FPGA helix tracking algorithm with STT

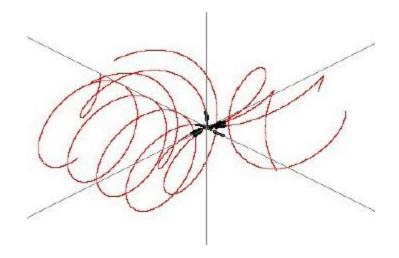
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II. Physikalisches Institut, JUSTUS-LIEBIG-UNIVERSITÄT GIESSEN Dec. 13 2011

Motivation

- Finding helix shaped tracks in the magnetic field
- ➤ Implement the algorithm on FPGA, as part of the online trigger for PANDA

Method: Using transformations to simplify calculations



Helical track \rightarrow circle in 2D (momentum $\leftarrow \rightarrow$ radius) \rightarrow straight line(by conformal transformation) \rightarrow obtain line parameters(by Hough transformation)

Based on David's previous work (using MC truth position as input), we studied the performance of the algorithm using information from STT detector.

As the first step:

Only consider the XY plan now (no stereo layers used), Study in C++ on PC.

Conformal Transformation

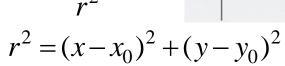
Used for projection perpendicular to the beam direction

(x,y)

Transform circles to straight lines

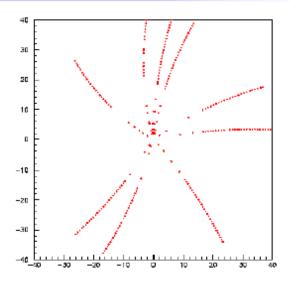
$$x' = \frac{x - x_0}{r^2}$$

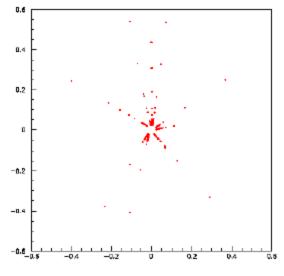
$$y' = \frac{y - y_0}{r^2}$$



Finding straight lines is less complex than finding circles

Transform circles to straight lines





Hough Transformation

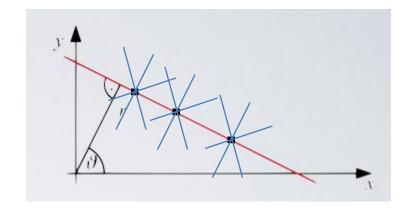
Describing points in real space by parameters

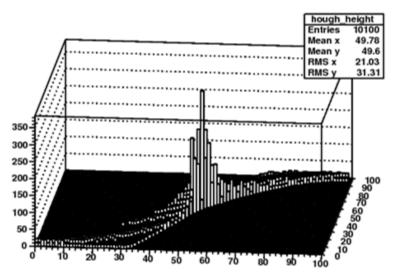
For lines:
$$y = mx + b$$

(x1, y1), (x2, y2),... \rightarrow (m,b)
or (r, θ)

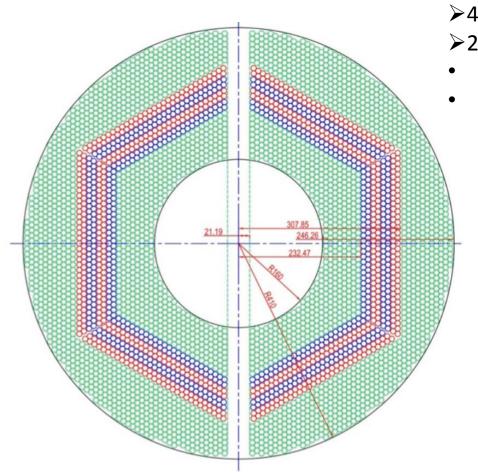
$$R = x \cos(\theta) + y \sin(\theta)$$

- ➤ Use all possible angles
- ➤ Save data in histogram
- ➤ Peaks in histogram represent possible lines in point set

