

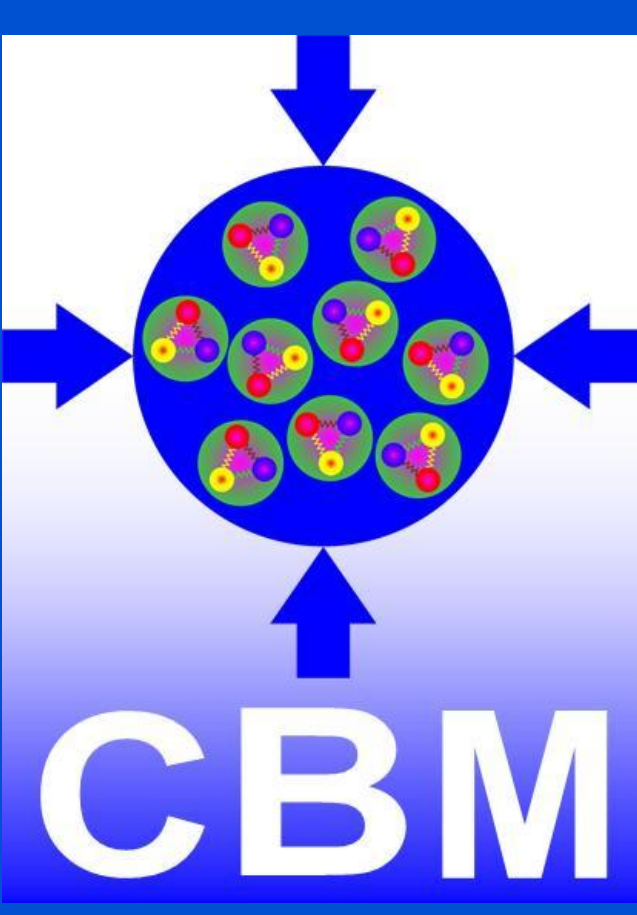
# Ladder Assembly for the Silicon Tracking System of the CBM Experiment at FAIR

S.Mehta<sup>1,2,\*</sup>, U.Frankenfeld<sup>2</sup>, O.Vasylyev<sup>2</sup>, and H.R.Schmidt<sup>1,2</sup>

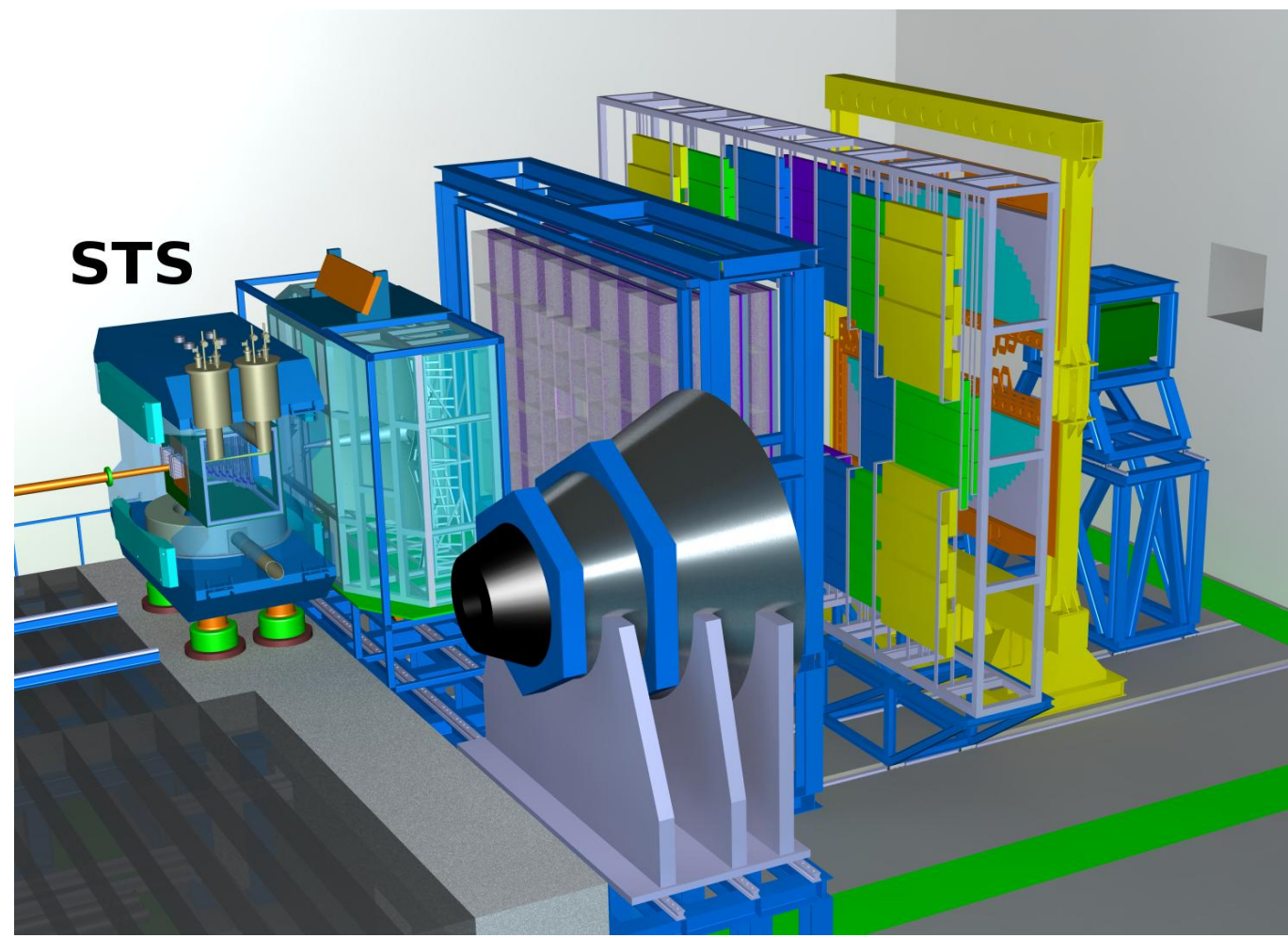
<sup>1</sup> Physikalisches Institut- Eberhard Karls Universität Tübingen, Auf der Morgenstelle, Tübingen, Germany

<sup>2</sup> GSI Helmholtzzentrum für Schwerionenforschung GmbH, Planckstrasse 1, Darmstadt, Germany

