



A detailed ML example: SPS spill quality control

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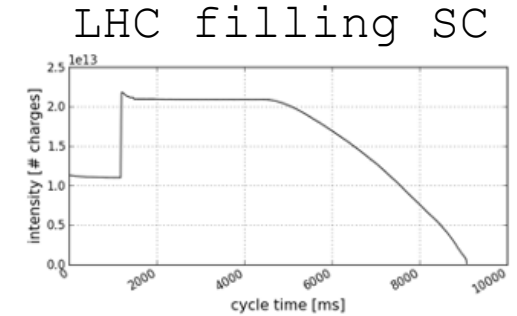
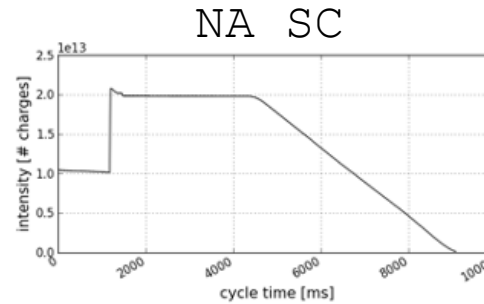
Motivation



Spill quality degrades with the slightest perturbation

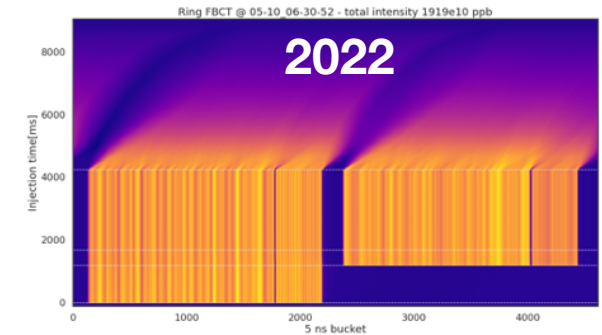
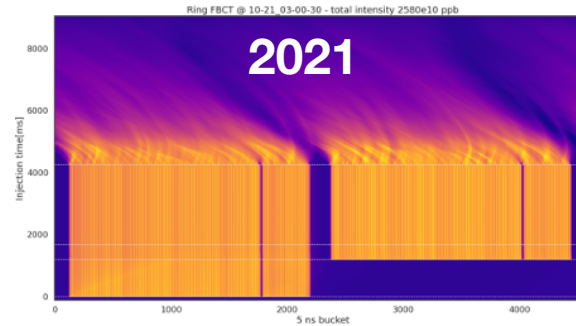
★ Macro-spill shape: Hysteresis

- * Is being addressed as part of PhD
- * Currently: manual adjustments



★ High frequency ripple from “slow” debunching

- * **Solved:** Regulating at 0 V



★ Low frequency ripple from power converters

- * Implemented solution: $n \times 50$ Hz active control + Empty Bucket Channeling with 800 MHz
- * **Goal:** keep modulation amplitudes below 0.15 normalised for $> 85\%$ of time

