

# Activities at the ESR and Requests to Controls

M. Steck, Accelerator Operations, Storage Rings,  
GSI Helmholtzzentrum, Darmstadt

# History of ESR Operation with the New Control System



After the termination of the old control system in 2016 the operation of the ESR is still in a recommissioning phase with the new LSA system, about half of the recommissioning is done.

Between autumn 2018 and spring 2019 the synchrotron mode was used at the ESR for studies of beam storage, cooling and optics measurements.

At the end of 2019 first tests of the storage ring mode were successful.

During the 2020 beamtime the storage ring mode was successfully employed in recommissioning and user operation.

Further recommissioning is needed to achieve the level of operation performed with the old control system.

During and after recommissioning new features will be introduced which were not available in the old control system.

# Requirements of ESR Operation



A storage ring is similar to a synchrotron: similar components, similar structure.

The modes of operation show significant differences compared to a synchrotron

- extensive use of cooling

- integration of experimental set-up, control of experimental devices

- cycle times from milliseconds to days (depending on the lifetime of the ion)

Storage ring operation requires large flexibility, depending on the experiment

- variable ion optics (cooling, internal target, spectrometry)

- ideal orbit depends on the experiment (due to large acceptance)

- not all installed components are needed for the different operation modes

  - e.g. operation without rf is common to many experiments

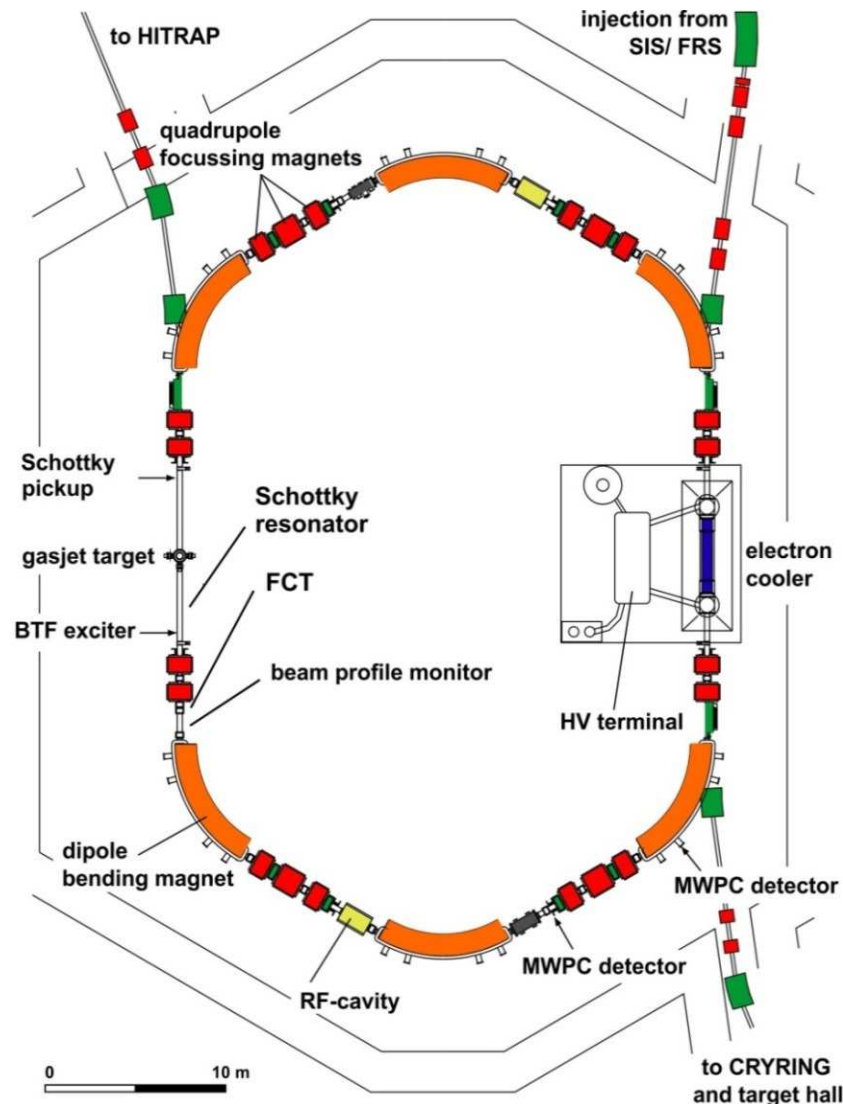
- orbit manipulations by magnetic components

- acceleration/deceleration by cooling systems or detuning of electrons (DR)

Operation in vivo, i.e. manipulation during the cycle with beam stored

Interfaces to experiments (cooling, target, lasers, detectors, data acquisition)

