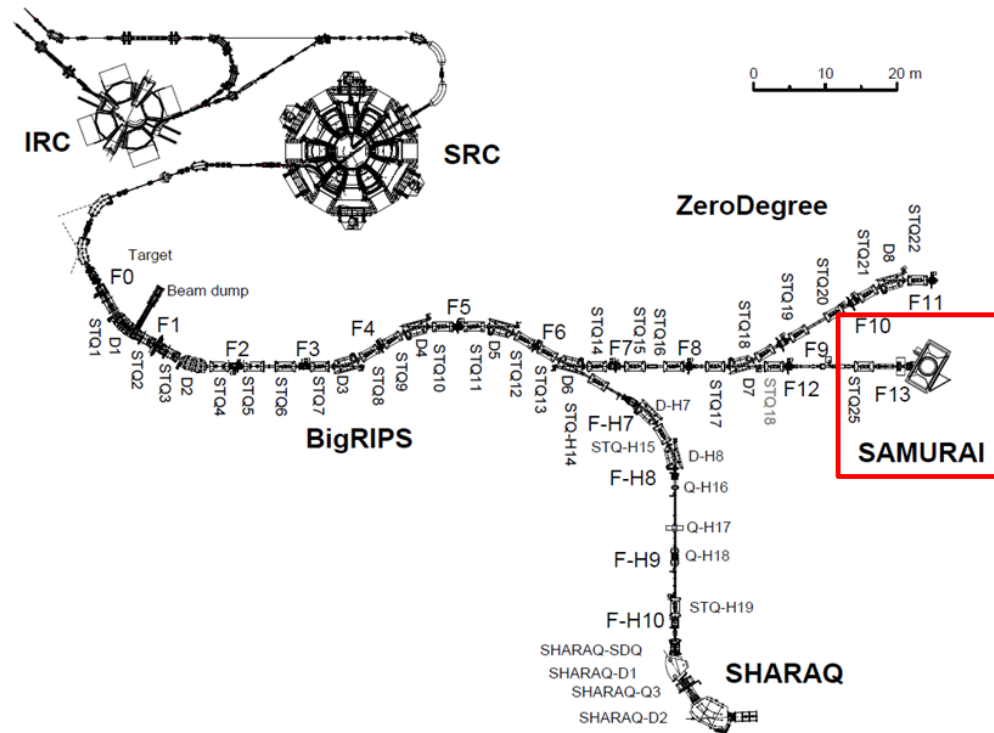


SAMURAI

Superconducting Analyzer for Multi-particles
from Radioisotope beams



Overview

The SAMURAI spectrometer is designed for kinematically complete reaction measurements by detecting multiple particles in coincidence.

Large angular- and momentum-acceptance

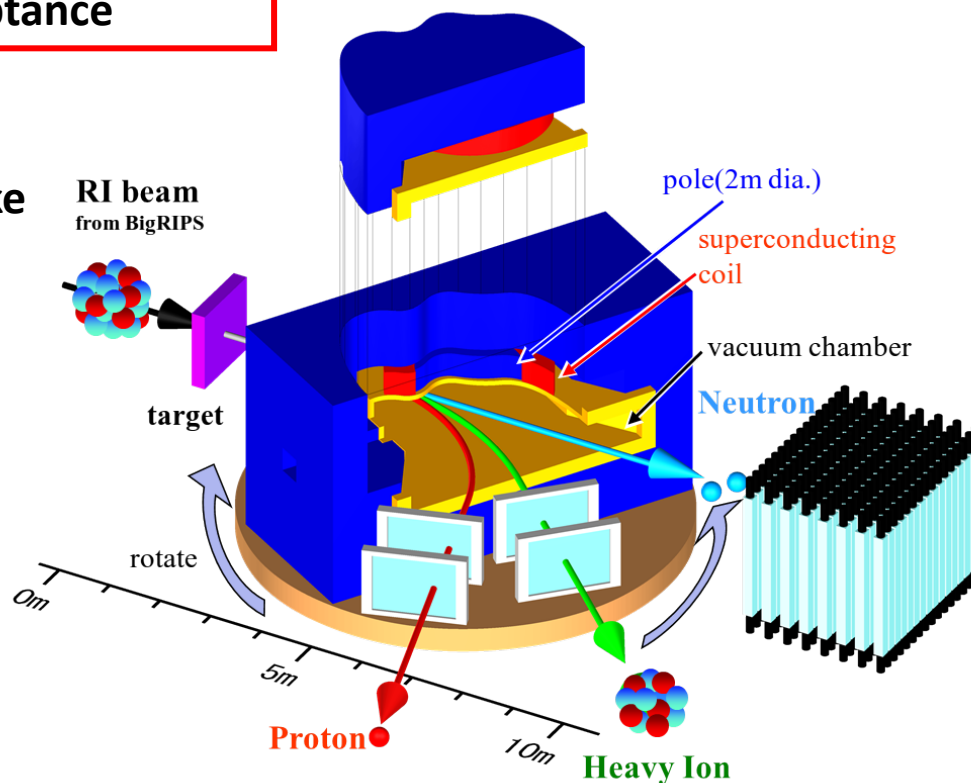


Large pole gap

Wide horizontal opening of a yoke

SAMURAI consists of ...

- ✓ **Superconducting dipole magnet**
- ✓ Heavy Ion detectors
- ✓ Proton detectors
- ✓ Neutron detectors
- ✓ Large vacuum chamber
- ✓ Rotatable base

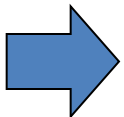


The construction of the SAMURAI was completed in Feb. 2012.

Requirements for Magnet

- Requirements
 - Large field integral --> for high precision momentum analysis
 - Large pole gap --> for large vertical acceptance for neutrons
 - No coil link --> for large acceptance in the horizontal direction
 - Small fringing field --> for detectors around the target region and tracking detectors
 - Flexibility --> for various experimental conditions
 - Large momentum acceptance --> for heavy fragments and protons in coincidence
 - High momentum resolution --> for deuteron-induced reactions

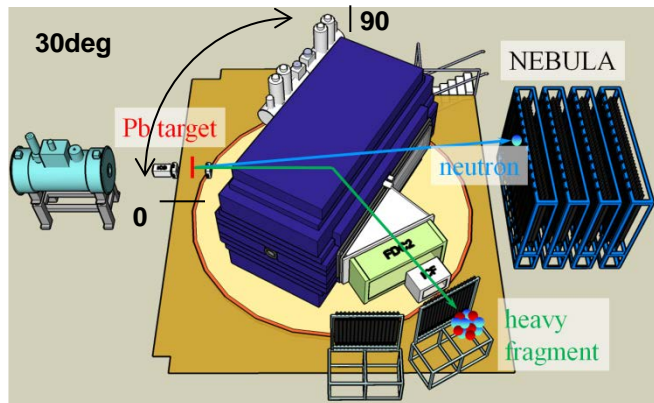
- ✓ Field Integral 7 Tm ($dR/R \sim 1/700$ @ 2.3 GeV/c for $A/Z=3$)
--> mass separation $\sigma_A=0.2$ for $A=100$
- ✓ Large Gap (0.8 m --> vertical ± 5 degrees)
- ✓ Large opening (3.4 m --> horizontal ± 10 degrees)
- ✓ Small Fringing Field (< 50 gauss @ 50cm from magnet)
- ✓ H-type magnet with cylinder poles (2m in diameter)
- ✓ Magnetic field ... about 3T at center by ~1.9MAT
- ✓ Field clamp
- ✓ Build-in vacuum chamber
- ✓ Rotatable base (from -5 to 95 deg, 0.1deg/sec)



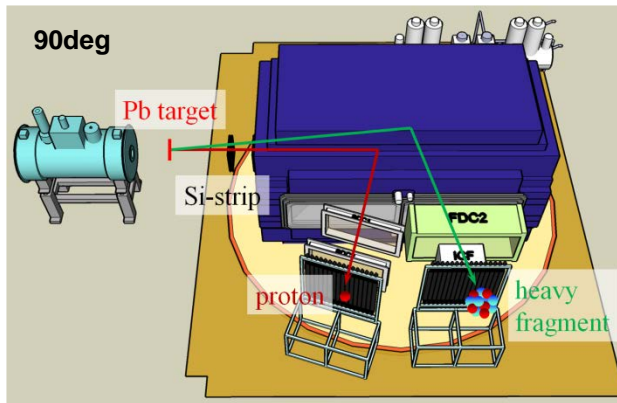
Versatile usage

Magnet can rotate around it's center.

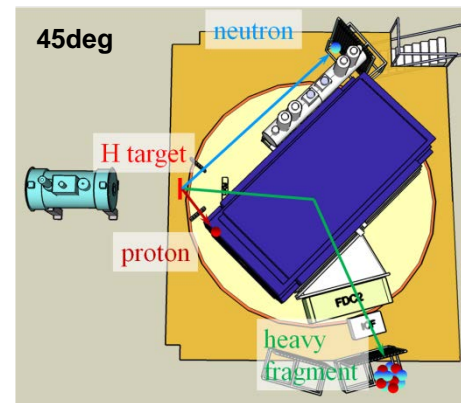
(γ, n) reaction: neutron-rich side



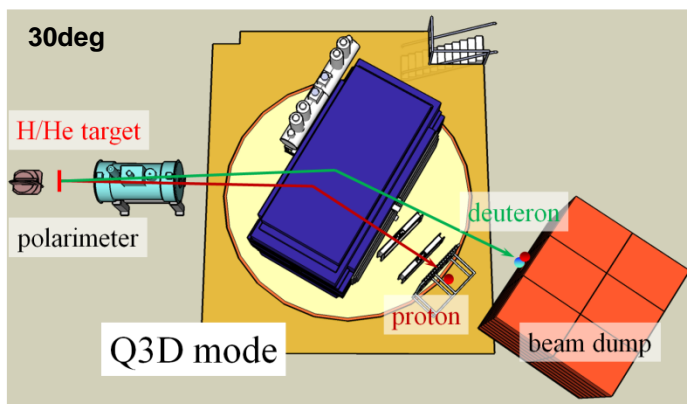
(γ, p) reaction: proton-rich side



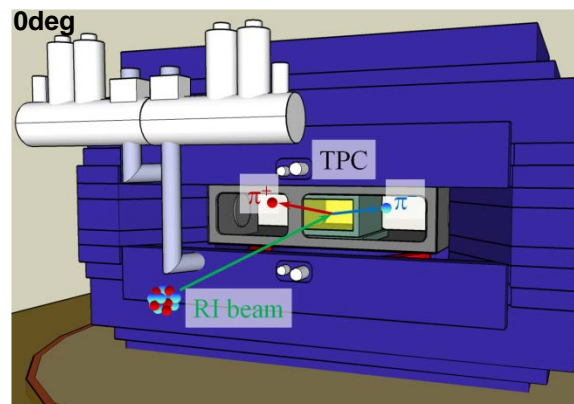
(p, p') , $(p, 2p)$, (p, pn) , ...



pol. d -induced reaction



EOS measurement



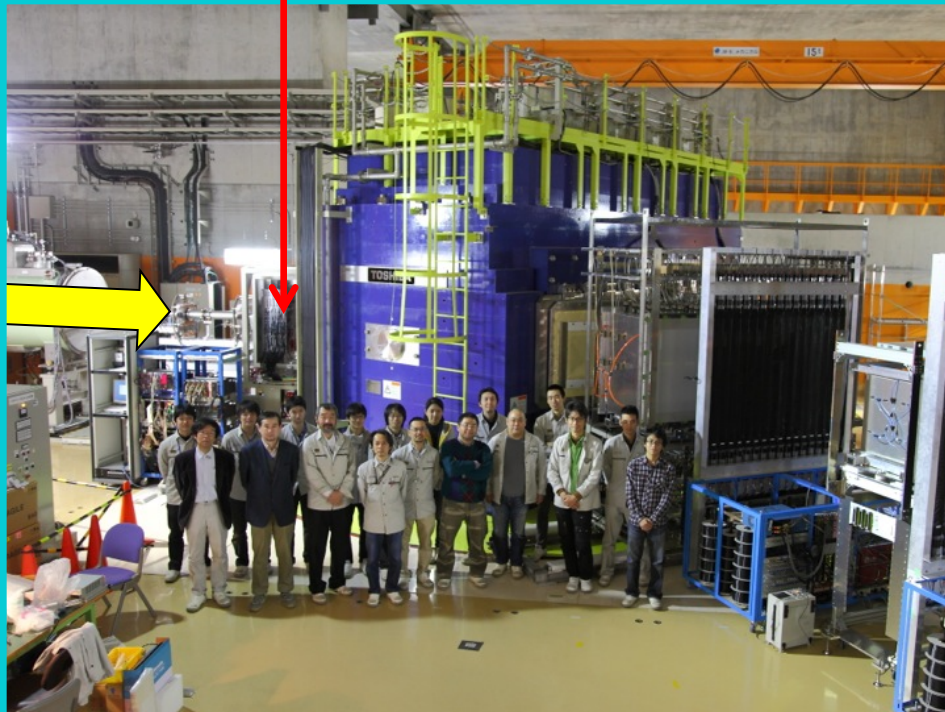
Flexibility of settings is one of the good properties of SAMURAI.

Photo

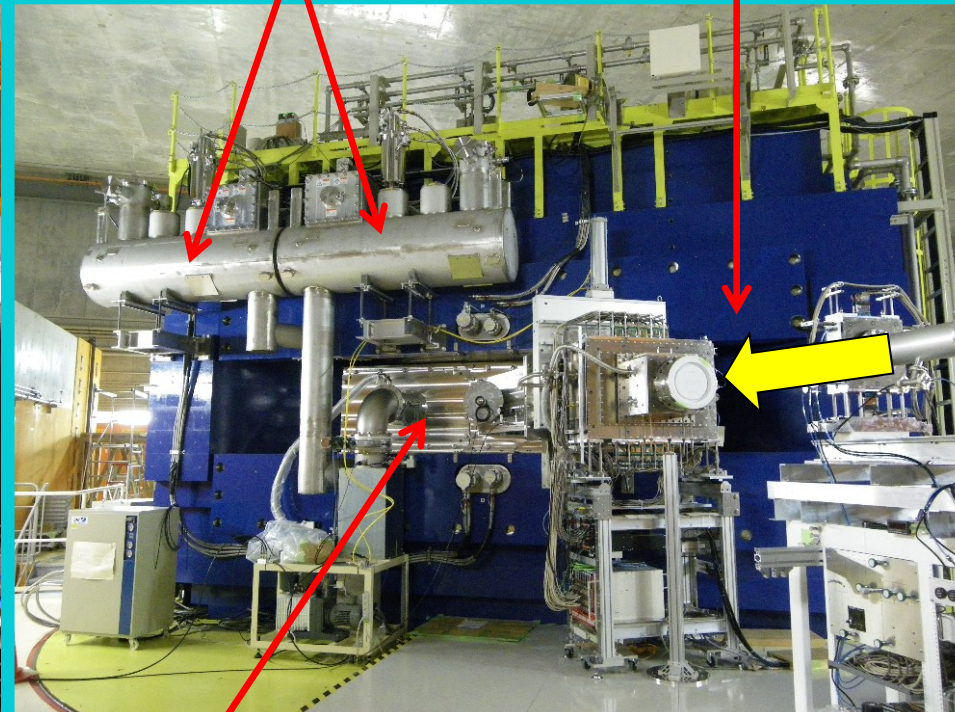
target

LHe reservoir vessels

Field cramp



side view



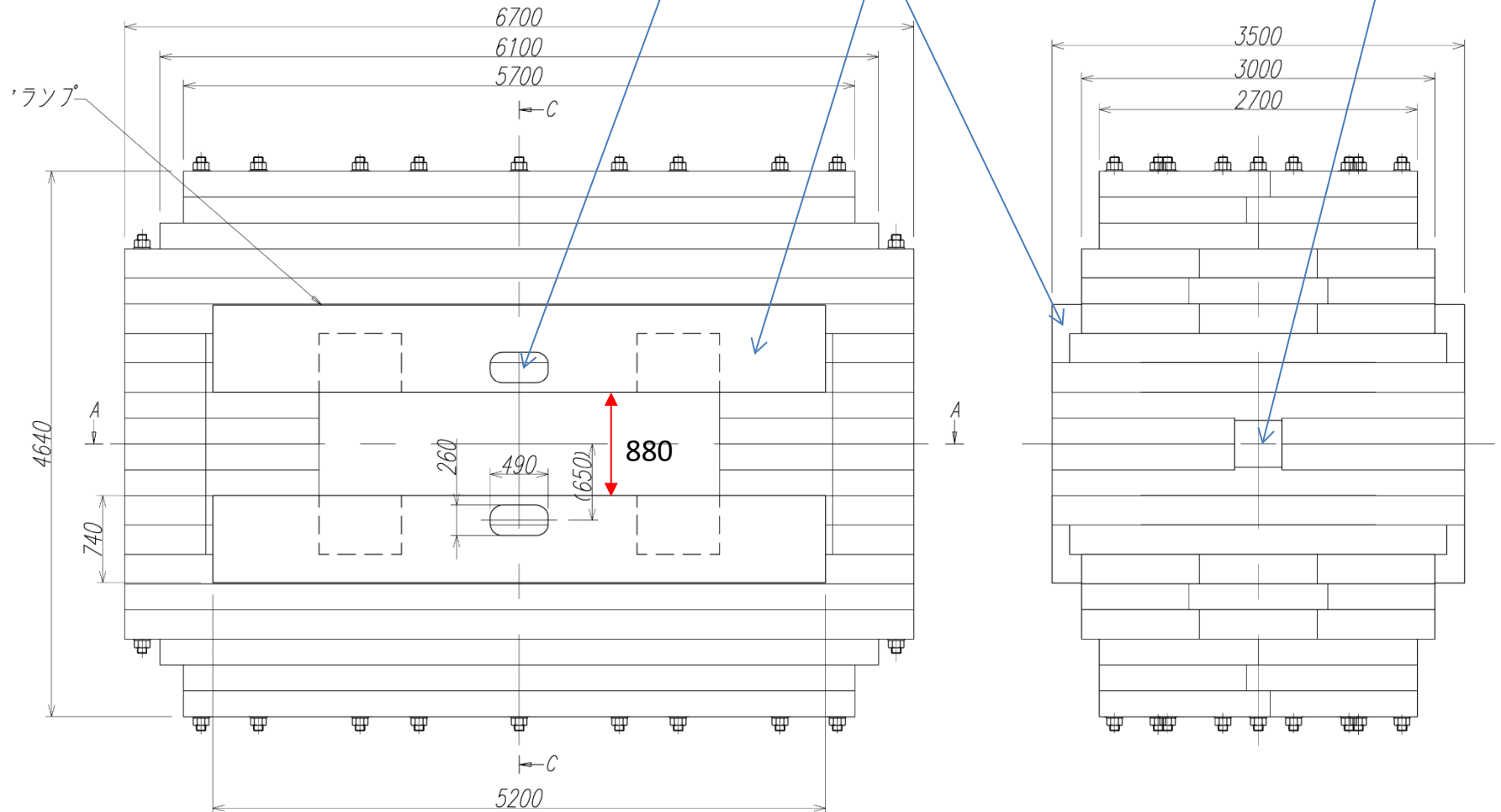
upstream

Vacuum chamber

* The magnet was rotated at an angle of 30°.