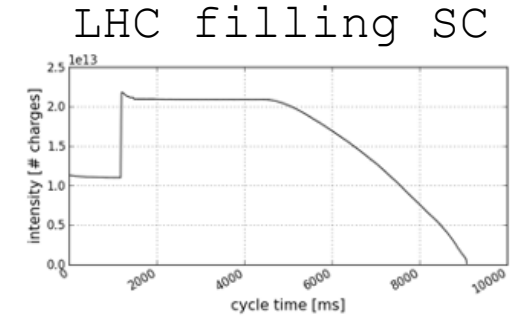
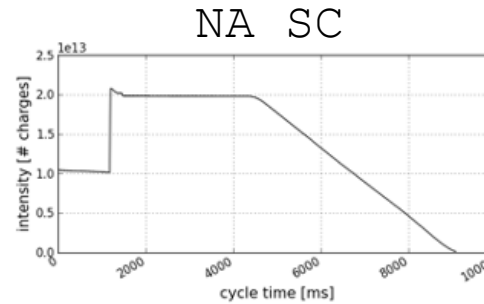
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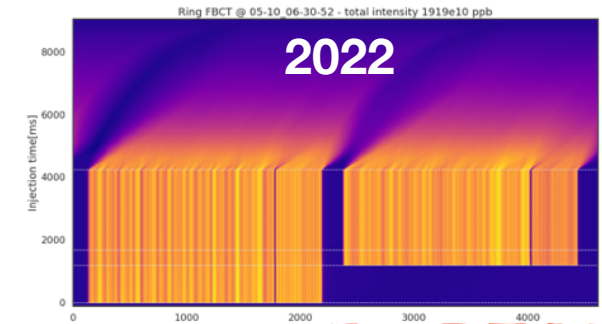
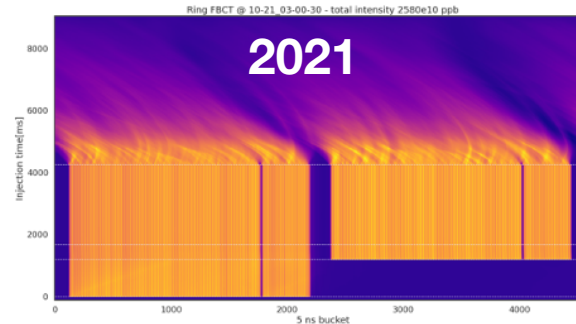
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Since Long Shutdown 2, 50 and i.e. 100 Hz noise problematic.

Also, larger shot-by-shot fluctuations during day.

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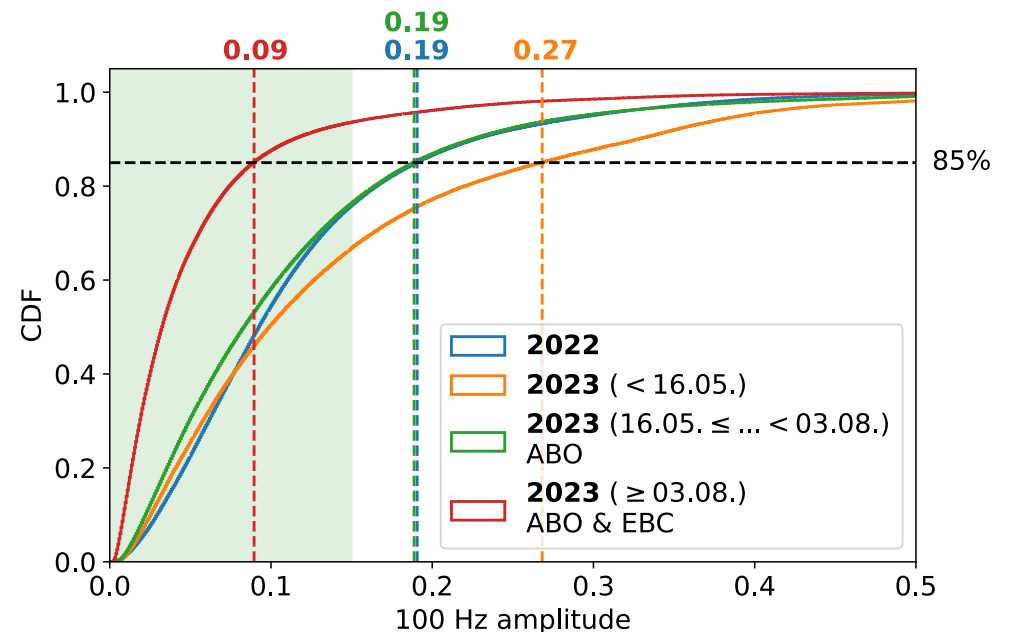
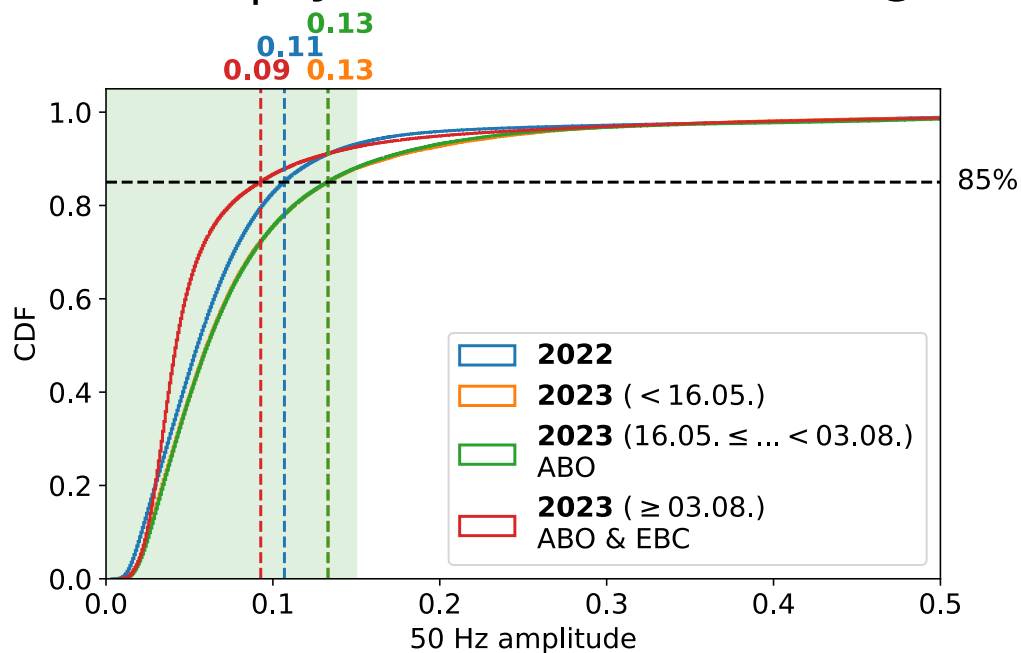


