



# Status of Vertex and Kinematic fitting for Panda

Vishwajeet Jha

(For the Panda Collaboration)

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## Outline:

- Introduction
- Vertex and kinematic Fitting with constraints
- Tests of Vertex & kinematic fitters
- Steps towards decay tree fitting
- Summary & Outlook

# Introduction:

- Vertex Fitting: To find the vertex position compatible with reconstructed tracks, Also its errors with fit probability
- Kinematic Fitting : Kinematic relation between particles imposed, fit probability to make cuts
- Improved track parameters for the daughter particles and new covariance matrix
- Track parameter of virtual particles and its covariance matrix

# Vertex and Kinematic Fitting Methods:

Solution can be obtained by using the least square minimization (LSM)

$$\chi^2 = (\alpha - \alpha_0)^T V_{\alpha_0}^{-1} (\alpha - \alpha_0)$$

$\alpha_0$  Track parameters from track fit ,  $V_{\alpha_0}$  Covariance Matrix from track fit

$\alpha$  New parameters, Iterations are needed to converge to the real solution

Methods :

- i) Lagrange multiplier method
- ii) Kalman Filter technique

## Vertex and kinematic Fitting method :

Constraint equations are applied for Vertex and kinematic fitting .

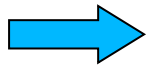
The constraint equation  $H(\alpha) = 0$  is linearized around suitable point  $(\alpha_a, x_a)$

$$\chi^2 = (\alpha - \alpha_0)^T V_{\alpha 0}^{-1} (\alpha - \alpha_0) + \lambda (D(\alpha - \alpha_a) + E(x - x_a) + d)$$

$D$  is derivative w.r.t  $\alpha$ ,

$E$  is derivative w.r.t  $x$ ,

$d$  is the value,  $H(\alpha_a, x_a)$



Minimize  $\chi^2$  with respect to  $\alpha$ ,  $x$  and  $\lambda$

## Vertex Fitting Outputs :

New Track parameters :  $\alpha = \alpha_0 - V_{\alpha 0} D^T \lambda$

New Covariance Matrix :  $V_{\alpha} = V_{\alpha 0} - V_{\alpha 0} D^T V_D D V_{\alpha 0} + V_{\alpha 0} D^T V_D E V_x E^T V_D D V_{\alpha 0}$

New Vertex Position :  $x = x_0 - V_{x 0} E^t \lambda$

Track parameters for the vertexed particle :  $x_V = x ; p_V = A \alpha + B x$

Vertex Covariance matrix :  $V_x$  &  $cov(\alpha, x) = - V_{\alpha 0} D^T V_D E V_x$

Covariance Matrix for the vertexed particle :

*Based on notes by Paul Avery*

## Constrained Vertex Fitting :

Vertex Constraint : Tracks pass through an unknown point,

For a solenoid field (along z direction) this leads to two equations

$$p_{xi}\Delta y_i - p_{yi}\Delta x_i - (a_i/2) (\Delta x_i^2 + \Delta y_i^2) = 0$$

$$\Delta z_i - (p_{zi}/a_i) \sin^{-1} [a_i (p_{xi}\Delta x_i + p_{yi}\Delta y_i) / p_{Ti}^2] = 0$$

