

# Status of CA Track Finder

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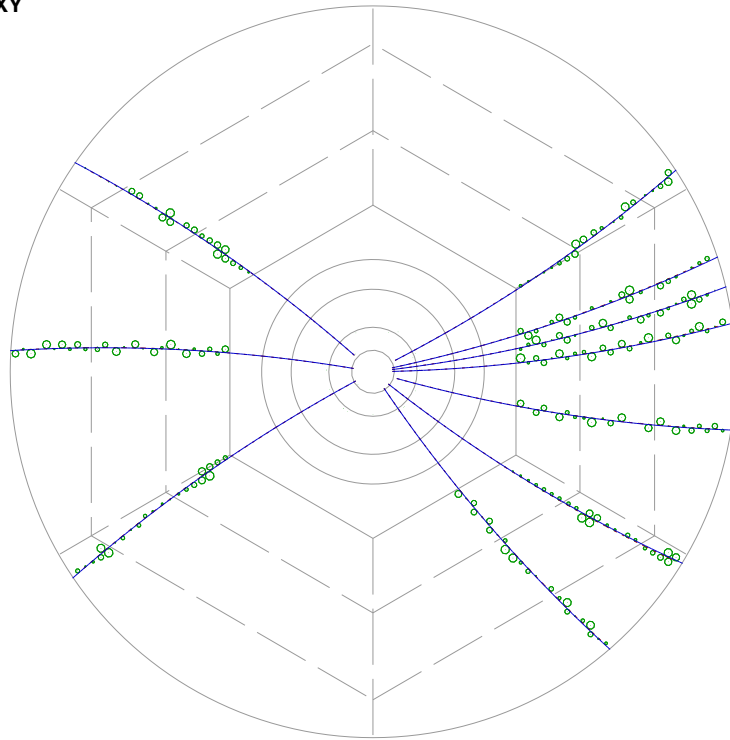
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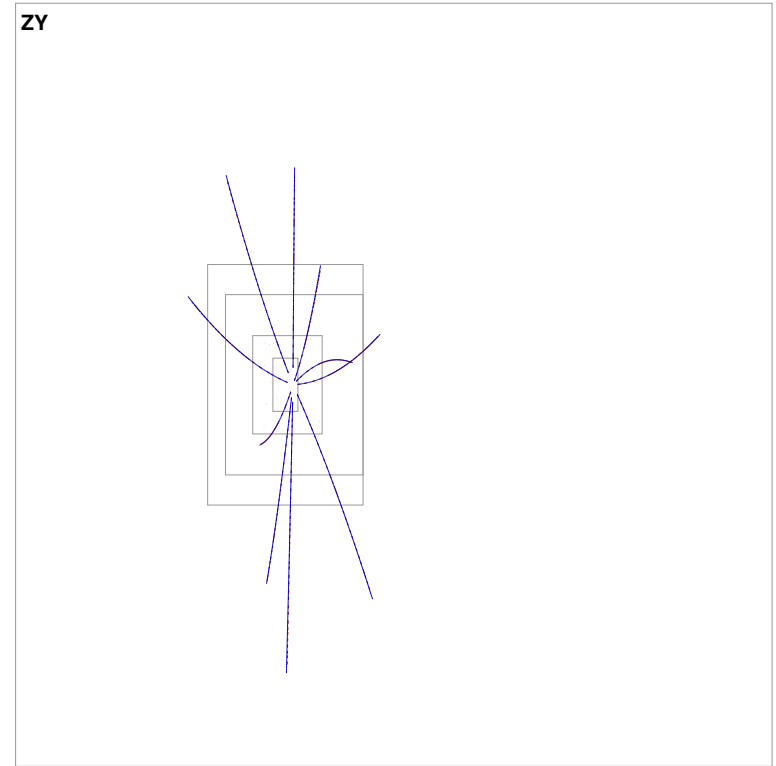
# CA Track Finder in STT and MVD

10 primary tracks with  $pt = 1 \text{ GeV}/c$

XY



ZY



	STT+MVD
Efficiency	100.0
Clone	4.8
Ghost	1.5
Tracks/event	10
Time, ms/event	1

S. Gorbunov, 10.12.2014

# Reconstruction Efficiency

Tobias found a problem in the CA TrackFinder:

Overall track finding efficiency was only 42% and no MVD hits

What was done:

1. Corrected normalisation (barrel only) of track efficiency calculation in standard QA (trackingQA)
2. Corrected track finder performance to account for tracks with > 1 hit/layer => QA efficiency = CA Track Finder Performance
3. Adjusted initialisation of the track finder to Panda data (detector geometry, errors on input hits, internal tracking cuts,...)