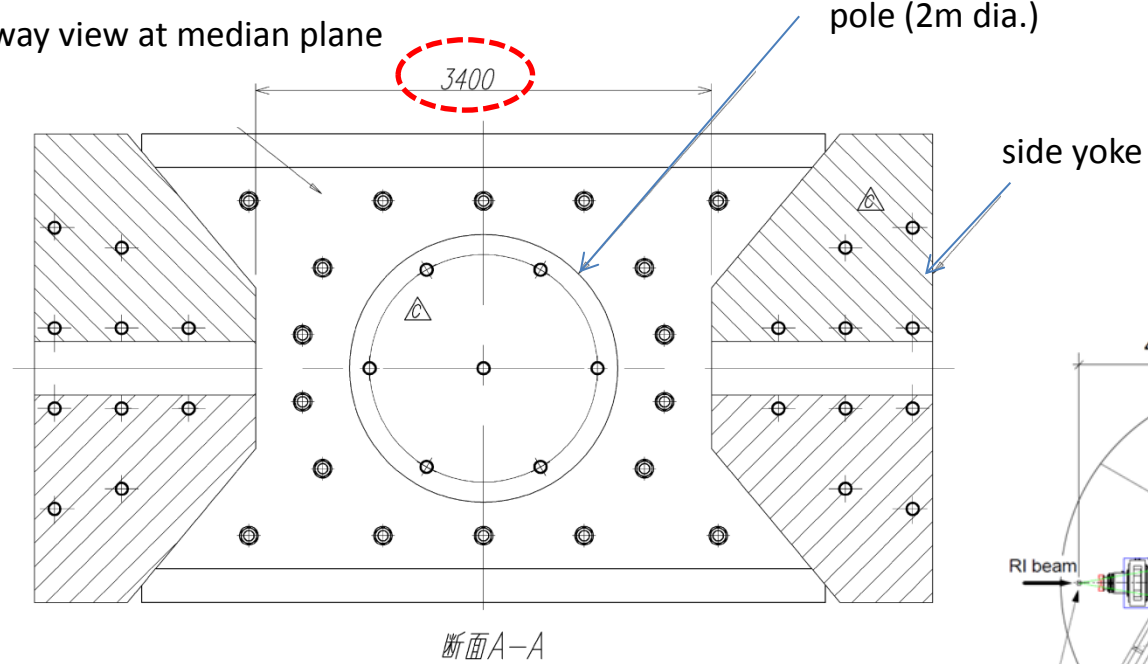
Yoke

Pole	shape	circular
	gap	0.88 m
	diameter	2.0 m ϕ
	height	0.5 m
Yoke	width	6.7 m
	depth	3.5 m
	height	4.64 m
	weight	566140 kg

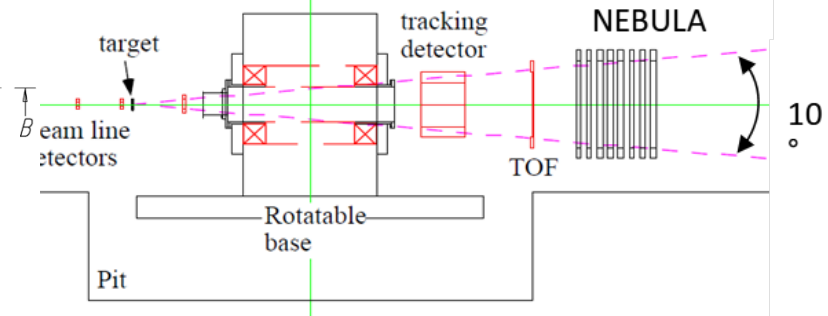
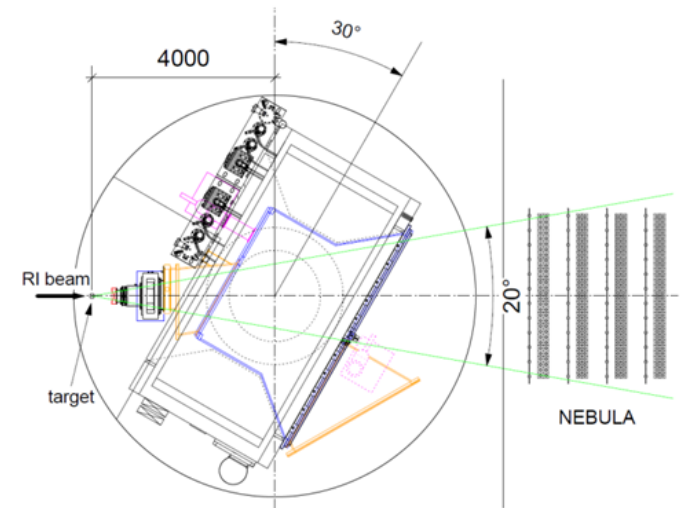
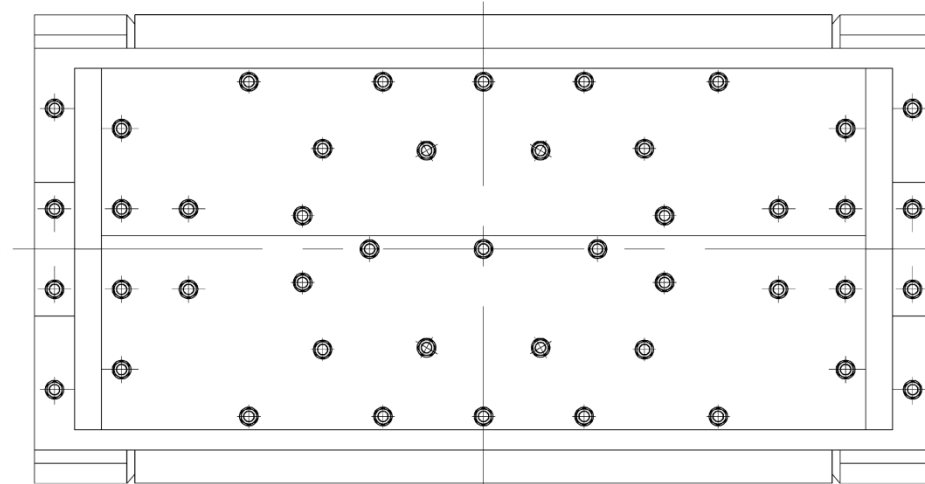


Yoke

cutaway view at median plane

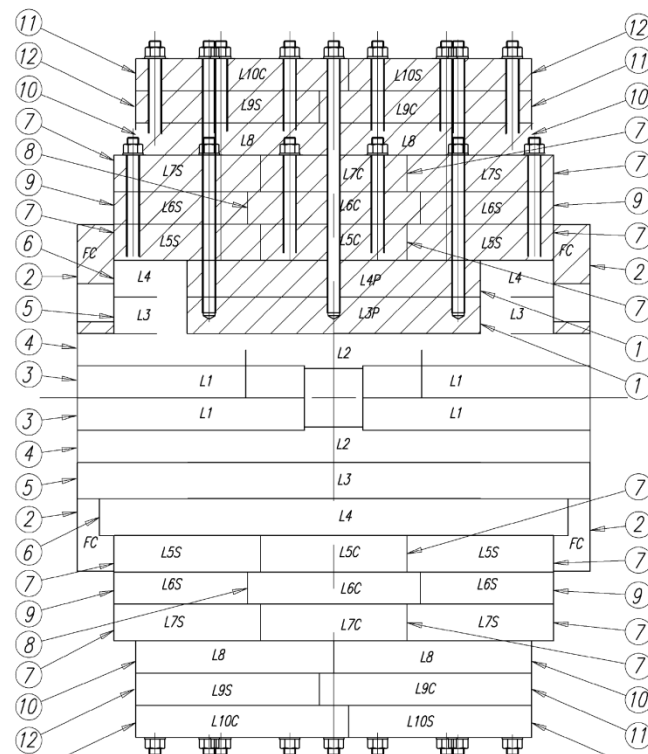
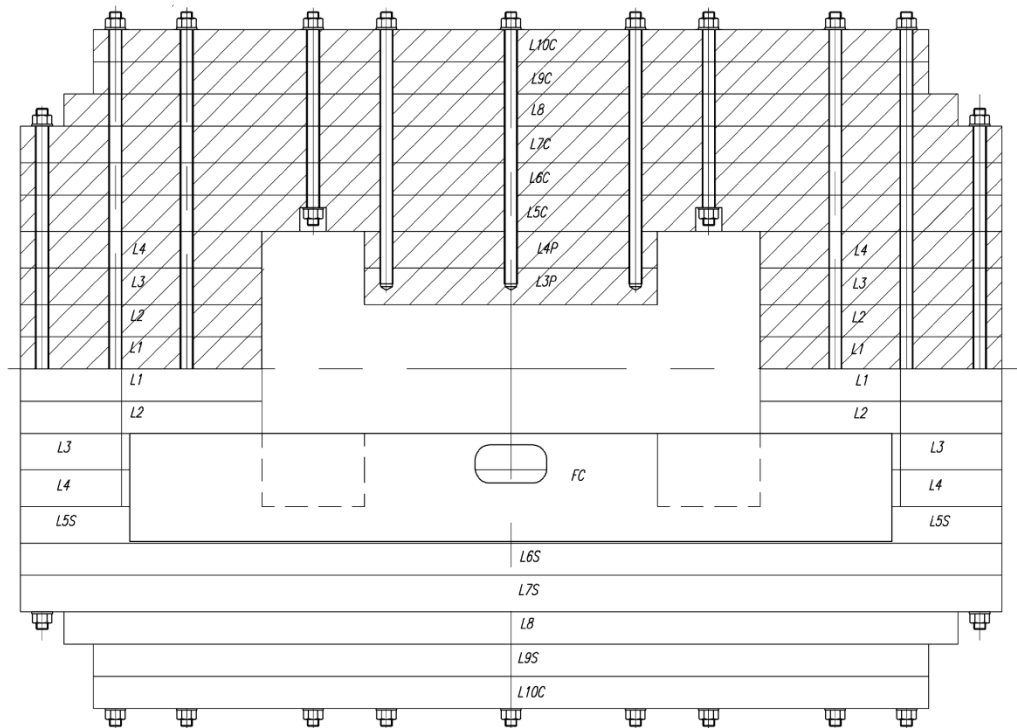


top view



70 stud bolts
M90, S45C

Yoke



鉄心構成鉄板

1) 材質：電磁軟鉄 (SUY-2相当)

yoke = 58 slabs

The slabs weigh less than 15 tons due to the load limit of the crane.

PNo.	名称	厚さ	幅(または直径)	長さ	質量 (kg)	数量
1	磁極鉄板L3P/L4P	250	φ2000	—	6120	4
2	フィールドコイルFC	250	740	5200	7410	4
3	サイドヨーク鉄板L1	220	1650	1550	3340	8
4	サイドヨーク鉄板L2	220 (一部240)	1650	3500	7900	4
5	サイドヨーク鉄板L3	250	1650	3500	8770	4
6	サイドヨーク鉄板L4	250	1650	3200	8370	4
7	天板鉄板L5C/L5S/L7C/L7S△	250	1000	6700	12880	12
8	天板鉄板L6C	220	1180	6700	13630	2
9	天板鉄板L6S	220	910	6700	10330	4
10	天板鉄板L8	220	1350	6100	14200	4
11	天板鉄板L9C/L10C	220	1450	5700	14200	4
12	天板鉄板L9S/L10S	220	1250	5700	12100	4
総合計					566140	58

注1) 寸法は製品仕上がり寸法

Specifications of the soft steel

- ✓ Company: JFE Steel Corporation
- ✓ Product name: Hot Rolled Steel Plate
- ✓ Model: JFE-EFE 2003
- ✓ SPEC: SUY-2 (defined in JISC2504)

Chemical components

	C	Si	Mn	P	S	Cu	Cr	Mo	Al	N
[%](mass)	< 0.03	< 0.20	< 0.50	< 0.03	< 0.03	(0.15)	(0.05)	(0.02)	(0.06)	(0.01)

Mechanical properties

0.2% proof stress	> 120 MPa
tensile strength	> 220 MPa
Elongation	> 20%

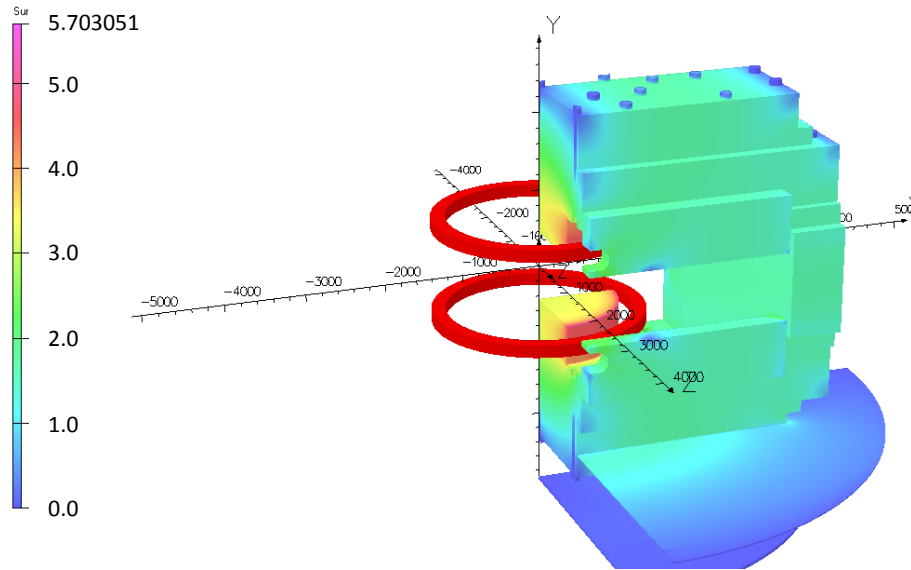
DC magnetic properties

H [A/m]	300	500	1000	4000
B [T]	> 1.15	> 1.30	> 1.45	> 1.60
coercive field strength	< 100 A/m @1.5 T			

Saturation of the Yoke

$B(0)=3.08\text{ T}$

$|B| \text{ [T]}$



opera
simulation software

UNITS

Length mm
Magn Flux Density T
Magnetic Field A/m
Magn Scalar Pot A
Current Density A/mm²
Power W
Force N

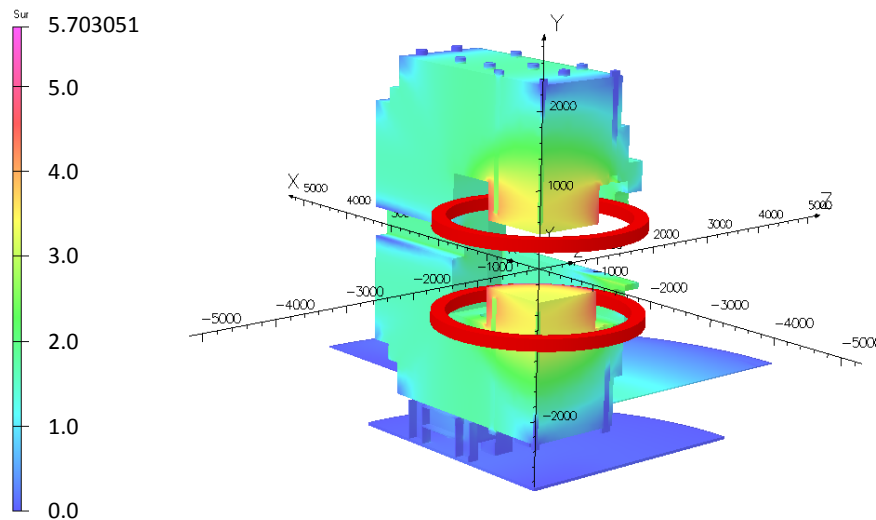
MODEL DATA

130809-bn_stage-d-3.08T.op3
Magnetostatic (TDSCA)
Nonlinear materials
Simulation No 1 of 1
20867978 elements
4439170 nodes
2 conductors
Nodally interpolated fields
Activated in global coordinates
Reflection in XY plane (Z field=0)
Reflection in YZ plane (X field=0)

Field Point Local Coordinates

Local = Global

$|B| \text{ [T]}$



opera
simulation software

UNITS

Length mm
Magn Flux Density T
Magnetic Field A/m
Magn Scalar Pot A
Current Density A/mm²
Power W
Force N

MODEL DATA

130809-bn_stage-d-3.08T.op3
Magnetostatic (TDSCA)
Nonlinear materials
Simulation No 1 of 1
20867978 elements
4439170 nodes
2 conductors
Nodally interpolated fields
Activated in global coordinates
Reflection in XY plane (Z field=0)
Reflection in YZ plane (X field=0)

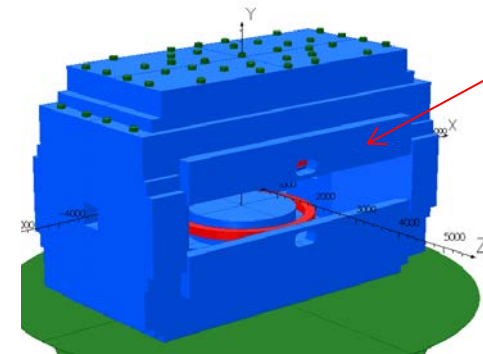
Field Point Local Coordinates

Local = Global

Field clamp (W5400 x H740 x D250) was designed so as to obtain smaller fringe field.

