

A 3D Method for Assigning MVD Hits to Tracks Fitted in the STT

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Computing Session

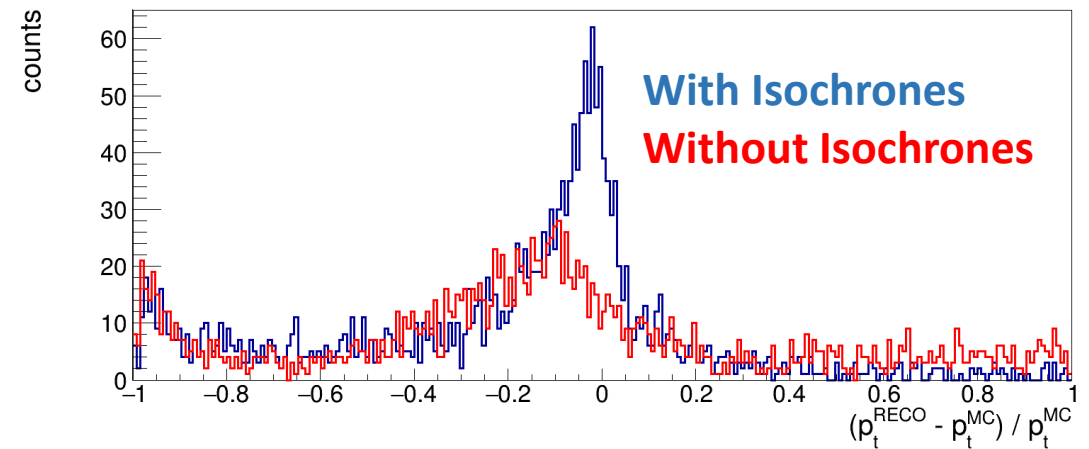
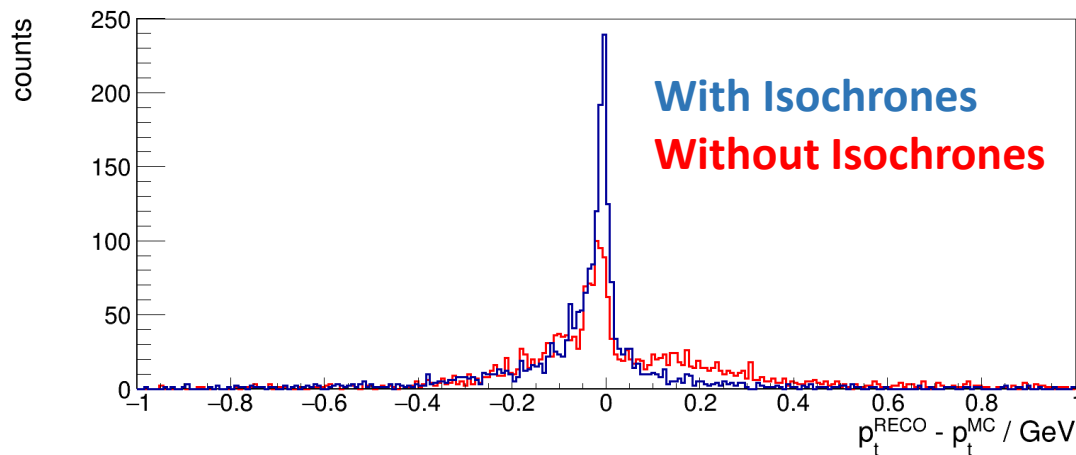
Outline:

- 1. Momentum Resolutions Discussion**
- 2. Background**
- 3. 3D Extrapolation Method**
- 4. Results**
- 5. Outlook**



Reason for Momentum Resolution Study

- SttCellTrackFinder basis for extrapolation procedure
- Right now also the most mature algorithm for running time-based
- Want (need!) to understand the absolute and relative momentum resolutions
 - Unexplained features in the distributions
 - One sub-structure in absolute momentum resolution when not using isochrones
 - A peak around -1 in relative momentum resolution independent of isochrones utilization
- The success of extrapolation for including hits from other detectors depend on how well the momentum was estimated

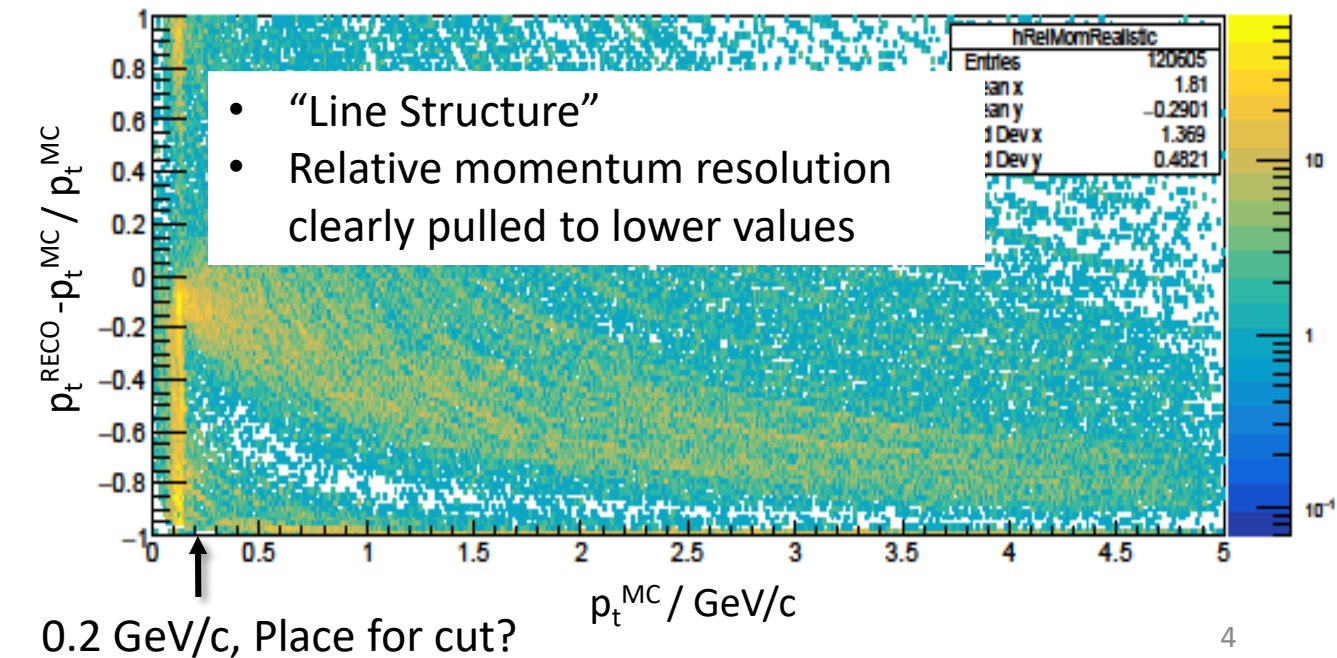
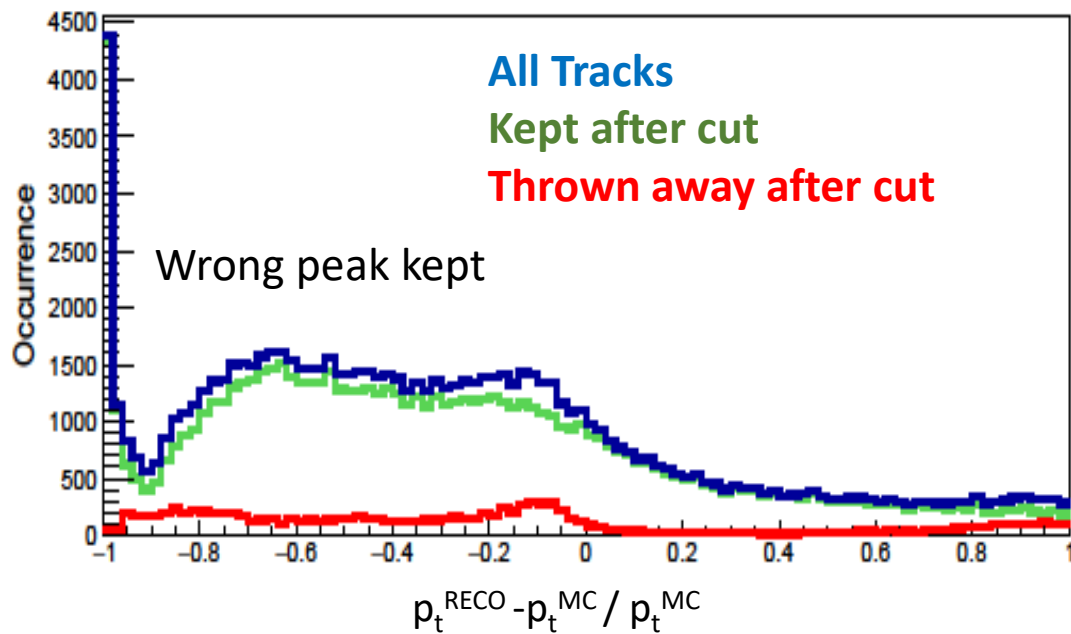
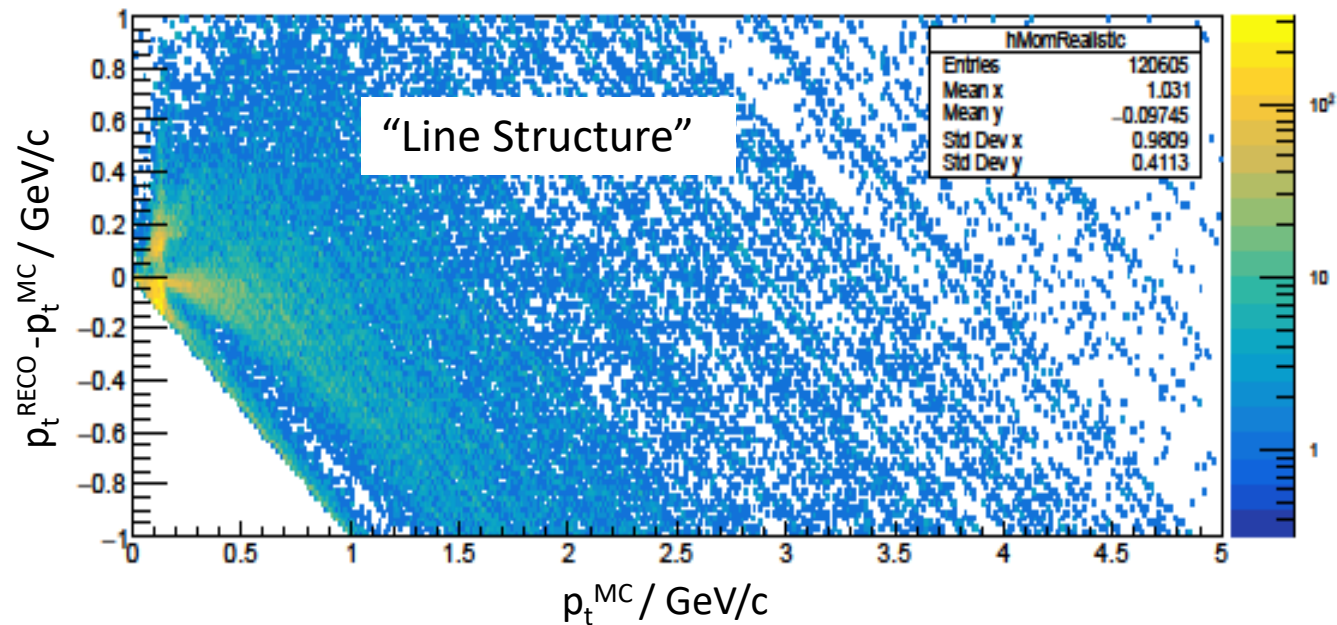
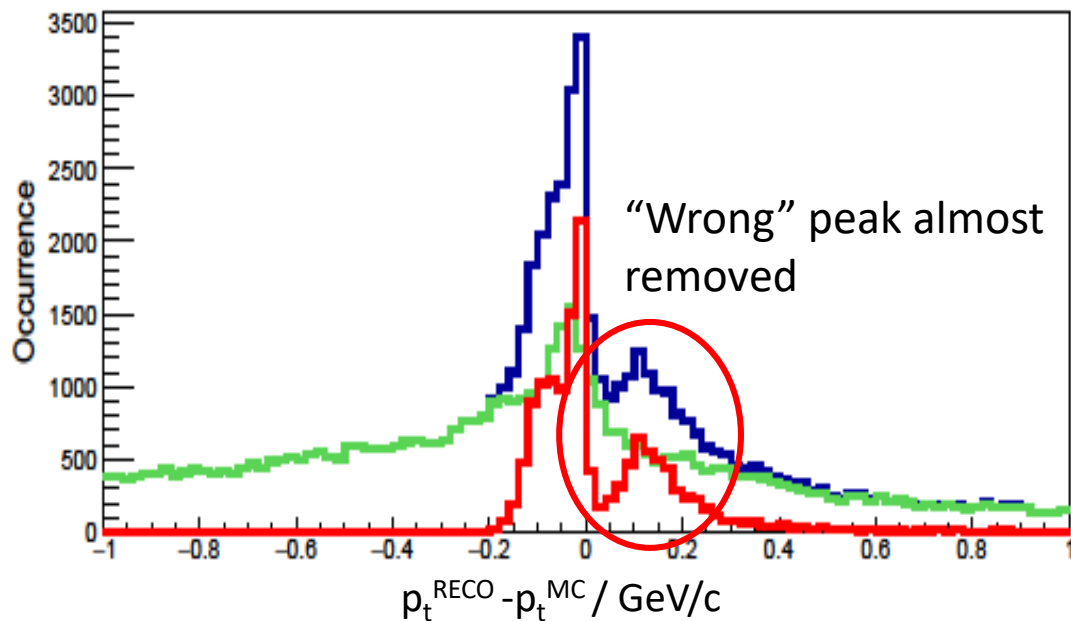


