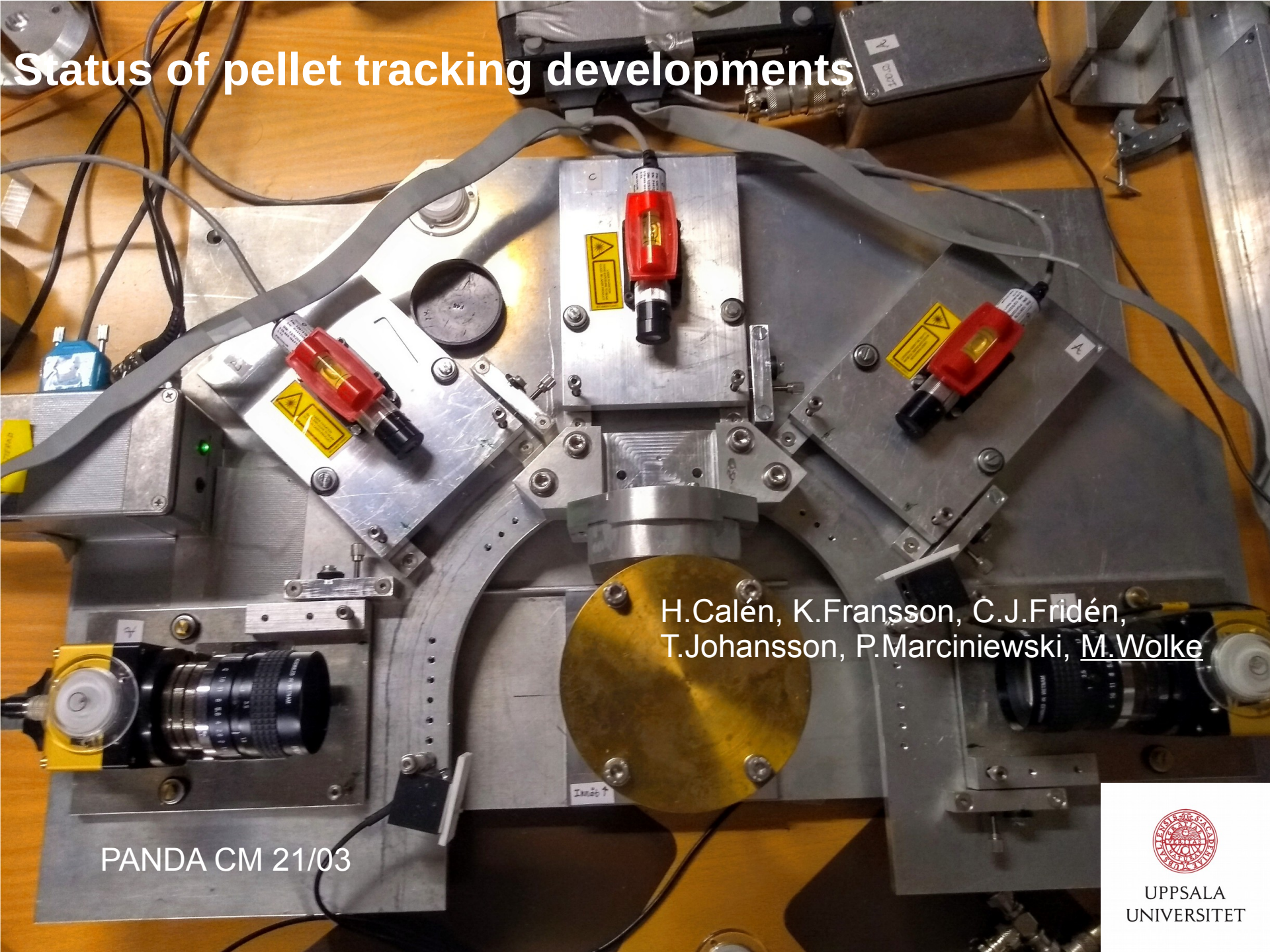


Status of pellet tracking developments



H.Calén, K.Fransson, C.J.Fridén,
T.Johansson, P.Marciniewski, M.Wolke

PANDA CM 21/03



UPPSALA
UNIVERSITET

Pellet tracking

The pellet tracking system for PANDA is based on line-scan CCD cameras and diode lasers configured in several measurement positions.

It is designed to provide:

- **individual pellet positions ($\sigma \approx 0.1$ mm)** at a hadronic event
- **useful information for ≈ 90 % of the hadronic events**

The tracking system is separated (geometrically, mechanically, electronically etc.) **from target generator and target dump.**

The tracking system can also be used as a monitoring system together with any target generator, but only with pellet target in **“Pellet Tracking mode”** operation it can provide useful tracking info.

For pellet **“Pellet High Luminosity mode”** and for Cluster-Jet, it mainly could provide stream (jet) position, shape and time structure info.

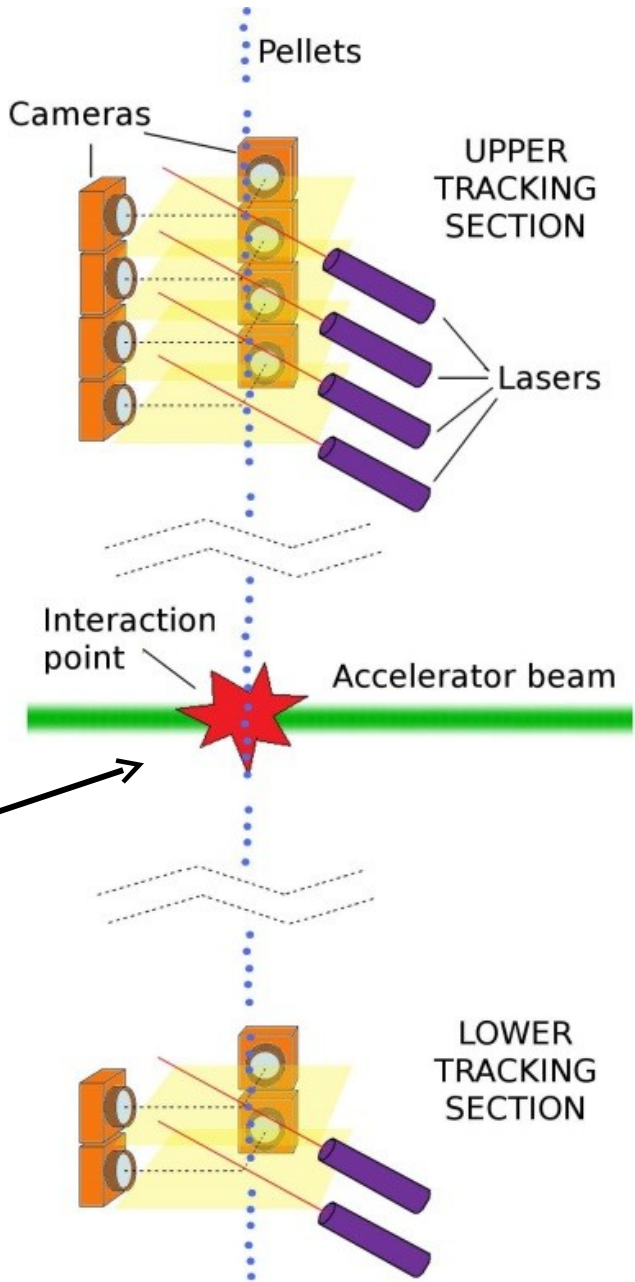


Detection configuration, multi-camera operation, readout and fast track finding algorithms are being developed at UU.