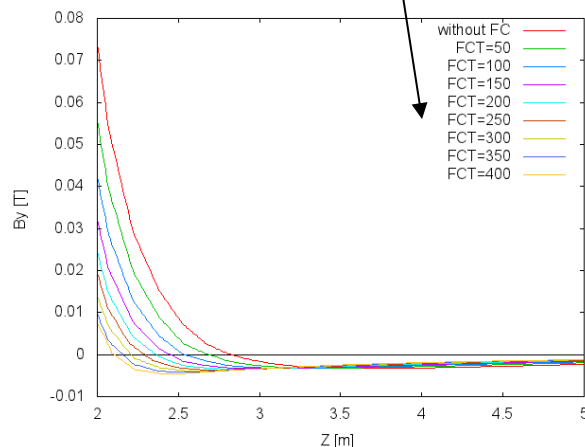
Field clamp

B=3.08T

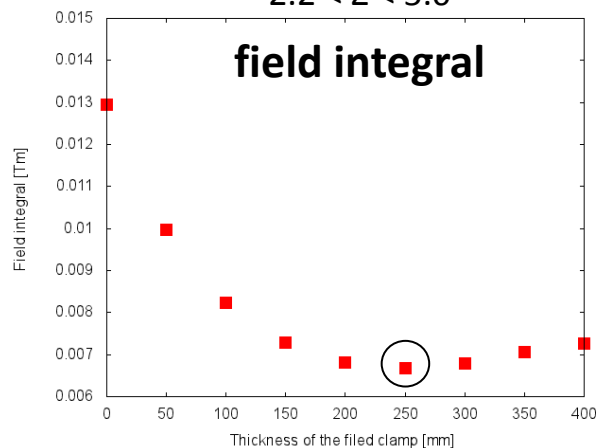


Thickness dependence

W5400 x H740 x D***

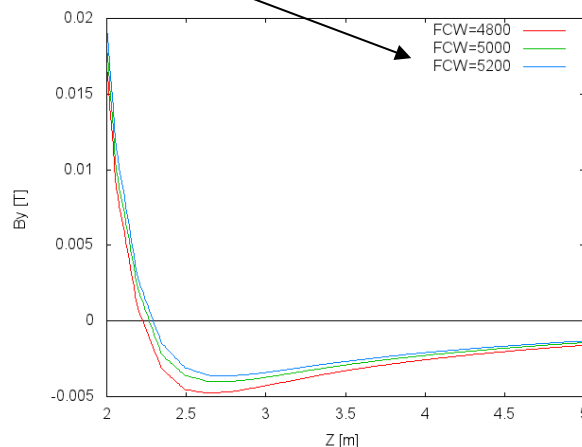


$2.2 < Z < 5.0$

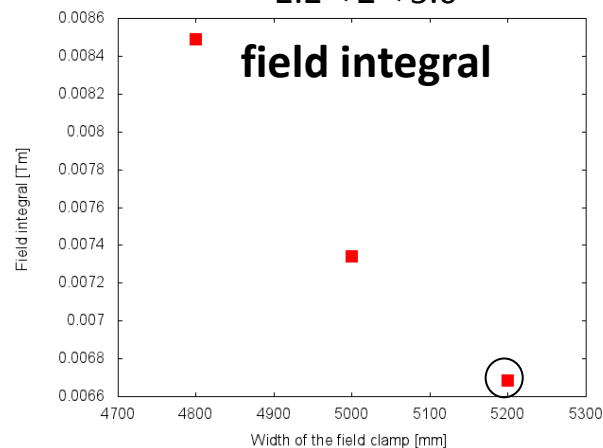


Width dependence

W*** x H740 x D250

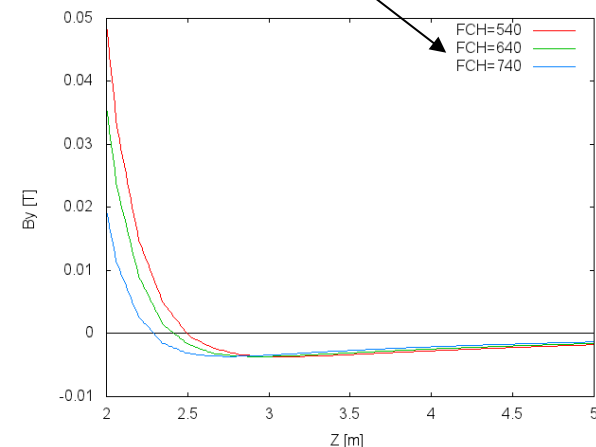


$2.2 < Z < 5.0$

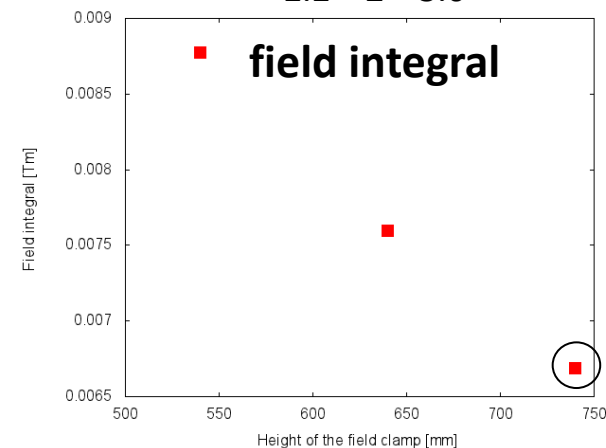


Height dependence

W5200 x H*** x D250



$2.2 < Z < 5.0$

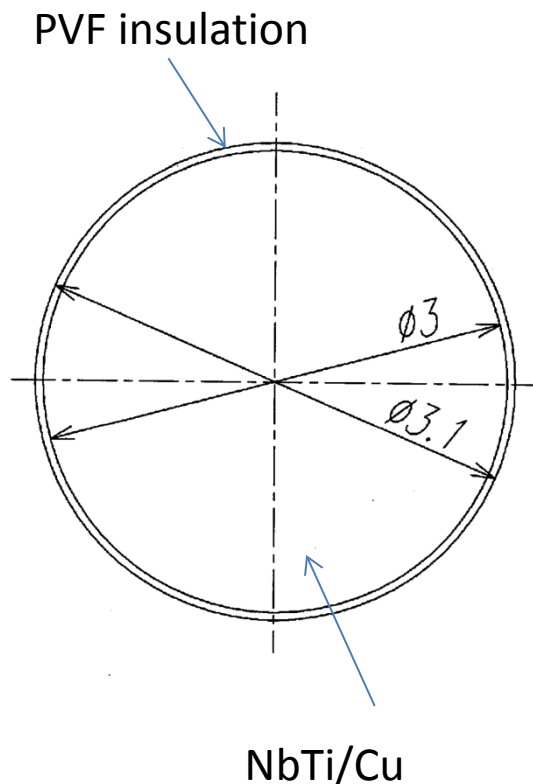


Super conducting wire

TABLE II

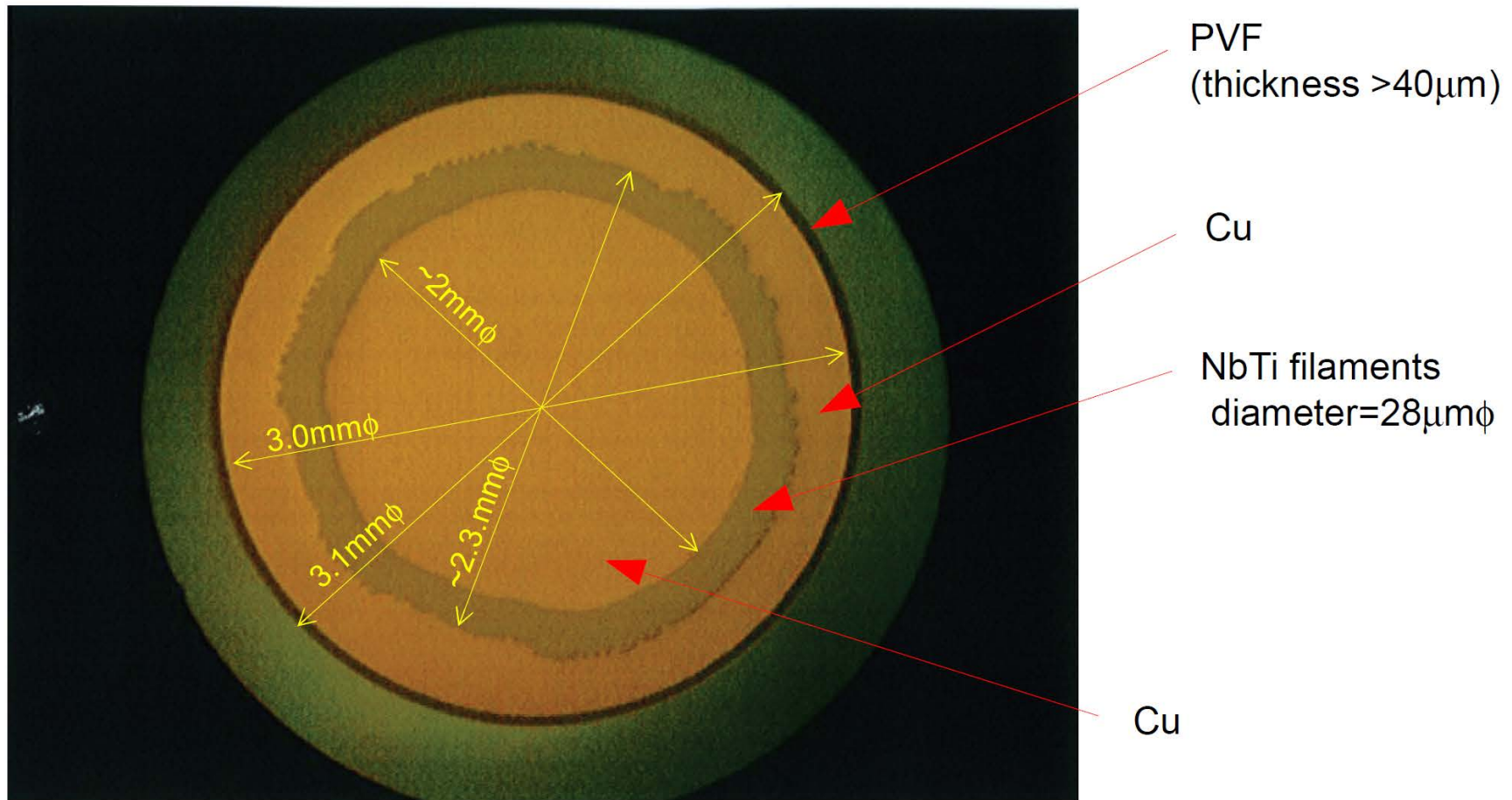
MAIN PARAMETERS OF THE SUPERCONDUCTING WIRE

	Value
Material	NbTi/Cu
Diameter (bare)	3.0 mm ϕ
Diameter (insulated)	3.1 mm ϕ
Cu/SC ratio	5.0 – 6.0
Insulation	PVF coating ($> 40 \mu\text{m}$)
Filament diameter	around $28 \mu\text{m}$
Number of filaments	around 1760
Twist pitch	around 88 mm
RRR	> 100
Critical current at 4.2 K	$> 4000 \text{ A at } 3 \text{ T}$ $> 3290 \text{ A at } 4 \text{ T}$ $> 2690 \text{ A at } 5 \text{ T}$ $> 2150 \text{ A at } 6 \text{ T}$



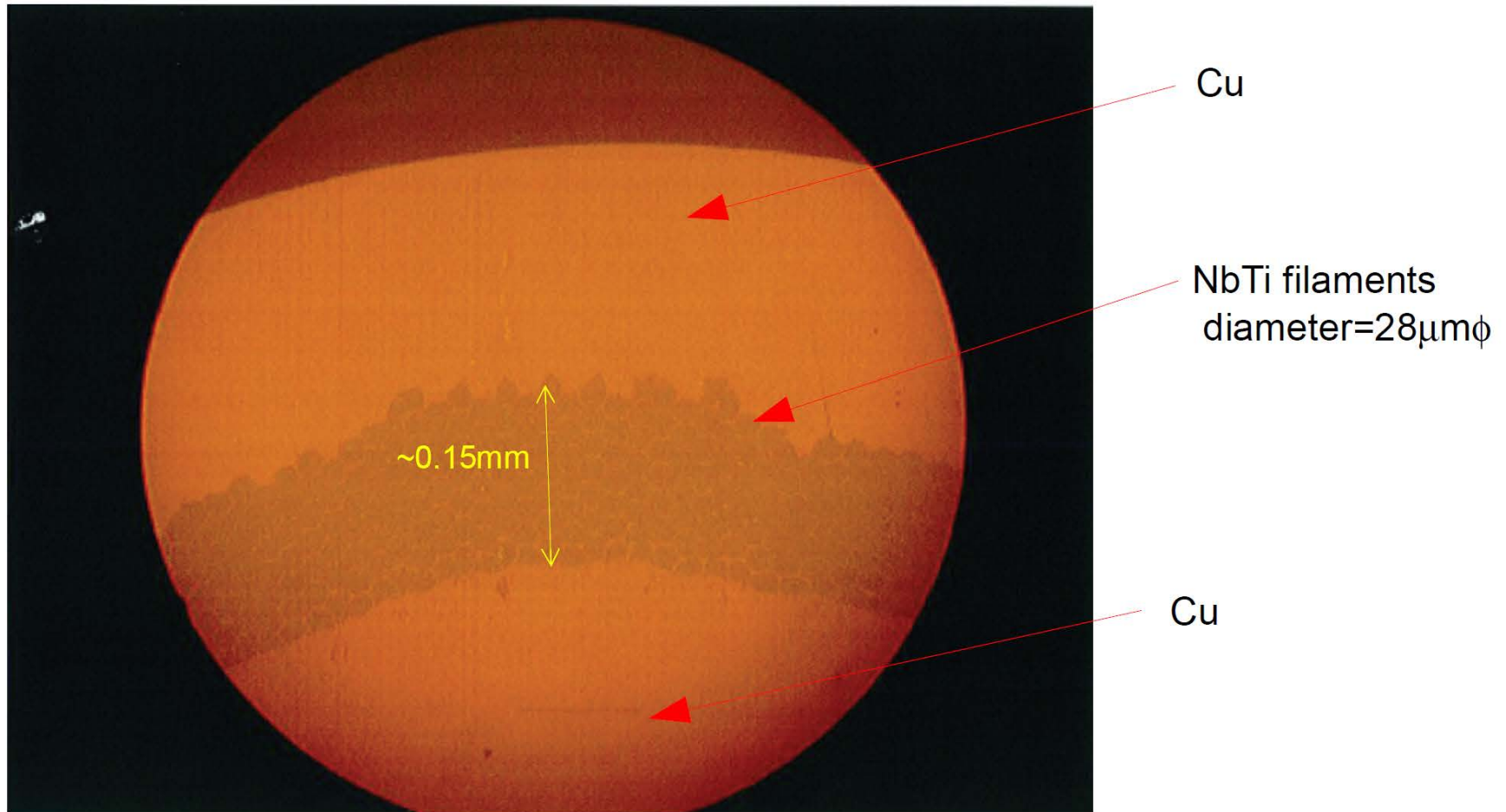
SC wire

Crosssection of the superconducting wire of the SAMURAI magnet

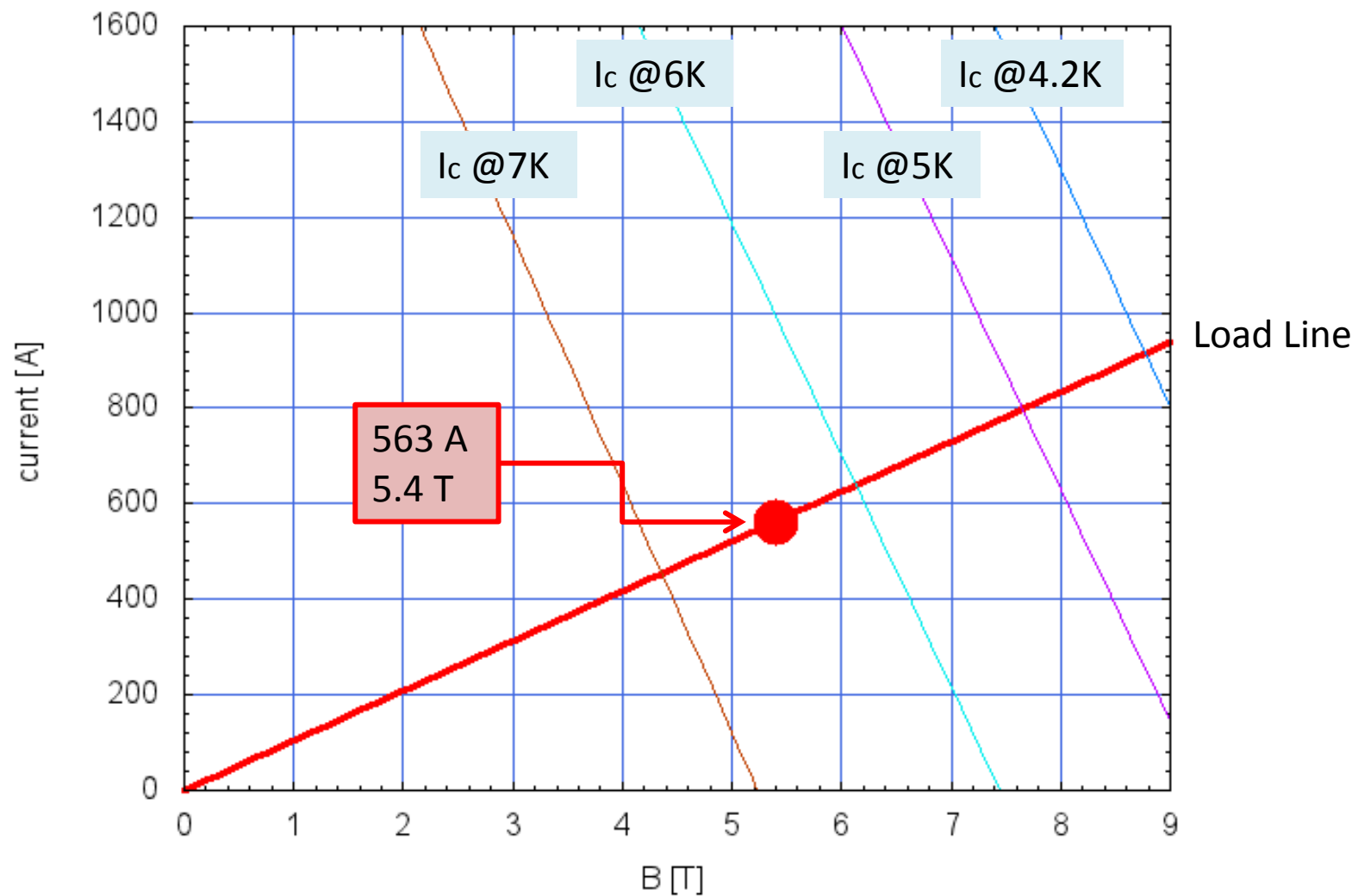


SC wire

Magnified view at the layer of the NbTi filaments



SC wire



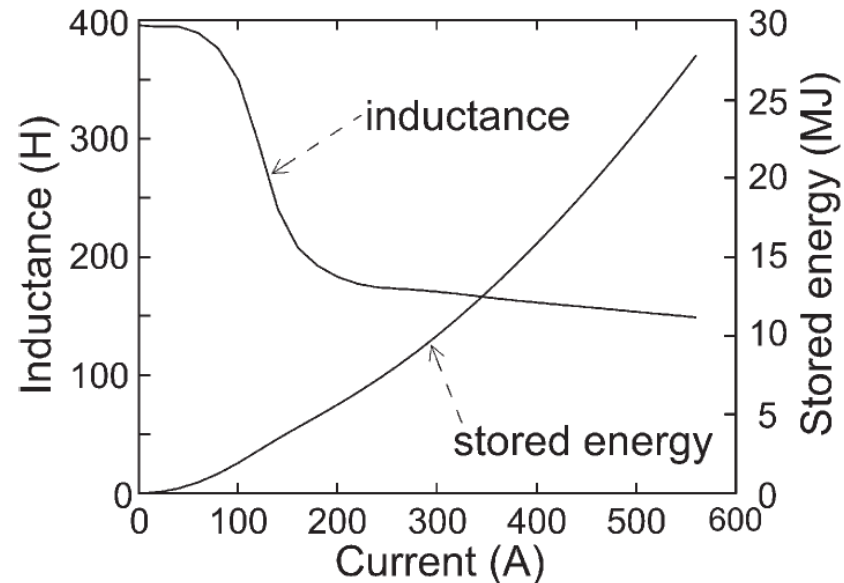
Load factor : 60% @4.2K

Specifications of the coil

TABLE I
MAIN PARAMETERS OF THE SUPERCONDUCTING DIPOLE MAGNET

	Value
Type	H-type, superconducting magnet
Number of turns	3414 turns/coil (51 turns \times 64 layers+50 turns \times 3 layers)
Windings of coil	impregnated close coiling, orderly winding
Maximum current	563 A
Magnetomotive force	1.922 MA turns/coil
Current density	66.74 A/mm ² (for coil cross-section)
Central field	3.08 T
Field integral at 3.08 T	7.05 Tm
Maximum field at coil	5.4 T
Inductance	396 – 150 H
Stored energy	27.4 MJ
Coil	
inner diameter	2.35 m (at 4 K)
outer diameter	2.71 m (at 4 K)
cross section	180 mm \times 160 mm (at 4 K)
weight	1783 kg/coil

- NOT stabilized
- Wet winding using the special epoxy resin



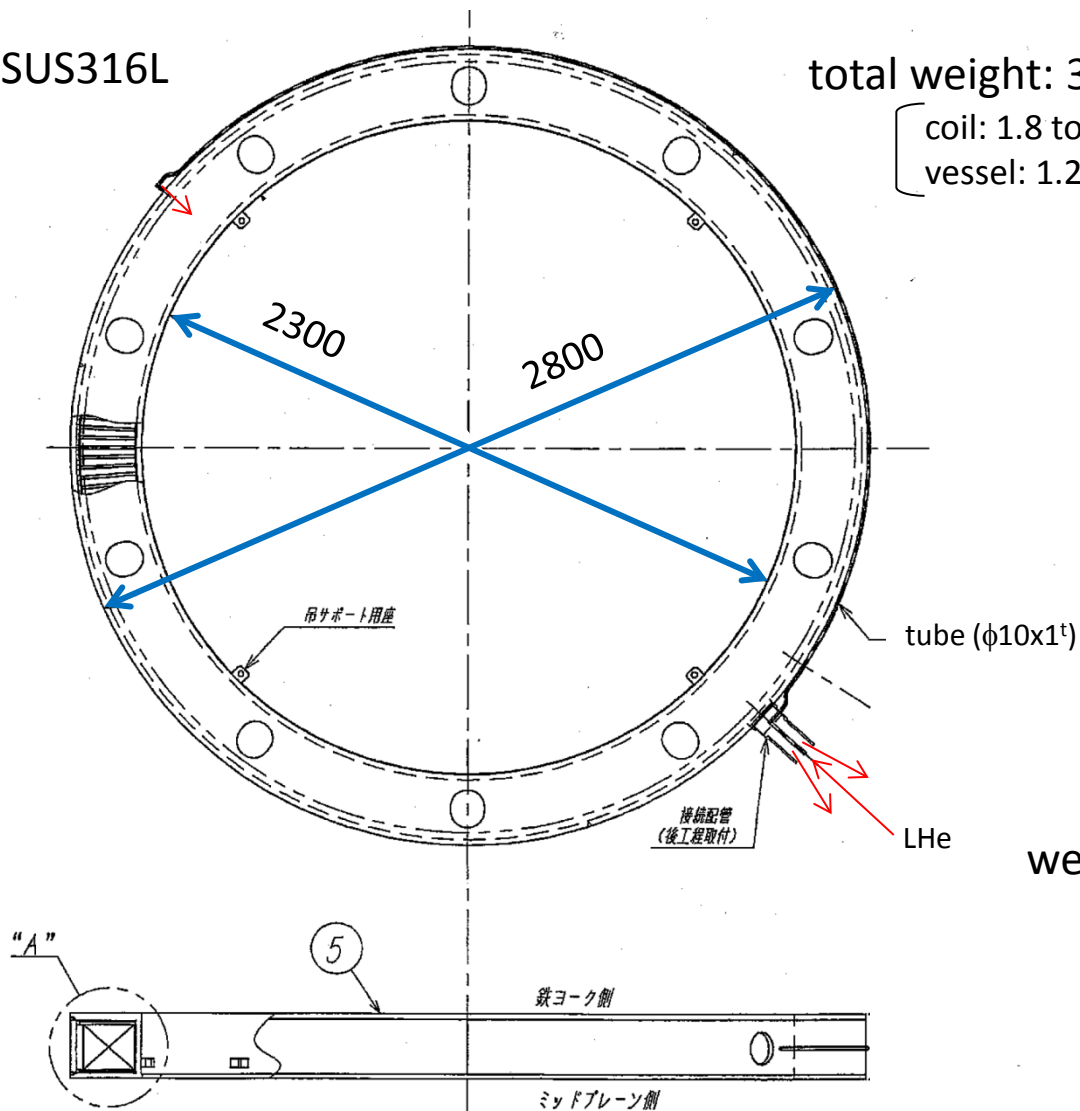
Coil vessel

SUS316L

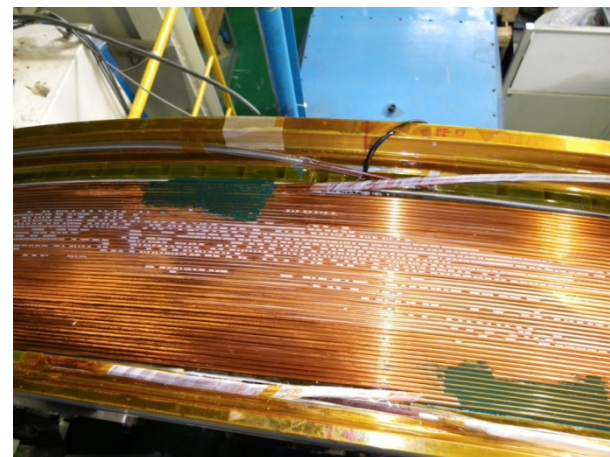
total weight: 3 ton

coil: 1.8 ton

vessel: 1.2 ton



LHe: 57.4 L



welding



Coil

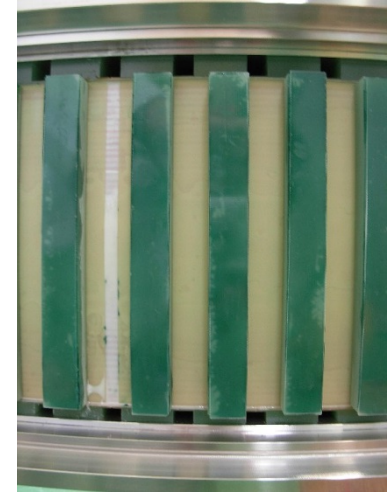
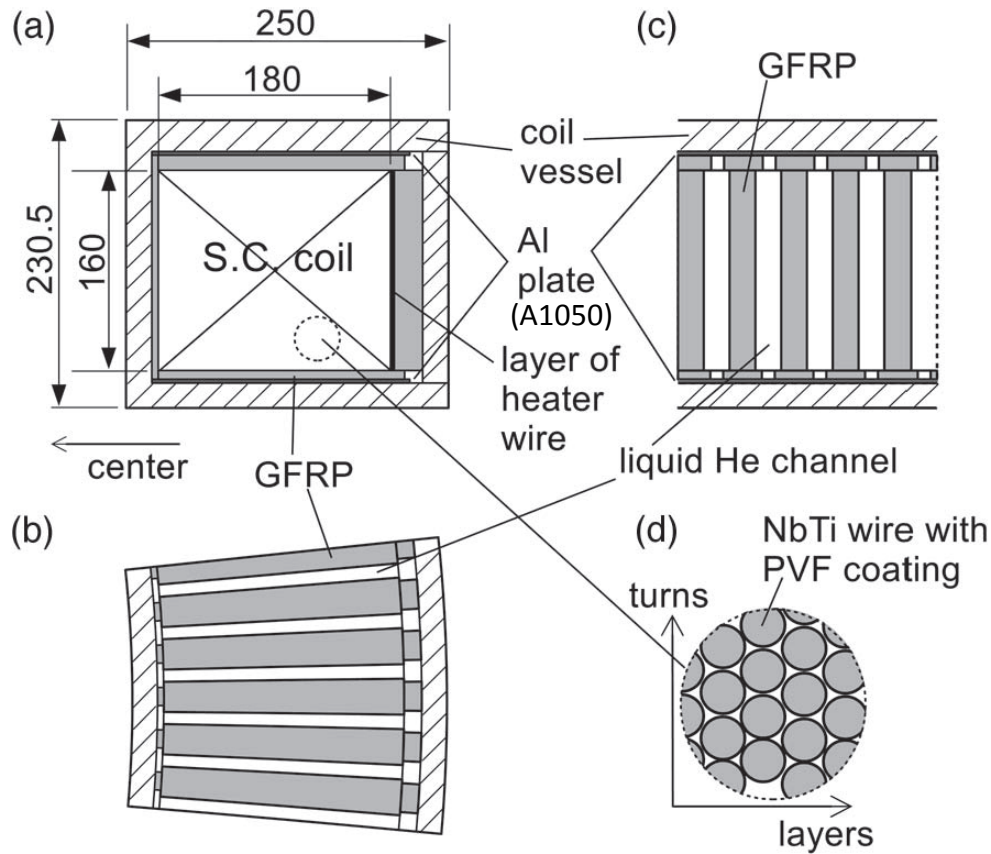


Fig. 7. Schematic view of the superconducting coil and the coil vessel. The coil vessel is made of SUS 316L. (a) Cross-sectional view. The copper heater wire is wound on the outermost layer of the coil. (b) Top (bottom) view of the inside of vessel. (c) Side view of the inside of vessel. (d) A detailed view of the wires in the coil. The epoxy resin is applied layer by layer.