\* email: s.mehta@gsi.de

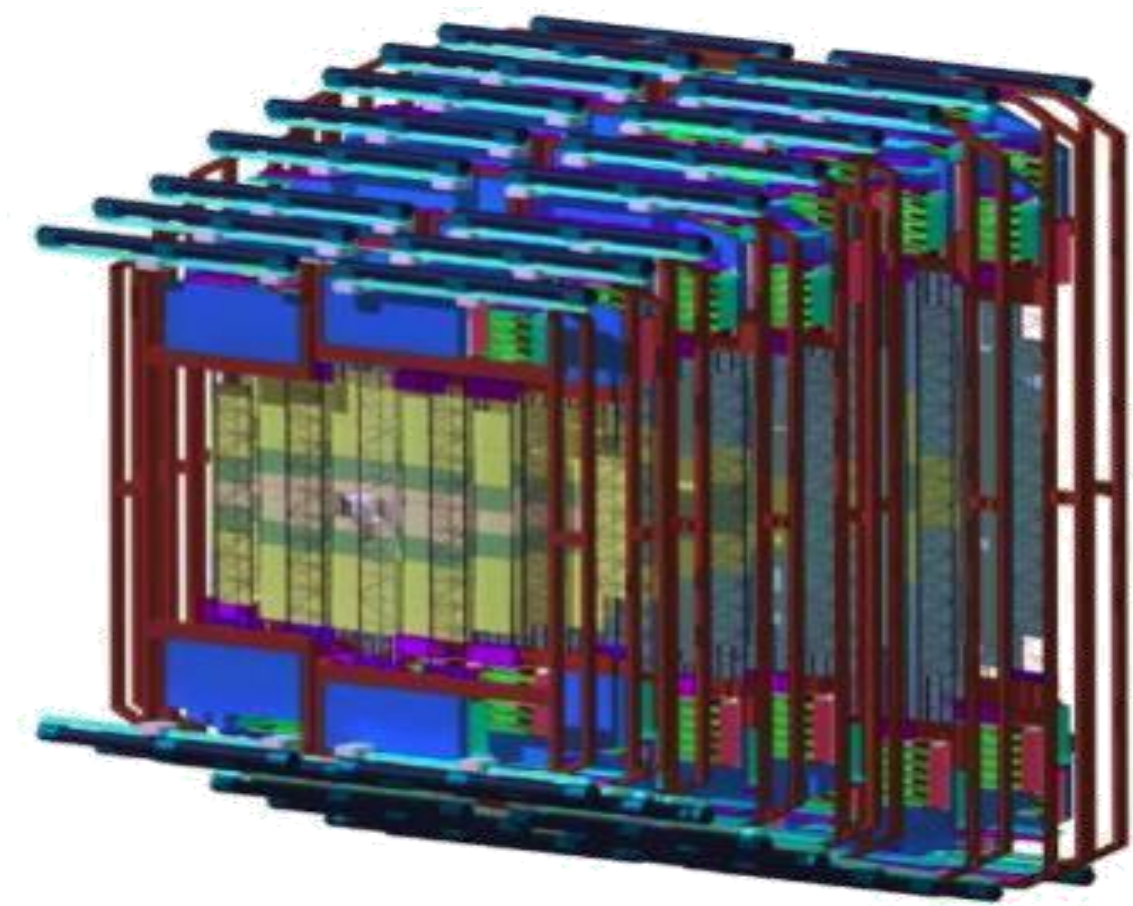


## The STS for the CBM experiment at FAIR



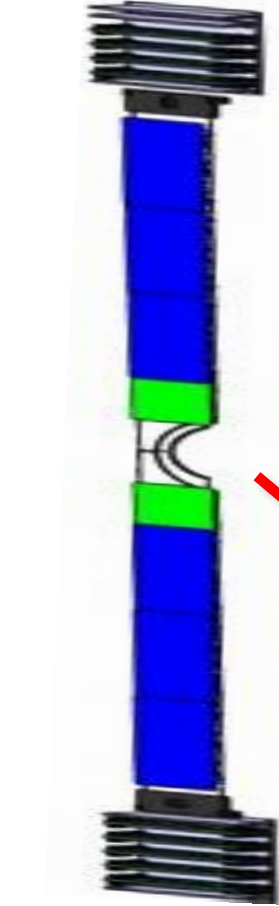
- STS is the core detector of CBM
- Located inside the dipole magnet
- Track reconstruction, momentum measurement

STS with 8 tracking stations

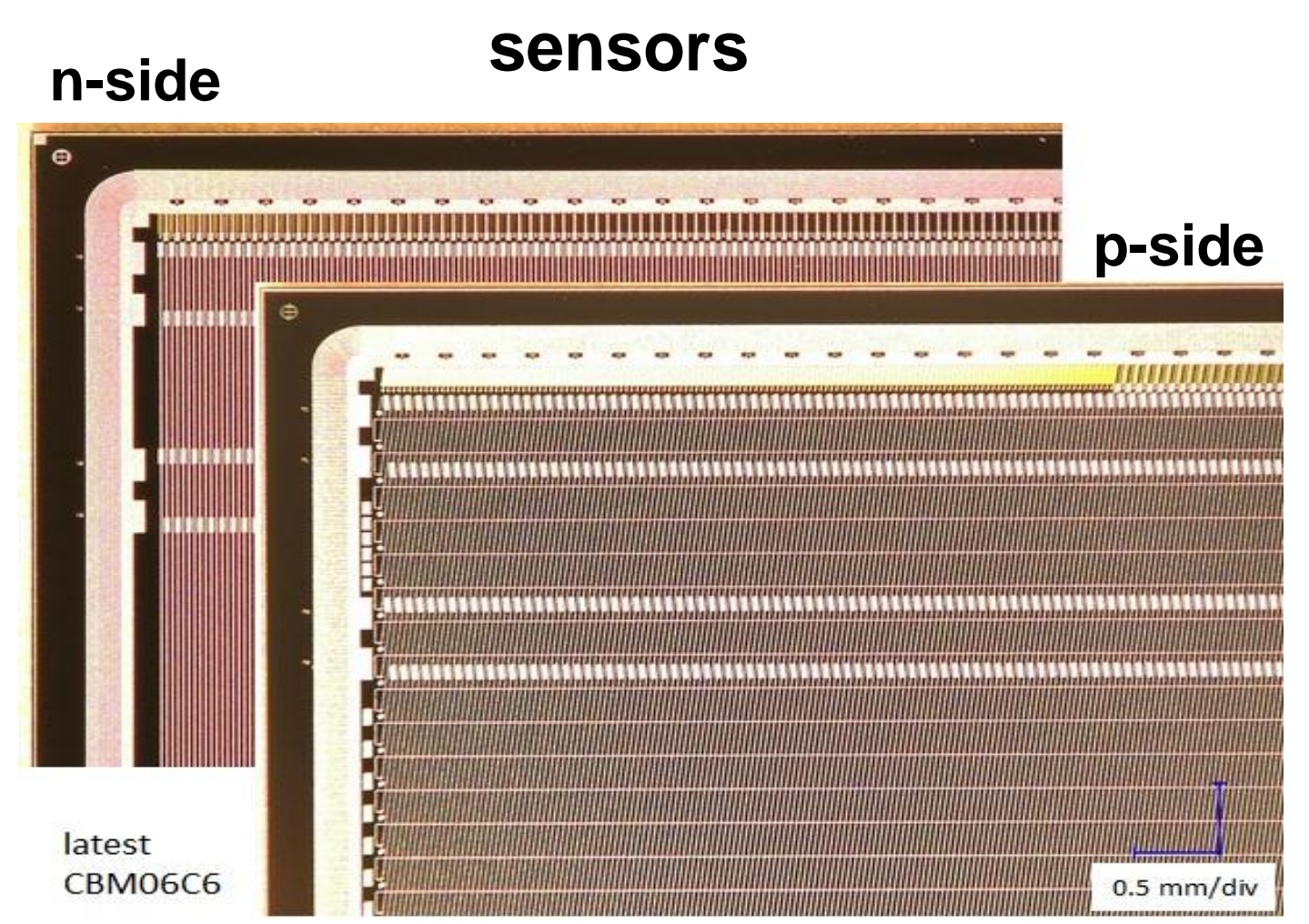
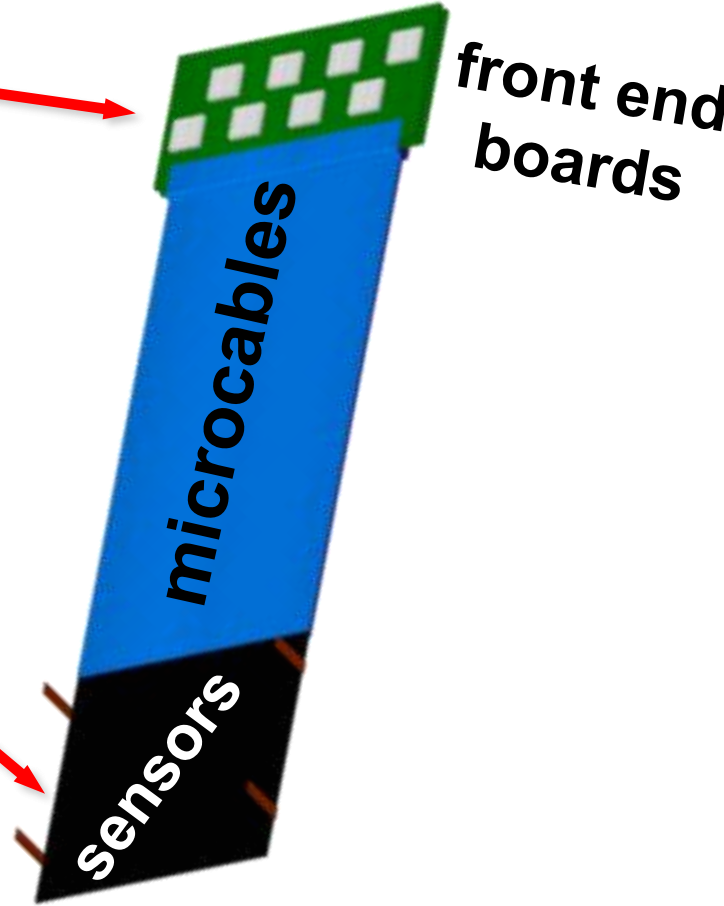