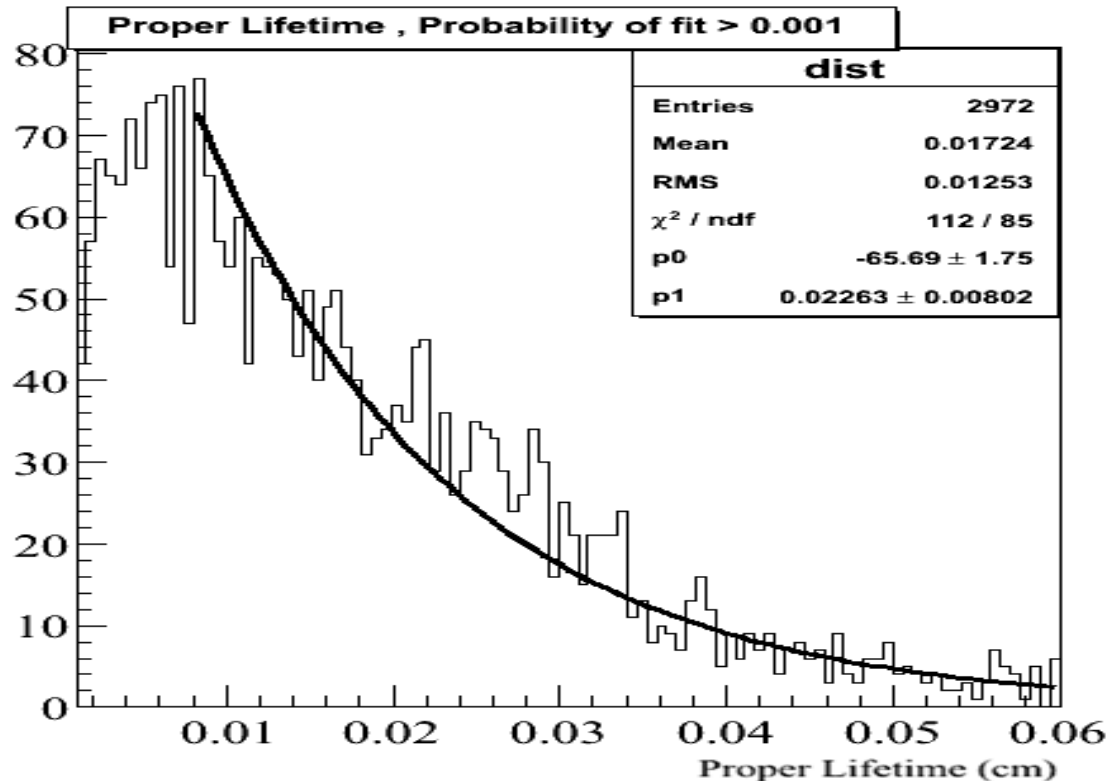
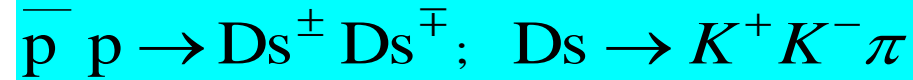
A good start point is needed specially for displaced vertices.

Start point : Vertex finder, ( crossing point , point of minimum distance)

Propagation of the track parameters and covariance matrix to the start point

Pointing Constraint : Reconstructed vertex points to another known vertex  
(e.g. primary vertex)

