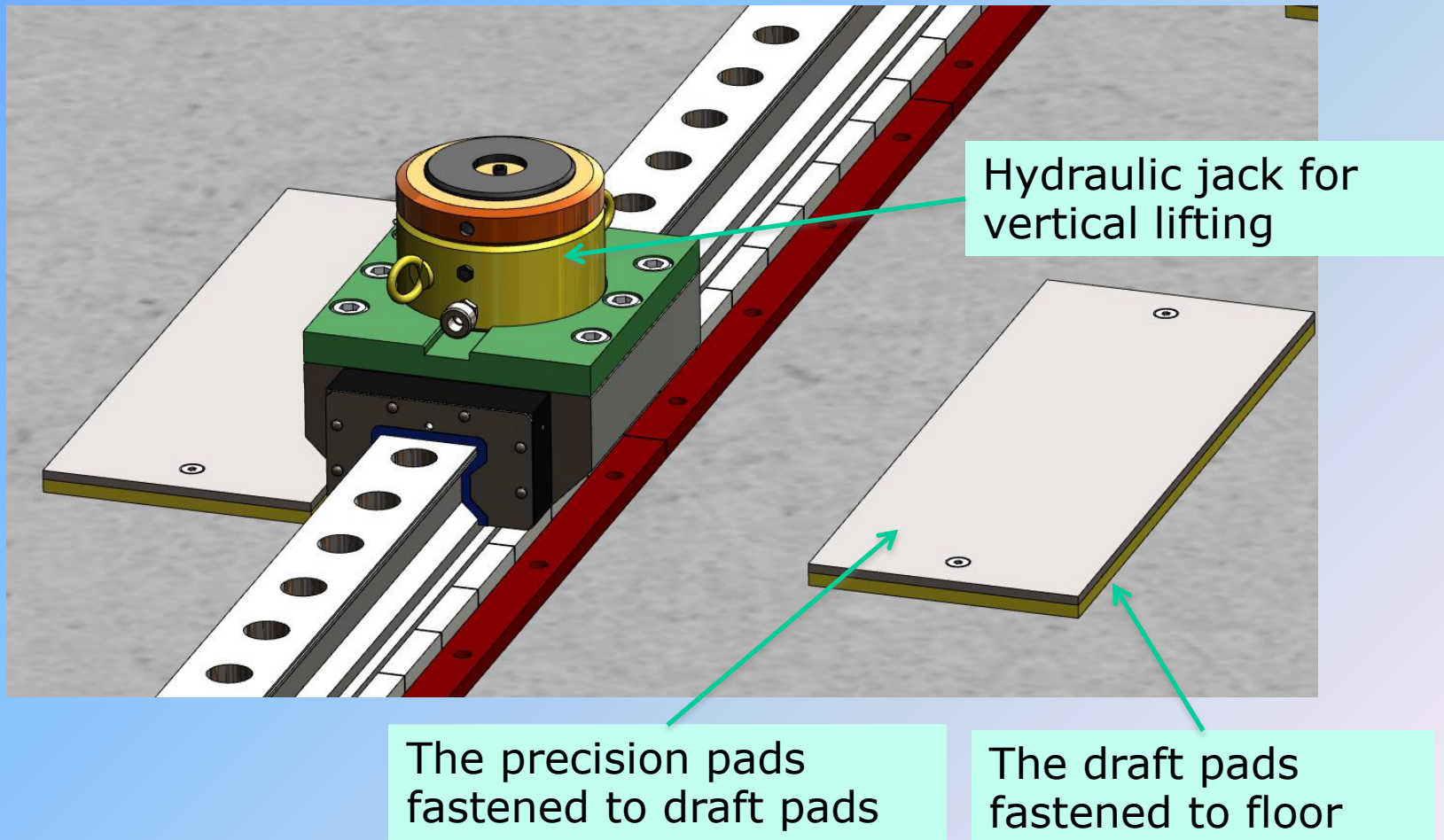
Hydraulic jack

Plate – nest  
for jack

Frame of  
the carriage

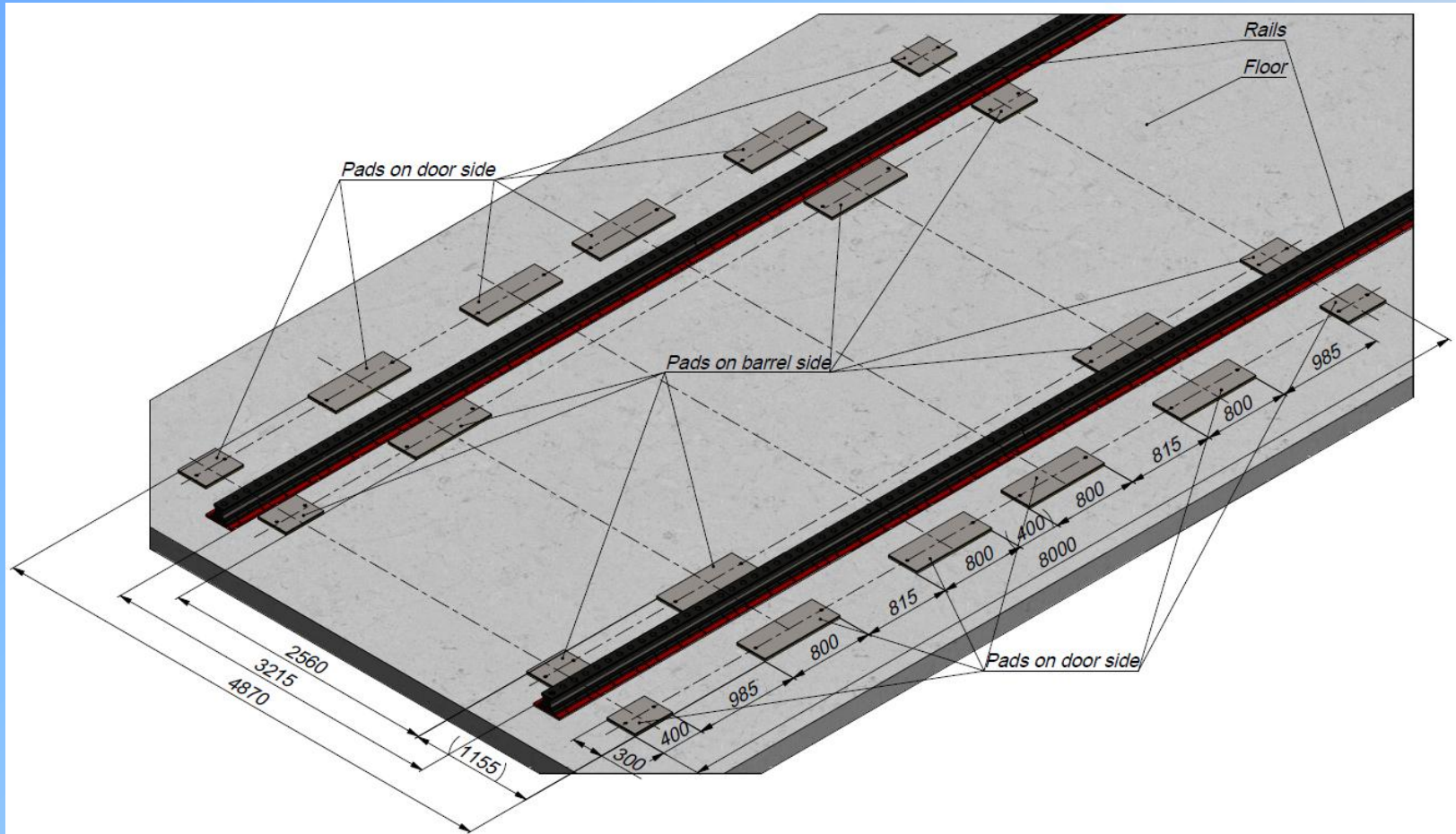


# Carriage, hydraulic jack and pads at the support point

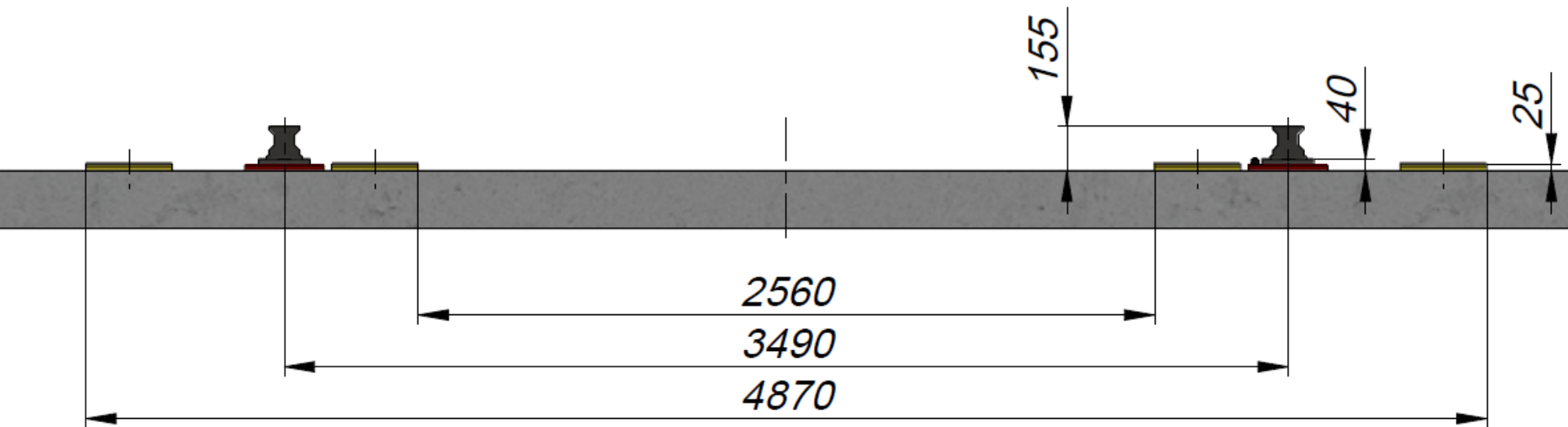