# The Heavy Ion Storage Ring ESR



- Fast injection (stable ions / RIBs)**
- Stochastic cooling ( $\geq 400$  MeV/u)**
- Electron cooling (3 - 430 MeV/u)**
- Laser cooling ( $C^{3+}$  120 MeV/u)**
- Internal gas jet target**
- Deceleration (down to 3 MeV/u)**
- Fast extraction (HITRAP/CRYRING)**
- Slow (resonant) extraction**
- Ultralow extraction (charge change)**
- Beam accumulation**
- Multi charge state operation**
- Schottky mass spectrometry of RIBs**
- Isochronous mode (TOF detector)**

# Status of ESR



Control of most power converters is migrated to SCUs. Typically SCUs show some dropouts at the beginning of a beamtime, but finally work reliably.

The storage ring mode has been established successfully (after one year of development) some specific aspects were implemented: waiting points, manipulations, repetitions.

The storage ring mode will be the basis for further developments and user operation.

To fully benefit from the new control system significant additional effort is required, development of control system, training of operators.

Presently the control system user interface is very complex, powerful, but intransparent.

A big deficiency is the lack of component value read back (power converters, vacuum). ESR operation is heavily relying on existing analog signals in the MCR.

Latency problem: waiting time 30 - 200 seconds after input of a new parameter.

New diagnostics components and GUIs are in development, only expert versions, but by now all diagnostics software is stand alone, links to control system are missing.

Interfacing to experiments is still based on old timing system events, modernized interfaces to cooling system components, internal target, detectors drives, experiment data acquisition are missing.

# Some Achievements of ESR Operation

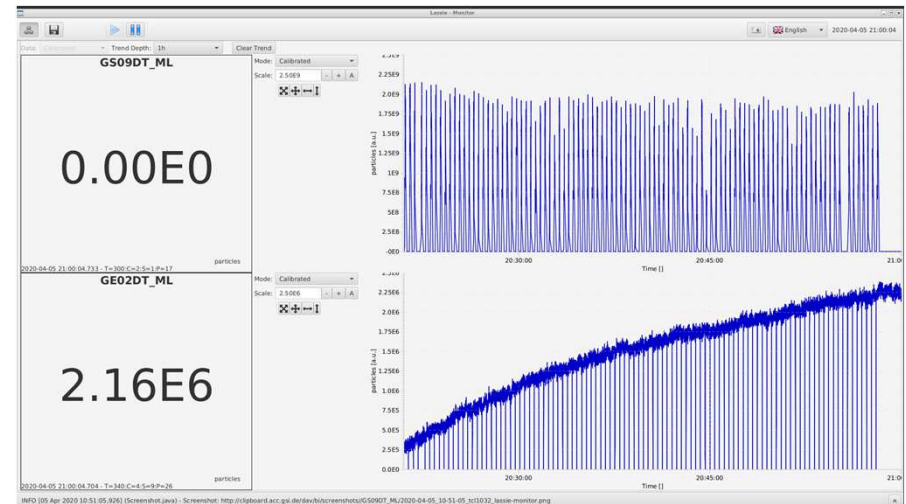
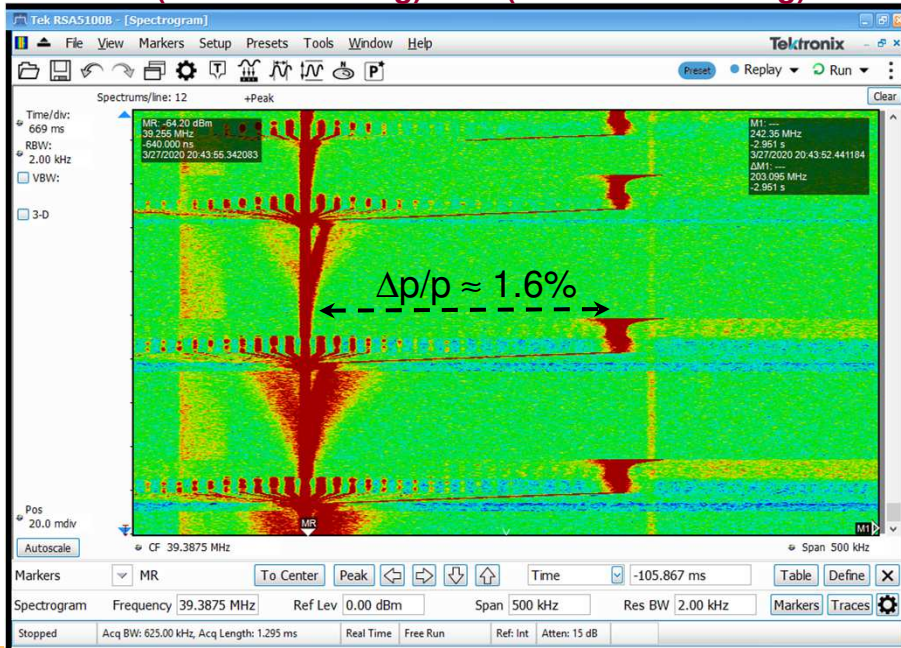