Pellet tracking

- laser beams with a horizontal beam line profile of 3 mm width and 50 μm height.
- line-Scan CCD cameras taking one line of 512 pixels, size $35 \times 35 \mu\text{m}^2$, at 100 kHz frequency.
- The camera line of sight and the beam line profile of the laser must coincide within 10 μm .
- A pellet measurement accuracy of 20 μm .

Position of a pellet in the interaction region can be reconstructed with a precision of 0.1 mm

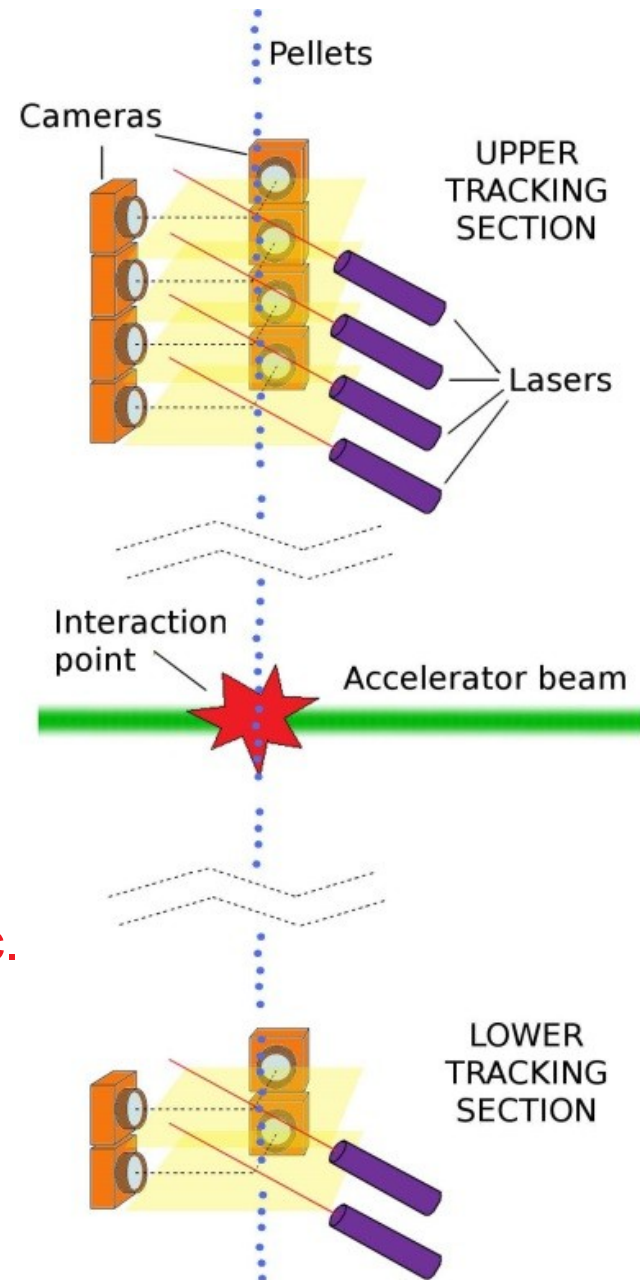


Pellet tracking

- laser beams with a horizontal beam line profile of 3 mm width and 50 μm height.
- line-Scan CCD cameras taking one line of 512 pixels, size $35 \times 35 \mu\text{m}^2$, at 100 kHz frequency.
- The camera line of sight and the beam line profile of the laser must coincide within 10 μm .
- A pellet measurement accuracy of 20 μm .

Alignment crucial! Has to be stable against

- mounting at the target chamber
- mechanical vibrations, temperature effects etc.



Pellet tracking

Equipment and procedures have been developed* so that the complete measurement level system can be (fine) tuned offline and then be securely installed at the tracking section of the target pipe.

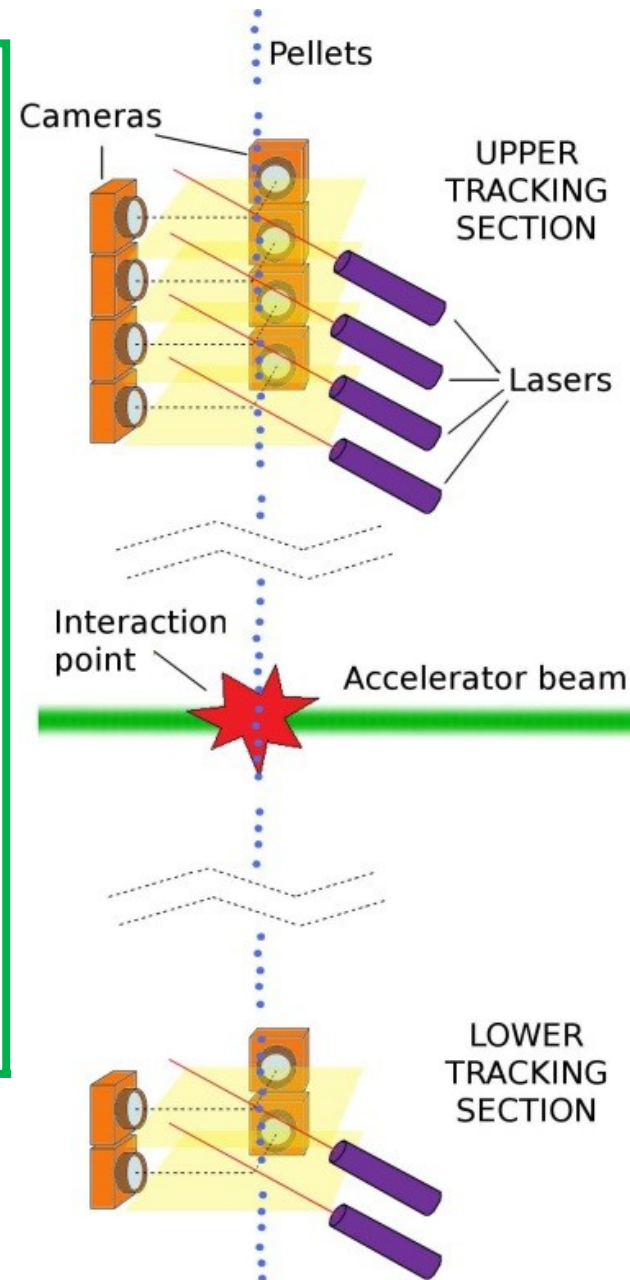
It then maintains its performance during the experimental conditions without need for further manipulation (continuous easy access).