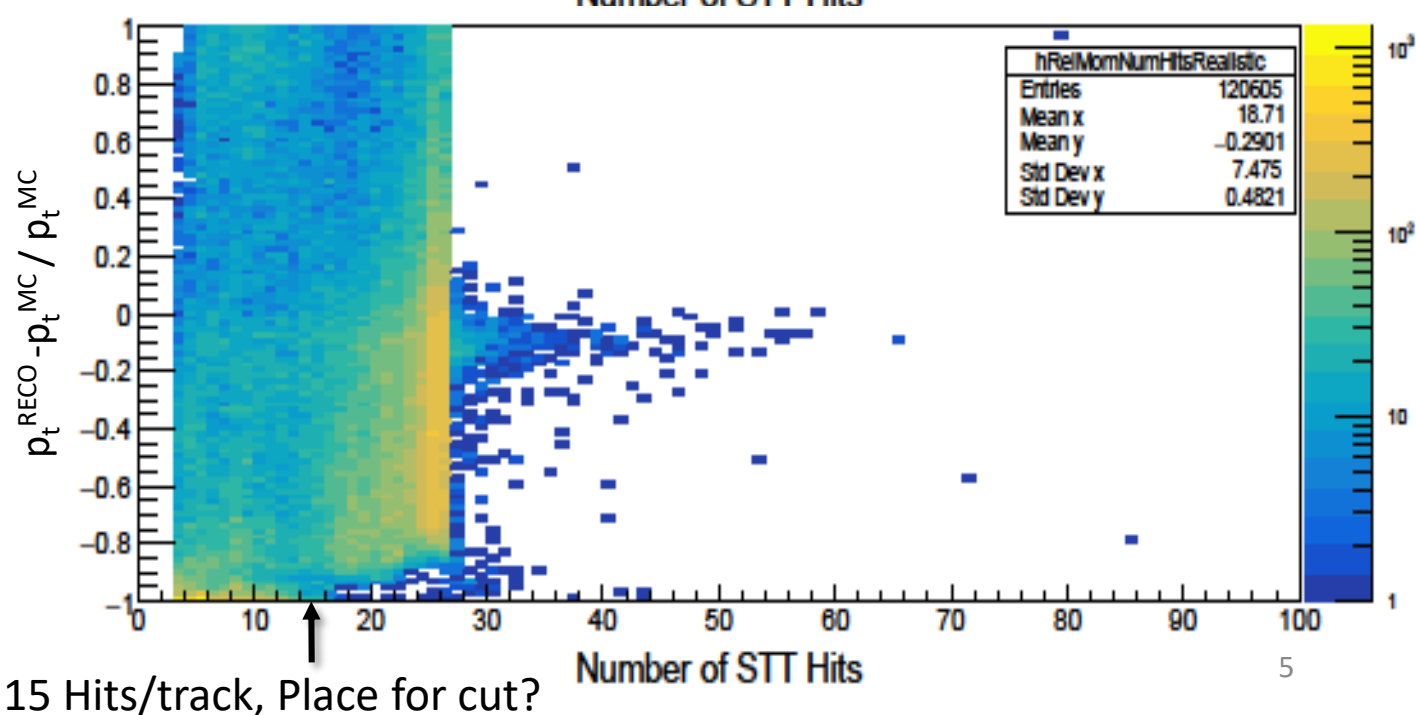
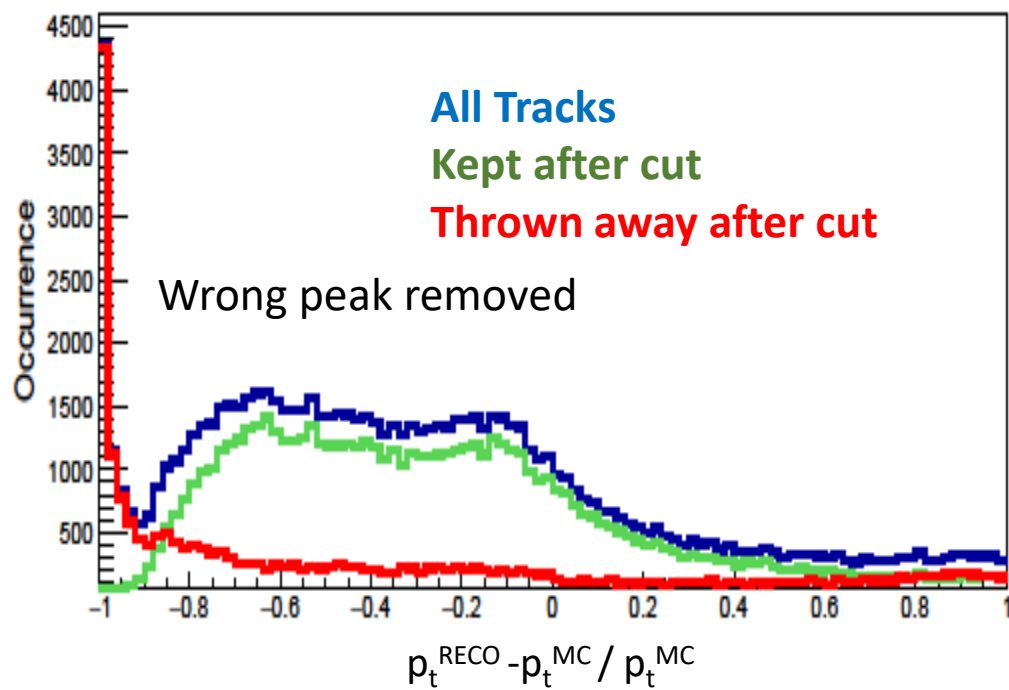
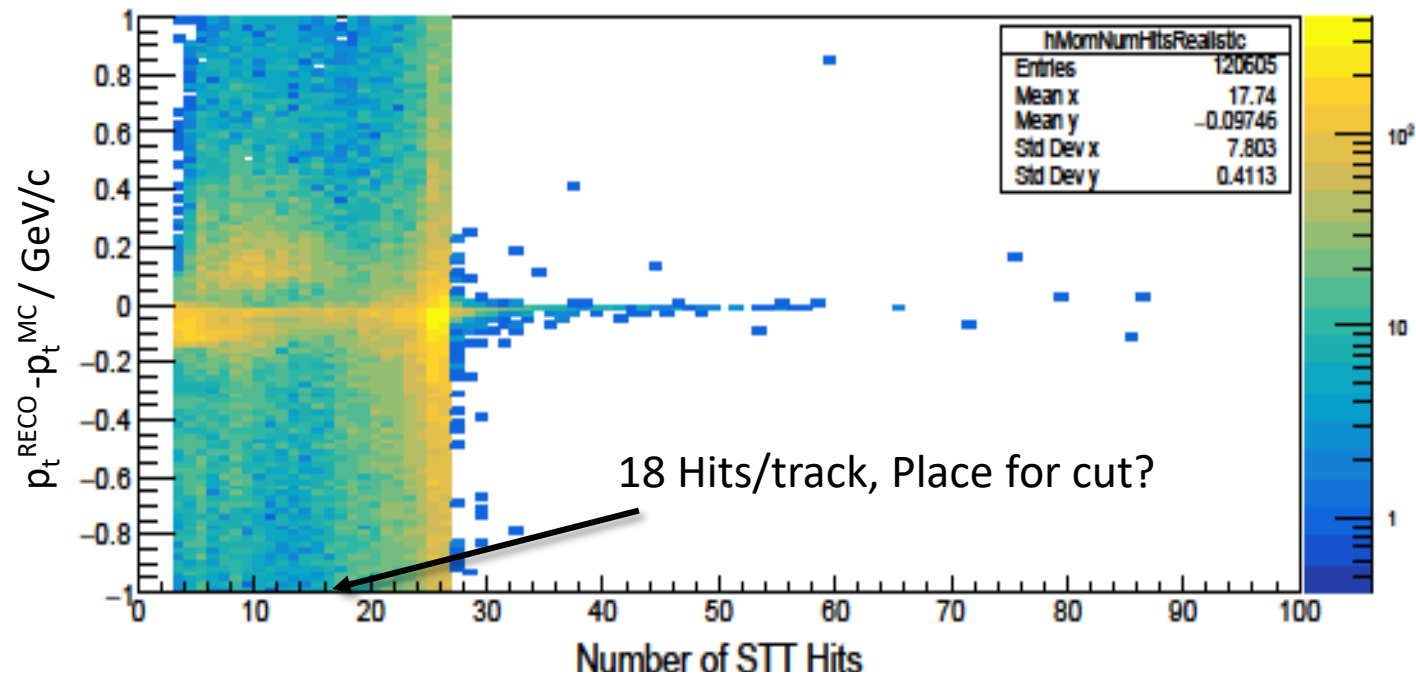
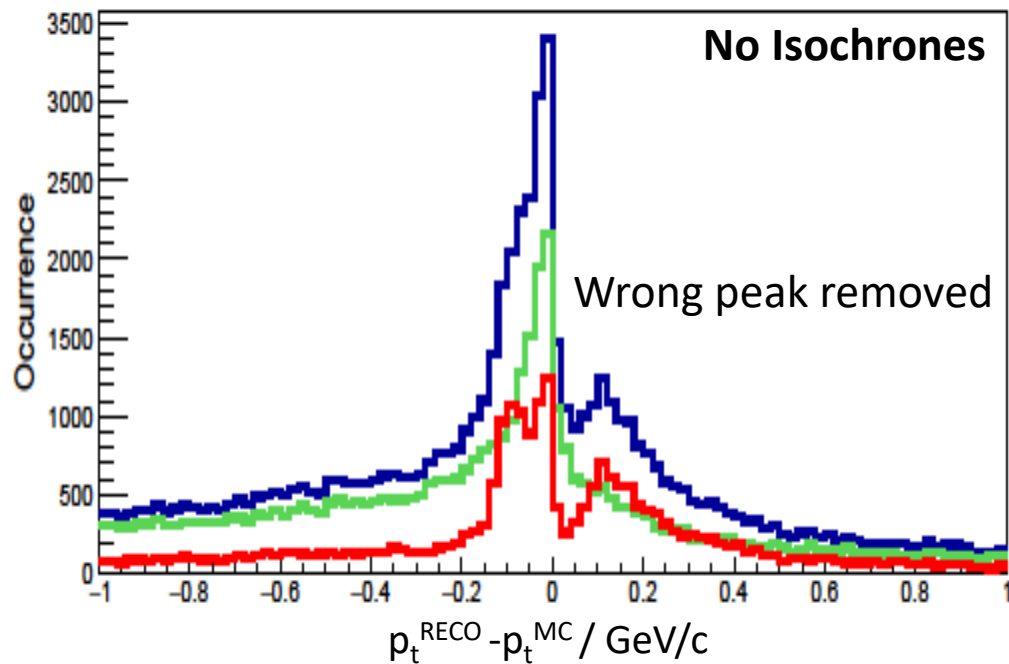
DPM, @ $P_{\text{beam}} = 6.2 \text{ GeV}/c$

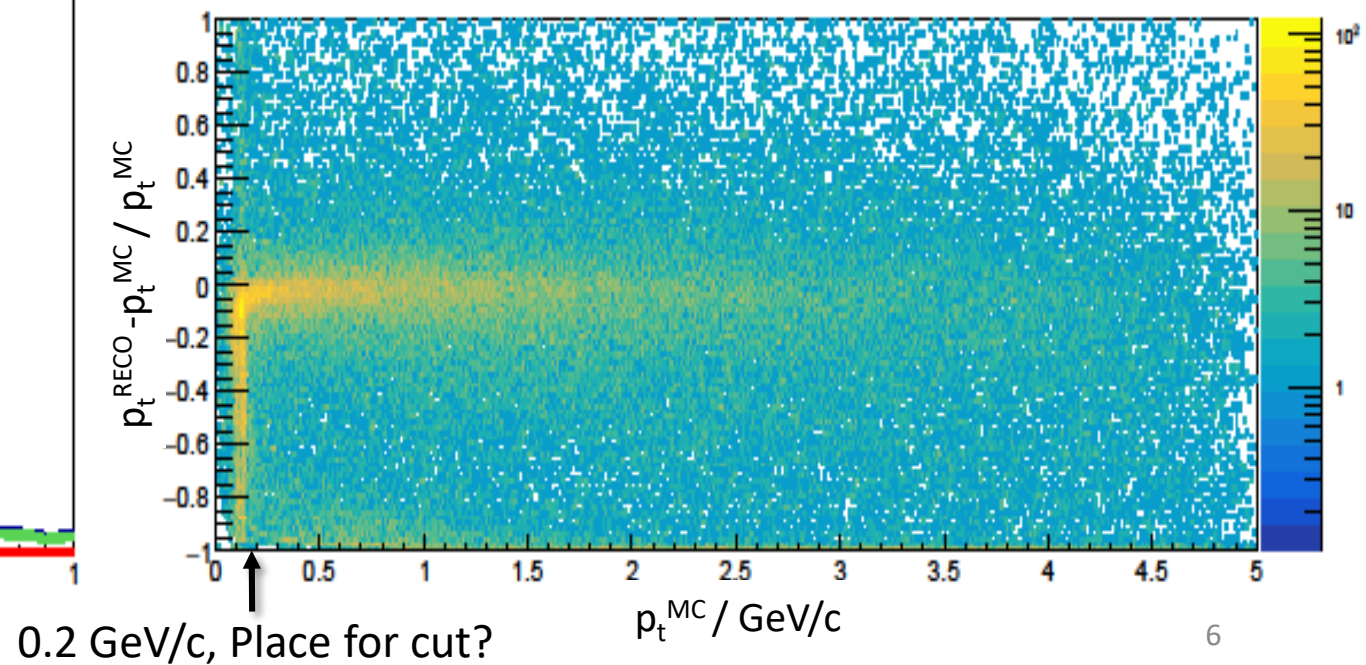
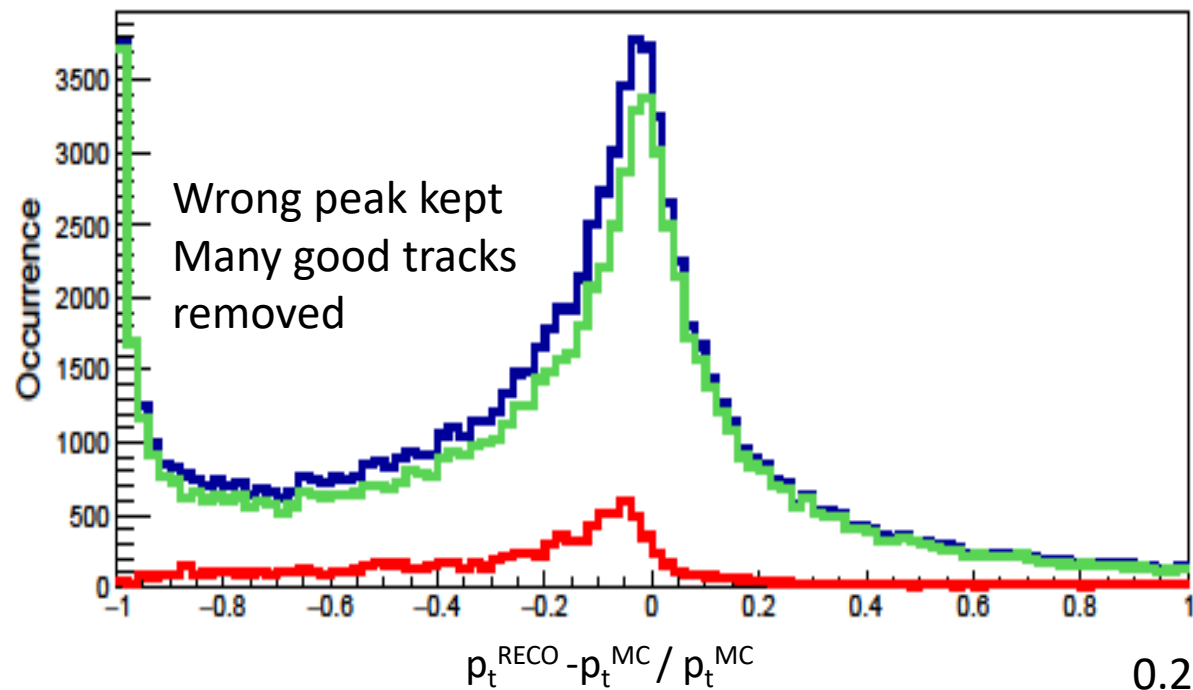
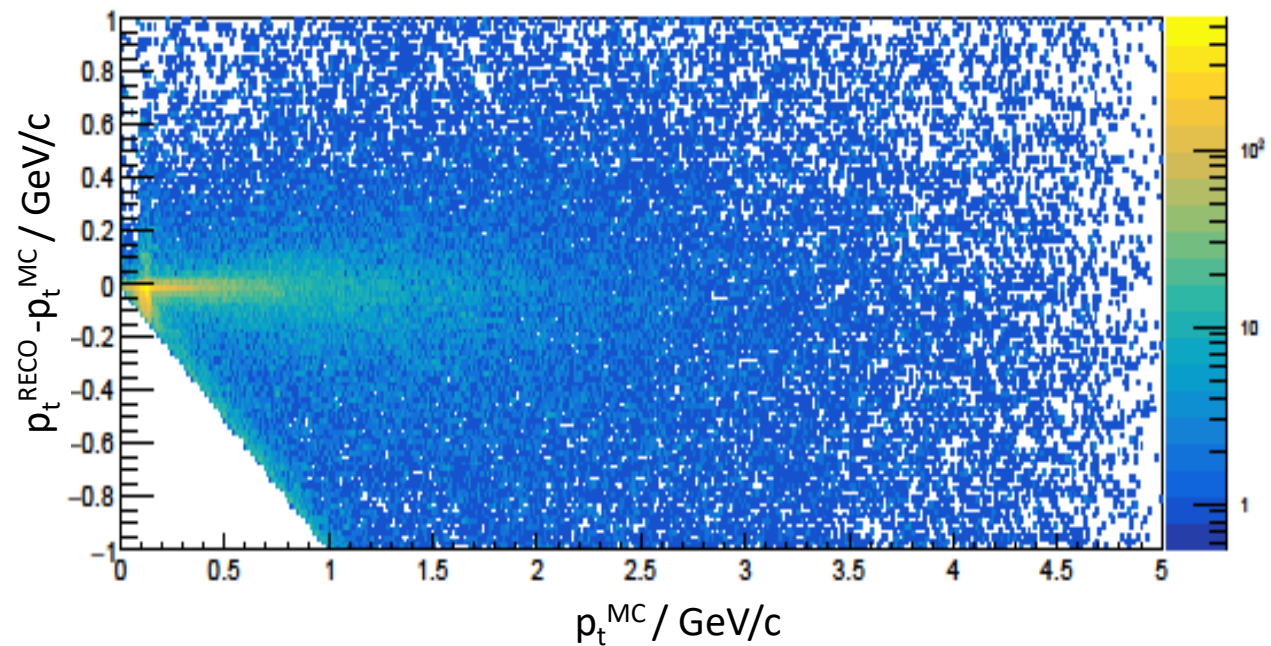
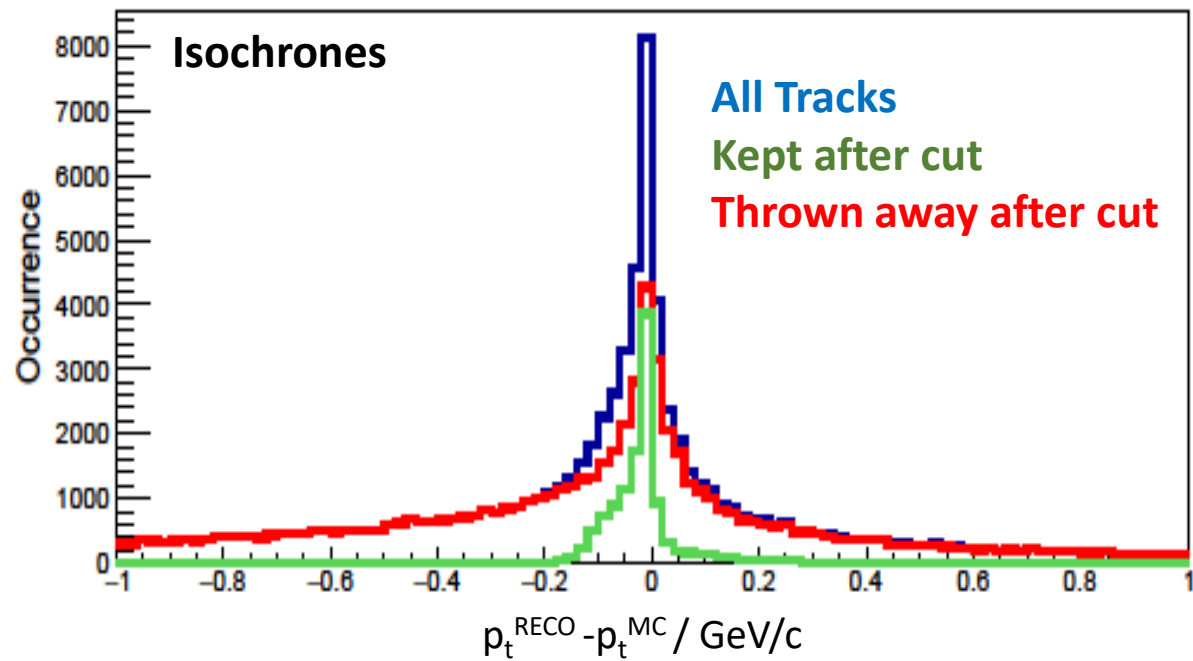
Simulation Details