# Technology of assembly – permanent support

1. Fasten rails with carriages to the floor very precisely.
2. Fasten draft pads (plates for hydraulic jack and frame) to the floor.
3. Regulate the height and flatness of the platform

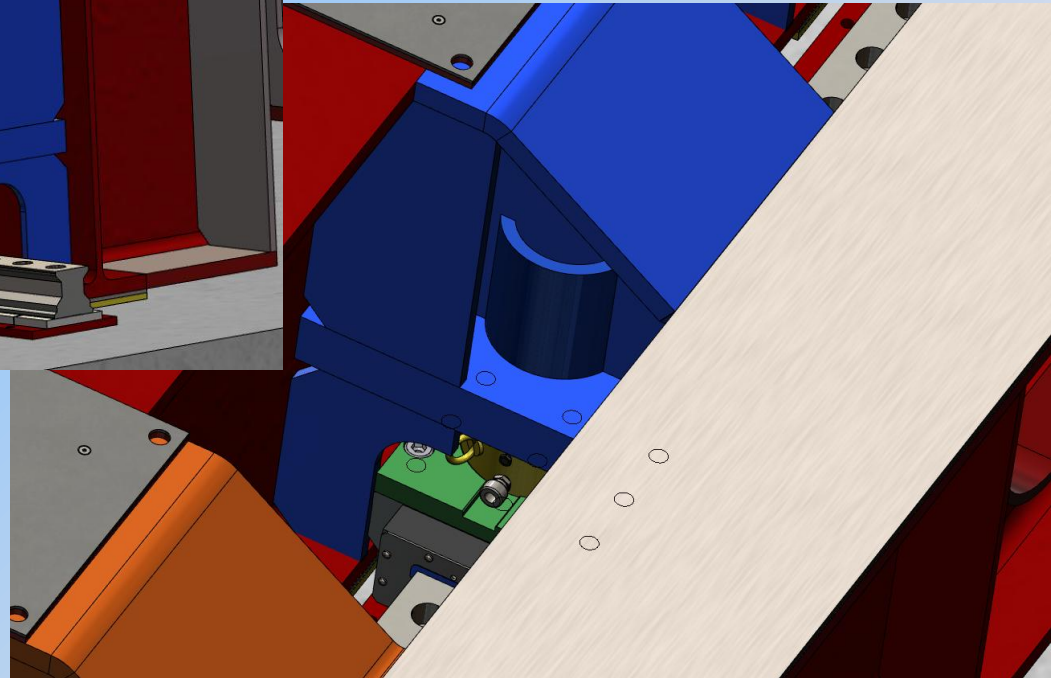
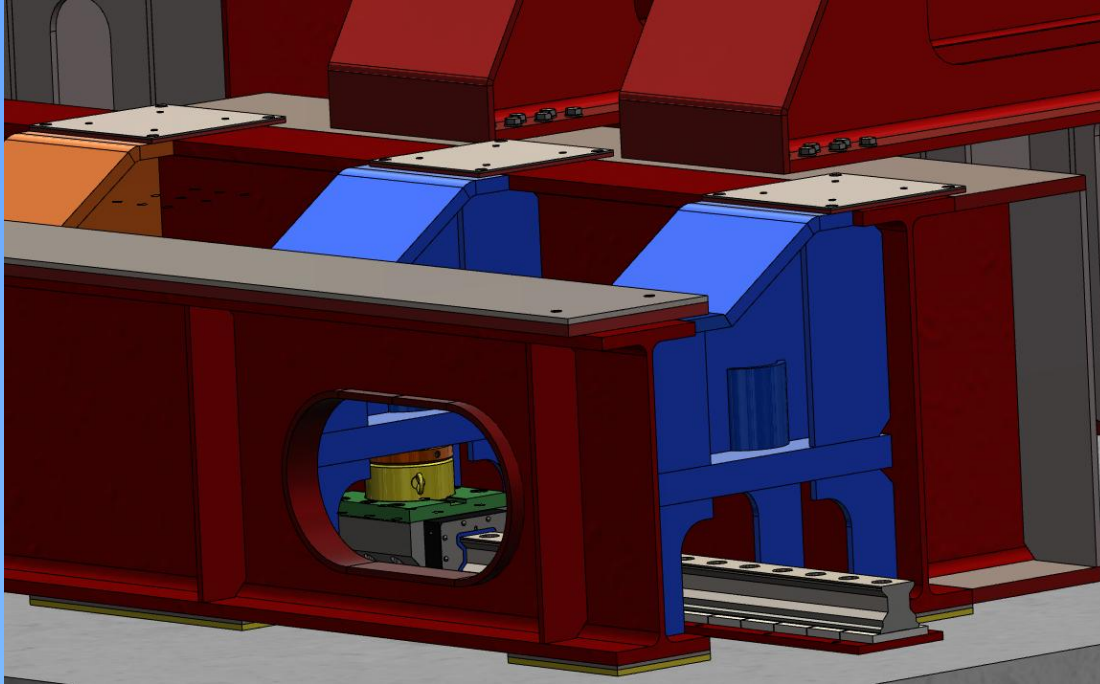