*) **Master thesis Jenny Regina:**

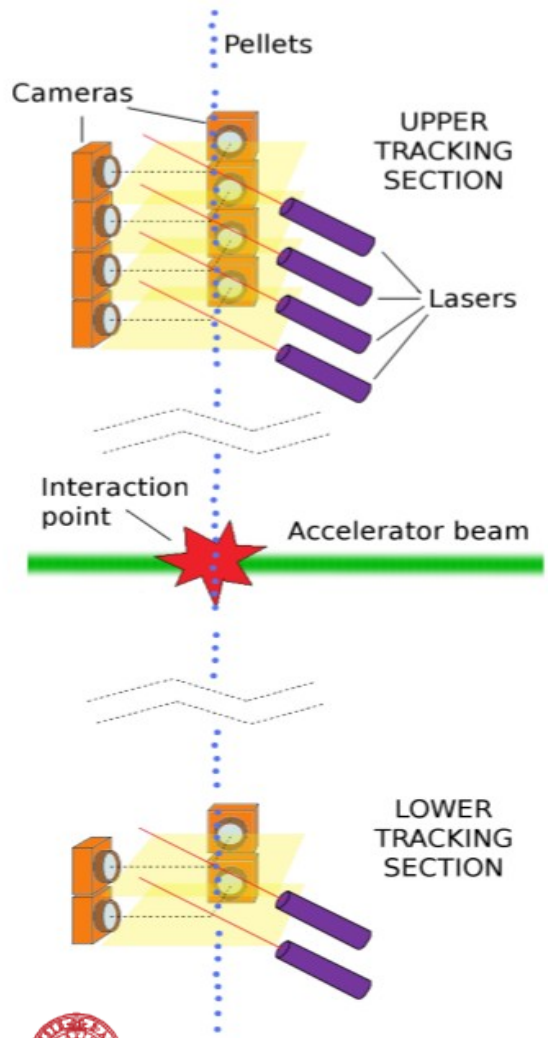
A measurement level module for a pellet tracking system (Feb 2017)

*) **Project report Dagmar Engelke:**

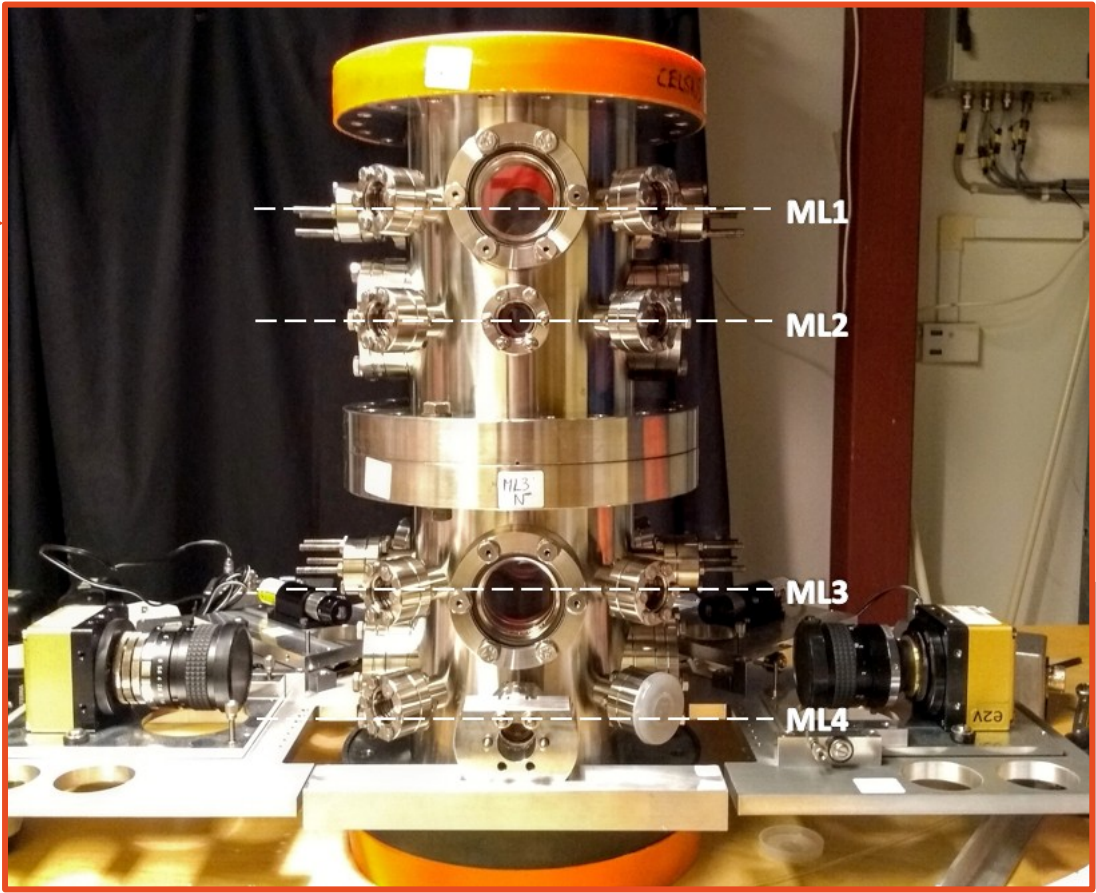
A hydrogen pellet tracking system (Jan 2020)



