

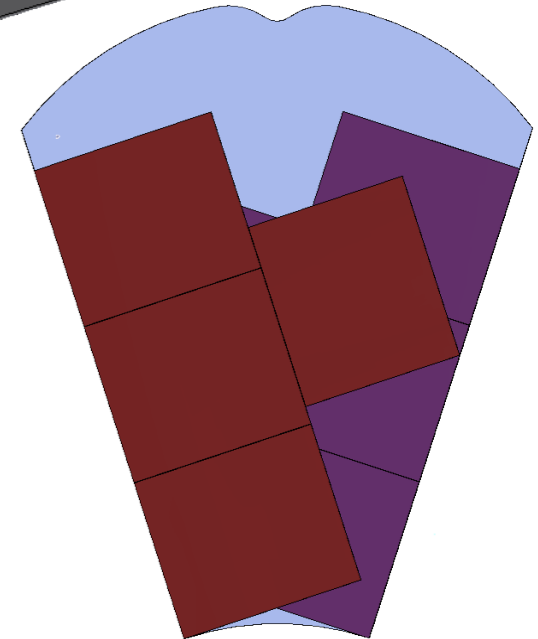
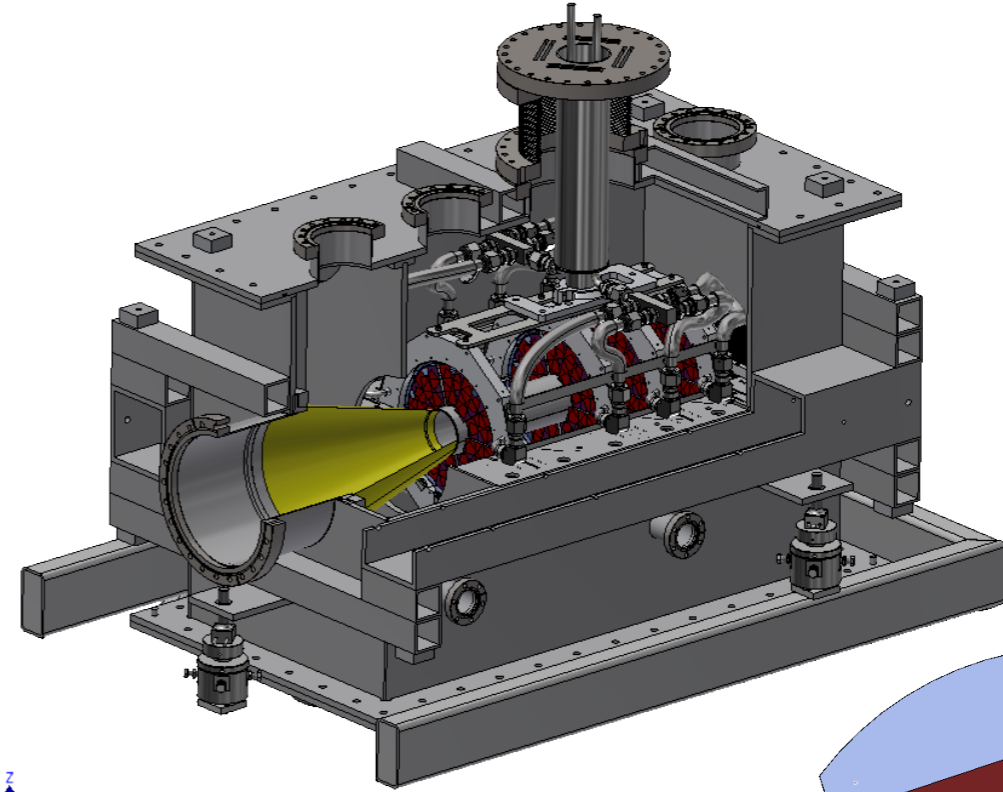
MuPix8 Status and Testbeam Results