# Rail and pads gauges



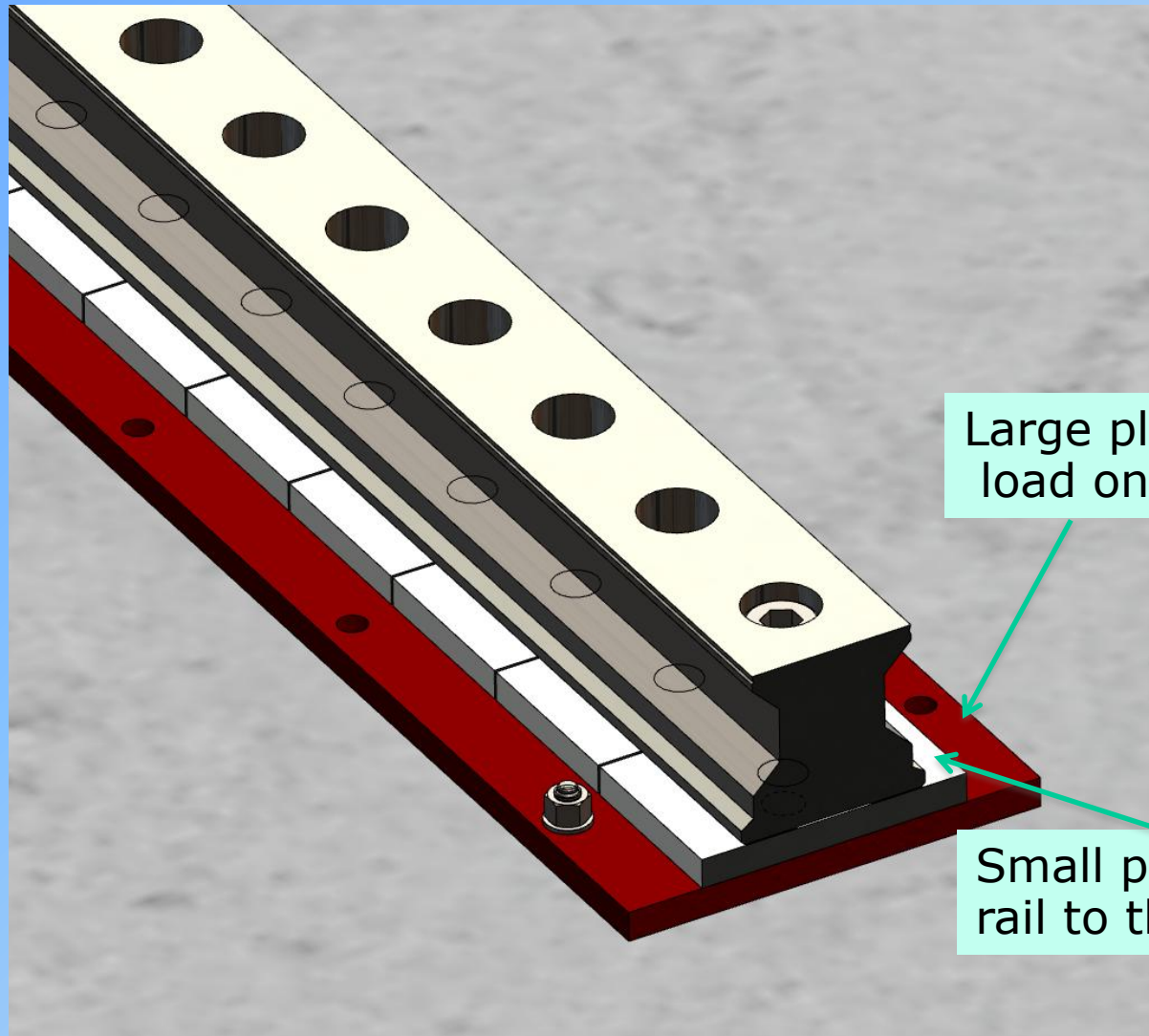
# Some details of installation

Access windows for carriage and hydraulic jack under platform





# Installation of the rail on the floor

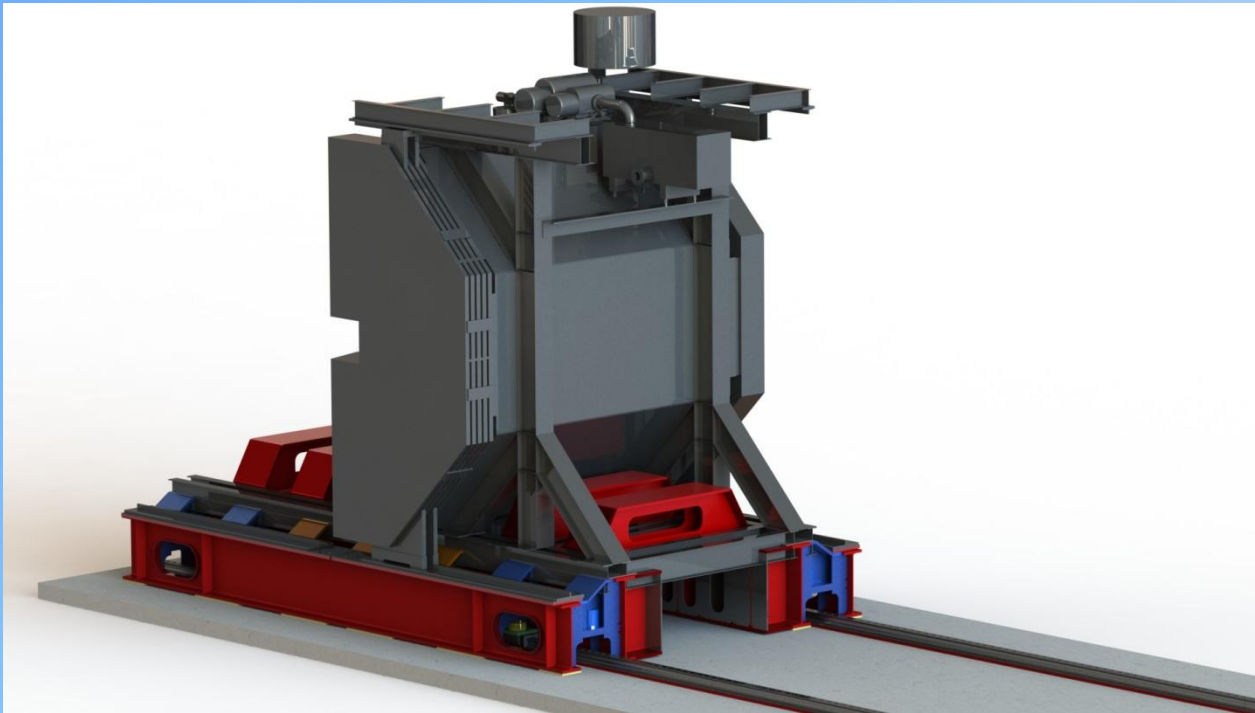