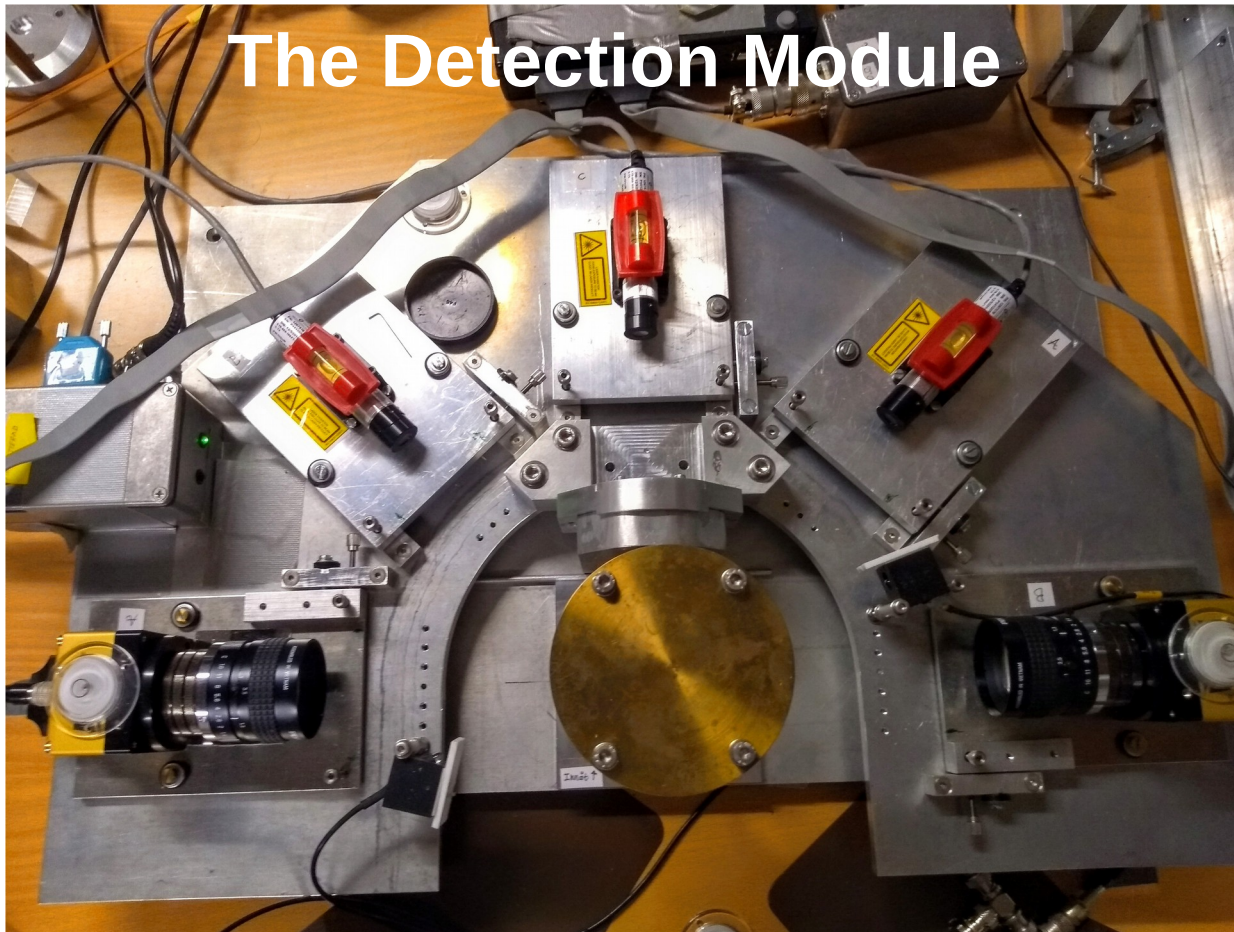
The pellet tracking section



from: D.Engelke, project report (2020)



4 measurement levels M1..4
each equipped with one
Detection Module

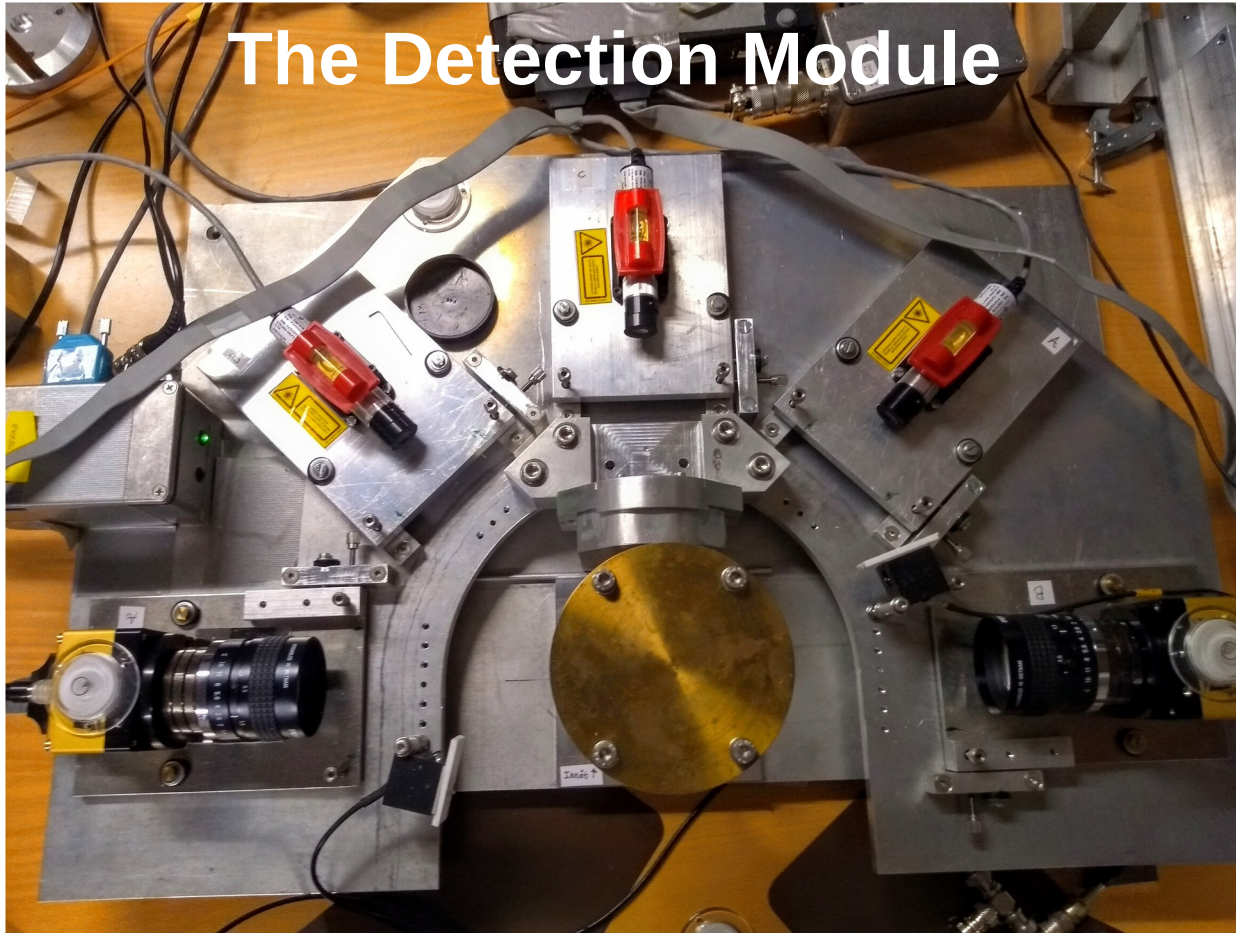


D.Engelke,
project report
(2020)

**each detection module
equipped with
3 lasers, 2 CCD cameras**

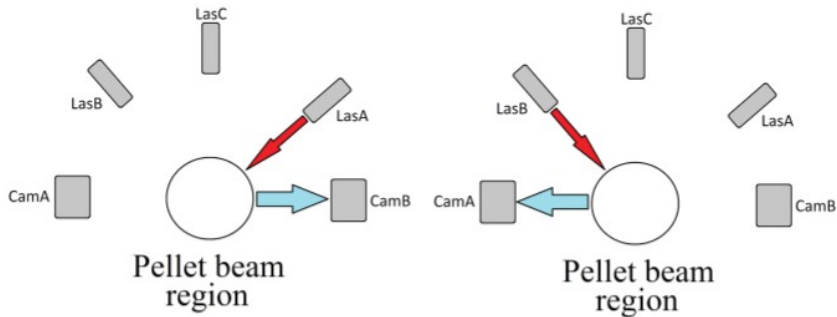
Note: a prototype measurement level DM was tested successfully earlier (2016) under real conditions with pellets.