**– PANDA Collaboration Meeting 2020/2 –
Luminosity Detector Session**

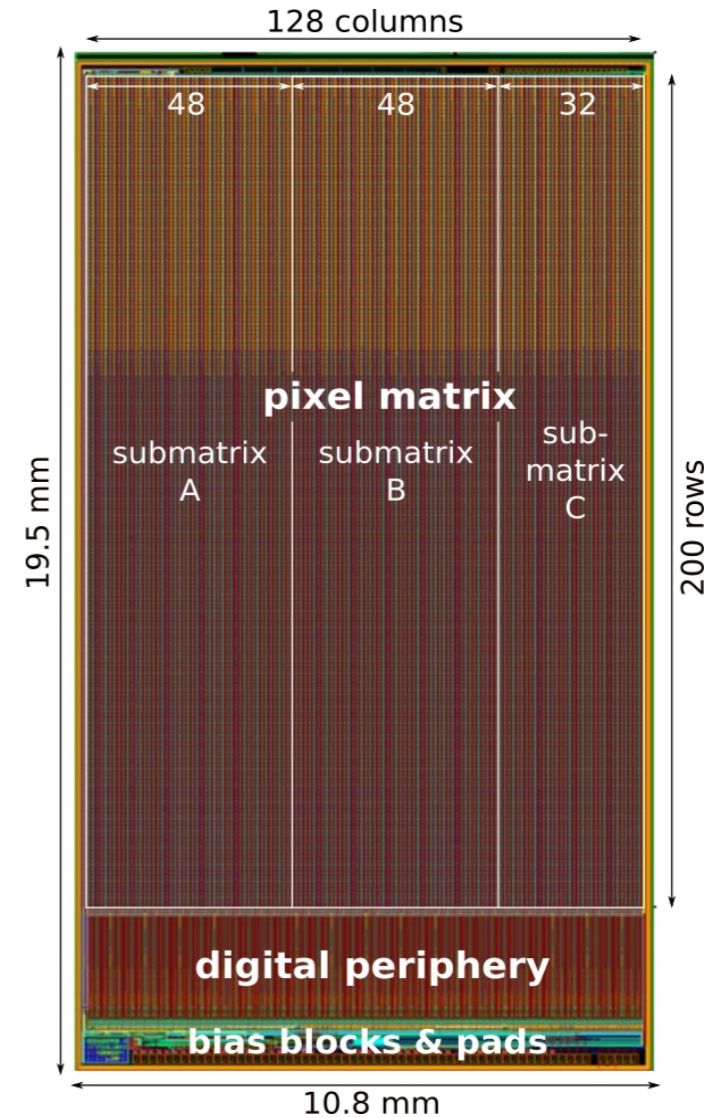
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June 23, 2020

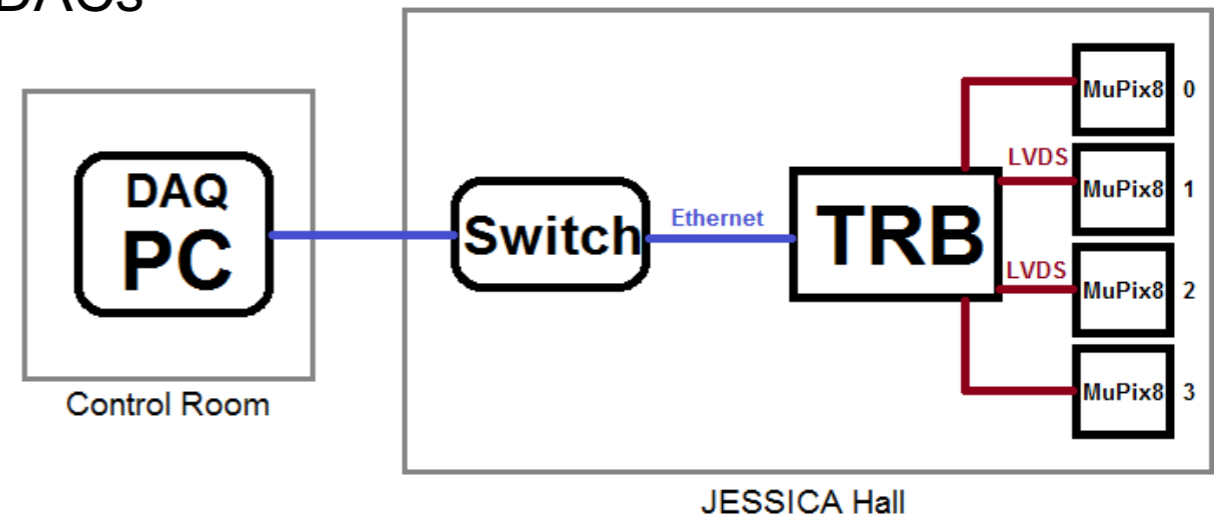
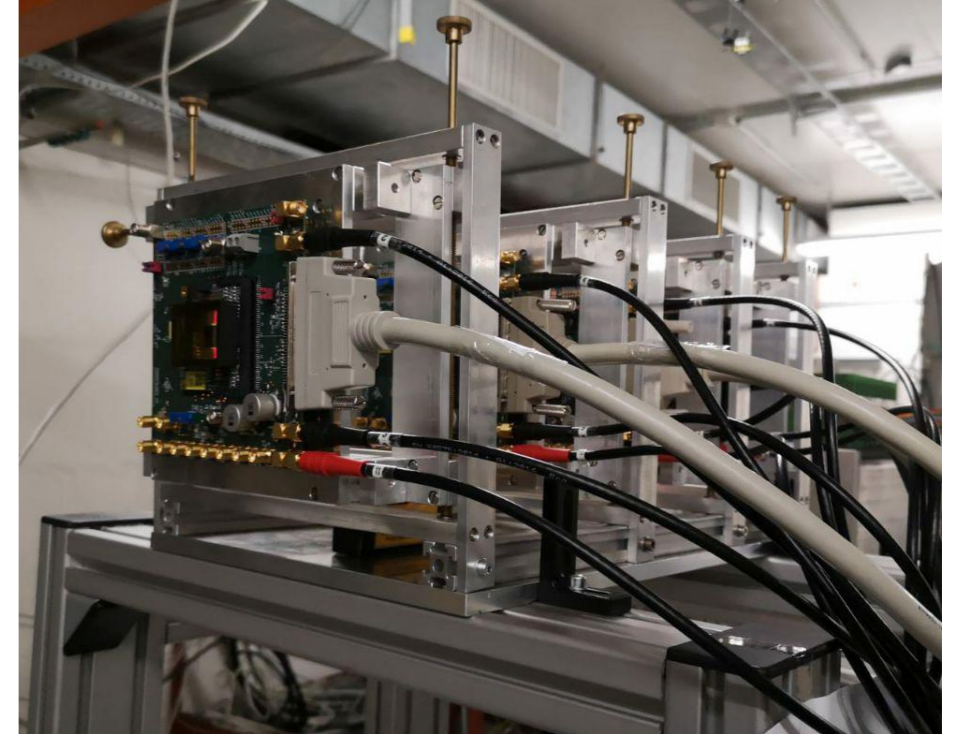
- 11 m behind IP
- Measure tracks of elastically scattered anti-protons
- Anti-protons enter detector vacuum through transition cone
- 4 detector layers with HV-MAPS on both sides
- 10 sensor modules per layer
- Aluminum holding structure with embedded steel pipe for cooling (coolant: -20°C ethanol)
- Total number of sensors: 320
- Active area of one sensor: $2 \times 2 \text{ cm}^2$
- Pixel size: $80 \times 80 \mu\text{m}^2$