Reconstructable track selection	Eff. old 1+2	Eff. new 1+2+3
StandardTrackFunctor: > 3 Hits in MVD or > 5 Hits in (MVD+STT+GEM)	42.3	64.1
OnlyBarrelFunctor: > 3 Hits in barrel MVD and > 5 Hits in (barrel MVD + STT)	57.6	87.3
OnlySttFunctor: > 5 Hits in STT	59.0	88.1
OnlyBarrelFunctor && ( p > 0.05 )	61.3	92.3
OnlySttFunctor && ( p > 0.05 )	62.5	92.5
OnlyBarrelFunctor && ( pt > 0.05 )	62.0	92.7
OnlyBarrelFunctor && ( pt > 0.1 )	66.9	94.6
(> 5 Hits in (barrel MVD + STT)) && ( p >= 0.05)	62.4	92.7
Performance of CA tracker: (> 5 Hits in (barrel MVD + STT)) && ( p >= 0.05)	62.5	93.0
<i>Performance of CA tracker: (&gt; 5 rows of hits in (barrel MVD + STT)) &amp;&amp; ( p &gt;= 0.05)</i>	65.9	96.6
Performance of CA tracker: (> 5 rows of hits in (barrel MVD + STT)) && ( pt >= 0.05)	66.1	96.9

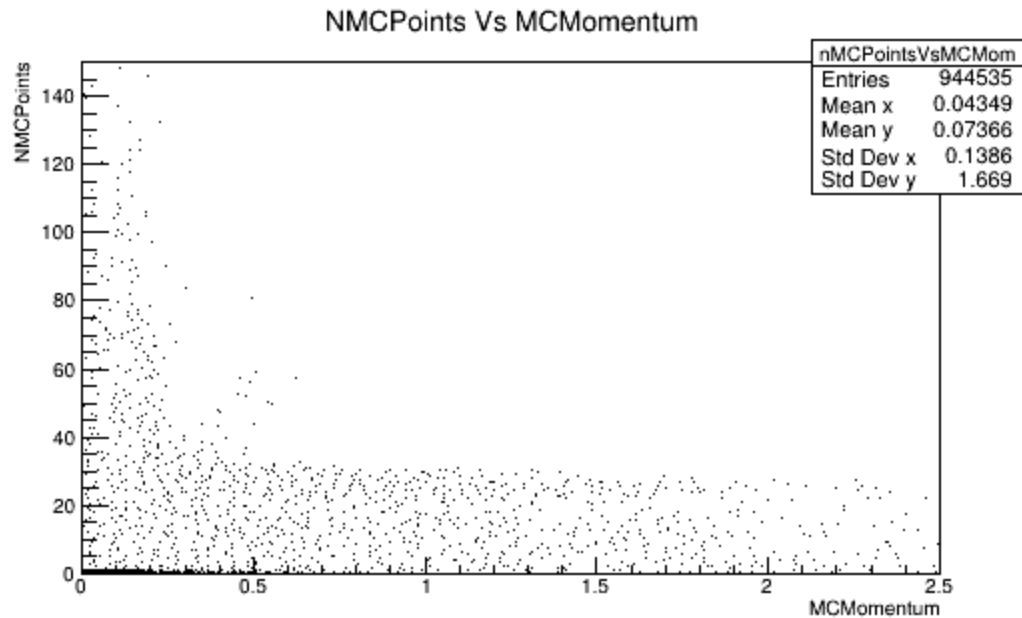
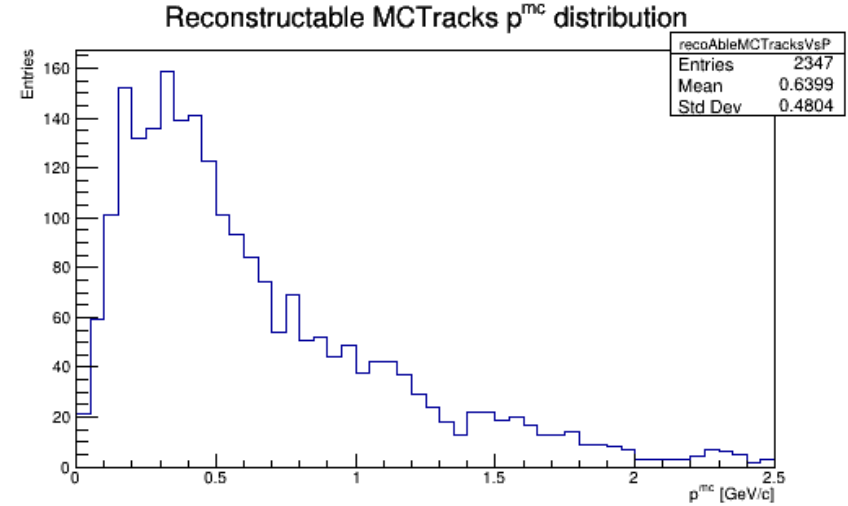
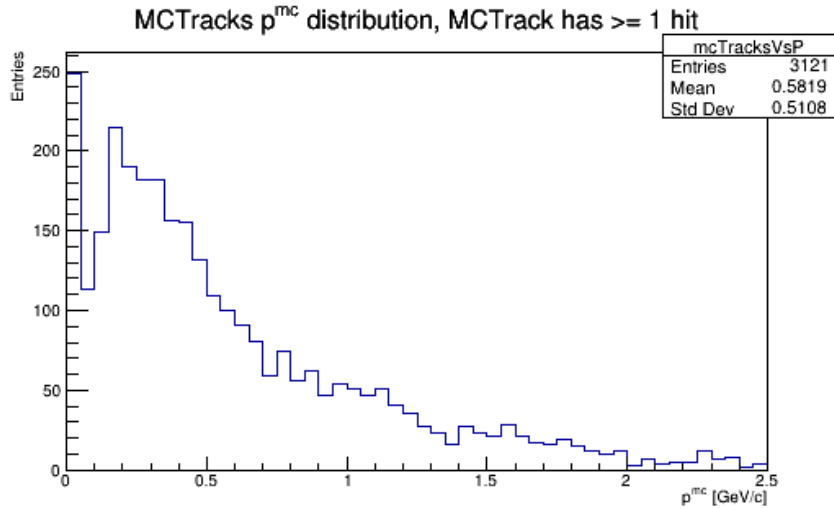
# Reconstruction Efficiency