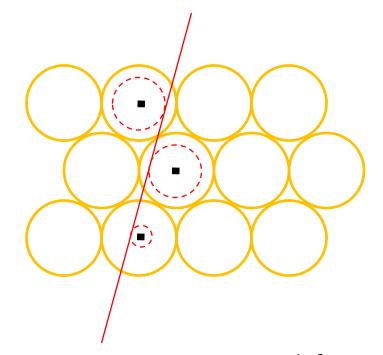




Straw Tube Tracker (STT)



- ➤ 4636 Straw tubes
- ≥23-27 planar layers
- 15-19 axial layers(green) in beam direction
- 4 stereo double-layers for 3D reconstruction, with \pm 2.89 skew angle(blue/red)



From STT: Wire position + drift time

Three cases used in this study

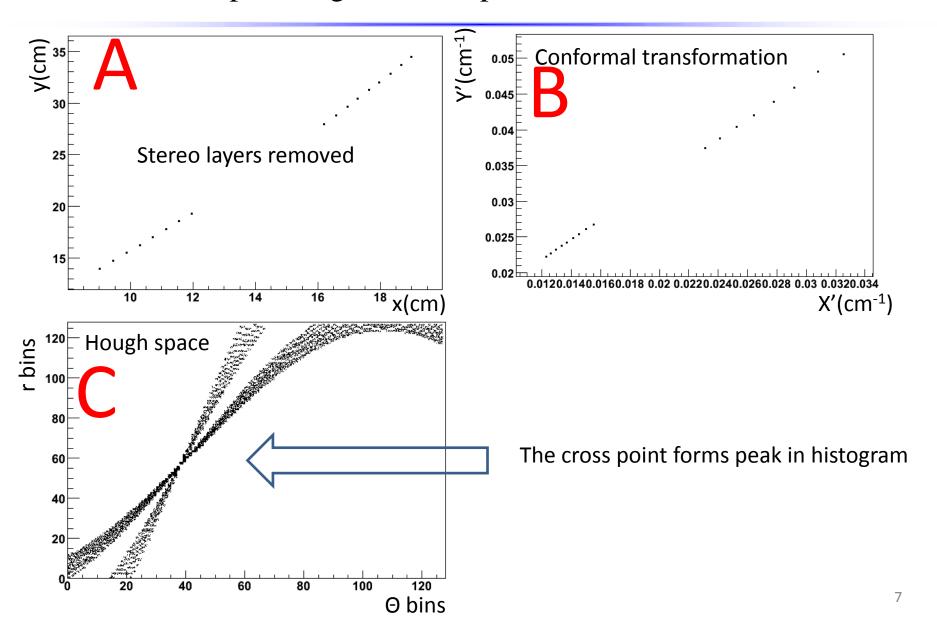
- 1. Ideal case: Use MC truth position.

 The previous algorithm uses this MC truth position as input.
- 2. Worst case: Use only wire position of STT
- 3. Realistic case: Use drift distance information from drift time.