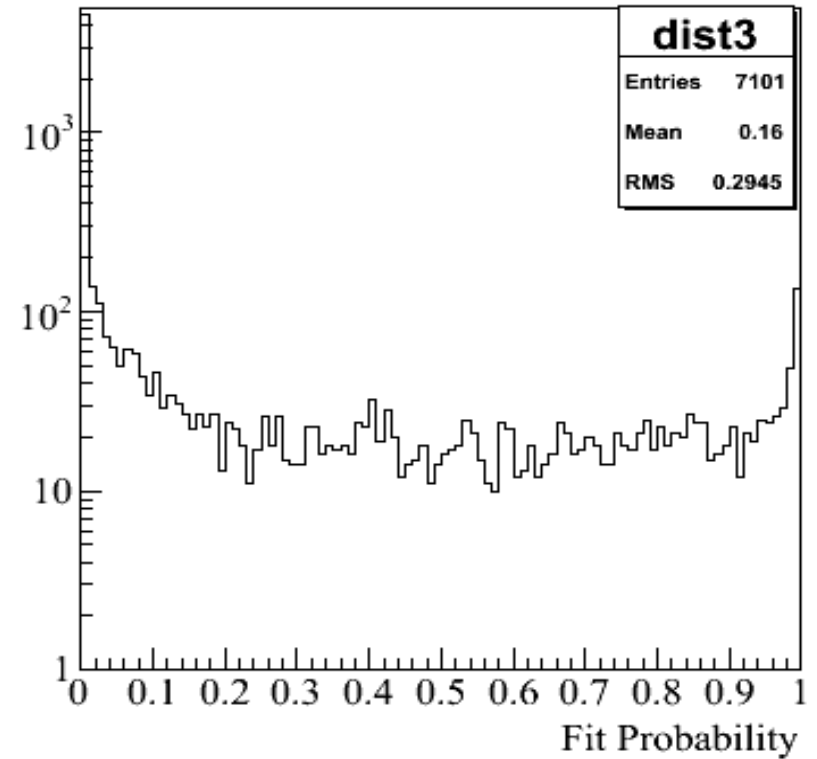
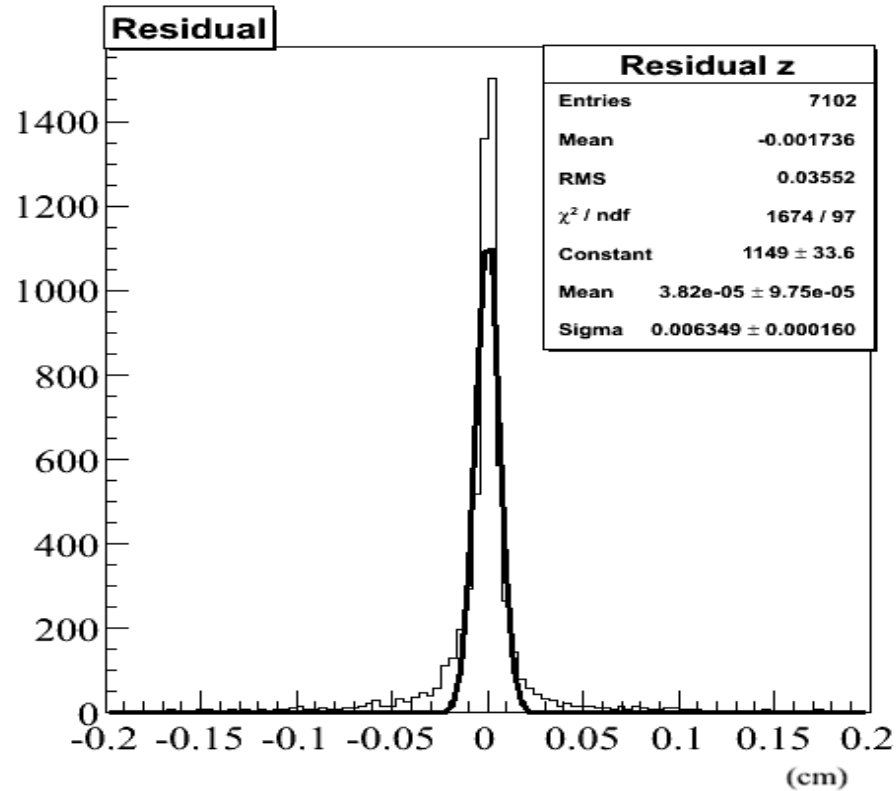
# D<sub>s</sub> Reconstruction and Vertex Fitting:



Fitted D<sub>s</sub> proper Lifetime = 152 μm, PDG Value = 147 μm



# Quality of the fit:



## Kinematic Fitting with Constraints:

One or more constraints can be used in combination ( PndKinFitter) :

Kinematic constraints:

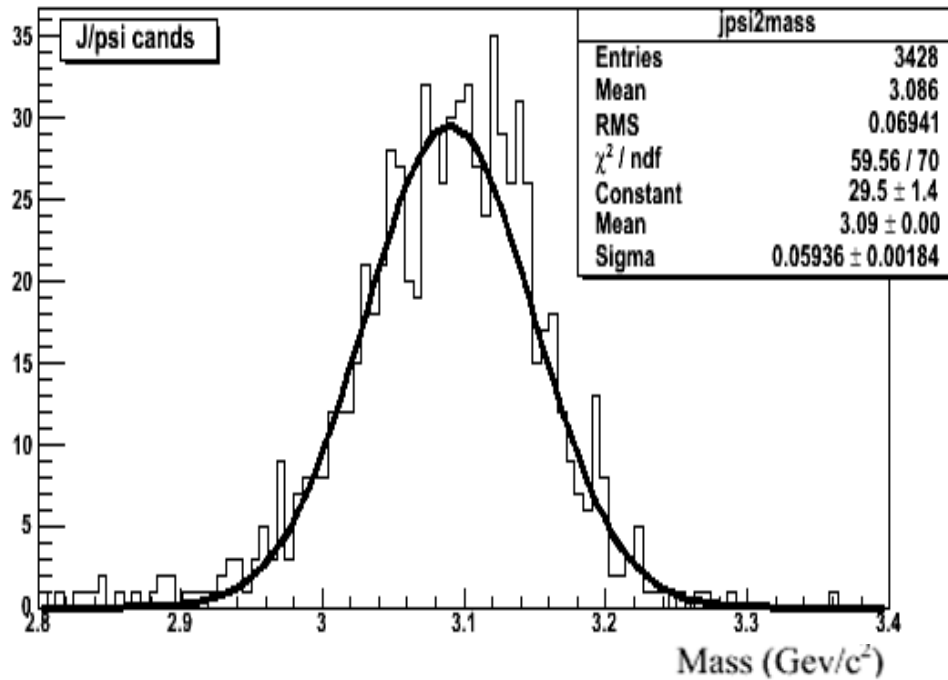
- i) 4 vector constraint : (Add4MomConstraint (TLorentzvector lv)
- ii) momentum constraint (AddMomConstraint (Tvector3 v)
- iii) Total energy /Momentum (AddTotEConstraint (double E)
- iv) Mass constraint (AddMassConstraint double mass)

Possibility to include them in combination : ( Global Fitting)

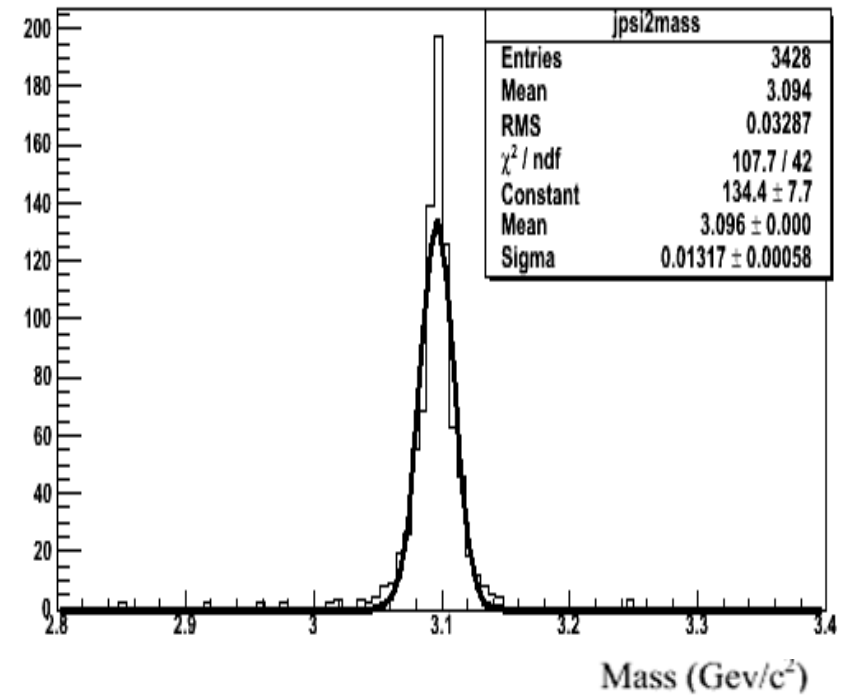
# Kinematic 4 Momentum Fitting:

ppbar -> J/ψ π<sup>+</sup>π<sup>-</sup>

4 Momentum fit for the ppbar system



$\sigma = 0.059 \text{ GeV}/c^2$

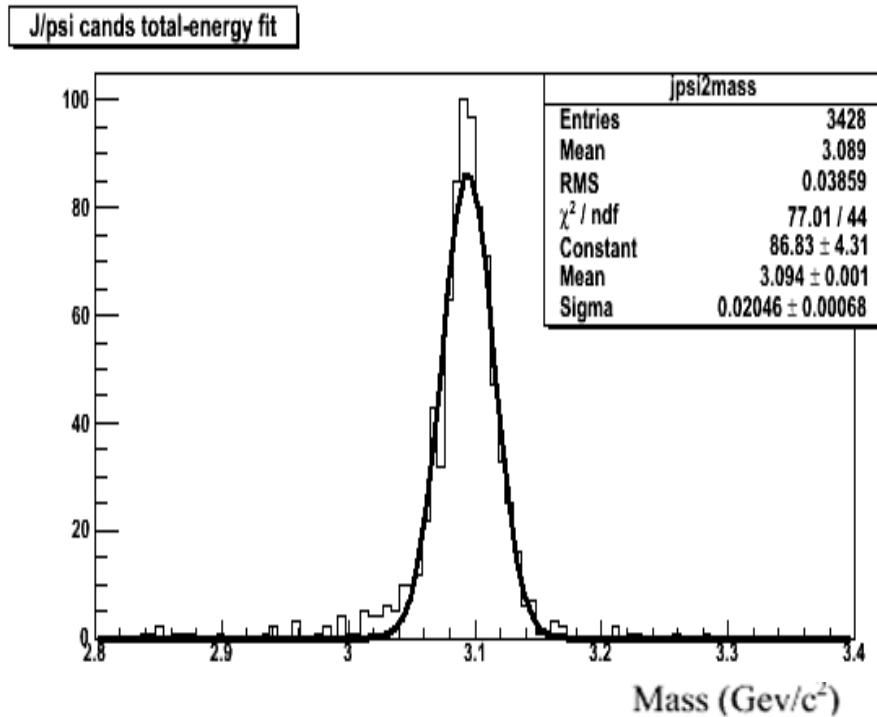


$\sigma = 0.013 \text{ GeV}/c^2$

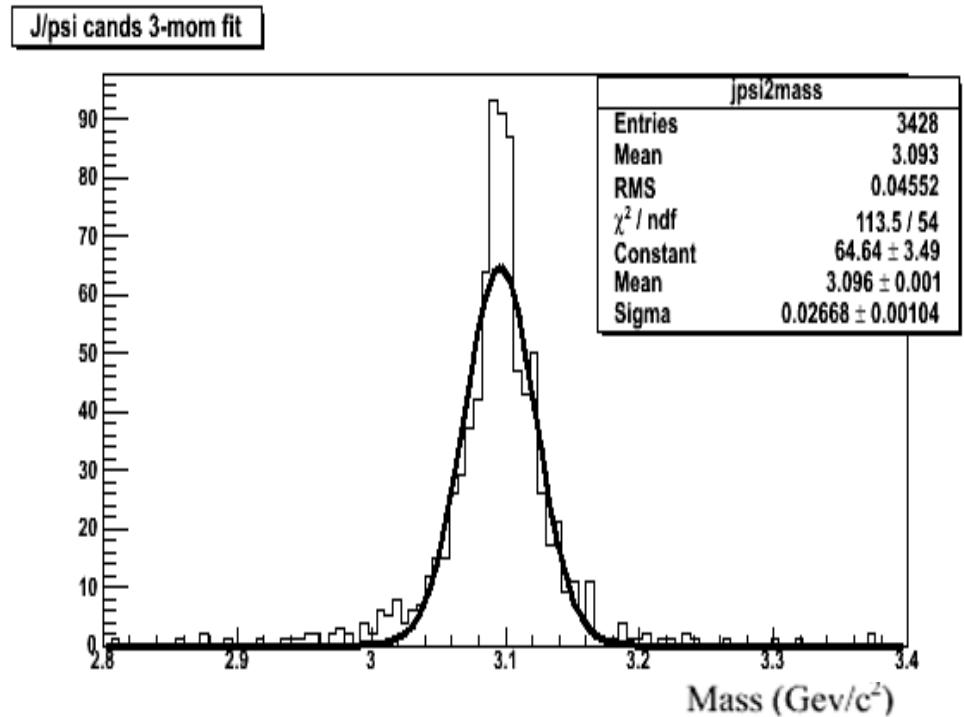
# Kinematic Fitting :