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Efficiency, %	Eff. old	Eff. new
High-p primary	97.9	98.1
High-p secondary	91.1	93.3
High-p set	97.3	97.7
Low-p primary	63.8	97.7
Low-p secondary	42.1	93.0
Low-p set	57.0	96.2
<b>All set</b>	<b>65.9</b>	<b>96.6</b>

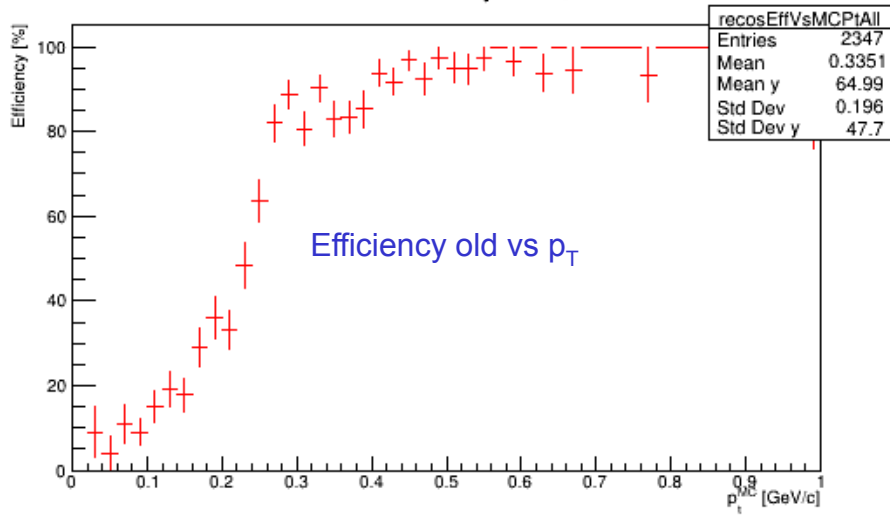
# Cut on Very Low-Momentum Tracks

A cut  $p > 0.05$  has been introduced in the CA performance to remove very low-momentum tracks