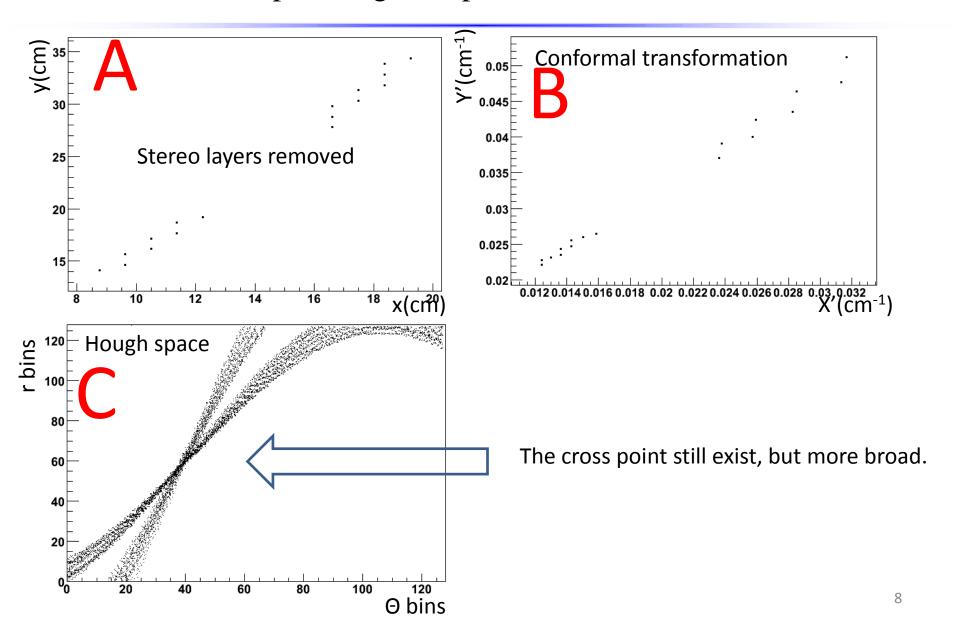
First Method A method B

Second Method

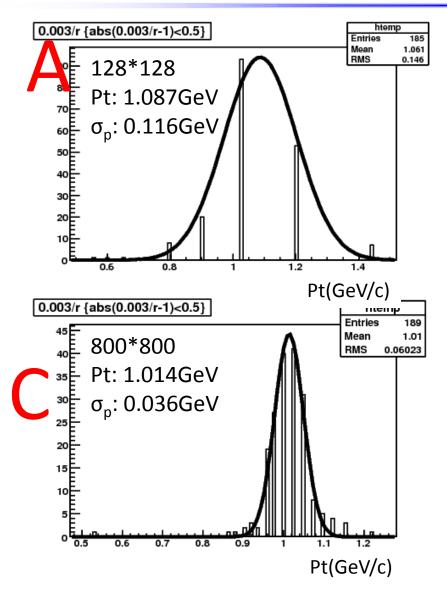
One example using MC truth position from STT – Ideal case

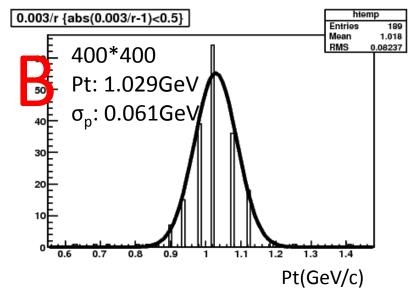


One example using wire position of STT – worst case



Momentum resolution using MC truth – varying bin size of Hough space



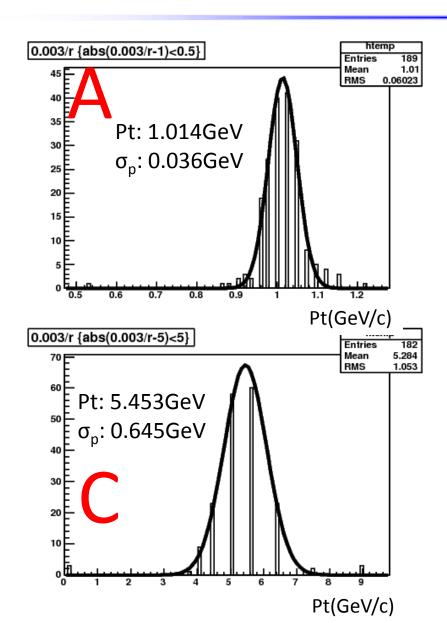


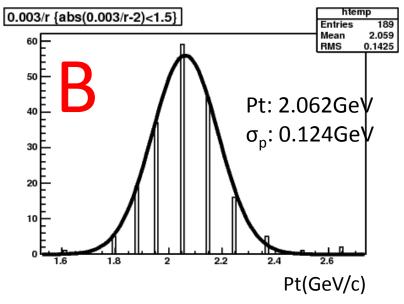
Input: single mu+, 200 events Pt: 1GeV, θ (15,120), Φ (0,360)

Using MC truth position in a straw tube.
Only pick up the highest bin in each event

The momentum resolution improves obviously using more bins.