The Detection Module

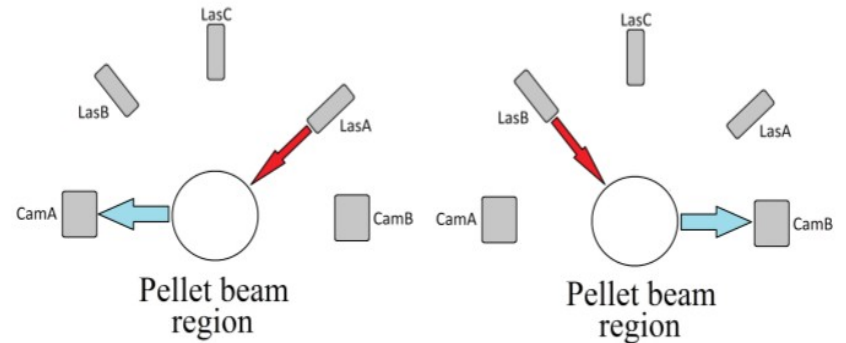


D.Engelke,
project report
(2020)

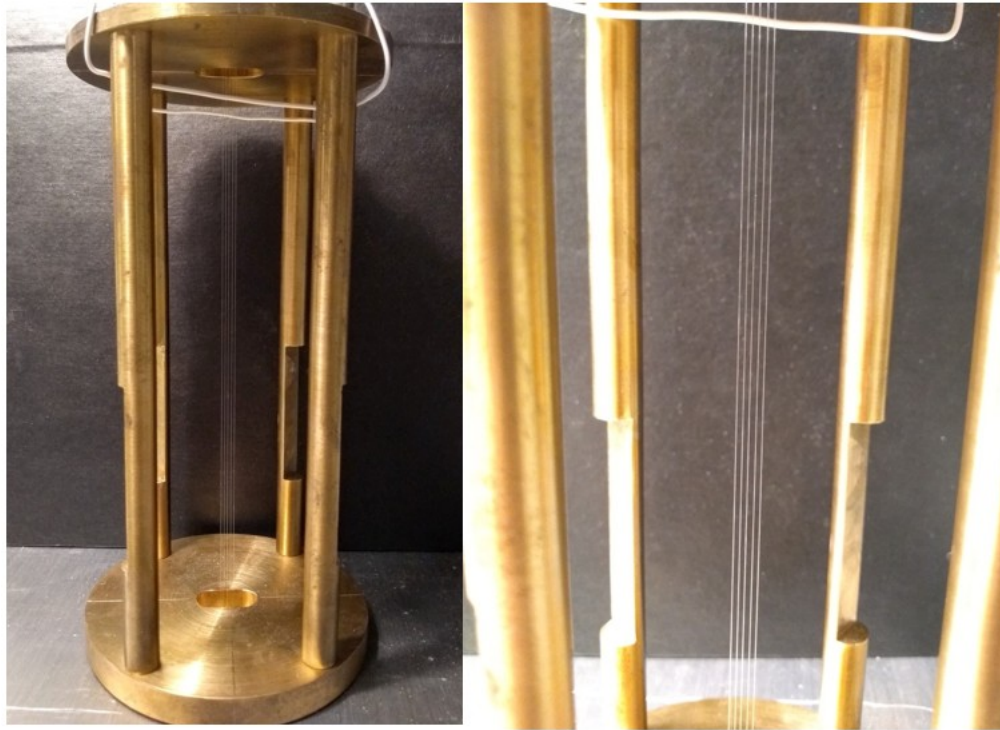
Reflected Light



Refracted Light



Zoom into the pellet beam region...