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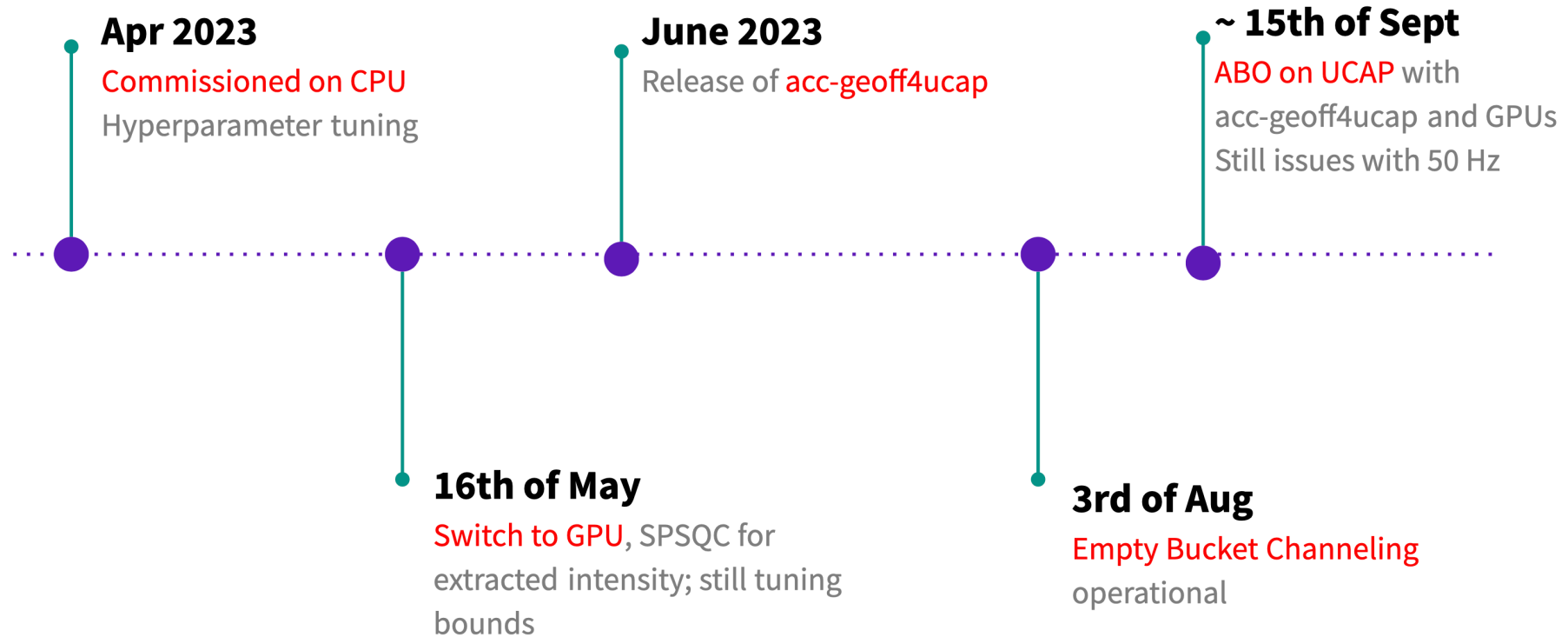
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Evolution through 2023