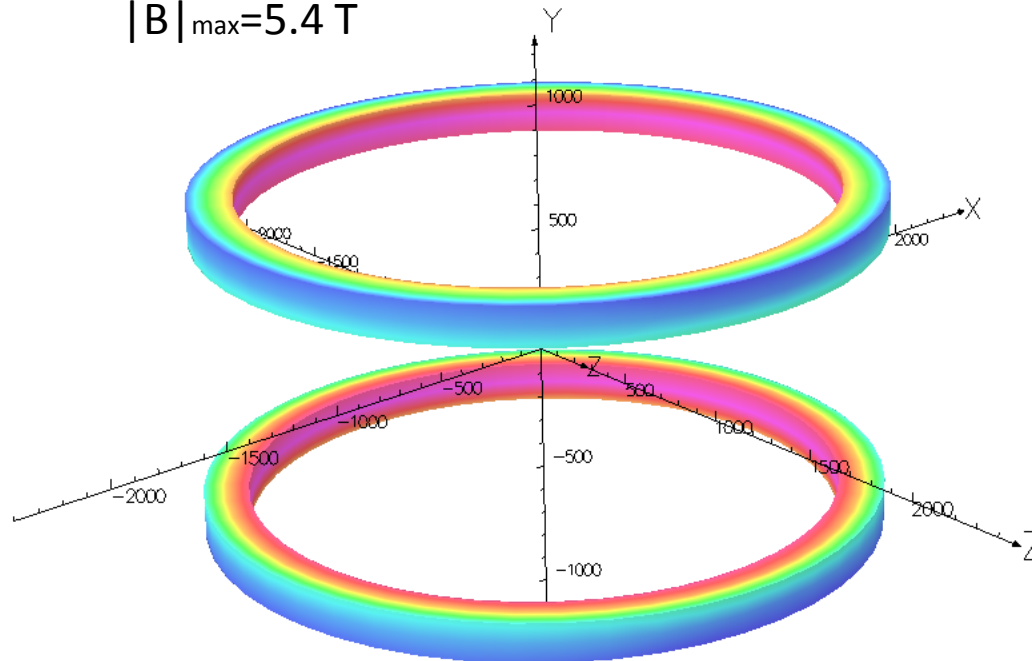
Coil

Fields at the coil surface

$|B|$ [T]

$I=563$ A, $B=3.08$ T

$|B|_{\max}=5.4$ T



UNITS

Length	mm
Magn Flux Density	T
Magnetic Field	A/m
Magn Scalar Pot	A
Current Density	A/mm ²
Power	W
Force	N

MODEL DATA

130806-bn_stage-d-3.08Top3
Magnetostatic (TOSCA)
Nonlinear materials
Simulation No. 1 of 1
20067978 elements
4439170 nodes
2 conductors
Nodally interpolated fields
Activated in global coordinates
Reflection in XY plane (Z field=0)
Reflection in YZ plane (X field=0)

Field Point Local Coordinates

Local = Global

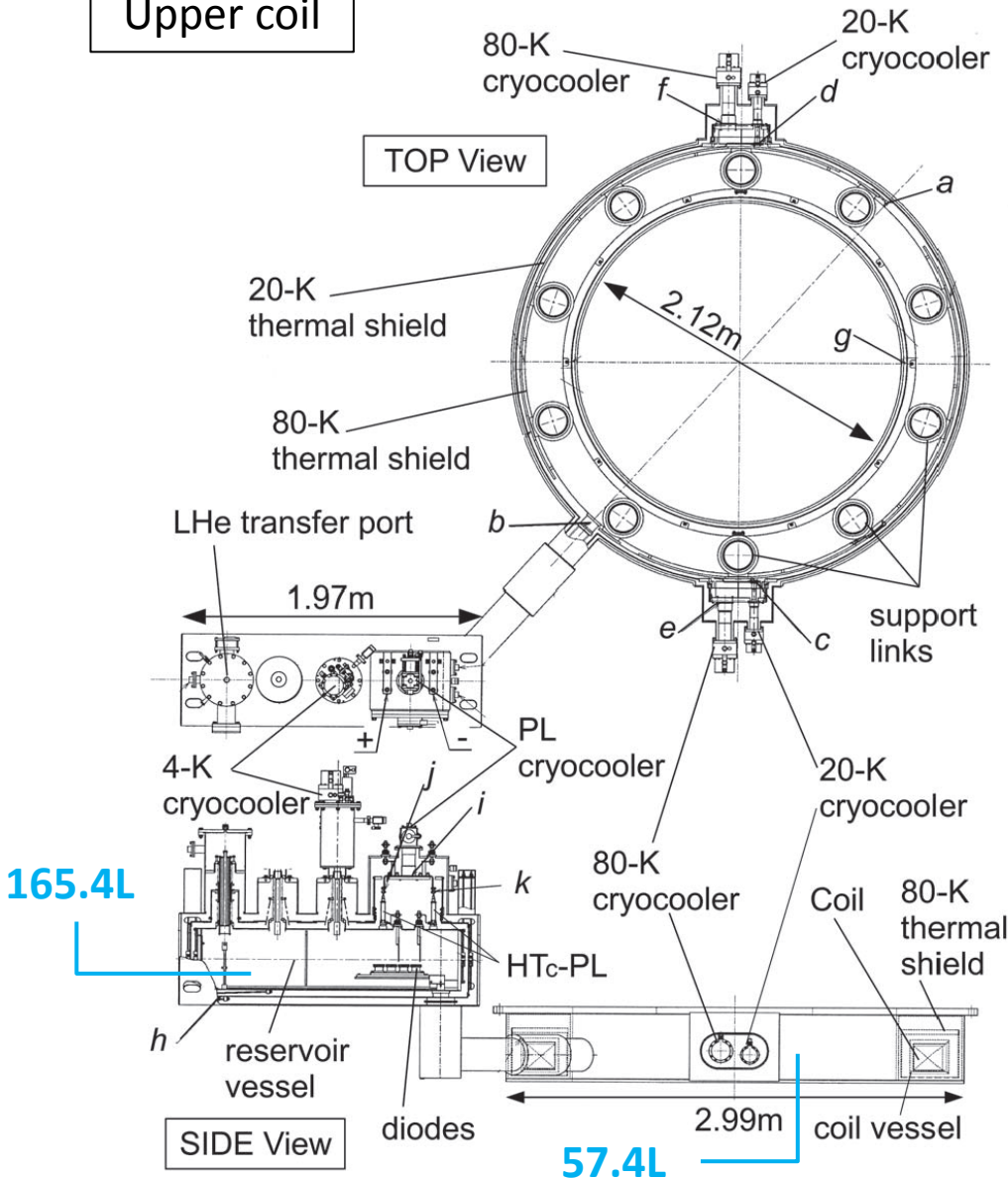
FIELD EVALUATIONS

Line LINE (nodal) 1001 Cartesian
x=0.0 y=0.0 z=-2000.0 to 2000.0

opera
simulation software

Cryostat

Upper coil



Cold mass (@4.2K)

- coil: 1.8 ton
- coil vessel: 1.2 ton
- reservoir vessel+pipe: 0.5 ton

➡ 3.5 ton / coil

From RT to 4.2K ...

LN₂: 3000L/coil

LHe: 1500L/coil

3 weeks / 2coils

Amount of LHe

- coil vessel: 57.4 L
- reservoir vessel: 165.4 L
- pipe: 10.9 L for upper coil
16.7 L for lower coil

➡ ~240 L/coil

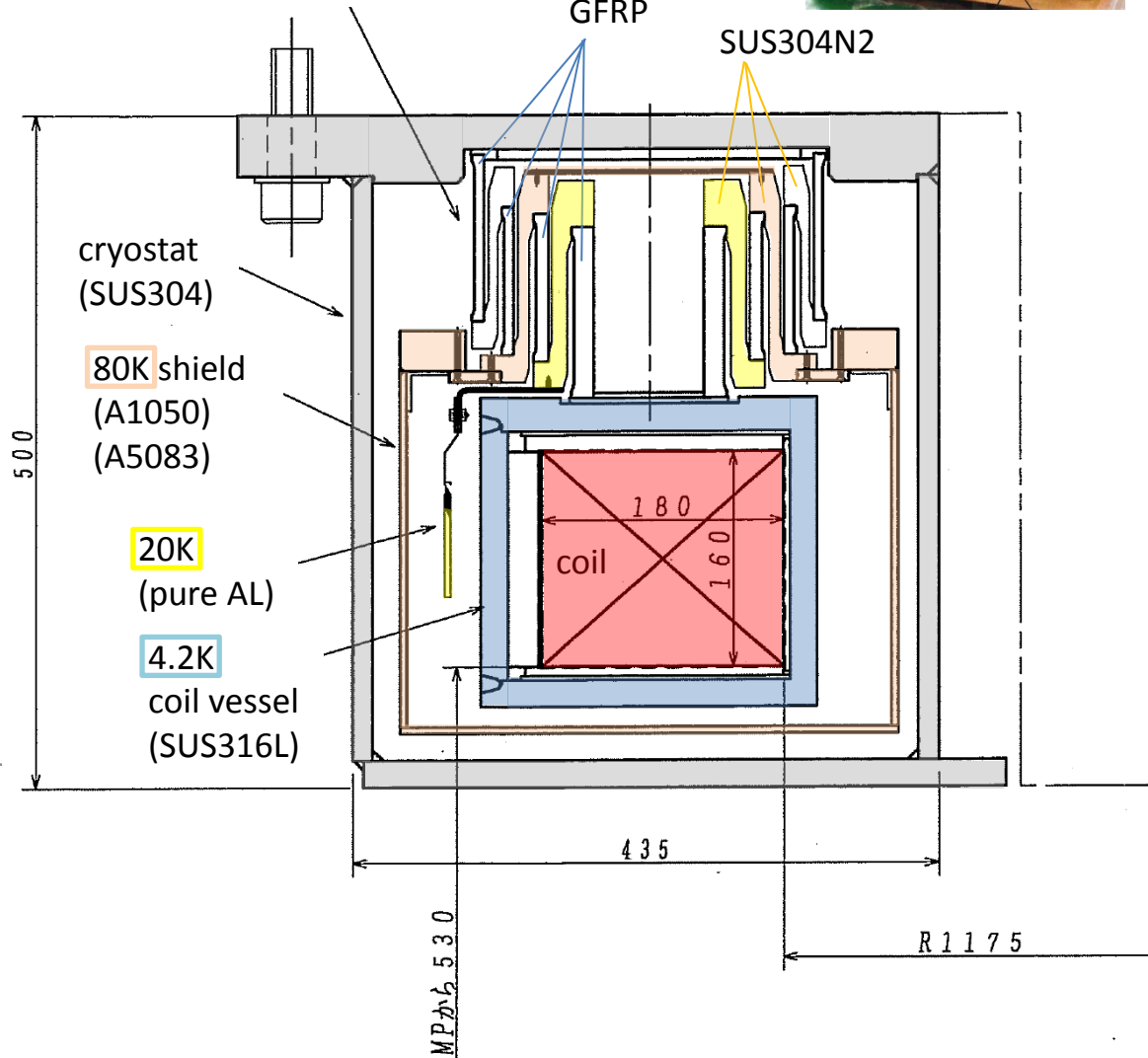
Cryostat



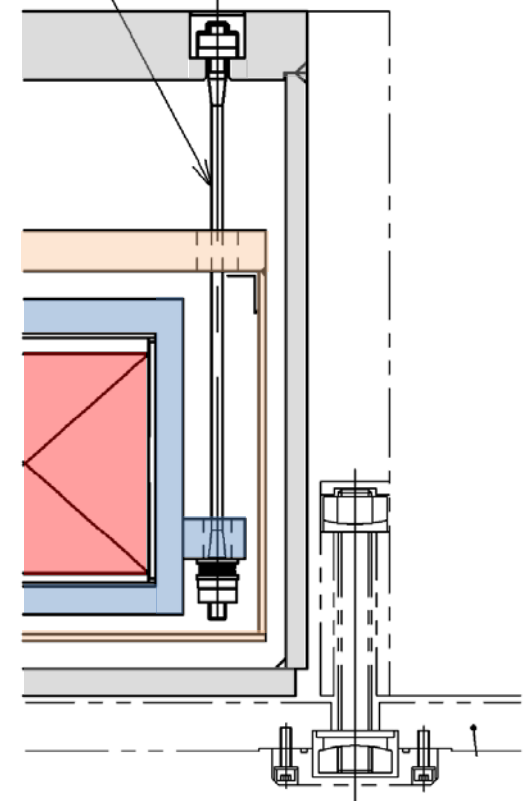
support link
(GFRP)
(SUS304N2)

GFRP

SUS304N2



suspension rod
(GFRP)



Estimated Heat load/coil

(calculated for the lower coil)

4K part

Place	Parts	Heat load	@ramping	@I=560 A	@I=0 A
In the cryostat + Chimney pipe	Thermal shield	Radiation	0.40	0.40	0.40
	Support	Conduction	1.35	1.35	1.35
	Coil	AC loss	0.50	0.00	0.00
In the reservoir vessel (port)	Thermal shield	Radiation	0.52	0.52	0.52
	Support	Conduction	0.04	0.04	0.04
	Power leads	Conduction + Joule loss	0.54	0.54	0.30
	He gas	Conduction	0.57	0.57	0.57
	Bellows		0.07	0.07	0.07
	Signal leads		0.12	0.12	0.12
Sum			4.11	3.61	3.37

GM/JT 2.5W@4.3K x2

20K part

Place	Parts	Heat load	@ramping	@I=560 A	@I=0 A
In the cryostat	Thermal Shield	Radiation	0.08	0.08	0.08
	Support	Conduction	4.88	4.88	4.88
Sum			4.96	4.96	4.96

GM 4.2W@12K x2

Estimated Heat load/coil

80K thermal shield

Place	Parts	Heat load	@ramping	@I=560 A	@I=0 A
In the cryostat + Chimney pipe	Thermal shield	Radiation	23.79	23.79	23.79
		Residual gas	0.60	0.60	0.60
	Support	Conduction	53.83	53.83	53.83
Sum			78.22	78.22	78.22

GM 100W@80K x2

Power lead

Place	Parts	Heat load	@ramping	@I=560 A	@I=0 A
In the reservoir vessel (port)	Vacuum chamber	Radiation	10.99	10.99	10.99
		Residual gas	0.28	0.28	0.28
	Support	Conduction	0.47	0.47	0.47
	Power lead	Conduction + Joule loss	40.496	40.496	22.344
	Bellows	Conduction	1.708	1.708	1.708
Sum			53.94	53.94	35.78

GM 54W@40K x1

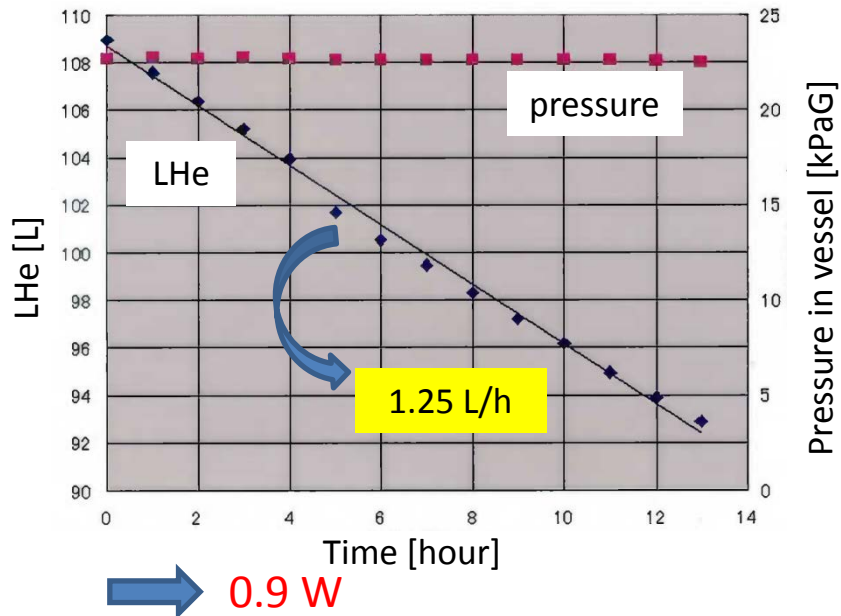
Heat load @4K

Heat load @4K /coil (estimation)

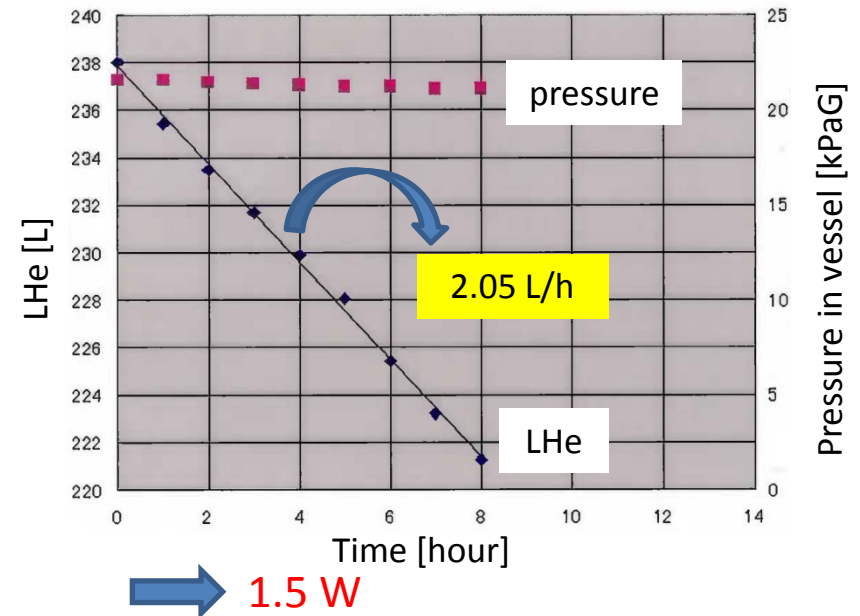
	@Ramping [W]	@I=560 A [W]	@I=0 A [W]
4 K part	4.11	3.61	3.37

Evaporation rate of LHe (measurement @I=0 A)

Upper cryostat



Lower cryostat



Two GM/JTs were prepared, but the measured heat load is smaller than the estimated value. Thus, just one GM/JT is used now.