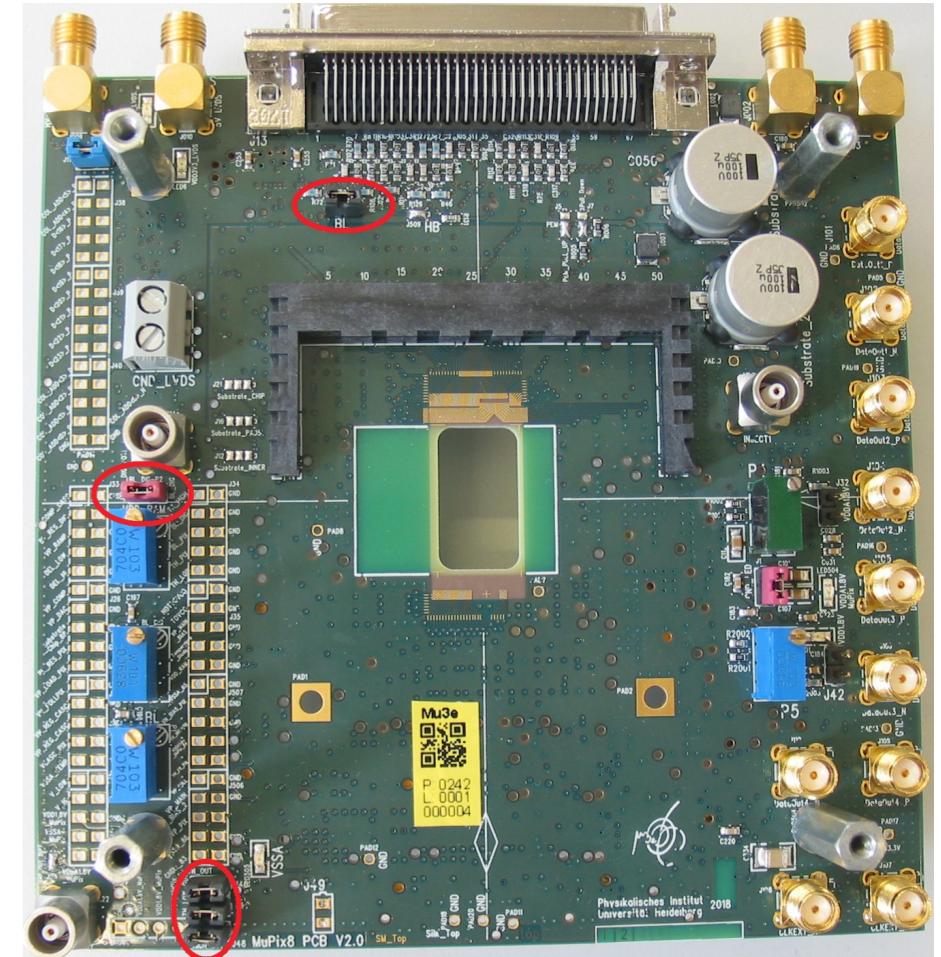
- Originally developed for Mu3e
- Physical size: $10.8 \times 19.5 \text{ mm}^2$
- Active area: $\sim 10.2 \times 16.2 \text{ mm}^2$
- Matrix: 128×200 Pixels, three Submatrices
MatA: source follower
MatB/C: current mode
- Pixel: $80 \times 81 \text{ }\mu\text{m}^2$
- Charge sensitive amplifier in each pixel
- Two comparators in each peripheral cell (timewalk compensation)
- 4 LVDS links (each submatrix + select/mux)
- Analog readout of Hitbus (ToT information) and amplifier output (for leftmost column only)



