Cluster Beam Shaping and Visualization

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Cluster-Jet Target Prototype for PANDA

- Prototype built up in complete PANDA geometry
- Target material with purity of 9.0
- Target thickness:
 - > 2 × 10¹⁵ $\frac{\mathrm{atoms}}{\mathrm{cm}^2}$
 - Adjustable by variation of pressure and temperature settings
 - Constant in time scales of at least several hours
- ightarrow See talk of E. Köhler





Variable Target Beam Size and Shape Use of a collimator

• Collimator installed behind the skimmer

- Cuts out a certain area of cluster beam ⇒ Shaping
 - of cluster beam
- Collimator with different shapes are in use



collimator



Specially Shaped Collimators



collimator with round orifice



 \implies Overlap of antiprotons and target beam small compared to the size of target beam



 \implies Target beam size as small as possible with same size of overlap region

 \longrightarrow Reduction of background pressure



collimator with slit orifice

Studies on defined Cluster Beams

Determination of target position, size, shape and thickness



Studies on defined Cluster Beams

Fit function and assumed density distribution

- Target thickness $ho_T \sim rac{p_{sc}}{v_c}$
 - psc: Pressure increase in scattering chamber
 - v_c: Velocity of cluster (200 1000 m/s) (see A. Täschner et al., in proceedings of STORI'11 conference, PoS(STORI11)065)
- Profiles can be described by a convolution of a rectangular and a Gaussian function



Assumed density distribution

$$\rho_{T}(x,y) = \rho_{0} \cdot \frac{erf(\frac{\frac{1}{2}b_{x}-x}{s}) - erf(\frac{-\frac{1}{2}b_{x}-x}{s})}{2} \cdot \frac{erf(\frac{\frac{1}{2}b_{y}-y}{s}) - erf(\frac{-\frac{1}{2}b_{y}-y}{s})}{2}$$

- erf(z): Error function
- s : Smearing factor \sim FWHM of Gaussian
- b_x : Size of cluster beam in x-direction
- b_y : Size of cluster beam in y-direction

Target Thickness of defined Cluster Beam



- Analysis of 5 different slit collimators
 - Length: $\approx 780\,\mu{\rm m}$
 - Width: 116 $\mu m -$ 194 μm (+)
 - 221 μm × 580 μm (+)
- Target thickness $> 10^{15} \, {{\rm atoms}\over{{
 m cm}^2}}$
- Smaller widths
 → less thicknesses
- Thickness about $2.2 \times 10^{15} \frac{atoms}{cm^2}$ with a collimator with $221 \ \mu m \times 780 \ \mu m$

It is possible to achieve the same target thickness as measured with a round collimator!

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Size of Cluster Beam at the Interaction Point

Minimal size of the cluster beam at the IP is limited by FWHM of Gaussian

•
$$f(x,y) = \frac{erf(\frac{\frac{1}{2}b_x - x}{s}) - erf(\frac{-\frac{1}{2}b_x - x}{s})}{2} \cdot \frac{erf(\frac{\frac{1}{2}b_y - y}{s}) - erf(\frac{-\frac{1}{2}b_y - y}{s})}{2}$$

• $b_x \approx s$: Smearing effects dominating \longrightarrow impact on thickness



Size of Cluster Beam at the Interaction Point Dependency between cluster beam width and collimator width



- Expected theory curve at a constant $s = 1.38 \,\mathrm{mm}$
- In good agreement with measurements
- Optimal collimator width around 200 µm

Minimal cluster beam width about 2 mm (at the IP)

Signal to Background Ratio

- Signal to background ratio is given by $r_{S/B} = \frac{\rho_T}{\rho_B}$
- Thickness of background: $\rho_B = \frac{p_B \cdot x}{k \cdot T} (x = 1 \text{ m})$
- Maximum signal to background ratio of 552 : 1
- Signal to background ratio of round collimator (Ø0.7 mm) about 375 : 1
- \Rightarrow Improvement of about 50 %
 - Geometrically expected: improvement by a factor of 2.5
- ⇒ Cause for deviation: residual gas comes directly from cluster source