- **stable beam storage** with (proven) storage time up to half a day, but with an extended pattern (very time consuming generation)
- **accumulation at 400 MeV/u** by combination of stochastic cooling on injection orbit, deceleration with rf, electron cooling on inner orbit



pattern with 15 subchains for TI205 experiment

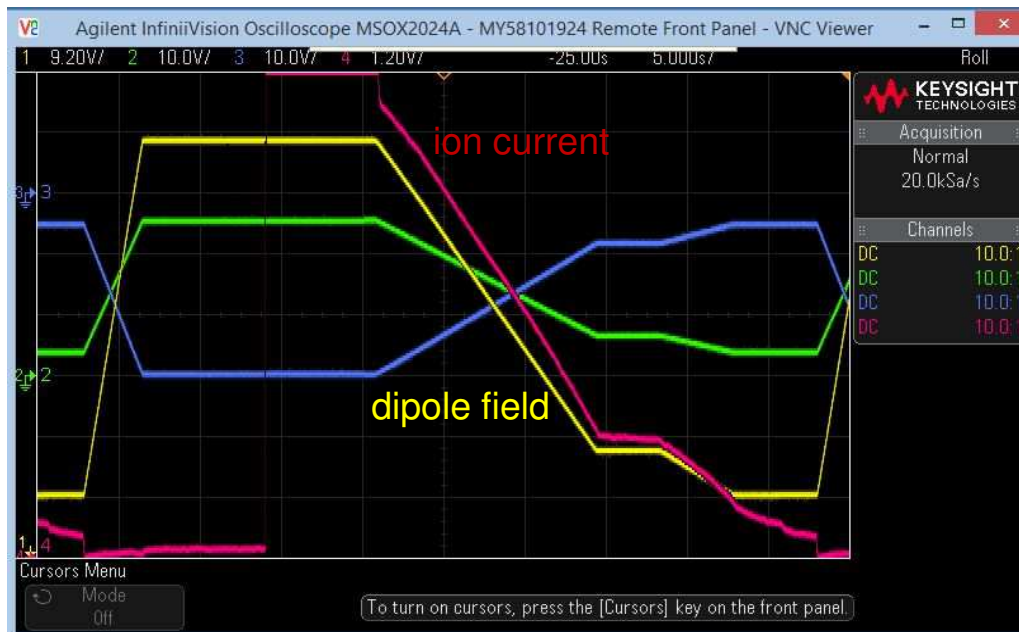
**stack orbit (electron cooling)**      **injection orbit (stochastic cooling)**



stored intensity in ESR

# Some Achievements of ESR Operation

- **deceleration** of  $\text{Pb}^{82+}$  from 400 to 10 MeV/u



for low intensity ( $N \leq 10^6$ )  
losses are negligible

losses at higher intensity  
are not attributed to  
improper control of the ESR

- **fast extraction** of decelerated beam from ESR and transport to CRYRING with synchronization of kickers  
but: without rf synchronization (B2B)
- **slow charge changing extraction** demonstrated  
but: trimming the beamline with stored beam in the ESR will be useful

# Requests from ESR



- availability of actual value read back is indispensable (not necessarily new digitization)
- improvement of latency problem (check the results of task force in 2021)
- improvement of reliability of DEVICE CONTROL
- migration of all components to new control system (device access units) and operation with one timing system
- rf synchronization between rings (B2B), for transfer to CRYRING and accumulation in the ESR
- remove limitation in allocatable patterns and simplify pattern generation
- flexibility in programming of timing events (for experiments)
- simplified system for saving and recall of settings
- removal of inconsistencies in parameter manipulations and trims (illogical and unpredictable response, unclear sequence of manipulations, interplay of pattern status and sending of new data, outage of AEG ? )
- integration of beam diagnostics into controls and use in machine optimization (tuning machine parameters, optimization of transmission)



# Summary and Outlook



**The new control system has made significant progress during the last 2 years when it was introduced into ESR operation.**

**It has a lot of features for advanced machine operation.**

**Presently the ESR operation for users is not as efficient as it was with the old system:      user operation ↔ controls development**

**More efforts are needed to achieve the previous level of operation both by the control system developers and the machine operators.**