Large plate distributes load on the floor

Small plates fix the rail to the main plate

# FEM Analysis

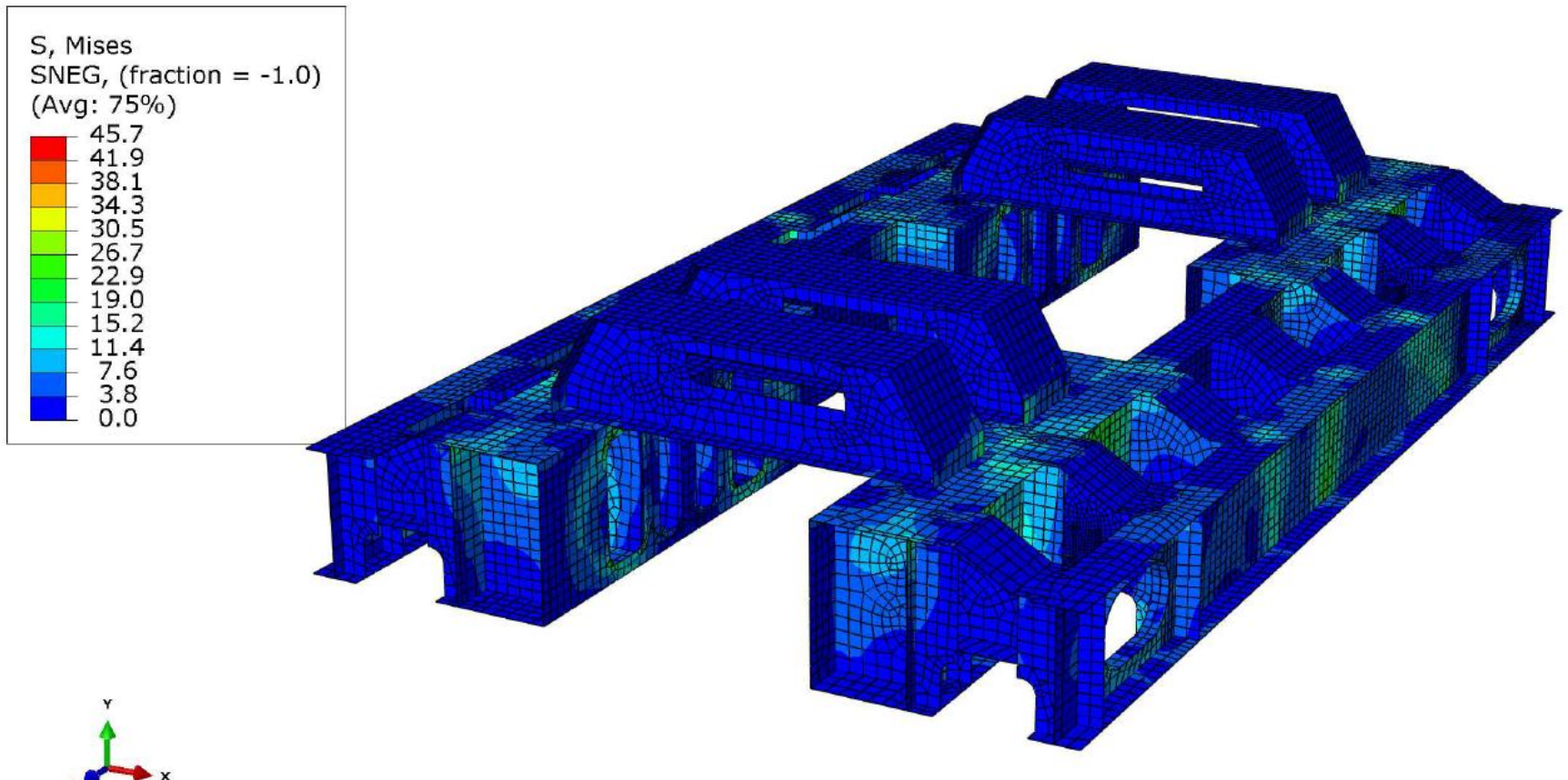
1. Permanent supports (domestic position)
2. Moving – supports platform on four carriages