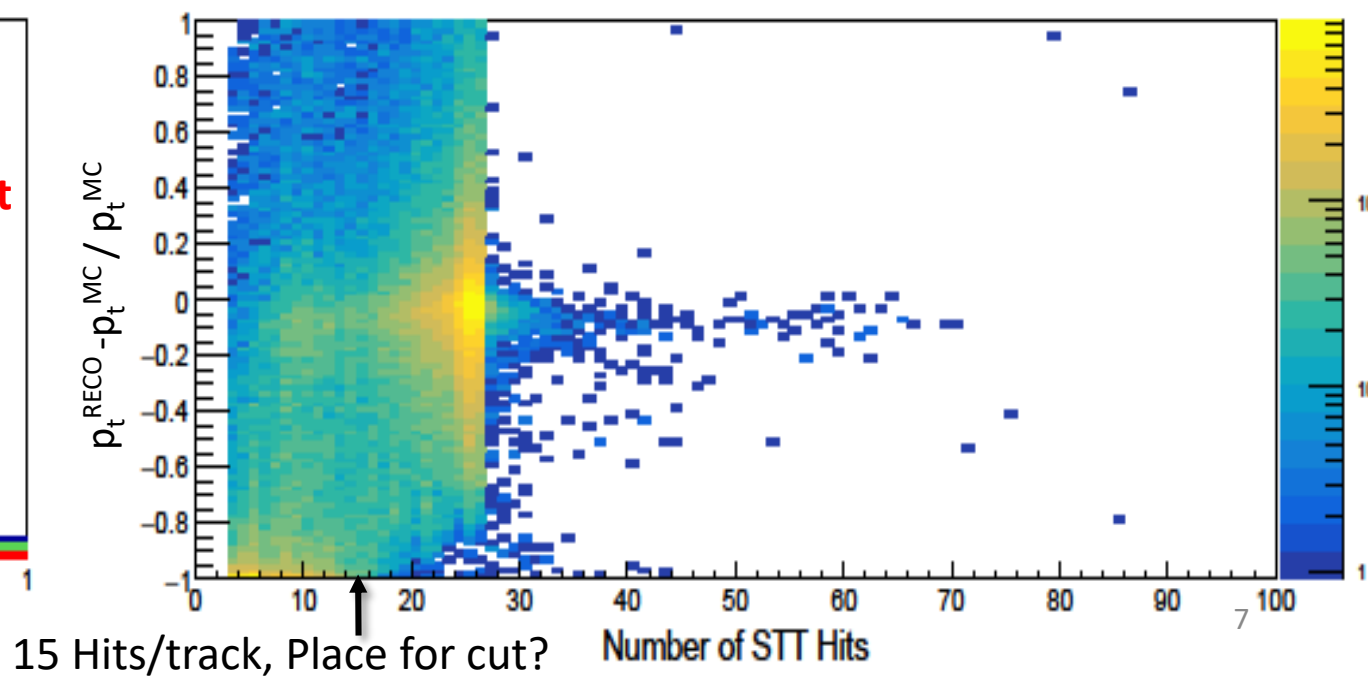
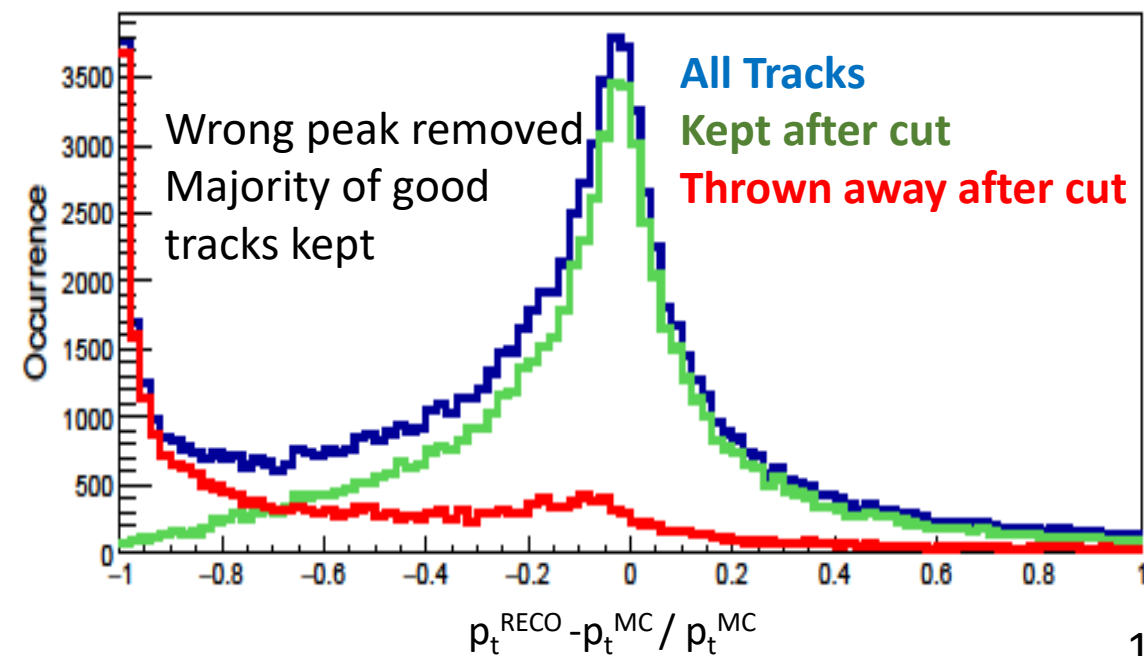
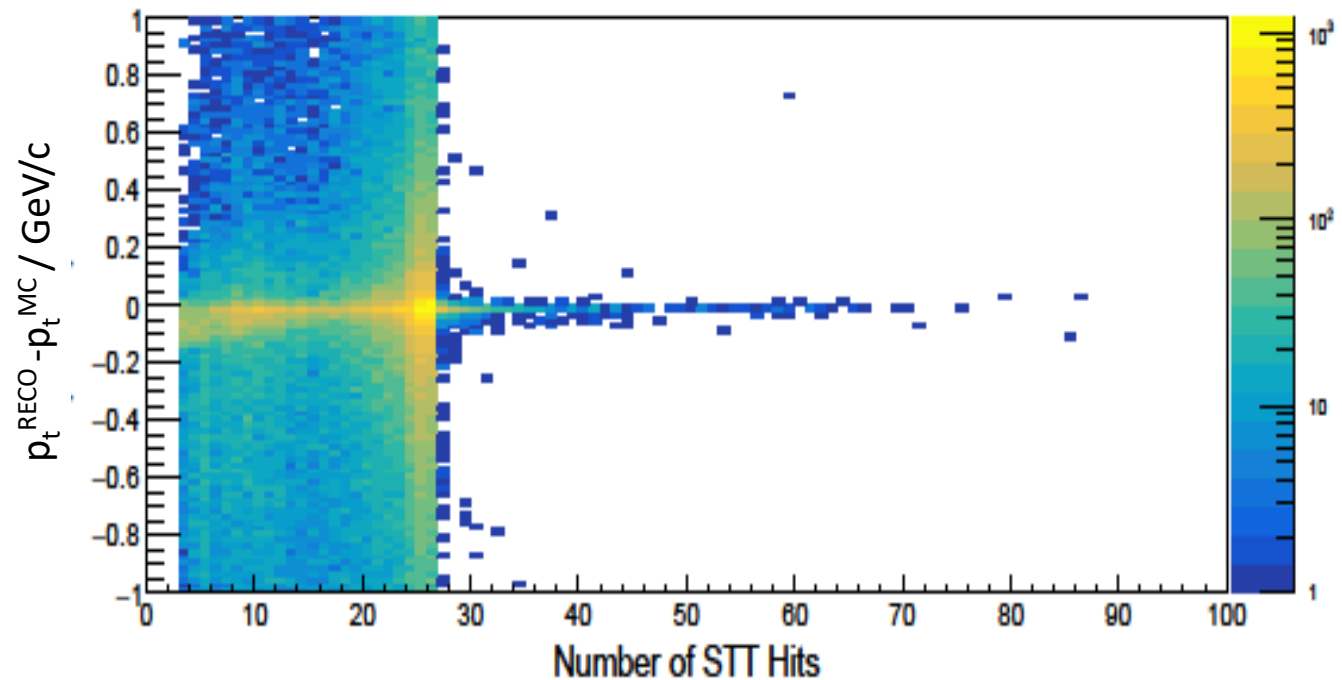
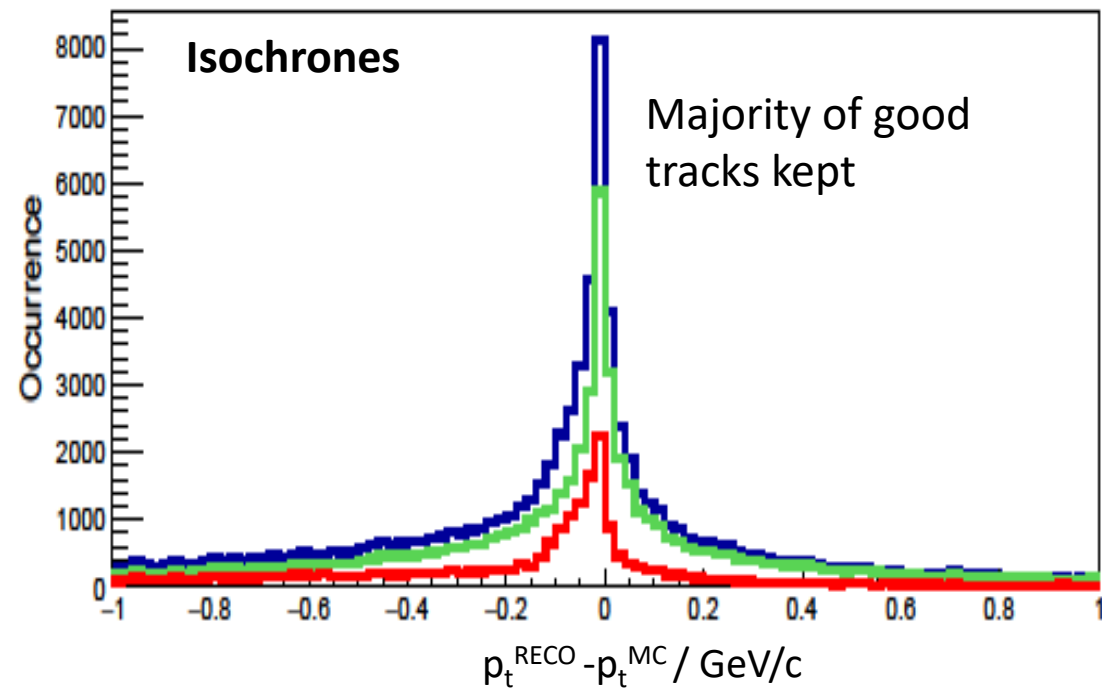
- 100 000 Events
- 1 Muon / Event
- All Muons from IP
- 0.1-5 GeV/c total particle momentum
- Apply SttCellTrackFinder

No Isochrones









Background

Including MVD hits in STT fitted tracks, 3D

- Want to try to include MVD hits in STT fitted tracks for improved momentum resolution
- SttCellTrackFinder makes no assumptions on the origin of the particle
 - Suitable for tracks from displaced vertices
- Expansion of 2D method [1, 2, 3]

[1] <https://arxiv.org/abs/1910.06086>

[2] https://indico.gsi.de/event/7315/contributions/32857/attachments/23675/29668/Jenny_Regina_CM_Stockholm_2018.pdf

[3] https://indico.gsi.de/event/7584/contributions/33670/attachments/24365/30482/TrackingWorkshop_Jenny_Regina_V2.pdf

3D Method

- Take one Riemann track fitted in the STT
 - Can also be other type of tracks
- Take all MVD Hits in one event/burst
 - Add all hits to the track
- Calculate the χ^2/ndf
- Iteratively remove the hits with the largest contribution to the χ^2/ndf

More detailed discussion on:

- Stopping condition
- Should **ALL** MVD hits be tested for compatibility?
 - Geometric considerations
- Weight

$$\chi^2 = \sum \frac{d^2}{\sigma_{hit}^2}$$

Sum over all hits in track

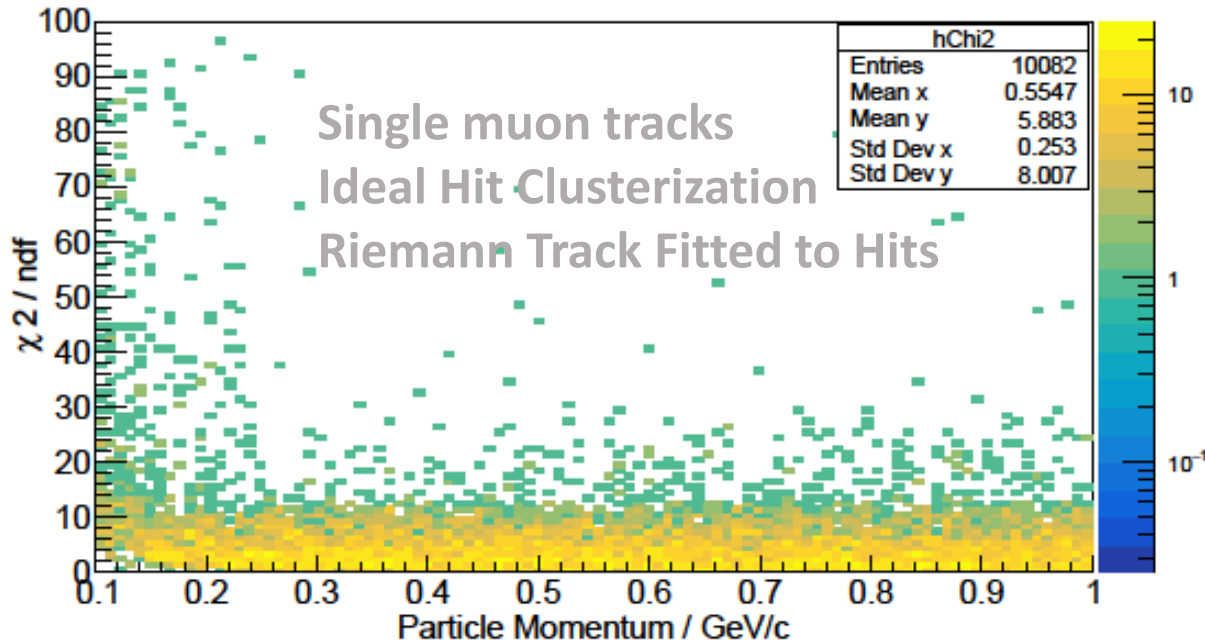
d - 3D distance between track and hit

σ_{hit} - uncertainty in the hit position

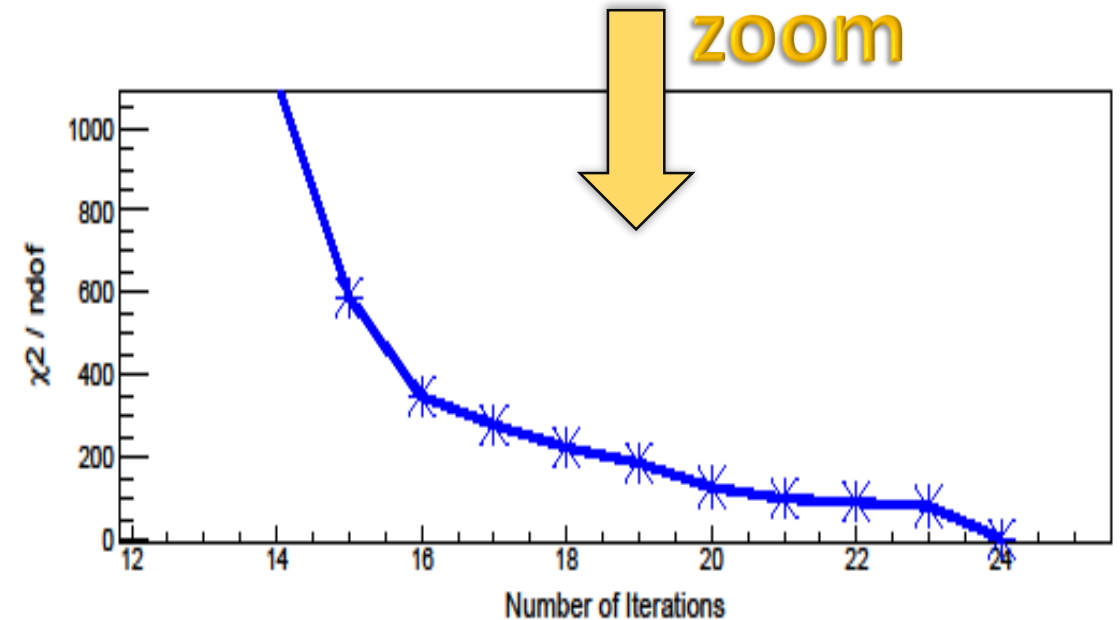
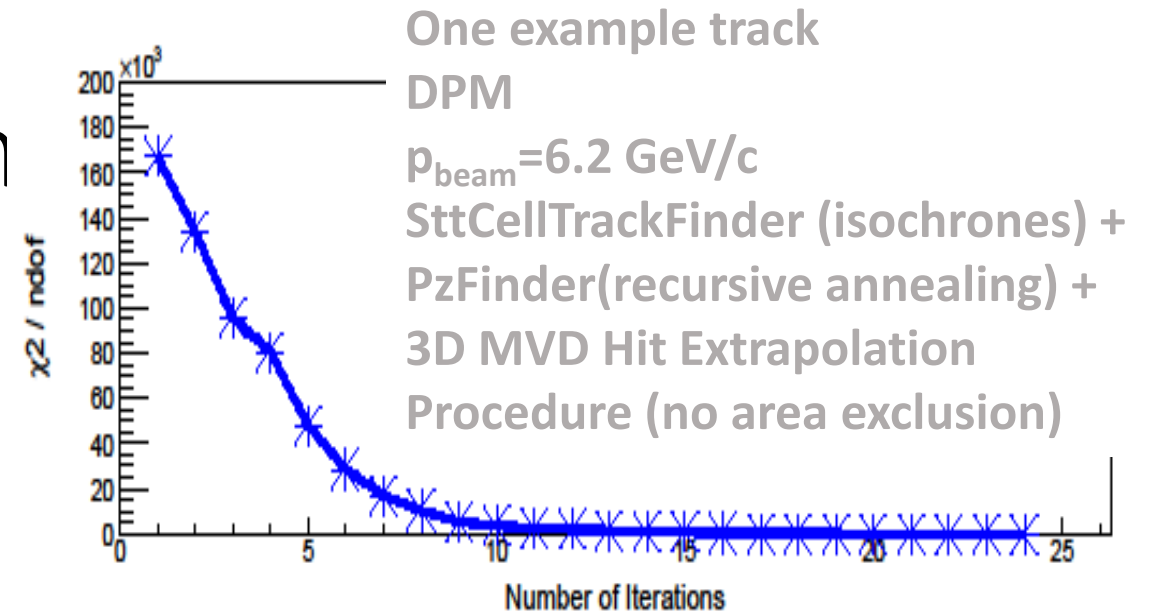
ndf - number of hits in track minus number of constraints (2, radius and center)

- Hits are **weighed** by inverse of their uncertainty **in the fit**
 - $\sigma_{x,y} = 0.002\text{-}0.0085$ cm for MVD
 - $\sigma_{x,y} = 0.015$ cm for STT
- > MVD will contribute with larger weight

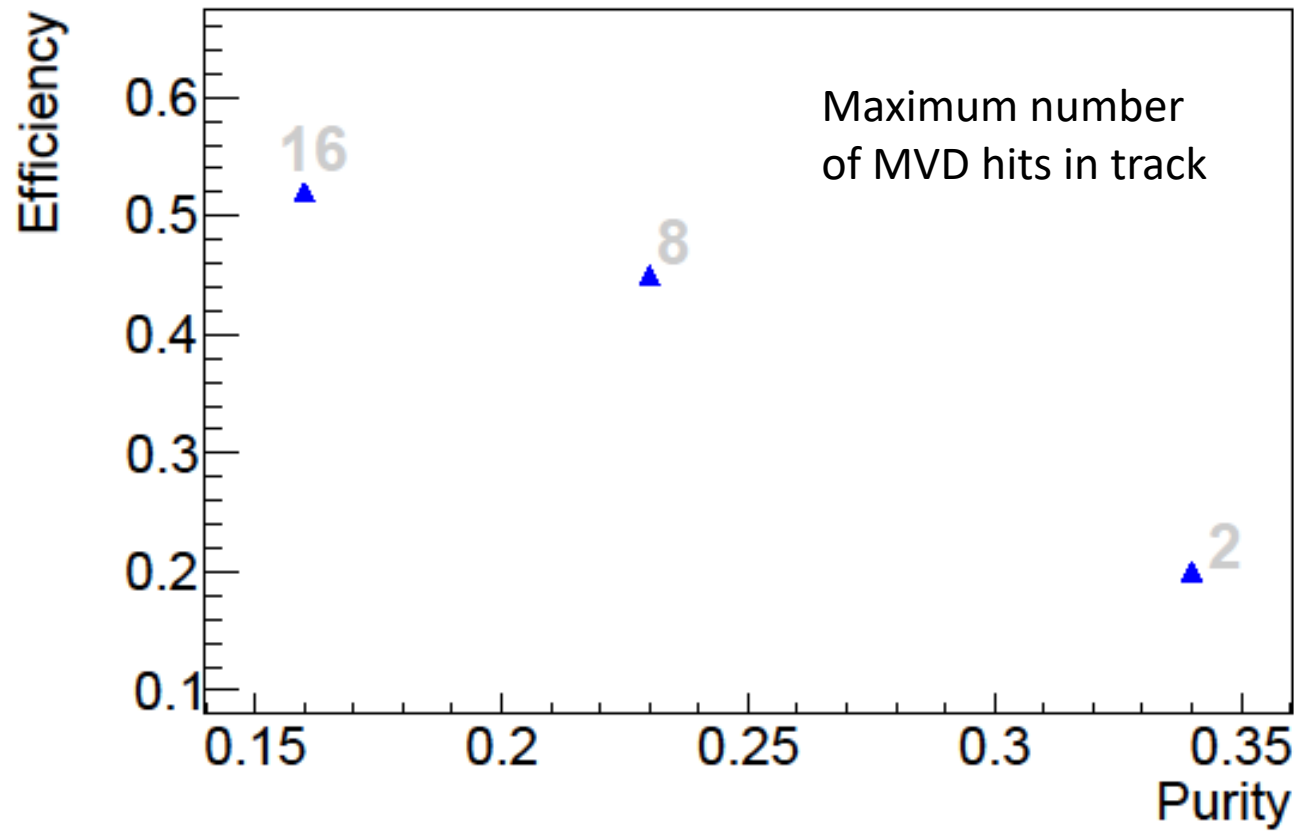
χ^2 as stopping condition



Trying different stopping conditions has not given a clue to what order of magnitude a stopping condition should be within



Stopping Condition

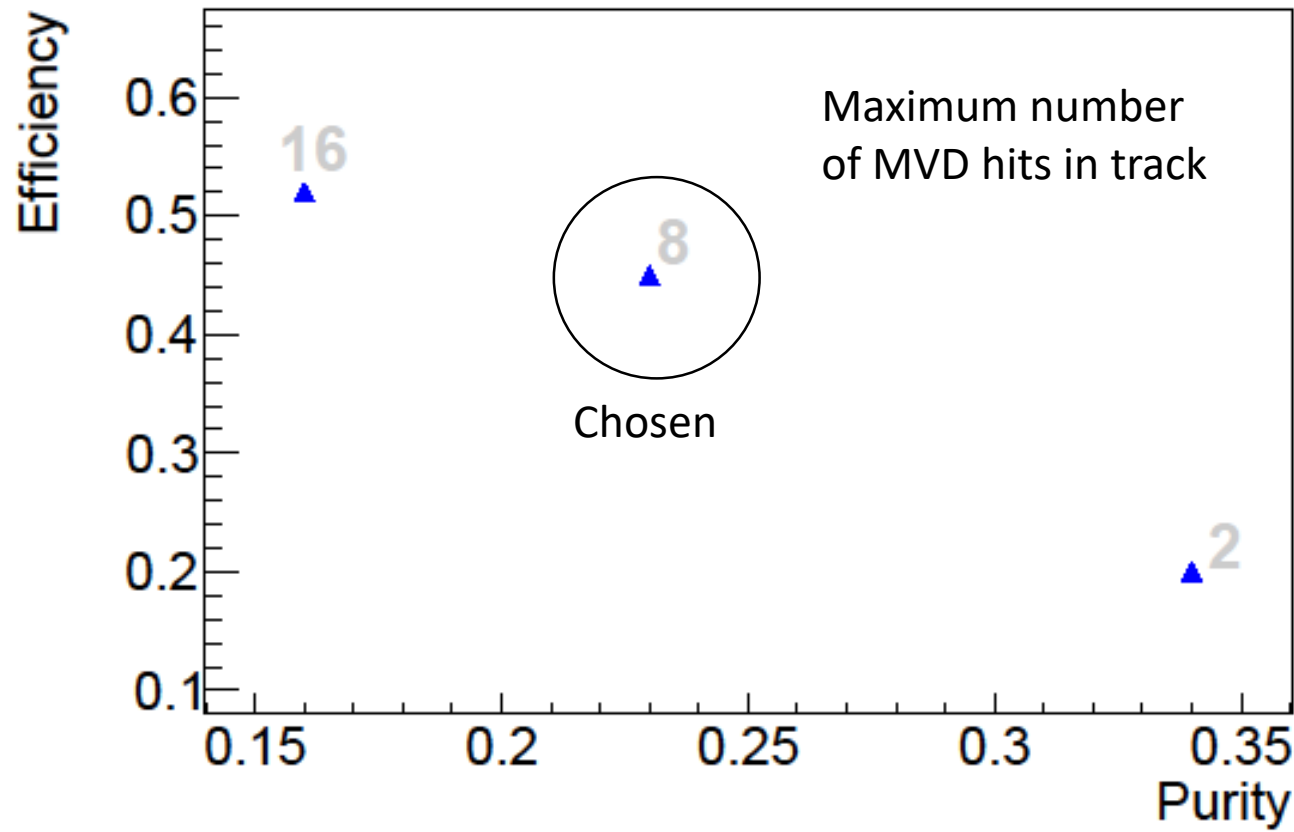


- MVD constructed to give around 4 hits / track
- Quite low efficiency and purity
- ROC curve might not be optimal tool in this case for choosing stopping condition
- Eff and Purity calculated for Pixel and Strip hits for entire track set