Total Energy Constraint

3-momentum Constraint

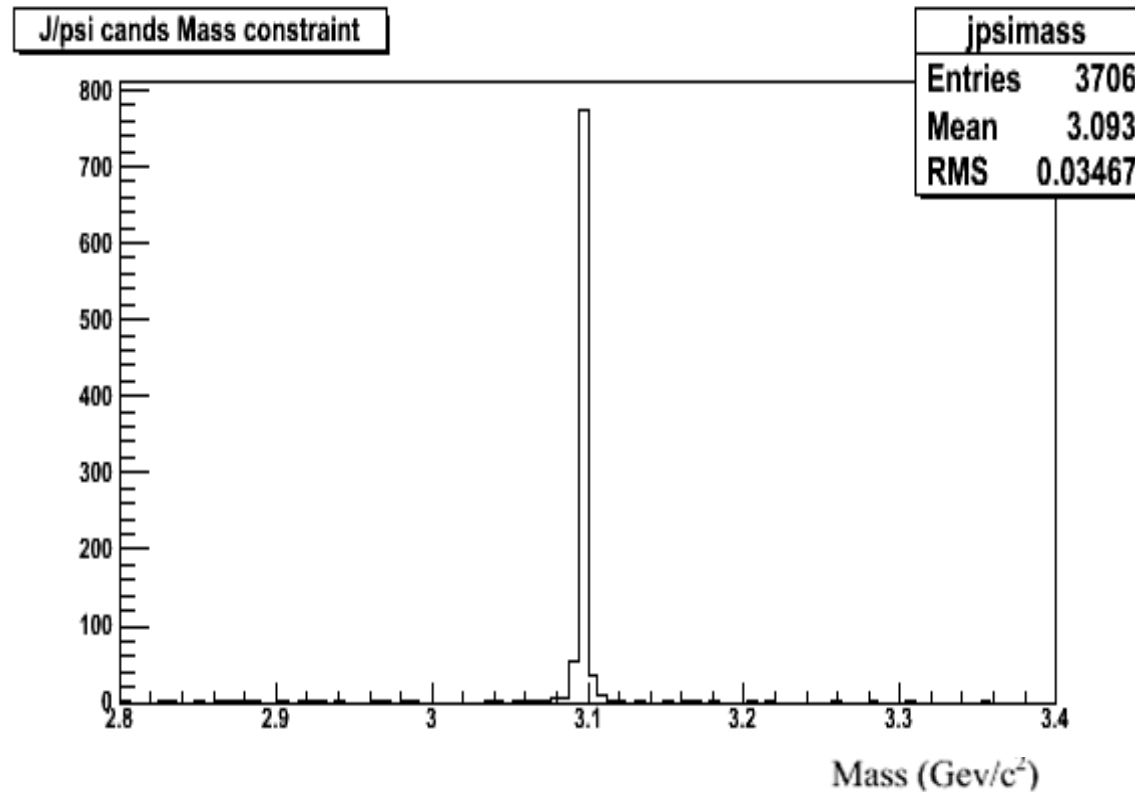


$$\sigma = 0.021 \text{ GeV}/c^2$$



$$\sigma = 0.026 \text{ GeV}/c^2$$

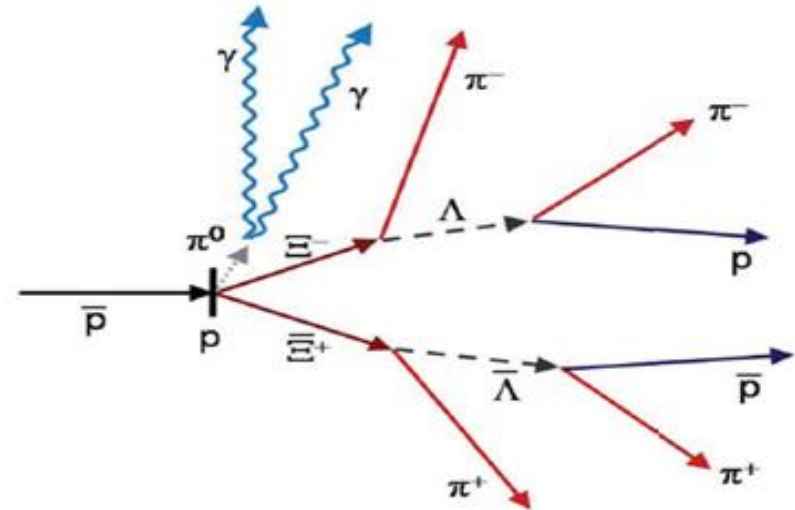
# Kinematic Fitting Mass Constraint :



# Fitting the complete Decay tree:

Four class of particles (objects) :

- i) Reconstructed Track as hypothesis
- ii) Reconstructed as cluster
- iii) Composites or virtual particles :
  - a) prompt decay (resonances)
  - b) Macroscopic decay length (composites)
- iv) Missing particles