Cryocoolers

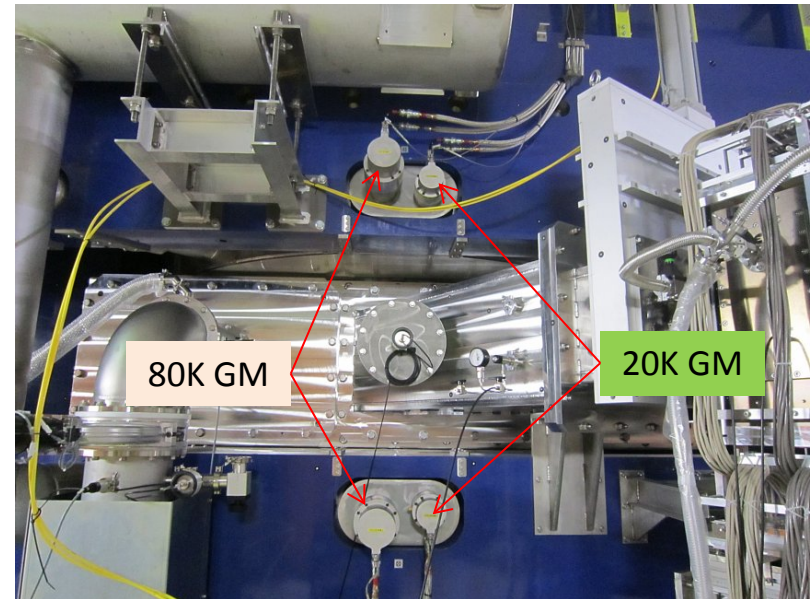
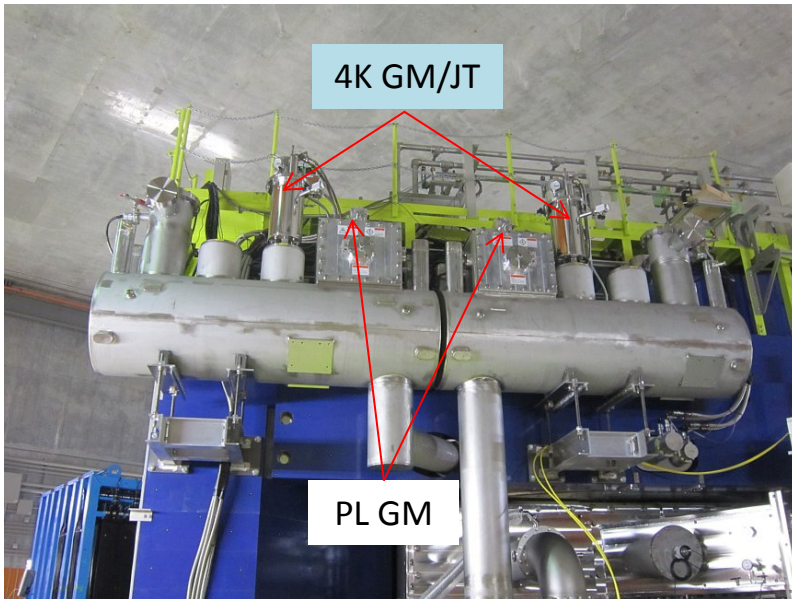
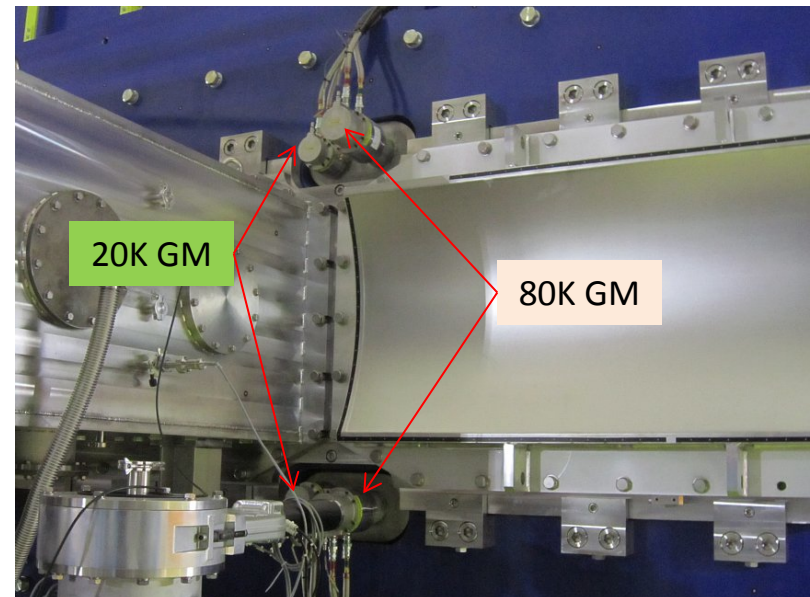


TABLE III
LIST OF THE CRYOCOOLERS FOR ONE CRYOSTAT

	He reservoir vessel	Thermal Shield		Power lead
		20 K	80 K	
Type	GM/JT	GM	GM	GM
No. of pcs	1	2	2	1
Model ^a	V308SLCR	V204SCP	V110CLR	RDK-400B
Cooling capacity	2.5 W @4.3 K	4.2 W @12 K	100 W @80 K	54 W @40 K

^aSumitomo Heavy Industries, Ltd.



12 cryocoolers are equipped.

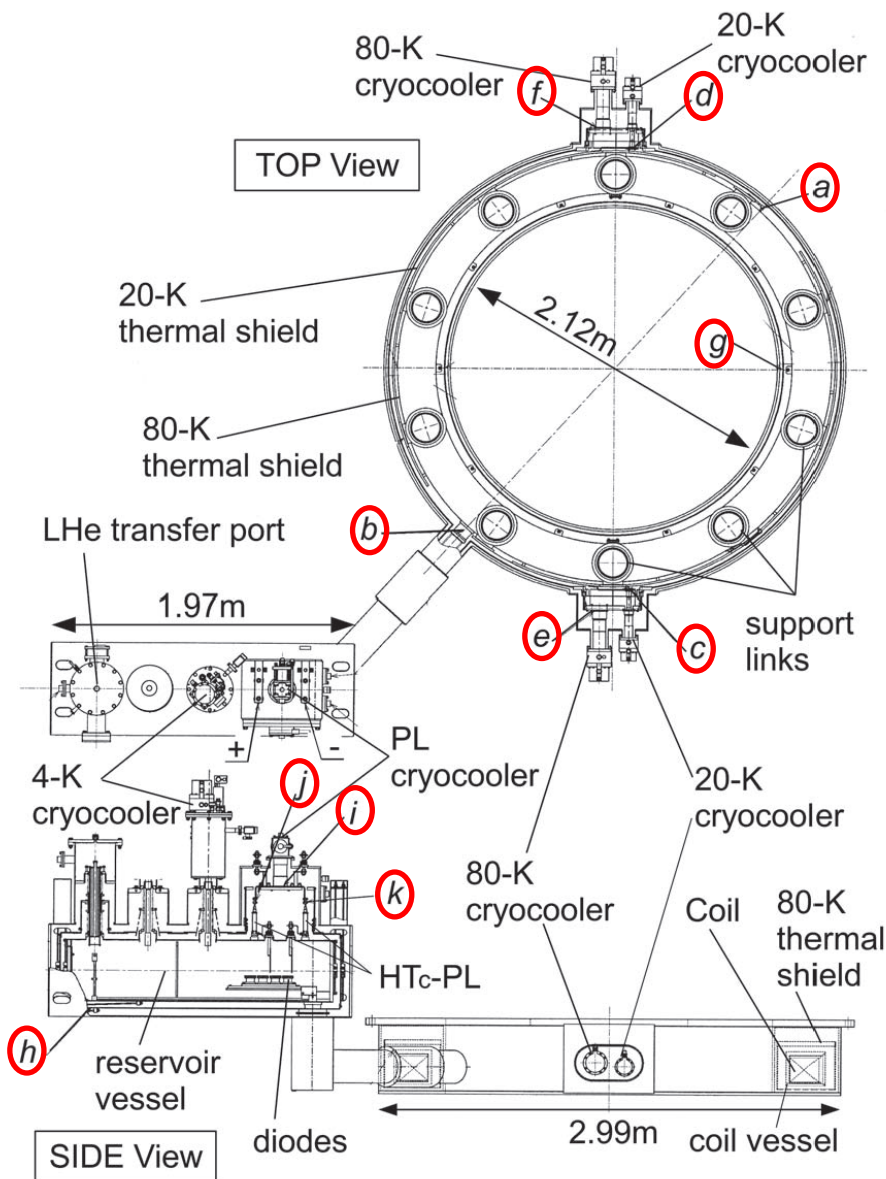
monitor screen of the controller
(6 Sept. 2013)

Temperature

常温2系統中フネット状態監視

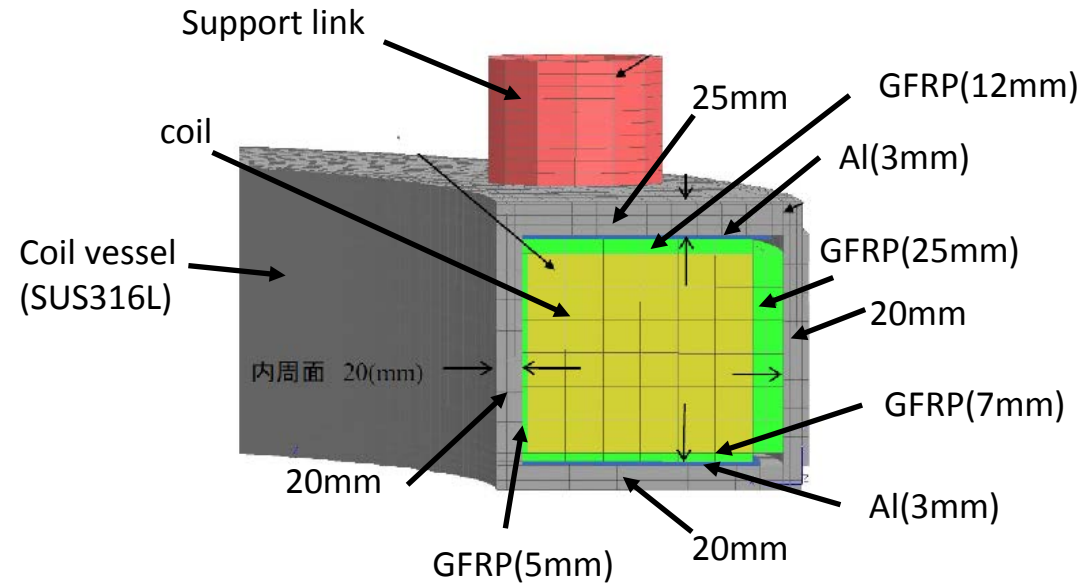
上3区 計測番号	計器名	測定値	下3区 計測番号	計器名	測定値
He容器(予冷管口) 温度	CKIU	4.2 K	He容器(予冷管口) 温度	CKIL	4.3 K
He容器(配管口) 温度	PLCoIU	7.1 K	He容器(配管口) 温度	PLCoIL	7.1 K
20K冷凍機A 温度	PLCoIU	11.8 K	20K冷凍機A 温度	PLCoIL	11.9 K
20K冷凍機B 温度	PLCoIU	11.6 K	20K冷凍機B 温度	PLCoIL	11.2 K
80K冷凍機A 温度	PLIU	40.9 K	80K冷凍機A 温度	PLIL	43.3 K
80K冷凍機B 温度	PLIU	41.6 K	80K冷凍機B 温度	PLIL	40.6 K
80K-84° 温度	PLIU	45.1 K	80K-84° 温度	PLIL	47.5 K
80K-84° 温度	PLIU	45.3 K	80K-84° 温度	PLIL	43.8 K
HTC-PL(+) 温度	PLIU	42.6 K	HTC-PL(+) 温度	PLIL	41.5 K
HTC-PL(-) 温度	PLIU	42.9 K	HTC-PL(-) 温度	PLIL	41.6 K
80K-84°(8°-1) 温度	PLIU	45.3 K	80K-84°(8°-1) 温度	PLIL	43.8 K
He容器 内圧	PTIU	7.8 PaG	He容器 内圧	PTIL	8.0 PaG
He容器 液面	LEIU	92.4 %	He容器 液面	LEIL	91.2 %
内圧制御-分 電圧		0.0 V	内圧制御-分 電圧		0.0 V
内圧制御-分 電流		0.0 A	内圧制御-分 電流		0.0 A
3区 電圧		-0.022 V	3区 電圧		-0.0 V
3区 電流		0.3 A	3区 電流		0.0 A

	Place	Upper coil [K]	Lower coil [K]
a	He vessel (outside of the wall)	4.2	4.3
b	He vessel (port)	7.1	7.1
c	20K GM A	11.8	11.9
d	20K GM B	11.6	11.2
e	80K GM A	40.9	43.3
f	80K GM B	41.6	40.6
g	80K thermal shield	45.1	47.5
h	80K thermal shield (reservoir vessel)	45.3	43.8
i	PL GM	42.6	41.5
j	PL (+)	42.9	41.6
k	PL (-)	42.8	41.6

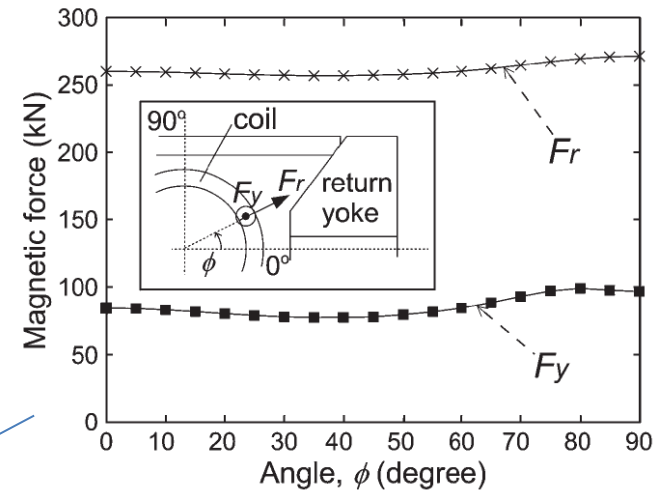


Structural Analysis

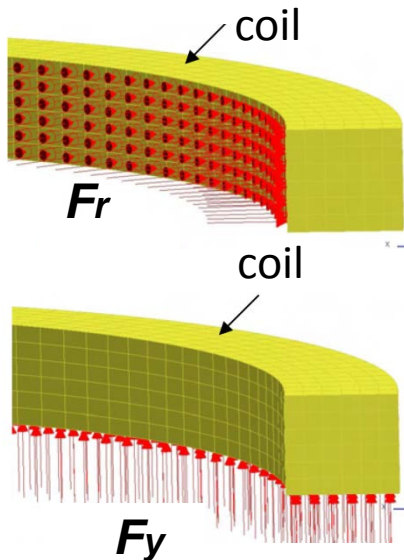
FEM analysis: coil + coil vessel + support link



Magnetic forces as a function of the azimuthal angle



integrate



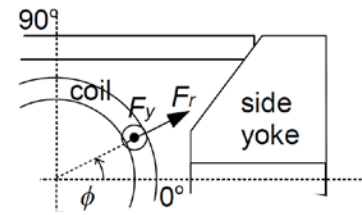
$$F_r = 5 \times 10^3 \text{ kN} \quad (2000 \text{ ton/coil})$$

$$F_y = 1.5 \times 10^3 \text{ kN} \quad (600 \text{ ton/coil})$$

TABLE V
MATERIAL PARAMETERS OF THE COIL AND THE VESSEL

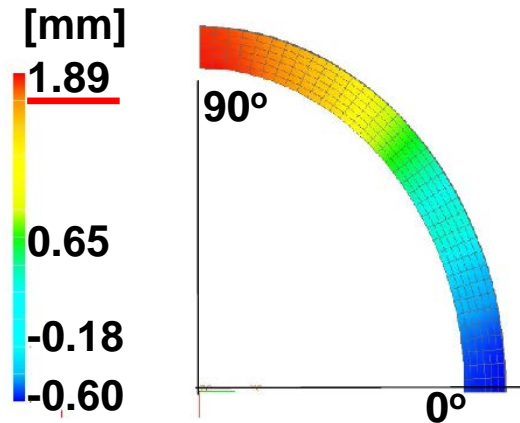
Material	Young's modulus	Poisson's ratio	Transverse elasticity modulus
Coil	r direction	0.3	17 GPa
	ϕ direction	0.3	19 GPa
	y direction	0.3	17 GPa
GFRP	32 GPa	0.3	-
SUS316L	200 GPa	0.3	-
Aluminum	80 GPa	0.3	-

Structural Analysis



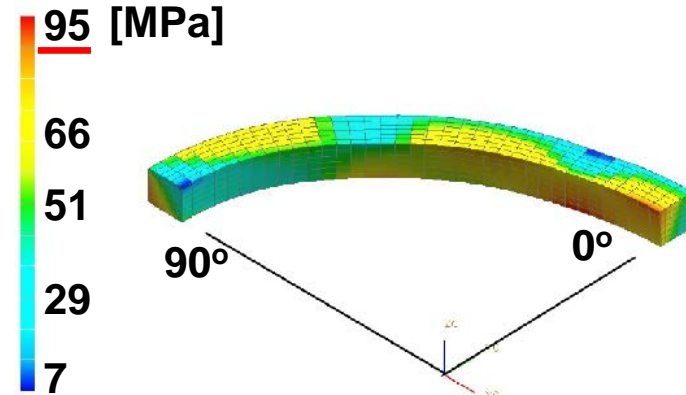
R-direction

Displacement of the coil



Y-direction: 0.22 mm

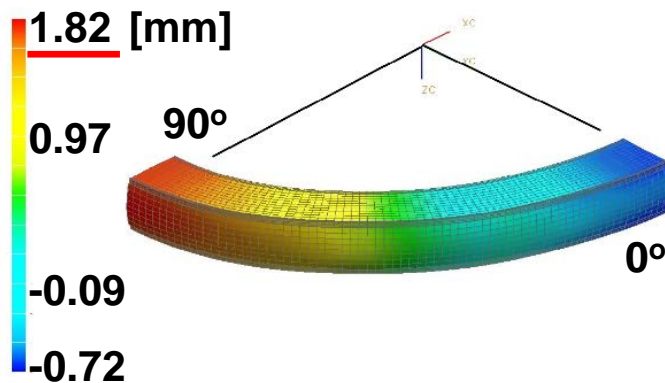
Principal stress in the coil



Allowable stress=180MPa@RT

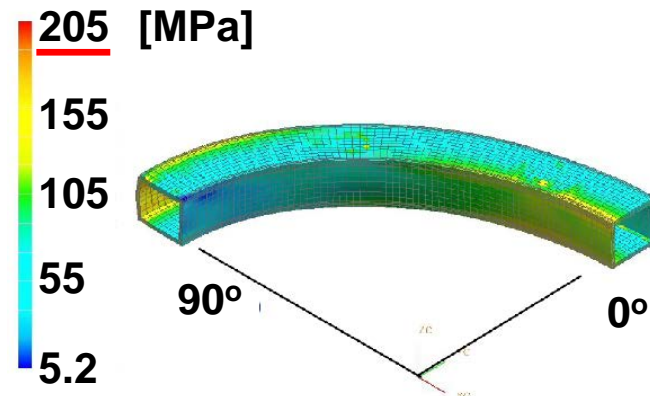
R-direction

Displacement of the vessel



Y-direction: 0.19 mm

Von Mises stress in the vessel



Allowable stress=600MPa@4K

Safety interlock

			Action			
	Interlock	Condition	CUT OFF (DCCB open)	Quench back heater ON	Power supply OFF	Alarm
1	Failure of power supply	Over voltage, Over current, Water leakage, Door open			○	○
		Fuse break Cryo-controller down	○	○		○
2	Water flow (PS) down	< 40 L/min			○	○
3	Quench	$V_{diff} > 1\text{ V}$ Duration time > 0.5 s	○	○		○
4	Power failure	Power failure	○	○		○
5	Failure of the PL cryocooler	Stop			○	○
6	Voltage of HT _c -PL	$V_{PL} > 10\text{ mV}$, $V_{PL} < -10\text{ mV}$	○	○		○
7	Temperature of HT _c -PL 1	$T > 70\text{ K}$			○	○
8	Temperature of HT _c -PL 2	$T > 75\text{ K}$	○	○		○
9	Lack of LHe	Level < 80%			○	○
10	Pressure of the vessel 1	$P > 19\text{ kPaG}$ (120.3 kPa)				○
11	Pressure of the vessel 2	$P > 40\text{ kPaG}$ (141.3 kPa)			○	○
12	Emergency stop	Push emergency button	○	○		○

cryostat

DCCB

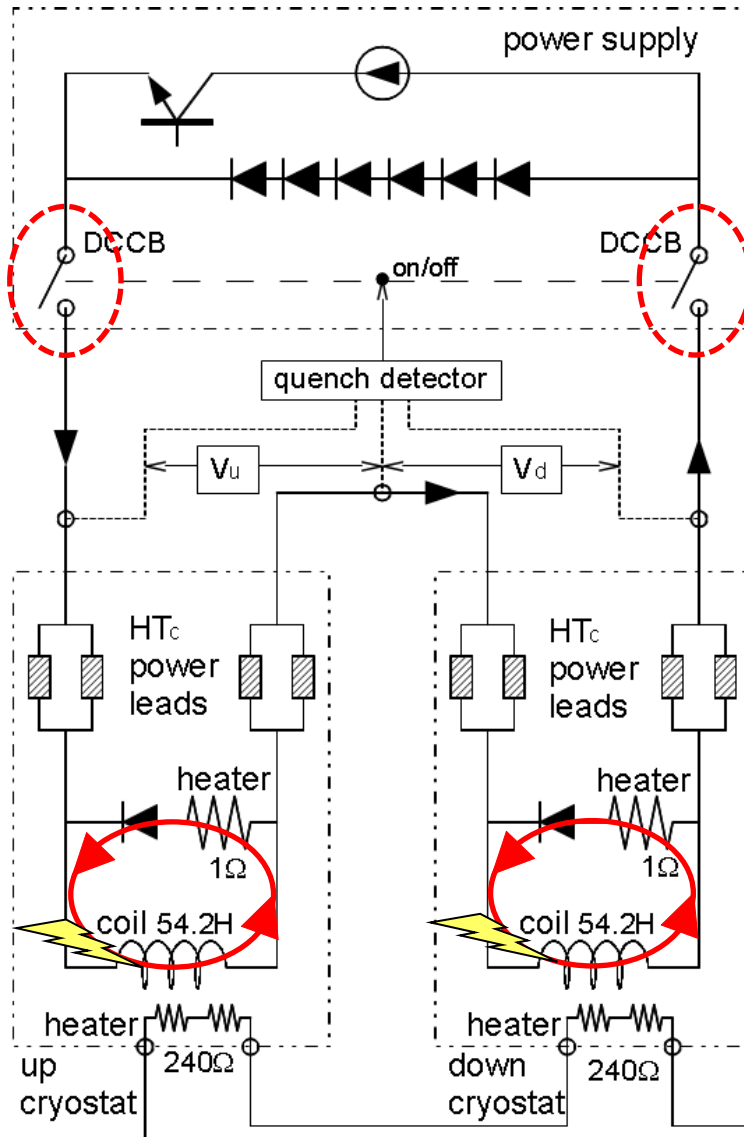
PS OFF

The coils are forced to quench. The current is discharged through the diodes in the cryostat and the coils.