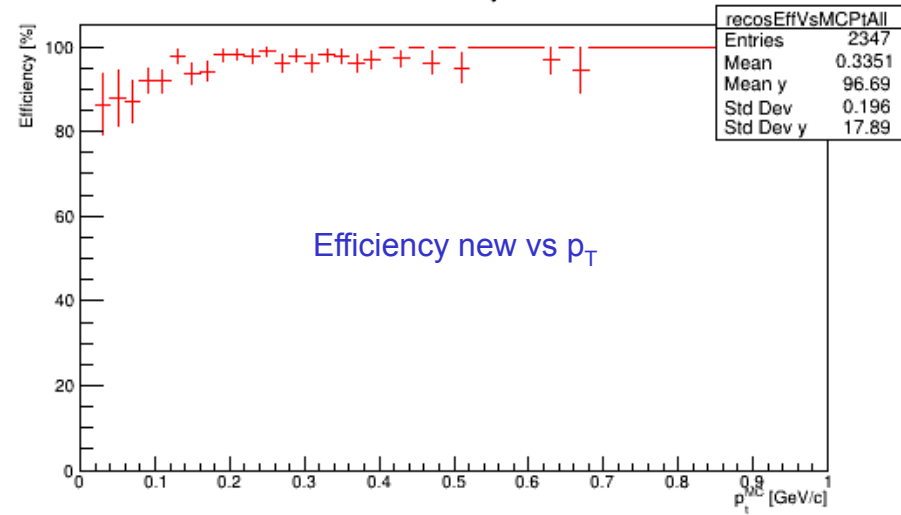


# All Set Efficiency vs $p_T$ and $p$

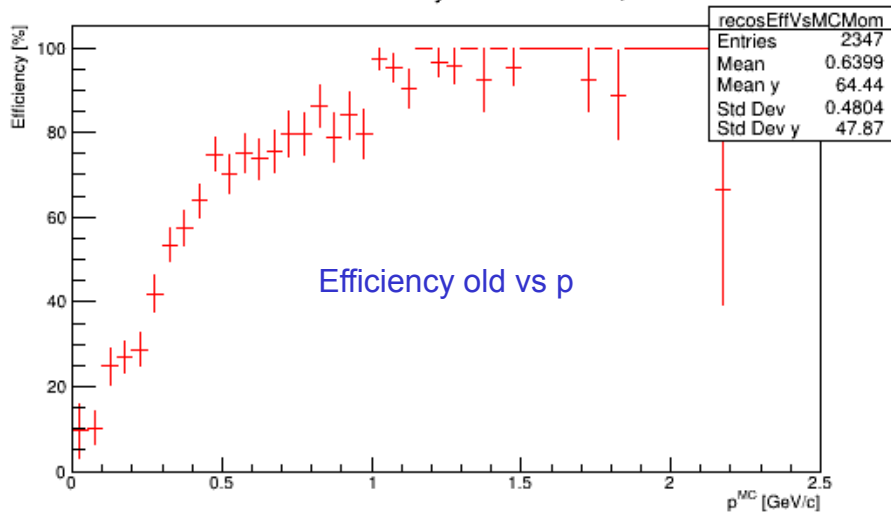
Reconstruction Efficiency vs  $p_T$ , All Tracks



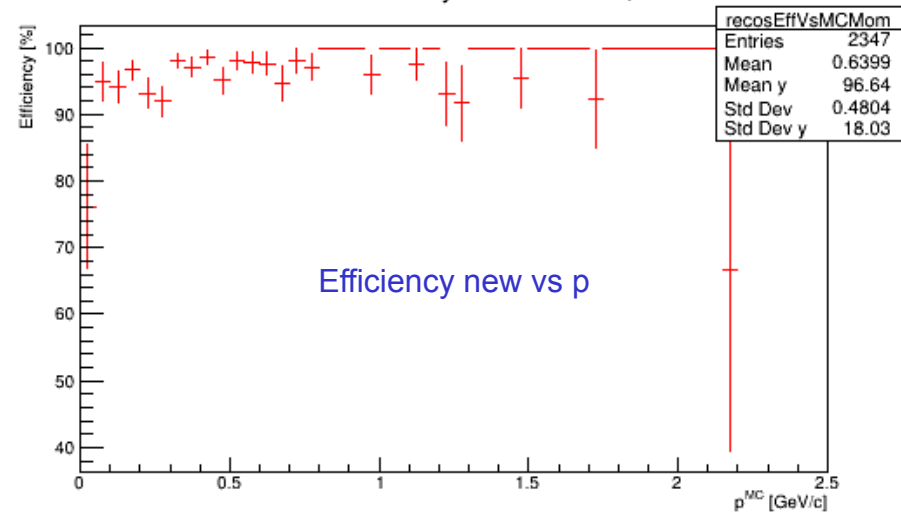
Reconstruction Efficiency vs  $p_T$ , All Tracks