- Consists of 8 tracking stations
- 896 detector modules mounted on 106 Carbon Fiber (CF) ladders
- 8-10 modules on each CF ladder
- Requirement: Precision of sensors in 3D with in the order of 100  $\mu\text{m}$

106 ladders



896 modules

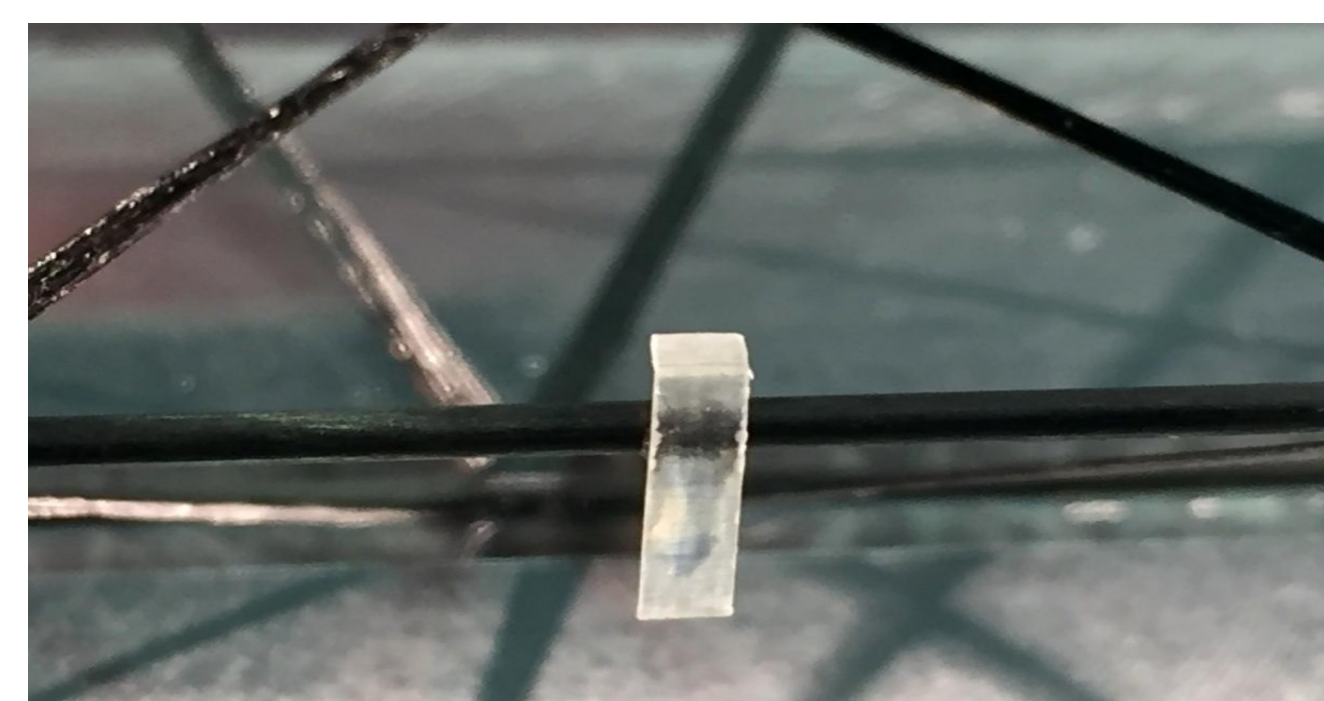


- Double-sided silicon micro-strip sensors
- 1024 strips on each side
- Stereo angle between front /back strips 7.5°
- 4 sensors size 6.2 x 2.2, 4,2, 6,2, 12.4 cm<sup>2</sup>