## Fitting the decay tree:

Sequential : Constraints applied sequentially to build the decay chain

The bottom up approach ,

Generating new composite particles /resonances along the way

Composite has all the information of daughter tracks in linear approx

Global : All constraints are applied simultaneously for complete tree

Better treatment of non-linearities and track-track correlation

Large Matrices to be inverted

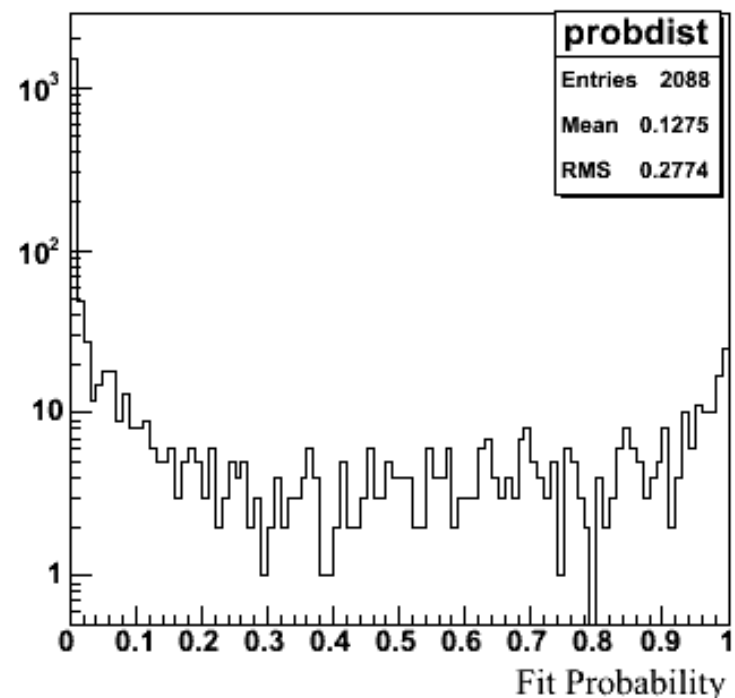
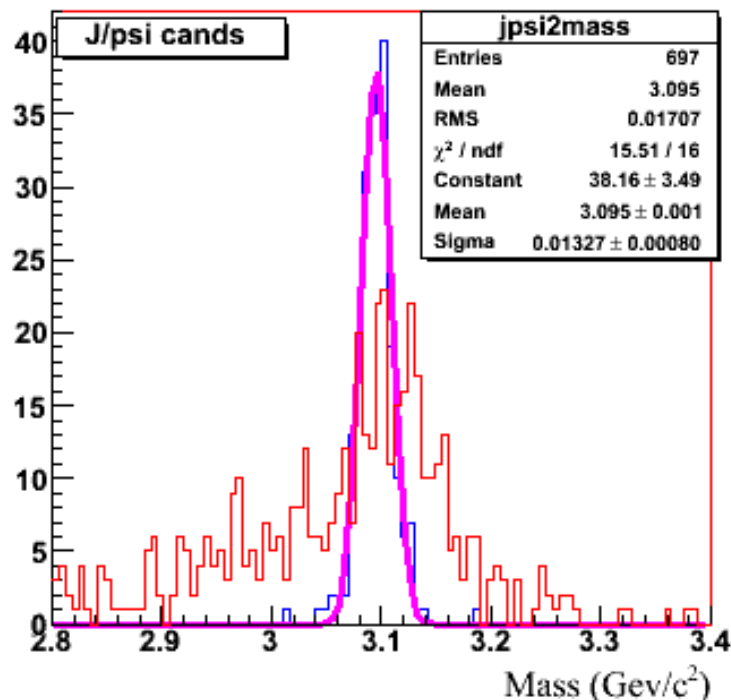
Progressive fit based on Kalman filter can be used.

