#### Status of simulation Background study $(p\bar{p} \rightarrow \pi^+\pi^- \text{ and } p\bar{p} \rightarrow K^+K^-)$ New algorithm for track-finder

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# Outline

- $◇ p\bar{p} \rightarrow \pi^+\pi^-$  and  $p\bar{p} \rightarrow K^+K^-$ (simulation in phase space)
  - Description of simulation
  - Results (and comparison with  $\bar{p}$  signal)
- Cellular Automaton as Track Finder
  - Introduction in Algorithm
  - Toy simulation
  - Implementation in PANDAROOT and results

Simulation with **EvtGen**: **PHSP**(phase space model)  $P_{beam} = 8.9 \text{ GeV/c}, \theta \in (0,\pi) \text{ rad}, \phi \in (0,2\pi) \text{ rad}.$  $10^6 \text{ events}$ 



track-candidates: **789** after cuts for  $(\theta, \phi)_{trk-cand}$ : **334 (0.03%)** 

In back-propagation usual assumption for particle is used ( $\bar{p}$  and  $P = P_{beam}$ )

#### Results

Most of reconstructed particles are  $\pi^-$  (4 tracks from  $\mu^-$ )



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9 9.5 P<sub>MC</sub>,GeV/c

0.012

θ<sub>MC</sub>,rad

#### Comparison results for $\bar{p} \& \pi^{-}$ signal



Distribution for  $\pi^-$ : shifted in X-coordinate and wider in Z-coordinate, but for Y-coordinate looks similar to  $\bar{p}$  distribution.

#### Correct study for nonpoint-like beam is needed! (Include beam/target size and beam emittance)

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### Conclusion

- $p\bar{p} \rightarrow \pi^+\pi^-$  and  $p\bar{p} \rightarrow K^+K^-$  were simulated with EvtGen(**PHSP**)
- Due to wrong assumption for back-propagation (particle momentum) is possible distinguish such background from signal (for point-like beam)

#### Plans

- Model for real cross-section is needed (generator  $p\bar{p} \rightarrow \pi^+\pi^-$ : M. Zambrana & D.Khaneft)
- Study with beam structure

#### Cellular Automation as a Track Finder

- A cellular automation for track search successfully used for HERA-B experiment at DESY and as algorithm for hardware trigger for CBM experiment at GSI.
- Authors claim high speed and stability of this algorithm in comparison to any other simple algorithms of track searching.
- Aim of this study:
  - Check it for our case
  - Compare cellular automation with standard track finder for the luminosity monitor



 Cell is a segment connecting two hits in neighboring layers. For taking into account inefficiencies (dead strips and so on) one can build cell skipping over one layer.



# Neighbors

 Cells with common point can be considered as neighbors. (track is a straight line -> additional requirement for bend angle of track line in middle point between two cells)



Instead of minimal bend angle -> requirement for distance between common point and line between extremities of cells ( $d_{max}$ ).

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#### Position value of cell



During evolution position value (**pv**) (an integer number) for each cell characterize its position on the track. In the beginning all cells have **pv** equal 1.

#### Position value of cell



In each step of evolution cell looks on neighbors in the previous layers and increase its **pv** by unit one if there is neighbor with the same **pv**.

#### Position value of cell



The evolution stops if there is no more neighbors with the same **pv**.

- All cells changing their states simultaneously.
- Track candidates are build from cell with the highest pv, adding its neighbor with (pv-1) and so on.

# Test with Toy Simulation

(conditions close to real design of the luminosity monitor)

- ♦ Tracks start from point (0,0,0) with uniformly distributed angles  $\phi \in (0, 20^\circ)$  and  $\theta \in (0.23^\circ, 0.45^\circ)$
- ◊ Hits are build at z = 1100, 1110, 1120, 1130 cm.
- For taking into account multiple scattering effect each hit has different error respectively to plane position ( $\sigma$ ={10, 31, 71 or 119}  $\mu$ m)



# Determination $d_{max}$



It's reasonable to set  $d_{max} = 20 \mu m$ .

# Efficiency

$N_{trk}$	$N_{rec}$	%(of total)	$N_{good}$	%(of total)
1	1	100	1	100
5	5	99.1	4	0.9
			5	98.2
	6	0.1	4	0.1
	7	0.1	4	0.1
	8	0.2	4	0.2
	9	0.4	4	0.4
	11	0.1	4	0.1

## Test with Toy Simulation(Noise)

Noise hits are uniformly distributed  $(X \in [4, 9]cm, Y \in [0, 4]cm)$ 



# Efficiency (with noise)

$N_{trk}$	$N_{rec}$	%(of total)	$N_{good}$	%(of total)
1	1	99.8	1	99.8
	2	0.2	1	0.2
5	4	0.1	4	0.1
	5	98.5	4	1.1
			5	97.4
	6	0.9	5	0.9
	7	0.2	4	0.2
	10	0.2	4	0.2
	11	0.1	4	0.1

New class **PndLmdTrackFinderCATask** with the same interface like **PndLmdTrackFinderTask** 



 $d_{max}$ =20  $\mu$ m.

Simulation: 5  $\bar{p}$ ,  $P_{beam}$ =1.5 GeV/c (928 events with 5 tracks = 4640 tracks)





• ghost tracks: 0.8% for CA 3% for TF



For 3 (and more) tracks per event "track-following" algorithm is faster.

#### Reduction number of cells with $\Delta \phi \& \Delta \theta$ requirements



cut:  $\phi \in$  (-0.3, 0.3) rad



cut:  $\theta \in$  (0.025, 0.055) rad



Cellular Automation Track-Following

# Conclusion

- Cellular Automation was tested in Toy Simulation
- and implemented in PANDAROOT
- For high density of tracks Cellular Automation algorithm has higher efficiency and less number of ghost tracks compare to track-following algorithm
- But speed is not extremely higher

#### Plans

- Extend algorithm for case with missing plane(s)
- Speed optimization (rewriting software code)

Simulation with **EvtGen**: **PHSP**(phase space model)  $P_{beam} = 8.9 \text{ GeV/c}, \theta \in (0,\pi) \text{ rad}, \phi \in (0,2\pi) \text{ rad}.$  $10^6 \text{ events}$ 

```
track-candidates:

695

after cuts for (\theta, \phi)_{trk-cand}:

341 (0.03%)
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In back-propagation usual assumption for particle is used ( $\bar{p}$  and  $P = P_{beam}$ )

#### Results

#### All of reconstructed particles are $K^-$



### Comparison results for $\bar{p} \& K^-$ signal



Distribution for  $K^-$ : shifted in X-coordinate and wider in Z-coordinate, but for Y-coordinate looks similar to  $\bar{p}$  distribution.

#### Correct study for nonpoint-like beam is needed! (Include beam/target size and beam emittance)

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#### Background study: Cut for track-candidates