- Same setup as previous testbeam (September 2019):
 - Four layers of MuPix8 sensors
 - All 3 submatrices active
 - Readout via TRBv3
- Change in sensor configuration:
 - Detection thresholds and baselines set via internal DACs
- Test of new DAQ with Kintex board postponed



- Previously: Using sensorboard DACs to set voltages:
 - 14 bit values for thresholds
(1900 mV sampled at 16383 steps \Rightarrow 0.116 mV/step)
 - Baseline voltages regulated by two potentiometers
- Internal voltage and threshold DACs (VDACs):
 - Implemented on the chip
 - 10 bit values
(1900 mV sampled at 1023 steps \Rightarrow 1.857 mV/step)
 - Always set during chip configuration but overridden by board DACs
- Cancel override by unplugging certain jumper connections
- Reasonable match between the two settings (confirmed by manual measurement)



Beam parameters:
 $p \sim 2.75 \text{ GeV}/c$
 $> 10^6 \text{ protons} / \text{s}$

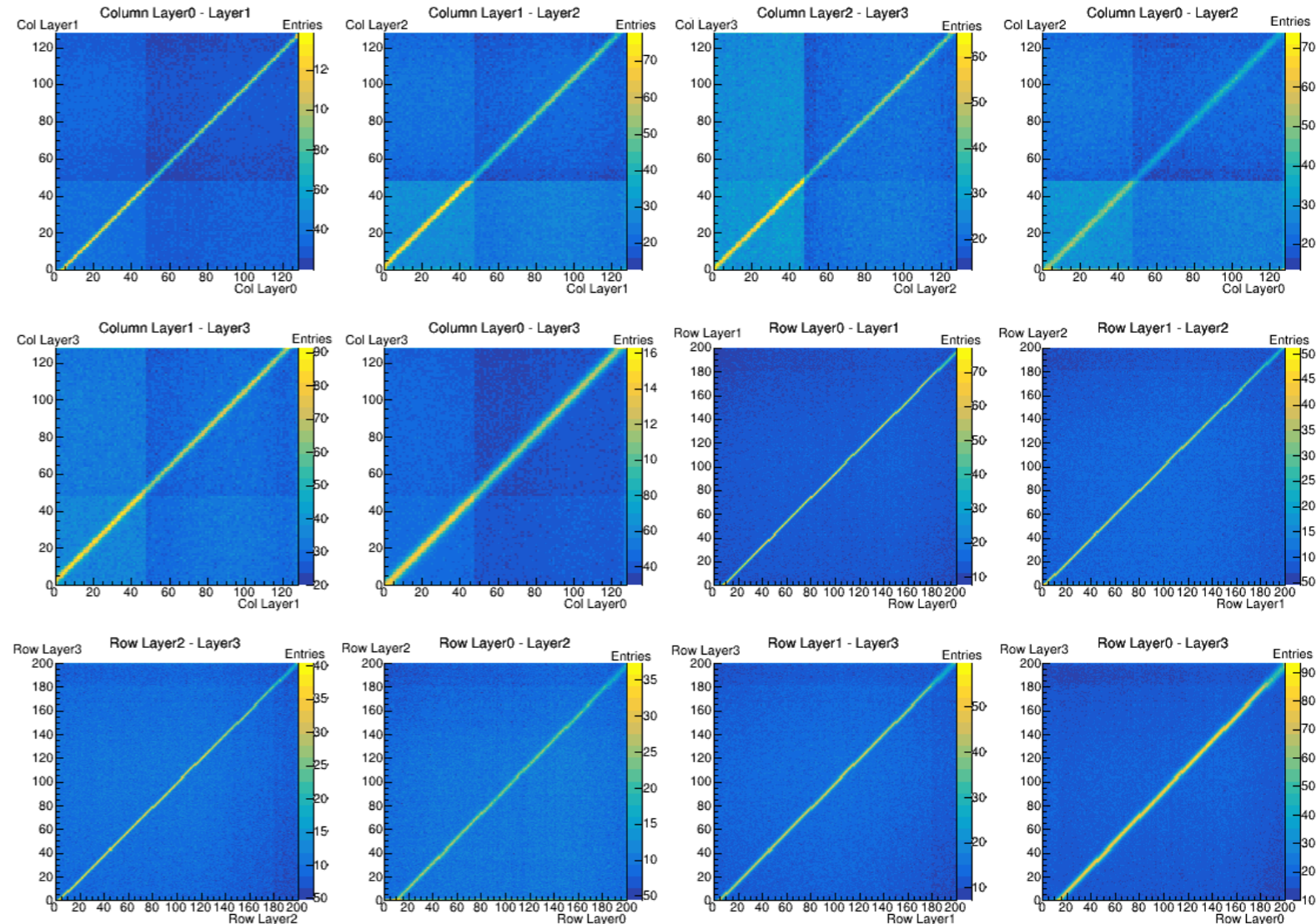
- Homogeneous illumination of all sensors (wide beam)
- Sharp cut between Matrix A and B/C
- Started at very low intensities, increased rate several times during beamtime