# Sequential Fitting I:

Constraints applied sequentially to build the decay chain

1<sup>st</sup> step  $p\bar{p} \rightarrow J/\psi \pi^+\pi^-$

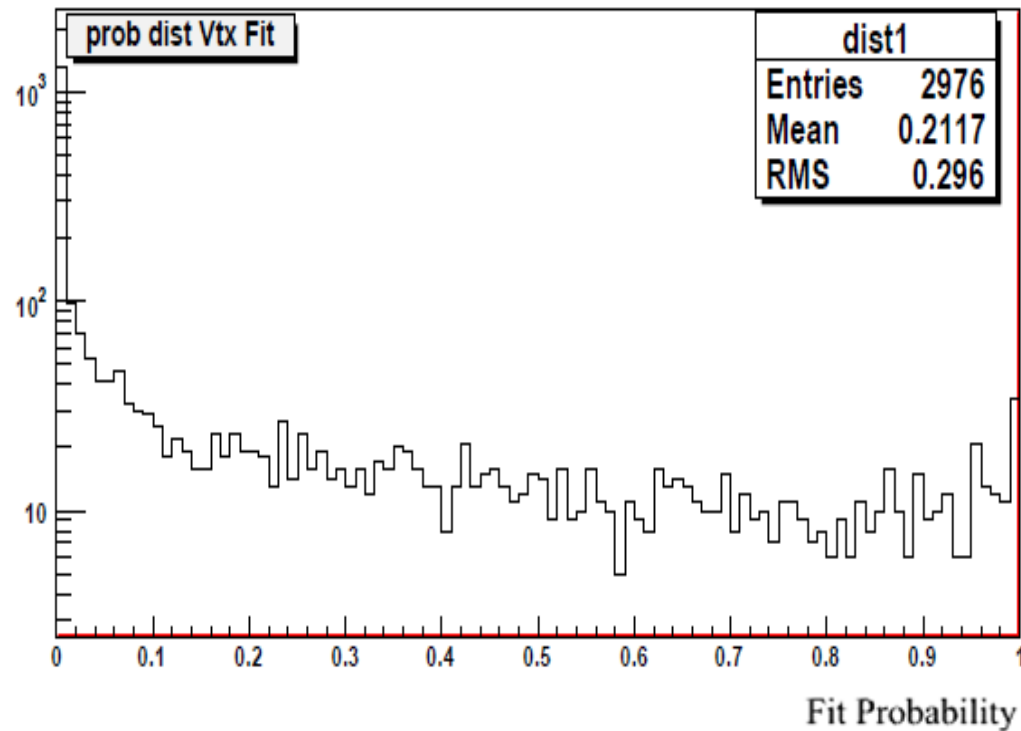
4 Momentum fit for the  $p\bar{p}$  system :





# Sequential Fitting II :

2<sup>nd</sup> Step : Probability of the Vertex fit for the pbar p vertex  
after the 4-momentum fit :



## Summary :

Vertex Fitters have been implemented

Kinematic fitters with many constraints have been included.

Tests of their performance have been made.

## Outlook :

Detailed tests of the fitters needs to be done ( Questions of efficiencies and reliability of covariance matrices)

Tests of the full decay tree fitting