$$Eff = \frac{Num\ True\ Hits}{Num\ True\ Hits + Num\ Missing\ Hits}$$

$$Purity = \frac{Num\ True\ Hits}{Num\ True\ Hits + Num\ Fake\ Hits}$$

Stopping Condition

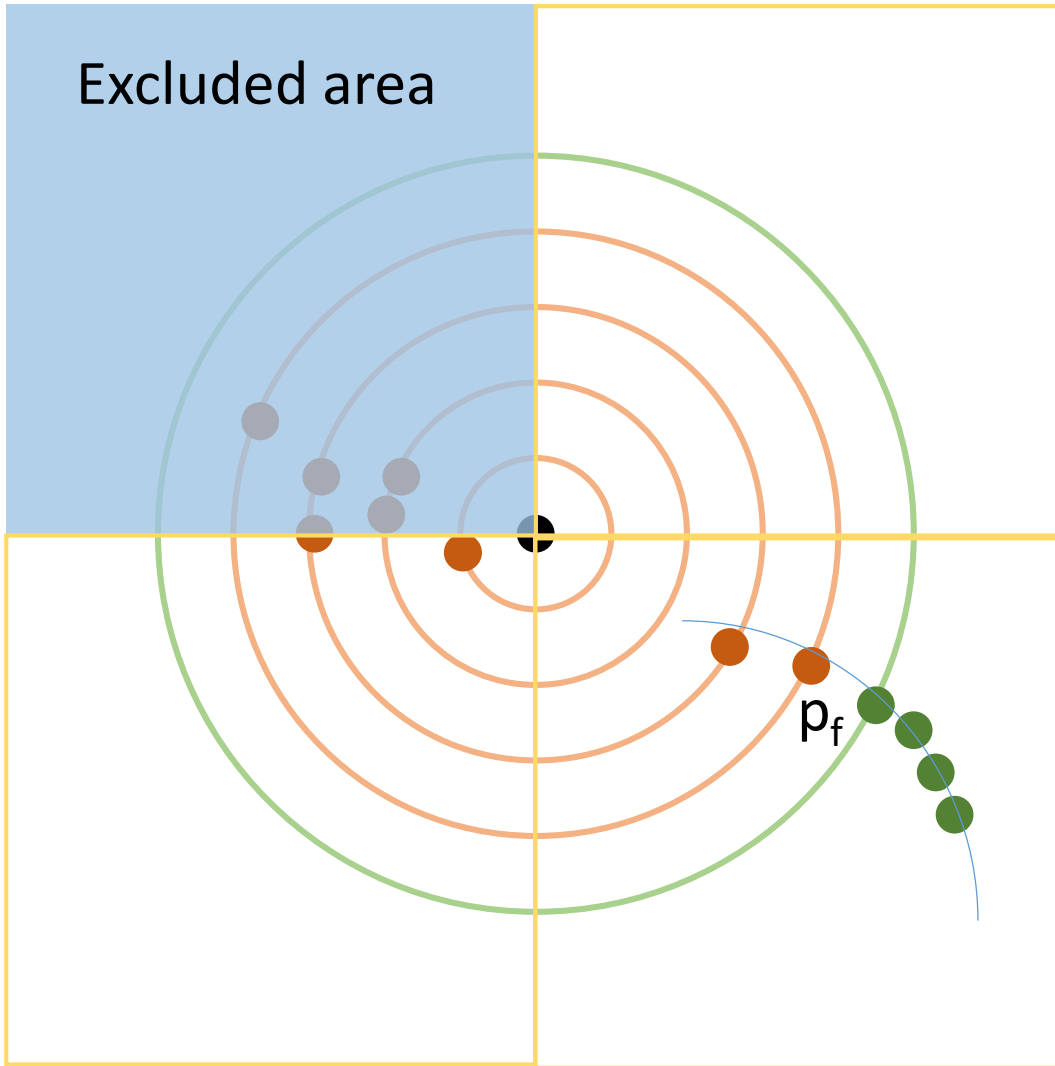


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$$Eff = \frac{Num\ True\ Hits}{Num\ True\ Hits + Num\ Missing\ Hits}$$

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Area Exclusion



Method 1: Defining Quadrants

P_f : first hit in track

p : MVD hit to be tested

If $\text{sign}(x_{p_f}) \neq \text{sign}(x_p)$ and $\text{sign}(y_{p_f}) \neq \text{sign}(y_p)$

Reject Hit;

Else

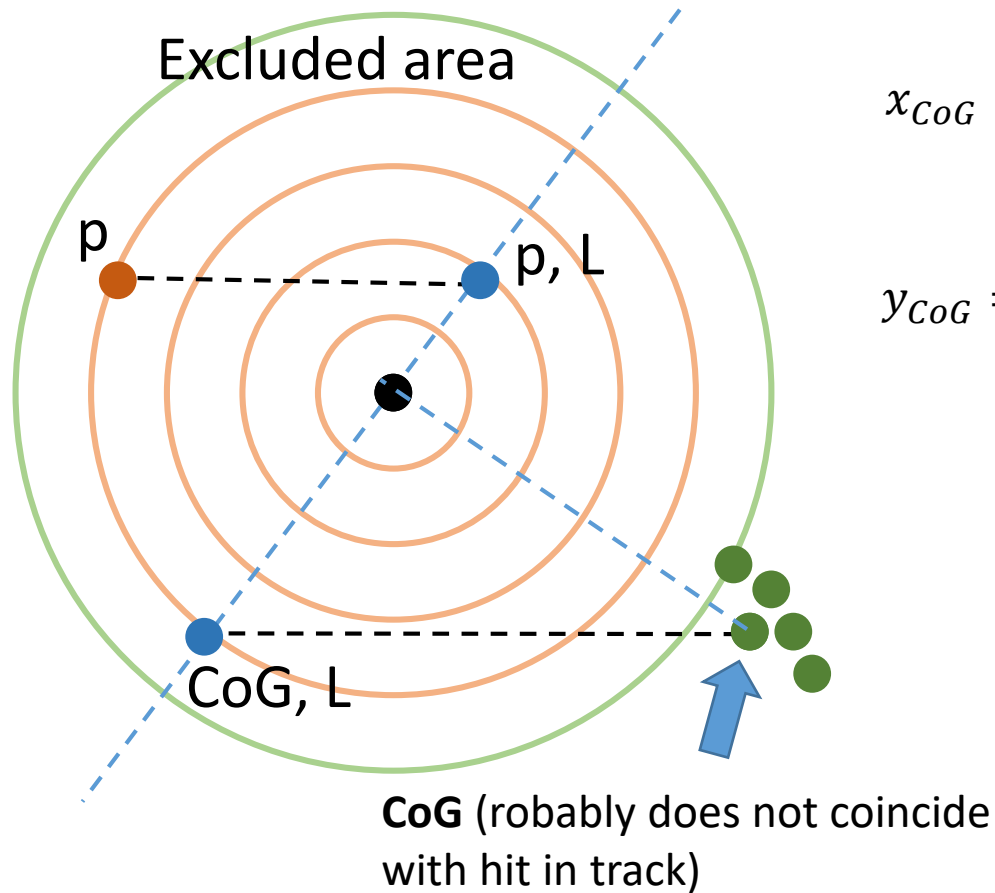
Accept Hit;

Downsides of method:

“Non-adaptive” within the limits of the quadrants

Much power is given to only the first hit

Method 2: Defining Hemisphere



Calculate **Center of Gravity** for all STT hits in track:

$$x_{CoG} = \sum_{i=0}^N \frac{x_i}{\sigma_{x_i}^2} \frac{1}{N}$$

$$y_{CoG} = \sum_{i=0}^N \frac{y_i}{\sigma_{y_i}^2} \frac{1}{N}$$

N – number of hits in track

x_i, y_i – 2D coordinate of hit i

$\sigma_{x_i}, \sigma_{y_i}$ – uncertainty in coordinate

If p on opposite side of line L compared to CoG

Reject Hit;

Else

Accept Hit;

Upside of method:

Adaptive

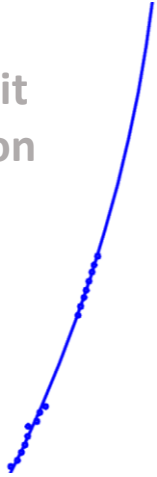
Information from all hits taken into account

Mathematical derivations in Backup!

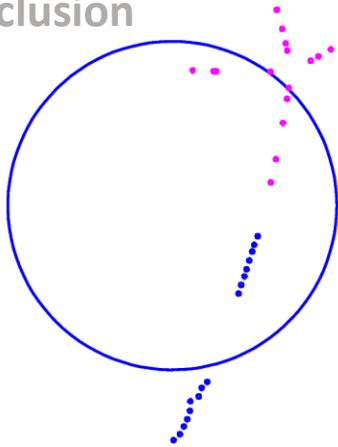
Weight of Hits

No Weights

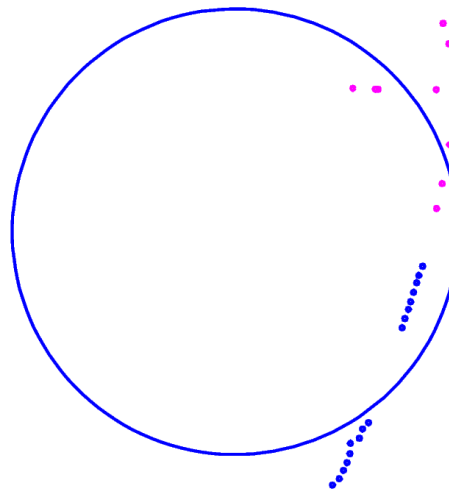
Before
MVD Hit
Inclusion



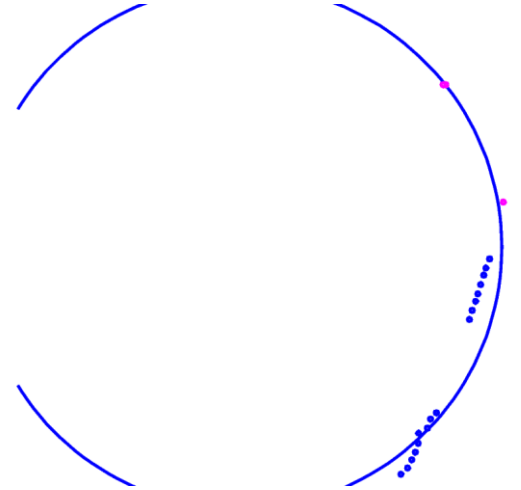
After
MVD Hit
Inclusion



After iteration
5

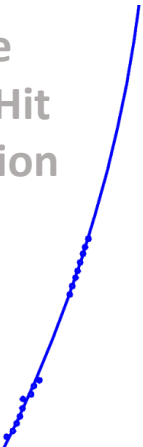


3 MVD Hits
Left
After iteration
13

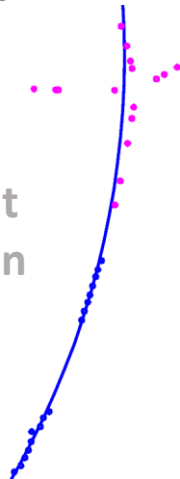


With Weight 10 corresponding to MVD hit uncertainty 0.1 cm

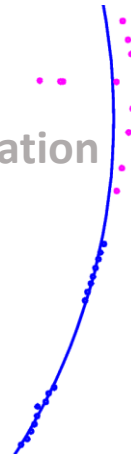
Before
MVD Hit
Inclusion



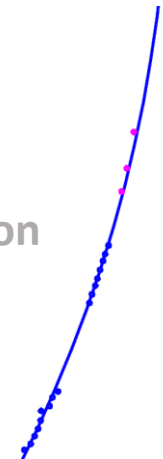
After
MVD Hit
Inclusion



After iteration
5



3 MVD Hits
Left
After iteration
13



Simulation Details for Results

- 10 000 DPM Events
- $p_{\text{beam}} = 6.2 \text{ GeV}/c$
- Event Based digitization
- Reconstruction
 - SttCellTrackFinder with isochrone correction
 - P_z -finder with Recursive annealing fit
 - 3D Mvd Hit finder with weight = 10
- Quality Assurance
 - Standard Track Functor: $\geq 4 \text{ MVD}$ or $\geq 6 \text{ MVD+STT+GEM hits}$

Results

	Pre-extrapolation	No Area Exclusion	Quadrant	Hemisphere
Number of possible tracks	29 493	29 493	29 493	29 493
Found Tracks:	11 347	9 503	9 648	10 574
Efficiency:	38 %	32 %	33 %	36 %

Track Category	Pre-extrapolation	No Area Exclusion	Quadrant	Hemisphere
Fully Pure	334	58	136	189
Fully Impure	0	0	0	0
Partially Pure	9 716	515	770	5 987
Partially Impure	1 297	8 930	8 742	4 398
Ghosts	1 489	4 056	3 871	2 579
Clones	1 932	1 915	1 919	1 924

Main Improvements going from Quadrant to Hemisphere:

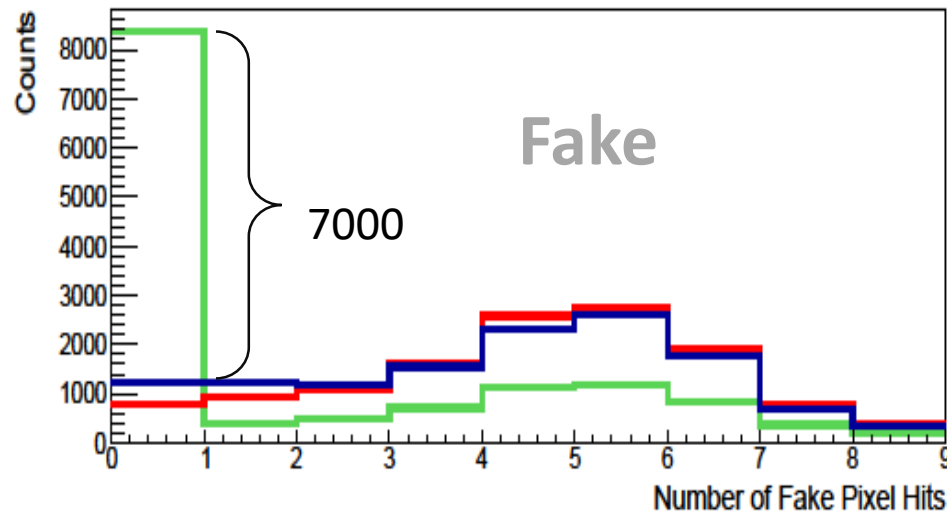
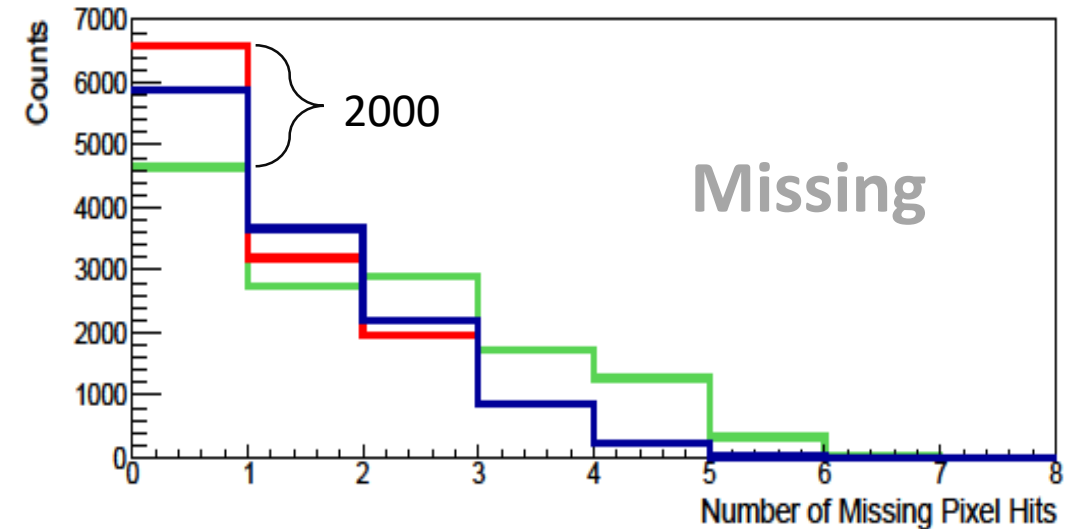
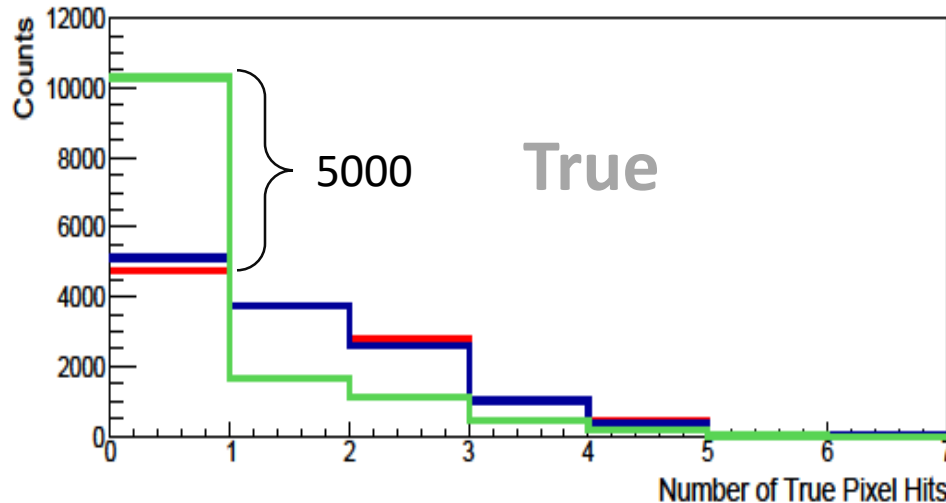
- Ghosts 13.1 % → 8.7 %
- More than half of all partially impure tracks pushed to partially pure category