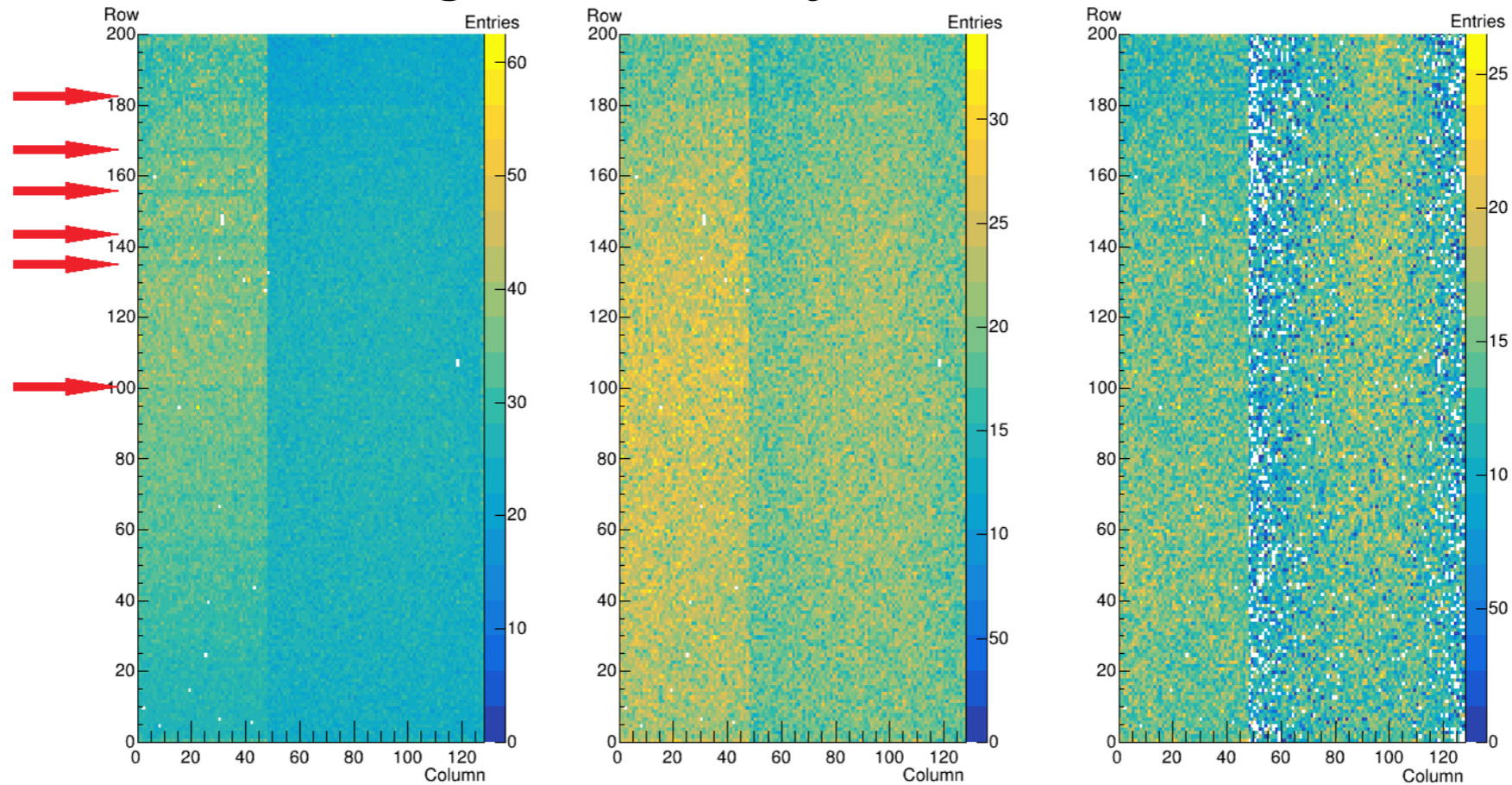
Hitmaps @ HV = 50 V and ThHigh = 600 mV

Column and Row Correlations for all matrices after alignment:
DUT: HV = 50 V and ThHigh = 600 mV

- Use Layer 1 as DUT with various HV and threshold settings
- Layer 0, Layer 2, and Layer 3 for tracking
- No rate problems due to beam intensity (usually seen in row correlations)
- Remaining offset can be corrected by software alignment