Reconstruction Efficiency vs Momentum, All tracks



Reconstruction Efficiency vs Momentum, All tracks



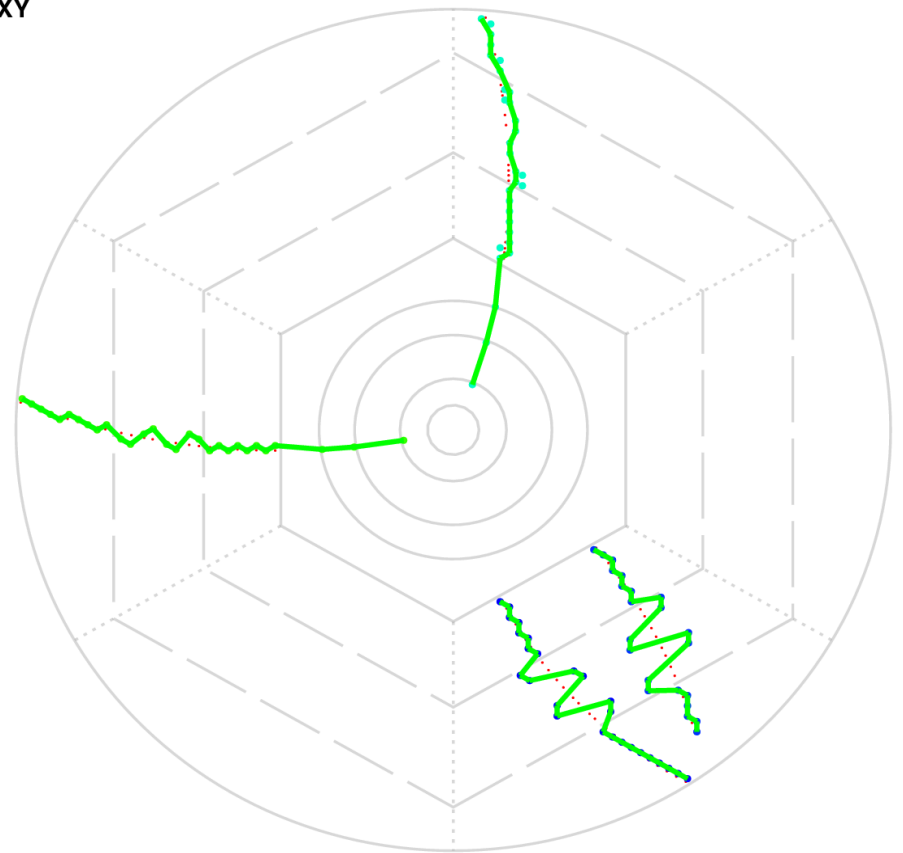
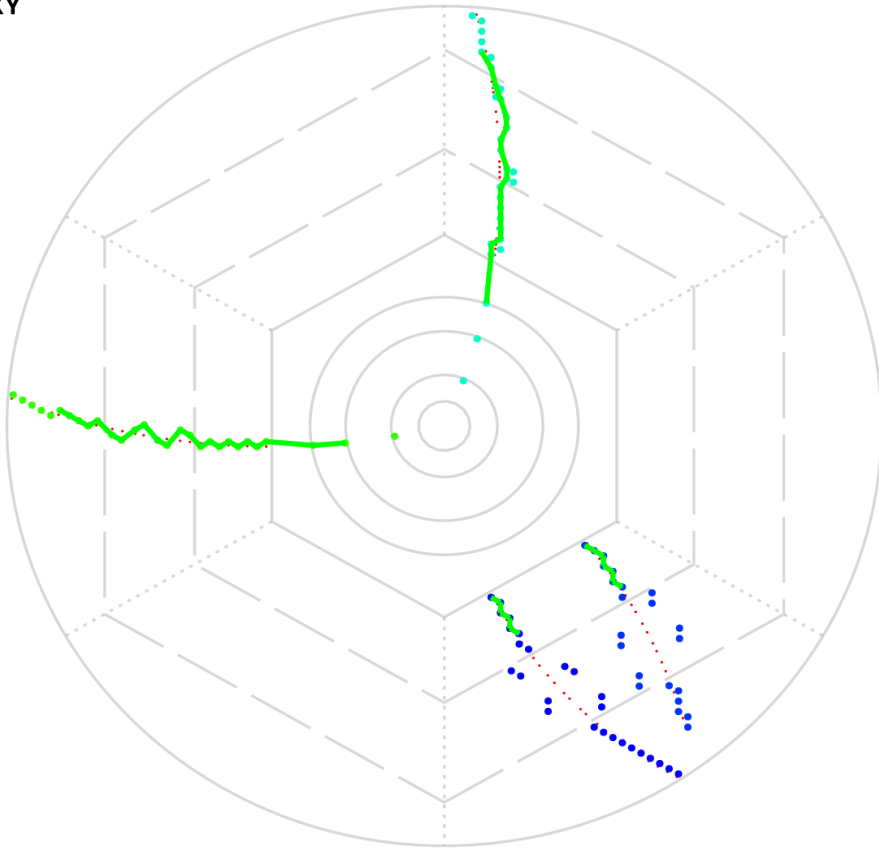
# Event 355