Momentum resolution using MC truth – varying Pt





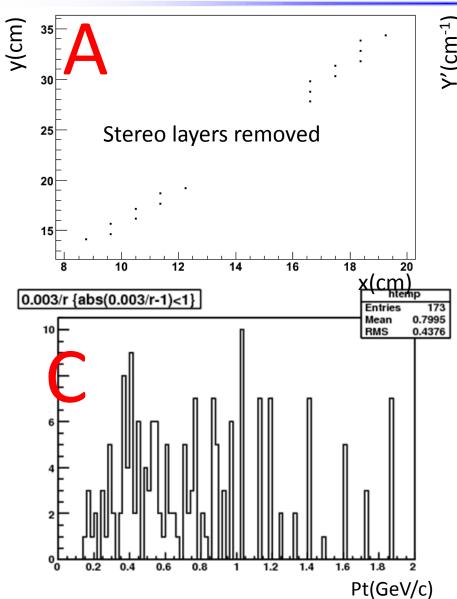
Momentum resolution:

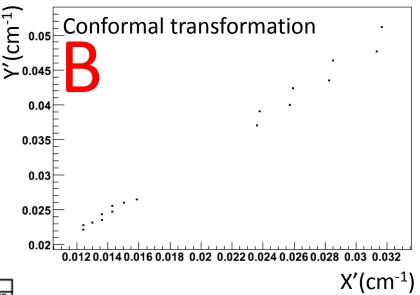
1GeV: ~3.6%

2GeV: ~6.2%

5GeV: ~12.9%

Performance of using STT information—only wire position



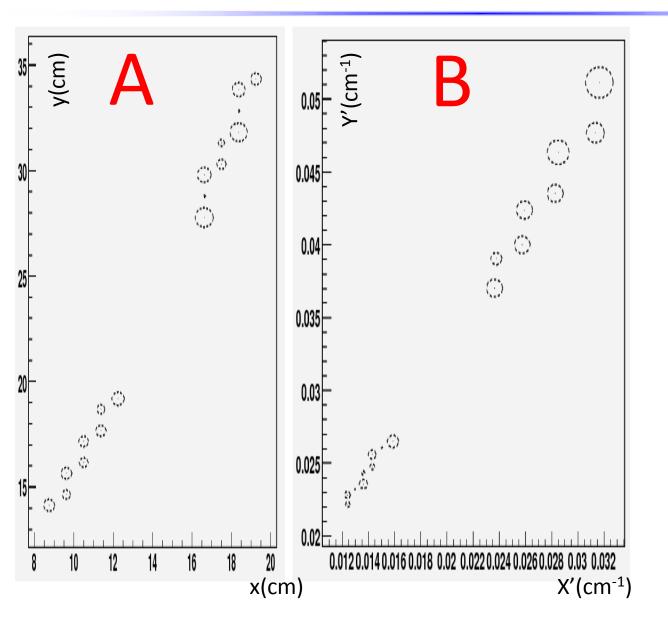


Input: single mu+, 200 events Pt: 1GeV, θ (15,120), Φ (0,360)

Using STT center position only.
Only pick up the highest bin in each event

The output momentum is too bad.

Attempt to include drift distance



Method:

(x_center, y_center) ± (drift distance)

Conformal:

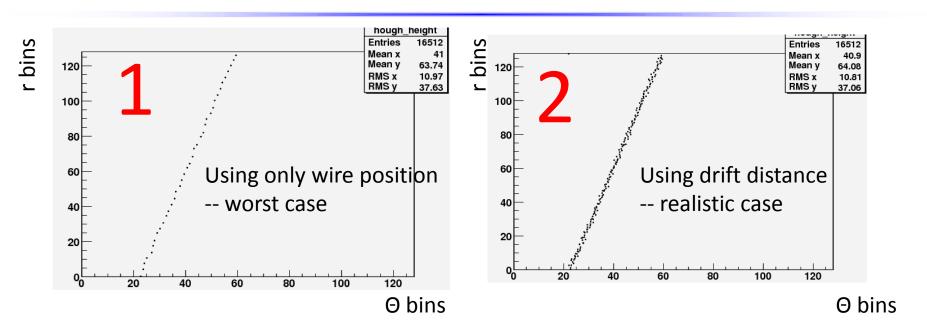
 $(x', y') \pm (error)$

Hough:

Before: Θ -> r

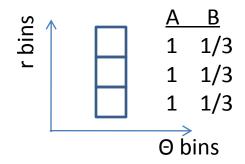
Now: $\Theta \rightarrow r \pm \Delta r$

Attempt to include drift distance

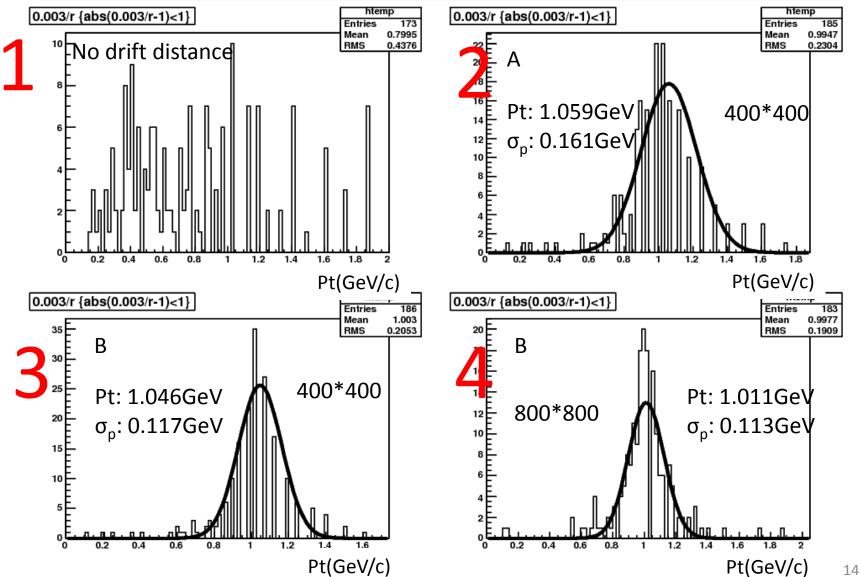


Two ways to fill the histogram:

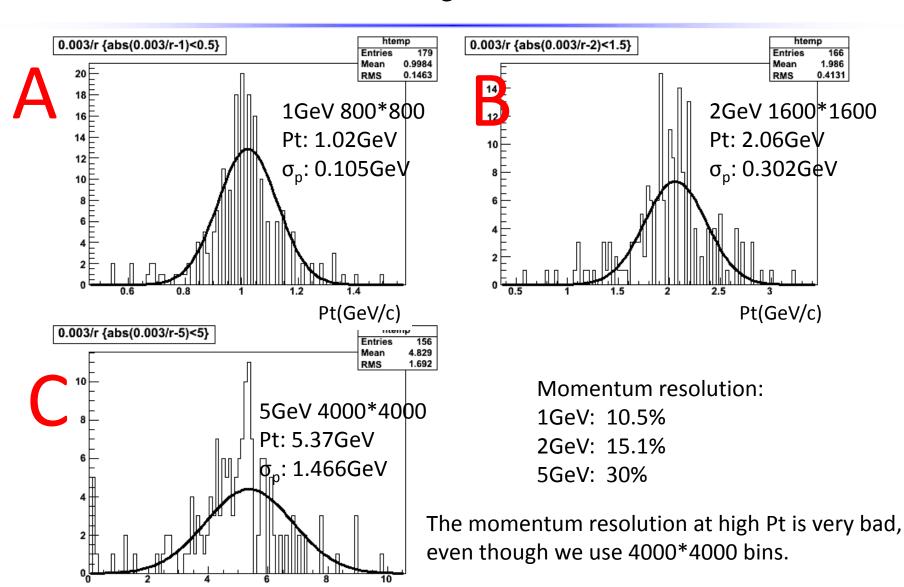
A: fill "1" to each possible (Θ, r) bin B: fill a weighted value $1/N_r(\Theta)$ to each bin possible (Θ, r) . $N_r(\Theta)$ stands for the number of r bins need to fill at Θ angle.