ABO 2023



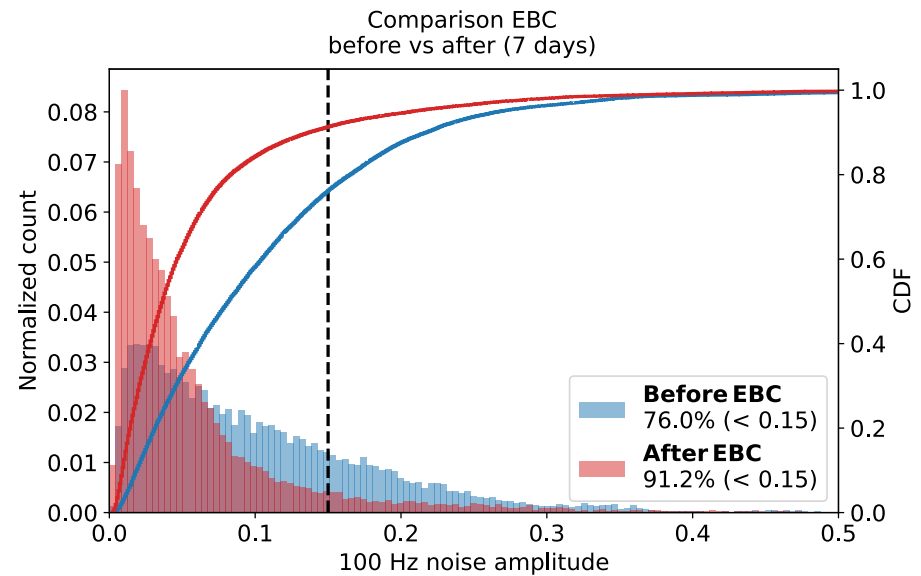
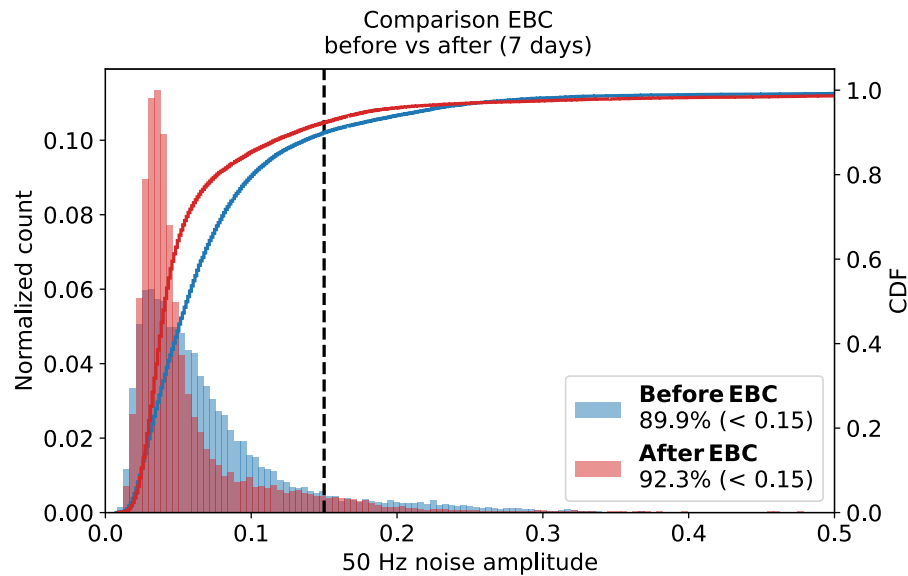
Performance improvements throughout the year!