old

new

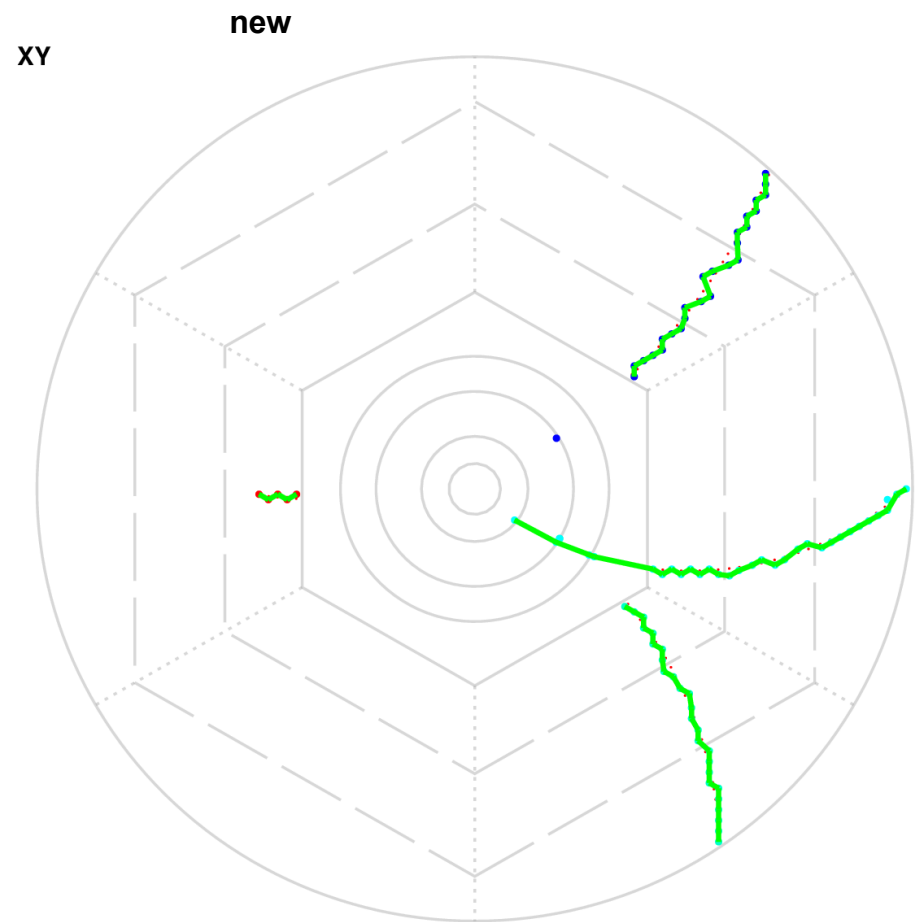
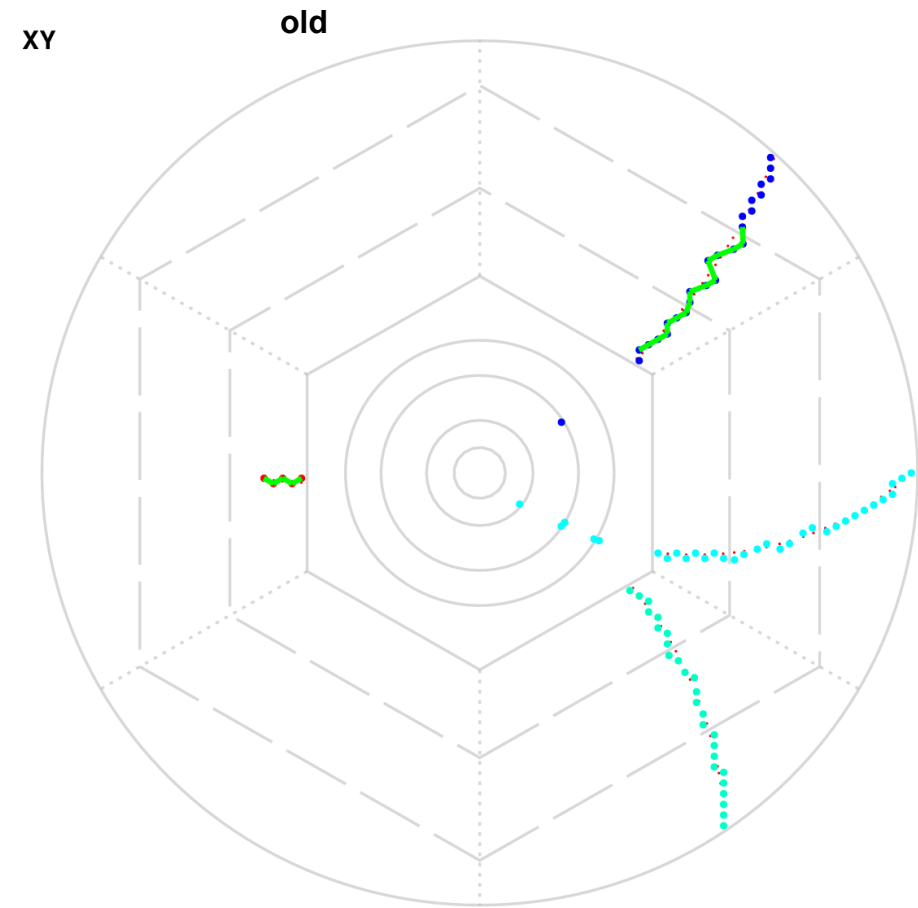
XY