## STS ladder components



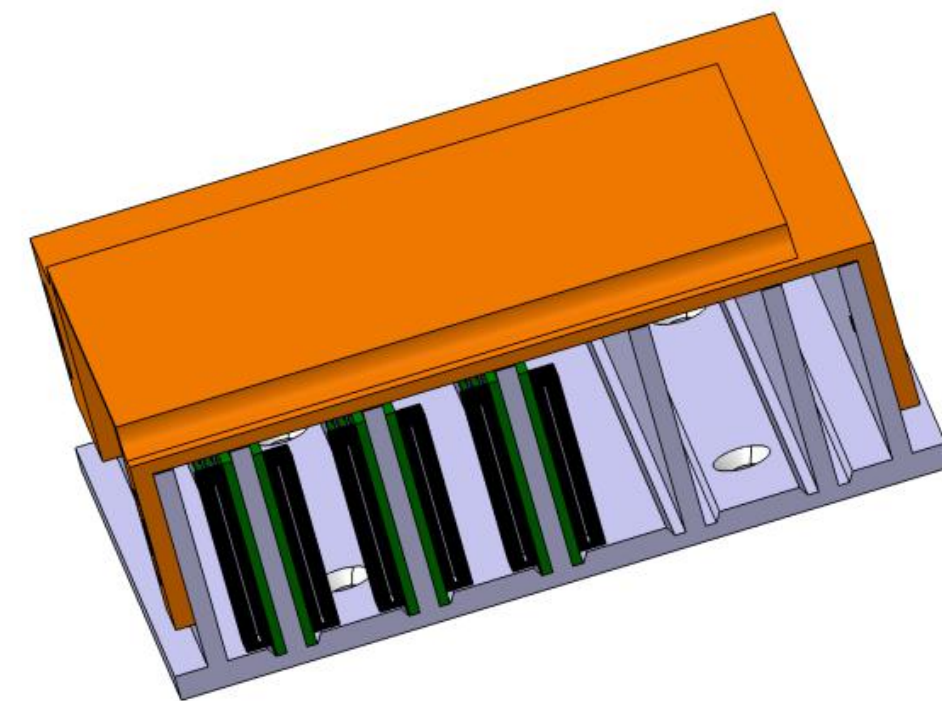
Carbon Fiber support structures



Sensor holding structures, L-legs

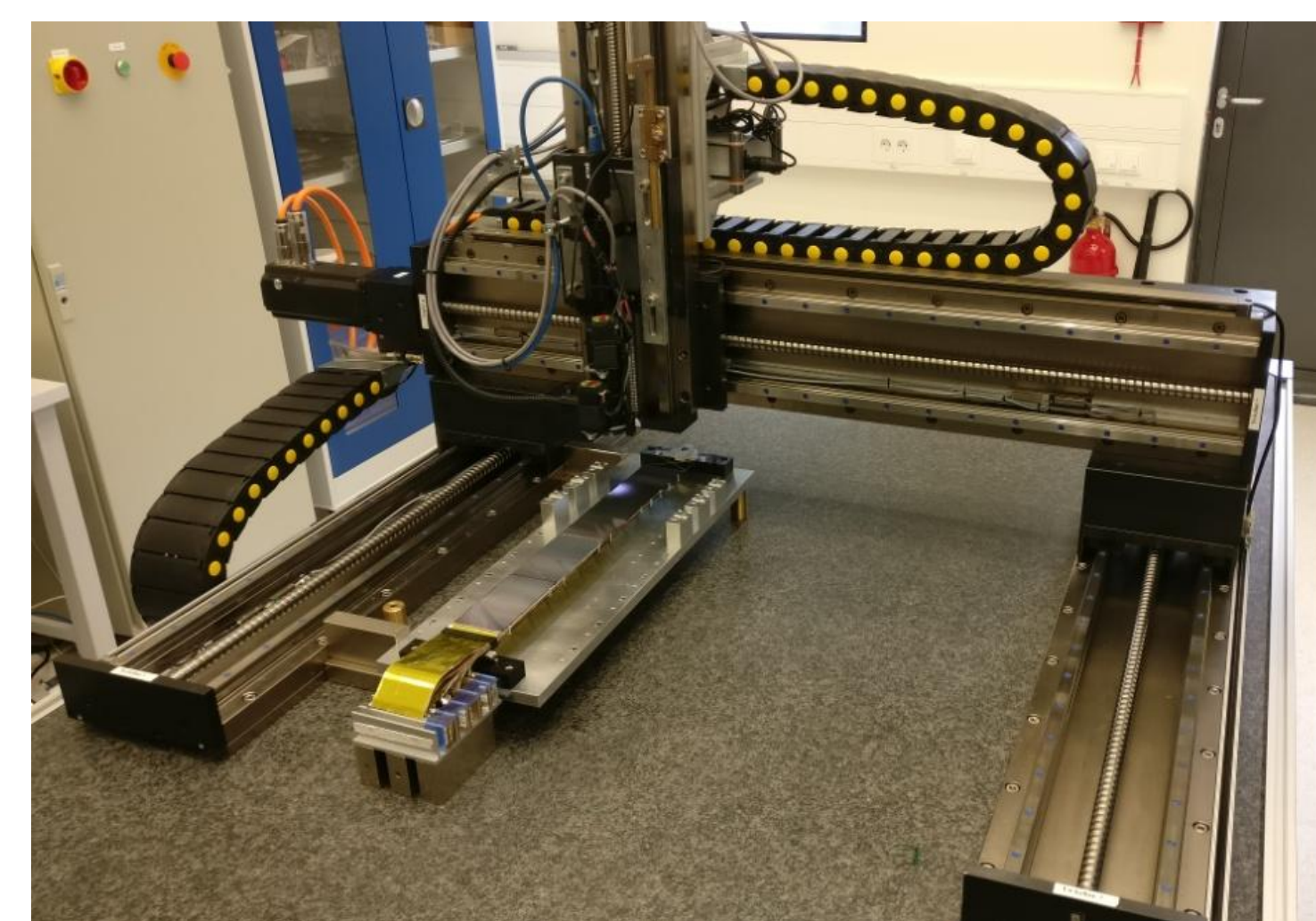


Sensor module: sensors, micro cables, FEBS



FEBS (Front End Boards)