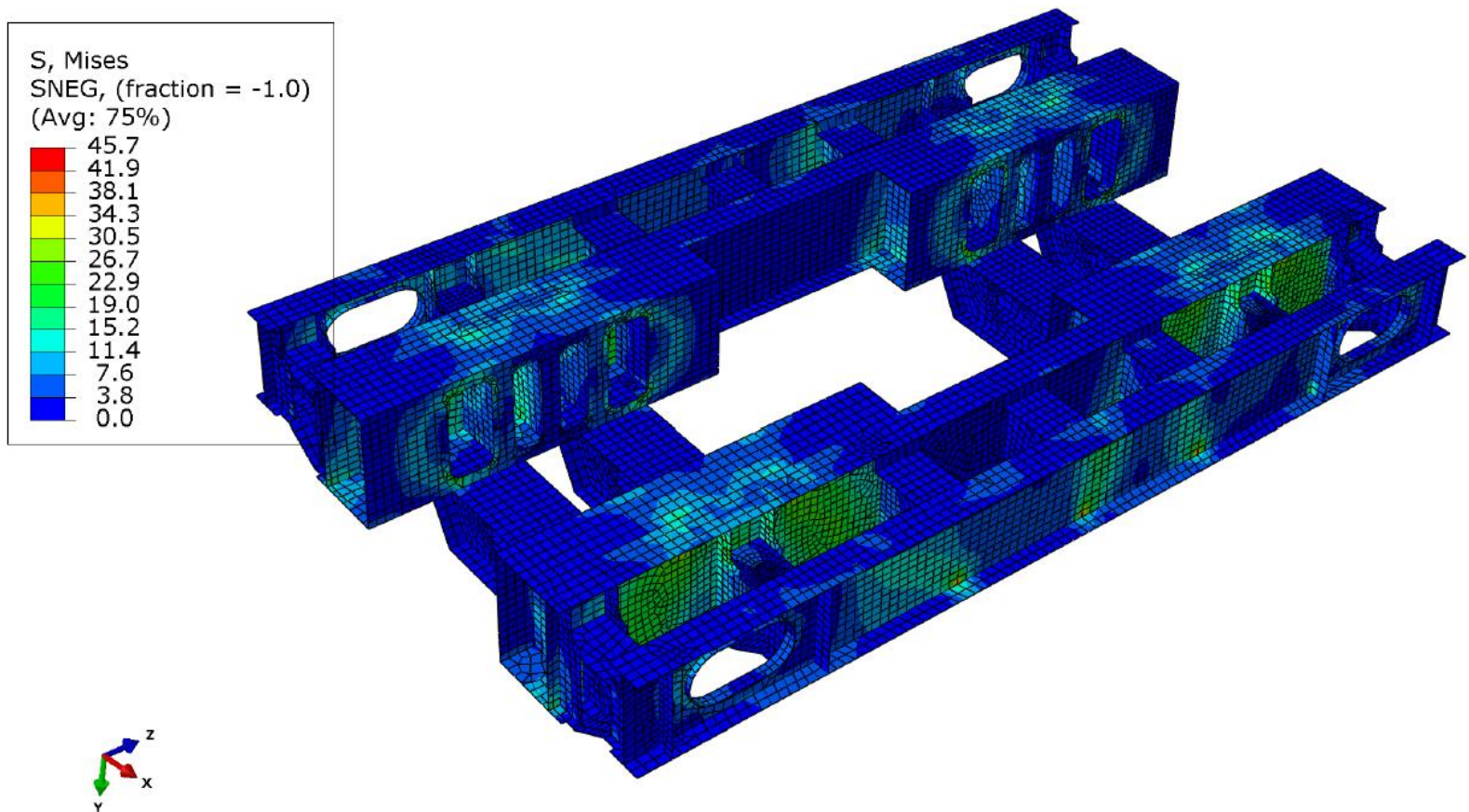
# Pernament supports on 12 pads, 8 under doors

## Stress von Mises – izo top view



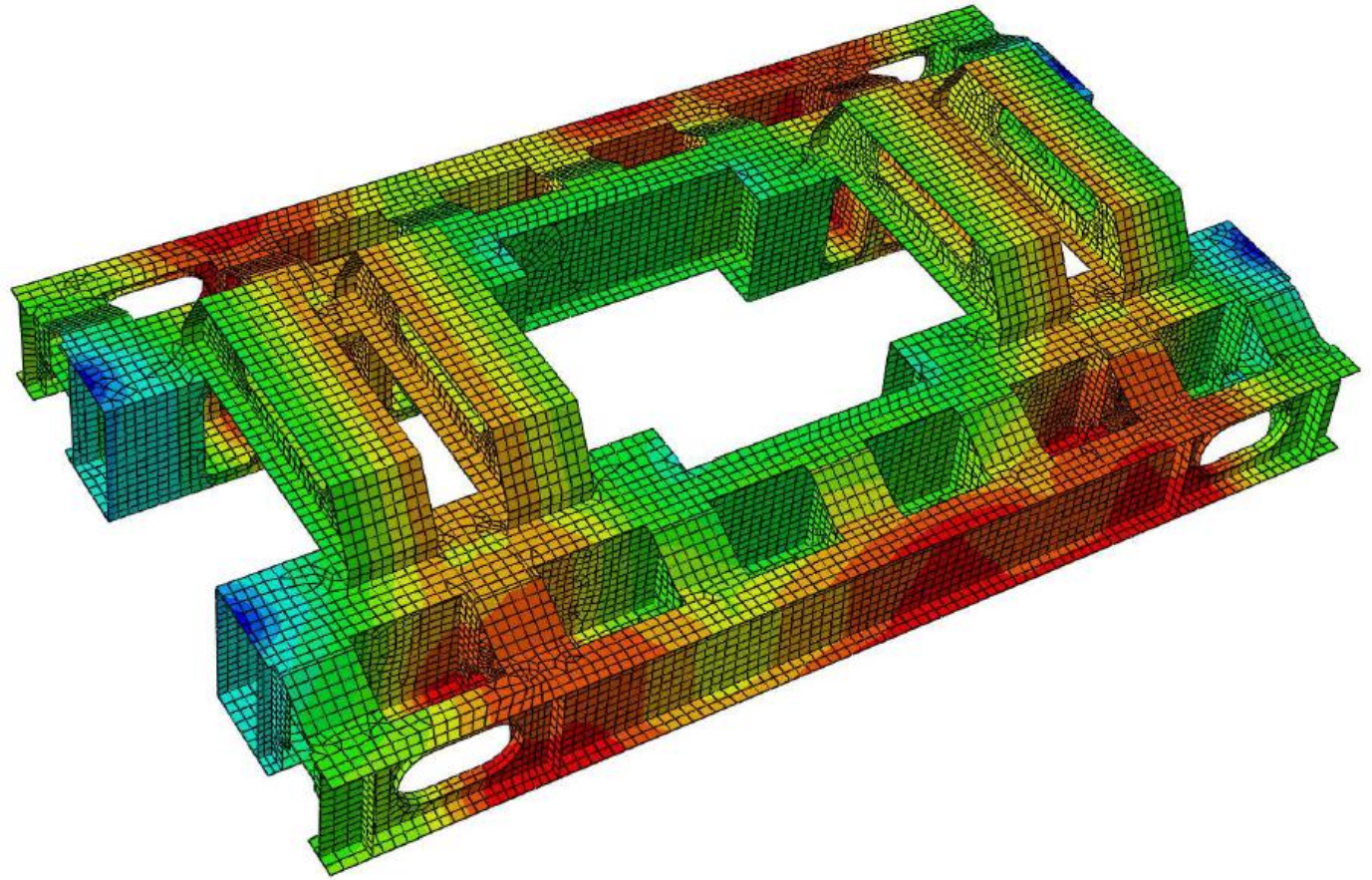
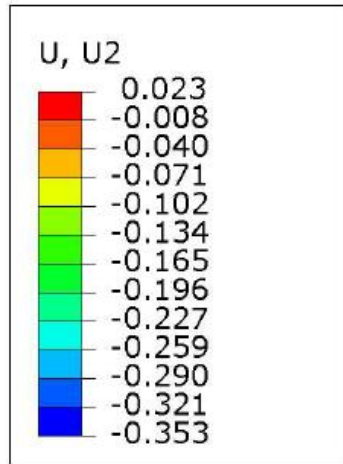
# Pernament supports on 12 pads, 8 under doors