 \longrightarrow Possible solution: installation of further orifices



Cluster Beam Shaping

Summary

- Cluster beam can be shaped arbitrarily (→ Can be visualized by a MCP detector)
- $\bullet\,$ Target thickness in the order of $2\times 10^{15}\,\frac{\rm atoms}{\rm cm^2}$ with a slit collimator
- Limitation of cluster beam size at IP
- \Rightarrow Minimal width currently about 2 mm (at the IP)
 - $\bullet\,$ Optimal collimator width around 200 μm
 - Signal to background ratio improved by 50 % compared to a round collimator
 - ightarrow Much more possible with a new pumping system

Visualization of the Cluster Beam Overview



 Visualization of Cluster beam with MCP detector (MicroChannel Plate detector)

Visualization of the Cluster Beam Overview



 Visualization of Cluster beam with MCP detector (MicroChannel Plate detector)



MCP detection system

MCP Detection System



• Phosphor screen (max. 3 kV)

MCP Detection System Overview



• Grid with 2.5 mm lattice spacing (electrically grounded)

Two MCPs

(chevron assembly, effective diameter of 40 mm)

• each capillary works as independent secondary-multiplier

- 1st MCP: max. -4 kV
- 2nd MCP: max. $-2 \,\mathrm{kV}$

Phosphor screen ٠ (max. 3 kV)



chevron assembly

Direct Observation of the Cluster-Jet Beam Microscopic View of Collimators and Resulting Images on MCP Detector

• Definition of target beam size and shape with collimators



Direct Observation of the Cluster-Jet Beam Microscopic View of Collimators and Resulting Images on MCP Detector

- Definition of target beam size and shape with collimators
- MCP images with expected beam shape and grid at approximately 5 m behind the collimator



Direct Observation of the Cluster-Jet Beam Performance

• Direct observation of an ionized cluster-jet beam

 \longrightarrow Cluster beam is very easy to shape with an orifice

• Estimation of the cluster beam size at the grid position

 \rightarrow Clearly visible grid structure (2.5 mm lattice spacing)



Direct Observation of the Cluster-Jet Beam Performance

- Direct observation of an ionized cluster-jet beam
 - \longrightarrow Cluster beam is very easy to shape with an orifice
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• **Identification** of cluster beam position and mechanical interferences

⇒New opportunity to run target beam adjustment checks during target operation

Direct Observation of the Cluster-Jet Beam Performance

• The image intensity corresponds to the **relative cluster beam density distribution**





- Test measurements within 2 h
- COSY beam (2 GeV/c) passes the internal hydrogen (deuterium) cluster-jet target
- ⇒ **lonization** of the cluster beam at the interaction zone
- ⇒ Detection of the ionized parts of the cluster beam at the end of the beam dump with MCPs
 - Measurements during a cycle of the COSY beam:
 Beam injection, acceleration, steerer magnet on/off

Projection of the interaction zone (in false colours) at COSY beam injection energies



COSY beam after acceleration (2 GeV/c) \rightarrow adiabatic cooling (reduced phase space)



Shift of the interaction zone \longrightarrow steerer magnet on



Shift of the interaction zone \longrightarrow steerer magnet off



\Rightarrow New possibility to monitor the interaction zone at internal target experiments

ightarrow a diagnostic tool for quantitative vertex point studies



Cluster Beam Visualization Summary and Outlook

Summary

• Target beam adjustment checks possible (during target operation)

- Direct observation of the cluster beam (shape)
- Estimation of target beam size (approximately 4.9 m after the nozzle)
- Identification of cluster beam position and possible interferences
- Image intensity $\widehat{=}$ relative density distribution
- Observation of beam and target interaction region
 - $\, \bullet \,$ Successfully demonstrated at ANKE/COSY \Longrightarrow New tool for $\overline{\mathsf{P}}\mathsf{ANDA}$

Outlook

- Estimation of the cluster mass
 - First tests with MCPs in combination with a deflecting field
- \Rightarrow See talk of E. Köhler

Thank you for your attention! * And special Thanks to the ANKE/COSY Crew *