Effect of Empty Bucket Channeling

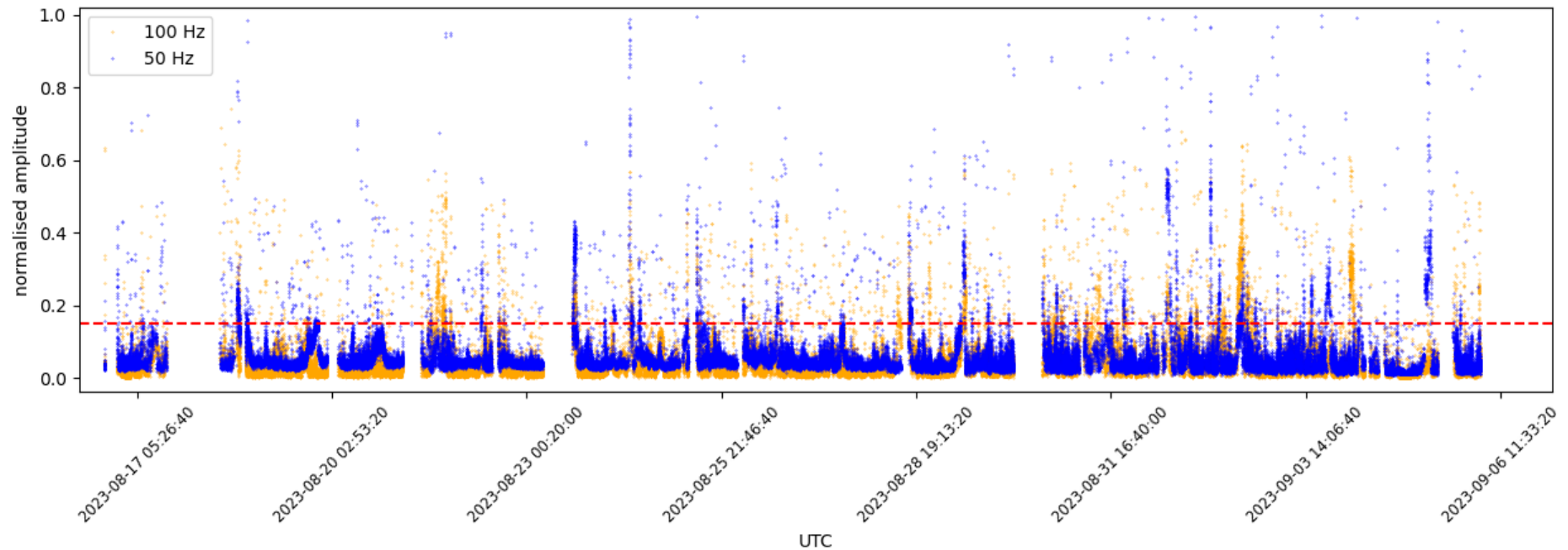


Comparison ABO+EBC of 7 days before and after switching on EBC.

- ★ Unfortunately EBC alone is not sufficient, ABO needs to do base correction
- ★ EBC improves the overall result