1

or

5

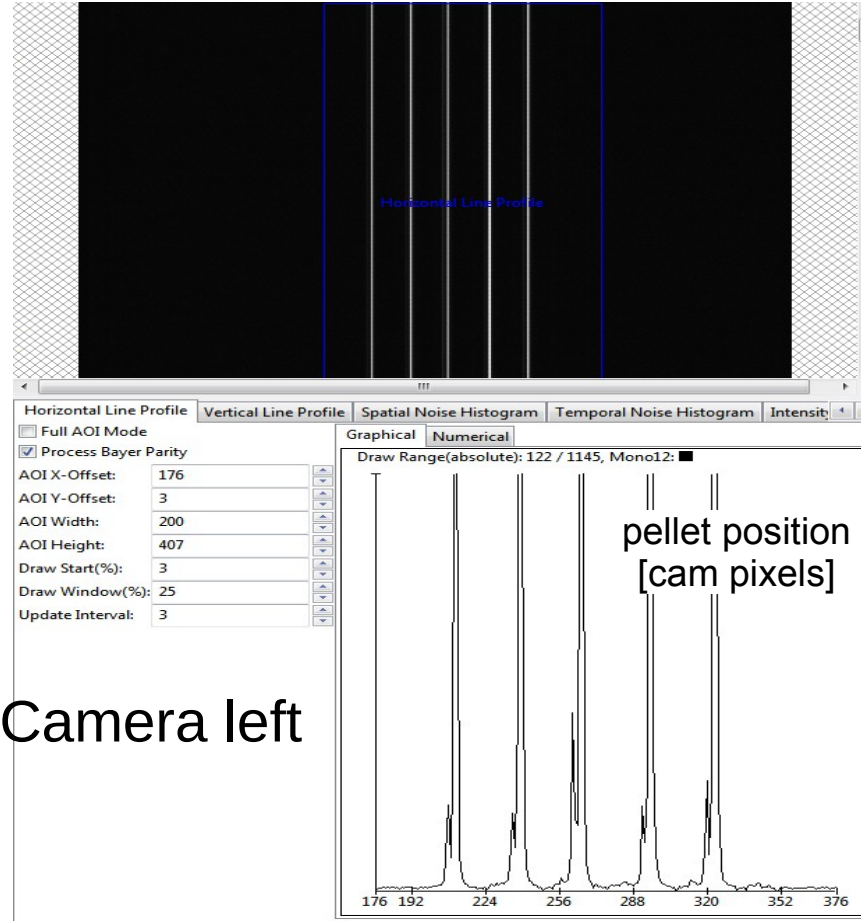
0,08 mm fishing lines



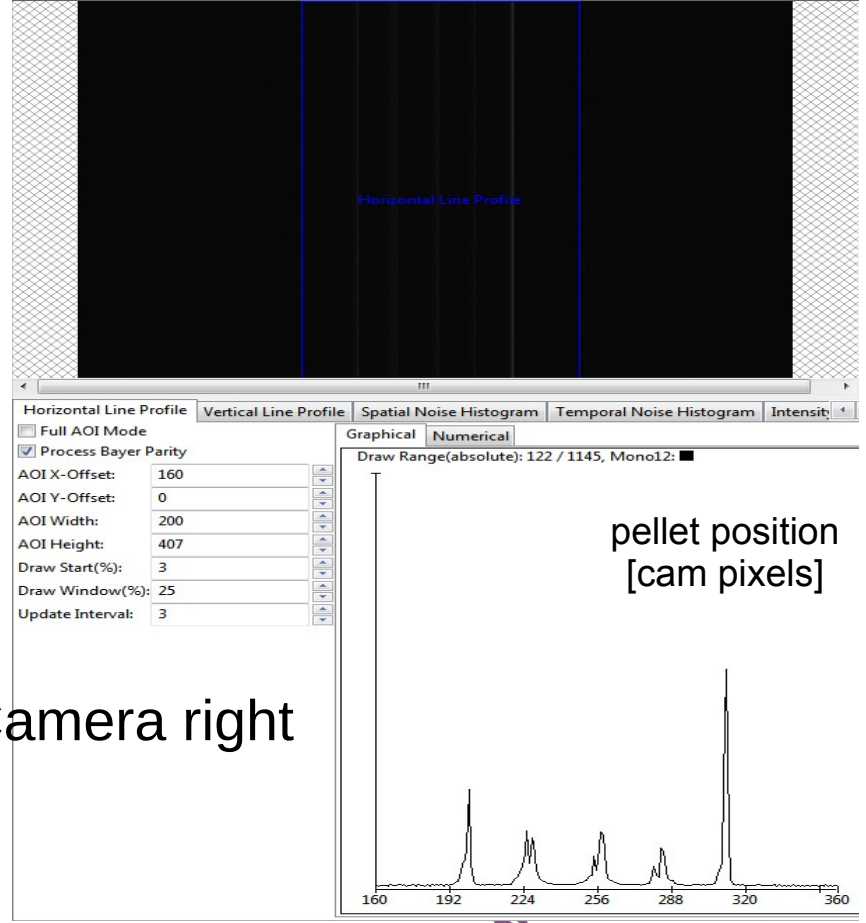
Camera and laser alignment at DM

refractions...

...and reflections



Camera left

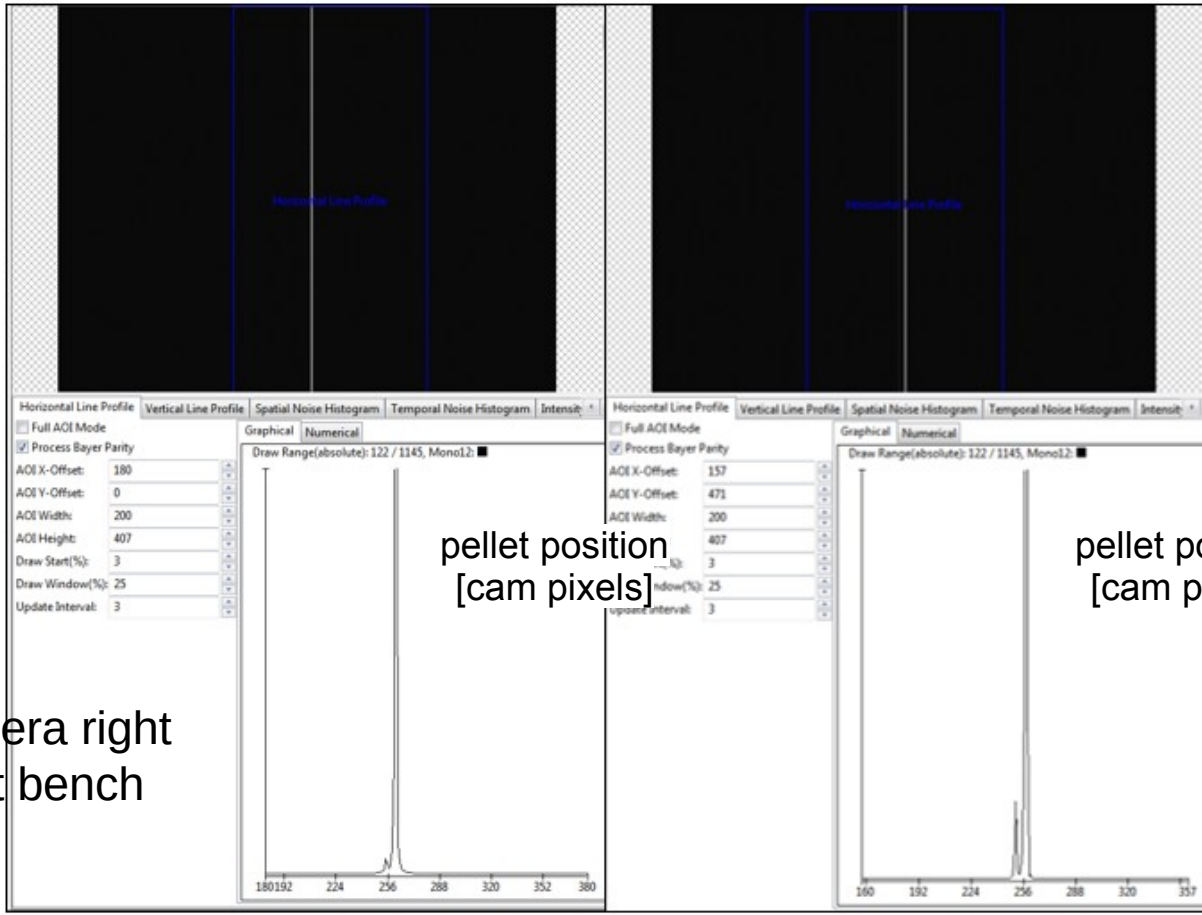


Camera right

Alignment on test bench and tracking chamber

test bench...