Different methods of using drift distance

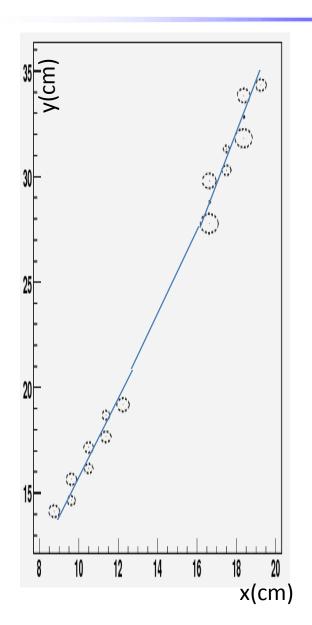


Momentum resolution using STT— drift distance method B

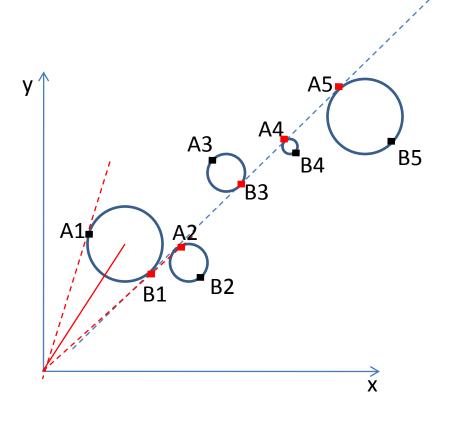


Pt(GeV/c)

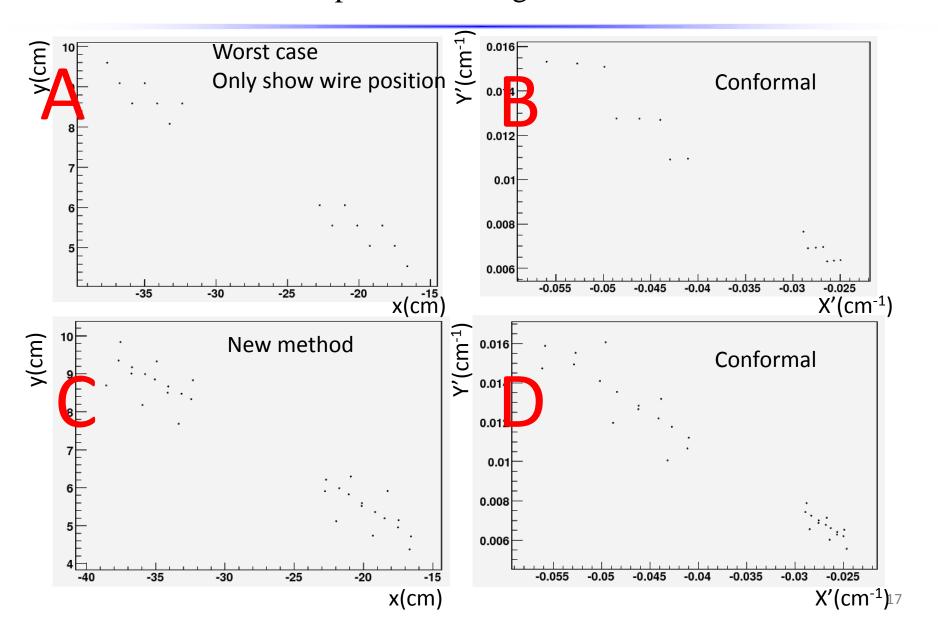
A try of new method to include drift distance



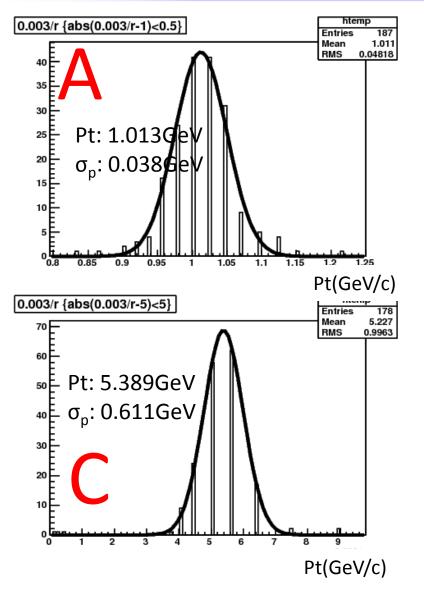
The last method: points inside the error box! The new method: points on the circle!