## Stress von Mises – izo bottom view

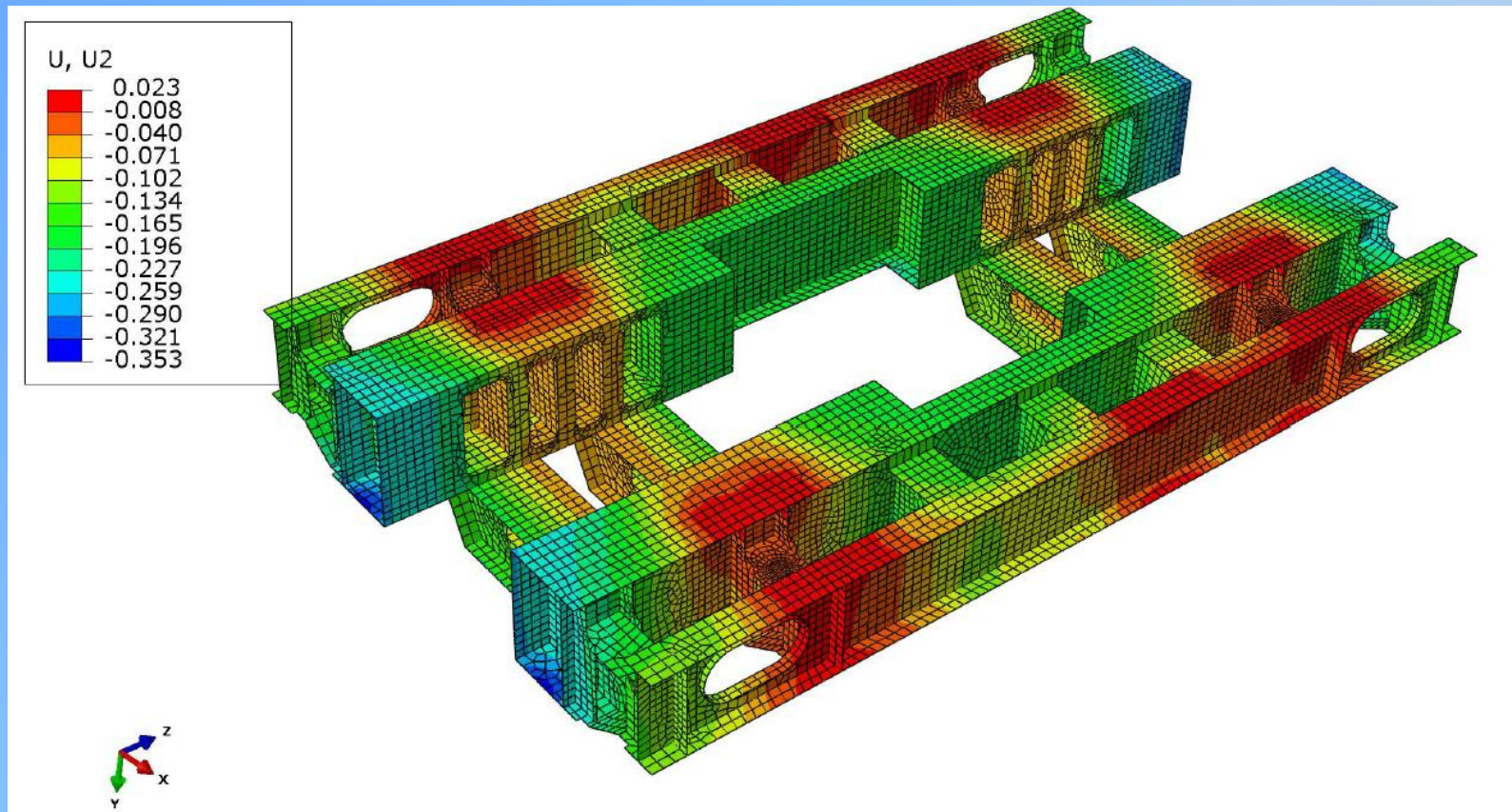




# Permanent supports on 12 pads, 8 under doors Displacement in Y direction – izo top view



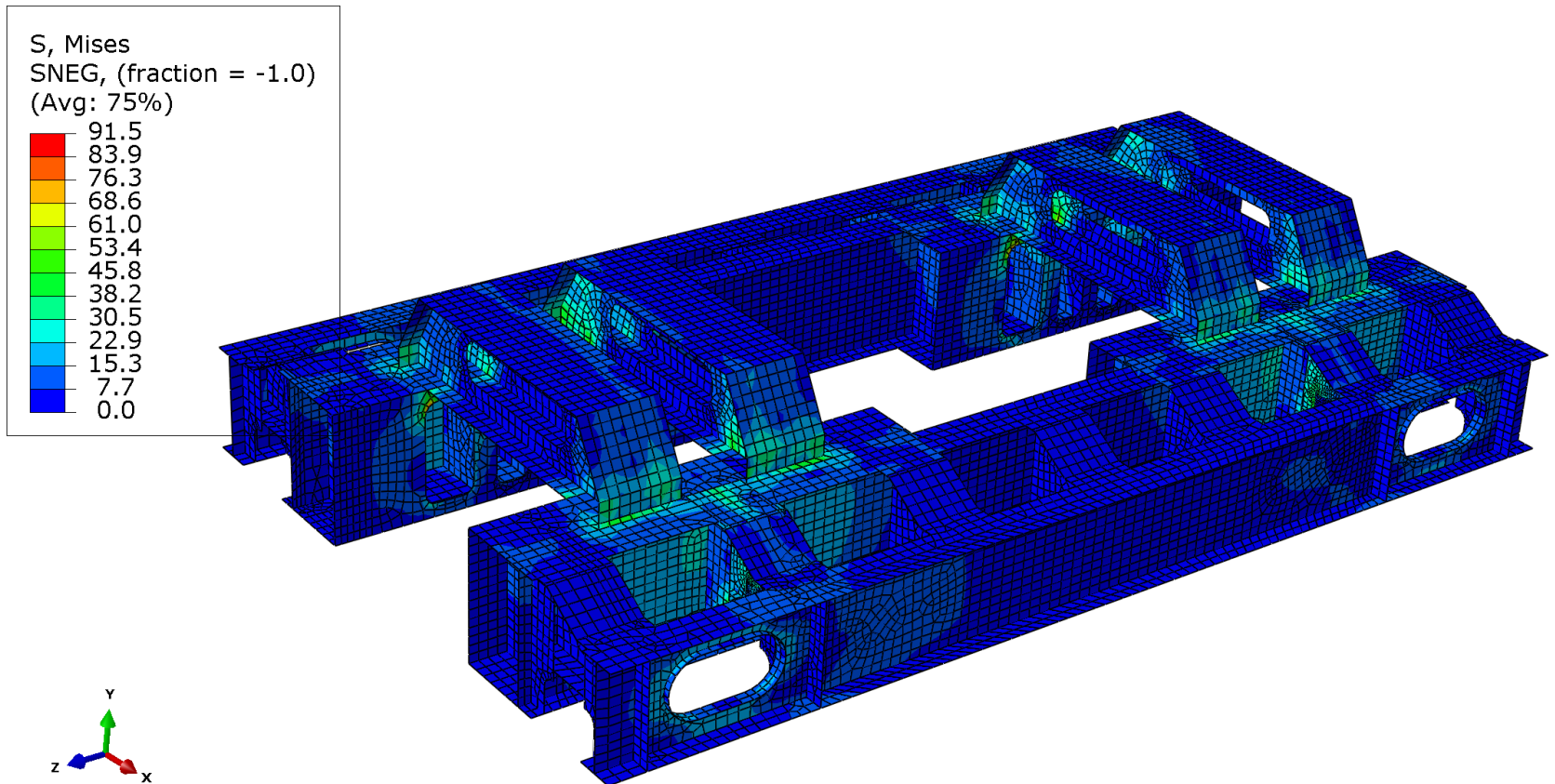
# Permanent supports on 12 pads, 8 under doors Displacement in Y direction – izo bottom view