XY



MVD pixel hits are now included in tracks

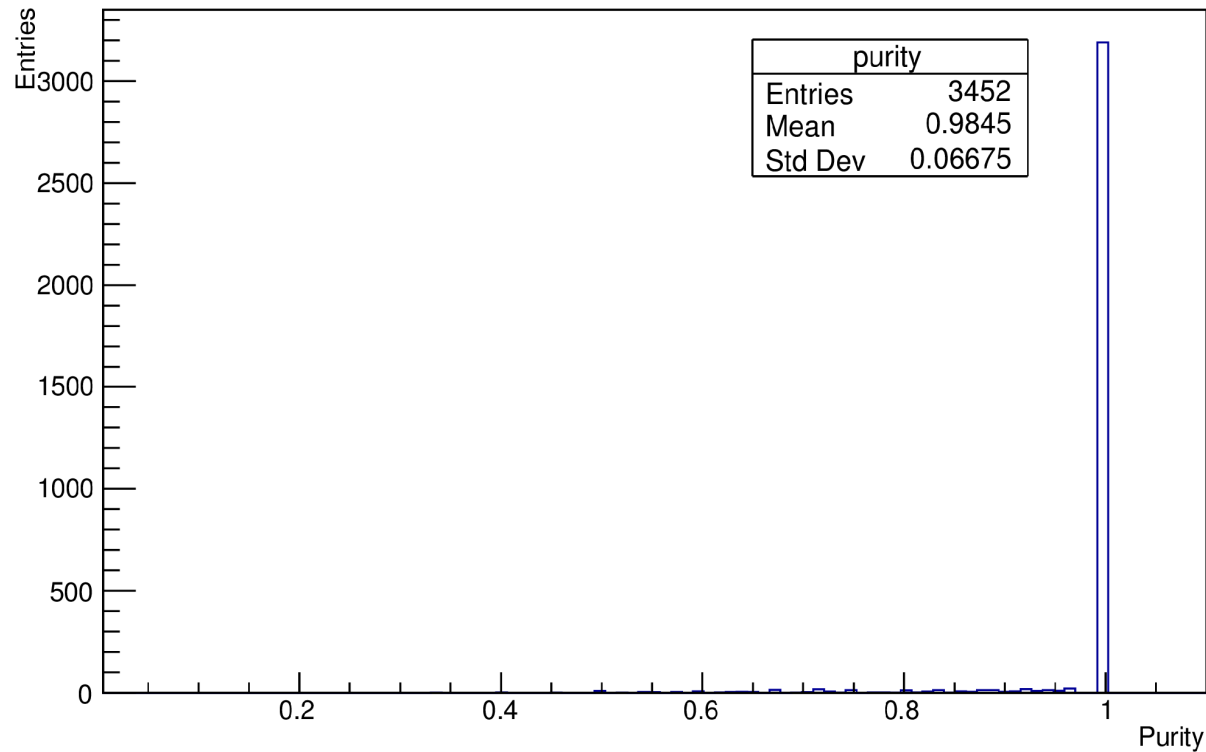
# Event 323



MVD pixel hits are now included in tracks and low  $p_T$  tracks are reconstructed

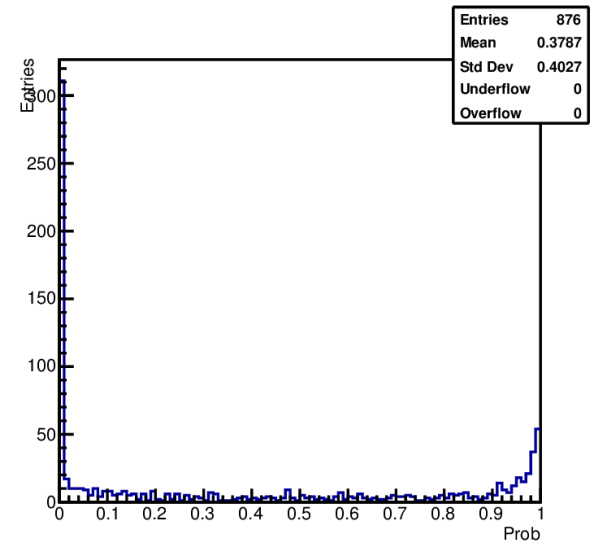
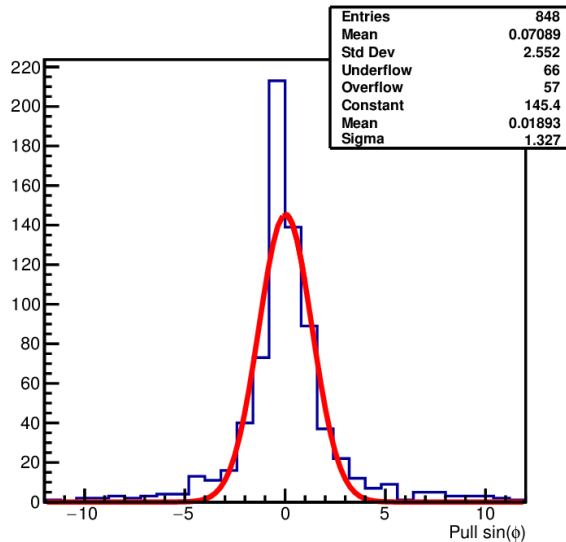
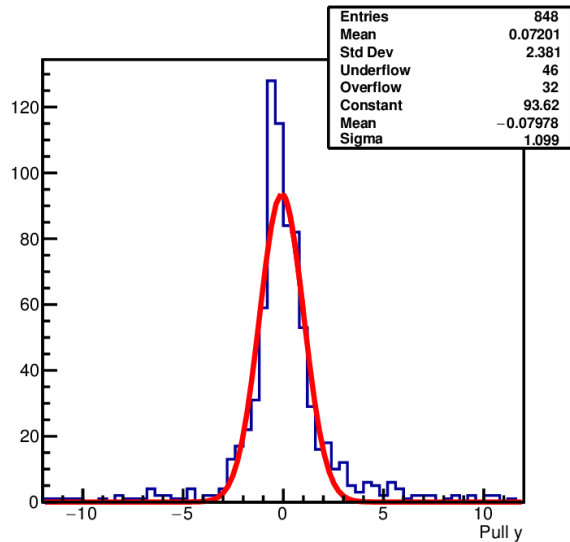
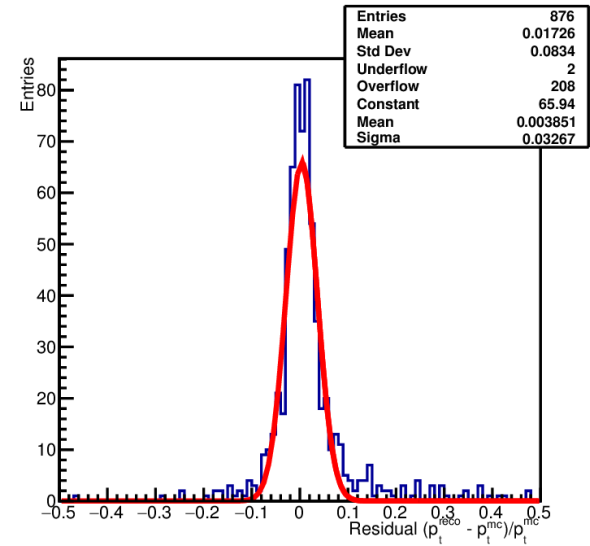
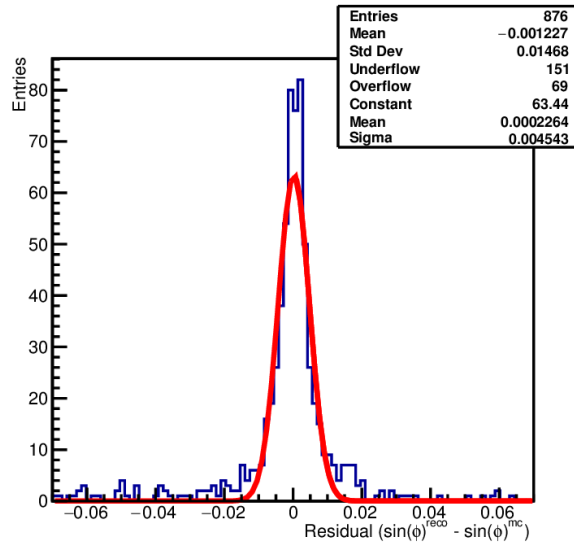
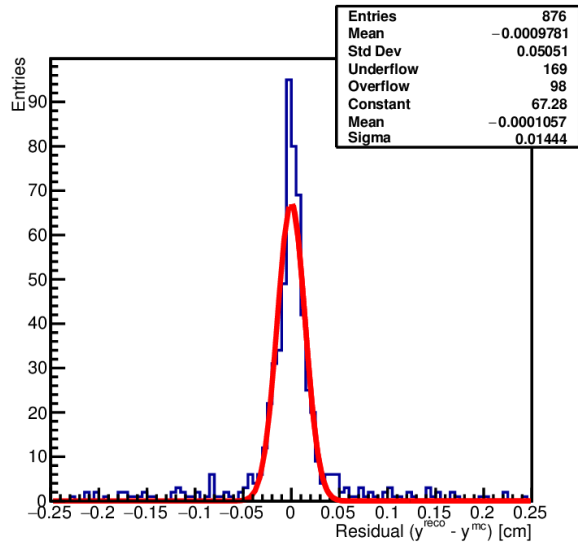