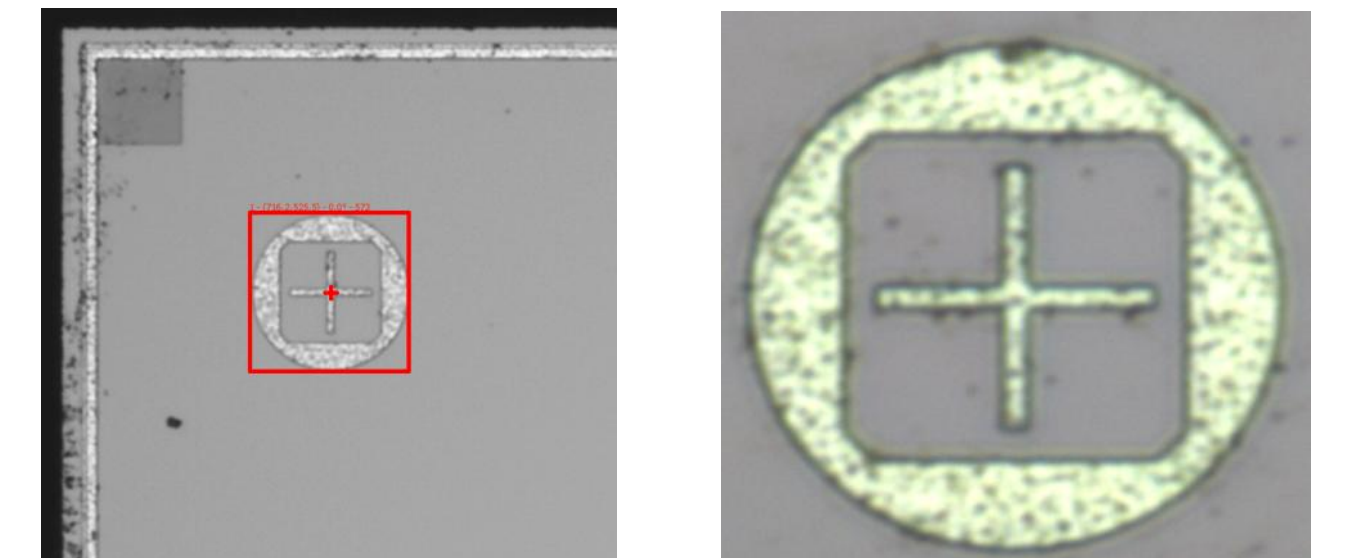
## Instrument for optical survey



- Three-axis measurement instrument (1100 x 800 x 170 mm)
- Equipped with camera
- Non-rectangularity of X & Y axis is 17  $\mu\text{m}$
- Overall precision of table taking long term reproducibility of measurement is  $\pm 10 \mu\text{m}$ .

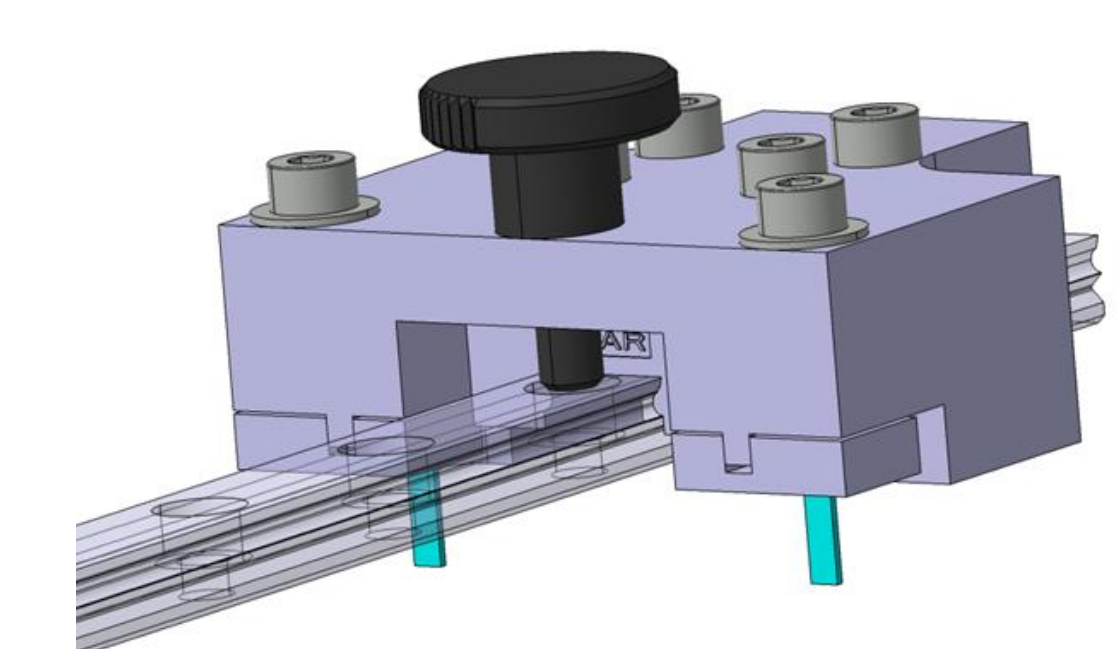
Reference paper: <http://arxiv.org/abs/1812.00917>

## Measurement Technique

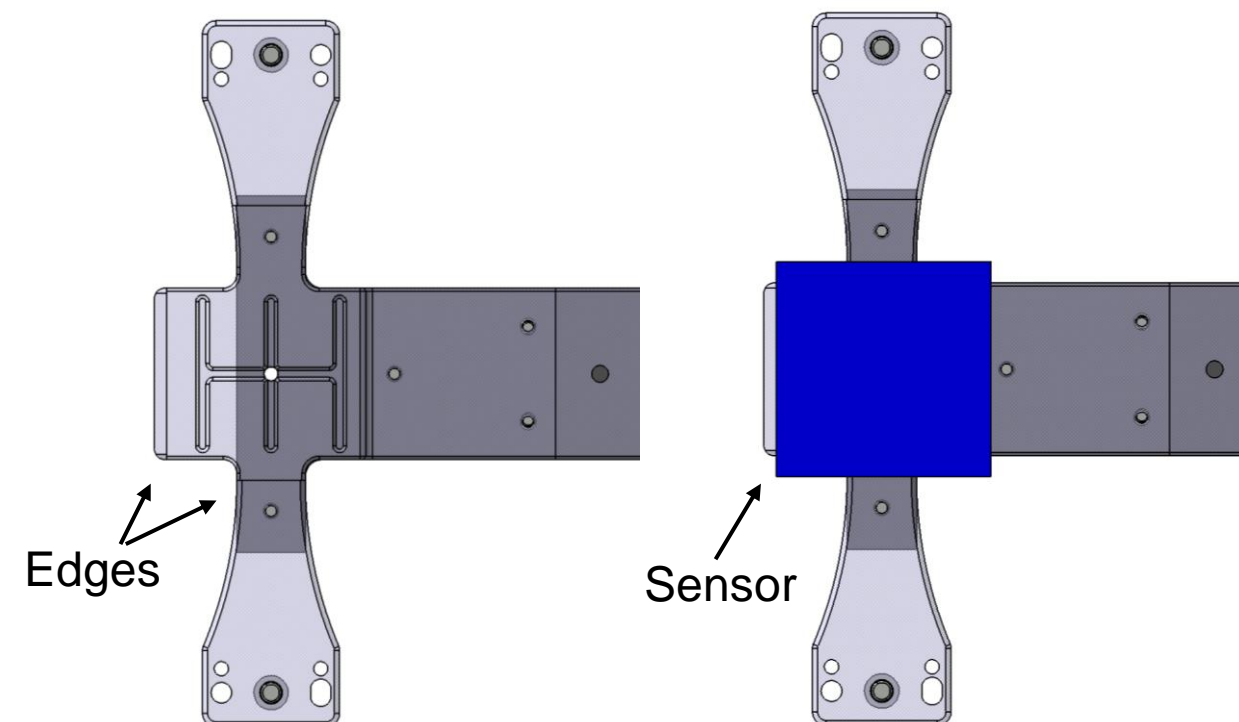


- LABVIEW software from NI is used for the optical survey of the table.
- 3D-position of sensors is determined from alignment marks on sensors surface.
- Measurement of height (in Z direction) is based on auto focusing.
- Measurement of XY surface is based on pattern recognition based on NI vision package.