Hit finding efficiency, pixels

No area excluded

Quadrant excluded

Hemisphere excluded



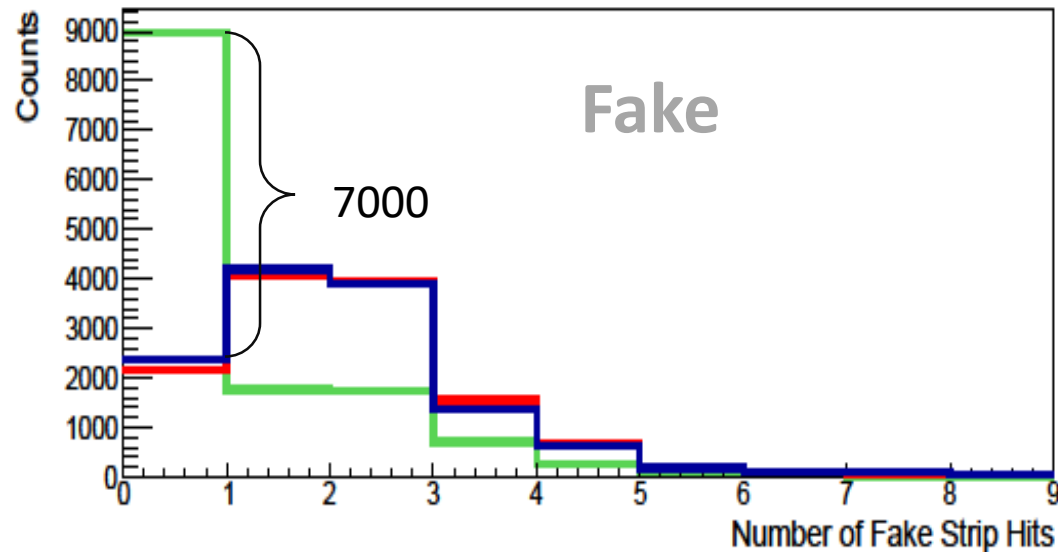
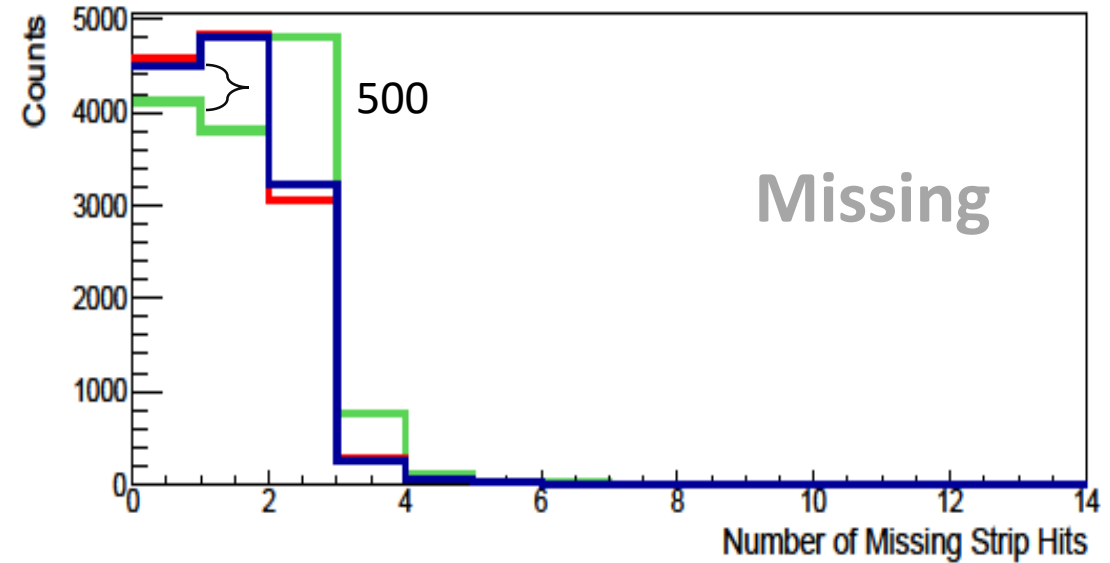
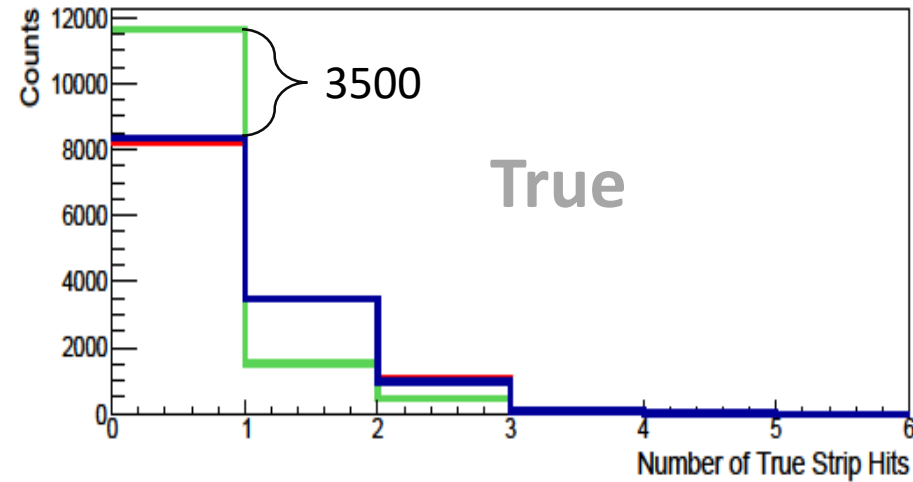
- Number of true hits/track somewhat reduced with hemisphere-method
- **Fake hits/track greatly reduced with hemisphere-method**
- Number of missing hits/track does not drastically increase with this method

Hit finding efficiency, strips

No area excluded

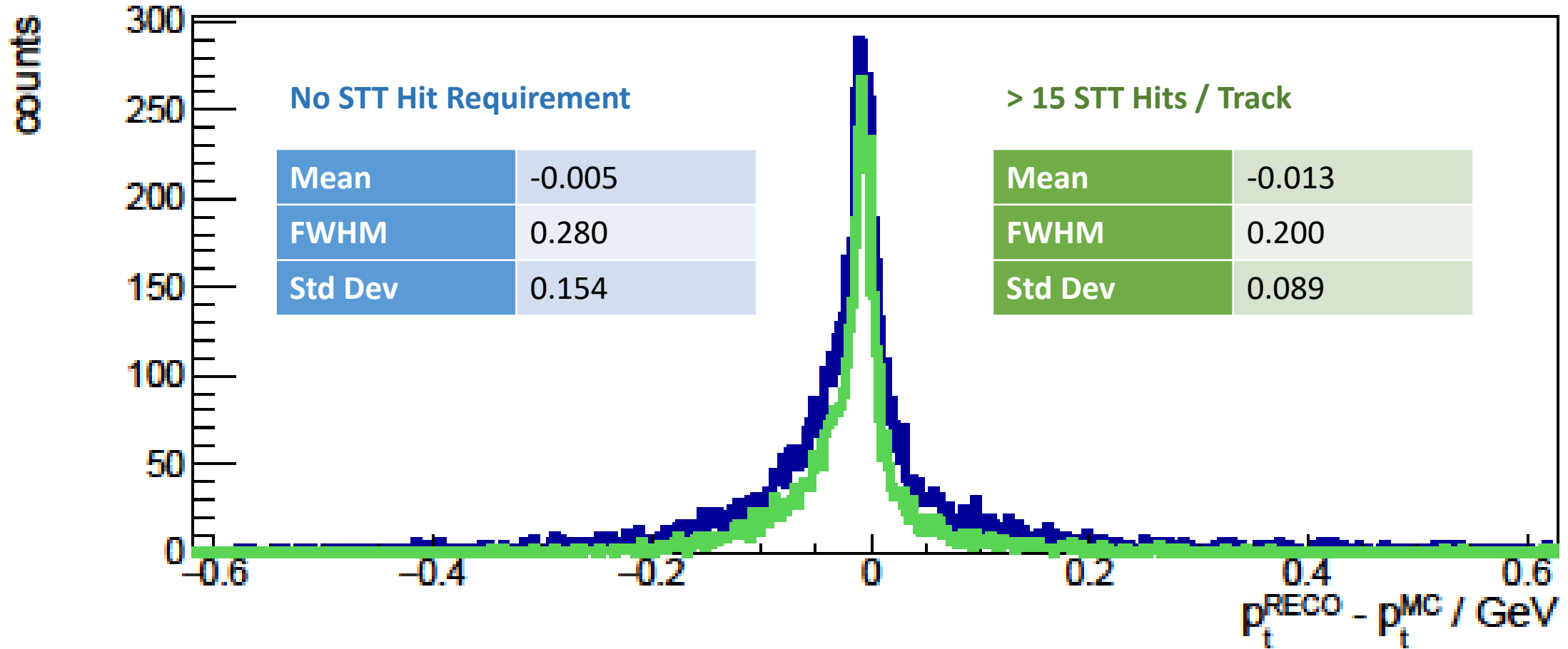
Quadrant excluded

Hemisphere excluded

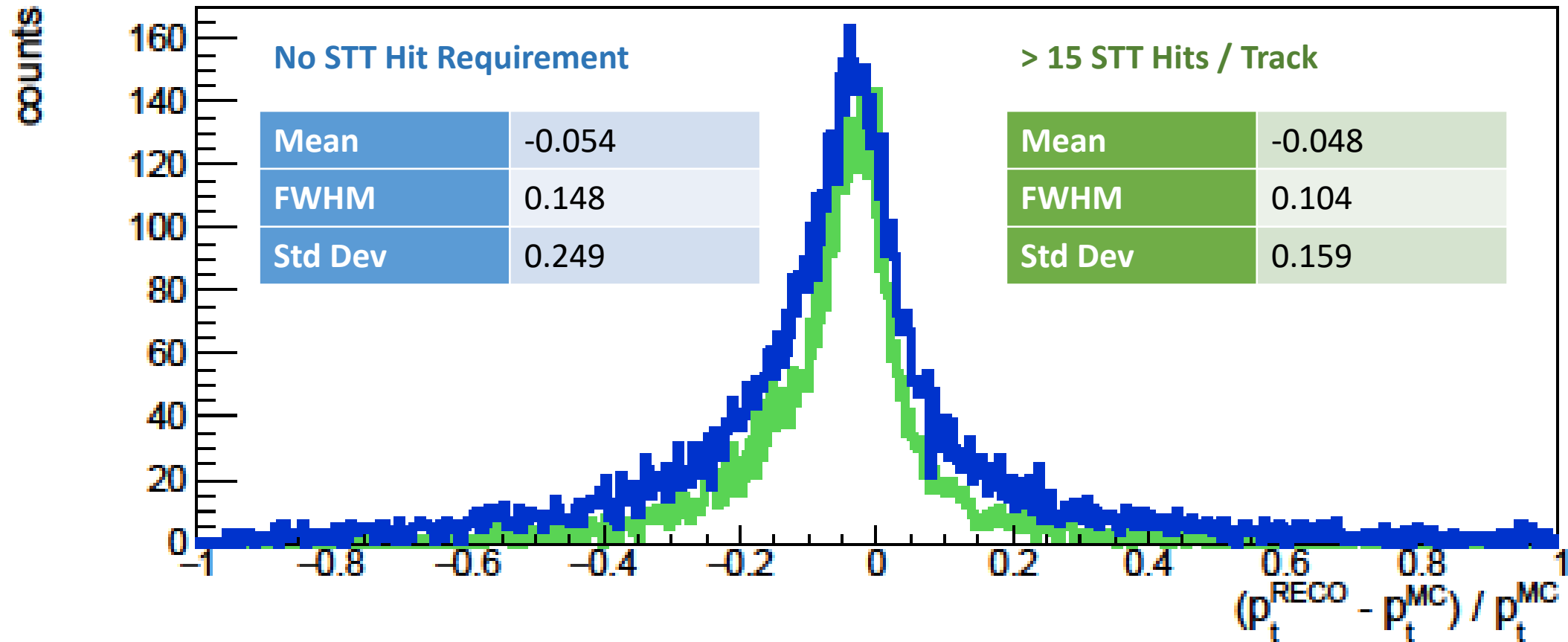


- Number of true hits/track somewhat reduced with hemisphere-method
- **Fake hits/track greatly reduced with hemisphere-method**
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Transverse Momentum Resolution



Relative Transverse Momentum Resolution



Summary

- SttCellTrackFinder: Momentum resolution of tracks with > 15 hits tend to be better than for shorter tracks
- 2D and 3D methods have been developed for assigning MVD hits to tracks reconstructed in other detectors. Optimizations needed

Outlook

- Memo currently in progress
- Code cleanup and merging
- Improve the hit finding purity and efficiency by combining the extrapolation method with local hit clustering in the MVD
- Use together with a primary (=suitable mainly for tracks from IP) track finder

Summary

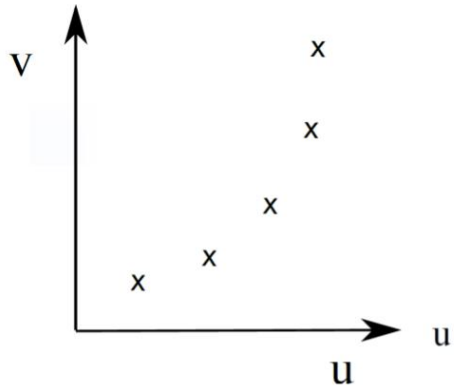
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Thank You!