Impression - some weeks in Aug '23



→ ABO tracks well; recovers after long stops

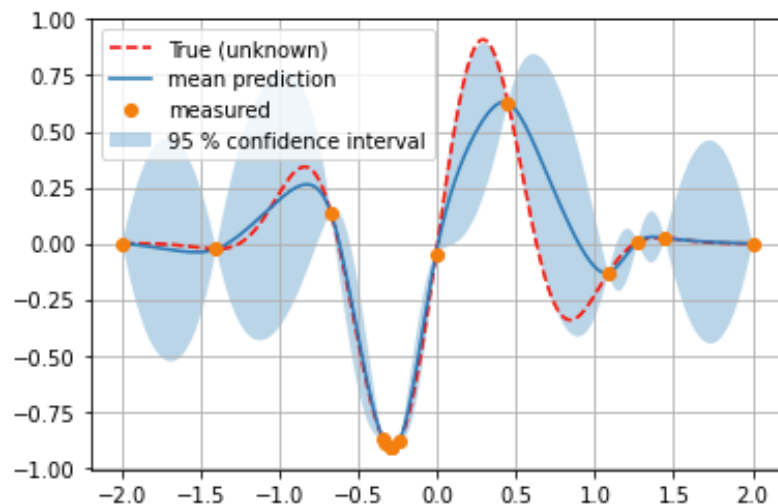
→ Some issues still in 2023 - all are being addressed

- * exploration and hyperparameters, sharing GPU with other processes (→ controller lock-up), exploration spikes

Bayesian Optimisation - brief intro



- ★ Regression of objective function with probabilistic model:
Gaussian process described by mean function $\mu(x)$ and covariance function $k(x, x') \rightarrow$ *kernel* function
- ★ GP is **conditioned** (no fit) with new data assuming prior and using Bayesian rule \rightarrow posterior
- ★ Optimisation: will not only use $\mu(x)$, but utilise also $\sigma(x) \rightarrow$ not optimising objective function directly, but **acquisition function** e.g. $\alpha(x) = \alpha(\mu(x), \sigma(x))$. Suitable for non-convex optimisation.



Example of 1D optimisation problem.

Can embed physics knowledge into kernel.

Kernel can also be tuned (fit) on historic data to increase sample-efficiency

Adaptive Bayesian Optimisation



Idea: build Gaussian Process for timeseries prediction with *SpectralMixtureKernel* $S(t, t')$

Gaussian Process Kernels for Pattern Discovery and Extrapolation

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→ add one dimension in problem space: t to predict $t + 1$ into future; optimise x at $t + 1$ → **continuous control**

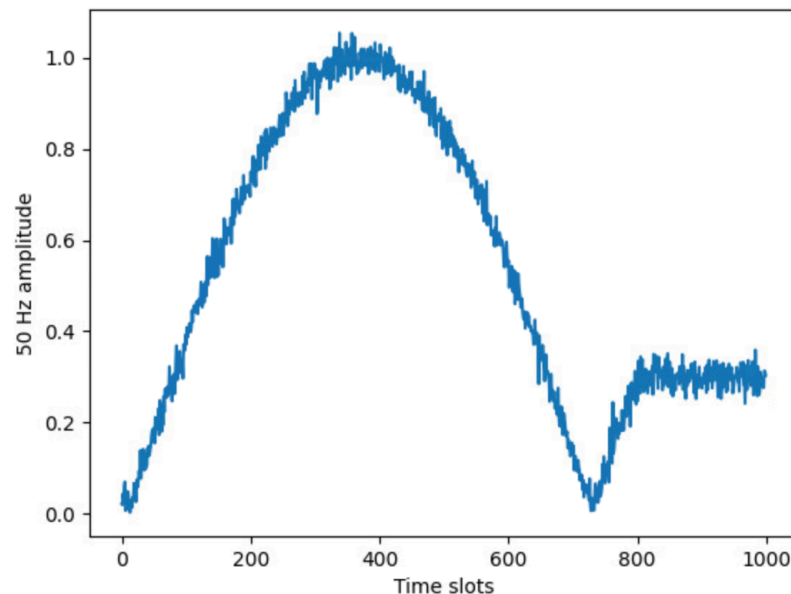
→ GP with composite kernel: the kernel that is currently used:
$$\sigma^2 \times S(t, t') \times RBF(x, x')$$

Tuning ABO - introduction



Simulation: simplified $n \times 50$ Hz control of slow extracted spill

- ★ Only 50 Hz
- ★ Only 1 D: find correct phase
- ★ phase of spill is linearly changing over time
- ★ the spill measurement is noisy