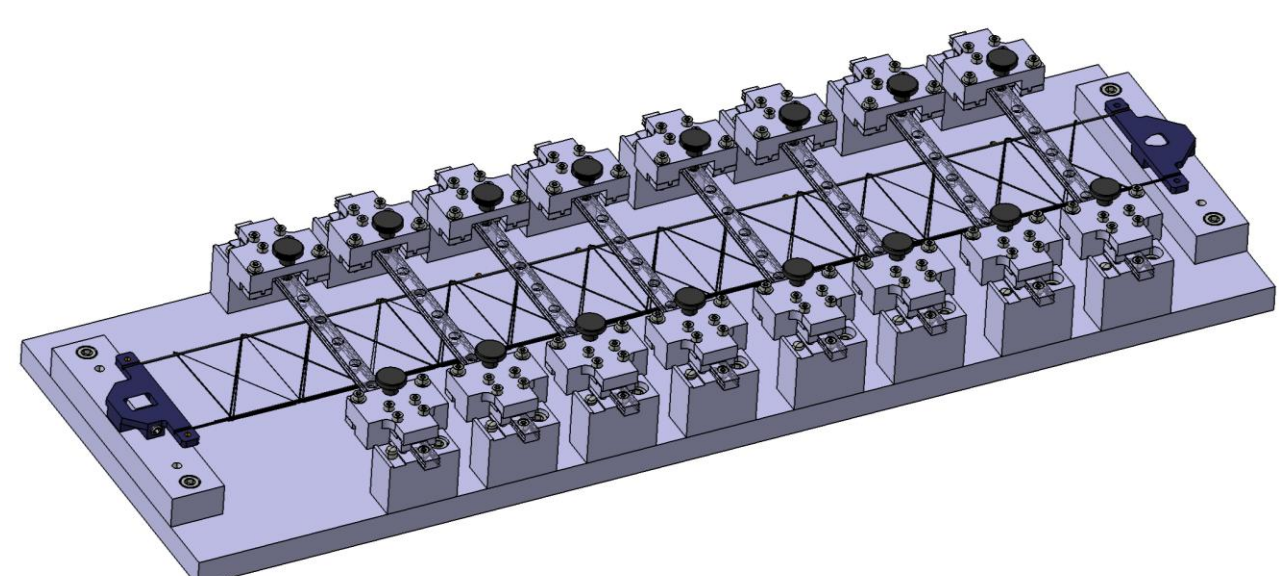
## Assembly technique



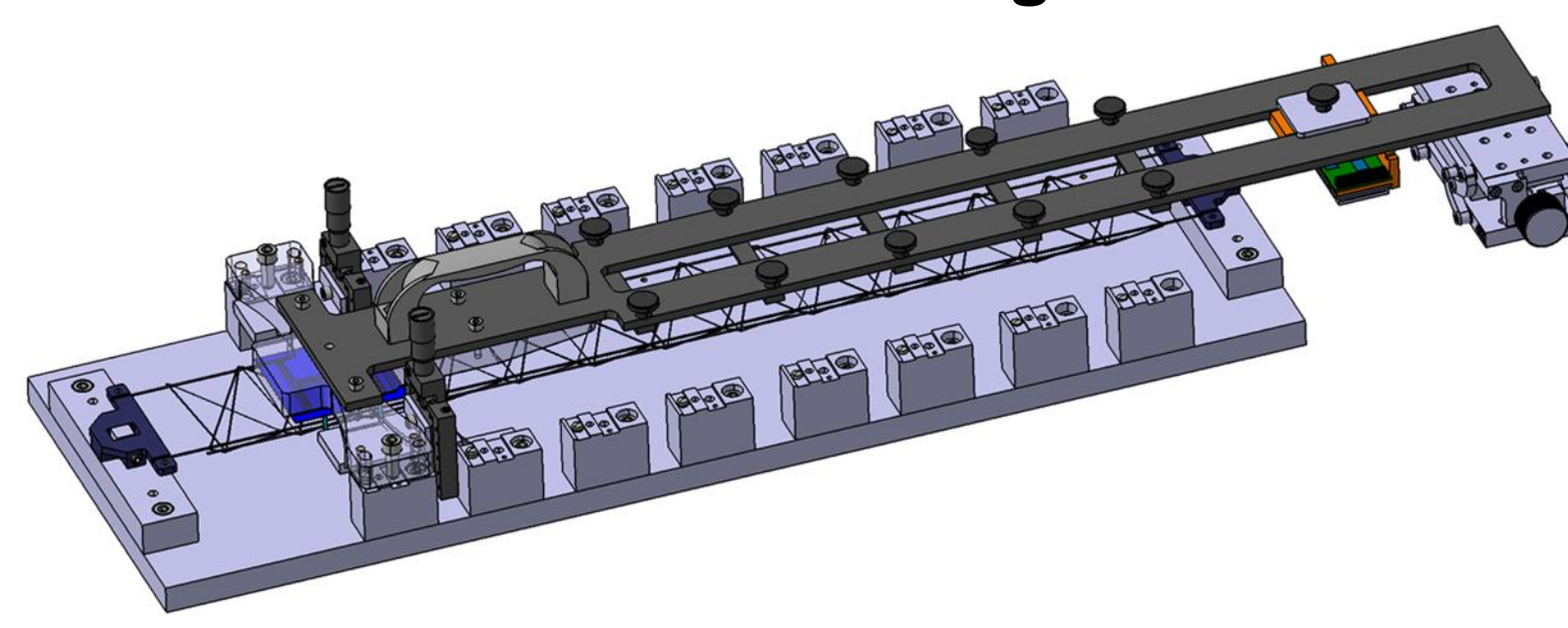
L-leg mounting tool holding I-legs (two I-legs goes in one fixture)