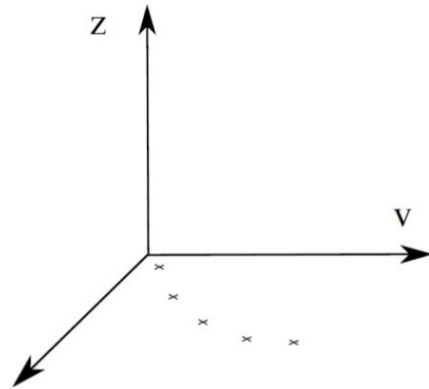
Backup

The Riemann Fit

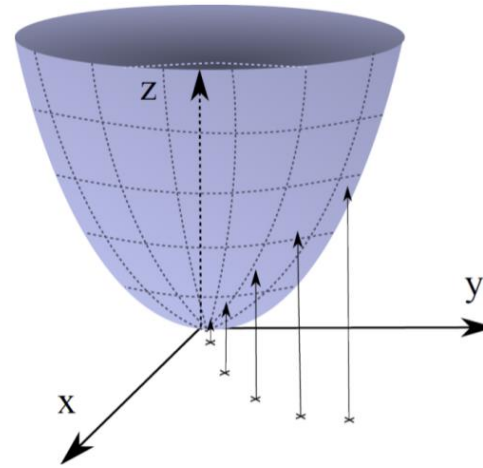


Points to be fitted

For STT, $u=x$, $v=y$

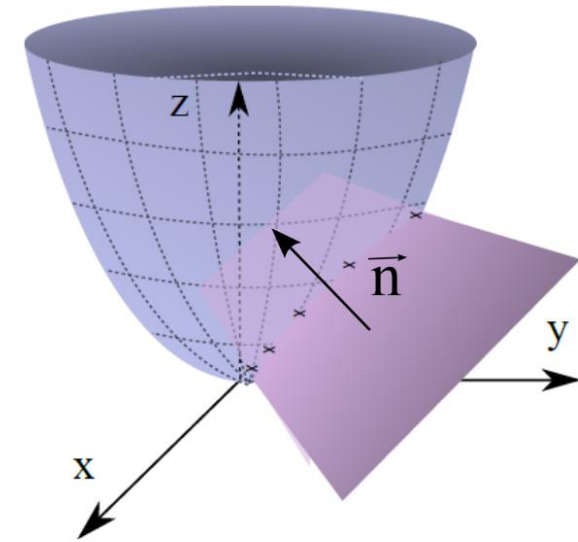


Add z-dimension



Map onto paraboloid

$$z=x^2+y^2$$



Calculation of plane
through 3D points
simple eigenvalue determination

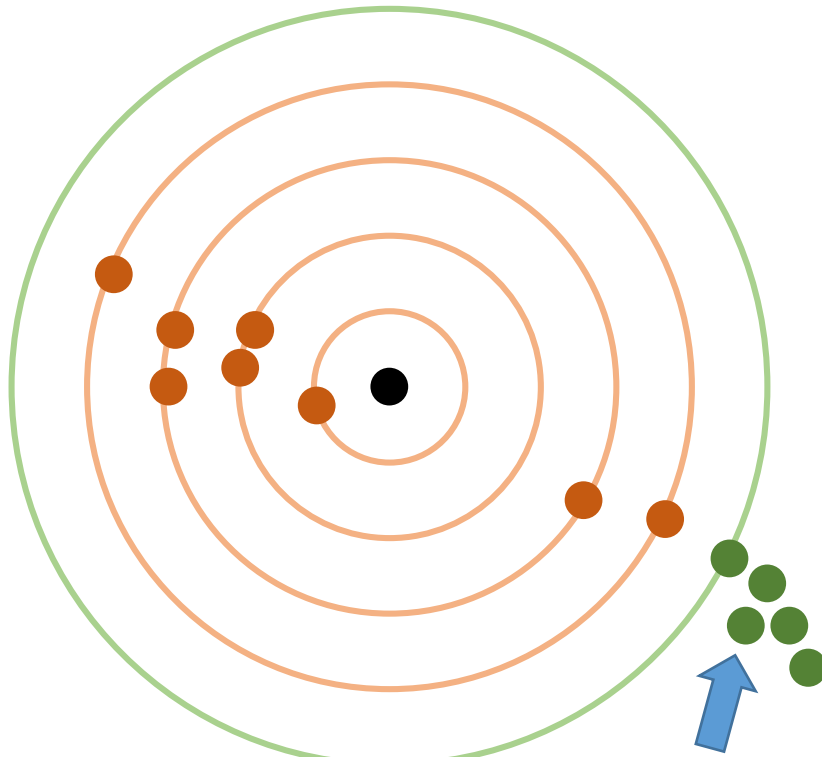
From \vec{n} , circle parameters are known:

$$\left. \begin{aligned} u_0 &= -\frac{n_1}{2n_3} \\ v_0 &= -\frac{n_2}{2n_3} \end{aligned} \right\} \text{Circle center}$$

$$\rho^2 = \frac{1 - n_3^2 - 4cn_3}{4n_3^2} \quad \text{Radius}$$

$$c+n_1x+n_2y+n_3z=0$$

Method 2: Defining Hemispheres

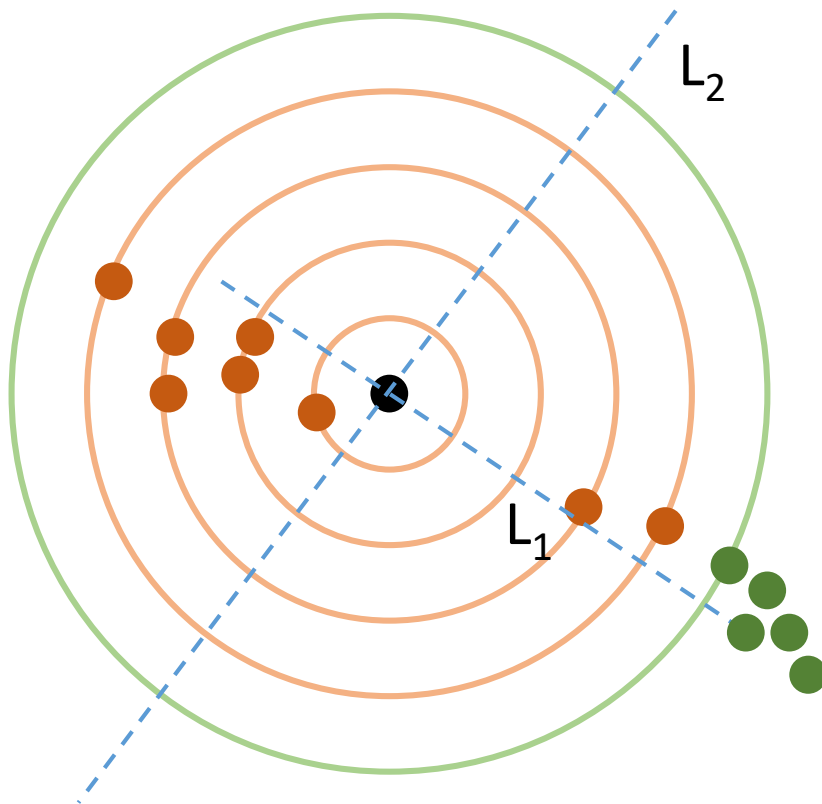


CoG (robably does not coincide with a hit in the track)

Calculate **C**enter **o**f **G**ravity
for all STT hits in track:

$$x_{CoG} = \sum_{i=0}^N \frac{x_i}{\sigma_{x_i}^2} \frac{1}{N}$$

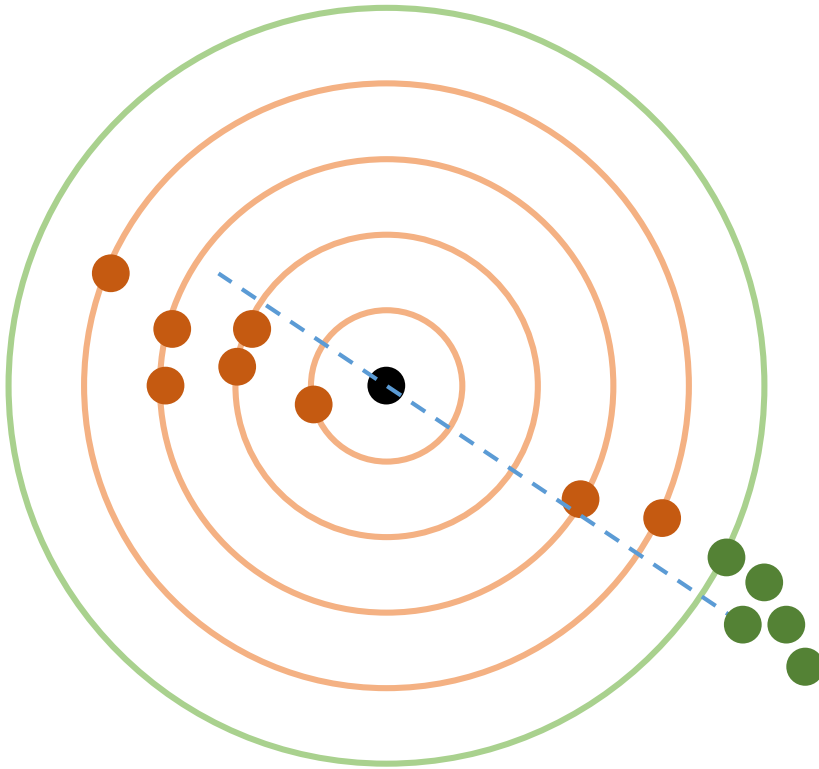
$$y_{CoG} = \sum_{i=0}^N \frac{y_i}{\sigma_{y_i}^2} \frac{1}{N}$$



$$L_1: y = \frac{y_{CoG}}{x_{CoG}} x$$

$$L_2: y = -\frac{x_{CoG}}{y_{CoG}} x$$

Slope of L2 = -1/L1 since they are perpendicular



Calculate Center of Gravity
for all STT hits in track:

$$x_{CoG} = \sum_{i=0}^N \frac{x_i}{\sigma_{x_i}^2} \frac{1}{N}$$

$$y_{CoG} = \sum_{i=0}^N \frac{y_i}{\sigma_{y_i}^2} \frac{1}{N}$$

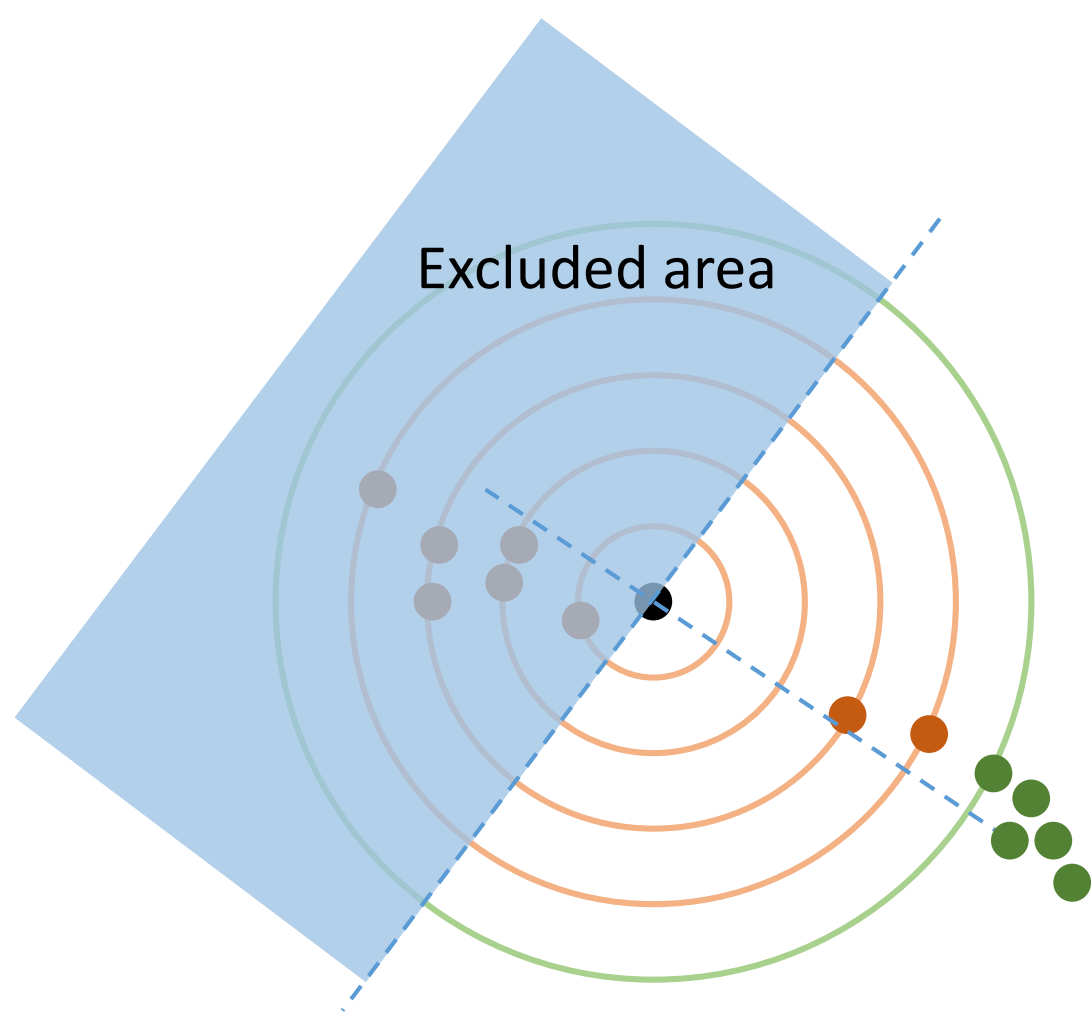
Find line going through CoG
and Origin:

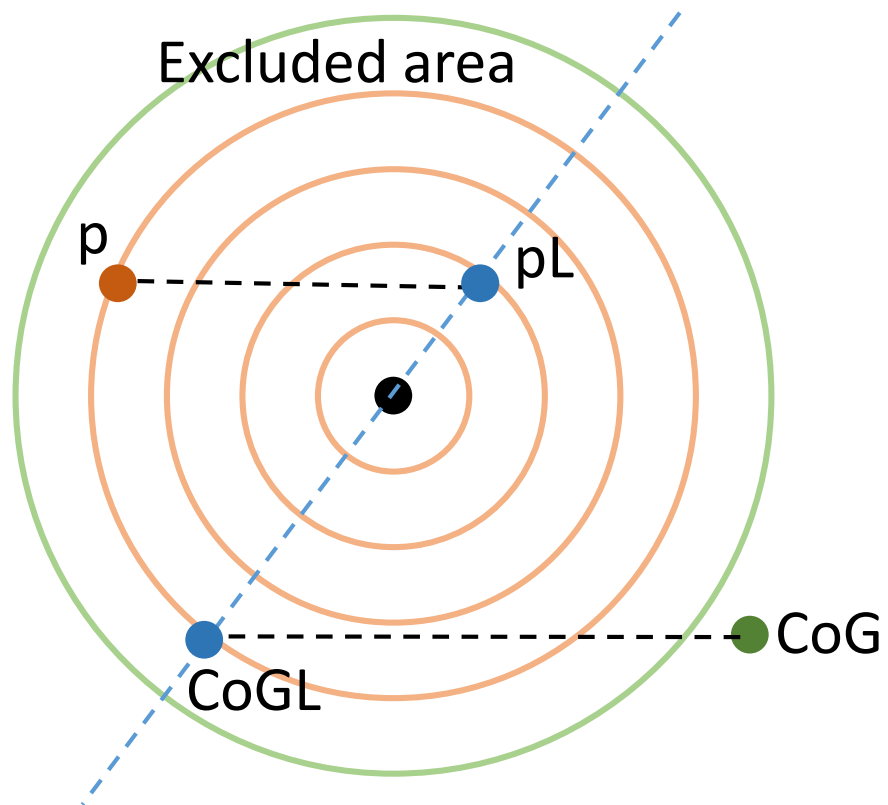
$$y = kx + m \rightarrow$$

$$y = \frac{y_1 - y_2}{x_1 - x_2} x + m$$

m=0 (line going
through origin)

$$y = \frac{y_1}{x_1} x = \frac{y_{CoG}}{x_{CoG}} x$$





$$y = -\frac{x_1}{y_1}x \rightarrow x_{pL} = -\frac{y_1}{x_1}y_p$$

$$y = -\frac{x_1}{y_1}x \rightarrow x_{CoGL} = -\frac{y_1}{x_1}y_{CoG}$$

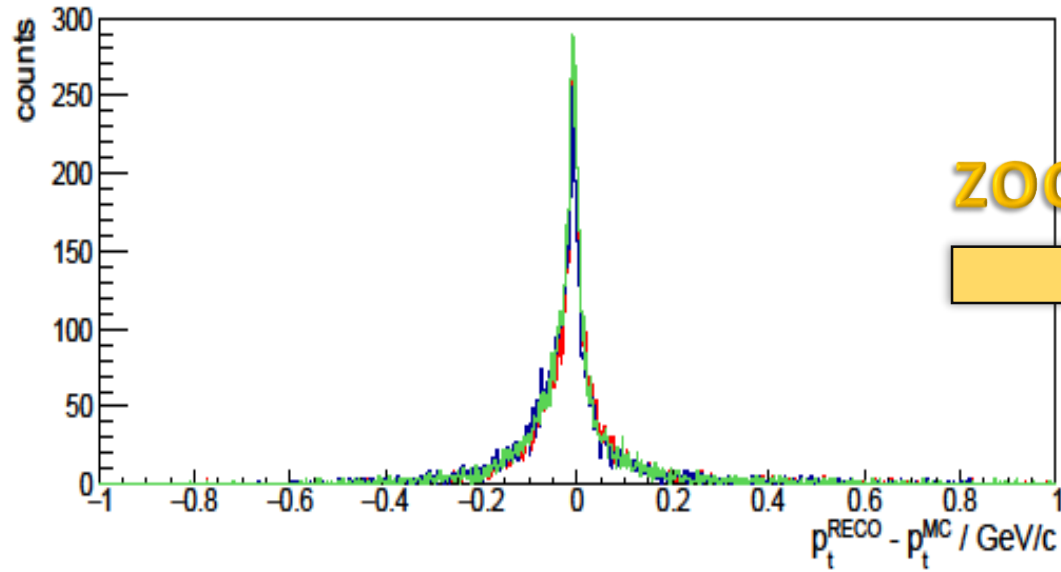
If $\text{sign}(x_{pL}-x_p)=\text{sign}(x_{CoGL}-x_{CoG})$
Accept Hit;