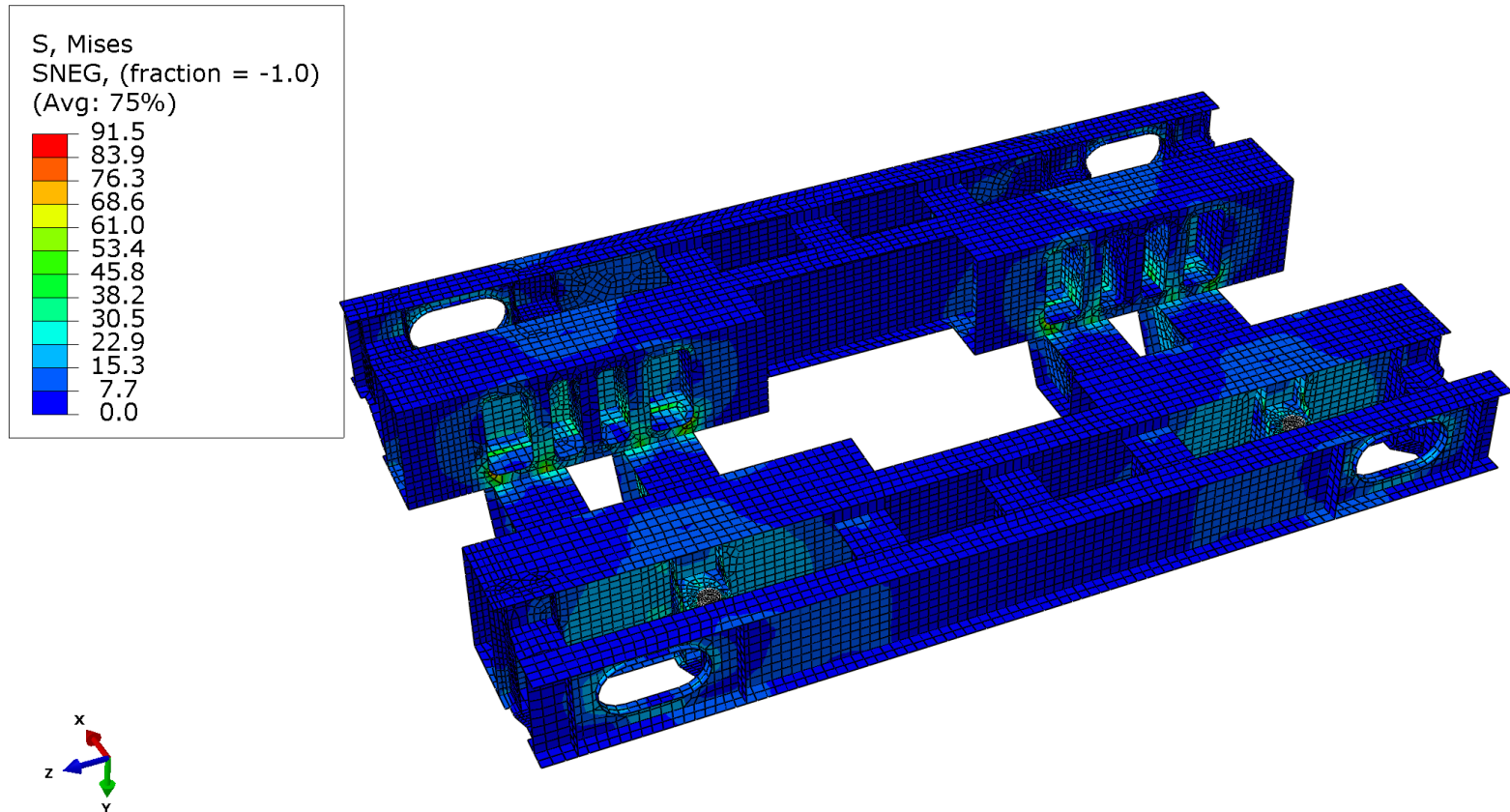
# Moving on 4 carriages, doors fixed to the yoke