...and tracking chamber



no effect of
- mounting at the tracking chamber
- glass windows

Camera right test bench

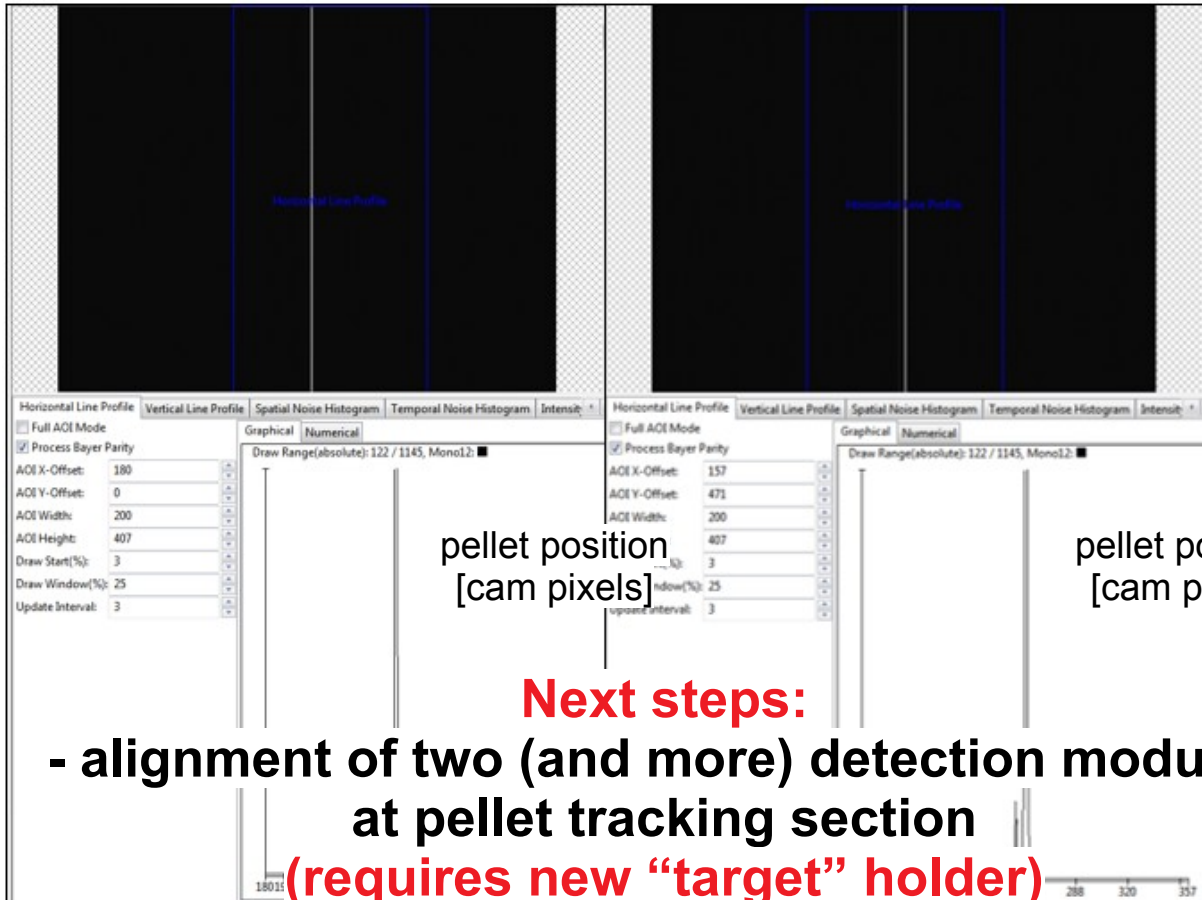
Camera right tracking chamber

➔ Alignment on the detection module can be kept stable when mounting at the target chamber

Alignment on test bench and tracking chamber

test bench...

...and tracking chamber



no effect of
- mounting at the tracking chamber
- glass windows

Next steps:

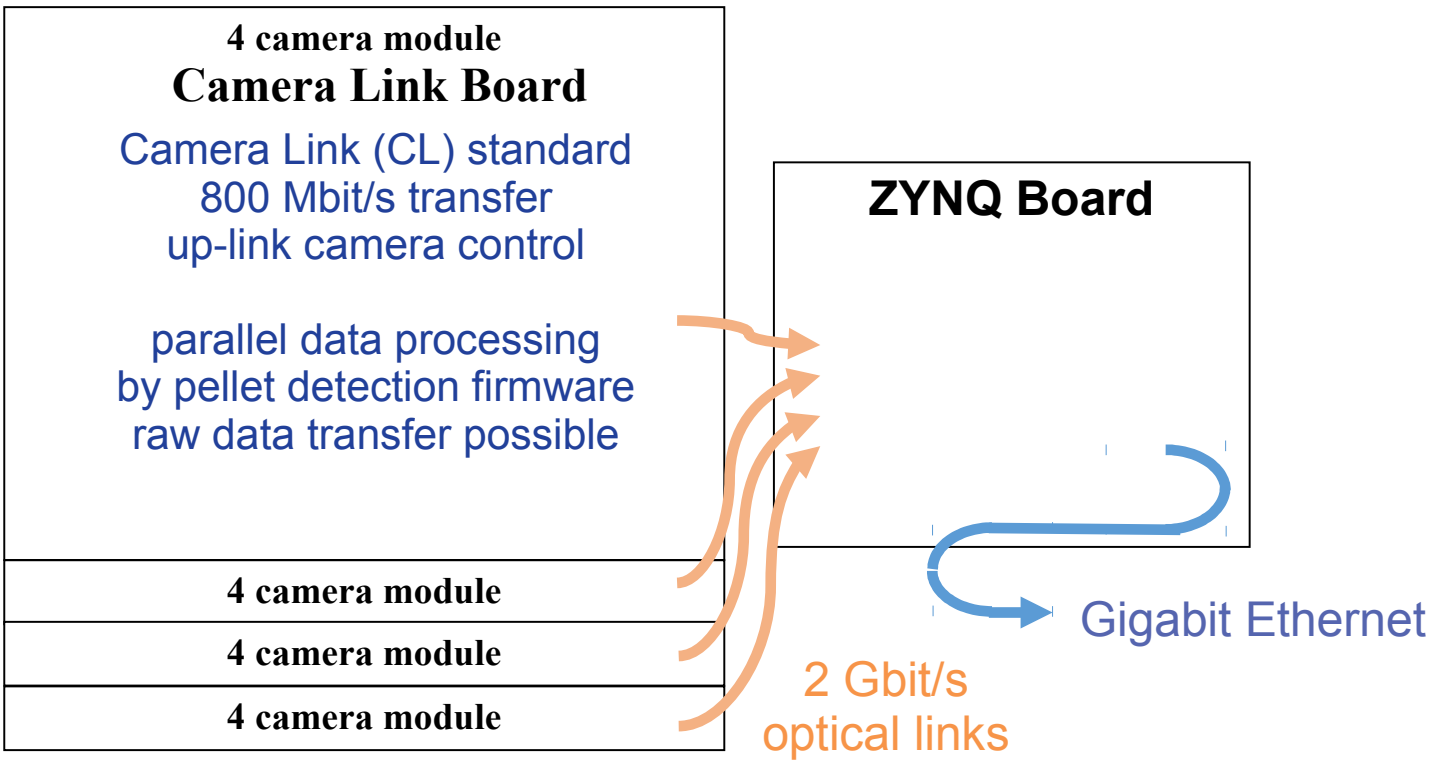
- alignment of two (and more) detection modules at pellet tracking section (requires new "target" holder)
- system test with two (and more) detection modules with pellet operation (requires sync/readout and pellet operation)