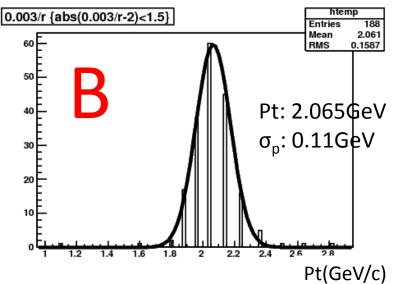


One example event using the new method



Momentum resolution using this new method



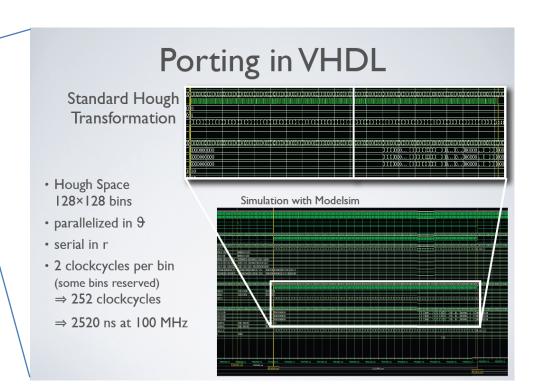


σ _p New method	First method	
1GeV: ~3.8%	Realistic 10.5%	Ideal case: ~3.6%
2GeV: ~5.5%	15.1%	~6.2%
5GeV: ~12.2%	30%	~12.9%

Status of this algorithm

David had implemented the algorithm in VHDL, in which the input is ideal positions.

The new method introduced here has only been studied in C++ on PC, to show the capability of this algorithm. We will implement this in VHDL in future.



Summary

- 1. The performance using only STT wire position is too bad.
- 2. First method: Including drift distance, filling weighted value in histogram, momentum resolution is bad.

σ_{pt}: 10% @ 1GeV, 15% @ 2GeV, 30% @ 5GeV

3. Second method: Draw tangent line from interaction point... σ_{nt} : 3.8% @ 1GeV, 5.5% @ 2GeV, 12.2% @ 5GeV

First method: depend on Vertex

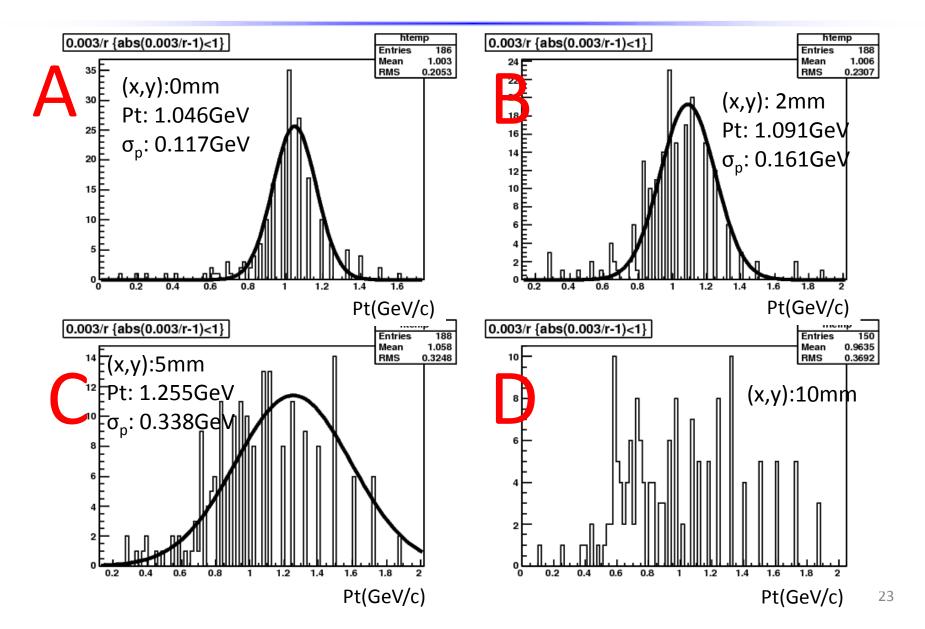
Second method: depend on Vertex, not suit for very low momentum