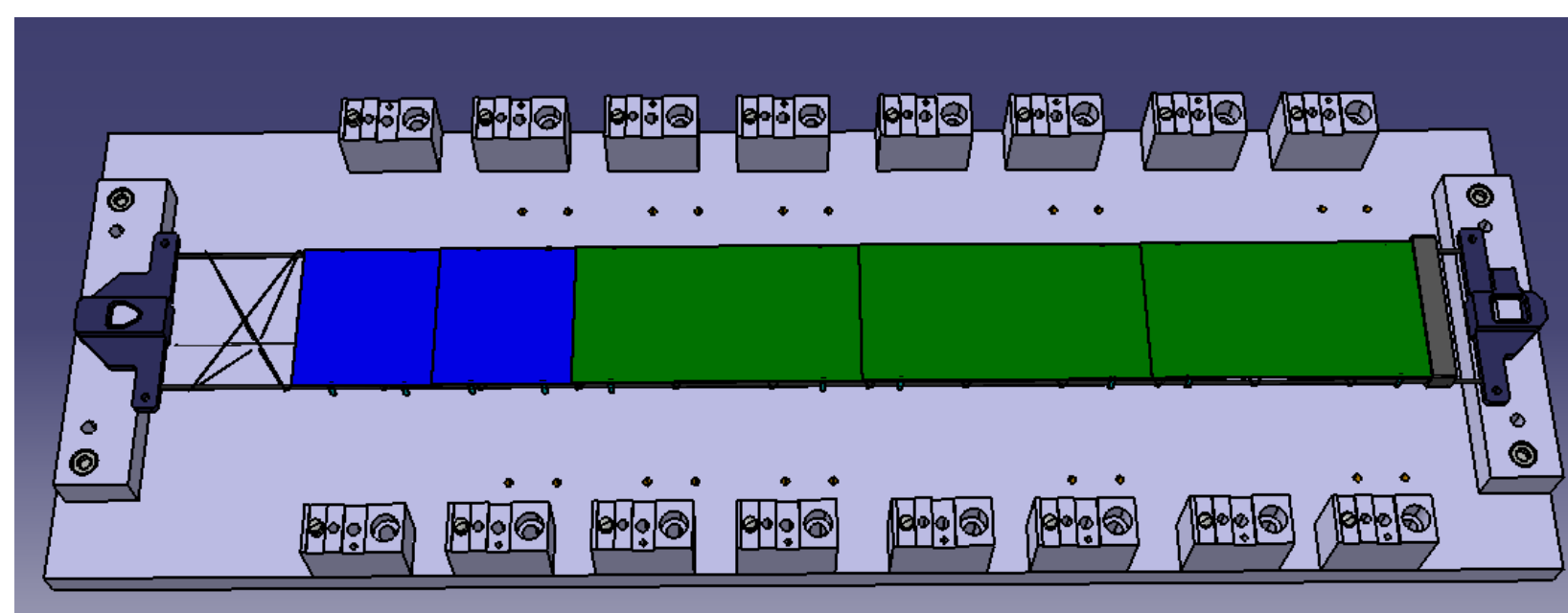
Sensor holding tool



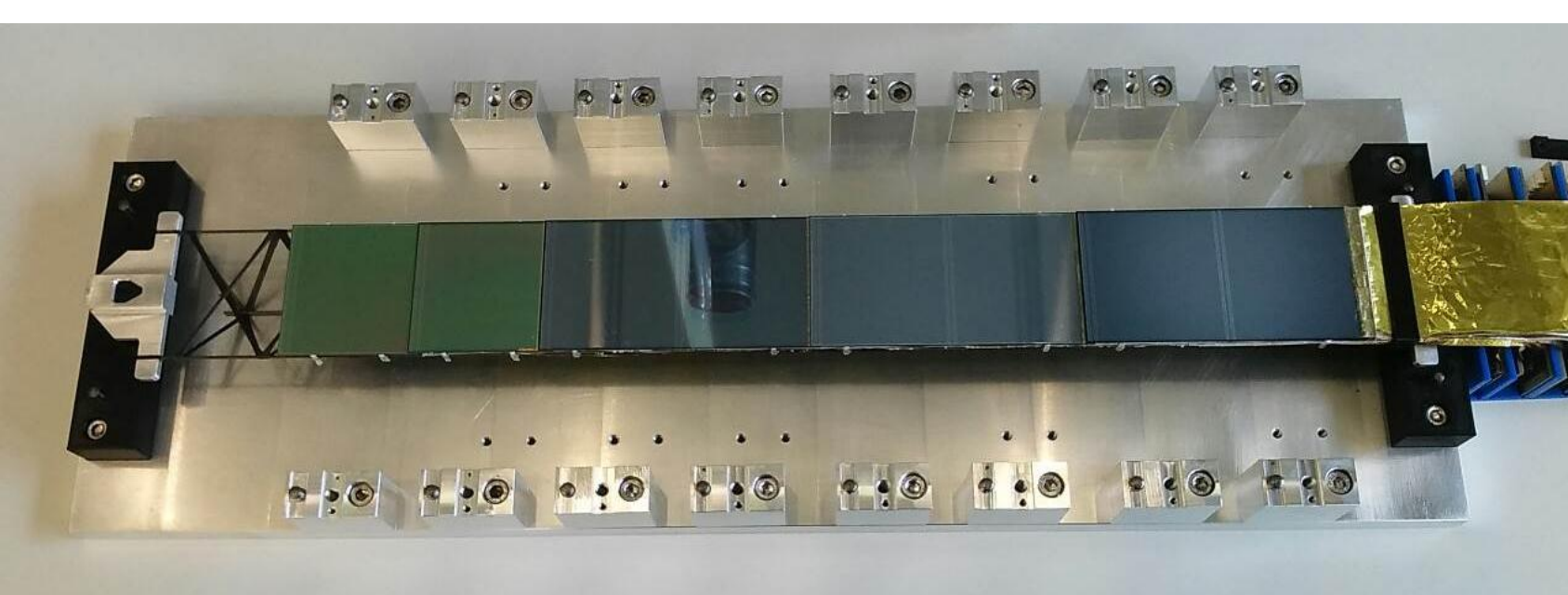
Tool to assemble 5 sensors on a ladder



Assembly of first module using module holder

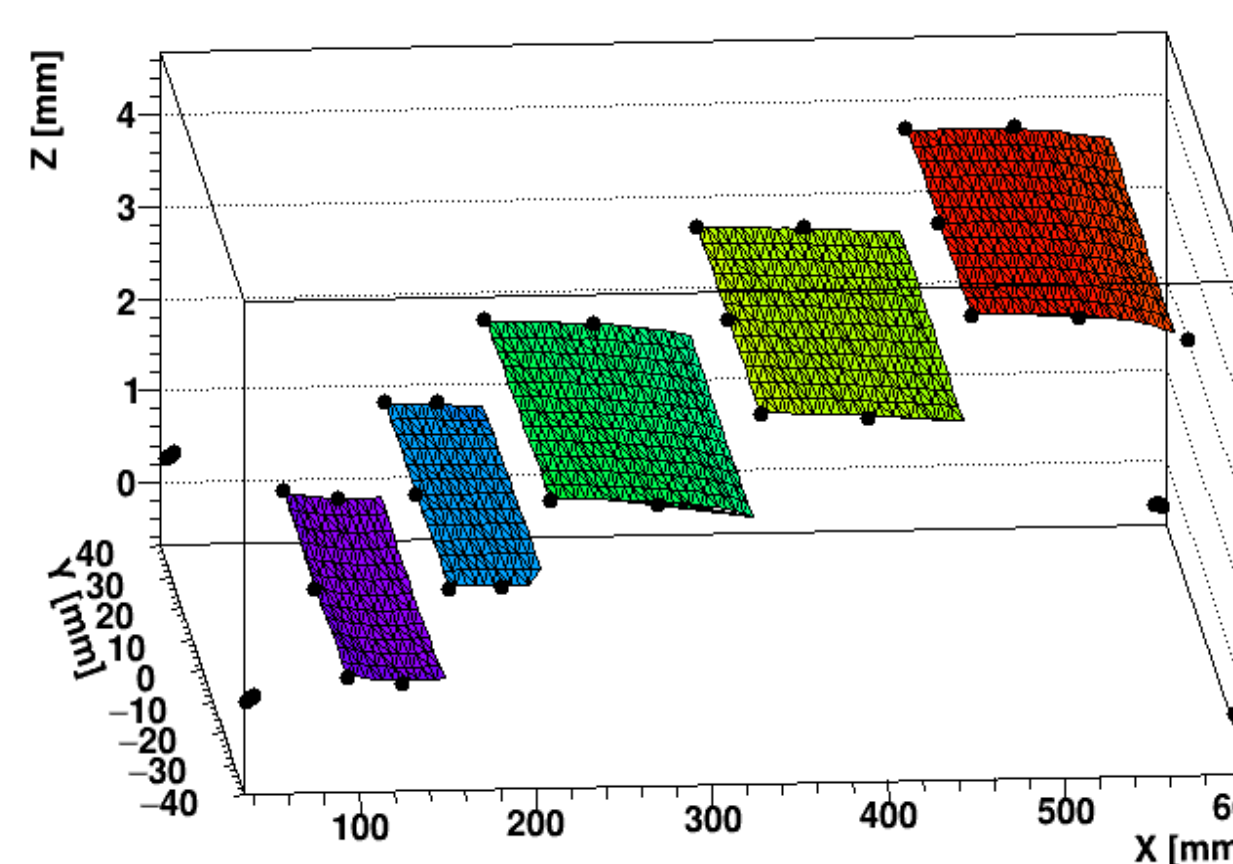


- A tool has been designed to mount the modules on the CF ladders.
- Sensors are positioned in respect to the supporting fixtures on the sensor holder.
- Sensor holder is positioned to the tool with dowel pins.

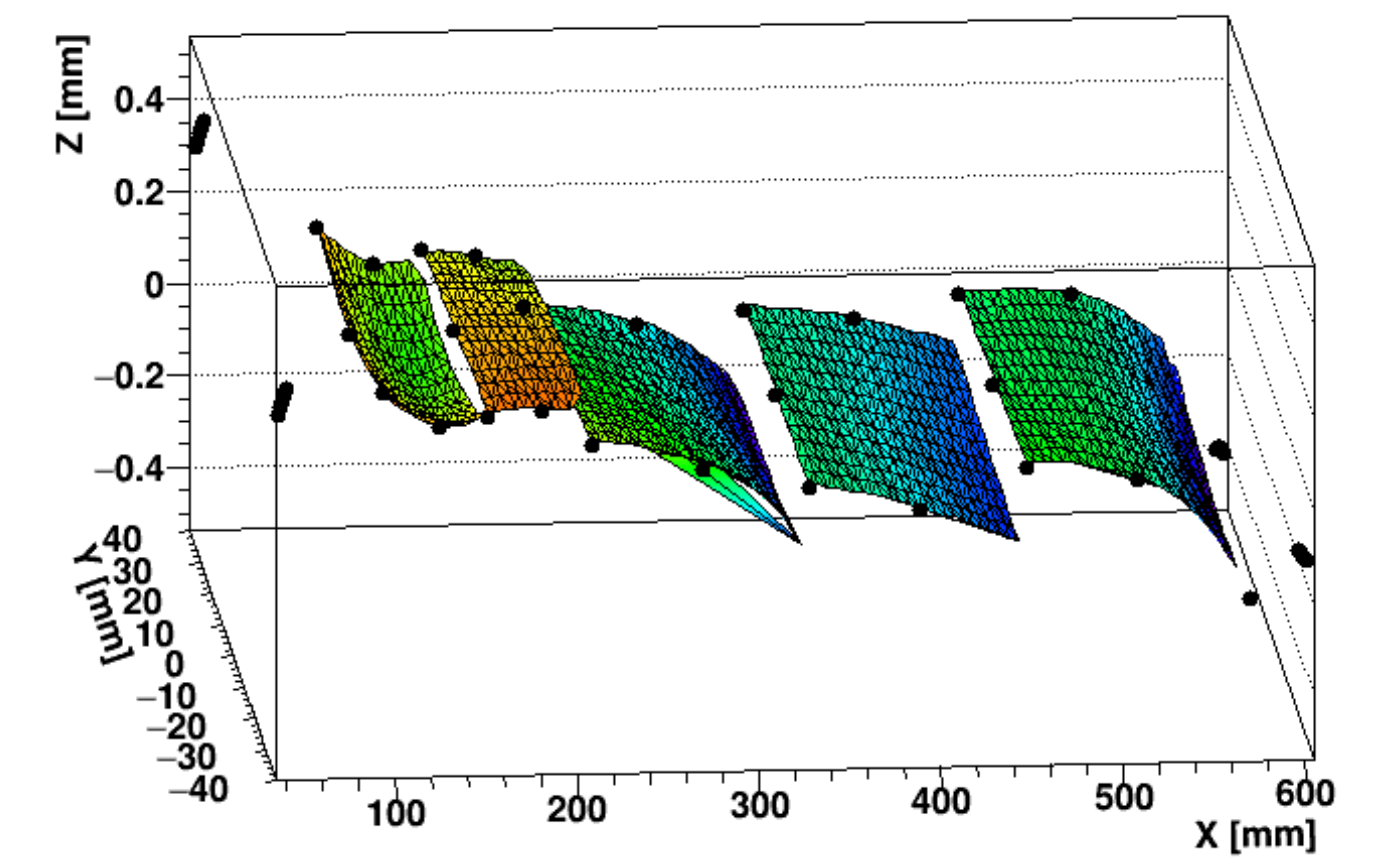


- Ensures the feasibility to mount the modules on the tool.
- Assembly of CF ladder with 5 non-functional modules mounted on it.

## Positioning accuracy of sensors on ladder



Measurement of the sensor surface space points. The black dots refer to the alignment marks on the sensor surface.



Nominal module Z position was shifted to zero for all the sensors  
ZMax-Min: Surface 417  $\mu\text{m}$   
Marks 483  $\mu\text{m}$

## Conclusion & Outlook

- A setup and procedure is developed to determine the position of objects in 3D with good precision.
- Pattern recognition technique based on NI vision package helps to make an automatic scan of the sensors.
- Mounting tools and jigs can be improved for the better precision.
- Measured sensor position on ladder will be further used as an input for the track based alignment.
- Based on the same concept of ladder assembly, a functional ladder is assembled for the mini-STS which is now under test.