Readout and data acquisition

presently: readout, data transfer from CamLink to ATLB and VME

ATLB/Optical Data Collection for VME, Internal report, P. Marciniewski (2013)

foreseen: readout, data transfer from CamLink to ZynqBoard



Readout and data acquisition

4 camera module Camera Link Board

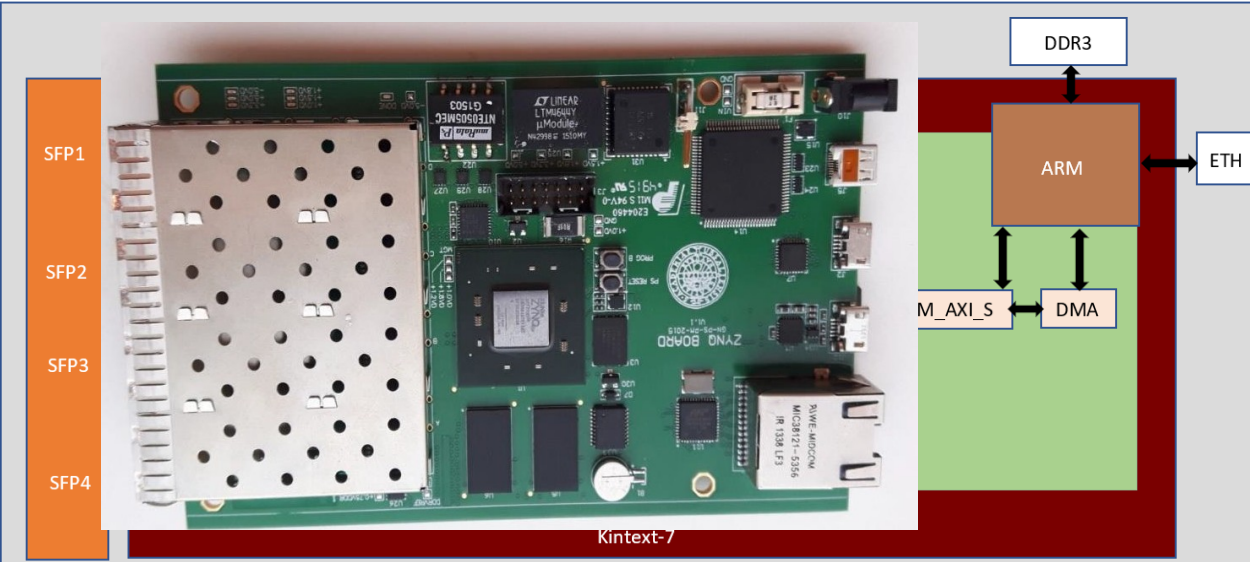
Camera Link (CL) standard
800 Mbit/s transfer
up-link camera control

parallel data processing
by pellet detection firmware
raw data transfer possible

4 camera module

4 camera module

4 camera module



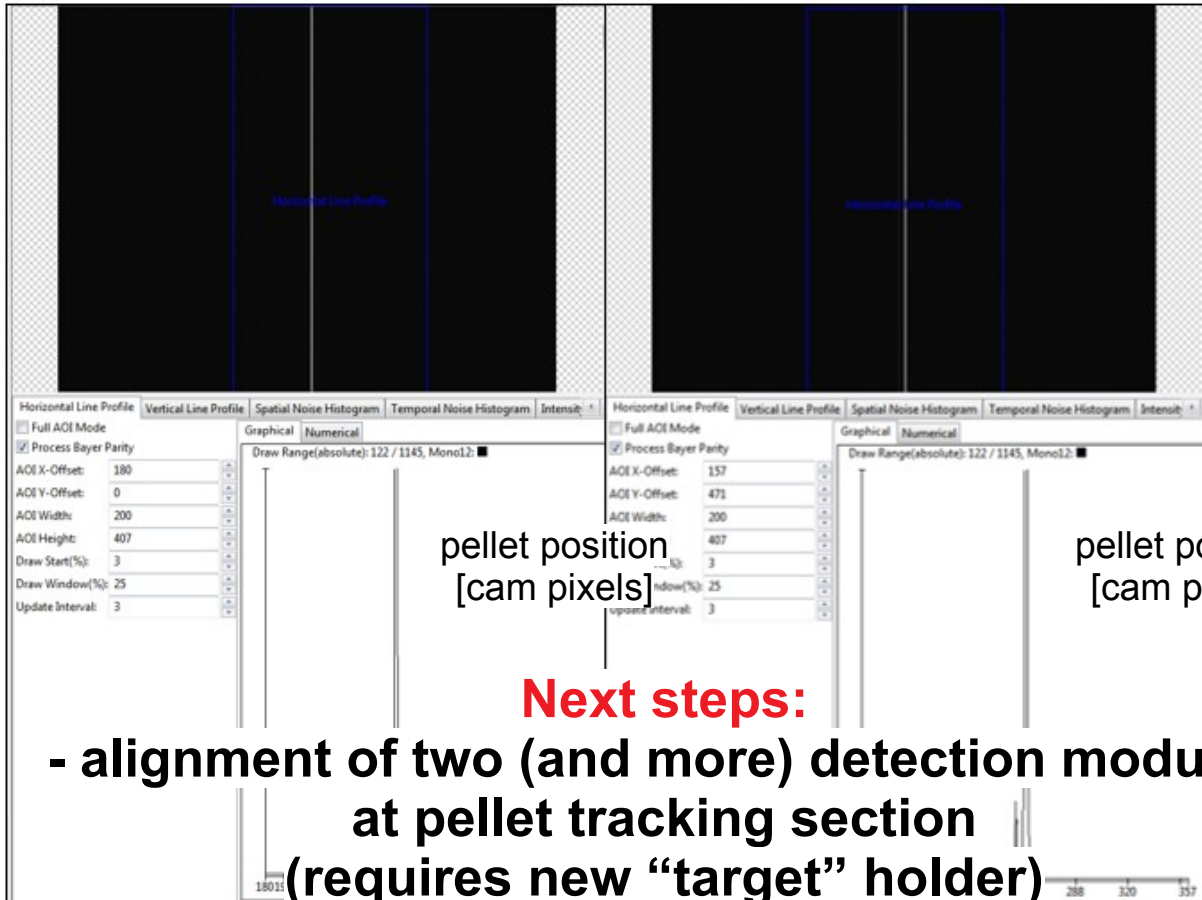
ZYNQ Xilinx SOC family (FPGA with PL, PS)

data buffering to collect full frames
optimized transfer to [Gigabit Ethernet port](#)

Alignment on test bench and tracking chamber

test bench...

...and tracking chamber



no effect of
- mounting at the tracking chamber
- glass windows

Next steps:

- alignment of two (and more) detection modules at pellet tracking section (requires new "target" holder)
- system test with two (and more) detection modules with pellet operation (requires sync/readout and pellet operation)

Pellet operation at UU/TSL

Slightly disadvantageous situation:

- pellet operation involves running costs (almost no funding for pellet tracking activities available)**
- TSL is being decommissioned → UPTS will lose available infrastructure**

The good news:

- successful application to UU Department of Physics and Astronomy Infrastructure Funding (≈15 kEUR/y for 4 years)**
- allows to pursue JRA11-Cryojet project, upgrades at UPTS to replace TSL infrastructure, operation with pellets**



Status of pellet tracking developments

Detection module alignment and installation procedure tested, fully documented

to be done: improved target holder for multi-level alignment

to be done: system test w.r.t temperature, mechanical shocks, vibrations

New readout hardware developed (ZynqBoard)

to be done: implement readout with ZynqBoard

UU Infrastructure funding secured for 4 years

prerequisite towards full mechanical/operational system test

Missing:

- full funding for complete system (cameras, lasers, mechanics, approx 20 + 40 kEUR for generator + dump)
- design of dump tracking section