Next to do:

- 1. Combine MVD information to improve the momentum resolution, could also be used as vertex.
- 2. Inclusion of stereo layers. 3. Implement on FPGA

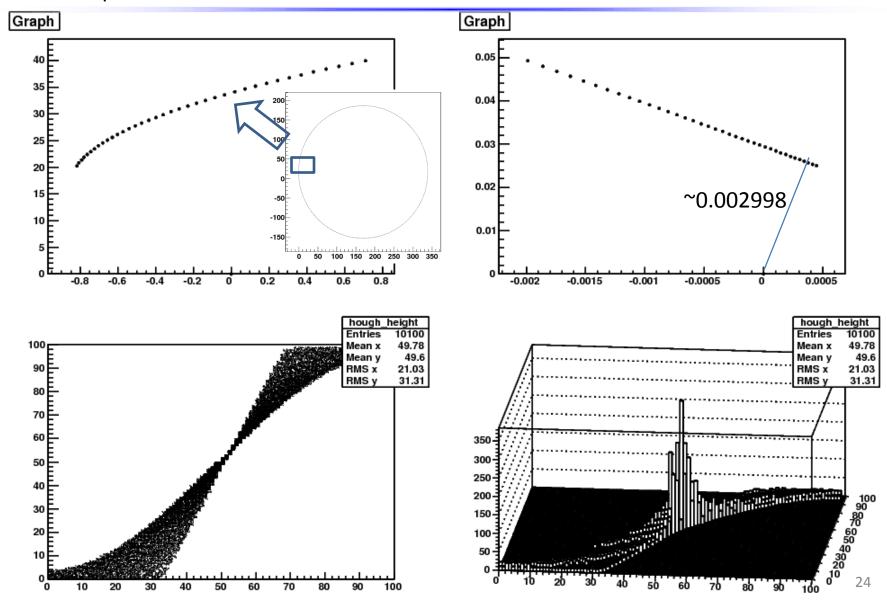
Thank you

Displaced vertex --old method



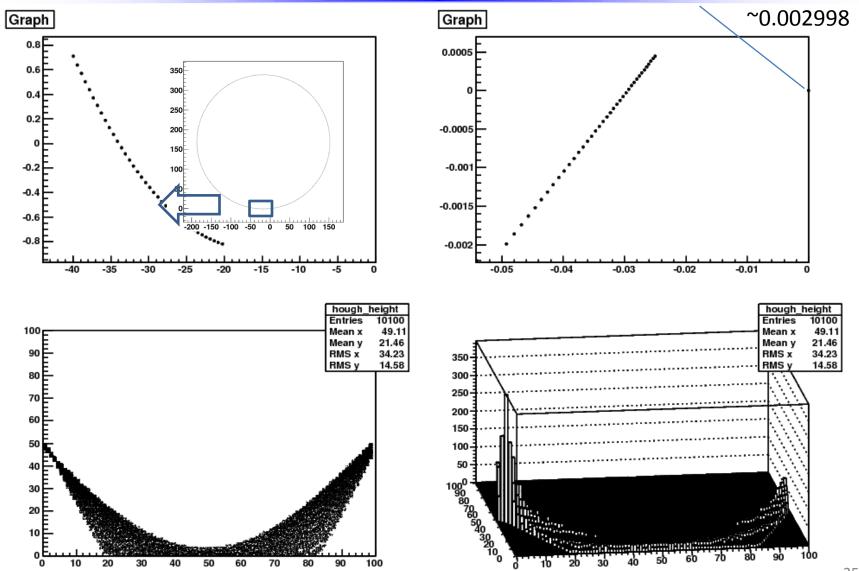
Behavior of transformations

P = 1GeV phi = 100



Behavior of transformations

P = 1GeV phi = 190



Behavior of transformations

P = 2GeV phi = 100