DUT @ HV = 50 V and ThHigh = 550 mV, 600 mV, 650 mV



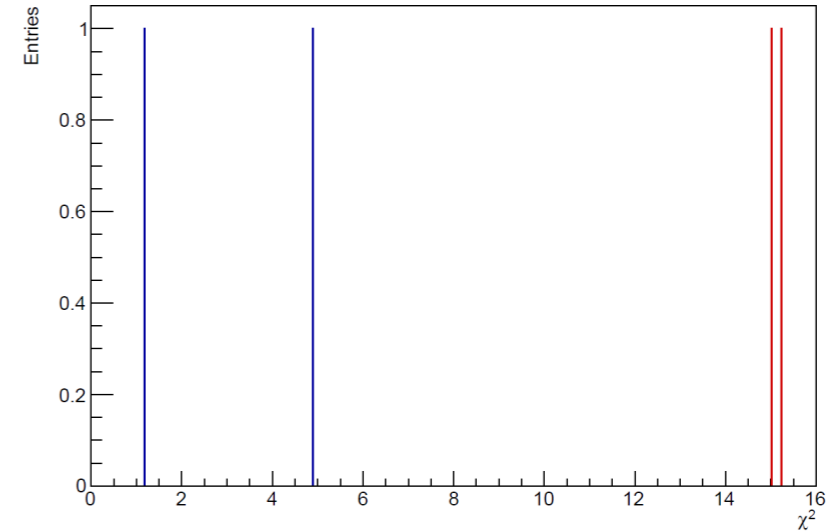
- Different response from matrix A and B/C (sharp cut)
- Insensitivities for edges of matrices B/C at higher thresholds
- No difference in response between B and C

Currently investigating code of MuPix6 analysis algorithm and adapting it for MuPix8 data:

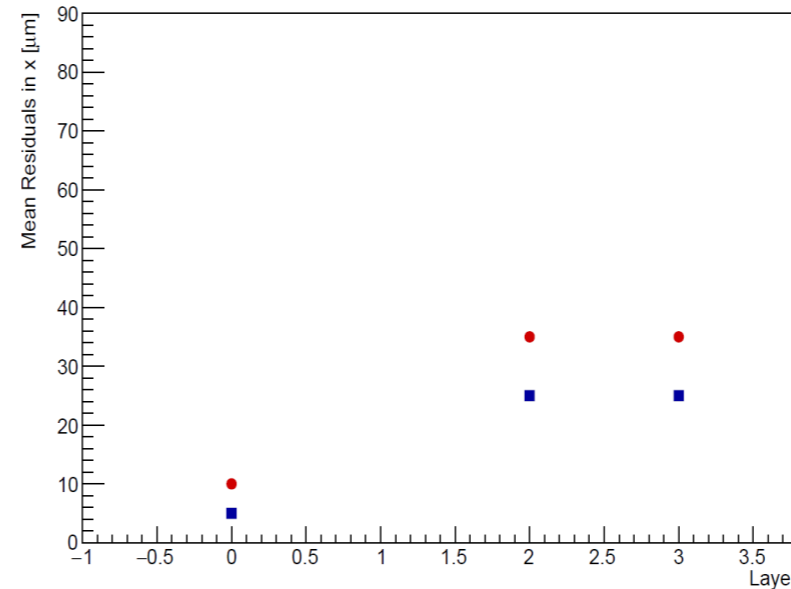
- Coordinate transformation to x-, y-, z-coordinates (✓)
- Software alignment of layers (✓)
- Cluster finder (✓)
- Tracking algorithm based on cellular automaton (✓/✗)
- Efficiency calculation for DUT, etc. (✗)

- Test of Tracking algorithm with two events from testbeam data set
- Each event containing a single hit in layers 0, 2, and 3
- Tested tracking with and without software alignment
- TODO / Improvements:
 - Replace current tracking algorithm with simplified version (originally designed for GPU or FPGA tracking)
 - Iterative alignment improvements after tracking