If $(x_{pL}-x_p)=0$ or $(x_{CoGL}-x_{CoG})=0$
Accept hit;

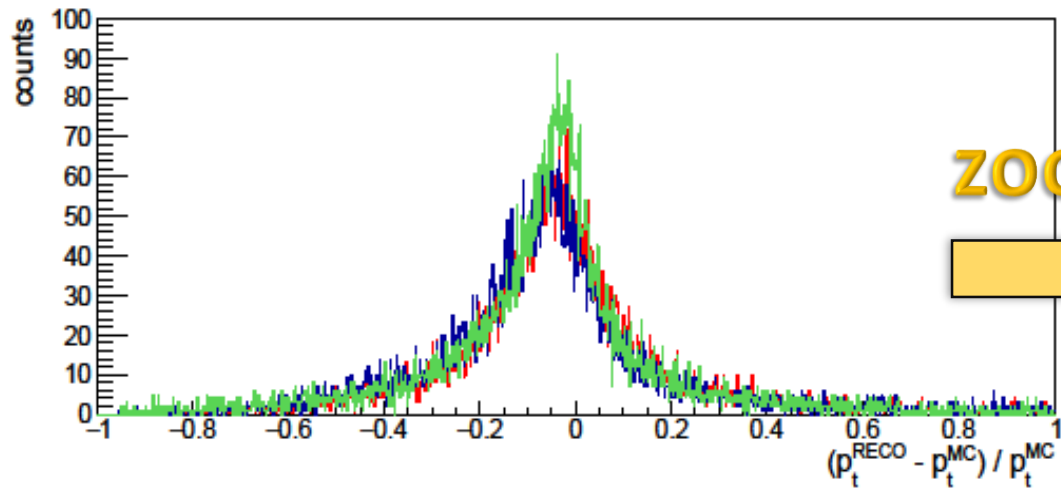
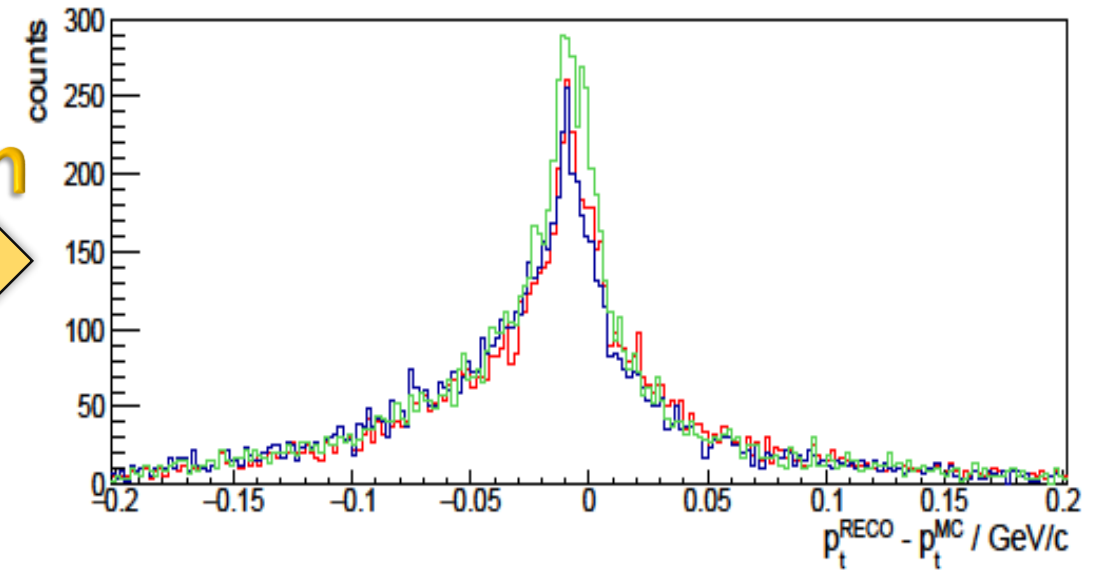
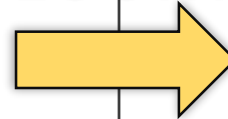
Else
Reject Hit;

Momentum Resolutions

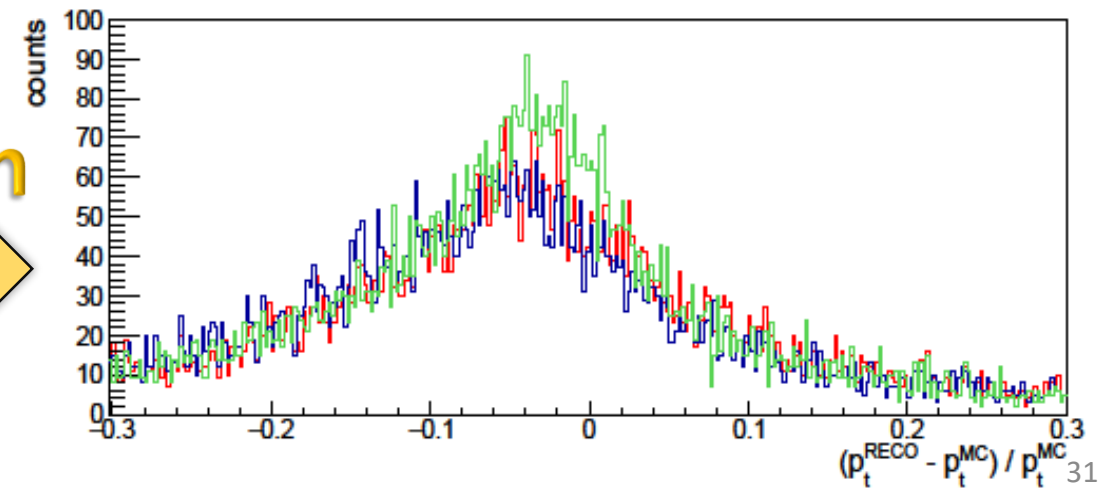
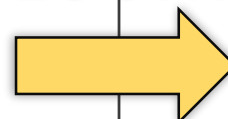
No area excluded
Quadrant excluded
Hemisphere excluded



zoom



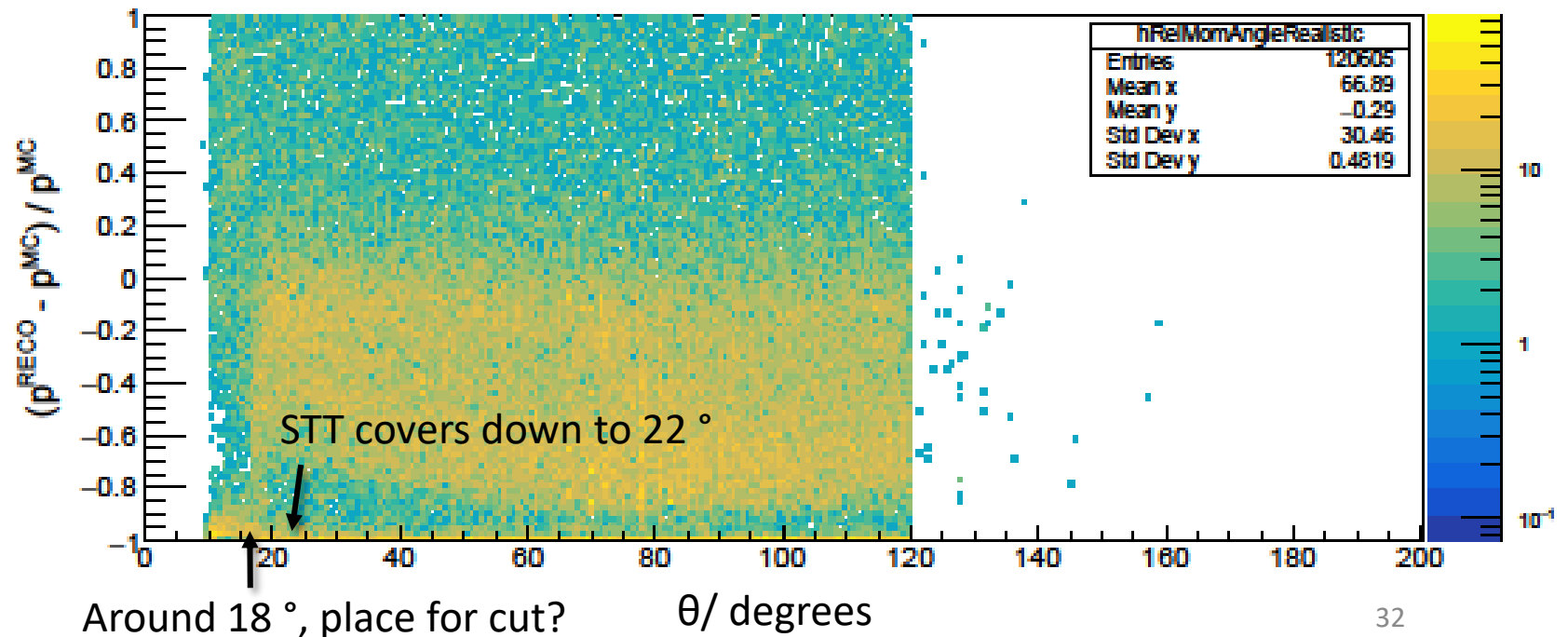
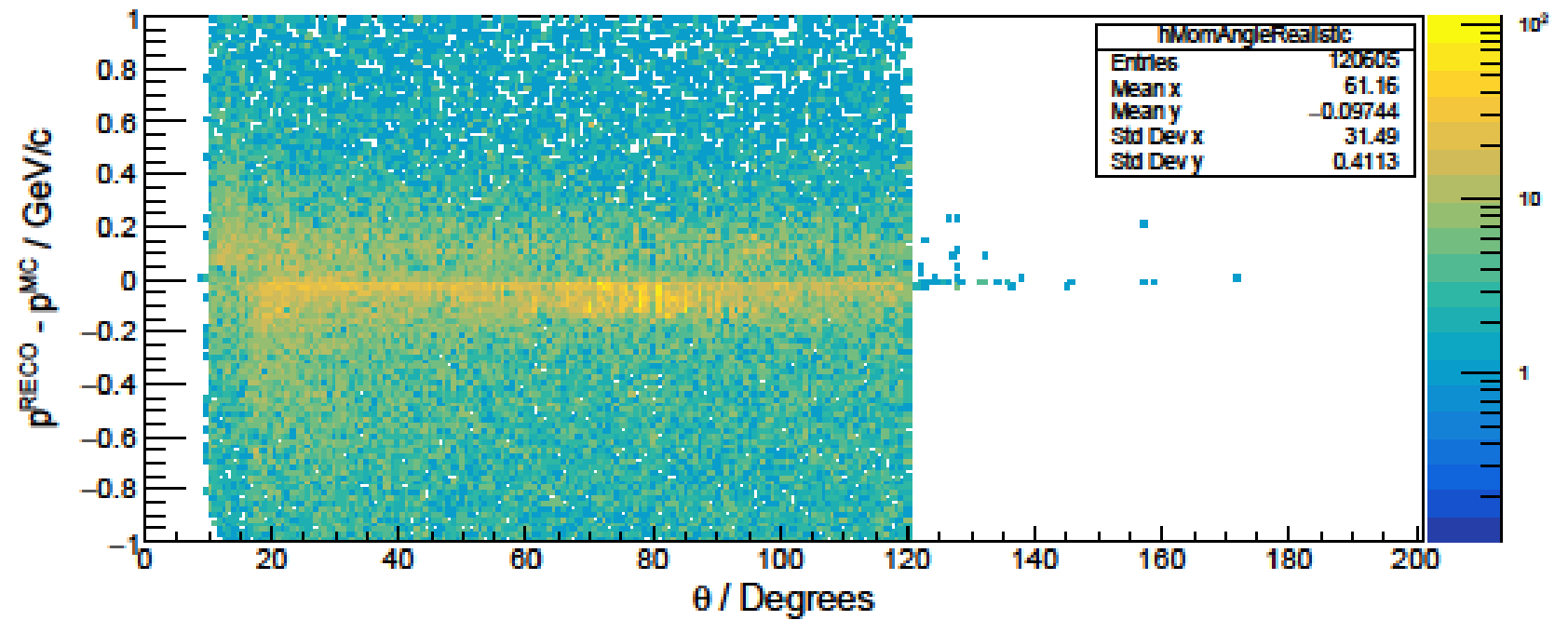
zoom



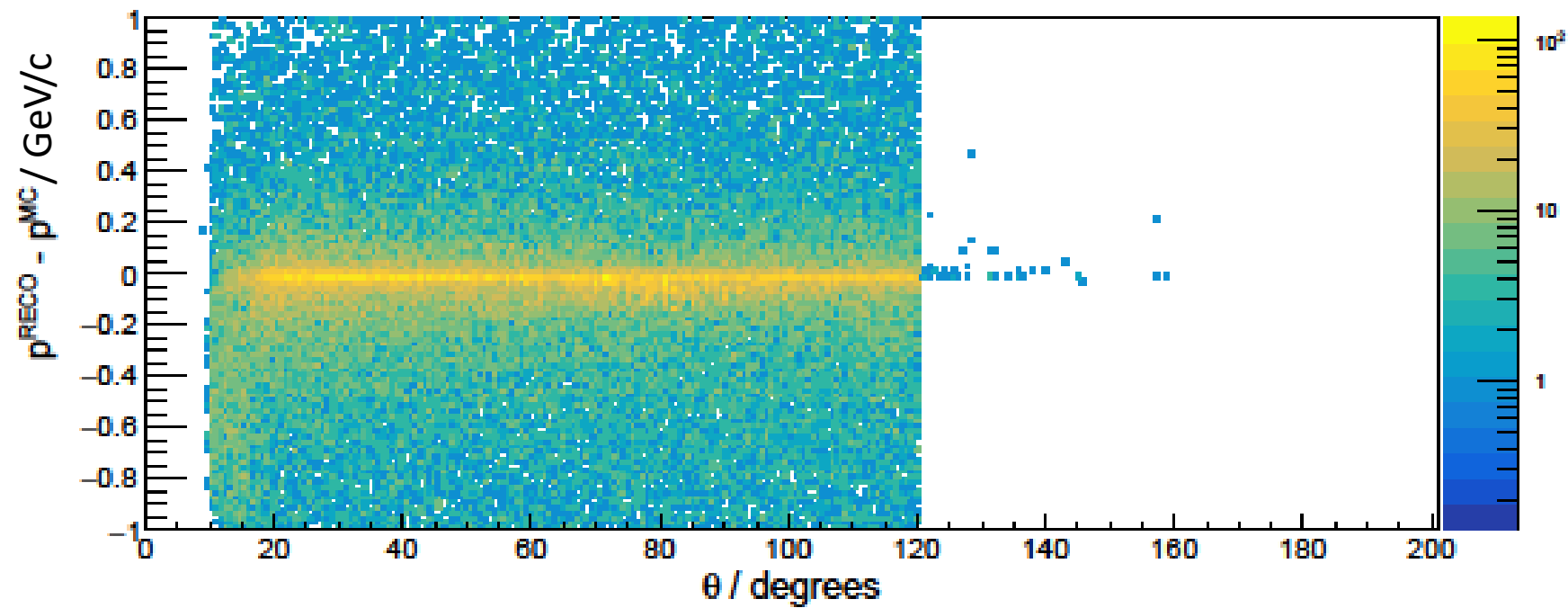
No Isochrones



- Not use as first cut
- Use as refining momentum resolution if needed



Isochrones



- Not use as first cut
- Use as refining momentum resolution if needed