The current is discharged through the diodes mounted in the power supply.

power
supply

Quench protection



Quench

1. The detector recognizes the quench. (1V, 0.5s)
2. DCCB open (Coils are cut off.)
3. Current flows to the heater layer on the outermost of the coil.
4. Backup heaters switch on within 50 ms.
5. Coils are forced to quench from the outer to inner layer.
6. Stored energy is dumped by the superconducting coils.

In the case ...

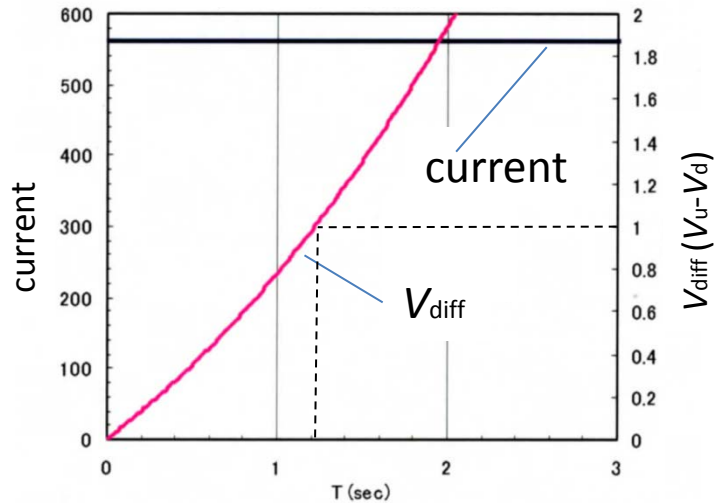
- cryo-controller down
- power failure
- $|V_{PL}| > 10 \text{ mV}$
- $T_{PL} > 75 \text{ K}$
- emergency stop



Same procedure as the quench case will be done.

Quench analysis

change of V_{diff} after quench



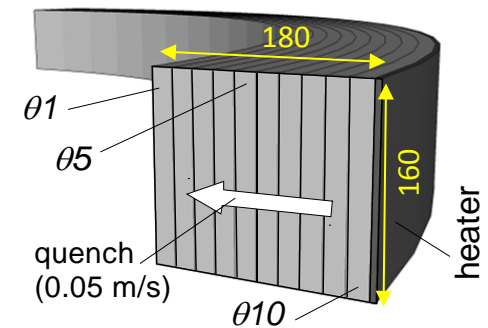
quench propagates longitudinal direction

$$v_{q//} = 10 \text{ m/s}$$

$V_{diff} > 1V$ at 1.2 sec.

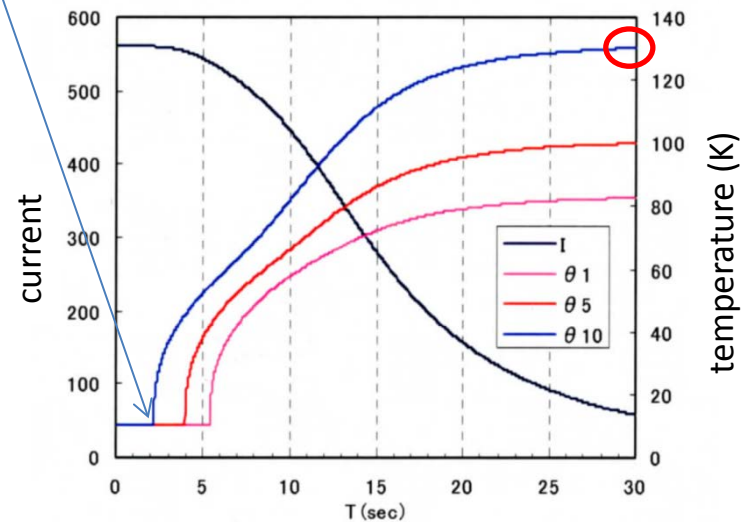
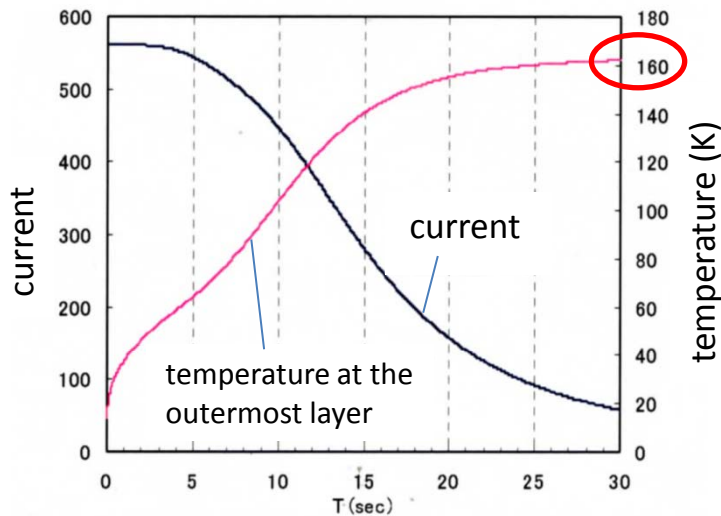
0.5 sec. before cut off
+
0.3 sec. delay before
heater on

Total: 2 sec.



quench propagates transverse (radial) direction

$$v_{q\perp} = 0.05 \text{ m/s (estimated from the value of KEK-SKS)}$$



Temperature rise is moderate and acceptable

Quench analysis

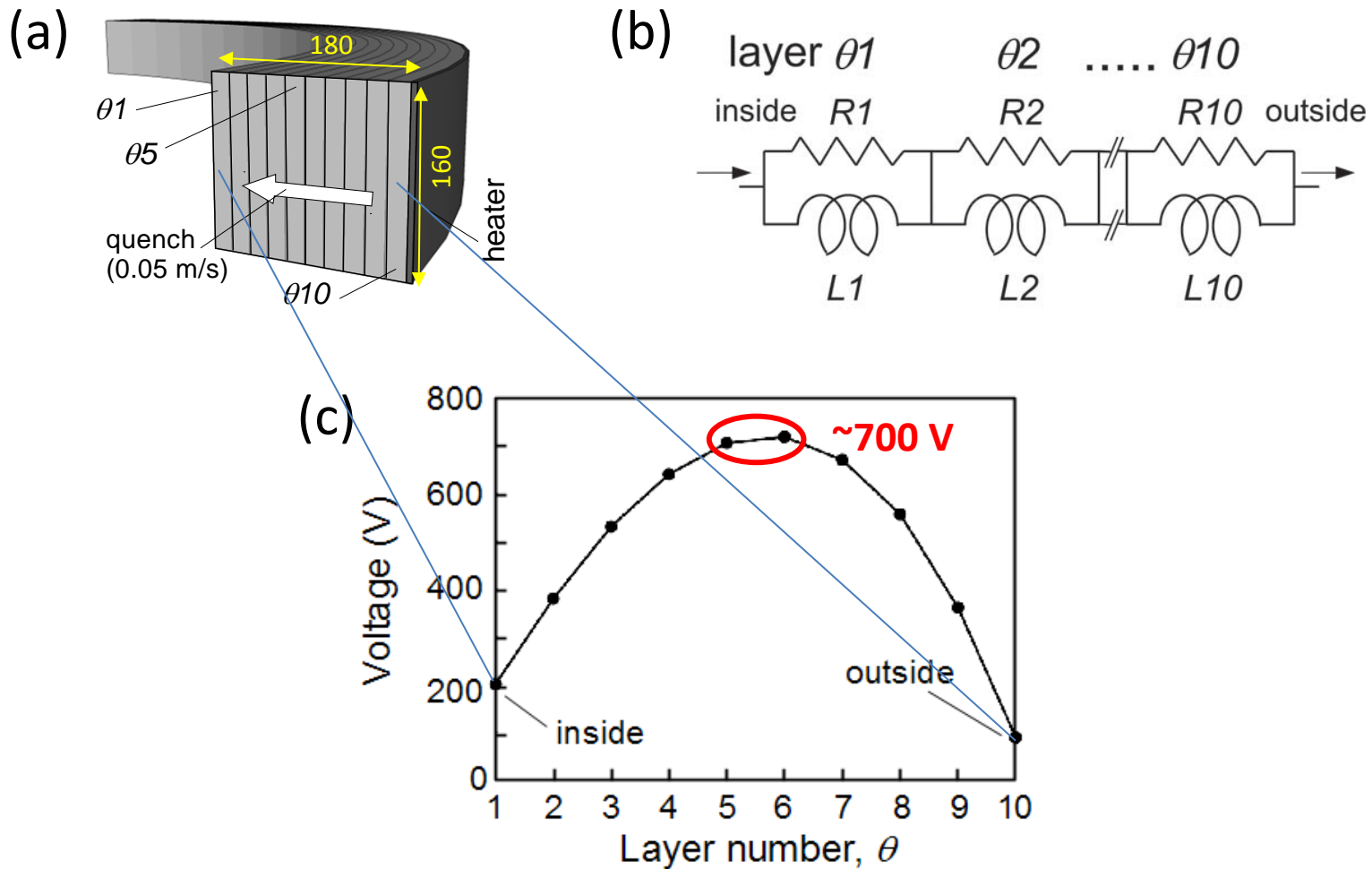
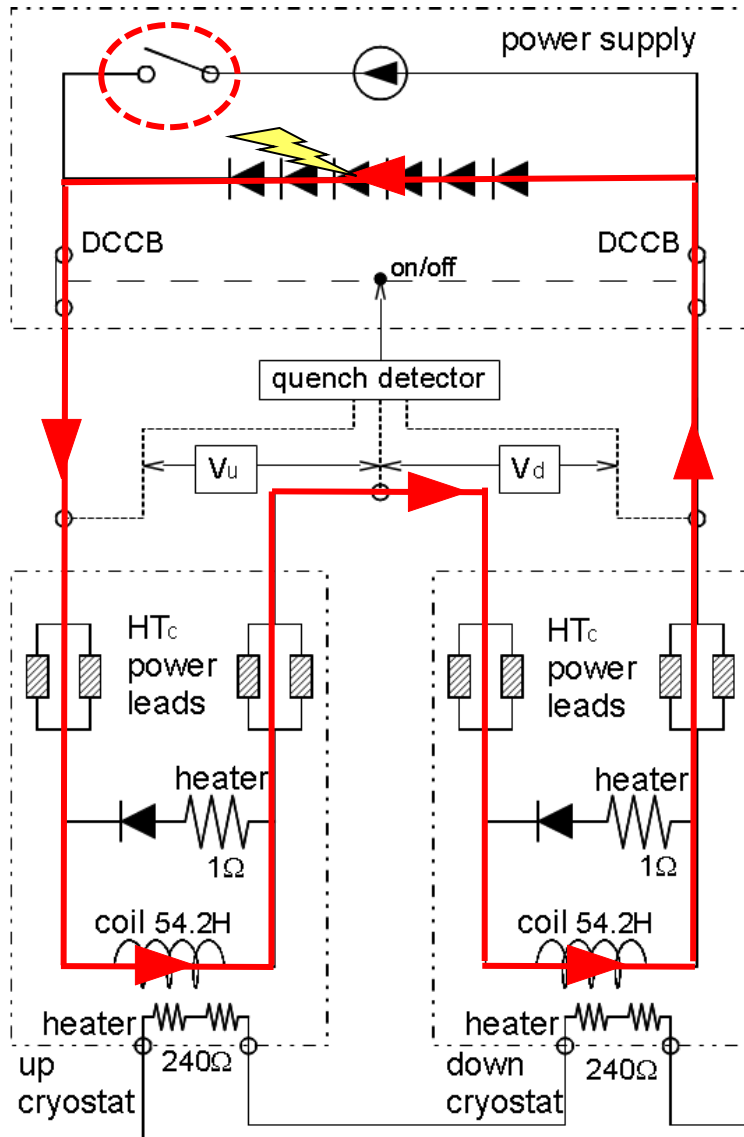


Fig. 13. Simulated quench characteristics for the induced voltage. (a) Definition of the layer segmentation. (b) Equivalent circuit of the coil assumed in the simulation. Each layer θ has a resistance R and an inductance L . (c) Maximum induced voltage at each layer.

Induced voltage is moderate and acceptable

Coil protection



In the case ...

- over voltage
- over current
- door open
- water leakage
- water flow down
- PL cryocooler failure
- $T_{PL} > 70\text{ K}$
- LHe level $< 80\%$
- $p_{He} > 40\text{ kPaG}$

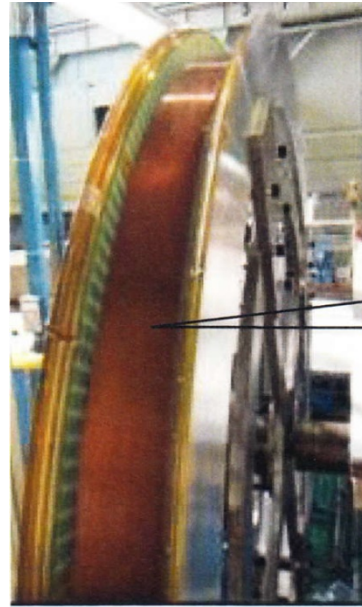
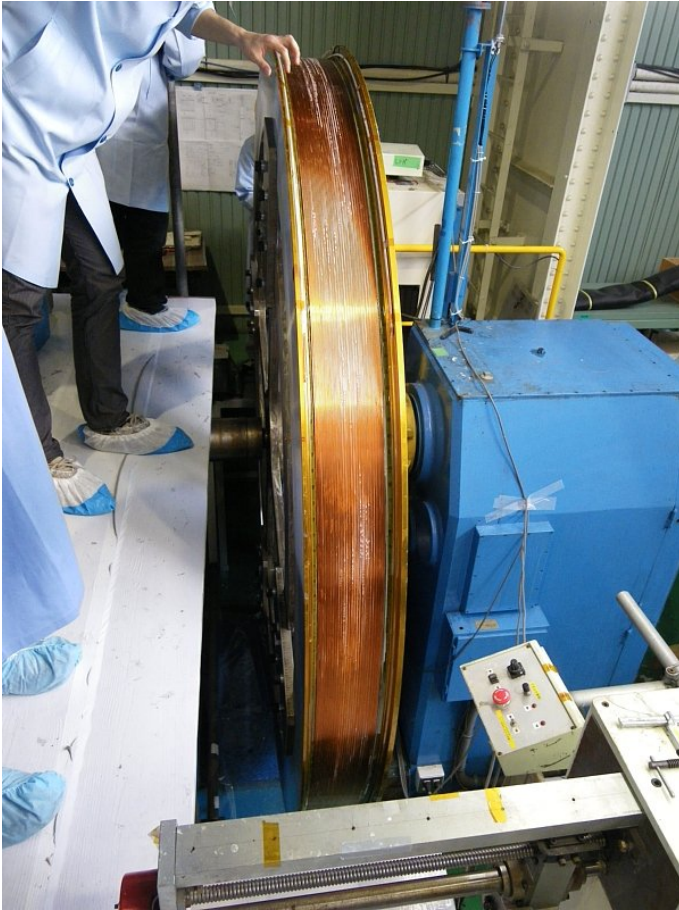
1. Power supply is cut off
2. Stored energy is dumped by diodes in the power supply
3. Diodes are cooled by heat-sink and fan