# Purity of Reconstructed Tracks

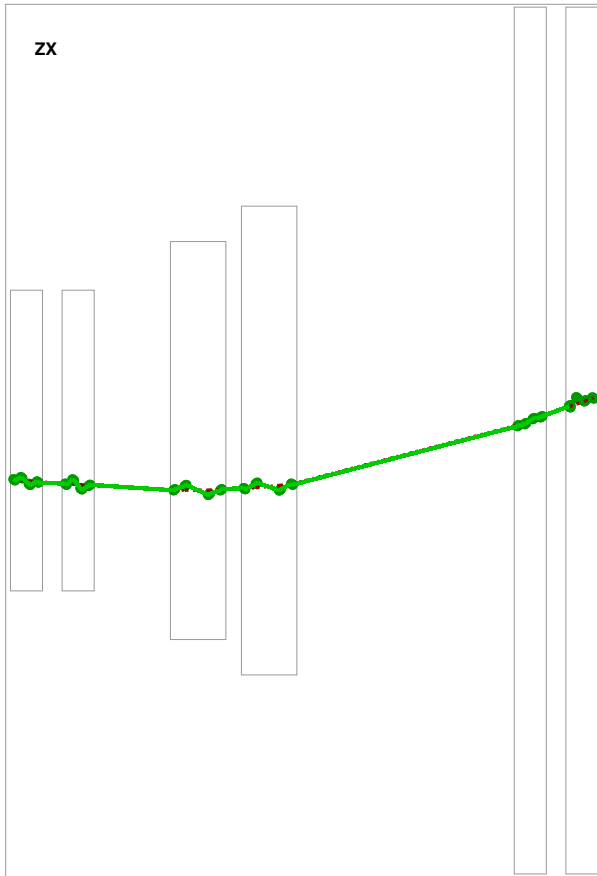


$$\text{Purity} = \text{Nmc\_true\_hits} / \text{All reco\_hits}$$

# Residuals and Pulls



# FTS CA Track Finder



STT CA track finder successfully applied to FTS:

- STT CA track finder in conjunction with the KF for the forward track-model.

Track-candidates creation in progress:

- Dropout of hits issue which will be resolved soon.
- Caused by the divergences in the Kalman filter.

- First measurement needs special filtration (because of the initial approximation for covariance matrix tends to infinity)
- In case of big errors in the covariance matrix the equations of filtration are modified by Taylor expansion because of their numerical divergency.
- Under investigation: numerical divergency because of the mixed covariance matrix with small errors on  $\{x,tx\}$  and big errors on  $\{y,ty,q/p\}$ . Appears after filtration of 2 first measurements with the same tube angle.

# Summary

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- CA track finder modified wrt. the detector geometry, hit errors etc.
- Tracking efficiency in the barrel STT/MVD detectors recovered.
- Kalman filter track fit is under investigation in the barrel and forward parts of the detector system.

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