**Evolution of 50 Hz amplitude
with constant correction**

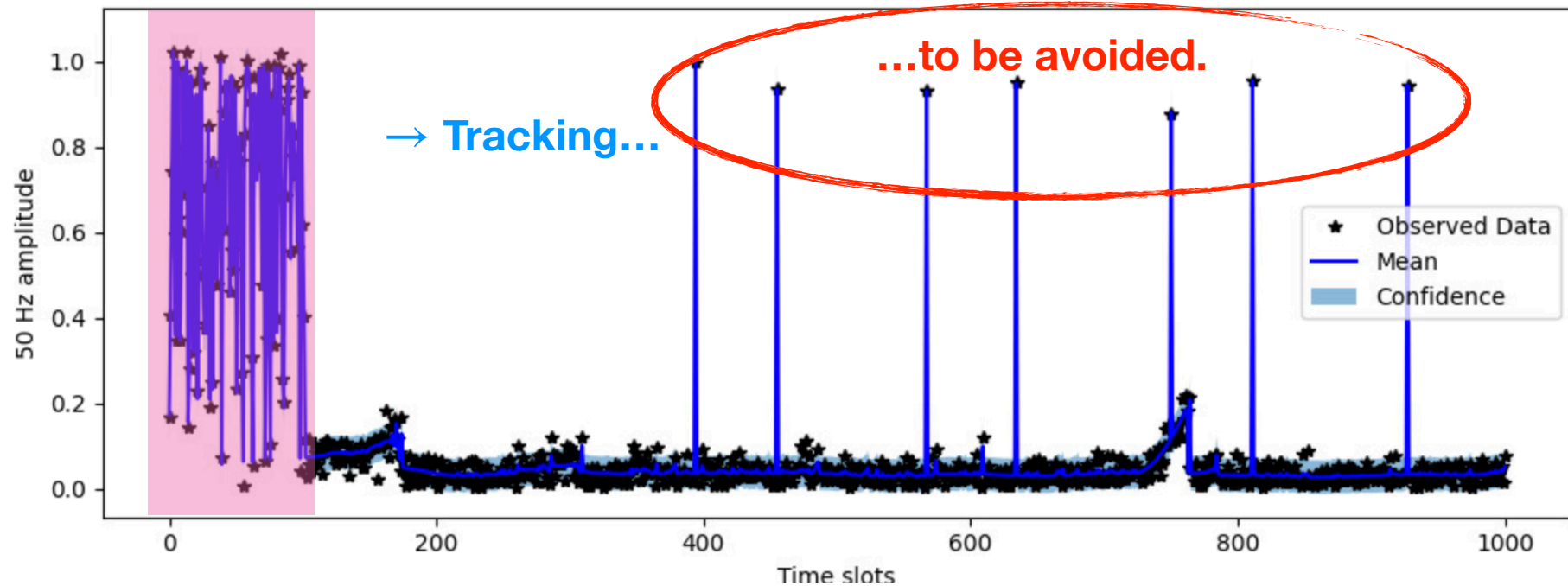
Tuning ABO - introduction



Using *Upper Confidence Bound* acquisition function:

★ hyperparameter β guides exploration, optimal: reactive, but sufficiently conservative

100 random training samples



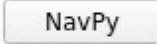
★ for continuous controller more hyperparameters: e.g. buffer length

* key for forecasting accuracy; optimum buffer length to be tuned again for UCAP with GPU.

Implementation



- ★ ABO custom made algorithm based on BoTorch and cernml-coi-optimizers package → GPU accelerated
- ★ 2 acc-geoff4ucap controllers: 50 Hz, 100 Hz
- ★ UCAP node with GPU: "Y" implementation
 - * `SpillNoiseController` sets QF phase and amplitude for $n \times 50$ Hz noise injection

Device: SPS.NASPILL.CONTROL  Grafana  NavPy

Transformations **Actors** JSON Active Subscriptions

Name	Description	Status	Queue	Calls	Issues
ControlSpill100Hz	100 Hz ABO	STOPPED	0 / 32 (0)	0 (0)	0
ControlSpill50Hz	50 Hz ABO	STOPPED	0 / 32 (0)	0 (0)	0
SpillNoiseController	Subscription to controllers and publishing to actors	STOPPED	0 / 32 (0)	0 (0)	0