## Stress von Mises – izo top view



# Moving on 4 carriages, doors fixed to the yoke

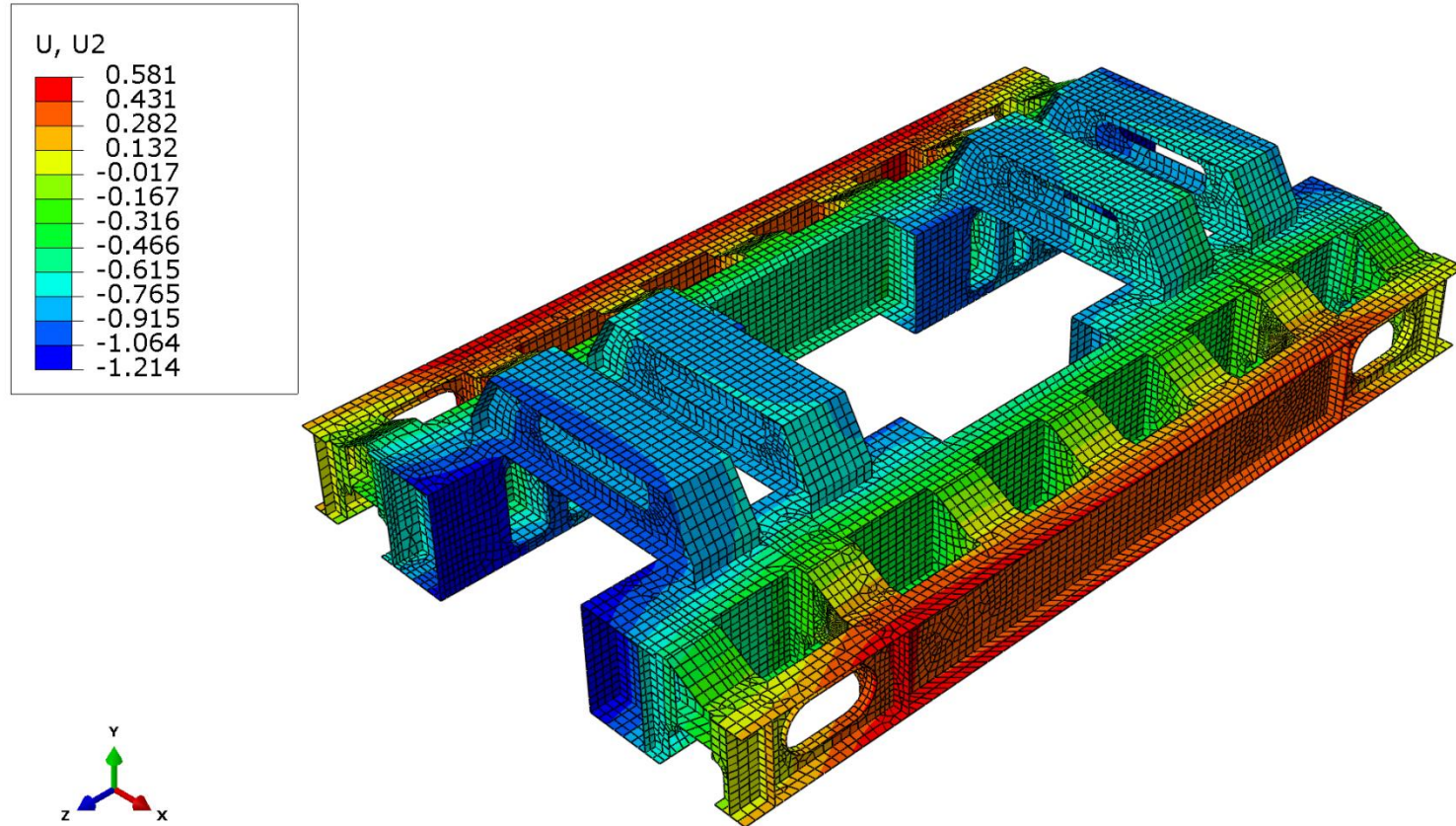
## Stress von Mises – izo bottom view



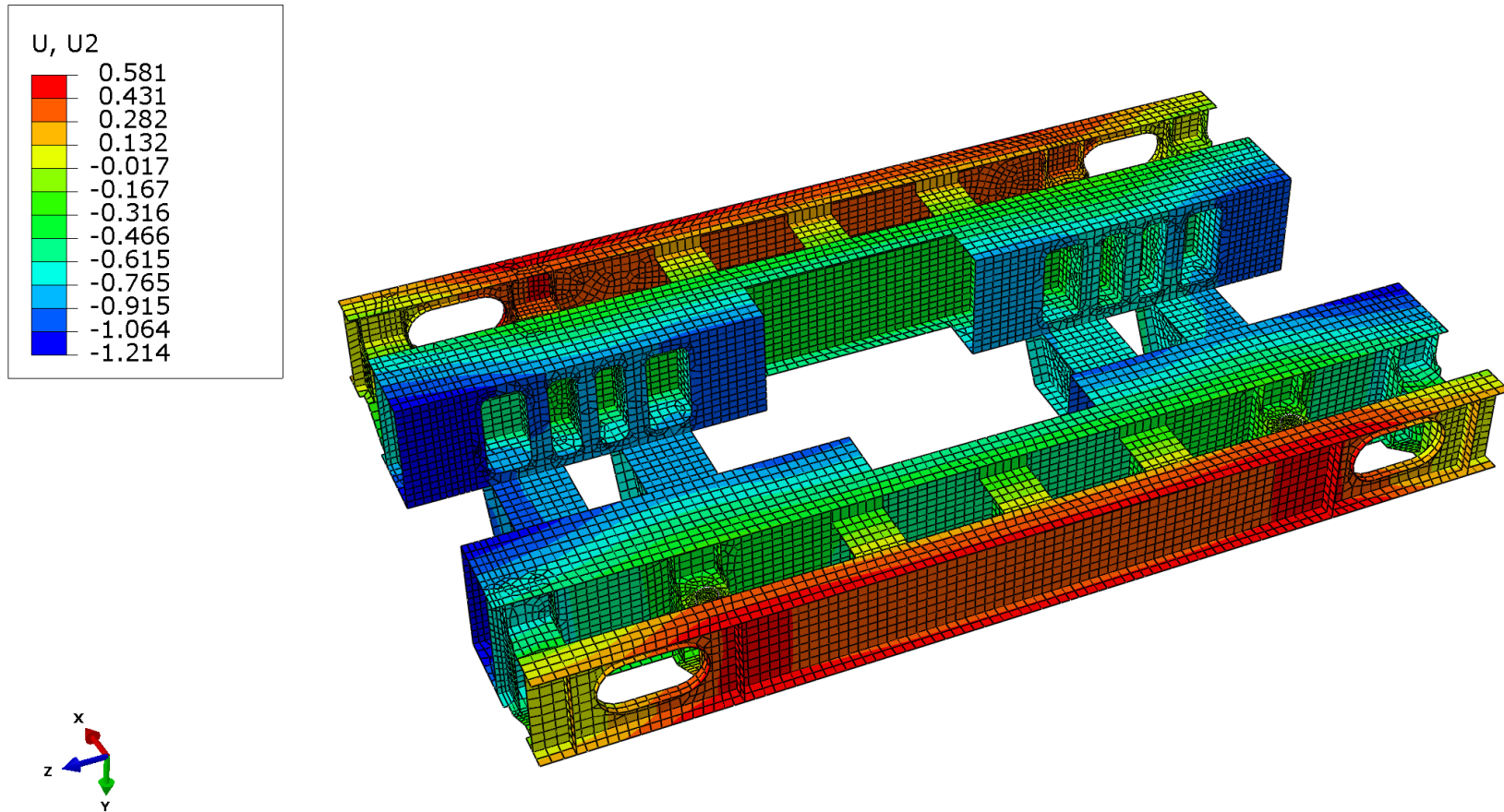


# Moving on 4 carriages, doors fixed to the yoke

## Displacement in Y direction – izo top view



# Moving on 4 carriages, doors fixed to the yoke Displacement in Y direction – izo bottom view



# Operation of device

1. Before first usage adjust the height of the platform using precise pads and hydraulic jack.
2. For the transport of the magnet from in-beam to park position lift the platform a few millimetres
3. Lock hydraulic jacks
4. Fasten the horizontal hydraulic actuators
5. Start slowly moving using hydraulic actuators to the park position.

# Resume

1. Secure level of risk about stress above 2.5
2. Magnet must be transport with closed door and fixed to the yoke
3. Very small speed of the transport, no vibrations
4. Very precise positioning and repositioning
5. The main element of the frame is I\_BEAM HEB1000 (it is standard in industry)
6. Total mas of the platform about 29 tones