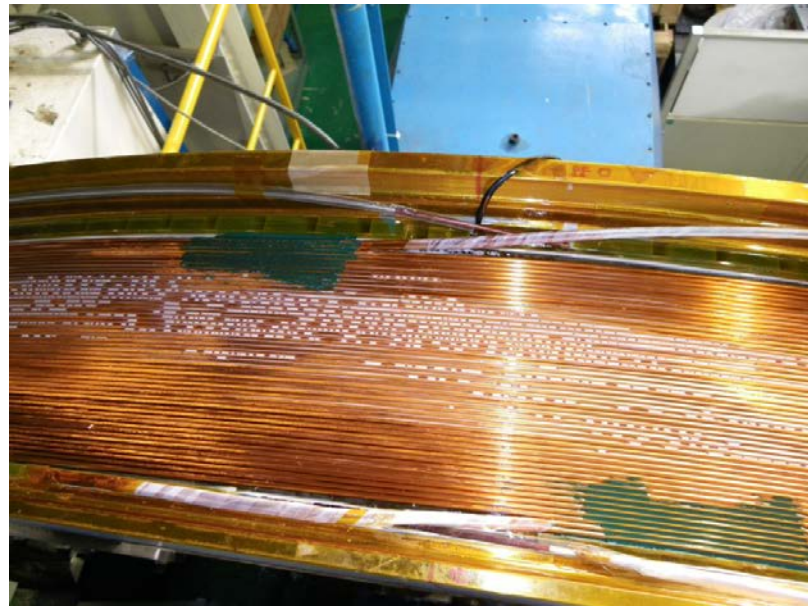
from 560A to 0A : ~1 hour

decay const. : 0.25A/sec

Cryostat assembling



coil winding



Cryostat assembling

reservoir vessel



cryostat chamber

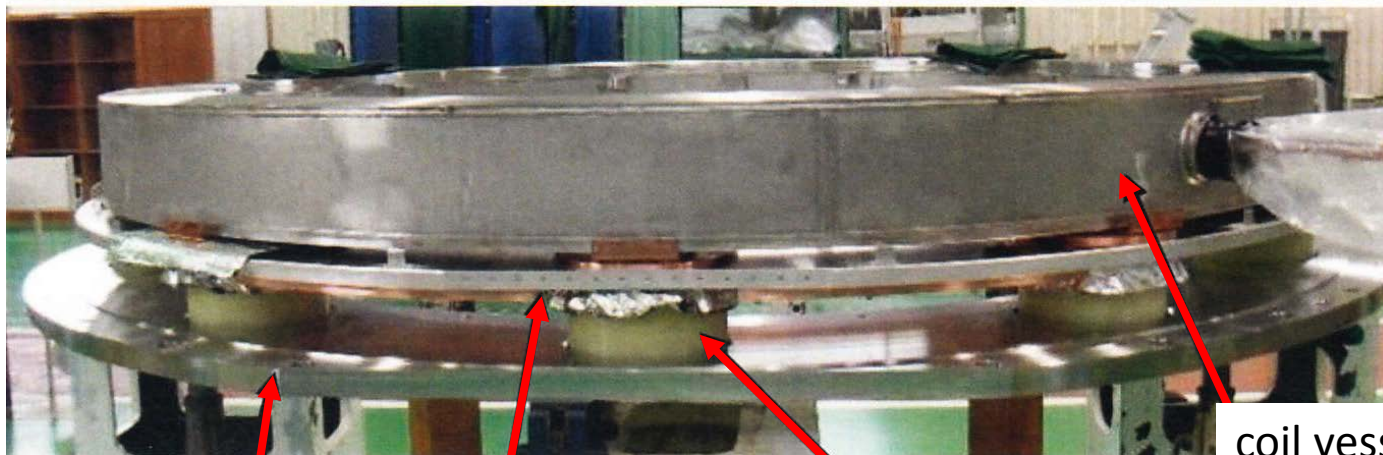


Cryostat assembling

Lower cryostat assembling



support link



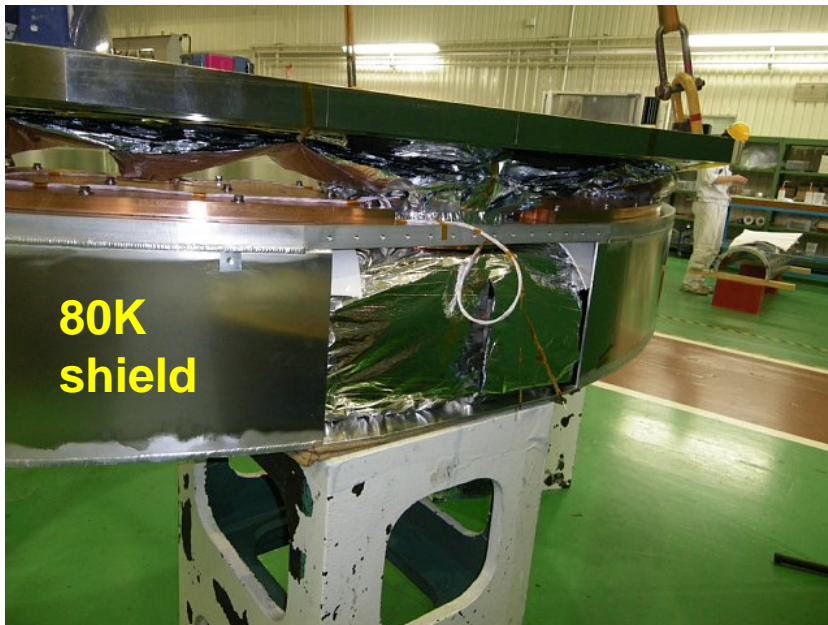
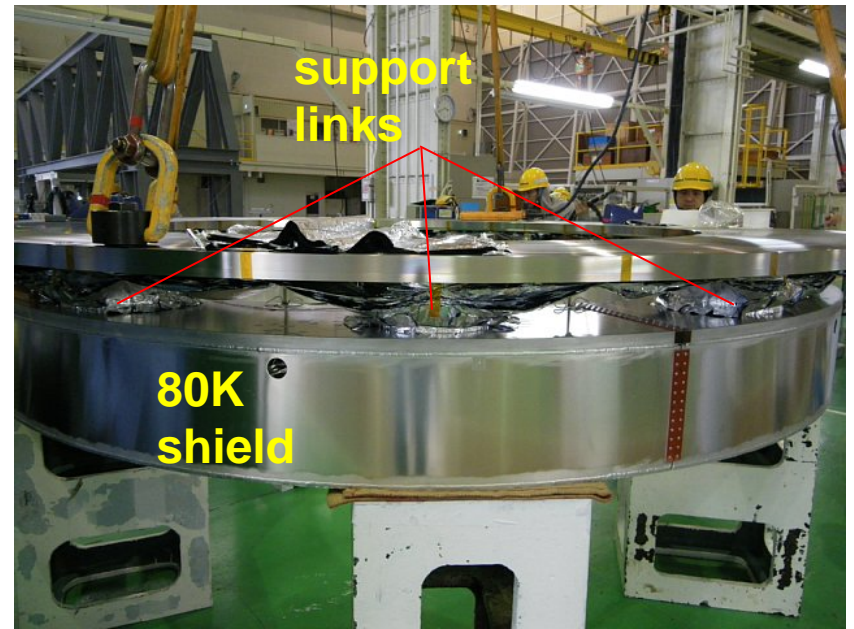
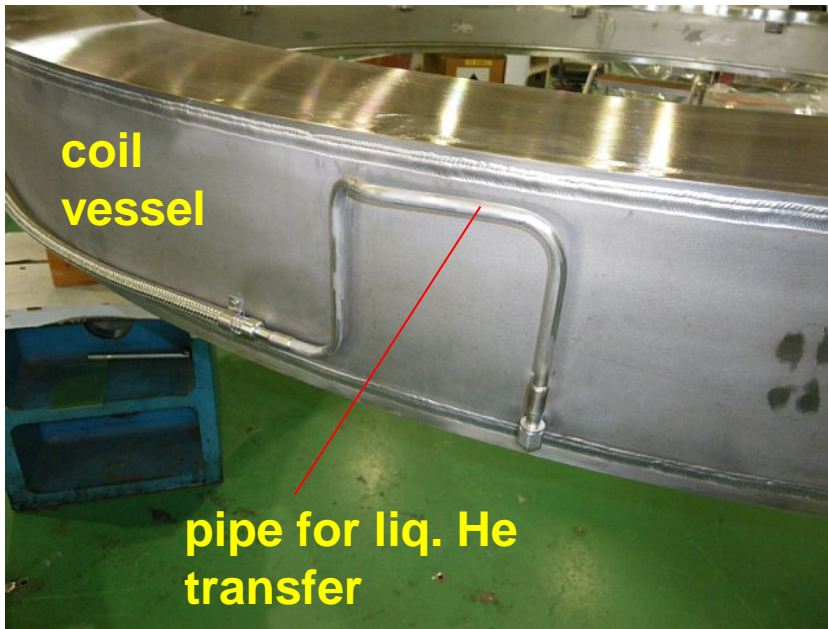
part of cryostat
chamber

part of 80K
shield

support link

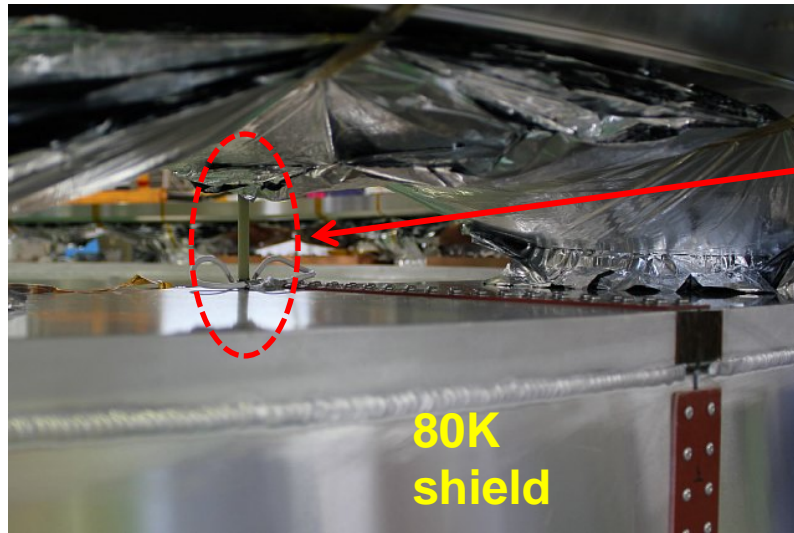
coil vessel

Cryostat assembling



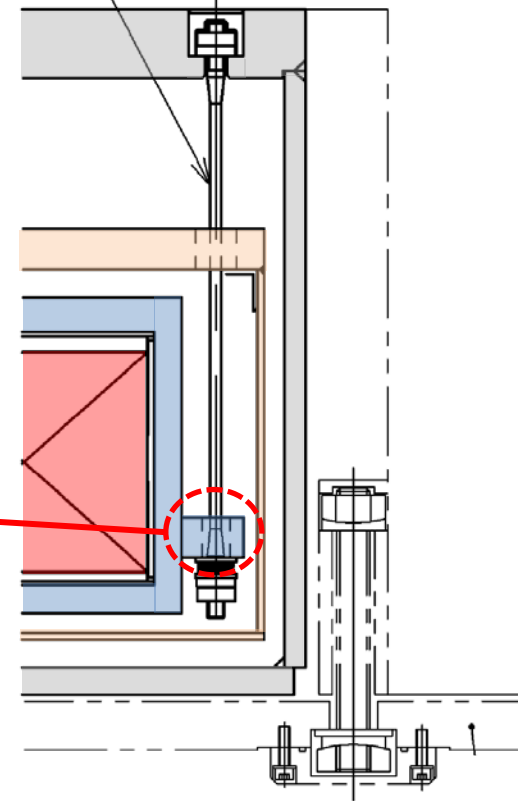
Cryostat assembling

Upper cryostat



Upper cryostat

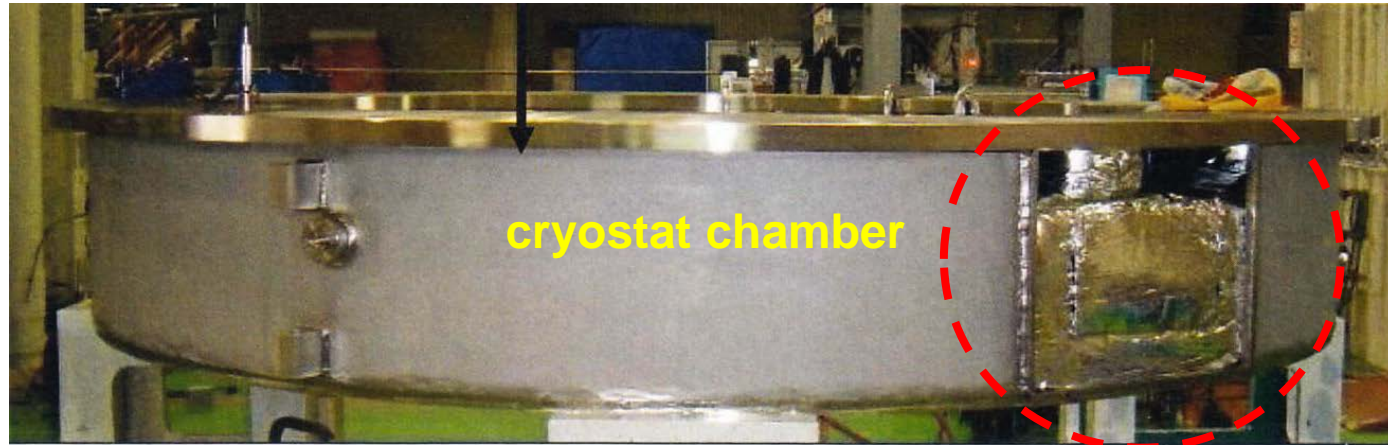
suspension rod
(GFRP)



Lower coil

Cryostat assembling

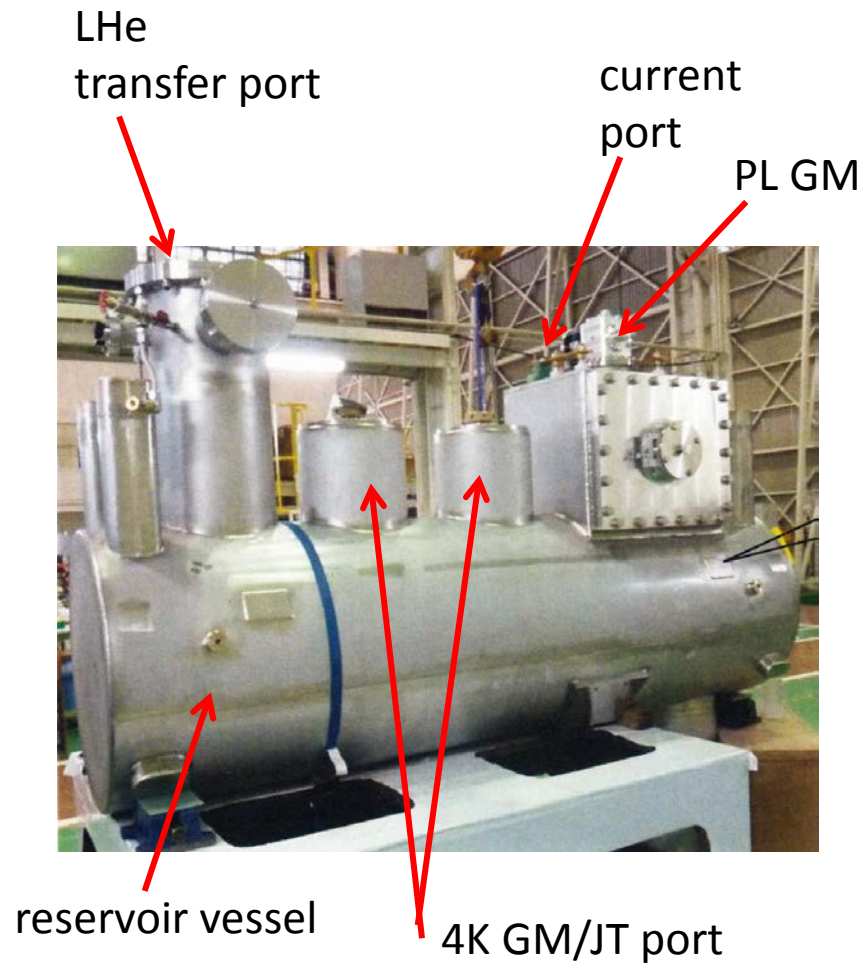
Upper cryostat



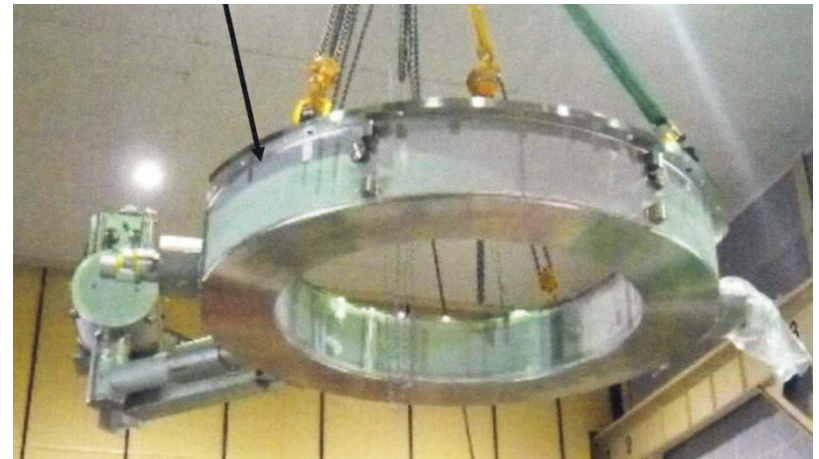
20K GM

80K GM

Cryostat assembling



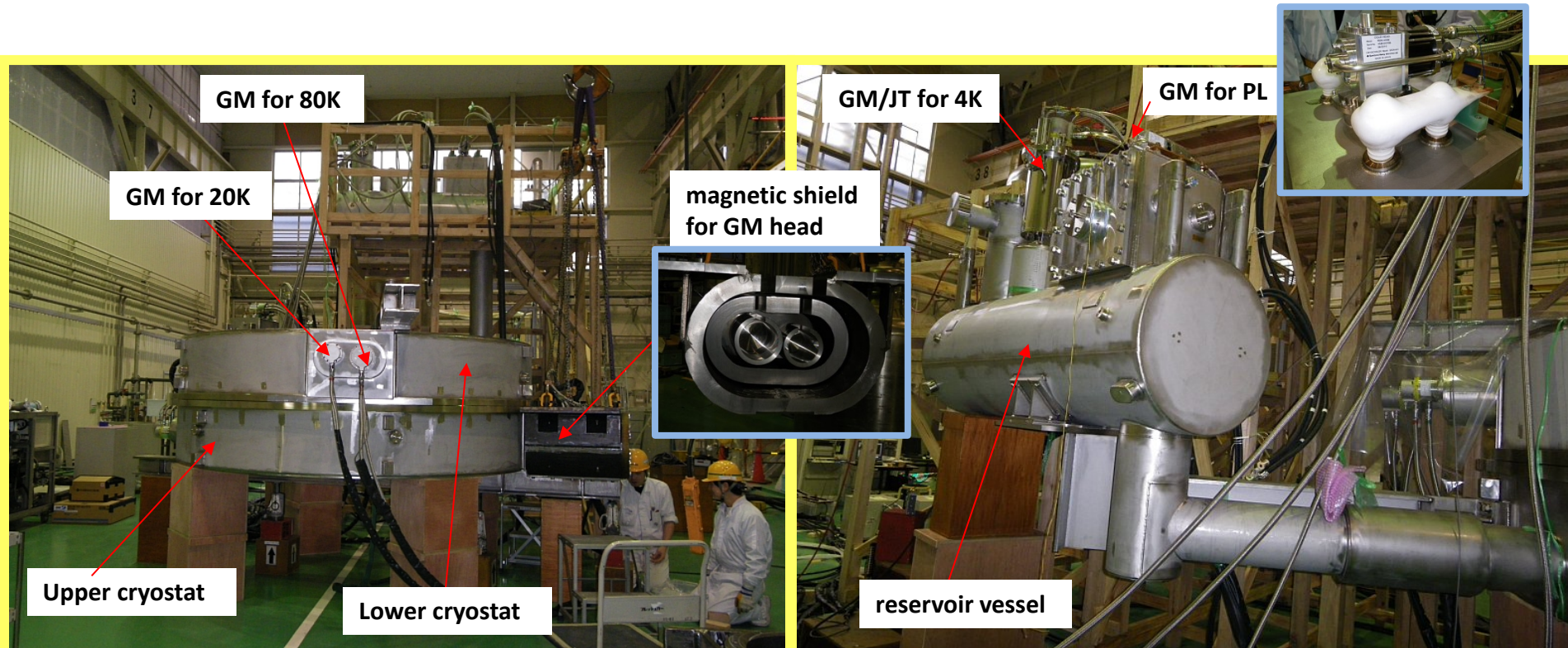
Upper cryostat



Lower cryostat



Test in Toshiba factory



Excitation test (1st time)

1. polarity check by applying 1 A
2. apply 10A -> cut off to check the protection sequence
3. excite to 518.4 A -> **training quench happened @450 A**

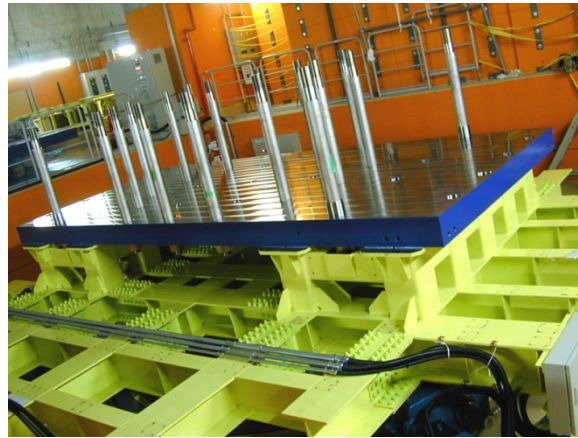
Excitation test (2nd time)

1. excite to 530 A -> **success without quench** ←
 - ~4 T in the coil region
 - ~624 ton

On site assembling



Rails for rotatable base
(11/13/2010)



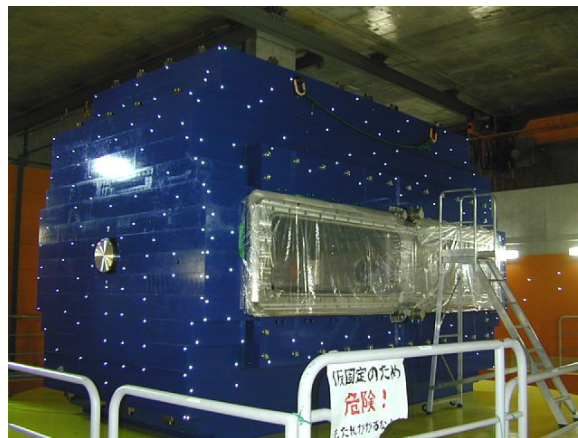
Rotatable base with the first
layer of the yoke



Magnet yoke with poles



Coils with cryostats, LHe
reservoir vessels



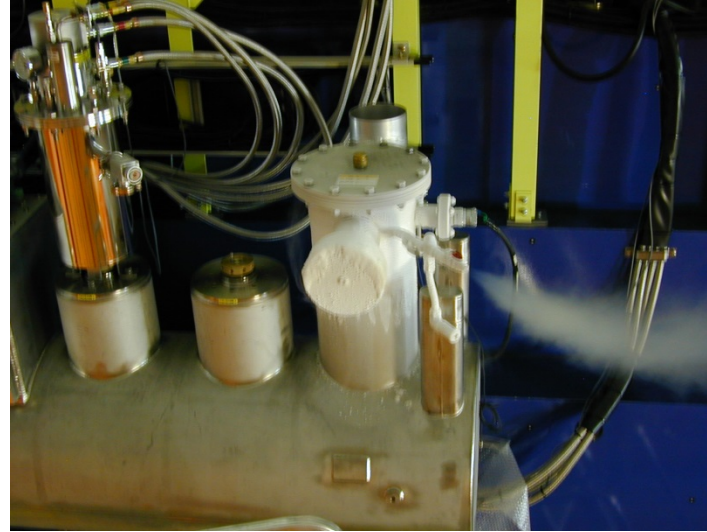
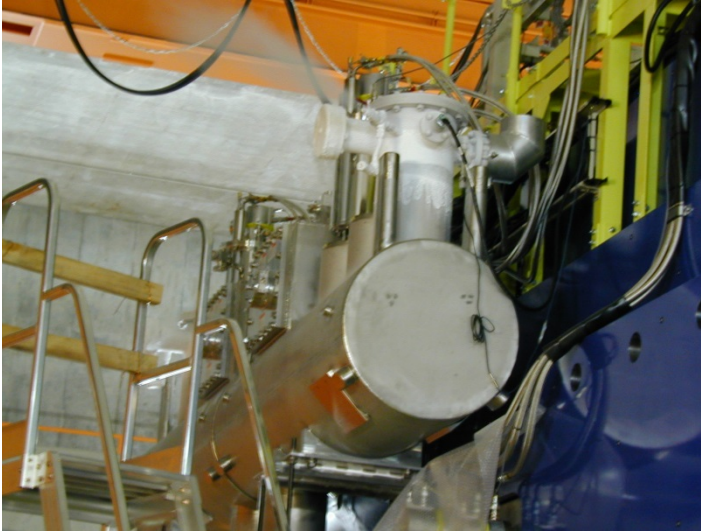
Vacuum chamber



After day-one experiments
(9/19/2012)

Excitation test

May 2011, excitation test was performed.



A training quench happened in the lower coil at 561 A (3.07 T), which corresponds to 99.6% of the maximum operation current, 563 A (3.08 T).

During subsequent excitation testing after refilling of LHe, the current reached 563 A without quenching and the test was continued up to 573 A (3.10 T) successfully.