Start Device Stop Device Reload Device Delete Device

Avoiding exploration spikes - Proximal biasing

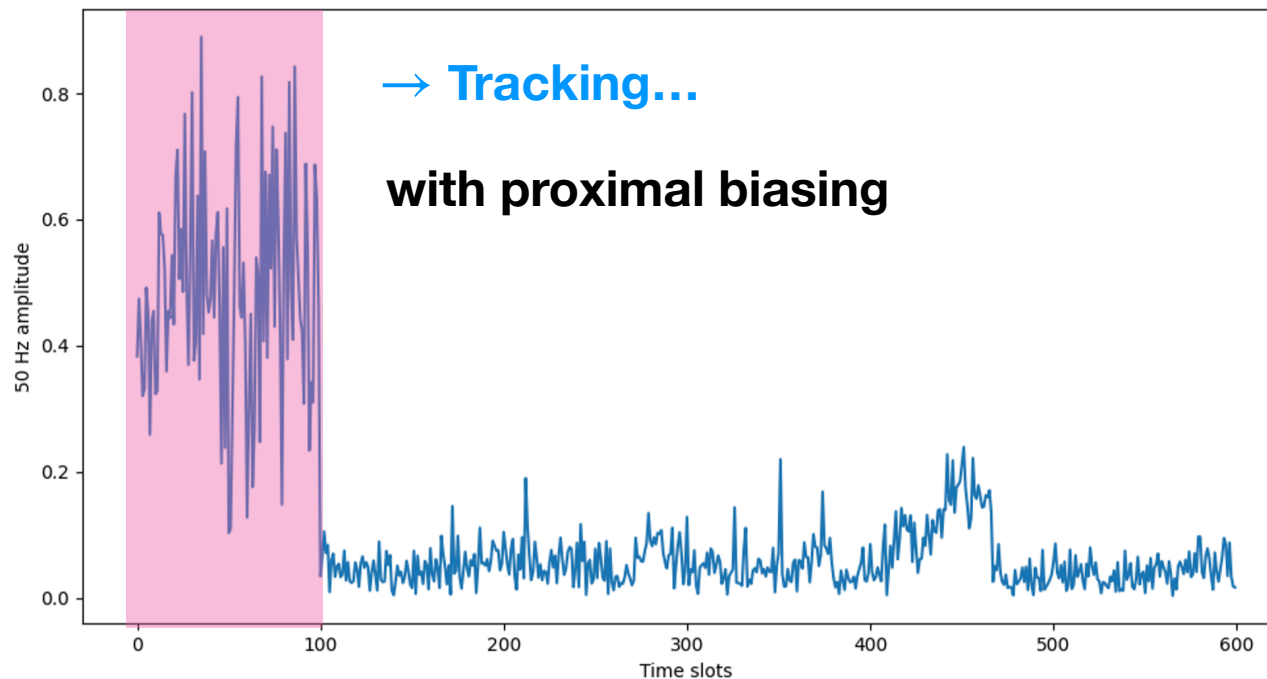


By wrapping the acquisition function $\tilde{\alpha}(x) = \alpha(x) \cdot \exp\left(-\frac{(x - x_0)^2}{2l^2}\right)$,
 x_0 is last observed location in parameter space. l is an additional hyperparameter

→ no exploration spikes, but slightly less reactive. To be tuned with beam.

Below: simulation with 2 DOF (phase, amplitude) → no (big) spikes!

100 random training samples



Conclusion and next steps



Adaptive Bayesian Optimisation and Empty Bucket Channeling can sufficiently stabilise $n \times 50$ Hz ripples of NA spill.

2023 = first operational experience with all controls components for EBC+ABO; improvements throughout the year

2024 = full exploitation!

Next steps:

- ★ dedicated GPU?
- ★ tune 50 Hz buffer length for UCAP controller
- ★ tune proximal biasing
- ★ ensure to be able to switch to spare power supply (QS) during run
 - * Current controls only for nominal power supply QF