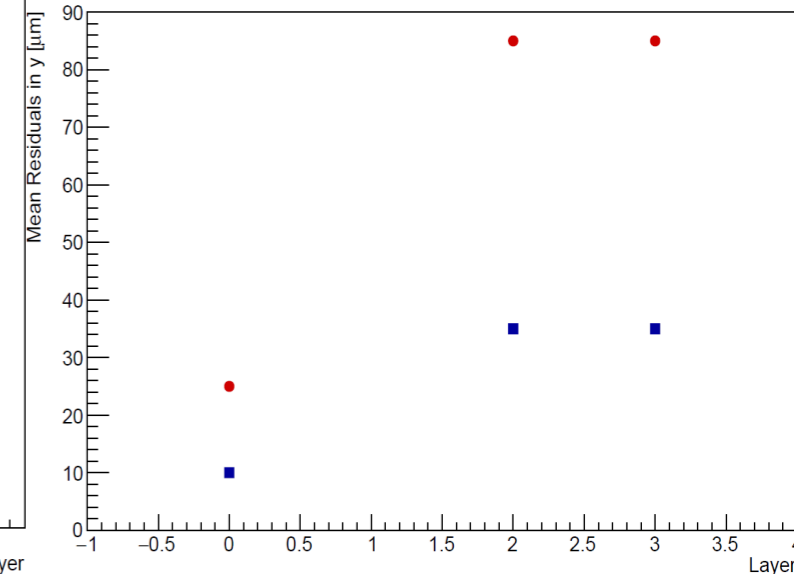
χ^2 Distribution



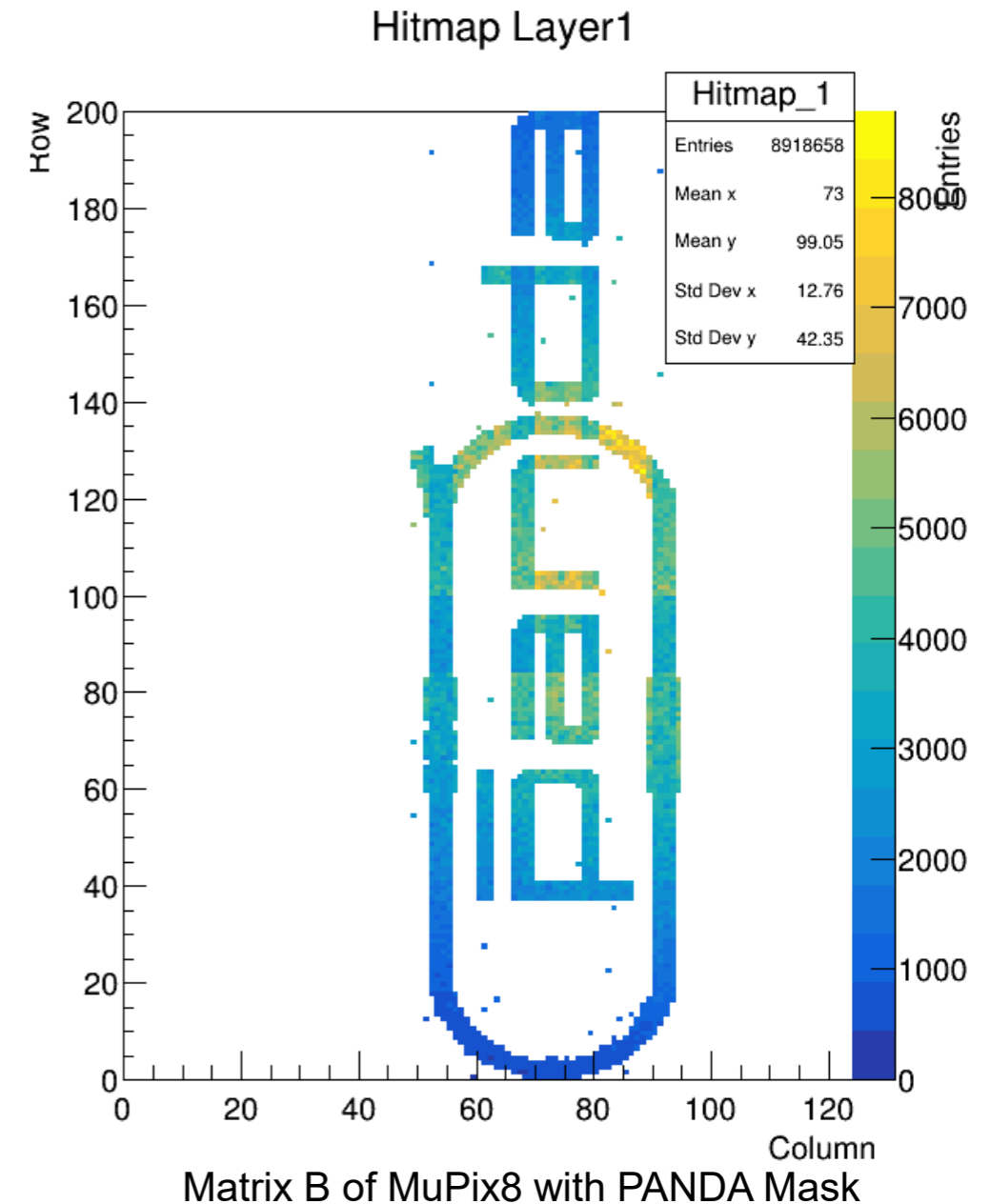
Mean x-Residuals before and after Alignment