Magnetic Field

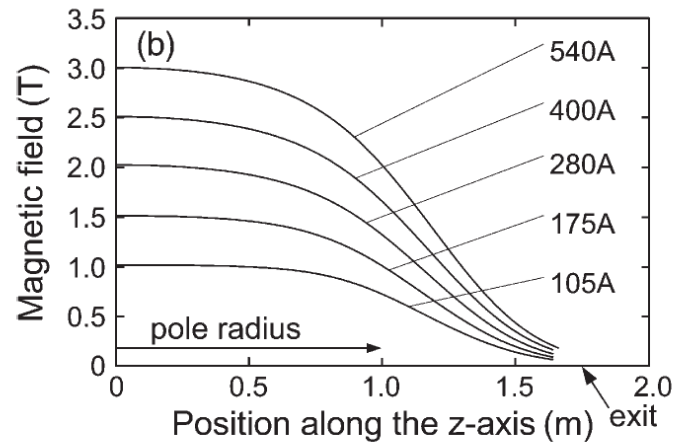
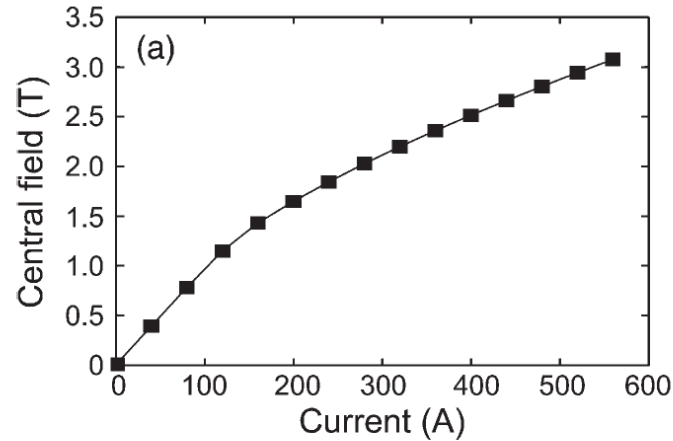


TABLE VI
RAMPING SPEED OF THE CURRENT

Current (A)	Magnetic Field (T)	Ramp Speed (A/s)
0 – 100	0 – 0.97	0.04
100 – 120	0.97 – 1.14	0.05
120 – 140	1.14 – 1.29	0.06
140 – 160	1.29 – 1.42	0.07
160 – 180	1.42 – 1.54	0.08
180 – 563	1.54 – 3.08	0.09

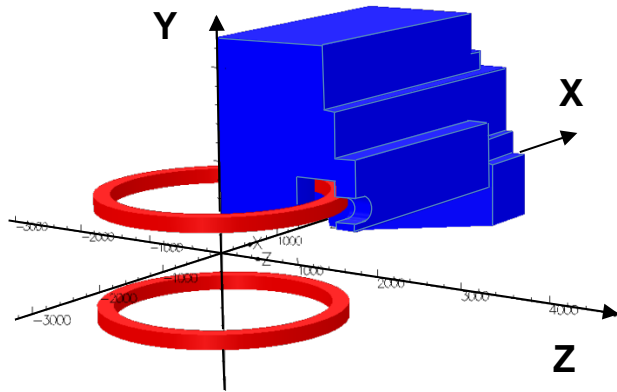
They are determined in response to changes in the inductance of the coil so as to keep the induced voltage below 20 V, which is the maximum voltage of the power supply.

Fig. 14. (a) Measured excitation curve of the SAMURAI dipole magnet. (b) Measured magnetic field distributions along the z -axis. The z position labeled as “exit” corresponds to the edge of the iron yoke which is located at $z = 1.75$ m.

Magnetic Field

The value of the **central field** is compared between measurements and calculations (TOSCA).

model 1



$$\frac{B_{meas} - B_{calc}}{B_{meas}}$$

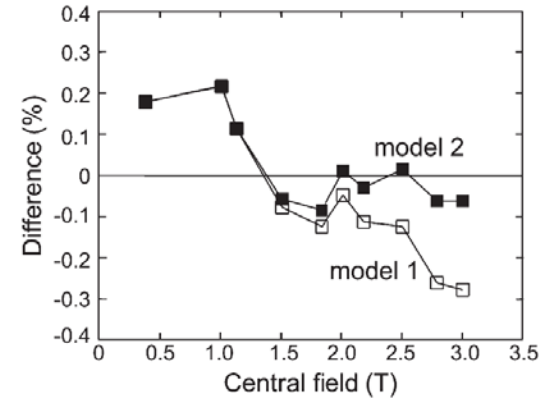
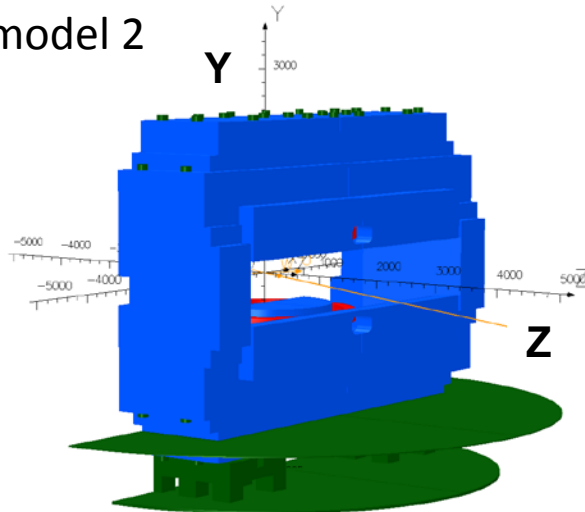
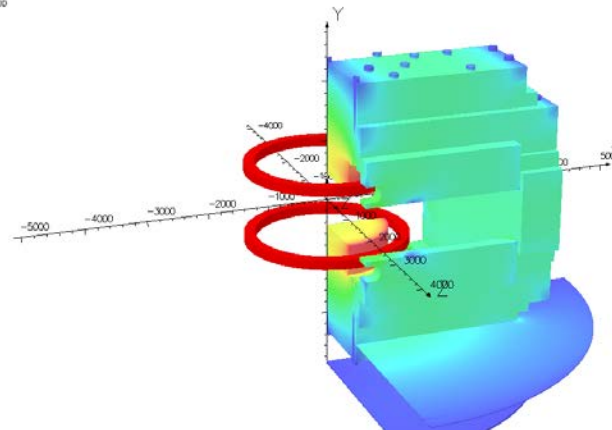
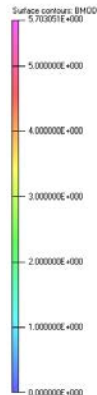


Fig. 15. Difference of the calculated central field from the measured value shown as a function of the central field. The open squares indicate the results with model 1 (TOSCA calculation with the iron yoke only) and the closed squares those with model 2 (TOSCA calculation with the iron yoke, the rotatable base, and the stud bolts).

model 2

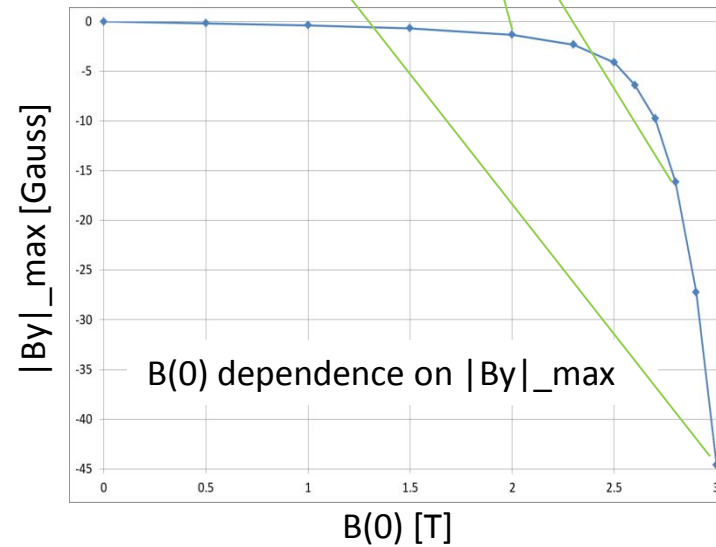
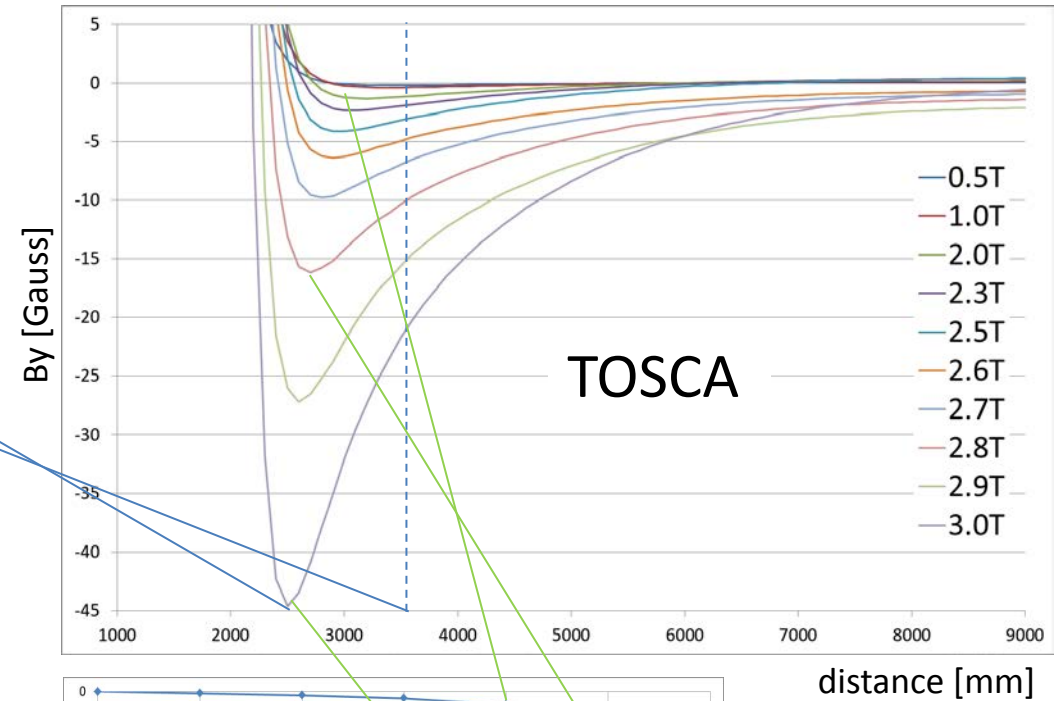
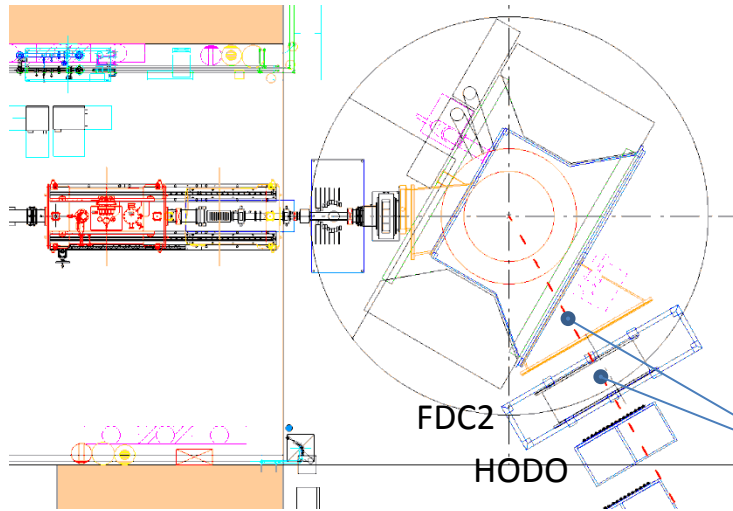


12/9/2013 17:29:17

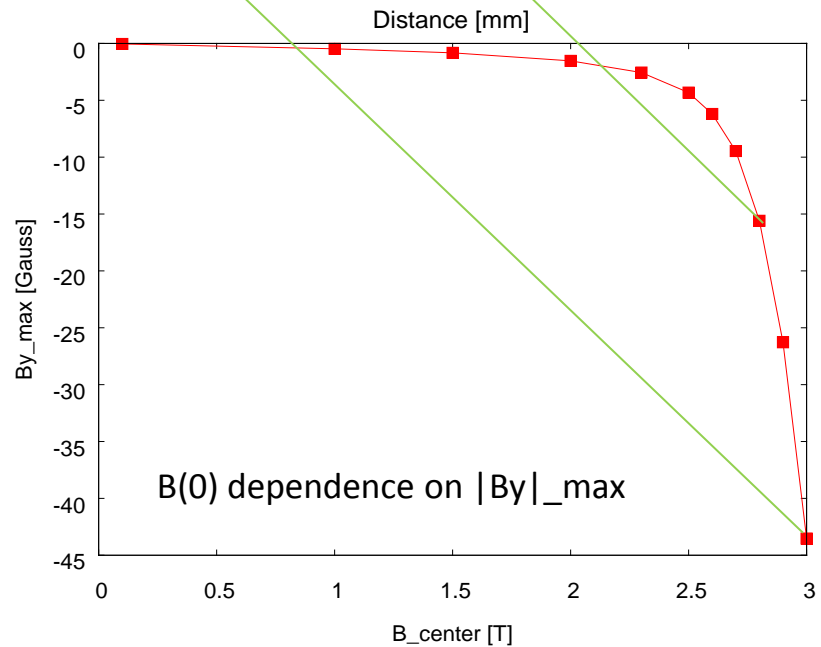
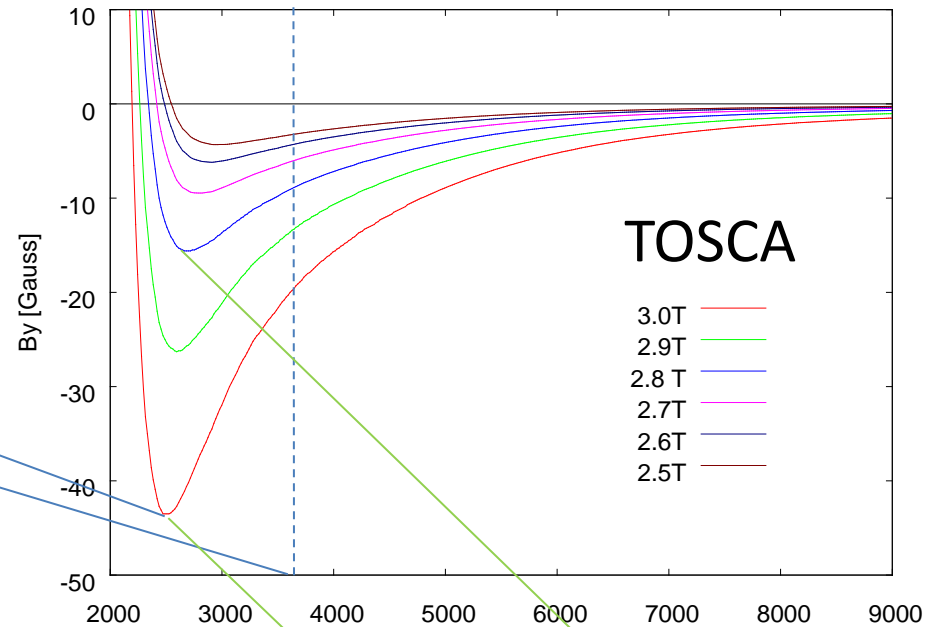
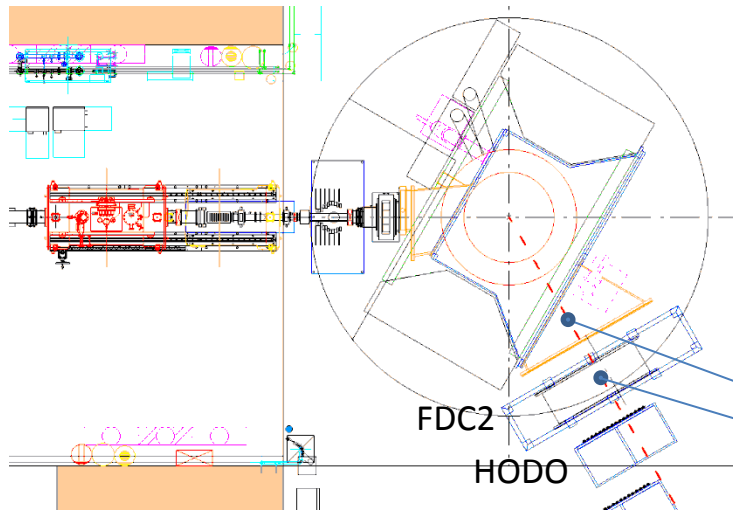


UNITS	
Length	mm
Mass Flux Density	T
Magnetic Field	A/m
Mass Scalar Pot	A
Current Density	A/mm²
Power	W
Force	N
MODEL DATA	
131058-01_shape-d-0307.ep3	
Magnetostatic (TOSCA)	
Nonlinear materials	
Simulation No 1 of 1	
20151212 elements	
4431170 nodes	
2 conductors	
Radially interpolated fields	
Activated in global coordinates	
Reflection in XZ plane (Z field=0)	
Reflection in YZ plane (X field=0)	
Field Point Local Coordinates	
Local = Global	

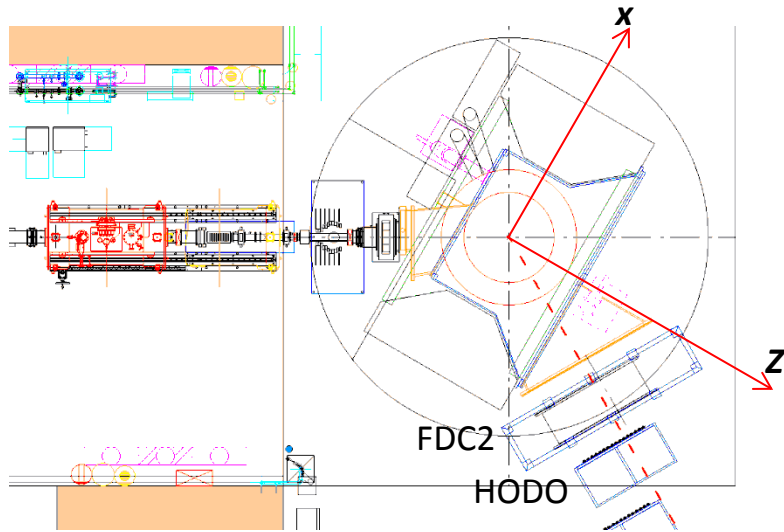
Fringe Field



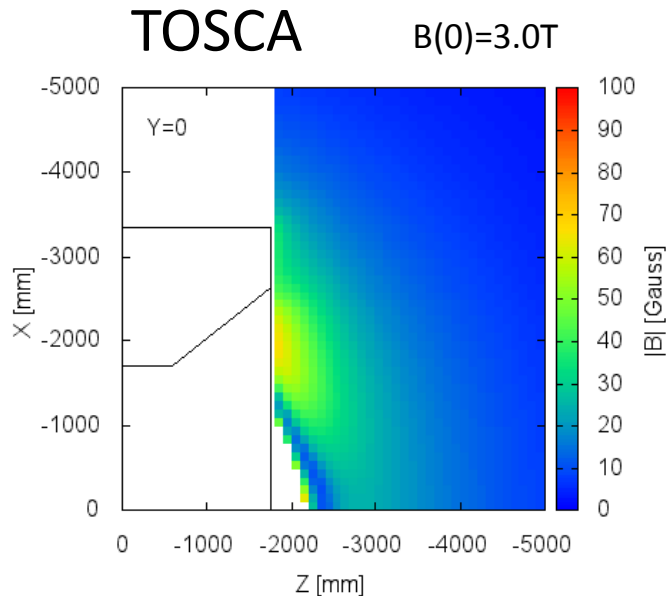
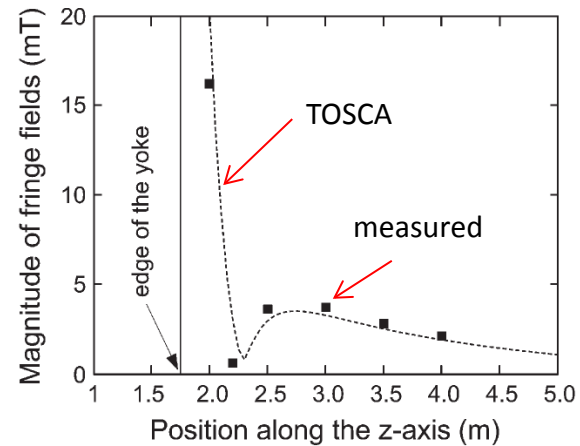
Fringe Field



Fringe Field



$$B_{y(\text{center})} = 3.08\text{T}$$



18. Magnitude of fringe fields on the z -axis at the central field of 3.0 T. The closed squares indicate the measured values, while the dotted line corresponds to the TOSCA calculation. Model 2 is used in the TOSCA calculation.

The calculated values and measured values agree well with each other. The fringe fields are smaller than 50 Gauss in the region more than 0.5 m distant from the edge of iron yoke, satisfying our experimental requirements.

Summary

- ✓ Large-acceptance spectrometer “SAMURAI” has been constructed at RIKEN RIBF.
- ✓ The construction of the H-type superconducting dipole magnet was finished in June 2011.
- ✓ Large pole gap (800mm effectively)
- ✓ Wide horizontal opening (3400mm)
- ✓ Central field = 3.08T, BL=7.05Tm, I=563A, E=27.4MJ
- ✓ The coils are cooled by liquid He.
- ✓ Twelve cryocoolers are used to keep the temperature.
- ✓ The first reaction experiments using SAMURAI were carried out in May 2012, and the second experiments were carried out in April 2013.