Mean y-Residuals before and after Alignment

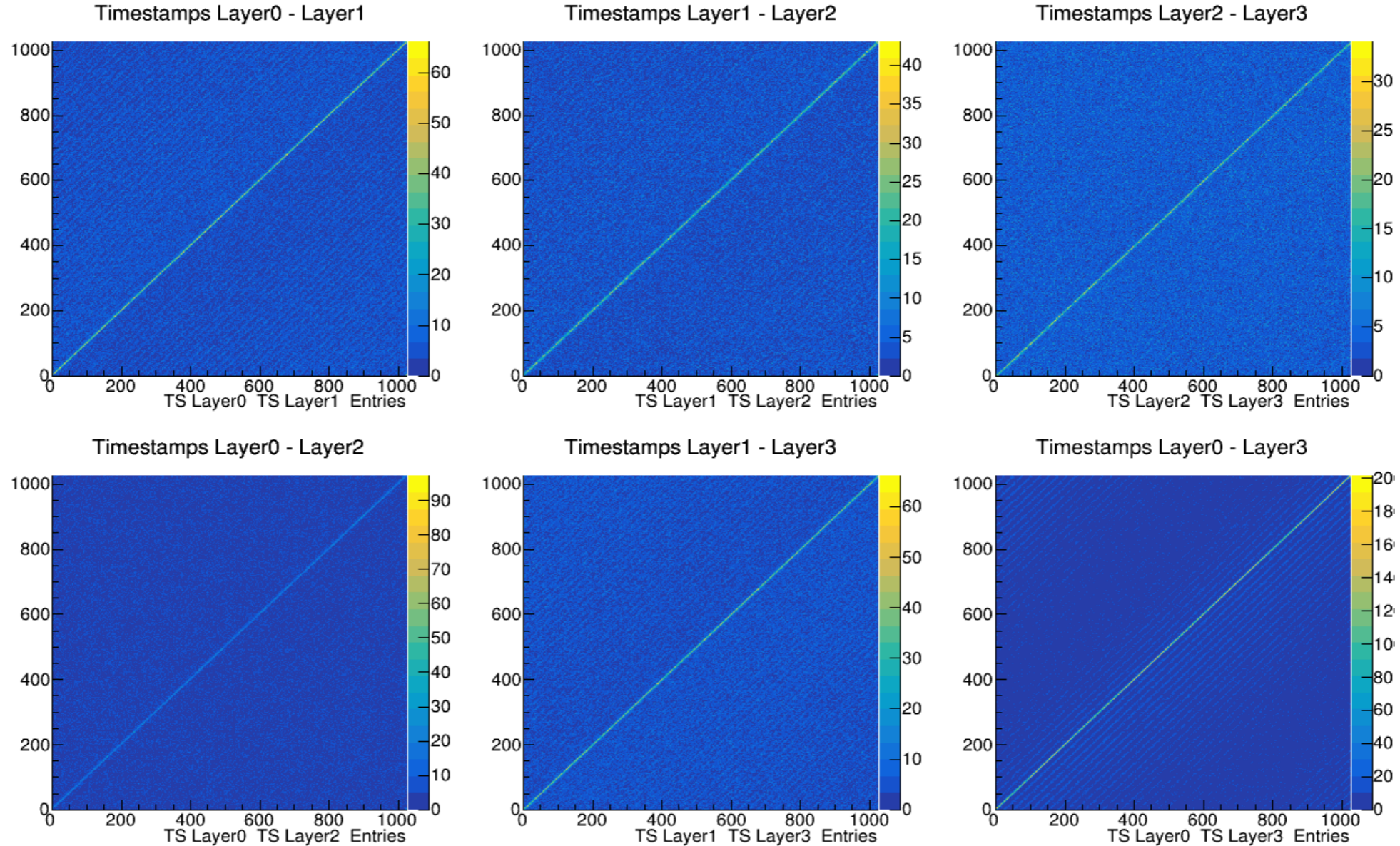


- Testbeam at COSY with four layer telescope
 - Chip configuration using VDACS
 - All submatrices read out simultaneously
 - No readout errors observed due to beam intensity
- Testbeam data analysis based on cellular automaton algorithm used for MuPix6
 - First test with MuPix8 beam data seems promising
- Possibility to use simplified tracking algorithm is being investigated

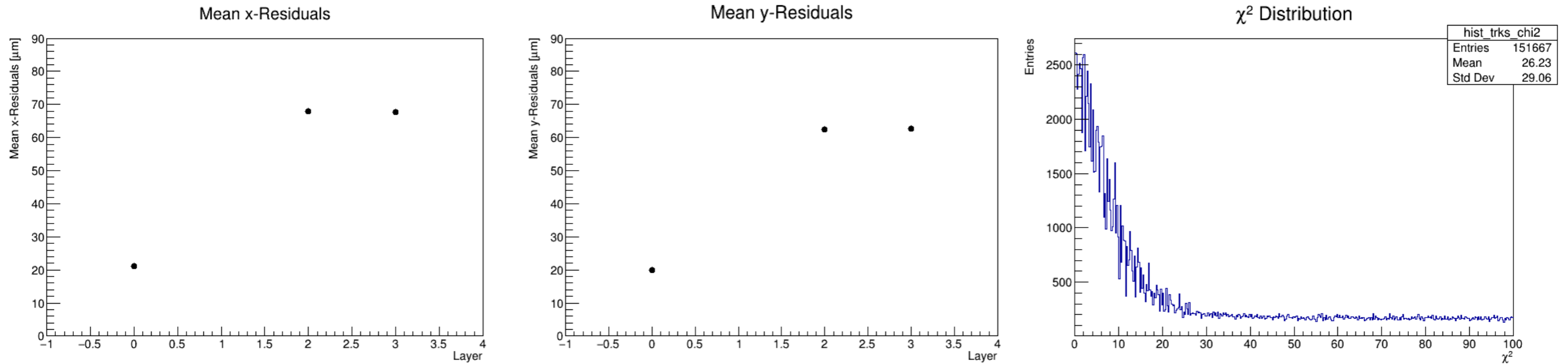


– Backup –

- All 4 Layers synchronized



- Test of tracking algorithm with one full run (settings: HV = 30V, ThHigh = 600mV):



Note: After software alignment, **no** cluster correction